

Lab Sheet 8 Problem Soluton

Course Tittle: Microprocessor and Microcontroller Lab

Course Code: CSE3102

Section: 3

Submitted To

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Problem: Create a simulation of a traffic light with red, yellow, and green LEDs. Use timers to control the light sequence.

Theory

The aim of this simulation is to simulate a traffic light system using an Arduino board. The traffic lights consist of three colors: red, yellow, and green. Additionally, there is a countdown display that shows the countdown from 9 to 0, indicating the remaining time for each light phase.

Components List

Name	Quantity	Component
UArduino UNO R3	1	Arduino Uno R3
Digit1	1	Cathode 7 Segment Display
R2	1	1000 Ω Resistor
D1	1	Red LED
D2	1	Yellow LED
D3	1	Green LED
R1 R3 R4	3	1 kΩ Resistor

Overview

The code utilizes an Arduino board to simulate a traffic light system. It defines pins for red, yellow, and green LEDs representing traffic lights, as well as pins for individual segments of a countdown display.

Functionality

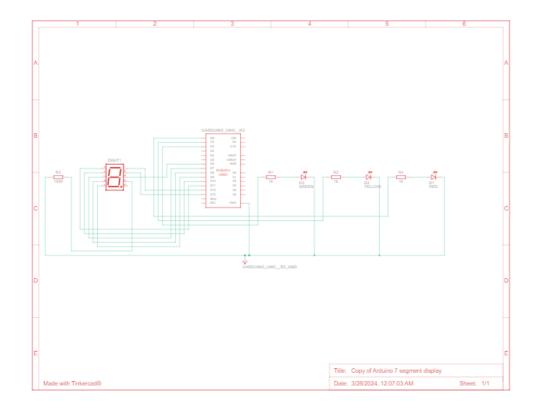
- Functions to display numbers 0-9 on the countdown display.
- A loop function to control the sequence of traffic lights:
- Red light for 15 seconds.
- Yellow light for 4 seconds with countdown.
- Green light for 20 seconds with countdown.
- Yellow light for 4 seconds as a transition phase.

Operation

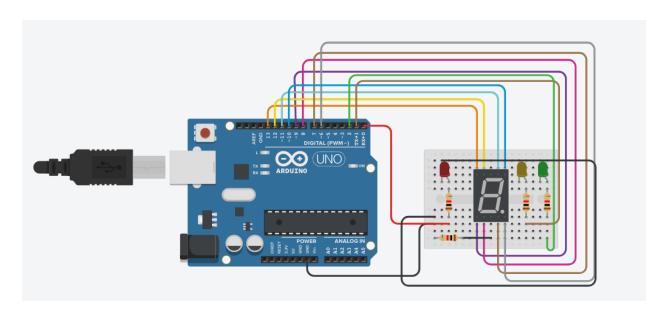
- Red light turns on for 15 seconds.
- Yellow light turns on with a countdown from 9 to 0 for 4 seconds.
- Green light turns on with a countdown from 9 to 0 for 20 seconds.
- Yellow light turns on for 4 seconds.

This sequence repeats indefinitely.

