

# Problemes Sessió 3



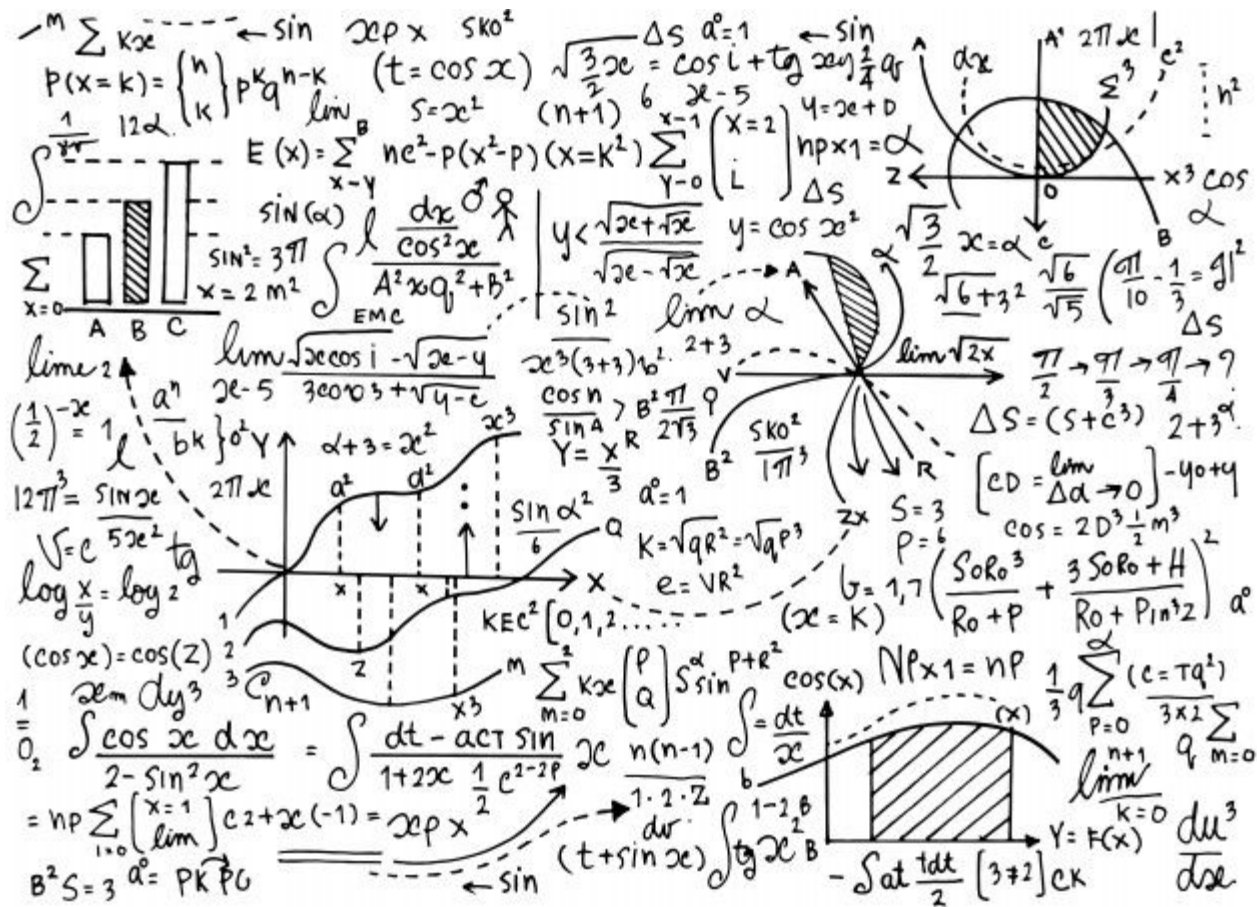
Universitat Autònoma  
de Barcelona

# Outline

## Sessió 2: Classificació

## Sessió 3: Backprop

## Sessió 4: Memorització



## Què es feia abans?

# Outline

Sessió 2: Intro + Classificació

Sessió 3: Nets + Backprop

Sessió 4: KNN + Memorització



Què voldriem fer ara?

# Entregues

Sessió 2: Intro + Classificació

**Regresor Logistic + SVM**

Sessió 3: Nets + Backprop

**Feedforward + CNN**

Sessió 4: KNN + Memorització

**NN search (raw data + features)**

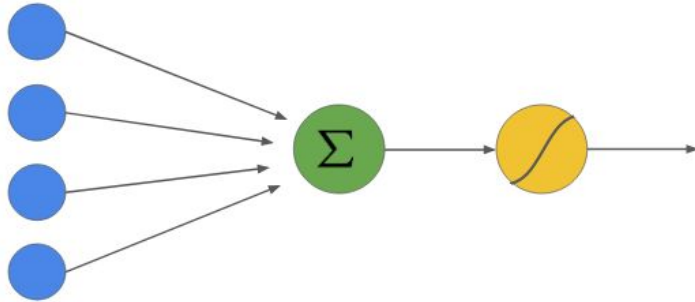


Haureu d'entregar un informe sobre Jupyter Notebook amb el codi explicant el que heu fet

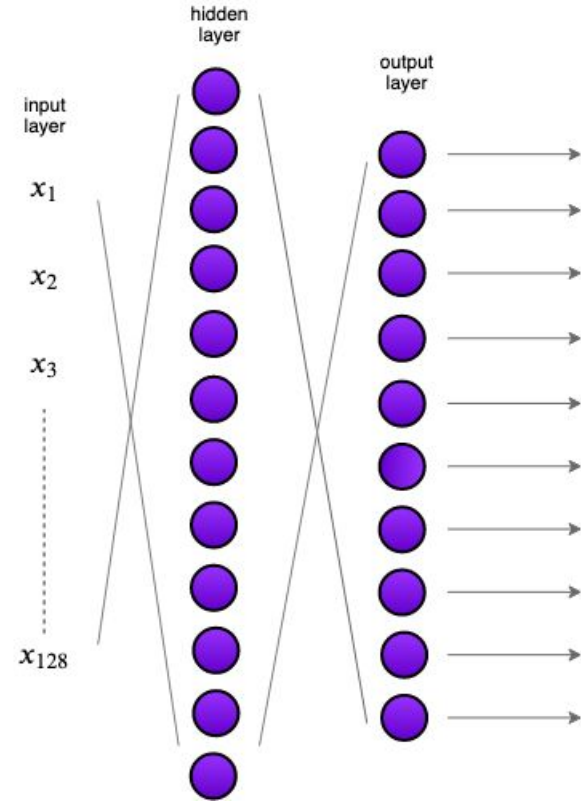
# Sessió 3: Backpropagation

Què permet fer?

# Què farem en aquesta sessió?



Regresor Logistic, SVM...



Perceptró, Multicapa...

# Part 1

Introducció al backprop a través de Autograd

# AUTOGRAD: Automatic Differentiation

Create a tensor and set `requires_grad=True` to track computation with it

```
In [2]: import torch
x = torch.ones(2, 2, requires_grad=True)
print(x)

tensor([[1., 1.],
        [1., 1.]], requires_grad=True)
```

Do a tensor operation:

```
In [3]: y = x + 2
print(y)

tensor([[3., 3.],
        [3., 3.]], grad_fn=<AddBackward0>)
```

`y` was created as a result of an operation, so it has a `grad_fn`.

