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```
% assignment4.m:  
%
```

ELEC4700, Assignment 4

Author: Jacob Godin Date: 2019/04/21

```
%-----  
  
global G C b;  
  
% Generate G, C, and b matrices  
netlist
```

Part 1

```
%-----  
% a) G, C, and F (b matrix) matrices  
%-----  
fprintf("The G, C, and F matrices:");  
G  
C  
b  
  
%-----  
% b) Plot of Vin vs Vout, DC case  
%-----  
  
% For DC analysis, C = 0  
  
Nrpt = 10000; % Number of points  
OutputNode = 6;  
Vin = linspace(-10,10,Nrpt);  
  
Vout = zeros(1,Nrpt);  
V3 = zeros(1,Nrpt);  
  
for i=1:Nrpt  
    b(7) = Vin(i);
```

```

        x = G\b;

        Vout(i) = x(OutputNode);
        V3(i) = x(3);
    end

    figure('Name','Vin-vs-Vout-and-V3-Response');
    plot(Vin, Vout,'LineWidth',3);
    hold on;
    plot(Vin, V3,'LineWidth',3);
    grid;
    title('Vin vs. Vout/V3', 'FontSize',12);
    xlabel('Vin (Volts)', 'FontSize',20);
    ylabel('Vout (Volts)', 'FontSize',20);
    legend('Vout', 'V3');

    % The relationship between Vout, Vin, and V3 is linear for DC.

    %-----
    % b) Plot of Vout as a function of w, AC case
    %-----

    f = linspace(0,100,Nrpt);

    V1 = zeros(1,Nrpt);

    for i=1:Nrpt
        w = 2*pi*f(i);
        s=1i*w;

        A = G+s.*C;

        x = A\b;

        Vout(i) = x(OutputNode);
        V1(i) = x(1);
    end

    amplitude = Vout./V1;
    gaindB = 20*log10(amplitude);

    figure('Name','Vout-Function-of-w');
    semilogx(f, Vout,'LineWidth',3);
    grid;
    title('Vout as a Function of w', 'FontSize',12);
    xlabel('w', 'FontSize',20);
    ylabel('Vout (Volts)', 'FontSize',20);

    figure('Name','Gain-Function-of-w');
    plot(f, gaindB,'LineWidth',3);
    grid;
    title('Gain as a Function of w', 'FontSize',12);
    xlabel('w', 'FontSize',20);

```

```

ylabel('Gain (dB)', 'FontSize', 20);

%-----
% b) Plot of Vout as a Function Random Pertubations of C
%-----

d = size(G,1);
std = 0.05;
x_plot = zeros(1,Nrpt);
count = 0;

for i=1:Nrpt
    w = 2*pi*f(i);
    s=1i*w;

    for row=1:d
        for col=1:d
            Cn = pi+rand()*std;
            C(row,col) = Cn;
        end
    end

    x_plot(i)=count+1;

    A = G+s.*C;

    x = A\b;

    Vout(i) = x(OutputNode);
    V1(i) = x(1);
end

amplitude = Vout./V1;
gaindB = 20*log10(amplitude);

figure('Name','Gain-Function-of-Random-Pert');
plot(1:Nrpt, gaindB, 'LineWidth', 1);
grid;
title('Gain as a Function of Random Pertubation Count in C
Matrix', 'FontSize', 12);
xlabel('Pertubation Count', 'FontSize', 20);
ylabel('Gain (dB)', 'FontSize', 20);

figure('Name','Hist-Gain-Function-of-Random-Pert');
histogram(abs(gaindB), 25)
grid;
title('Histogram', 'FontSize', 12);
xlabel('Gain (dB)', 'FontSize', 20);
ylabel('Count', 'FontSize', 20);

