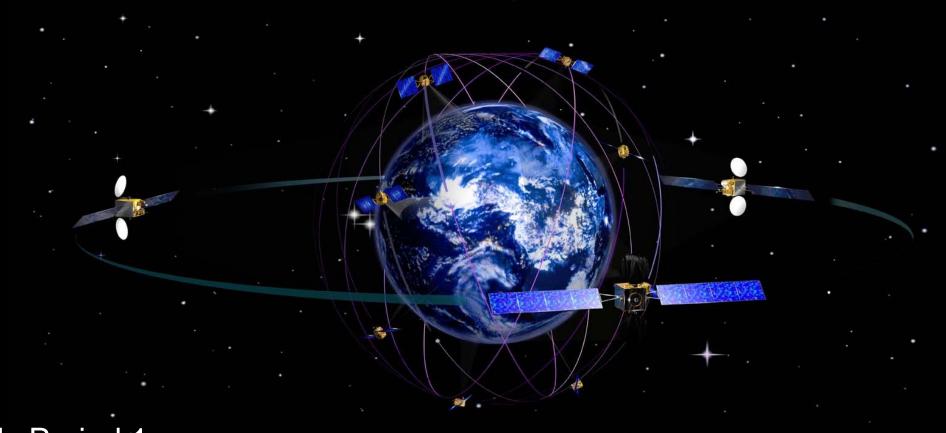
Satellite Communications - RRY100 -

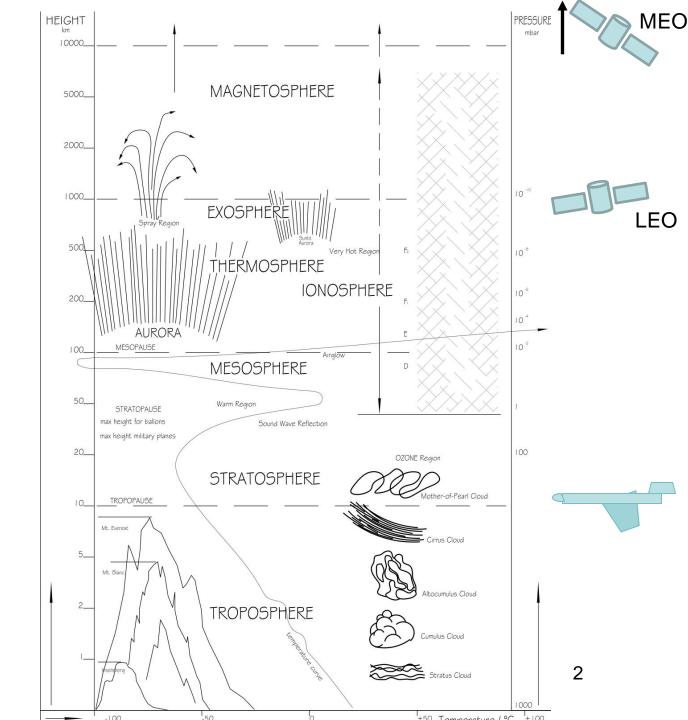


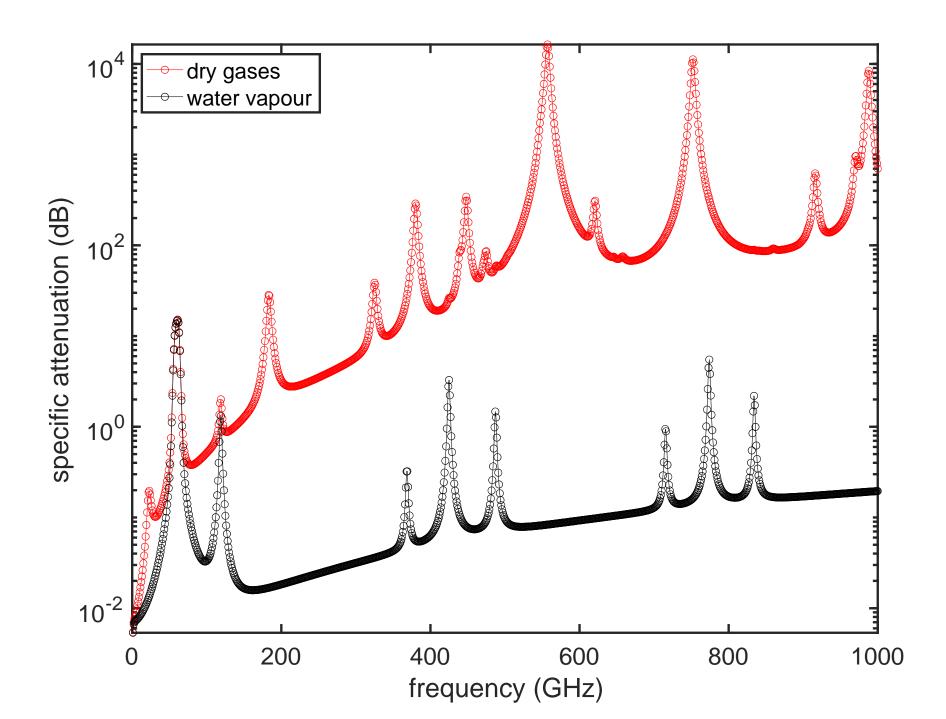
2024 Study Period 1 Lecturer: Rüdiger Haas