Do more operations on `y`

```
In [5]: z = y * y * 3
out = z.mean()
print(z, out)

tensor([[27., 27.],
        [27., 27.]], grad_fn=<MulBackward0>) tensor(27., grad_fn=<MeanBackward0>)
```

`.requires_grad_( ... )` changes an existing Tensor's `requires_grad` flag in-place. The input flag defaults to `False` if not given.



# AUTOGRAD: Automatic Differentiation

## Gradients

Let's backprop now. Because `out` contains a single scalar, `out.backward()` is equivalent to `out.backward(torch.tensor(1.))`.

```
In [8]: out.backward()
```

Print gradients  $d(out)/dx$

```
In [9]: print(x.grad)
tensor([[ 4.5000,  4.5000],
        [ 4.5000,  4.5000]])
```

You should have got a matrix of `4.5`. Let's call the `out` Tensor " $o$ "

We have that

$$o = \frac{1}{4} \sum_i z_i$$

where

$$z_i = 3(x_i + 2)^2$$

and

$$z_i|_{x_i=1} = 27$$

Therefore,

$$\frac{\partial o}{\partial x_i} = \frac{3}{2}(x_i + 2)$$

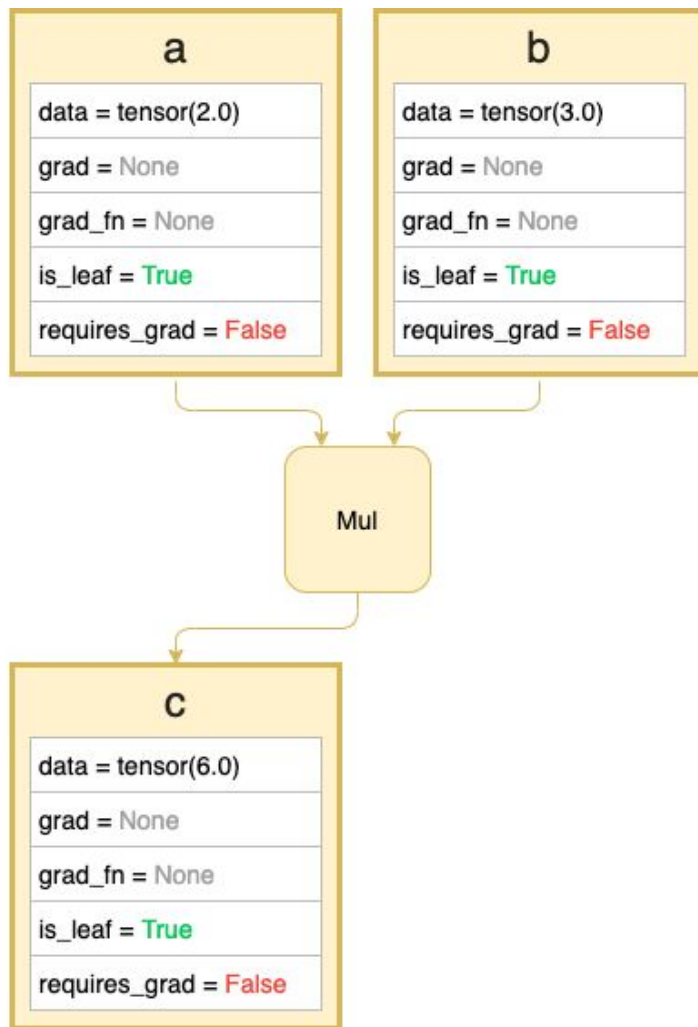
hence

$$\frac{\partial o}{\partial x_i}|_{x_i=1} = \frac{3}{2}(1 + 2) = \frac{9}{2} = 4.5$$

Com funciona autograd internament?

