Curriculum Vitae

PERSONAL DETAILS

Name Choi, Jaehee
Mobile 010-2669-8681
E-mail jchoi@kaist.ac.kr
Date of Birth 1996.02.11

Gender Male Military Service Yes

Address Bucheon, Gyeonggi-do, Republic of Korea

EDUCATION

Korea Advanced Institute of Science and Technology Aug. 2022 ~ Present

193, Munji-ro, Yuseong-gu, Daejeon, Republic of Korea

Cho Chun Shik Graduate School of Mobility

M.S. student

Advisor: Prof. Kitae Jang

Inha University Mar. 2016 ~ Aug. 2022

100, Inha-ro, Michuhol-gu, Incheon, Republic of Korea Department of Mechanical Engineering

B.S. student

INTEREST

- -Autonomous Vehicle
- -Path/motion planning
- -Robotics
- -Lane change model

SKILLS AND TECHNIQUES (SOFTWARE)

- -CARLA simulator
- -Python
- -ROS
- -Matlab(Simulink)
- -C/C++
- -Autodesk Fusion 360
- -Ansys 2021 R2
- -Arudino

EXPERIENCE

- -Undergraduate Research Student Intern at Electrical Engineering, Autonomous Systems Laboratory, Inha Univ. (Advisor : Prof. Kwangki Kim) Sep. 2021 ~ June. 2022
- -Master of Science Student at Transportation Operation and Planning for Sustainability Laboratory, KAIST (Advisor : Prof. Kitae Jang) Aug. 2022 ~ Present

PUBLICATIONS

Domestic Journals

- Shin, G., **Choi, J.**[†], & Kim, G. (2022, May). A Fast Correspondence Matching for Iterative Closest Point Algorithm. *The Journal of Korea Robotics Society*, https://doi.org/10.7746/jkros.2022.17.3.373

Article(s) under revision

- Oh, S., Choi, J., Jang, K., & Yoon, J. (2024). Analysis of Autonomous Vehicles Risk Cases for Developing Level 4+ Autonomous Driving Test Scenarios: Focusing on Perceptual Blind. *The Journal of The Korea Institute of Intelligent Transportation Systems*

AWARDS

2016	1/3 academic scholarship
2021	Engineering design club competition(공학설계 동아리 경진대회) Bronze prize
2021	i-STARTUPLAB accelerating(아랩 액셀러레이팅) Excellence Award
2021	Hanium Competition(한이음 공모전) Participation Award

2022 2/3 academic scholarship

2022 Academic honors

GIT REPOSITORIES

https://github.com/jahii?tab=repositories https://gitlab.com/jahii

Last Update: April 27, 2024