SCC5809 - Redes Neurais

Avaliação Empírica de Unidades Recorrentes na Modelagem de Sequências

Leonardo Leite de Melo Wagner W. Ávila Bombardelli

04 de outubro 2018

SUMÁRIO

1. Introdução

Aplicações com RNN / Resumo do Artigo

2. Contextualização

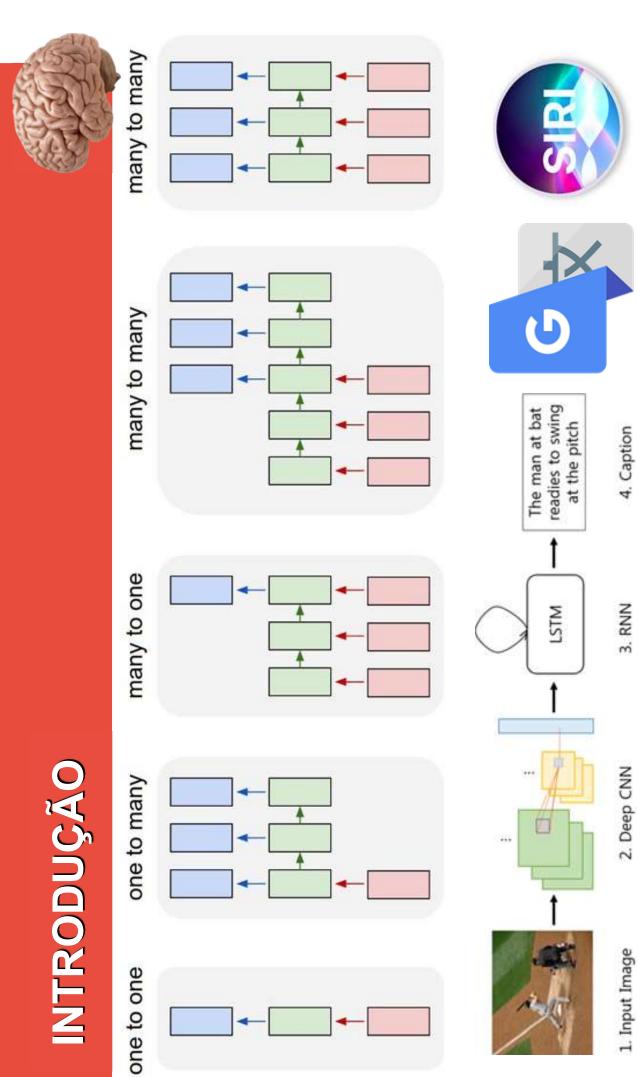
RNN / LTSM / GRU / Discussão

3. Experimentação

Tarefas e Conjunto de Dados / Modelos

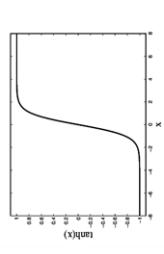
4. Resultados e Análise

5. Conclusão



RESUMO DO ARTIGO





GRU

On the Properties of Neural Machine Translation: Encoder-Decoder Approaches

Bart van Merriënboer Université de Montréal Kyunghyun Cho

Dzmitry Bahdanau* Jacobs University, Germany

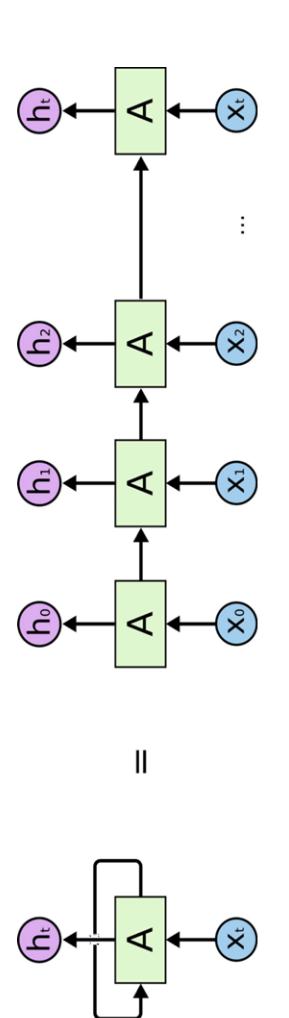
Gated Recurrent Neural Networks **Empirical Evaluation of** on Sequence Modeling