`a = torch.tensor(2.0)`

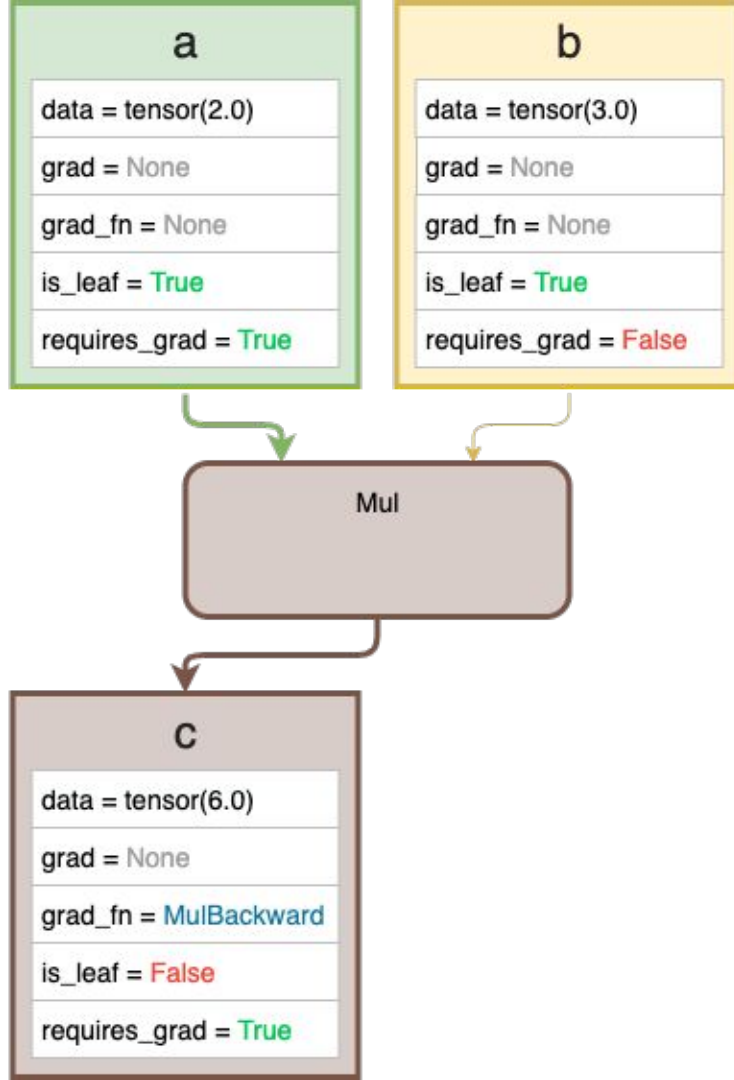
`b = torch.tensor(3.0)`



`c = a * b`

`a = torch.tensor(2.0,  
requires_grad=True)`

`b = torch.tensor(3.0)`

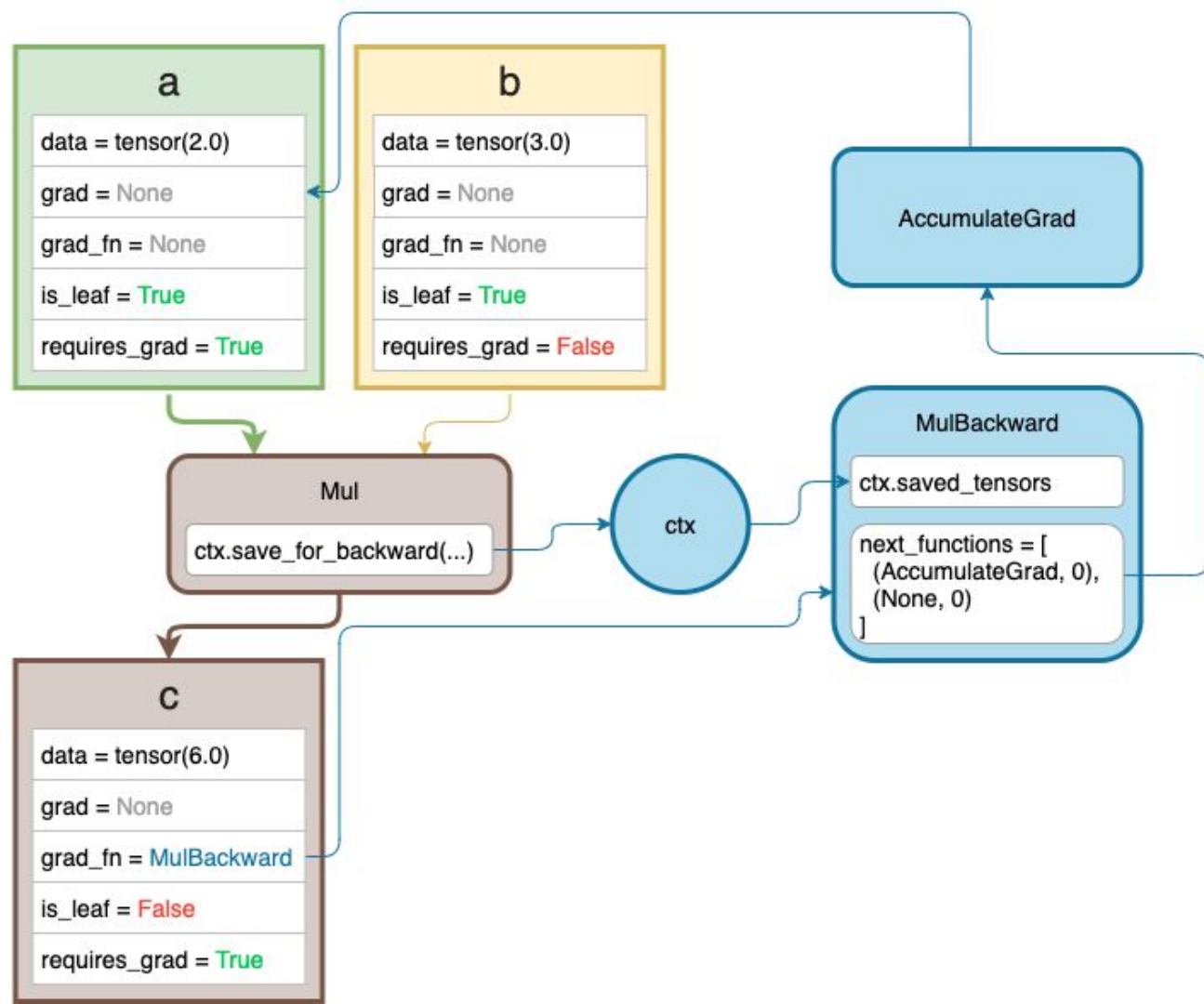


`c = a * b`

`a = torch.tensor(2.0,  
requires_grad=True)`

`b = torch.tensor(3.0)`

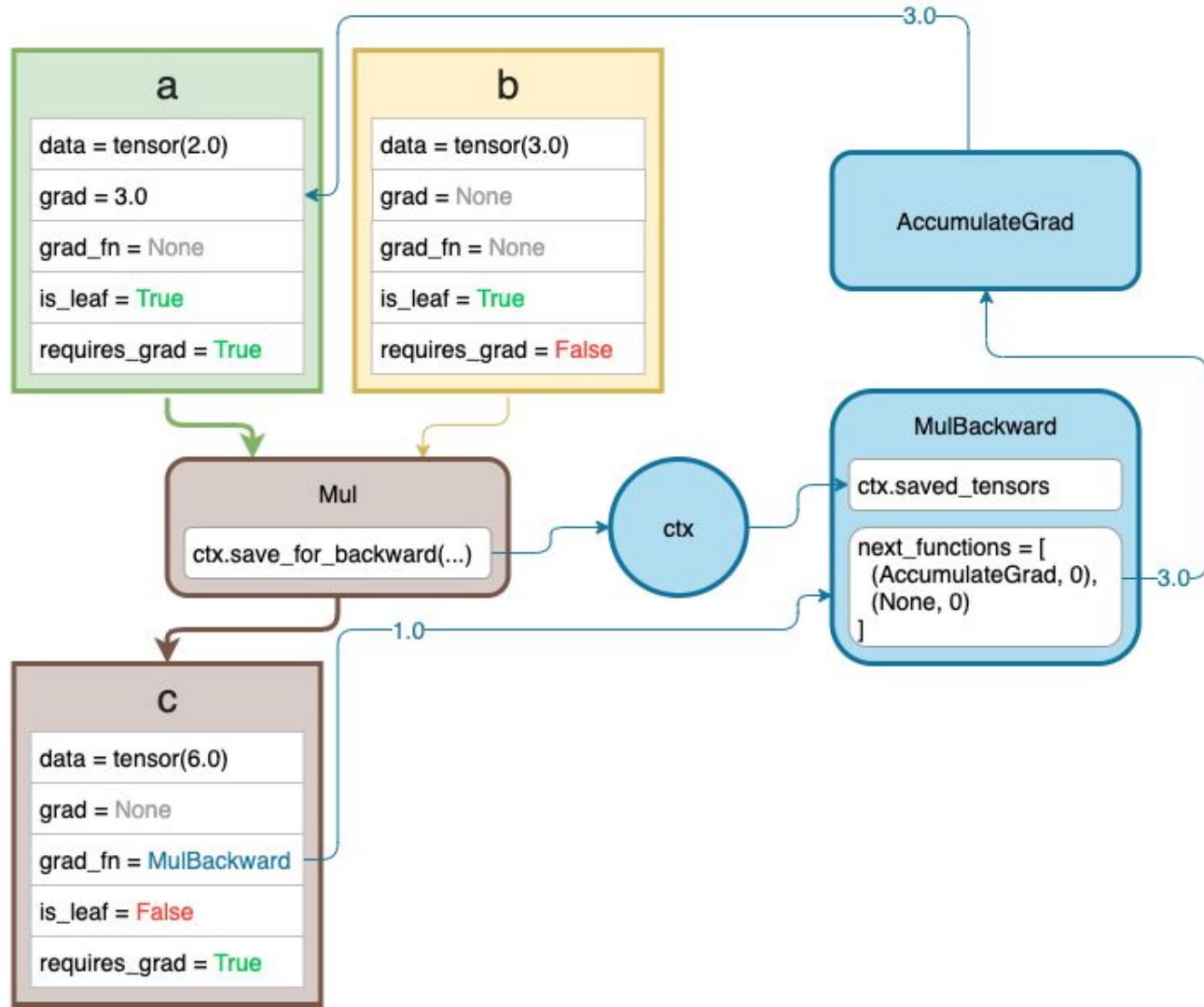
`c = a * b`



`a = torch.tensor(2.0,  
requires_grad=True)`

`b = torch.tensor(3.0)`

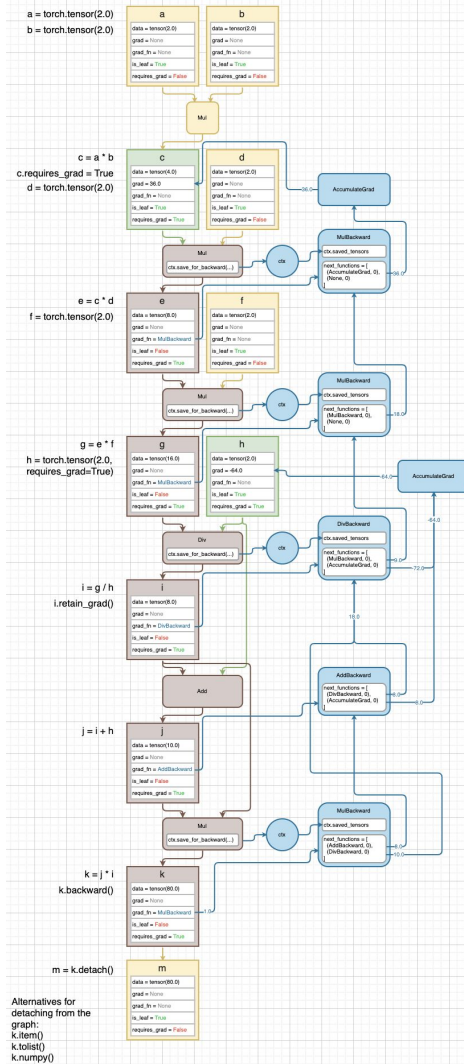
`c = a * b`  
`c.backward()`



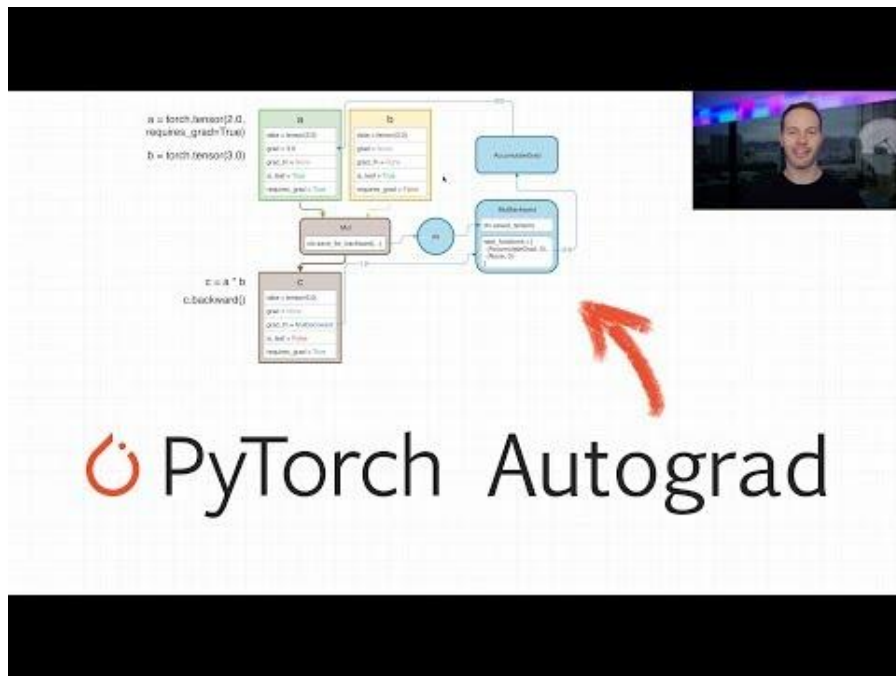