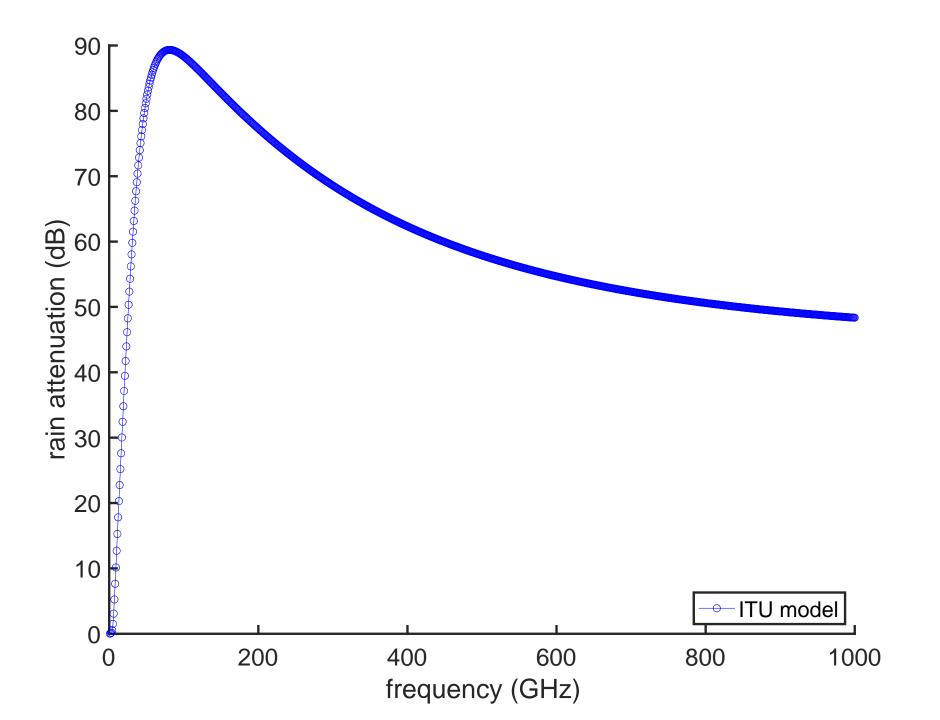
Lecture-6: Signal propagation

Signal propagation:

- Satellite communication signals pass through the Earth's atmosphere
- effects in ionosphere:
 - attenuation
 - depolarization
- effects in troposphere:
 - rain attenuation and
 - depolarization
- frequency dependent







- Electromagnetic wave is a transverse wave and consists of
 - electric field (E) and
 - magnetic field (H)
- Field strength E and H are perpendicular to each other
- Propagation direction:
 - vector product of E and H vector => Poynting vector, direction of energy flow
- Polarization direction: direction of E field vector
- Plane of polarization: made by E field vector and propagation direction
- Electric field vector can be split up into two components:

$$E_{x} = E_{1} \times \sin(W \times t - k \times z)$$

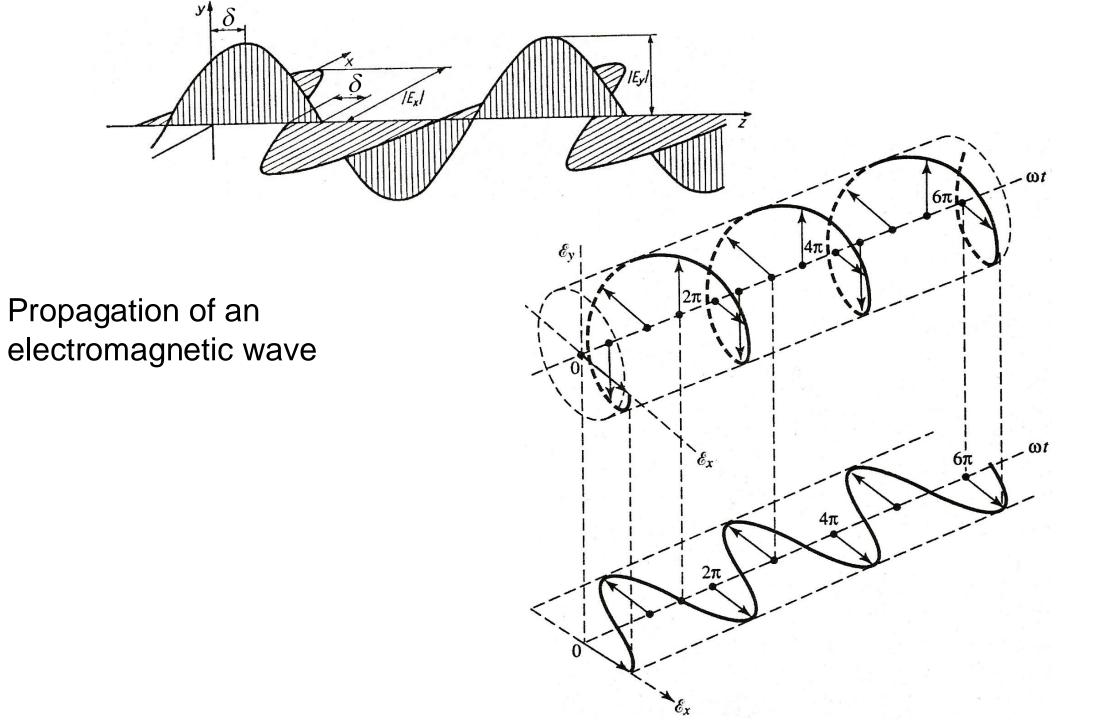
$$E_{y} = E_{2} \times \sin(W \times t - k \times z + O)$$