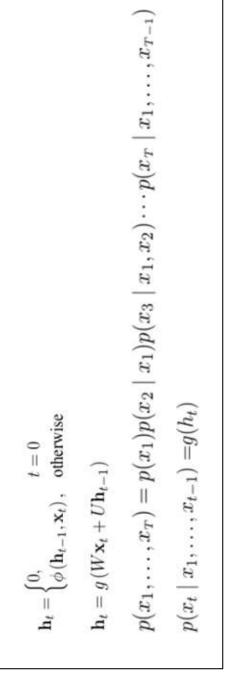
Junyoung Chung Caglar Gulcehre KyungHyun Cho Université de Montréal

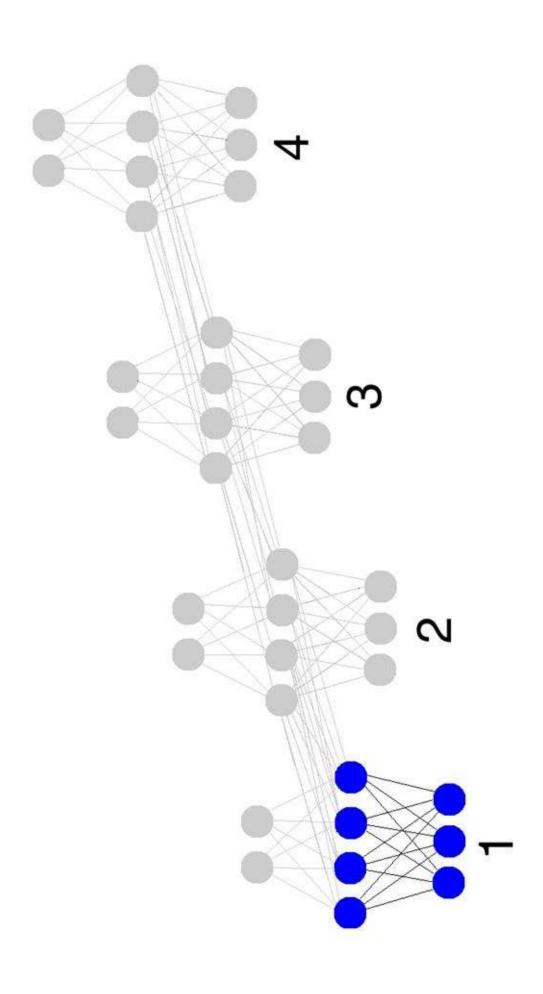
Yoshua Bengio Université de Montréal CIFAR Senior Fellow



