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Laplace Transform

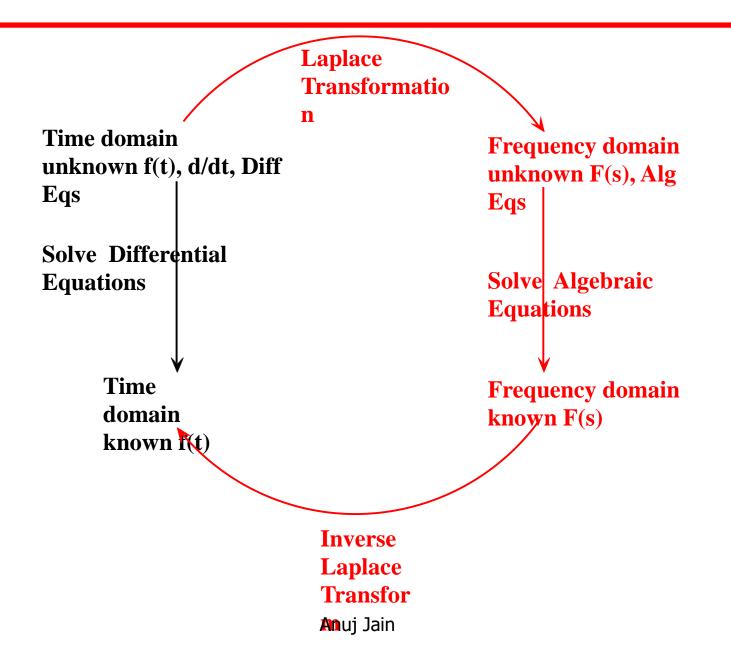
> To evaluate the performance of an automatic control

system commonly used mathematical tool is "Laplace

Transform"

- ➤ Laplace transform converts the differential equation into an algebraic equation in 's'.
- > Laplace transform exist for almost
- · all signals Anuj Jain of practical interest. 2

Why Laplace Transform?



Laplace Transform- Definition

The Laplace transform of a function, f(t), is defined as

$$F(s) = \mathsf{L} [f(t)] = \int_0^\infty f(t) e^{-st} dt \qquad (1-1)$$

where F(s) is the symbol for the Laplace transform, L is the Laplace transform operator, and f(t) is some function of time, t.

Note: The L operator transforms a time domain function f(t) into an s domain function, F(s). s is a complex variable:

$$s = a + bj$$
, $j B \sqrt{-1}$

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Inverse Laplace Transform

By definition, the inverse Laplace transform operator, L^{-1} , converts an s-domain function back to the corresponding time domain function:

$$f(t) = L^{-1} \lceil F(s) \rceil$$

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Transfer Function

➤ The relationship between input & output of a system is

given by the transfer function.

➤ <u>Definition:</u> The ratio of Laplace transform of the output to the Laplace transform of the input under the assumption of zero initial conditions is defined as

"Transfer Function".

The Laplace Transform of a function, f(t), is defined as;

$$L[f(t)] = F(s) = \int_{0}^{\infty} f(t)e^{-st}dt$$

Eq A

The Inverse Laplace Transform is defined by

$$L^{-1}[F(s)] = f(t) = \frac{1}{2\pi j} \int_{\sigma - j\infty}^{\sigma + j\infty} F(s)e^{ts}ds$$
 Eq B

Laplace Transform of the unit step.

$$\boldsymbol{L}[\boldsymbol{u}(t)] = \int_{0}^{\infty} 1e^{-st} dt = \frac{-1}{s} e^{-st} \Big|_{0}^{\infty}$$

$$L[u(t)] = \frac{1}{s}$$

The Laplace Transform of a unit step is:

 $\frac{1}{s}$

*notes

The Laplace transform of a unit impulse:

Pictorially, the unit impulse appears as follows:

Mathematically:

$$\delta(t-t_0)=0 \quad t\neq 0$$

$$\delta(\mathbf{t} - \mathbf{t_0}) = \mathbf{0} \quad \mathbf{t} \neq \mathbf{0}$$

$$\int_{t_0 - \varepsilon}^{t_0 + \varepsilon} \delta(t - t_0) dt = 1 \quad \varepsilon > 0$$

The Laplace transform of a unit impulse:

In particular, if we let $f(t) = \delta(t)$ and take the Laplace

$$L[\boldsymbol{\delta}(t)] = \int_{0}^{\infty} \boldsymbol{\delta}(t)e^{-st}dt = e^{-0s} = 1$$