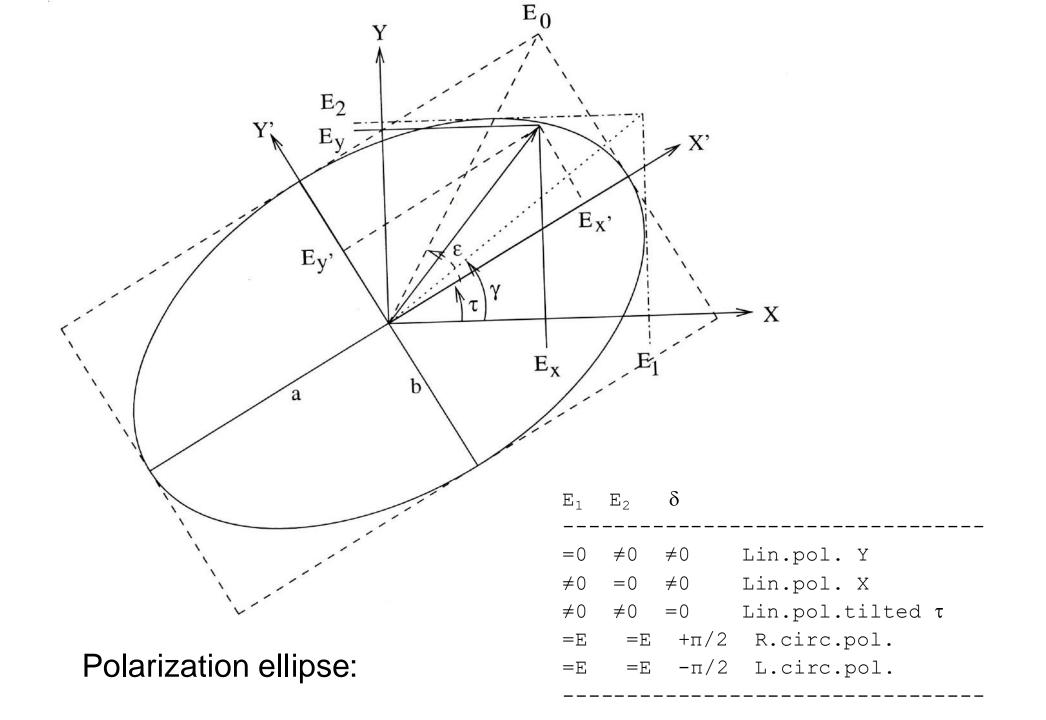
circular frequency:

$$\omega = 2 \cdot \pi \cdot f$$

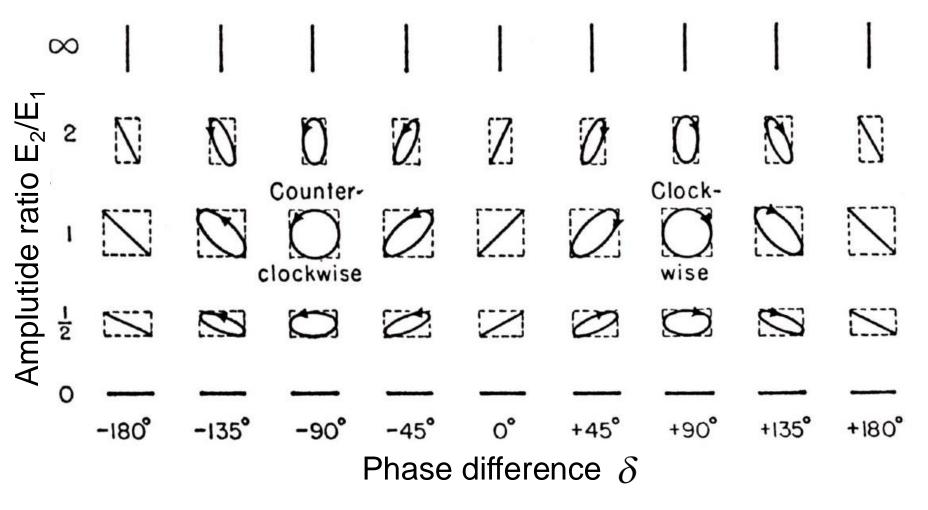
phase difference: δ

wave constant
$$k$$
: $k = \frac{2 \cdot \pi}{\lambda}$

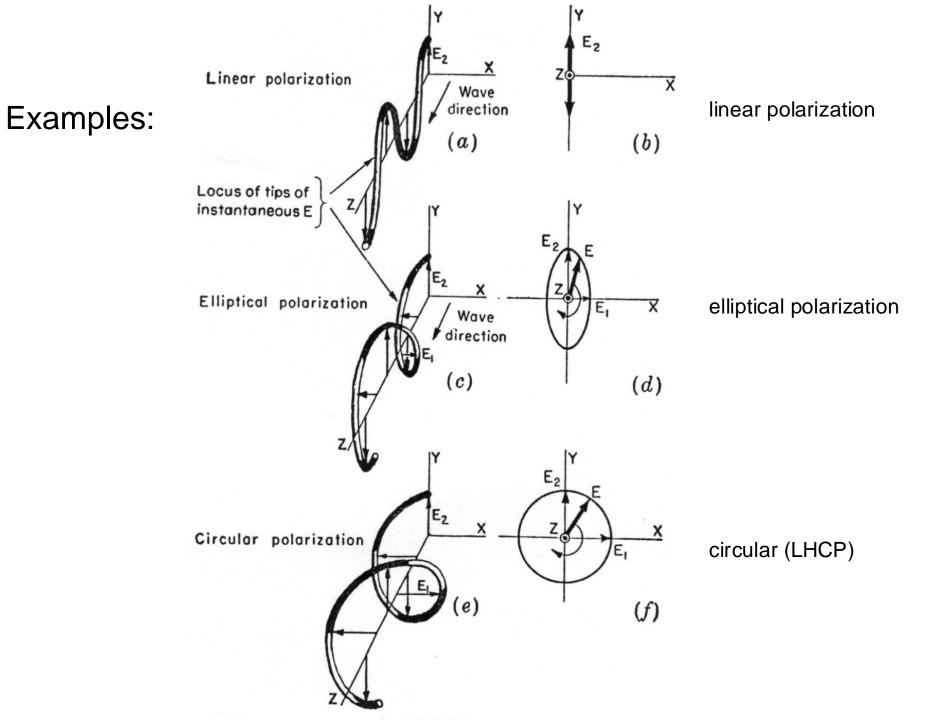




Different polarization states of an approaching wave:



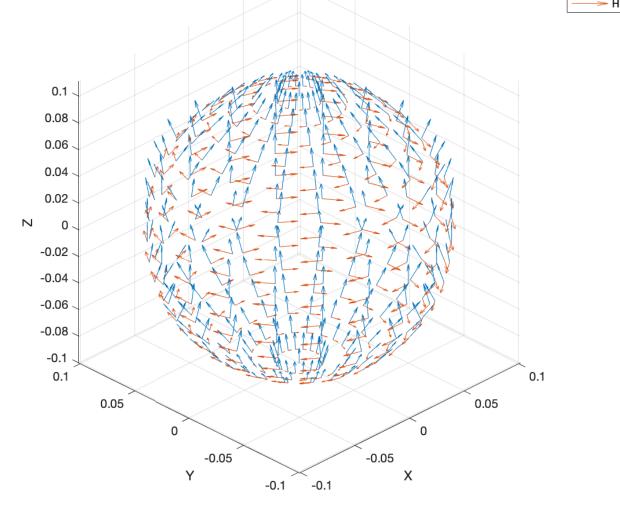
| Polarization | Radiowaves | Classical physics |
|-------------------------|--|--|
| Right-hand Left-hand | wave receeding clockwise wave receeding counterclockwise | wave approaching counterclockwise wave approaching clockwise |