The G, C, and F matrices:
G =

Columns 1 through 7

```

1.0000	-1.0000	0	0	0	0	1.0000
-1.0000	1.5000	0	0	0	0	0
0	0	0.1000	-0.1000	0	0	0
0	0	-0.1000	0.1000	0	0	0
0	0	0	0	10.0000	-10.0000	0
0	0	0	0	-10.0000	10.0010	0
1.0000	0	0	0	0	0	0
0	1.0000	-1.0000	0	0	0	0
0	0	0	0	1.0000	0	0
0	0	0	1.0000	0	0	0

Columns 8 through 10

0	0	0
1.0000	0	0
-1.0000	0	0
0	1.0000	0
0	0	-1.0000
0	0	0
0	0	0
0	0	0
0	-100.0000	0
0	0	0

C =

Columns 1 through 7

0.2500	-0.2500	0	0	0	0	0
-0.2500	0.2500	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0

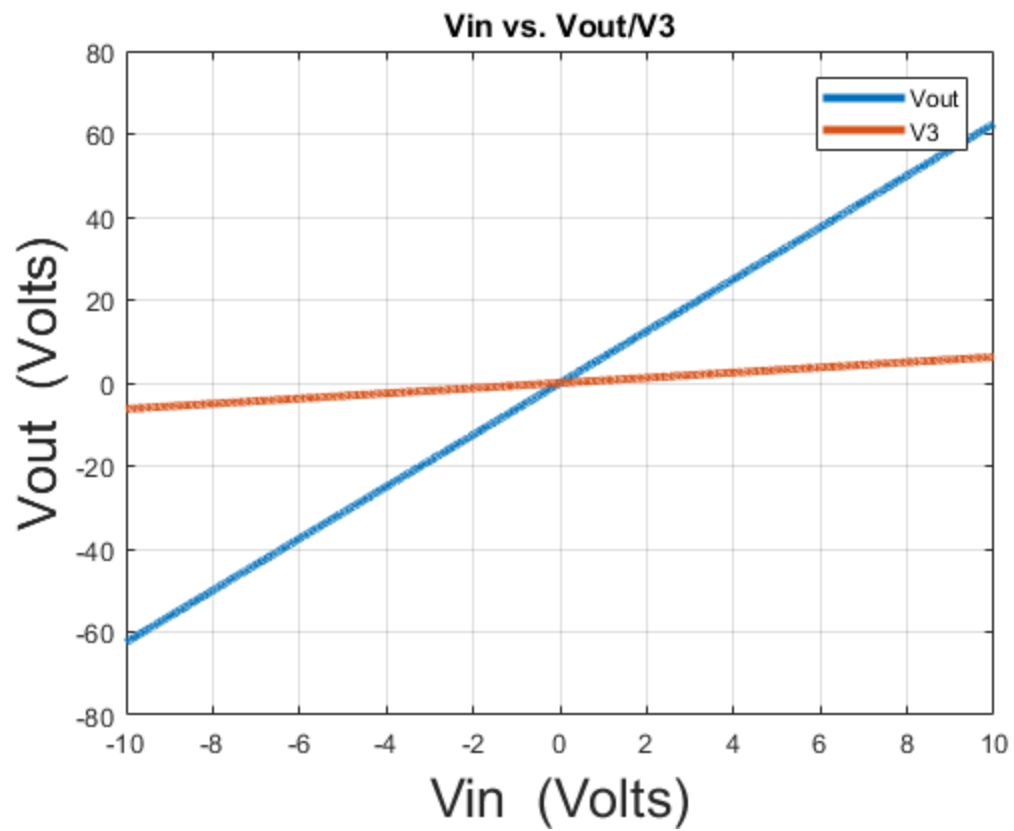
Columns 8 through 10

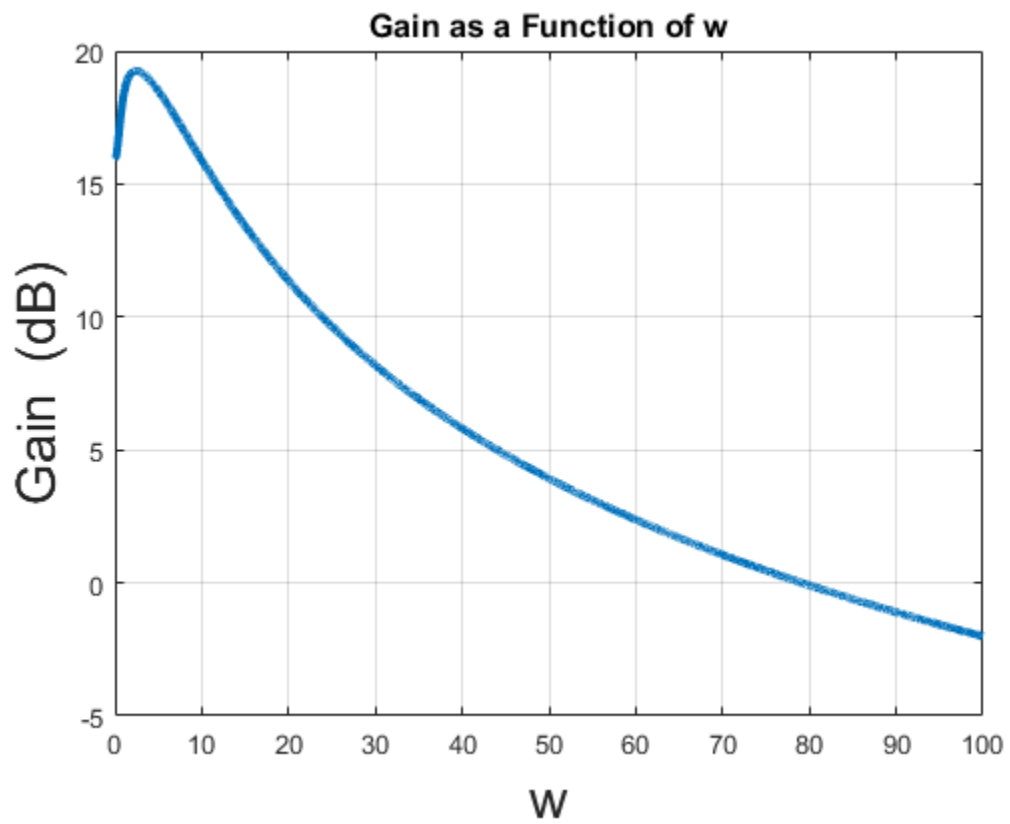
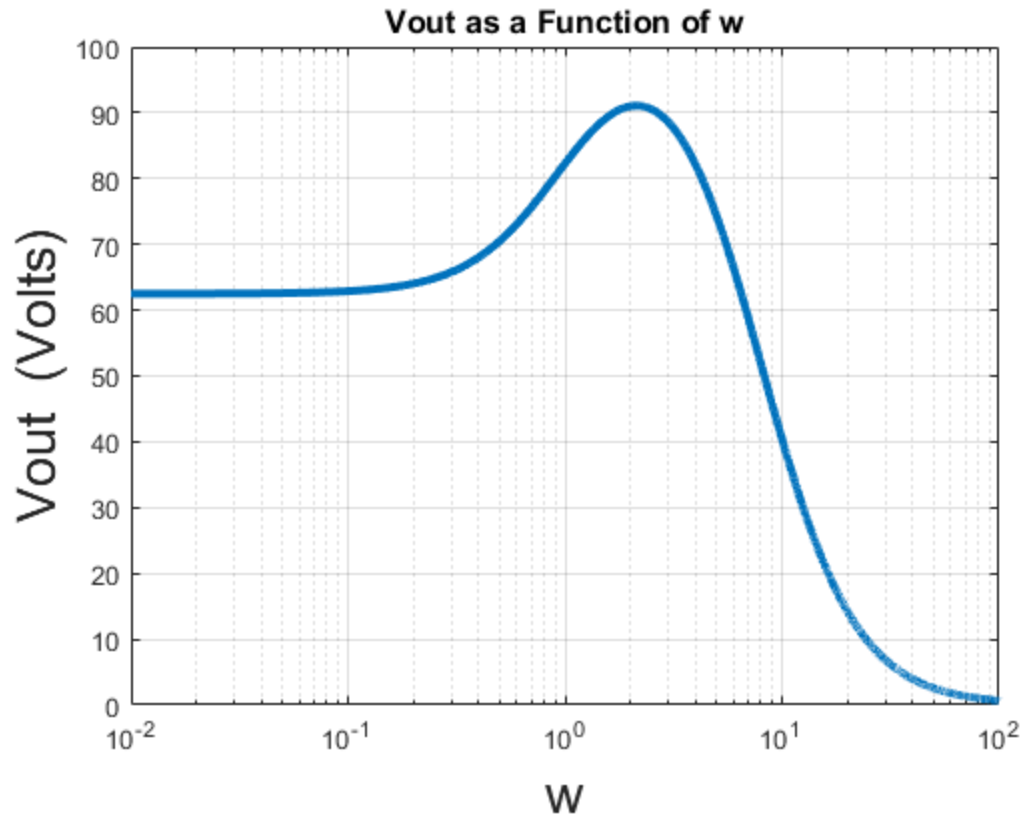
0	0	0
0	0	0
0	0	0
0	0	0
0	0	0
0	0	0
0	0	0
-0.2000	0	0
0	0	0
0	0	0

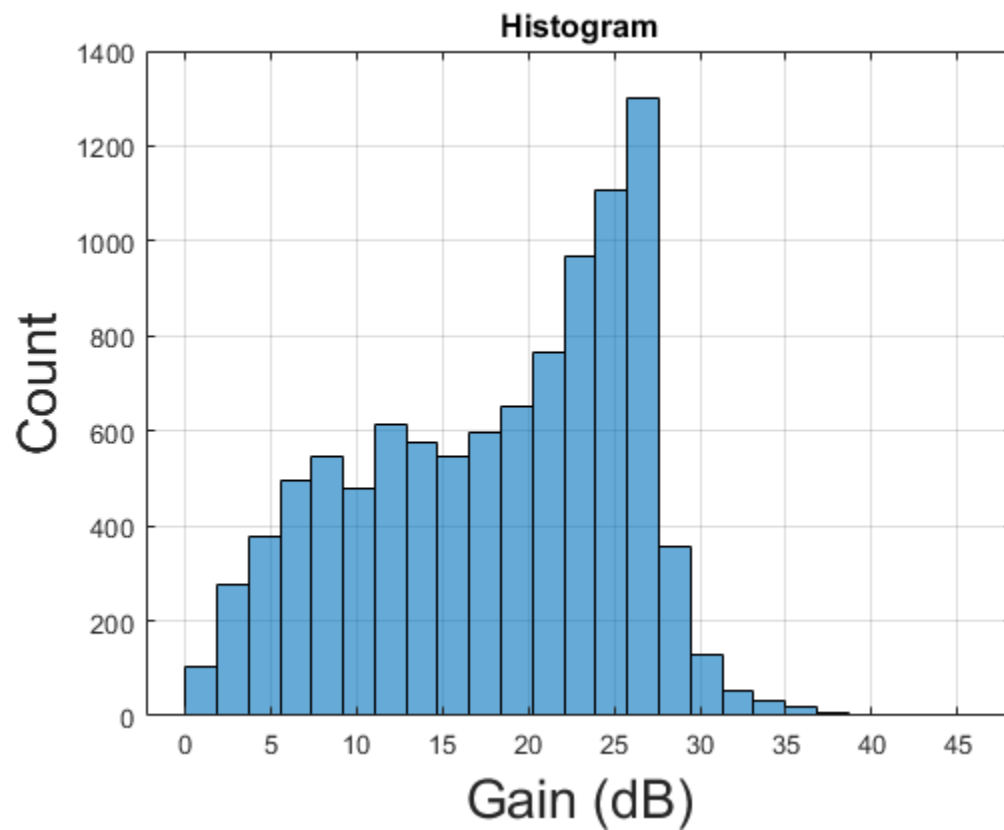
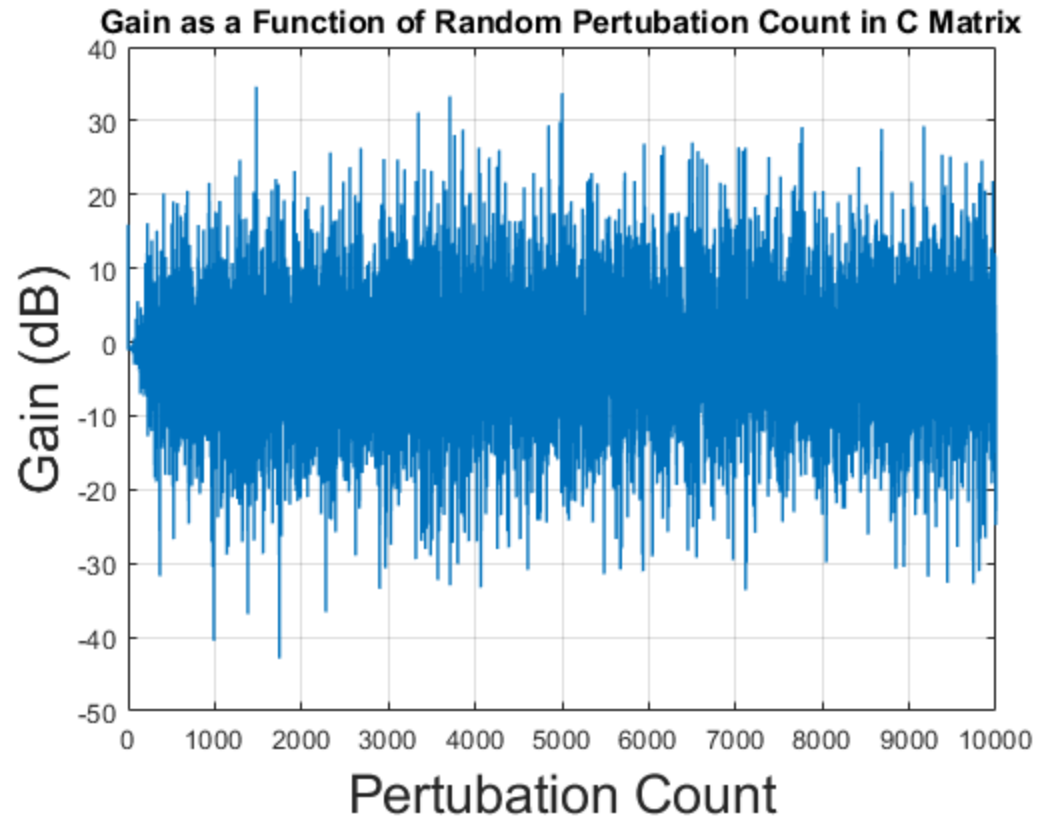
$b =$

0
0
0
0
0
0
0
1
0
0
0

Warning: Imaginary parts of complex X and/or Y arguments ignored
Warning: Imaginary parts of complex X and/or Y arguments ignored
Warning: Imaginary parts of complex X and/or Y arguments ignored







Part 2: Transient Circuit Simulation