# Com funciona autograd internament

Una mica més complicat..

4 variables  
6 operacions...



# Com funciona autograd internament



Elliot Waite  
2750 suscriptores

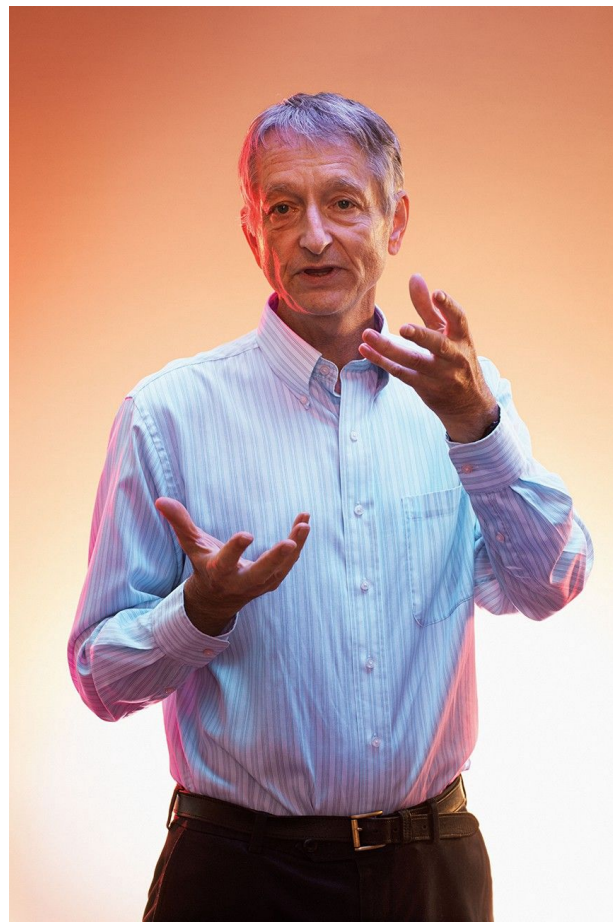
PyTorch Autograd Explained - In-depth Tutorial

<https://www.youtube.com/watch?v=MswxJw-8PvE>

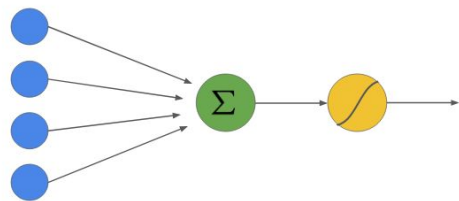


# Què deu passar a la realitat?

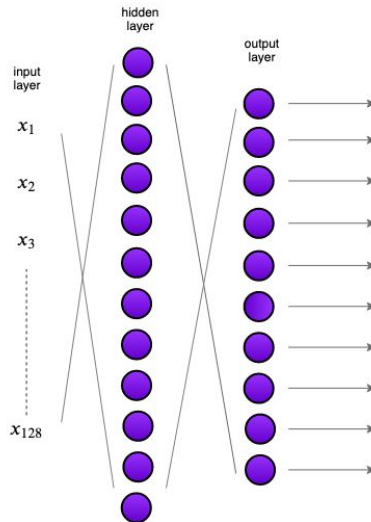
To deal with hyper-planes in a 14-dimensional space, visualize a 3-D space and say 'fourteen' to yourself very loudly. Everyone does it —Geoffrey Hinton