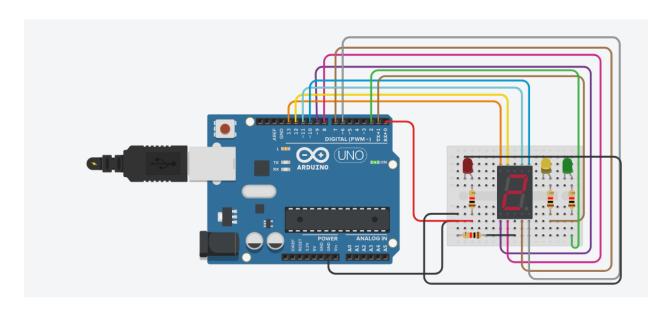
Schematic View



Before Connection



After Connection



Source Code

```
const int red = 0;
const int yellow = 1;
const int green = 2;
const int A = 13;
const int B = 12;
const int C = 11;
const int D = 10;
const int E = 9;
const int F = 8;
const int G = 7;
const int H = 6;

void setup(){
    pinMode(red, OUTPUT);
    pinMode(yellow, OUTPUT);
```

```
pinMode(green, OUTPUT);
 pinMode(A, OUTPUT);
 pinMode(B, OUTPUT);
 pinMode(C, OUTPUT);
 pinMode(D, OUTPUT);
 pinMode(E, OUTPUT);
 pinMode(F, OUTPUT);
 pinMode(G, OUTPUT);
 pinMode(H, OUTPUT);
void zero(void) {
digitalWrite(A, LOW);
digitalWrite(B, HIGH);
 digitalWrite(C, HIGH);
digitalWrite(D, HIGH);
 digitalWrite(E, HIGH);
 digitalWrite(F, HIGH);
 digitalWrite(G, HIGH);
digitalWrite(H, LOW);
}
void one(void) {
digitalWrite(A, LOW);
digitalWrite(B, LOW);
 digitalWrite(C, LOW);
digitalWrite(D, HIGH);
 digitalWrite(E, LOW);
digitalWrite(F, LOW);
 digitalWrite(G, HIGH);
digitalWrite(H, LOW);
}
void two(void) {
digitalWrite(A, HIGH);
 digitalWrite(B, LOW);
```

```
digitalWrite(C, HIGH);
 digitalWrite(D, HIGH);
 digitalWrite(E, HIGH);
 digitalWrite(F, HIGH);
 digitalWrite(G, LOW);
 digitalWrite(H, LOW);
void three(void) {
 digitalWrite(A, HIGH);
 digitalWrite(B, LOW);
 digitalWrite(C, HIGH);
 digitalWrite(D, HIGH);
 digitalWrite(E, LOW);
 digitalWrite(F, HIGH);
 digitalWrite(G, HIGH);
 digitalWrite(H, LOW);
void four(void) {
 digitalWrite(A, HIGH);
 digitalWrite(B, HIGH);
 digitalWrite(C, LOW);
 digitalWrite(D, HIGH);
 digitalWrite(E, LOW);
 digitalWrite(F, LOW);
 digitalWrite(G, HIGH);
 digitalWrite(H, LOW);
void five(void) {
 digitalWrite(A, HIGH);
 digitalWrite(B, HIGH);
 digitalWrite(C, HIGH);
 digitalWrite(D, LOW);
 digitalWrite(E, LOW);
 digitalWrite(F, HIGH);
```

```
digitalWrite(G, HIGH);
digitalWrite(H, LOW);
void six(void) {
digitalWrite(A, HIGH);
 digitalWrite(B, HIGH);
 digitalWrite(C, HIGH);
 digitalWrite(D, LOW);
 digitalWrite(E, HIGH);
 digitalWrite(F, HIGH);
digitalWrite(G, HIGH);
digitalWrite(H, LOW);
}
void seven(void) {
digitalWrite(A, LOW);
 digitalWrite(B, LOW);
 digitalWrite(C, HIGH);
 digitalWrite(D, HIGH);
 digitalWrite(E, LOW);
 digitalWrite(F, LOW);
digitalWrite(G, HIGH);
digitalWrite(H, LOW);
}
void eight(void) {
digitalWrite(A, HIGH);
 digitalWrite(B, HIGH);
 digitalWrite(C, HIGH);
 digitalWrite(D, HIGH);
 digitalWrite(E, HIGH);
 digitalWrite(F, HIGH);
digitalWrite(G, HIGH);
digitalWrite(H, LOW);
```

```
void nine(void) {
digitalWrite(A, HIGH);
 digitalWrite(B, HIGH);
digitalWrite(C, HIGH);
digitalWrite(D, HIGH);
digitalWrite(E, LOW);
digitalWrite(F, HIGH);
 digitalWrite(G, HIGH);
digitalWrite(H, LOW);
}
void timer(void)
{
 nine();
delay(1000);
eight();
delay(1000);
 seven();
delay(1000);
 six();
delay(1000);
 five();
delay(1000);
 four();
delay(1000);
 three();
delay(1000);
 two();
delay(1000);
```

```
one();
delay(1000);
 zero();
 delay(1000);
}
void loop(void){
digitalWrite(red, HIGH);
delay(15000);
digitalWrite(red, LOW);
digitalWrite(yellow, HIGH);
delay(4000);
timer();
digitalWrite(yellow, LOW);
digitalWrite(green, HIGH);
delay(20000);
timer();
digitalWrite(green, LOW);
digitalWrite(yellow, HIGH);
delay(4000);
digitalWrite(yellow, LOW);
}
```