Building transform pairs:

$$L[e^{-at}u(t)] = \int_{0}^{\infty} e^{-at}e^{-st}dt = \int_{0}^{\infty} e^{-(s+a)t}dt$$

$$L[e^{-at}u(t)] = \frac{-e^{-st}}{(s+a)}\Big|_0^\infty = \frac{1}{s+a}$$

pair

A transform
$$e^{-at}u(t) \Leftrightarrow \frac{1}{s+a}$$

Building transform pairs:

$$L[\cos(wt)] = \int_{0}^{\infty} \frac{(e^{jwt} + e^{-jwt})}{2} e^{-st} dt$$

$$= \frac{1}{2} \left[\frac{1}{s - jw} - \frac{1}{s + jw} \right]$$

$$= \frac{s}{s^2 + w^2}$$

$$\cos(wt)u(t) \Leftrightarrow \frac{s}{s^2 + w^2}$$
 A transform pair

Time Shift

$$L[f(t-a)u(t-a)] = \int_{a}^{\infty} f(t-a)e^{-st}$$

$$Let \ x = t - a, then \ dx = dt \ and \ t = x + a$$

$$As \ t \to a, \ x \to 0 \ and \ as \ t \to \infty, x \to \infty. \ So,$$

$$\int_{0}^{\infty} f(x)e^{-s(x+a)}dx = e^{-as} \int_{0}^{\infty} f(x)e^{-sx}dx$$

$$L[f(t-a)u(t-a)]=e^{-as}F(s)$$

Frequency Shift

$$L[e^{-at}f(t)] = \int_{0}^{\infty} [e^{-at}f(t)]e^{-st}dt$$

$$= \int_{0}^{\infty} f(t)e^{-(s+a)t}dt = F(s+a)$$

$$L[e^{-at}f(t)]=F(s+a)$$

Example: Using Frequency Shift

Find the L[e^{-at}cos(wt)]

In this case, $f(t) = \cos(wt)$ so,

$$F(s) = \frac{s}{s^2 + w^2}$$
and $F(s+a) = \frac{(s+a)}{(s+a)^2 + w^2}$

$$L[e^{-at}\cos(wt)] = \frac{(s+a)}{(s+a)^2 + (w)^2}$$

Time Integration:

Making these substitutions and carrying out The integration shows that

$$L\left[\int_{0}^{\infty} f(t)dt\right] = \frac{1}{s} \int_{0}^{\infty} f(t)e^{-st}dt$$
$$= \frac{1}{s} F(s)$$

Time Differentiation:

If the L[f(t)] = F(s), we want to show:

$$L\left[\frac{df(t)}{dt}\right] = sF(s) - f(0)$$

Integrate by parts:

$$u = e^{-st}, du = -se^{-st}dt \text{ and}$$

$$dv = \frac{df(t)}{dt}dt = df(t), \text{ so } v = f(t)$$

Time Differentiation:

Making the previous substitutions gives,

$$L\left[\frac{df}{dt}\right] = f(t)e^{-st} \Big|_{0}^{\infty} - \int_{0}^{\infty} f(t)\left[-se^{-st}\right] dt$$
$$= 0 - f(0) + s \int_{0}^{\infty} f(t)e^{-st} dt$$

So we have shown:

$$L\left[\frac{df(t)}{dt}\right] = sF(s) - f(0)$$

Time Differentiation:

We can extend the previous to show;

$$L\left[\frac{df(t)^2}{dt^2}\right] = s^2F(s) - sf(0) - f'(0)$$

$$L\left[\frac{df(t)^{3}}{dt^{3}}\right] = s^{3}F(s) - s^{2}f(0) - sf'(0) - f''(0)$$

general case

$$L\left[\frac{df(t)^{n}}{dt^{n}}\right] = s^{n}F(s) - s^{n-1}f(0) - s^{n-2}f'(0)$$
$$-...-f^{(n-1)}(0)$$

Transform Pairs:

f(t)	F(s)
$\delta(t)$	1
u(t)	$\frac{1}{s}$
e^{-st}	$\frac{1}{s+a}$
t	$\frac{1}{s^2}$
t ⁿ	$\frac{n!}{s^{n+1}}$

Transform Pairs:

$te^{-at} \qquad \frac{1}{(s+a)^n}$)
(s+a)	
	$(u)^2$
$t^n e^{-at}$	
(s+a)	$)^{n+1}$
$\sin(wt)$ $\frac{w}{2}$	
$s^2 + 1$	w ²
$\cos(wt)$ $\frac{s}{s^2+1}$	2
3 +	//

Transform Pairs:

f(t)	F(s)
$e^{-at}\sin(wt)$	$\frac{w}{(s+a)^2+w^2}$
$e^{-at}\cos(wt)$	$\frac{s+a}{(s+a)^2+w^2}$
$\sin(wt + \theta)$	$\frac{s\sin\theta + w\cos\theta}{s^2 + w^2}$
$\cos(wt + \theta)$	$\frac{s\cos\theta - w\sin\theta}{s^2 + w^2}$

Common Transform Properties:

f(t)