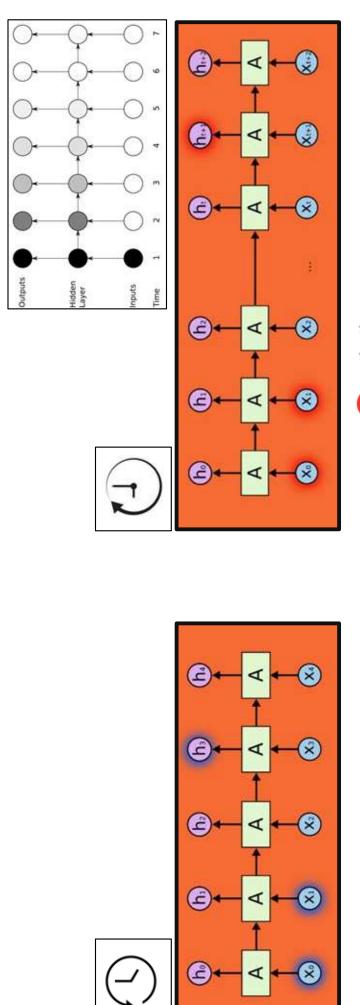
CONTEXTUALIZAÇÃO

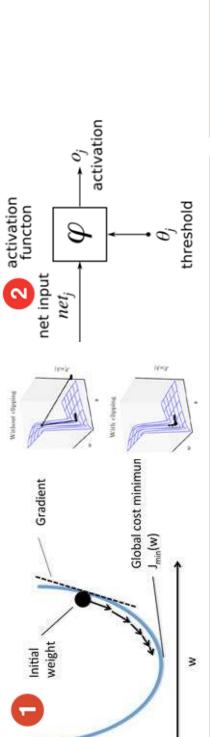






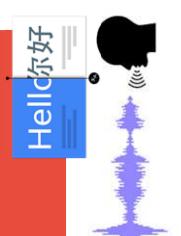
VANISHING GRADIENT PROBLEM

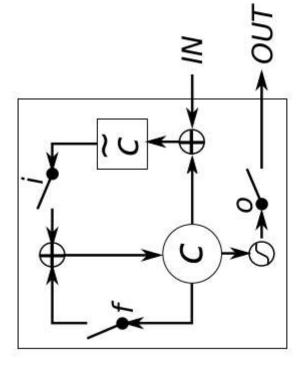


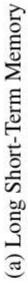


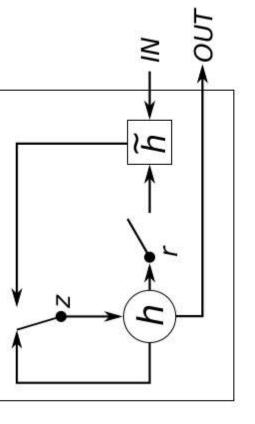
(w)r

LSTM × GRU









(b) Gated Recurrent Unit

[Cho et al., 2014]



[Hochreiter and Schmidhuber, 1997]

LSTM was the winner of the ICDAR (International Conference on Document Analysis and Recognition) 2009 - Handwriting Competition for the best known results in h

$$h_t^j = o_t^j \tanh \left(c_t^j \right)$$

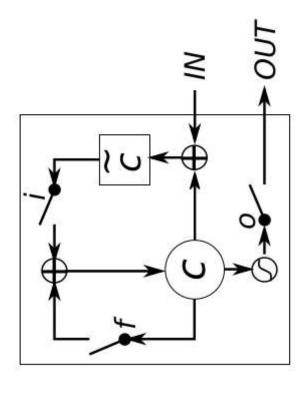
$$o_t^j = \sigma \left(W_o \mathbf{x}_t + U_o \mathbf{h}_{t-1} + V_o \mathbf{c}_t \right)^j$$

$$c_t^j = f_t^j c_{t-1}^j + i_t^j \tilde{c}_t^j$$

$$\tilde{c}_t^j = \tanh (W_c \mathbf{x}_t + U_c \mathbf{h}_{t-1})^j$$

$$f_t^j = \sigma (W_f \mathbf{x}_t + U_f \mathbf{h}_{t-1} + V_f \mathbf{c}_{t-1})^j$$

$$i_t^j = \sigma (W_i \mathbf{x}_t + U_i \mathbf{h}_{t-1} + V_i \mathbf{c}_{t-1})^j$$



(a) Long Short-Term Memory

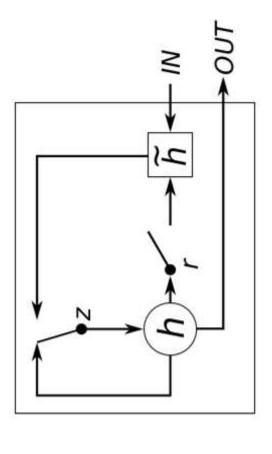
A célula de memória pode manter seu valor por um tempo curto ou longo como uma função de suas entradas, o que permite que a célula se lembre daquilo que é Introduziu o conceito de célula de memória.

$$h_t^j = (1 - z_t^j) h_{t-1}^j + z_t^j \tilde{h}_t^j$$

$$z_t^j = \sigma \left(W_{\mathbf{z}} \mathbf{x}_t + U_{\mathbf{z}} \mathbf{h}_{t-1} \right)^j$$

$$\tilde{h}_t^j = \tanh \left(W \mathbf{x}_t + U \left(\mathbf{r}_t \odot \mathbf{h}_{t-1} \right) \right)^j$$

$$r_t^j = \sigma \left(W_{\mathbf{r}} \mathbf{x}_t + U_{\mathbf{r}} \mathbf{h}_{t-1} \right)^j$$



(b) Gated Recurrent Unit

DISCUSSÃO

SEMELHANÇA



(i) É fácil para cada unidade lembrar a existência de um recurso específico no fluxo de entrada

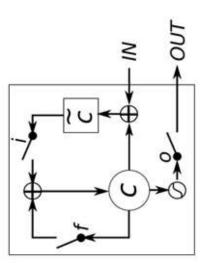
(ii) Essa adição cria efetivamente caminhos de atalho que ignoram várias etapas temporais.