```
% The equation can be represented in the finite difference formulation
% by
% the following equation:
%
%  $C(V_{\text{new}} - V_{\text{old}})/\Delta t + G \cdot V = F$ 
%  $V_{\text{new}}(C/\Delta t + G) = F + (C/\Delta t) \cdot V_{\text{old}}$ 

%-----
% d) Circuit Simulation
%-----
netlist % regen circuit

% Step function
Nrpt = 1000;
t_final = 1;
delta_t = t_final/Nrpt;
time_vec = linspace(0,1,Nrpt);

VinStep = zeros(1,Nrpt);
Vold = zeros(length(b),1);
VoutStep = zeros(length(b),1);

OutputNode = 6;
t=0;

for i=1:Nrpt
    if t >= 0.03
        VinStep(i) = 1;
    else
        VinStep(i) = 0;
    end

    b(7) = VinStep(i);

    A = C/delta_t + G;
    B = b + C*Vold/delta_t;
    x = A\B;

    VoutStep(i) = x(OutputNode);

    Vold = x;

    t = t+delta_t;
end

figure('Name','Step-Func-Response');
plot(time_vec, VoutStep,'LineWidth',1);
grid;
hold on;
plot(time_vec, VinStep,'LineWidth',1);
title('Step Function Response', 'FontSize',12);
```

```

xlabel('Time (s)', 'FontSize', 20);
ylabel('Voltage (V)', 'FontSize', 20);
legend('Vout', 'Vin');

F = abs(fftshift(fft(VoutStep)));
magVout = 20*log10(F);

figure('Name', 'Freq-Response');
plot((1:length(F))/Nrpt, magVout, 'LineWidth', 1);
grid;
hold on;

F = abs(fftshift(fft(VinStep)));
magVin = 20*log10(F);

plot((1:length(F))/Nrpt, magVin, 'LineWidth', 1);
title('Frequency Domain Step Function Response', 'FontSize', 12);
xlabel('Frequency (Hz)', 'FontSize', 20);
ylabel('Magnitude', 'FontSize', 20);
legend('Vout', 'Vin');

% Sine function
netlist

f = 1/0.03;

t=0;
VinSin1 = zeros(1, Nrpt);
VoutSin1 = zeros(1, Nrpt);
for i=1:Nrpt
    VinSin1(i) = sin(2*pi*f*t);

    b(7) = VinSin1(i);

    A = C/delta_t + G;
    B = b + C*Vold/delta_t;
    x = A\B;

    VoutSin1(i) = x(OutputNode);

    Vold = x;

    t = t+delta_t;
end

figure('Name', 'Sin-Func-Response');
plot(time_vec, VoutSin1, 'LineWidth', 1);
grid;
hold on;
plot(time_vec, VinSin1, 'LineWidth', 1);
hold on;

f = 1/0.003;

```

```

t=0;
VinSin2 = zeros(1,Nrpt);
VoutSin2 = zeros(1,Nrpt);
for i=1:Nrpt
    VinSin2(i) = sin(2*pi*f*t);

    b(7) = VinSin2(i);

    A = C/delta_t + G;
    B = b + C*Vold/delta_t;
    x = A\B;

    VoutSin2(i) = x(OutputNode);

    Vold = x;

    t = t+delta_t;
end
plot(time_vec, VoutSin2,'LineWidth',1);
hold on;

f = 1/0.3;

t=0;
VinSin3 = zeros(1,Nrpt);
VoutSin3 = zeros(1,Nrpt);
for i=1:Nrpt
    VinSin3(i) = sin(2*pi*f*t);

    b(7) = VinSin3(i);

    A = C/delta_t + G;
    B = b + C*Vold/delta_t;
    x = A\B;

    VoutSin3(i) = x(OutputNode);

    Vold = x;

    t = t+delta_t;
end
plot(time_vec, VoutSin3,'LineWidth',1);
title('Sine Wave Response', 'FontSize',12);
xlabel('Time (s)','FontSize',20);
ylabel('Voltage (V)','FontSize',20);
legend('Vout, f = 33 Hz','Vout, f = 333 Hz','Vout, f = 3.3 Hz','Vin');

F = abs(fftshift(fft(VoutSin1)));
magVout = 20*log10(F);

figure('Name','Freq-Response');
plot((1:length(F))/Nrpt, magVout,'LineWidth',1);
grid;
hold on;

```

