Practical 5: Hill Climbing

Q1) Demonstrate Hill Climbing Technique.

return [d1[0], d1[1]]

return [d2[0], d2[1]]

return [d3[0], d3[1]]

elif d2[2] == minimum:

elif d3[2] == minimum:

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Ans:
                                  p5 hill climbing.pv
.. .. ..
p5 hill climbing.py
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Practical: 5
Objective: Demonstrate Hill Climbing Technique
import math
increment = 0.5
startingPoint = [1, 1]
point1 = [1,7]
point2 = [6,4]
point3 = [5,2]
point4 = [3,1]
def distance(x1, y1, x2, y2):
    dist = math.pow(x2-x1, 2) + math.pow(y2-y1, 2)
    return dist
def sumOfDistances(x1, y1, px1, py1, px2, py2, px3, py3, px4, py4):
    d1 = distance(x1, y1, px1, py1)
    d2 = distance(x1, y1, px2, py2)
    d3 = distance(x1, y1, px3, py3)
    d4 = distance(x1, y1, px4, py4)
    return d1 + d2 + d3 + d4
def newDistance(x1, y1, point1, point2, point3, point4):
    d1 = [x1, y1]
    d1temp = sumOfDistances(x1, y1, point1[0], point1[1], point2[0], point2[1],
point3[0], point3[1], point4[0], point4[1])
    d1.append(d1temp)
    return d1
def newPoints(minimum, d1, d2, d3, d4):
    if d1[2] == minimum:
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elif d4[2] == minimum:
        return [d4[0], d4[1]]
minDistance = sumOfDistances(
    startingPoint[0], startingPoint[1],
    point1[0], point1[1], point2[0], point2[1],
    point3[0], point3[1], point4[0], point4[1]
flag = True
i = 1
while flag:
    d1 = newDistance(startingPoint[0]+increment, startingPoint[1],
    point1, point2, point3, point4)
    d2 = newDistance(startingPoint[0]-increment, startingPoint[1],
    point1, point2, point3, point4)
    d3 = newDistance(startingPoint[0], startingPoint[1]+increment,
    point1, point2, point3, point4)
    d4 = newDistance(startingPoint[0], startingPoint[1]-increment,
    point1, point2, point3, point4)
    print (i,' ', round(startingPoint[0], 2), round(startingPoint[1], 2))
    minimum = min(d1[2], d2[2], d3[2], d4[2])
    if minimum < minDistance:</pre>
        startingPoint = newPoints(minimum, d1, d2, d3, d4)
        minDistance = minimum
    #print i,' ', round(startingPoint[0], 2), round(startingPoint[1], 2)
    else:
        flag = False
```