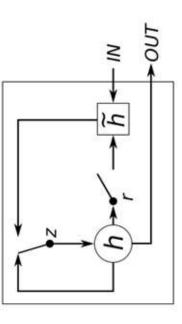
DISCUSSÃO

DIFERENÇAS

(i) Na unidade LSTM, a quantidade de conteúdo da memória acessada por outras unidades n

(ii) Localização do gate de input e gate de reset correspondente.





INFORMAÇÕES ADICIONAIS

Attention Is All You Need

Ashish Vaswani*	Google Brain	avaswani@google.com

Noam Shazeer* Google Brain

noam@google.com

nikip@google.com Google Research Niki Parmar*

Jakob Uszkoreit Google Research

usz@google.com

Lukasz Kaiser Google Brain

University of Toronto Aidan N. Gomez*

llion@google.com Google Research Llion Jones*

lukaszkaiser@google.com aidan@cs.toronto.edu

illia.polosukhin@gmail.com Illia Polosukhin* ‡



sequences. Aligning the positions to steps in computation time, they generate a sequence of hidden states h, as a function of the previous hidden state h, -1 and the input for position t. This inherently sequential nature precludes parallelization within training examples, which becomes critical at longer sequence lengths, as memory constraints limit batching across examples. Recent work has achieved Recurrent models typically factor computation along the symbol positions of the input and output significant improvements in computational efficiency through factorization tricks [2]] and conditional computation [32], while also improving model performance in case of the latter. RNN (LSTM e GRU em particular) foram firmemente estabelecidas como abordagens de última geração em modelagem de sequência, como processamento de lin

Inúmeros esforços, desde então, continuaram a empurrar os limites de modelos de linguagem recorrente e arquiteturas encoder-decoder.

(VASWANI, Ashish et al. Attention is all you need. In: Advances in Neural Information Processing Systems. 2017. p. 5998-6008.)

CONFIGURAÇÃO DO EXPERIMENTO I

 Comparação de LSTM, GRU e tanh na tarefa de modelar uma sequência de dados. Aprender a probabilidade de distribuição em uma sequência de dados.

$$\max_{\theta} \frac{1}{N} \sum_{n=1}^{N} \sum_{t=1}^{T_n} \log p\left(x_t^n \mid x_1^n, \dots, x_{t-1}^n; \theta\right),\,$$

CONFIGURAÇÃO DO EXPERIMENTO II

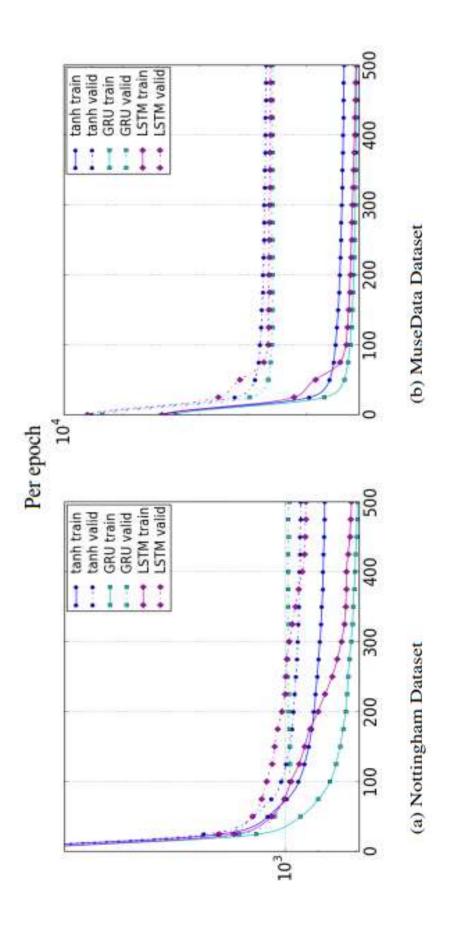
Unit	# of Units	# of Units # of Parameters
Poly	Th.	nonic music modeling
L'STM	36	$\approx 19.8 \times 10^3$
GRU	46	$\approx 20.2 \times 10^3$
tanh	100	$\approx 20.1 \times 10^3$
	speech signal	modeling
STM	195	$\approx 169.1 \times 10^{3}$
GRU	227	$\approx 168.9 \times 10^3$
tanh	400	$\approx 168.4 \times 10^3$

Table 1: The sizes of the models tested in the experiments.