# Què deu passar a la realitat?

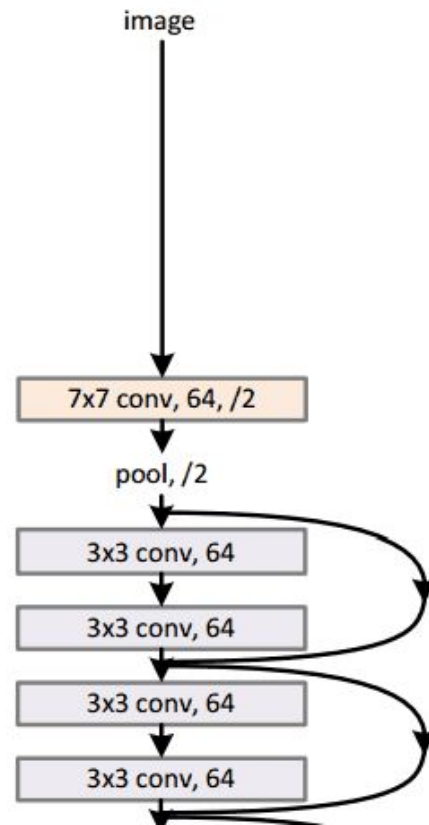


Regresor  
Logistic, SVM...



Perceptró,  
Multicapa...

34-layer residual

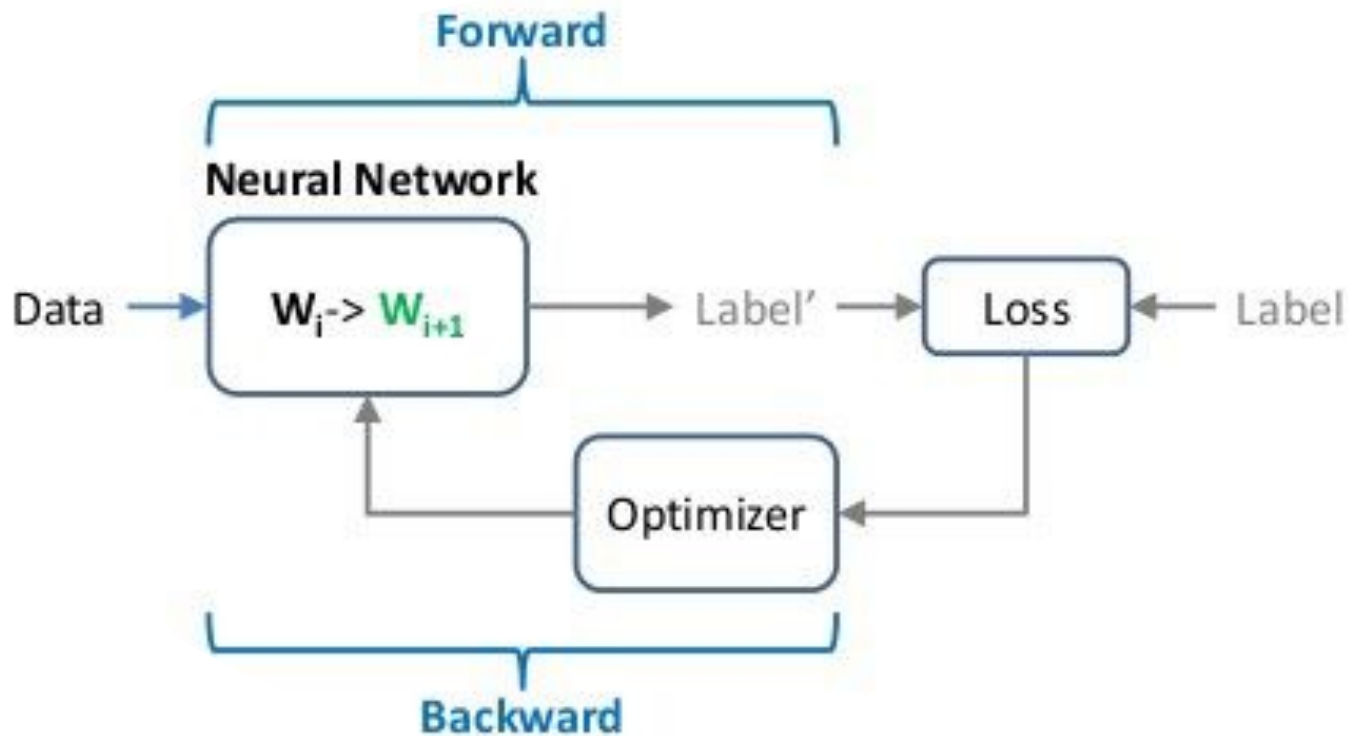


resnet-34 (la ràpida..)

# Part 2

Què haureu de fer?

# Pytorch steps



# Data

Fashion-MNIST

60.000 training samples

10.000 testing samples

each sample is 28x28 pixels

784 dimensions

10 categories

T-Shirt/Top

Trouser

Pullover

Dress

Coat

Sandals

Shirt

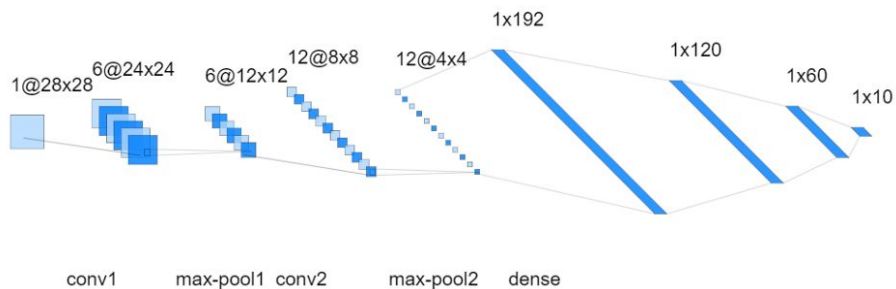
Sneaker

Bag

Ankle boots



# Classificació Multi Categoria amb Pytorch



```
# Build the neural network, expand on top of nn.Module
class Network(nn.Module):
    def __init__(self):
        super().__init__()
        # define layers
        self.conv1 = nn.Conv2d(in_channels=1, out_channels=6, kernel_size=5)
        self.conv2 = nn.Conv2d(in_channels=6, out_channels=12, kernel_size=5)

        self.fc1 = nn.Linear(in_features=12*4*4, out_features=120)
        self.fc2 = nn.Linear(in_features=120, out_features=60)
        self.out = nn.Linear(in_features=60, out_features=10)

    # define forward function
    def forward(self, x):
        # conv 1
        x = self.conv1(x)
        x = F.relu(x)
        x = F.max_pool2d(x, kernel_size=2, stride=2)

        # conv 2
        x = self.conv2(x)
        x = F.relu(x)
        x = F.max_pool2d(x, kernel_size=2, stride=2)

        # fc1
        x = x.reshape(-1, 12*4*4)
        x = self.fc1(x)
        x = F.relu(x)

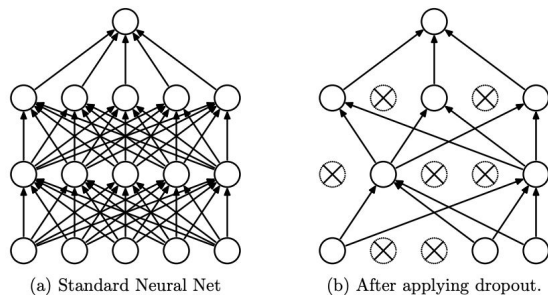
        # fc2
        x = self.fc2(x)
        x = F.relu(x)

        # output
        x = self.out(x)
        # don't need softmax here since we'll use cross-entropy as activation.

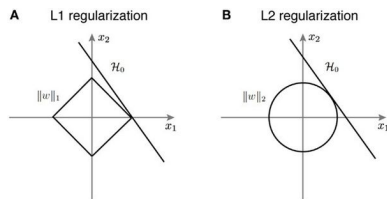
        return x
```

# Regularització

## Dropout



## Lasso (L1) - Ridge (L2. also known as weight decay)



**Batch Normalisation:** Batch Normalisation tends to fix the distribution of the hidden layer values as the training progresses.