```

F = abs(fftshift(fft(VinSin1)));
magVin = 20*log10(F);

plot((1:length(F))/Nrpt, magVin, 'LineWidth',1);
title('Frequency Domain Sine Function Response', 'FontSize',12);
xlabel('Frequency (Hz)', 'FontSize',20);
ylabel('Magnitude', 'FontSize',20);
legend('Vout', 'Vin');

% Gaussian Pulse
netlist
std = 0.03;
mean = 0.06;
VinGaus = gaussmf(linspace(0,1,Nrpt),[std mean]);
VoutGaus = zeros(1,Nrpt);
for i=1:Nrpt
    b(7) = VinGaus(i);

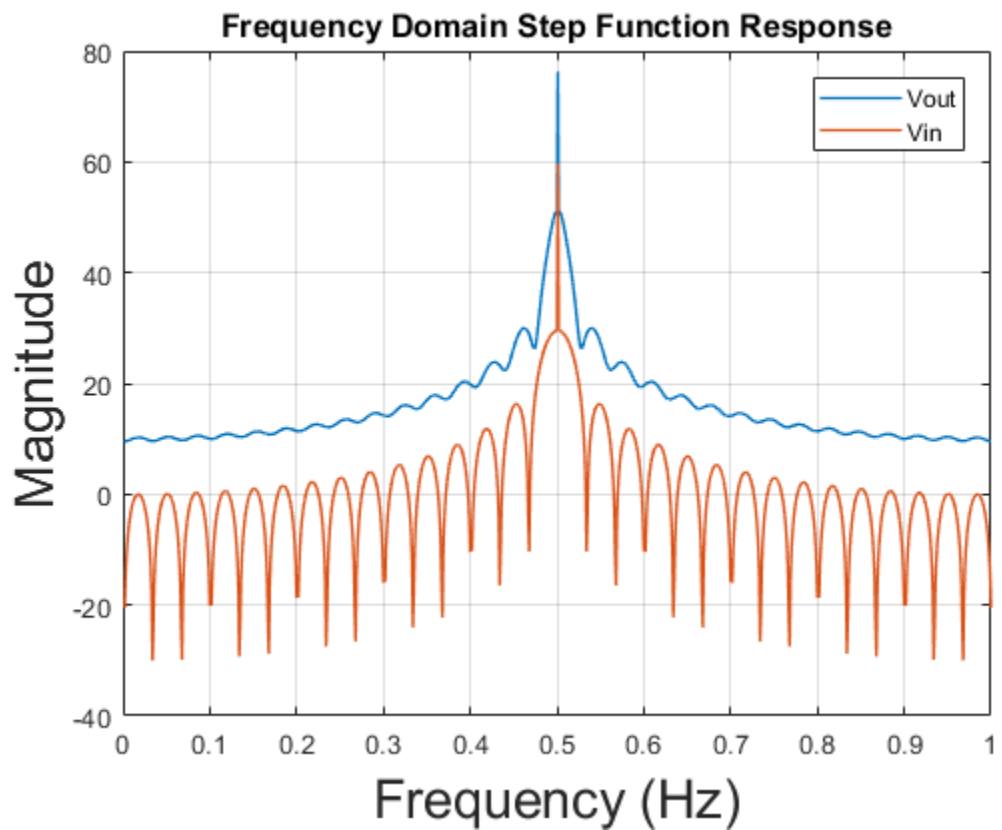
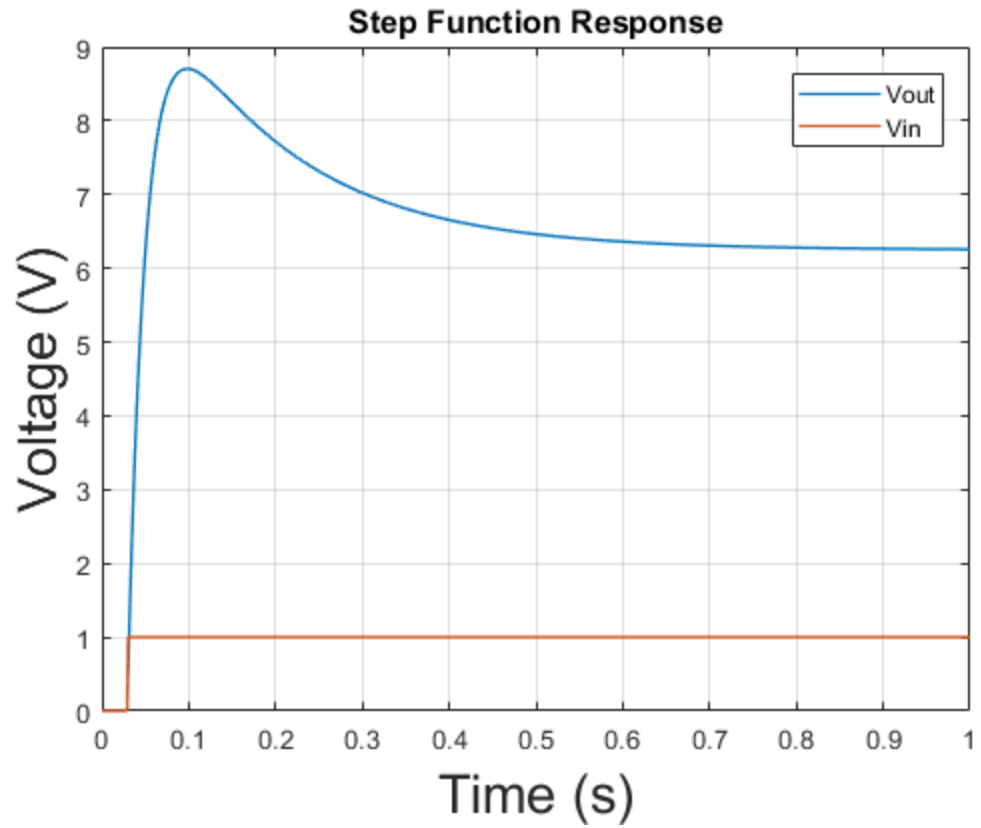
    A = C/delta_t + G;
    B = b + C*Vold/delta_t;
    x = A\B;