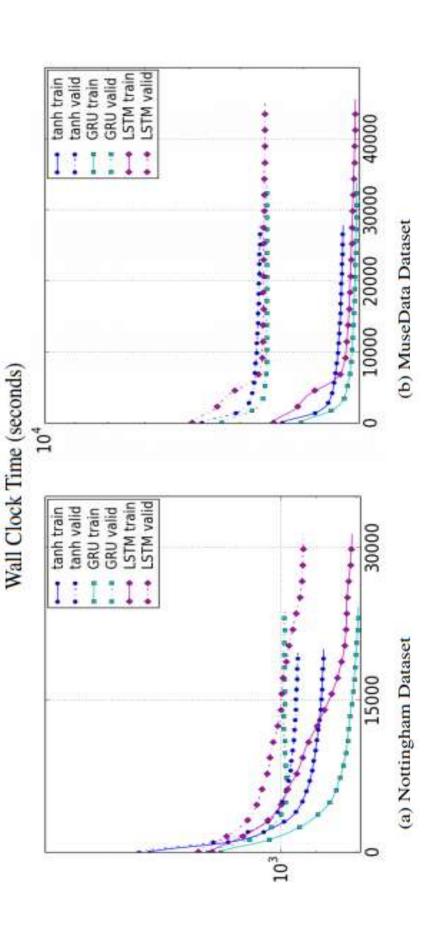
			tanh	GRU	GRU LSTM
	1 14	train	3.22	2.79	3.08
	Nottingnam	test	3.13	3.23	3.20
Music Datasets	TOD OF T	train	8.82	6.94	8.15
	Job Chorales	test	9.10	8.54	8.67
	10.00	train	5.64	5.06	5.18
	MuseData	test	6.23	5.99	6.23
142	Tr.	train	5.64	4.93	6.49
	Flano-midi	test	9.03	8.82	9.03
	This & Leaves A	train	6.29	2.31	1.44
	Consoit dataset A	test	6.44	3.59	2.70
Ubisoft Datasets	Th.: - A J D	train	7.61	0.38	0.80
	Unison dataset b	test	7.62	0.88	1.26

Table 2: The average negative log-probabilities of the training and test sets.

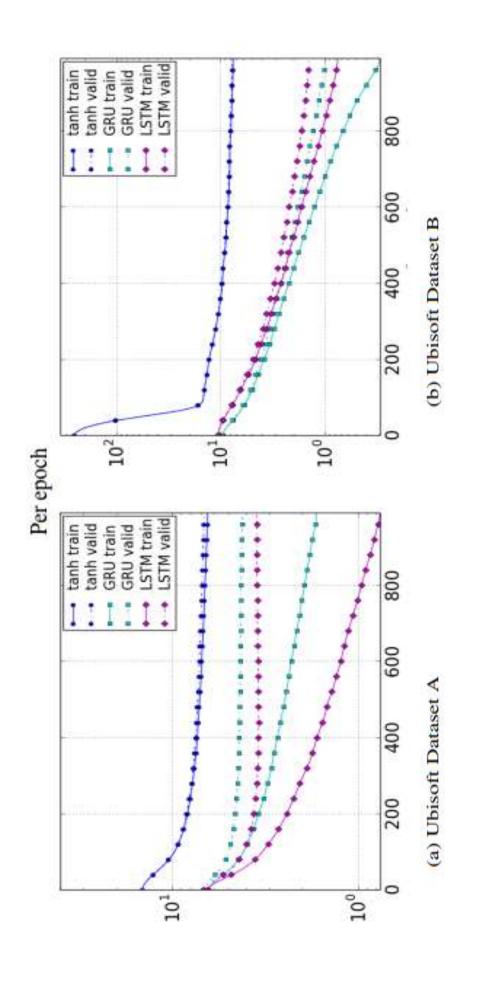
RESULTADOS E ANÁLISE I



RESULTADOS E ANÁLISE II



RESULTADOS E ANÁLISE III



RESULTADOS E ANÁLISE IV