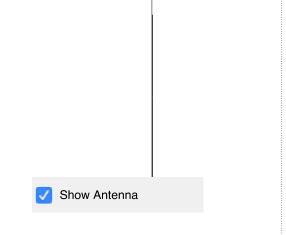


Electric (E) and Magnetic (H) Field

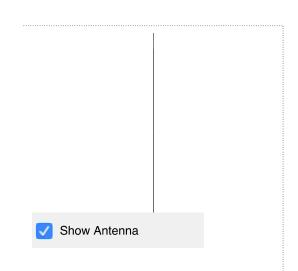


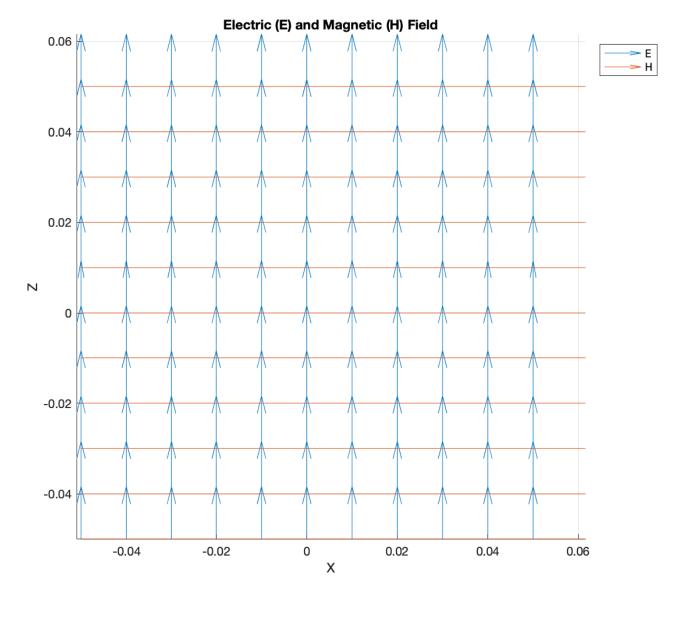
Dipole





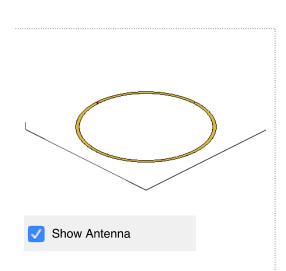
Dipole

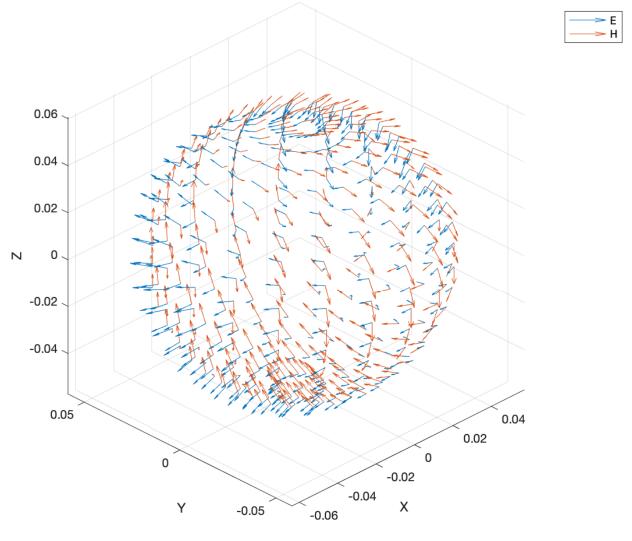




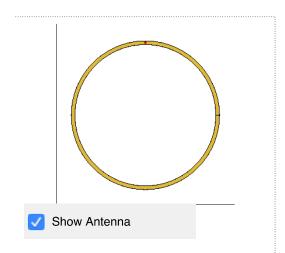
Electric (E) and Magnetic (H) Field

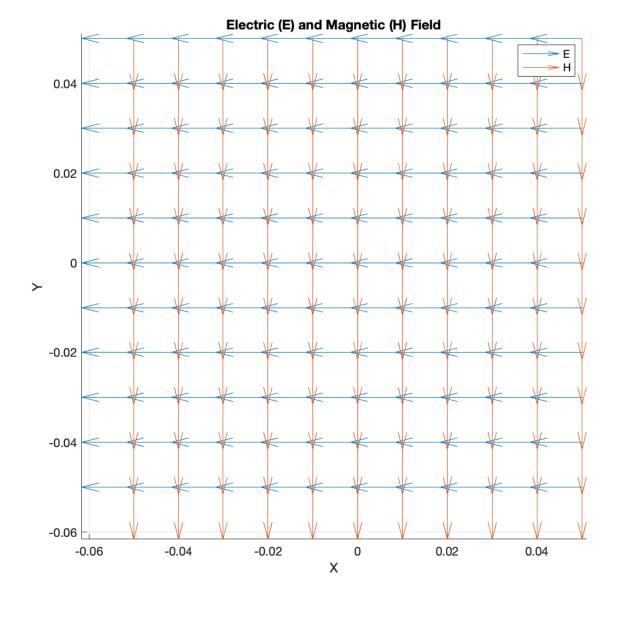
Circular loop



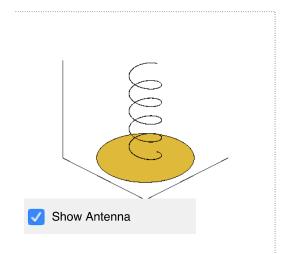


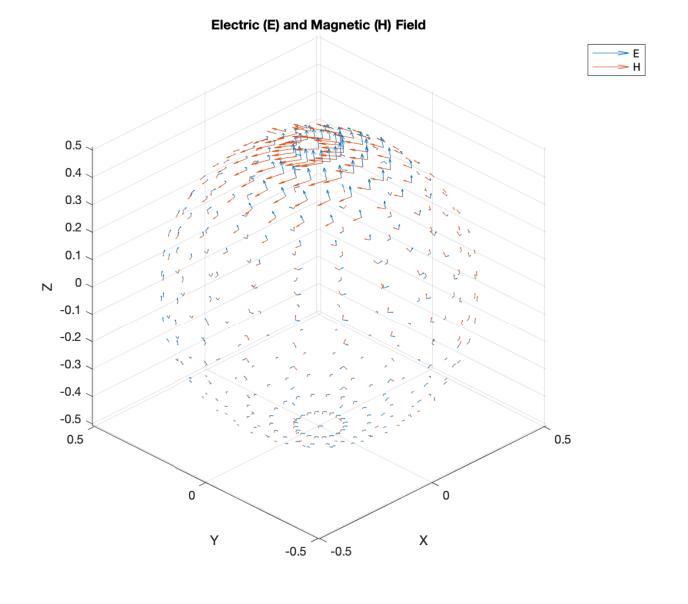
Circular loop



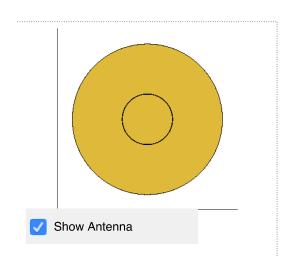


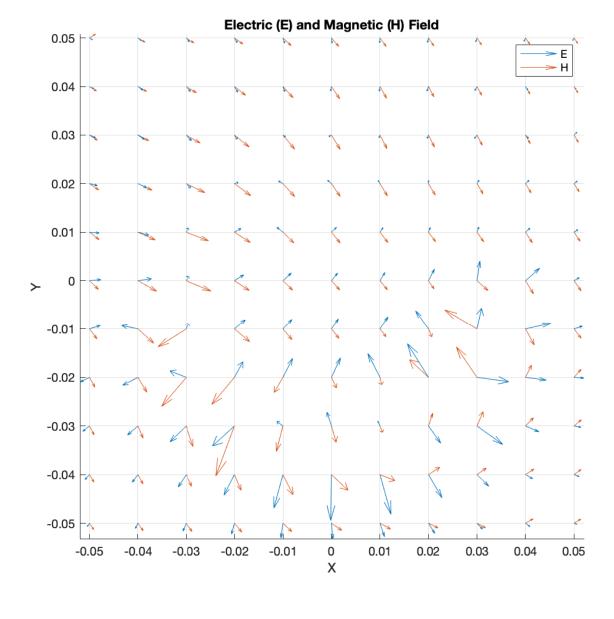
Helix (end-fire mode)