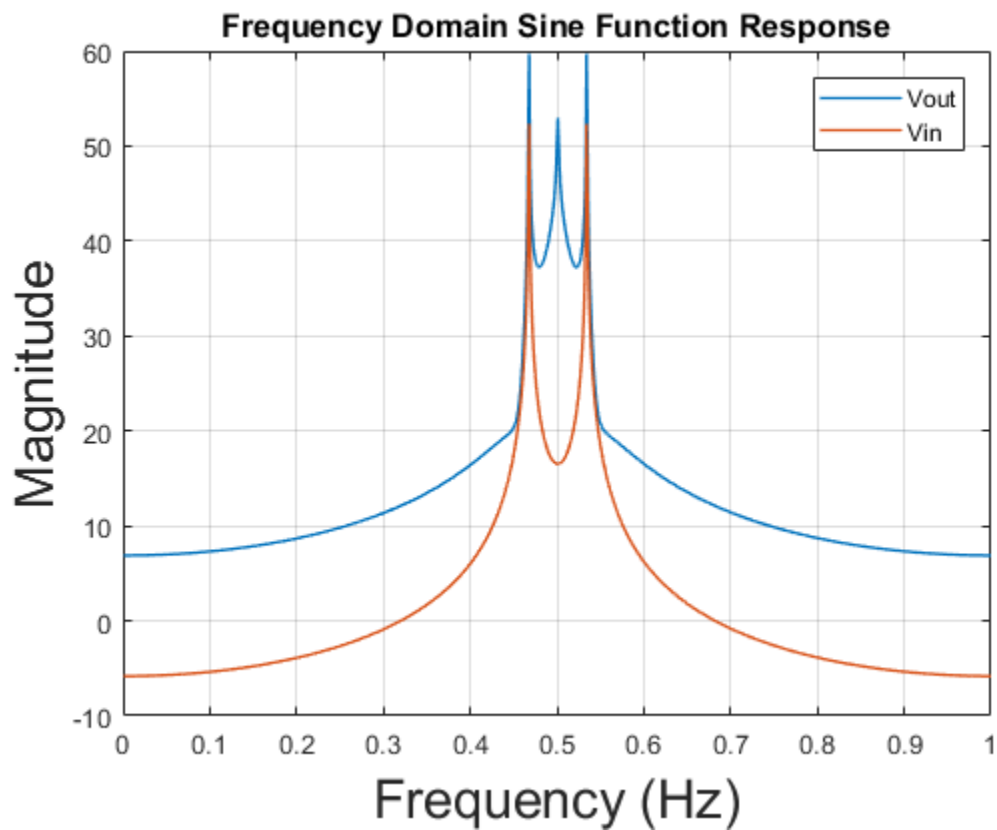
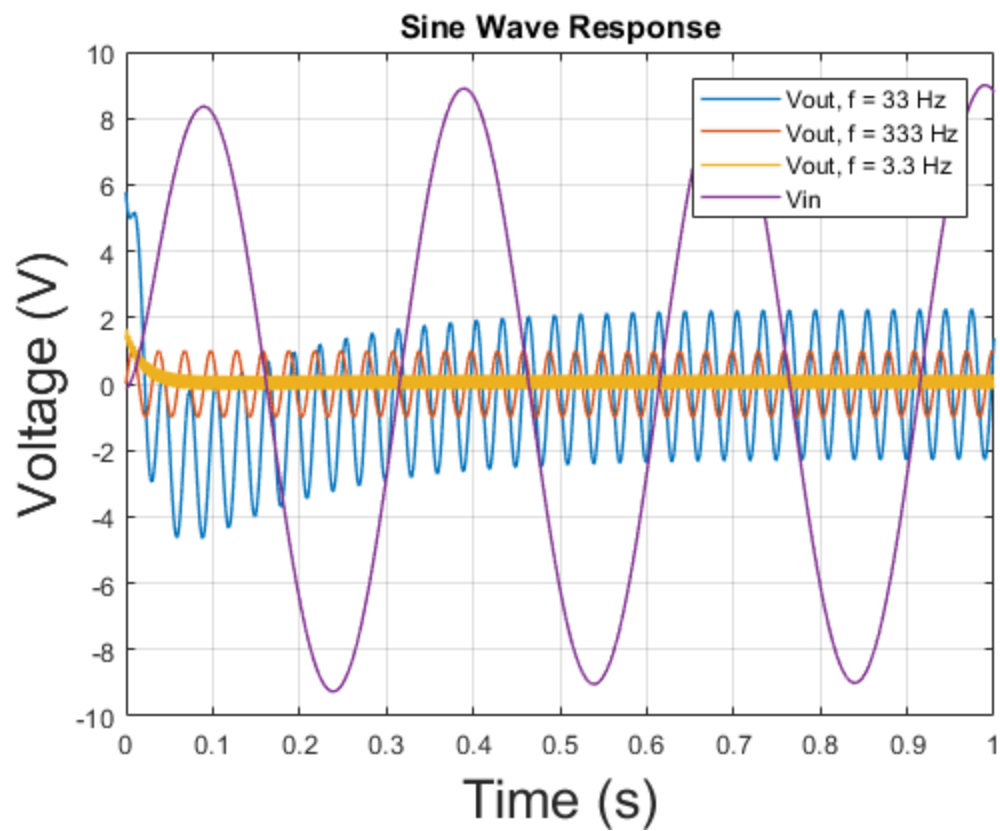
    VoutGaus(i) = x(OutputNode);

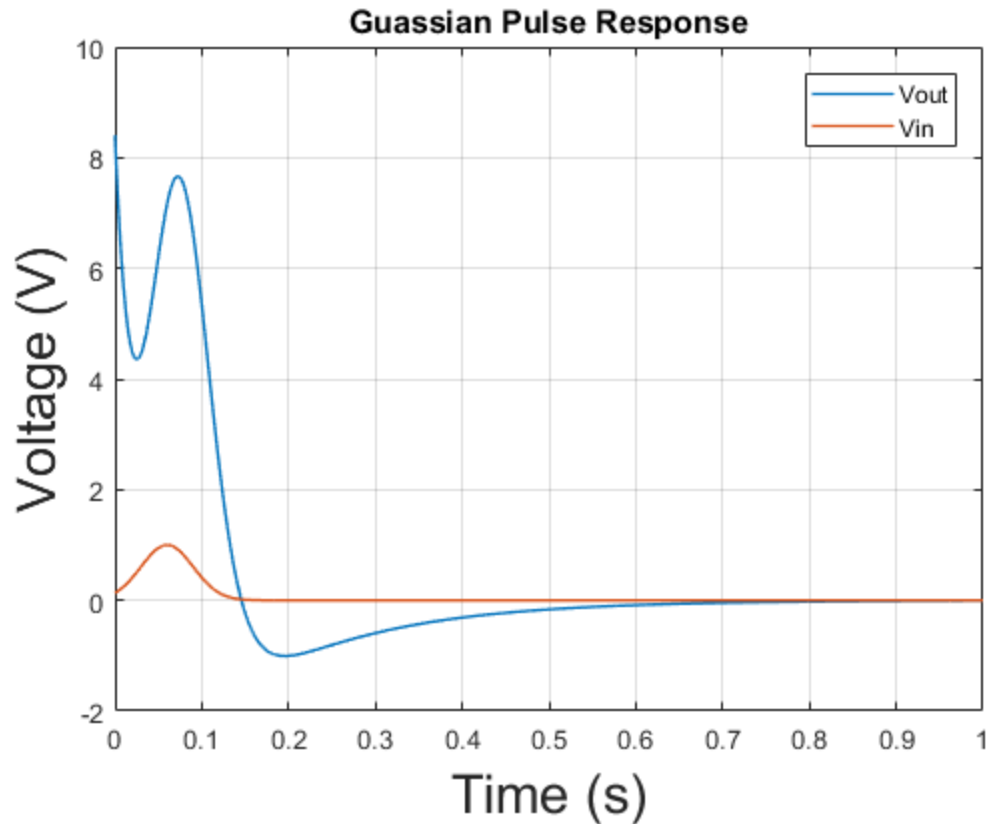
    Vold = x;

    t = t+delta_t;
end
figure('Name', 'Gaus-Response');
plot(time_vec, VoutGaus, 'LineWidth',1);
grid;
hold on;
plot(time_vec, VinGaus, 'LineWidth',1);
title('Guassian Pulse Response', 'FontSize',12);
xlabel('Time (s)', 'FontSize',20);
ylabel('Voltage (V)', 'FontSize',20);
legend('Vout', 'Vin');

```







Part 3: Circuit with Noise

```
netlist % regenerate original C matrix
```

```
%-----  
% a) Add Current Source In to Global MNA Network  
%-----
```

```
cur(3,4,1);
```

```
%-----  
% b) Add Capacitor Cn to Global MNA Network  
%-----
```

```
Cn = 0.0001;  
cap(3,4, Cn);
```

```
fprintf("The updated C matrix:");  
C  
%-----  
% c) Simulation  
%-----
```

```
clear Vout;
```

```

Nrpt = 1000;

% Time variables
t = 1; % s
delta_t = t/Nrpt;
time_vec = linspace(0,1,Nrpt);
% Generate noisy In and Vin
mean = 0.06;
std = 0.03;
InMag = 0.0001;
In = InMag*rand(Nrpt,1);
Vin = gaussmf(linspace(0,1,Nrpt),[std mean]);