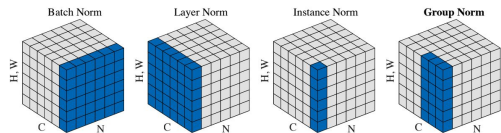
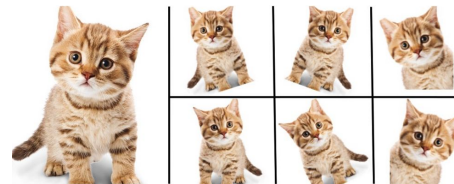


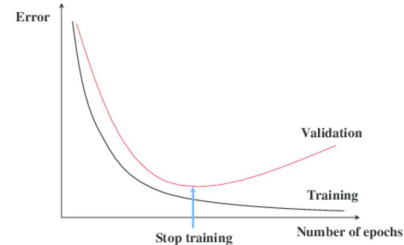
Figure 2. **Normalization methods.** Each subplot shows a feature map tensor, with  $N$  as the batch axis,  $C$  as the channel axis, and  $(H, W)$  as the spatial axes. The pixels in blue are normalized by the same mean and variance, computed by aggregating the values of these pixels.

**More training data:** Adding additional data will add more diversity to the train data and thus reducing the chances of overfitting .

**Data Augmentations:** It aids in increasing the variety of data for training models thus increasing the breadth of available information.



**Early stopping:** It implies to stop training of the model early before it reaches overfitting stage. Performance metrics (eg. accuracy, loss) can monitored for train and validation sets to implement this.



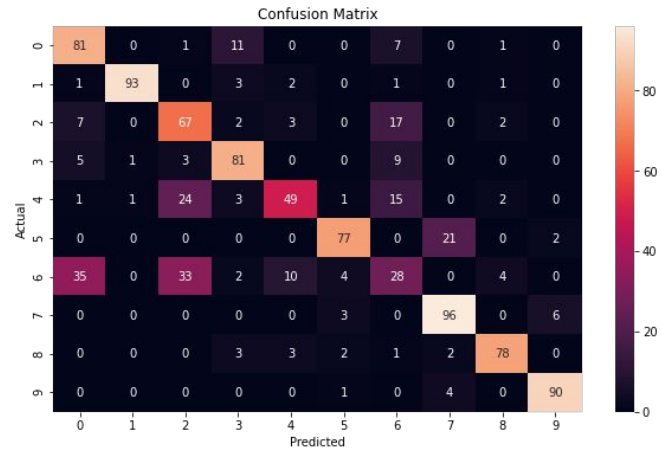
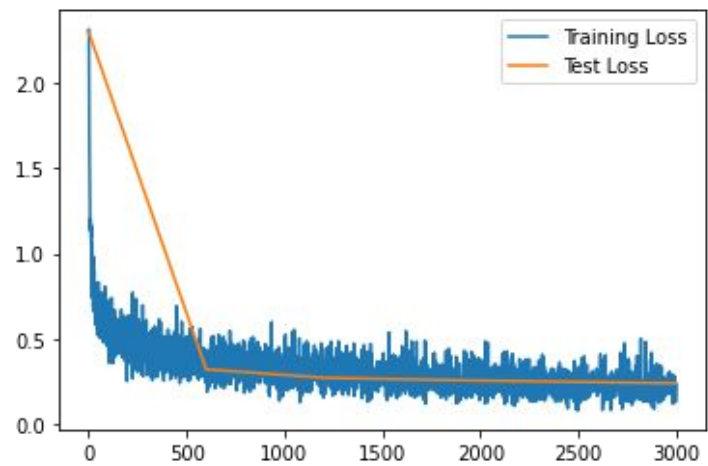
Méthode	Détail	Accuracy Test	Temps Train	Temps Test
SVC	{"C":10,"kernel":"poly"}	0.897	1:12:39	?
RandomForestClassifier	{"criterion":"entropy","max_depth":50,"n_estimators":100}	0.879	0:08:39	?
MLPClassifier	{"activation":"relu","hidden_layer_sizes":[100]}	0.877	0:16:03	?
KNeighborsClassifier	{"n_neighbors":5,"p":1,"weights":"distance"}	0.860	0:41:53	?
LinearSVC	{"C":1,"loss":"hinge","multi_class":"ovr","penalty":"l2"}	0.837	0:44:59	?
2 Conv	<100K parameters	0.925	?	?
MobileNet	augmentation (horizontal flips)	0.950	?	?
ResNet18	Normalization, random horizontal flip, random vertical flip, random translation, random rotation.	0.949	?	?
WRN40-4 8.9M params	standard preprocessing (mean/std subtraction/division) and augmentation (random crops/horizontal flips)	0.967	?	?
Google AutoML	24 compute hours (higher quality)	0.939	24h	?



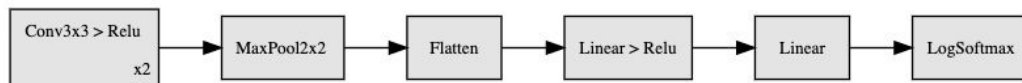
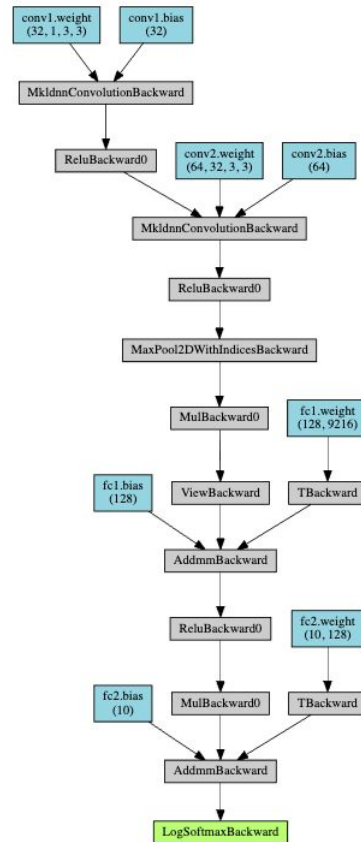
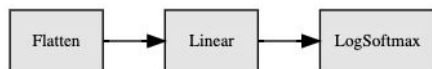
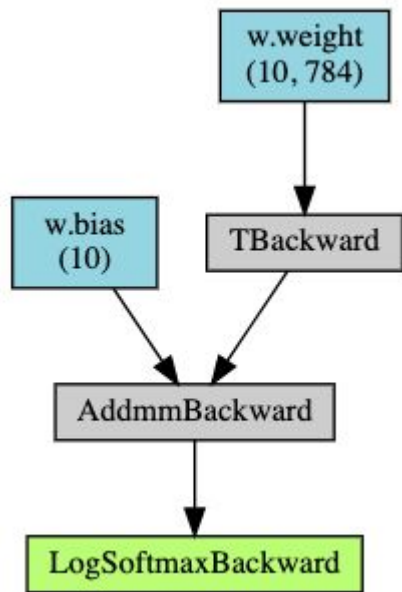
# Entrega