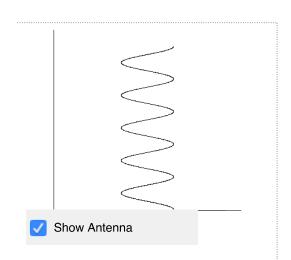


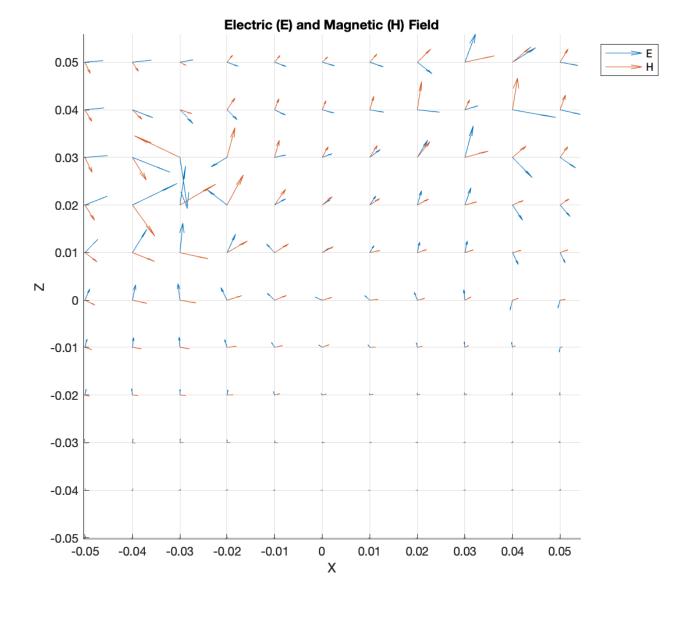
Helix (end-fire mode)





Helix (end-fire mode)





- Two sets to describe state of polarization
 - Using γ and δ , i.e. based on the amplitudes and the phase difference
 - Using ϵ and τ , i.e. based on the semi-major and semi-minor axes and the tilt angle
- Visualization with Poincarés sphere:
 - Expressing a point on the sphere with either γ and δ or ϵ and τ
 - Orthogonal polarization states are on opposite sides of the Poincaré sphere
 - Equator represents linear polarization
 - Poles represent circular polarization
 - Latitude represents axial ratio
 - Longitude represents tilt angle

Polarization description with γ and δ :

$$\gamma = \arctan\left(\frac{E_2}{E_1}\right)$$

$$0^{\circ} < g < 90^{\circ}$$

$$-180^{\circ} < d < +180^{\circ}$$

Polarization description with ϵ and τ :

$$\varepsilon = \arctan\left(\frac{b}{a}\right)$$

$$-45^{\circ} \, \text{feftage} + 45^{\circ}$$

$$-90^{\circ} < t < +90^{\circ}$$

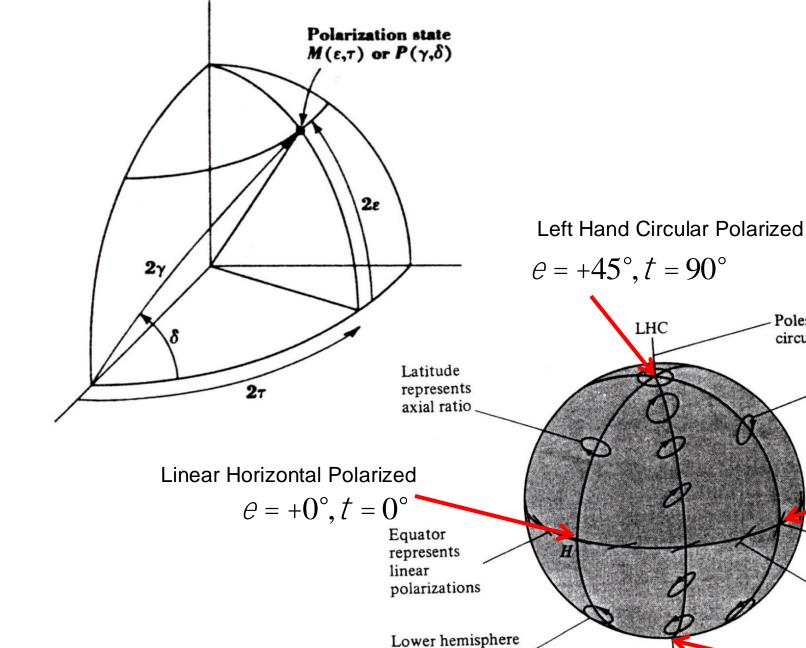
Conversion formulas:

$$\cos(2g) = \cos(2e) \times \cos(2t)$$

$$\tan(2t) = \tan(2g) \times \cos(2t)$$

$$\tan(2t) = \tan(2g) \times \sin(2t)$$

$$\sin(2e) = \sin(2g) \times \sin(2t)$$



right-hand sense

Right Hand Circular Polarized

RHC

Poles represent

circular polarizations

Upper hemisphere

Linear

45 deg

Longitude represents

 $e = -45^{\circ}, t = 90^{\circ}$

45° linear

tilt angle

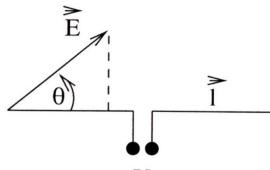
Polarized

 $e = 0^{\circ}, t = 45^{\circ}$

left-hand sense

- Antenna signal for an arbitrarily polarized wave:
 - Example linear polarized antenna
 - Output voltage is:

$$V = \vec{E} \cdot \vec{l} = E \cdot l \cdot \cos \theta$$



 Can be described with great circle distances between polarization states on Poincaré's sphere:

$$V = E \cdot l \cdot \cos\left(\frac{M_W M_A}{2}\right)$$

- Matched antenna and wave: $=> M_W M_A = 0^\circ => V = E I$
- Orthogonal circular polarizations: => $M_W M_A = 180^\circ$ => V = 0
- Orthogonal linear polarizations: $=> M_W M_A = 180^\circ => V = 0$