Vold = zeros(length(b),1);
Vout = zeros(length(b),1);

OutputNode = 6;

for i=1:Nrpt
    % Overwrite b matrix with noisy Vin
    b(7) = Vin(i);

    % Overwrite b matrix with noisy In
    b(3) = -In(i);
    b(4) = In(i);

    A = C/delta_t + G;
    B = b + C*Vold/delta_t;
    x = A\B;

    Vout(i) = x(OutputNode);
    V1(i) = x(1);

    Vold = x;
end

figure('Name','Gauss-Func-Response');
plot(time_vec, Vout,'LineWidth',1);
grid;
hold on;
plot(time_vec, Vin,'LineWidth',1);
title('Gaussian Function Response', 'FontSize',12);
xlabel('Time (s)', 'FontSize',20);
ylabel('Voltage (V)', 'FontSize',20);
legend('Vout','Vin');

% Using fft function to calculate the spectrum on the output

F = abs(fftshift(fft(Vout)));
magVout = 20*log10(F);

figure('Name','Freq-Response');
plot((1:length(F))/Nrpt, magVout,'LineWidth',1);
grid;

```

```

hold on;

F = abs(fftshift(fft(Vin)));
magVin = 20*log10(F);

plot((1:length(F))/Nrpt, magVin, 'LineWidth',1);
title('Frequency Domain Gaussian Function Response', 'FontSize',12);
xlabel('Frequency (Hz)', 'FontSize',20);
ylabel('Magnitude', 'FontSize',20);
legend('Vout', 'Vin');

% Vary Cn to see how bandwidth changes

% Cn 1
Cn = 0.001;
clear G C b;
netlist;
cap(3,4,Cn);
Vout = generate(G, C, b, Vin, In, Nrpt, delta_t, OutputNode);

F = abs(fftshift(fft(Vout)));
magVout = 20*log10(F);

figure('Name','Freq-Response');
plot((1:length(F))/Nrpt, magVout, 'LineWidth',1);
grid;
hold on;

plot((1:length(F))/Nrpt, magVin, 'LineWidth',1);
title('Frequency Domain Gaussian Function Response, with Cn =
0.001', 'FontSize',12);
xlabel('Frequency (Hz)', 'FontSize',20);
ylabel('Magnitude', 'FontSize',20);
legend('Vout', 'Vin');

% Cn 2
Cn = 1e-10;
clear G C b;
netlist;
cap(3,4,Cn);
Vout = generate(G, C, b, Vin, In, Nrpt, delta_t, OutputNode);

F = abs(fftshift(fft(Vout)));
magVout = 20*log10(F);

figure('Name','Freq-Response');
plot((1:length(F))/Nrpt, magVout, 'LineWidth',1);
grid;
hold on;

plot((1:length(F))/Nrpt, magVin, 'LineWidth',1);
title('Frequency Domain Gaussian Function Response, with Cn =
0.0000000001', 'FontSize',12);
xlabel('Frequency (Hz)', 'FontSize',20);

```

```

ylabel('Magnitude','FontSize',20);
legend('Vout','Vin');

% Cn 3
Cn = 0.01;
clear G C b;
netlist;
cap(3,4,Cn);
Vout = generate(G, C, b, Vin, In, Nrpt, delta_t, OutputNode);

F = abs(fftshift(fft(Vout)));
magVout = 20*log10(F);

figure('Name','Freq-Response');
plot((1:length(F))/Nrpt, magVout,'LineWidth',1);
grid;
hold on;

plot((1:length(F))/Nrpt, magVin,'LineWidth',1);
title('Frequency Domain Gaussian Function Response, with Cn =
    0.01', 'FontSize',12);
xlabel('Frequency (Hz)','FontSize',20);
ylabel('Magnitude','FontSize',20);
legend('Vout','Vin');

% Decreasing Cn produced more noise in the output frequency response.

% Vary timestep
Cn = 0.00001;
clear G C b;
netlist;
cap(3,4,Cn);
Nrpt = 10000;
delta_t = 1/Nrpt;
In = InMag*rand(Nrpt,1);
Vin = gaussmf(linspace(0,1,Nrpt),[std mean]);
Vout = generate(G, C, b, Vin, In, Nrpt, delta_t, OutputNode);
time_vec = linspace(0,1,Nrpt);
figure('Name','Gauss-Func-Response');
plot(time_vec, Vout,'LineWidth',1);
grid;
hold on;
title('Gaussian Function Response With 10000 Time
    Steps', 'FontSize',12);
xlabel('Time (s)','FontSize',20);
ylabel('Voltage (V)','FontSize',20);

Nrpt = 100;
delta_t = 1/Nrpt;
In = InMag*rand(Nrpt,1);
Vin = gaussmf(linspace(0,1,Nrpt),[std mean]);
Vout = generate(G, C, b, Vin, In, Nrpt, delta_t, OutputNode);
time_vec = linspace(0,1,Nrpt);
plot(time_vec, Vout,'LineWidth',1);

```

```

hold on;

Nrpt = 1000;
delta_t = 1/Nrpt;
In = InMag*rand(Nrpt,1);
Vin = gaussmf(linspace(0,1,Nrpt),[std mean]);
Vout = generate(G, C, b, Vin, In, Nrpt, delta_t, OutputNode);
time_vec = linspace(0,1,Nrpt);
plot(time_vec, Vout, 'LineWidth',1);
legend('10000 Steps','100 Steps', '1000 Steps');

