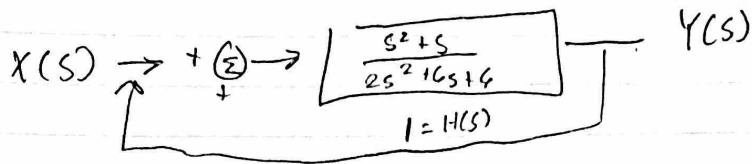


Signals and Systems Test 2

1



$$\text{Let } G(s) = \frac{s^2 + s}{2s^2 + 6s + 6}$$

$$H(s) = 1$$

$$1 + G(s) = \frac{G(s)}{1 - G(s)H(s)}$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{s^2 + s}{2s^2 + 6s + 6} \cdot \frac{1}{1 - \left(\frac{s^2 + s}{2s^2 + 6s + 6} \right) (1)}$$

$$\Rightarrow \frac{s^2 + s}{2s^2 + 6s + 6 - s^2 - s} = \frac{s^2 + s}{s^2 + 5s + 6} = \frac{s^2 + s}{s^2 + 2s + 3s + 6}$$

$$\Rightarrow \frac{s(s+1)}{(s+2)(s+3)} \Rightarrow H(s) = \frac{s(s+1)}{(s+2)(s+3)}$$

b) poles

$$(s+2)(s+3) = 0 \Rightarrow s = -2, -3$$

poles

-2, -3

$$\text{zeros } s(s+1) = 0 \Rightarrow s = 0, -1$$

zeros

0, -1

(2)

$$x(t) = e^{-t} u(t)$$

$$x(t-2) = e^{-t-2} u(t-2)$$

$$\mathcal{L}\{x(t-2)\} = \boxed{\frac{e^{-2s}}{s+1}}$$

$$t x(t-2) = t e^{-t-2} u(t-2)$$

$$\mathcal{L}\{t x(t-2)\} = \boxed{\frac{e^{-2s}}{(s+1)^2}}$$

3

$$(a) \quad s^2 + 9 = 0 \quad \text{so } s = \sqrt{-9}$$

$$2(s+1) = 0 \Rightarrow s = -1$$

$$s^2 + 6s + 8 = 0$$

$$\Rightarrow s = \frac{-6 \pm \sqrt{6^2 - 4(8)}}{2} = \frac{-6 \pm \sqrt{36 - 32}}{2}$$

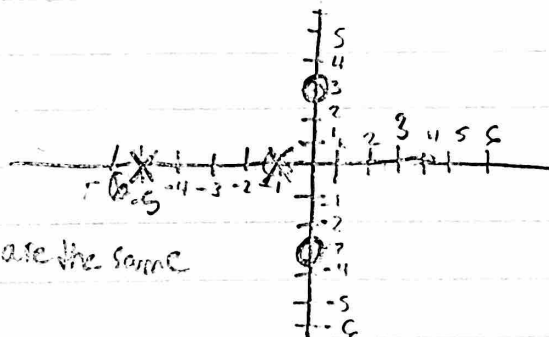
$$\Rightarrow -3 \pm 2 \quad \text{so } s = -1, -5$$

a)

ZerosPoles

$$\pm 3i, -$$

$$-1, -5$$



b) No, Degree of numerator
→ denominator are the same

c) Yes, 0

$$\lim_{s \rightarrow \infty} \frac{s(s^2 + 9)}{2(s+1)(s^2 + 6s + 8)}$$

$$\lim_{s \rightarrow 0} \frac{s(s^2 + 9)}{2(s+1)(s^2 + 6s + 8)}$$

4

$$a) \quad H(s) = \frac{2s+4}{s^2+4s+8}$$

$$H(s) = \frac{2s+4}{(s+2)^2+(2)^2} = \frac{2s}{(s+2)^2+(2)^2} + \frac{4}{(s+2)^2+(2)^2}$$

$$= \frac{2(s+2-2)}{(s+2)^2+(2)^2} + \frac{4}{(s+2)^2+(2)^2}$$

$$= \frac{2(s+2)-4}{(s+2)^2+(2)^2} + \frac{4}{(s+2)^2+(2)^2} = \frac{2(s+2)}{(s+2)^2+(2)^2} + \frac{2}{(s+2)^2+(2)^2}$$

$$\cos \omega t \rightarrow \frac{s}{s^2+\omega^2}$$

$$e^{-at} \cos \omega t \rightarrow \frac{s+a}{(s+a)^2+\omega^2}$$

\therefore Inv Laplace

$$\text{so, } \frac{2(s+2)}{(s+2)^2+(2)^2} = 2e^{-2t} \cos 2t$$

$$\text{Inv Laplace } \frac{2}{(s+2)^2+(2)^2} = e^{-2t} \sin 2t$$

$$\text{so } \Rightarrow h(t) = 2e^{-2t} \cos 2t + e^{-2t} \sin 2t$$

(b) on next page

#4 (b) Input $x(t) = e^{-3t} u(t)$

$$X(s) = \frac{1}{s+3}$$

$$H(s) = \frac{2s+4}{s^2+4s+8}$$

output $y(s) = H(s) \cdot X(s)$

$$\frac{2(s+3)}{s^2+4s+8} \cdot \frac{1}{(s+3)}$$

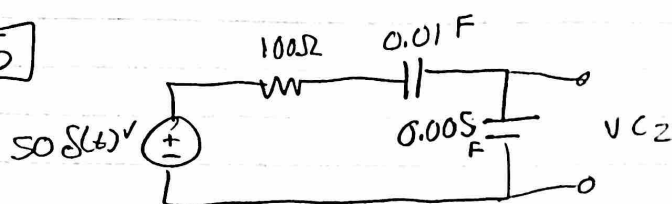
$$y(s) = \frac{2}{s^2+4s+8} \Rightarrow \frac{2}{(s+2)^2+2^2}$$

Inv Laplace

$$y(s) = \frac{2}{(s+2)^2+2^2}$$

$$\Rightarrow y(t) = e^{-2t} \sin 2t$$

5



$$\delta(t) = 1$$

$$= \Delta \left[100 + \frac{1}{0.01s} + \frac{1}{0.005s} \right] I(s)$$

$$= \left[100 + \frac{100}{s} + \frac{1000}{5s} \right] I(s) = \Delta \boxed{I(s) = \frac{50s}{100s+300}}$$

$$V_{c2}(s) = I(s) \cdot \frac{1}{C_2 s}$$

$$= \left[\frac{50s}{100s+300} \right] \cdot \frac{1}{0.005s} = \frac{50 \cdot s}{100[s+3]} \cdot \frac{200}{s}$$

$$V_{c2}(s) = \frac{100}{s+3}$$

$$\text{Inv Laplace: } V_{c2}(t) = \mathcal{L}^{-1} \left[\frac{100}{s+3} \right]$$

$$\boxed{V_{c2}(t) = 100 e^{-3t} \text{ V}}$$