Polarization states:

- Complete polarization: => E_1 , E_2 and δ are constants
- Random polarization: => sum of many independent waves with different polarization (e.g. atmospheric emission), also called unpolarized: => no preferred direction of oscillation when averaged over time

$$E_x = E_1(t) \times \sin(W \times t)$$

$$E_y = E_2(t) \times \sin(W \times t + O(t))$$

 Partial polarization: mix of complete and random polarization, is the most common case

- Stokes parameters for a completely polarized wave
 - Magnitude of Poynting vector (Flux density):

$$S = S_x + S_y = \frac{E_1^2 + E_2^2}{Z} = \frac{E_0^2}{Z}$$

Definition of four Stokes parameters:

$$\begin{array}{ll} \text{total power} & I = S = S_x + S_y \\ \text{Difference between Lin. H-V} & Q = S_x - S_y \\ \text{Difference between Lin. tilted} & U = (S_x - S_y) \times \tan(2\,t) = S \times \cos(2\,\theta) \times \cos(2\,t) \\ \text{Difference between circular} & V = (S_x - S_y) \times \frac{\tan(2\,\theta)}{\cos(2\,t)} = S \times \sin(2\,\theta) \\ & \frac{U}{Q} = \tan(2\,t) \\ & \frac{V}{S} = \sin(2\,\theta) \end{array}$$

22

- Six special cases of completely polarized waves:
 - 1) Linear polarization, τ =0°

• Sx=S, Sy=0, a/b=
$$\infty$$
, => ϵ = 0° IQUV = [S S 0 0]

$$IQUV = [S S 0 0]$$

– 2) Linear polarization, τ =90°

$$IQUV = [S - S 0 0]$$

- 3) Linear polarization, τ =45°

•
$$Sx=Sy=S/2$$
, $a/b=\infty$, $=> \epsilon= 0^{\circ}$ $IQUV = [S \ 0 \ S \ 0]$

$$IQUV = [S 0 S 0]$$

- 4) Linear polarization, τ =-135°

•
$$Sx=Sy=S/2$$
, $a/b=\infty$, $=> \epsilon= 0^{\circ}$ $IQUV = [S 0 -S 0]$

$$IQUV = [S 0 -S 0]$$

- 5) Left circular polarization, τ =0°

• Sx=Sy=S/2, a/b+=1, =>
$$\varepsilon$$
= 45° IQUV = [S 0 0 S]

- 6) Right circular polarization, τ = +90°

• Sx=Sy=S/2, a/b= -1, =>
$$\varepsilon$$
= -45° IQUV = [S 0 0 -S]

Consequences:

- Two waves with identical Stokes parameters => identical
- Superposition of two waves that propagate in same directionadd Stokes parameters
- Randomly polarized waves => [S 0 0 0]
- Degree of polarization:

$$d = \frac{\sqrt{Q^2 + U^2 + V^2}}{I}$$

Normalizing Stokes parameters:

$$s_0 = I/S = 1$$

$$s_1 = Q/S$$

$$s_2 = U/S$$

$$s_3 = V/S$$

Splitting up in polarized and non-polarized part:

$$S[s_i] = S \times \begin{vmatrix} 1 - d \\ 0 \\ 0 \end{vmatrix} + S \times \begin{vmatrix} d \\ d \times \cos(2e) \times \cos(2t) \\ d \times \cos(2e) \times \sin(2t) \end{vmatrix}$$

$$d \times \cos(2e) \times \sin(2t)$$

$$d \times \sin(2e)$$

Antenna aperture can be described in a similar way:

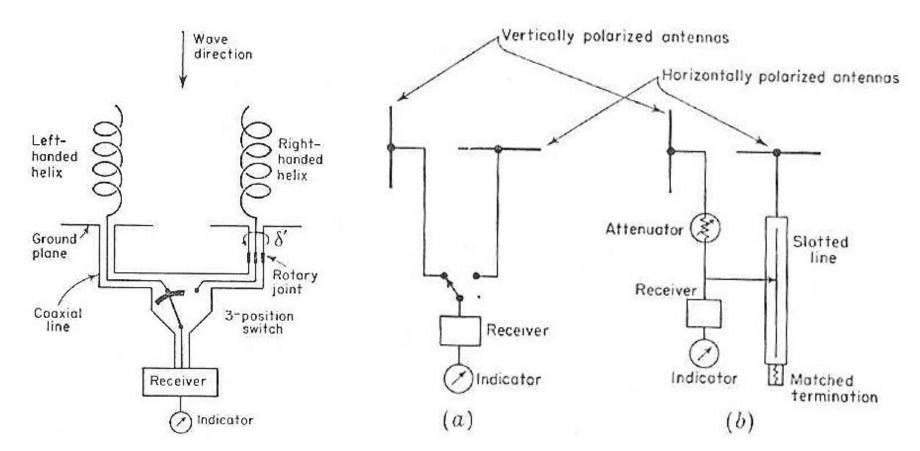
$$A_e[a_i] = A_e \times \begin{vmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{vmatrix}$$

Available power from the antenna:

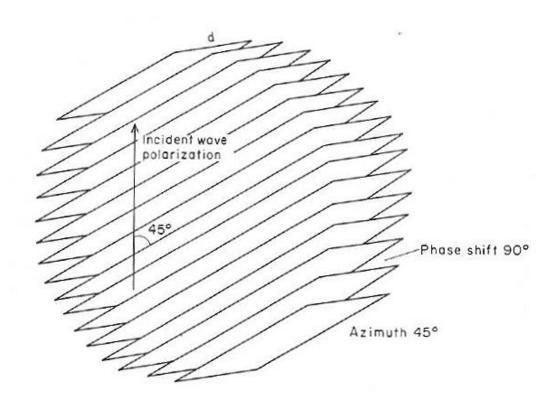
$$P = \frac{1}{2} S \times A_e \times \mathop{a}_{i=0}^{3} a_i \times s_i$$

Polarization measurements:

- Many methods possible
- E.g. With six antennas: two pairs of linearly polarized (dipoles) and one pair of circular polarized antennas (helix)
- Stokes parameters can be derived from power levels



- Changing polarization:
 - E.g. to generate circular polarization
 - Using polarization rotators
 - Natural phenomea (e.g. ionosphere, rain)

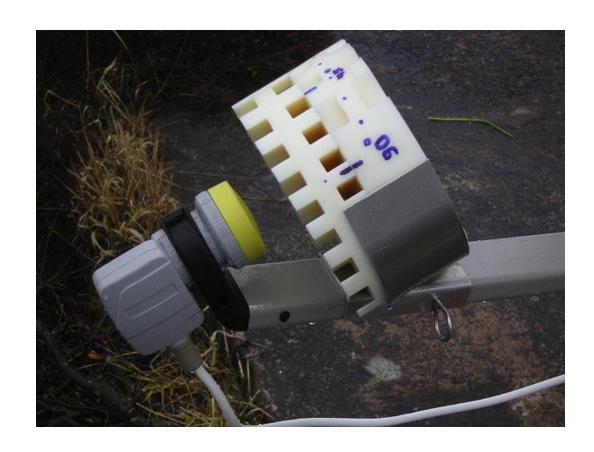


Experiment with polarizer

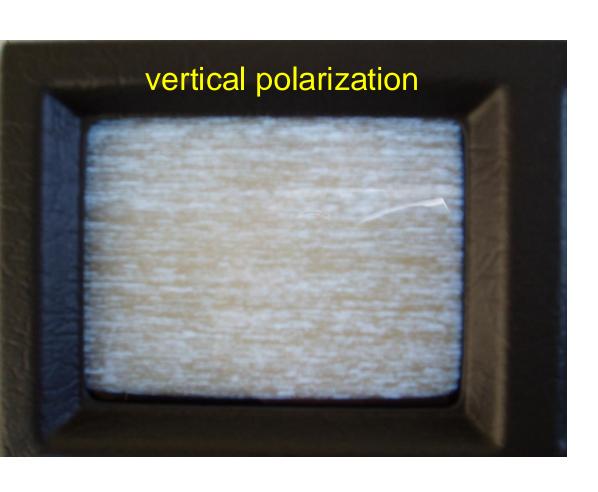
- Using a standard satellite TV set
- "watching" a horizontally polarized TV-channel
- Rotating a polarizer in front of the LNB
 - 0 degree orientation: no change, original polarization
 - 45 degree orientation: generating circular polarization
 - 90 degree orientation: reaching opposite polarization

Experimental setup



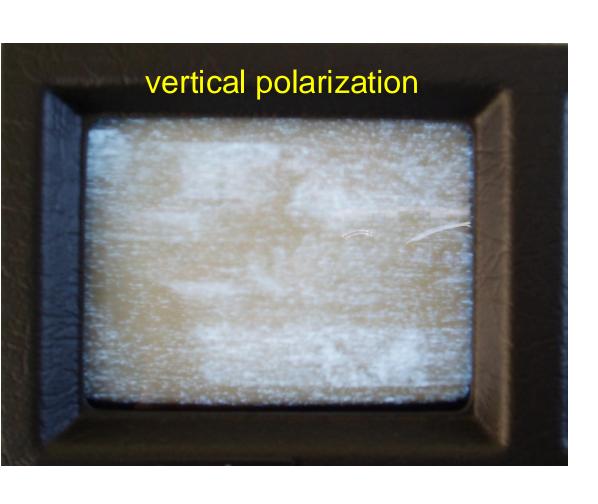


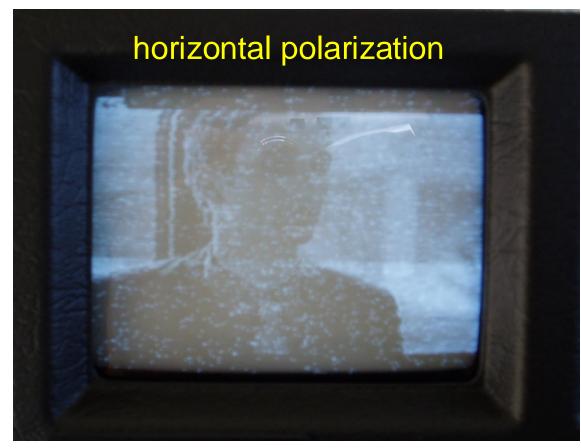
Polarizer orientation 0 degree





Polarizer orientation 45 degree





Polarizer orientation 90 degree





Short summary of today's topics

- Earth's atmosphere
- Polarization definition
- Polarization of antennas
- Poincaré sphere
- Polarization state
- Stokes parameters
- Measuring polarization