- A. Fes varis entrenaments amb diferents models. **(5pts)**
  - Utilitza els 4 models aquí definits.
  - **Defineix 3 nous models diferents, explica'ls i entrena'ls.** Pots crear-ne de simples, de més complexes, treure poolings o afegir-ne, modificar el percentatge de regularització del dropout, canviar la funció d'activació, buscar altres definicions per Internet, altres tipus de capes, amb més o menys neurones per capa, capes residuals, provar d'agafar-ne alguna de pre-entrenada... Podeu provar altres configuracions d'entrenament, més o menys èpoques, diferent learning rate, diferent optimitzador, afegir weight\_decay....
- B. **Mostra les corbes d'aprenentatge** de cadascun d'ells i compara-les amb les aquí definides. (7 en total) **(2pts)**
  - Per cada model, mostra la loss d'entrenament i la de test en una mateixa gràfica.
  - Mostra les matrius de confusió del model de la última època sobre el conjunt de test.
- C. **Mostra els models**, parametres, flops teòrics i temps real dels models **(3pts)**
  - Us he deixat varies funcions que us mostren els models. Haureu d'instal·lar les llibreries corresponents:
    - [thop](#) per mostrar número de parametres i flops (o macs)..
    - [hiddenlayer](#) i [torchviz](#). Per mostrar els graphs. Aquestes també requereixen tenir instal·lat [graphviz](#)

B.



C.



C.

1% of the DATA training  
10% of the DATA testing

Net	Details	Elapsed Time	Accuracy Test	Flops	Params
Net_Linear	1 capa lineal	1.03s	66.5%		
LeNet_tiny	4 vegades més petita que LeNet	1.95s	55.0%		
LeNet	La que es feia servir per MNIST	6.15s	73.7%		
FashionCNN	d'un de kaggle.. (similar a LeNet + batchnorm)	4.75s	72.8%		
X1					
X2					
X3					

C.

10% of the DATA training  
10% of the DATA testing

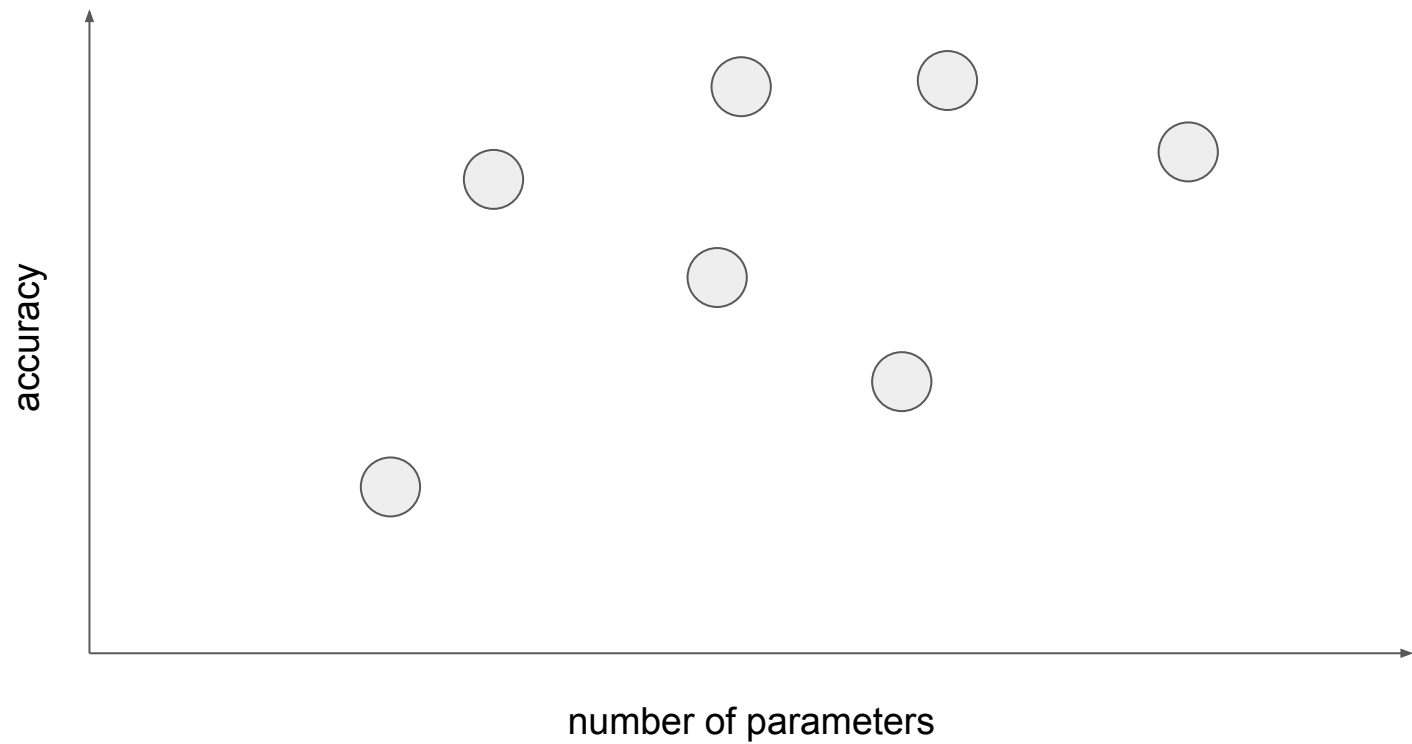
Net	Details	Elapsed Time	Accuracy Test	Flops	Params
Net_Linear	1 capa lineal	3.7s	80.2%		
LeNet_tiny	4 vegades més petita que LeNet	7.7s	79.8%		
LeNet	La que es feia servir per MNIST	30.9s	83.7%		
FashionCNN	d'un de kaggle.. (similar a LeNet + batchnorm)	27.4s	83.7%		
X1					
X2					
X3					

C.