% Varying the timestep did not seem to produce a noticeable effect on
the
% noise of the circuit. A larger timestep produced a less accurate
model of
% the transient response.

```

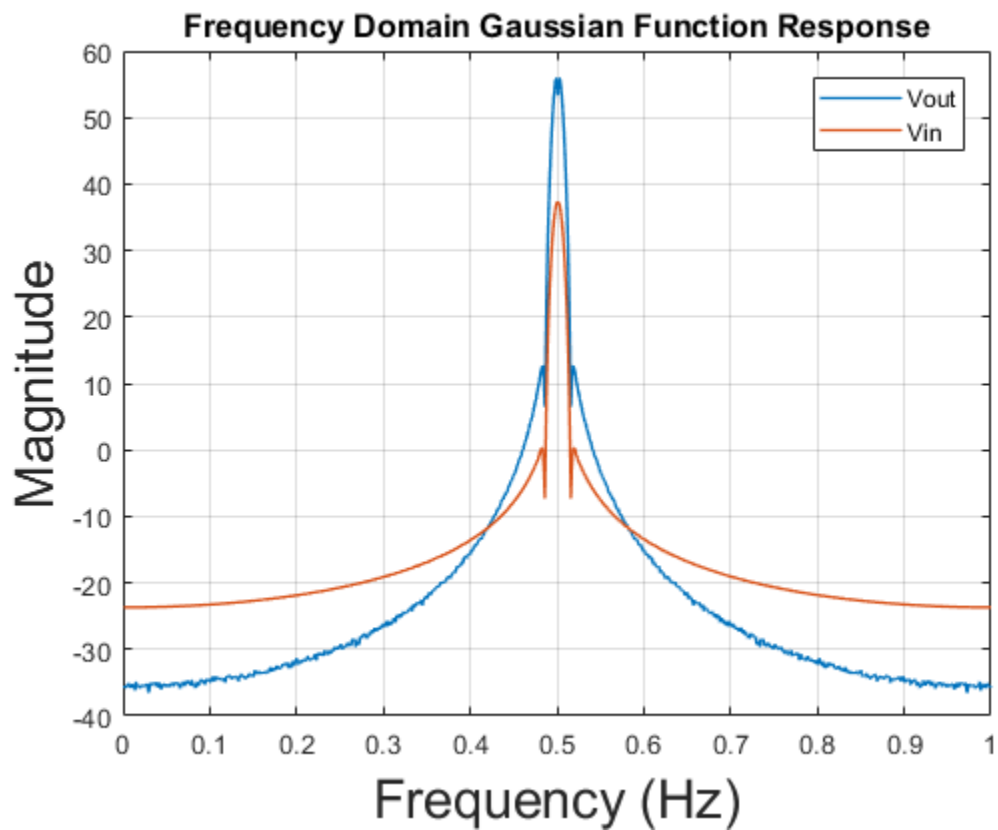
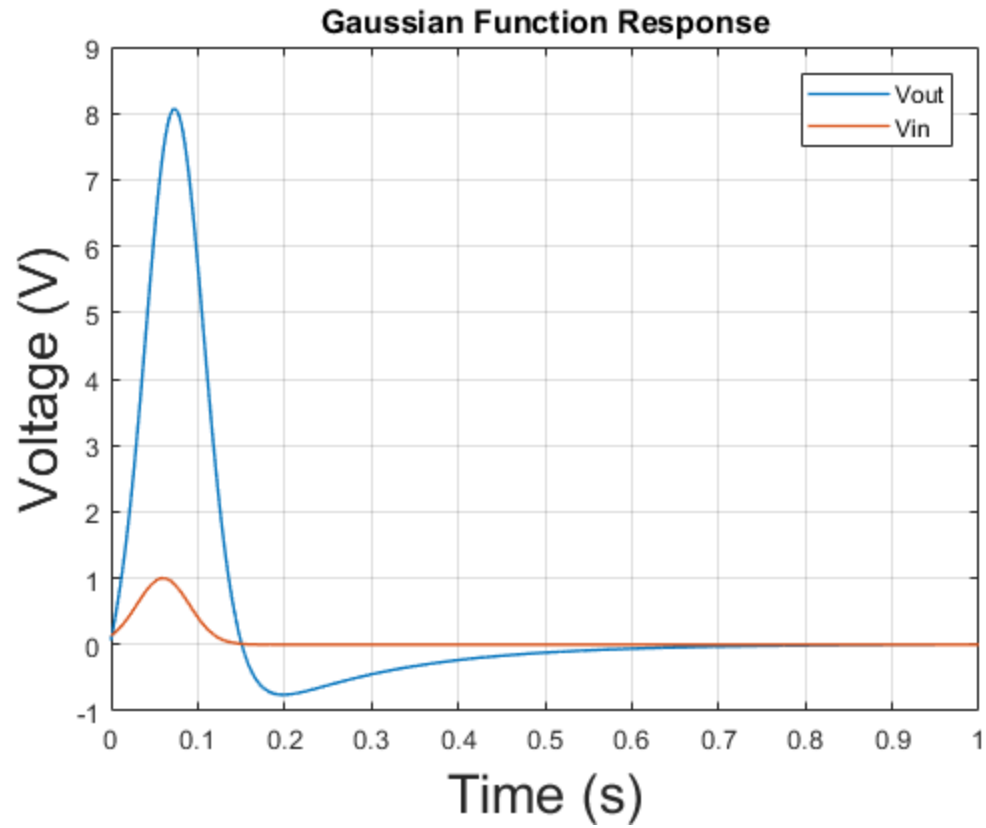
The updated C matrix:
C =

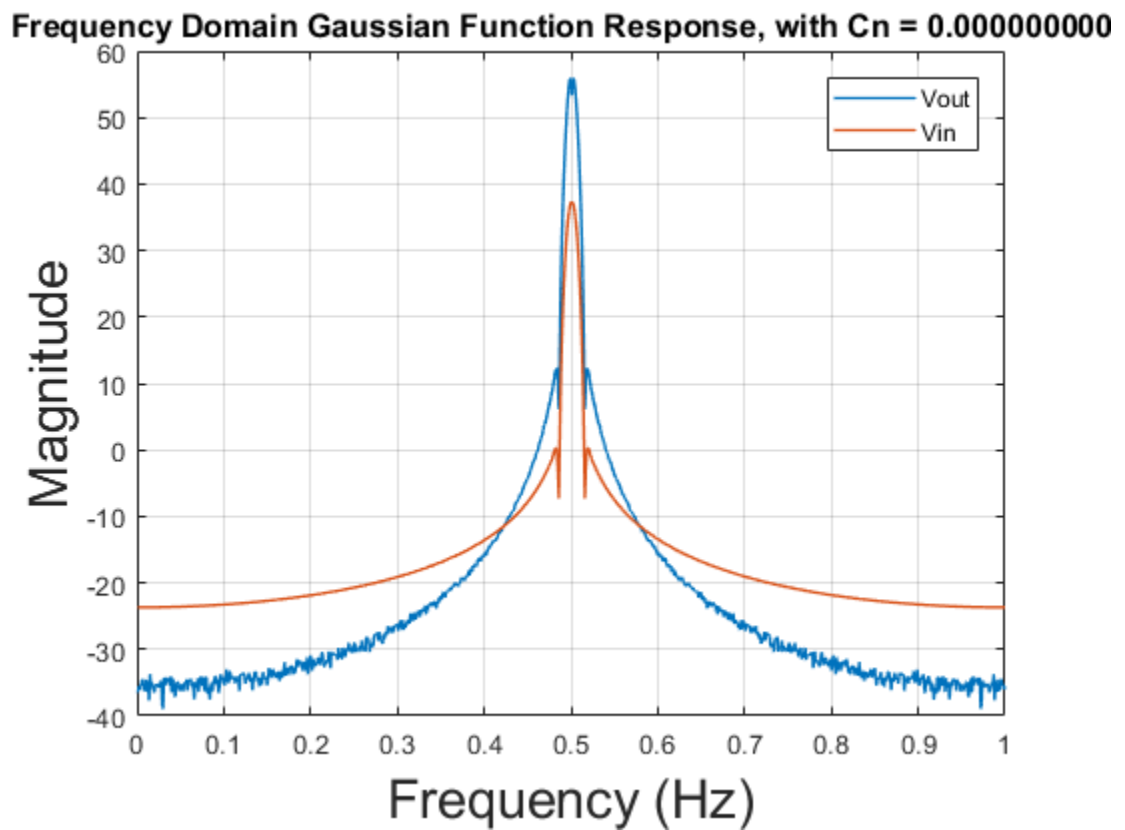
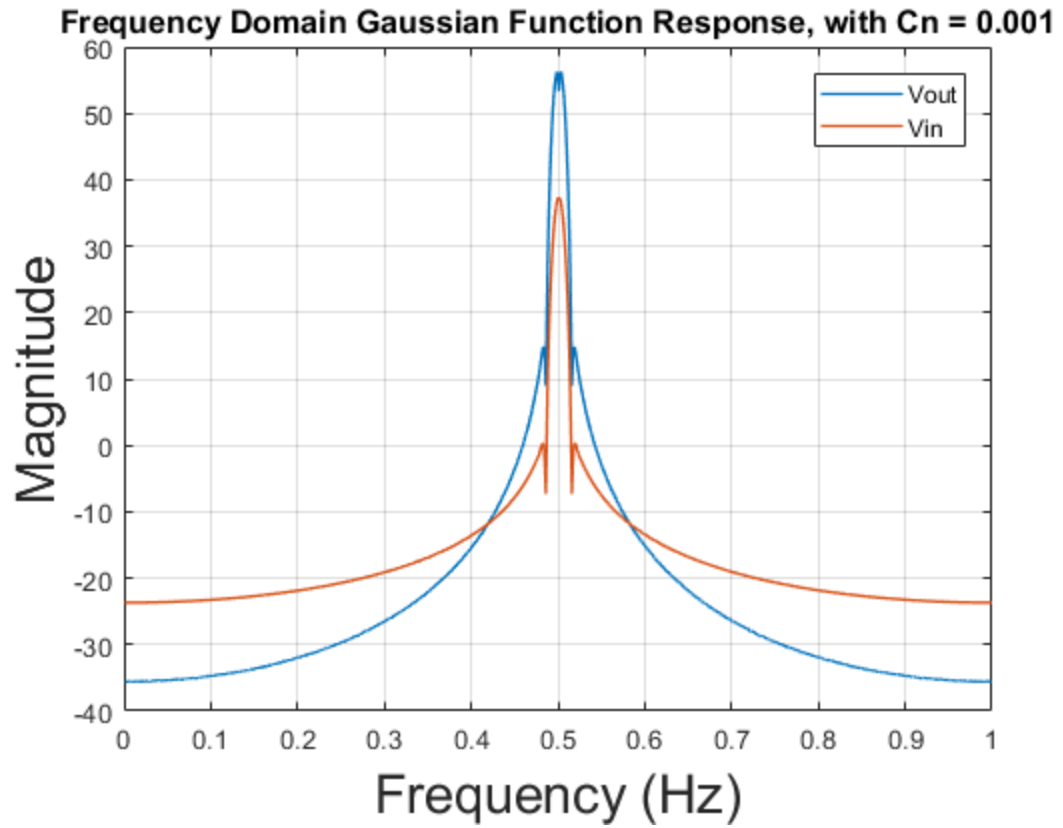
Columns 1 through 7

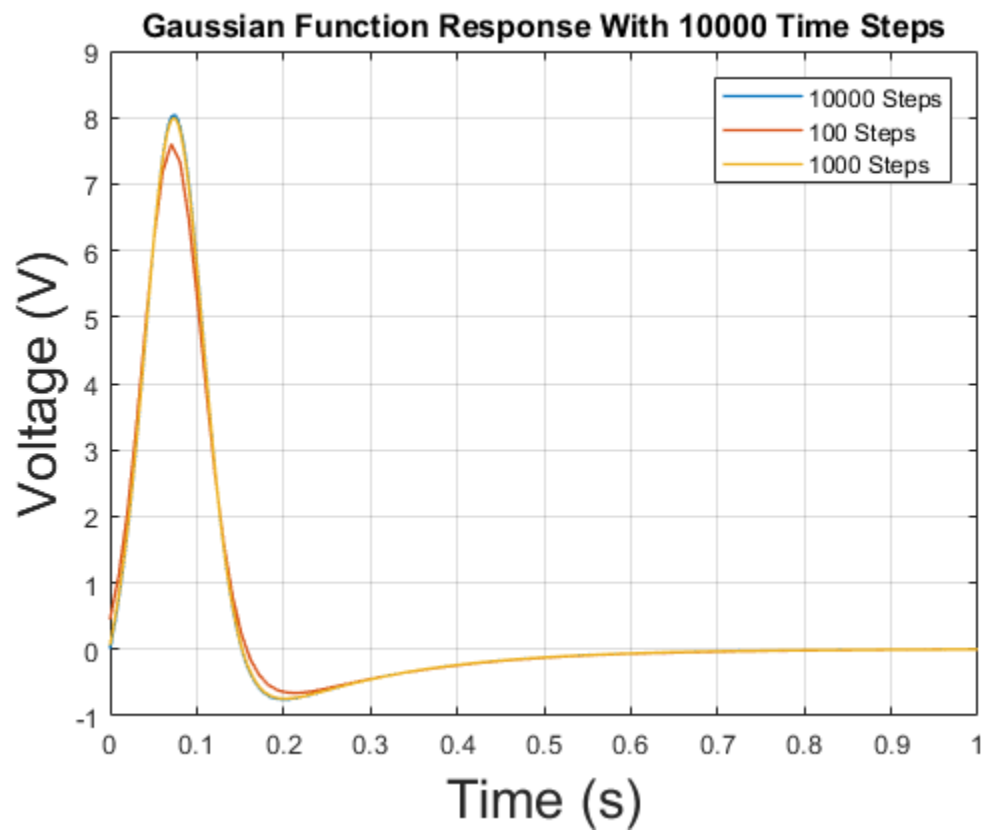
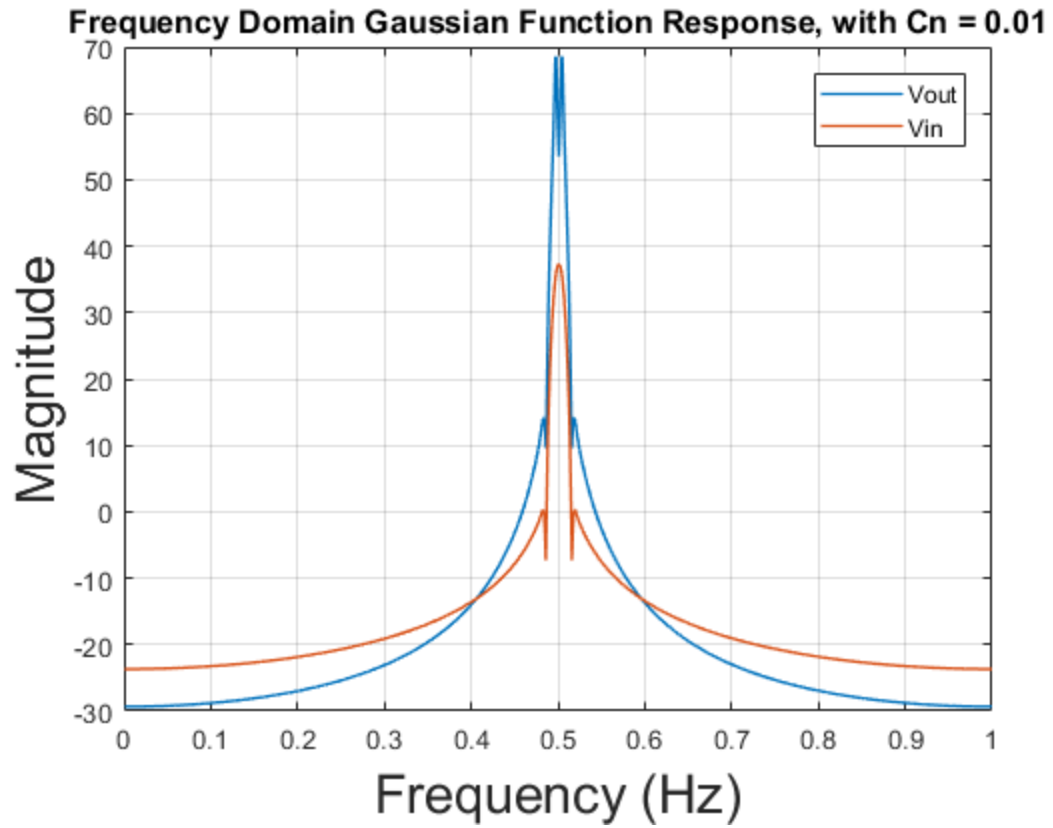
0.2500	-0.2500	0	0	0	0	0
-0.2500	0.2500	0	0	0	0	0
0	0	0.0001	-0.0001	0	0	0
0	0	-0.0001	0.0001	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0

Columns 8 through 10

0	0	0
0	0	0
0	0	0
0	0	0
0	0	0
0	0	0
0	0	0
-0.2000	0	0
0	0	0
0	0	0







Part 4

```
% a) An additional matrix must be added to the time domain equation to  
% solve for a non-linear output.
```

```
% The new MNA equation can be represented by the following
```

```
%  $C \cdot (dV/dt) + GV + F(V) = b(t)$ 
```

```
% b) In order to solve this equation, it must be done iteratively. The  
% Newton-Raphson method can be used to converge on a threshold voltage  
% difference error.
```

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