 $\mathbf{F}(\mathbf{s})$

$$f(t-t_0)u(t-t_0), t_0 \ge 0 \qquad e^{-t_0 s} F(s)$$

$$f(t)u(t-t_0), t \ge 0 \qquad e^{-t_0 s} L[f(t+t_0)]$$

$$e^{-at} f(t) \qquad F(s+a)$$

$$\frac{d^n f(t)}{dt^n} \qquad s^n F(s) - s^{n-1} f(0) - s^{n-2} f'(0) - \dots - s^0 f^{n-1} f(0)$$

$$tf(t) \qquad -\frac{dF(s)}{ds}$$

$$\int_0^t f(\lambda) d\lambda \qquad \frac{1}{s} F(s)$$

Using Matlab with Laplace transform:

Example

Use Matlab to find the transform of

$$te^{-4t}$$

The following is written in italic to indicate Matlab code

```
syms t,s

laplace(t*exp(-4*t),t,s)

ans = \frac{1/(s+4)^2}{2}
```

Using Matlab with Laplace transform:

Example

Use Matlab to find the inverse transform of

$$F(s) = \frac{s(s+6)}{(s+3)(s^2+6s+18)}$$
 prob.12.19

syms s t $ilaplace(s*(s+6)/((s+3)*(s^2+6*s+18)))$ ans = -exp(-3*t)+2*exp(-3*t)*cos(3*t)

Theorem:

Initial Value Theorem:

If the function f(t) and its first derivative are Laplace transformable and f(t) Has the Laplace transform F(s), and the $\lim_{s \to \infty} sF(s)$ exists, then

$$\begin{vmatrix}
\lim sF(s) = \lim f(t) = f(0) \\
s \to \infty & t \to 0
\end{vmatrix}$$

Initial Value
Theorem

The utility of this theorem lies in not having to take the inverse of F(s) in order to find out the initial condition in the time domain. This is particularly useful in circuits and systems.

Example: Initial Value Theorem:

Given;

$$F(s) = \frac{(s+2)}{(s+1)^2 + 5^2}$$

Find f(0)

$$f(0) = \lim_{s \to \infty} sF(s) = \lim_{s \to \infty} s \frac{(s+2)}{(s+1)^2 + 5^2} = \lim_{s \to \infty} \left[\frac{s^2 + 2s}{s^2 + 2s + 1 + 25} \right]$$
$$= \lim_{s \to \infty} \frac{s^2/s^2 + 2s/s^2}{s^2/s^2 + 2s/s^2 + (26/s^2)} = 1$$

Theorem:

Final Value Theorem:

If the function f(t) and its first derivative are Laplace transformable and f(t) has the Laplace transform F(s), and the $\lim_{s \to \infty} sF(s)$ exists, then

$$\lim_{s \to 0} sF(s) = \lim_{t \to \infty} f(t) = f(\infty)$$

Final Value Theorem

Again, the utility of this theorem lies in not having to take the inverse of F(s) in order to find out the final value of f(t) in the time domain. This is particularly useful in circuits and systems.

Example: Final Value Theorem:

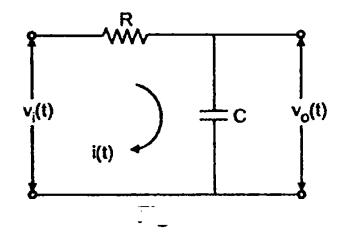
Given:

$$F(s) = \frac{(s+2)^2 - 3^2}{[(s+2)^2 + 3^2]} \quad note \ F^{-1}(s) = te^{-2t} \cos 3t$$

Find $f(\infty)$.

$$f(\infty) = \lim_{s \to 0} sF(s) = \lim_{s \to 0} s \frac{(s+2)^2 - 3^2}{[(s+2)^2 + 3^2]} = 0$$

Example For a system shown in the Fig. . calculate its transfer function where $v_o(t)$ is output and $v_i(t)$ is input to the system.



Solution: We can write for this system, equations by applying KVL as,

$$v_i(t) = R \cdot i(t) + \frac{1}{C} \int i(t) dt \qquad ... (1)$$

and
$$v_o(t) = \frac{1}{C} \int i(t) dt$$
 ... (2)

We are interested in $\frac{V_o(s)}{V_i(s)}$ where $V_o(s)$ is Laplace of $v_o(t)$ and $V_i(s)$ is Laplace of $v_i(t)$ and initial conditions are to be neglected.

So taking Laplace of above two equations and assuming initial conditions zero we can write,

$$V_i(s) = RI(s) + \frac{1}{sC}I(s)$$
 ... (3)

$$V_o(s) = \frac{1}{sC}I(s)$$
 ... (4)

$$I(s) = sCV_o(s)$$

Substituting in equation (3),

$$V_i(s) = sCV_o(s)\left[R + \frac{1}{sC}\right]$$

$$\therefore V_i(s) = sCR V_o(s) + V_o(s) = V_o(s) [1 + sCR]$$

$$\frac{V_o(s)}{V_i(s)} = \frac{1}{1 + sCR}$$

We can represent above system as in the Fig. - which is called transfer function model of the system.

$$V_i(s) \longrightarrow \frac{1}{1 + sRC} \longrightarrow V_o(s)$$