

Signals and Systems HW 7

3.1

(a) ^{waveform} $x_1(t) = 4[U(t) - U(t-1)] - 2[U(t-1) - U(t-2)]$

Laplace: $x_1(s) = 4\left[\frac{1}{s} - \frac{e^{-s}}{s}\right] - 2\left[\frac{e^{-s}}{s} - \frac{e^{-2s}}{s}\right]$

(f) $x_6(t) = -Stu(t) + 10(t-2)u(t-2) - 10(t-6)u(t-6) + 5(t-8)u(t-8)$

Laplace transform

$$x_6(s) = \frac{-S}{s^2} + 10 \cdot \frac{e^{-2s}}{s^2} - 10 \cdot \frac{e^{-6s}}{s^2} + 5 \cdot \frac{e^{-8s}}{s^2}$$

3.3

(a) $x_1(t) = 4t e^{-2t} u(t)$

det $g(t) = e^{-2t} u(t)$

$G(s) = \mathcal{L}[e^{-2t} u(t)] = \frac{1}{s+2}$

$x_1(s) = \frac{d}{ds} \left(\frac{1}{s+2} \right) = \left(\frac{-4}{(s+2)^2} \right)$

(c)

$x_3(t) = 12 e^{-3(t-4)} u(t-4)$

$\Rightarrow \mathcal{L}[e^{-a(t-T)} u(t-T)] \rightarrow \frac{e^{-Ts}}{s+a}$

$x_3(s) = \frac{e^{-4s}}{s+3}$

3.5 (a) $x_1(t) = 16e^{-2t} \cos 4t u(t)$

$$\cos \omega_0 t \xrightarrow{\omega} \frac{s}{s^2 + \omega_0^2}$$

$$e^{s_0 t} x(t) \rightarrow X(s - s_0)$$

$$\cos 4t u(t) \rightarrow \frac{s}{s^2 + (4)^2}$$

$$e^{-2t} \cos 4(t) u(t) \rightarrow \frac{s+2}{(s+2)^2 + (4)^2}$$

$$x(t) = 16e^{-2t} \cos 4t u(t)$$

$$x(s) = 16 \frac{s+2}{(s+2)^2 + 16}$$

(c) $x_3(t) = 10 \cdot e^{-3t} u(t-4)$

$$= 10 e^{-3t-12+12} u(t-4) = 10 e^{-12} e^{-3(t-4)} u(t-4)$$

$$e^{-at} u(t) \rightarrow \frac{1}{s+a}$$

$$x(t-t_0) \rightarrow e^{-st_0} x(s)$$

$$e^{-3t} u(t) \rightarrow \frac{1}{s+3}$$

$$e^{-3(t-4)} u(t-4) \rightarrow \frac{e^{-4s}}{s+3}$$

$$x_3(t) = 10 e^{-12} e^{-3(t-4)} u(t-4)$$

$$x_3(s) = \frac{10 e^{-12} e^{-4s}}{s+3}$$

3.6 (a) $x_1(t) = 30(e^{-3t} + e^{3t})u(t)$

$$e^{-at}u(t) \rightarrow \frac{1}{s+a}$$

$$X_1(s) = L[x_1(t)] = 30\left[\frac{1}{s+3} + \frac{1}{s-3}\right]$$

$$= 30\left[\frac{(s-3) + (s+3)}{(s+3)(s-3)}\right]$$

$$= 30\left[\frac{2s}{s^2-9}\right]$$

$$X_1(s) = \frac{60s}{s^2-9}$$