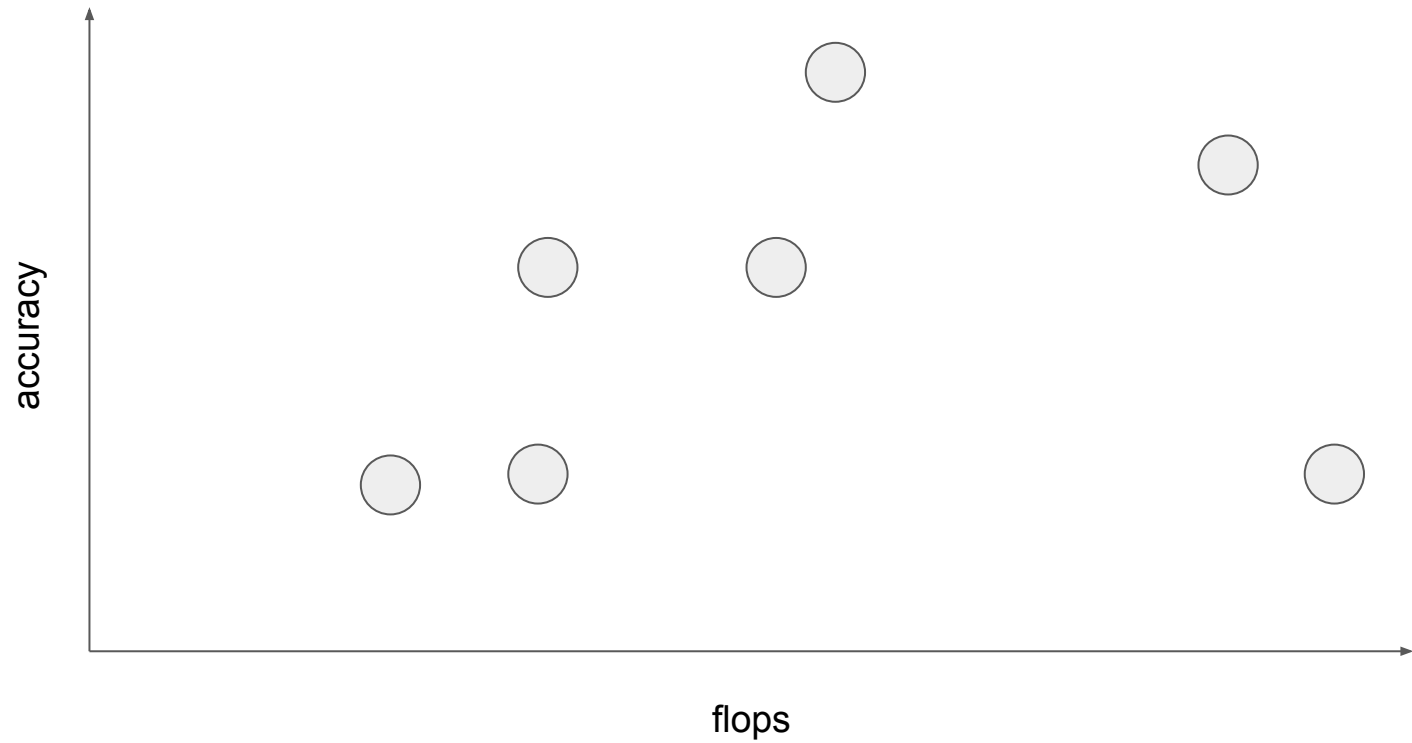
100% of the DATA training  
100% of the DATA testing

Net	Details	Elapsed Time	Accuracy Test	Flops	Params
Net_Linear	1 capa lineal	58.4s (~1min)	83.7%		
LeNet_tiny	4 vegades més petita que LeNet	129.2s (~2min)	87.4%		
LeNet	La que es feia servir per MNIST	536.0s (~9min)	91.2%		
FashionCNN	d'un de kaggle.. (similar a LeNet + batchnorm)	454.7s (~8min)	89.7%		
X1					
X2					
X3					

C.

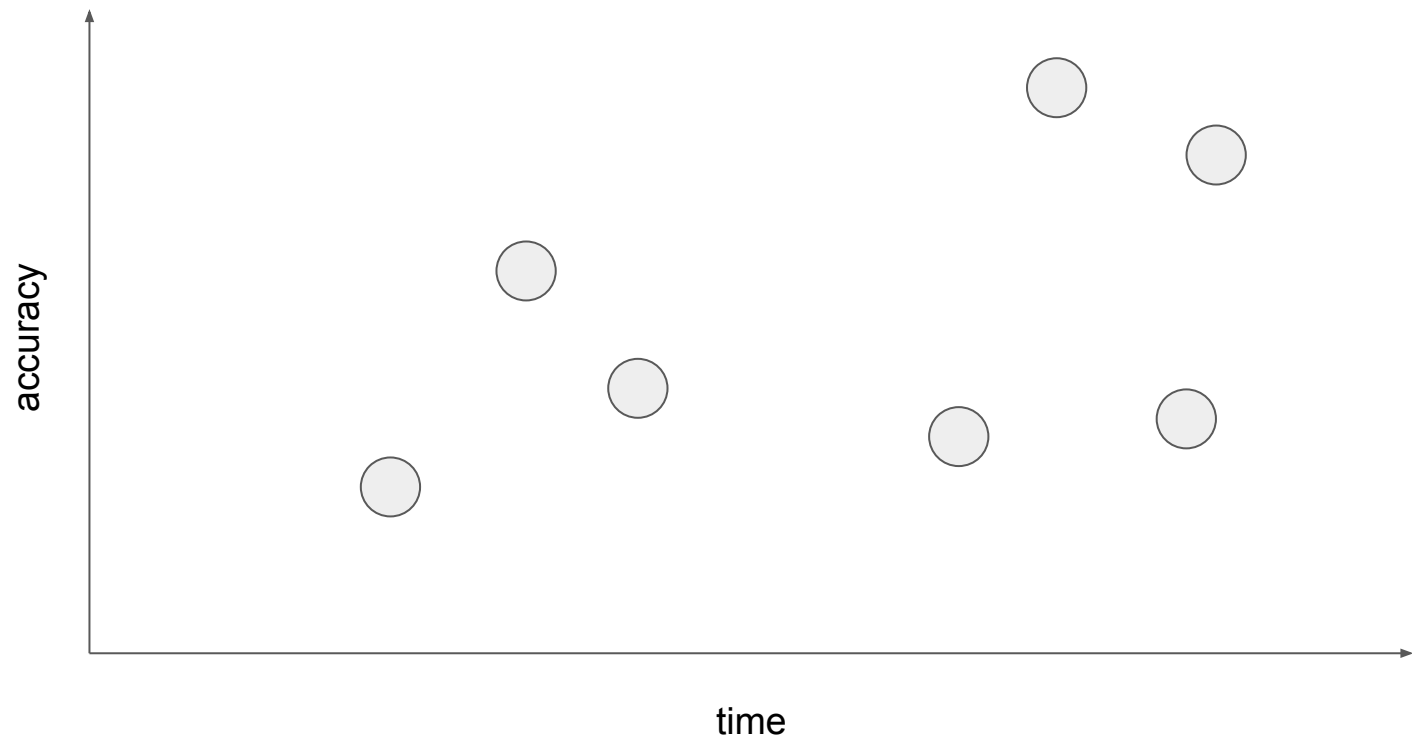


C.





C.



# Resum

A classe:

- Explicació de com es fa un Xarxa neuronal de Classificació Multi-categoria sobre BBDD Fashion MNIST

A entregar:

- **Jupyter Notebook** executat, mostrant les xarxes definides, entrenades i amb les gràfiques corresponents.