# CLASSIFICATION OF SONAR DATASET USING DECISION TREE CLASSIFIER IN R

#### Aim:

- In this case study, we will be able to build decision tree models using the tree and rpart libraries in R. In addition, we will evaluate the model's performance and learn how to save the trained model on the local system.
- A dataset called "Sonar" has been taken. This is the data set used by Gorman and Sejnowski in their study of the classification of sonar signals using a neural network.
- The data reports the patterns obtained by bouncing sonar signals at various angles and under various conditions.
- There are 208 patterns in all, 111 obtained by bouncing sonar signals off a metal cylinder and 97 obtained by bouncing signals off rocks.
- Each pattern is a set of 60 numbers (variables) taking values between 0 and 1.
- These data have been taken from the UCI Repository Of Machine Learning Databases at

ftp://ftp.ics.uci.edu/pub/machine-learning-databases

http://www.ics.uci.edu/~mlearn/MLRepository.html

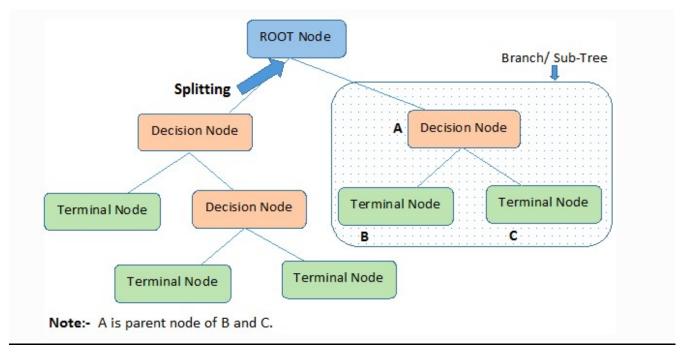
and were converted to R format by Evgenia Dimitriadou.

### **Objectives:**

- 1. Understand the concept of the decision tree algorithm
- 2. Build decision tree models
- 3. Evaluate the performance of the model

#### Procedure:

# **Decision Tree Representation:**



# **Importing the libraries:**

```
19 * ```{r}
20 ## 2.1: Import the required packages
21
22 library(tree)
23 library(caret)
24 library(rpart)
25 library(rpart.plot)
26 library(mlbench)
27
28 * ```
```

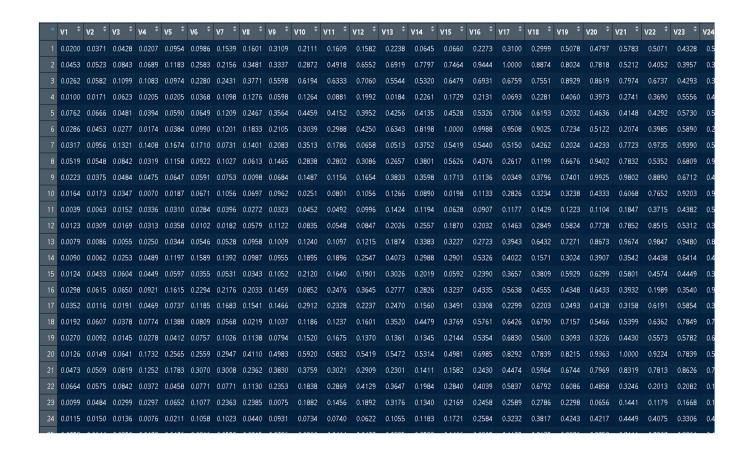
# Importing and Exploring the dataset:

```
```{r}
34
35
36
      data("Sonar")
37
      View(Sonar)
38
39
40
41
      table(Sonar$Class)
42
      ## 3.4: Check for missing values
sum(is.na(Sonar))
43
44
45
46
48
      anyNA(Sonar)
49
      ## 3.5: Summarise the data set
summary(Sonar)
50
51
52
      nrow(Sonar)
54
      ncol(Sonar)
55
56
      set.seed(11)
57
58
59
     columns ← sample(x = 1:60, size = 9)

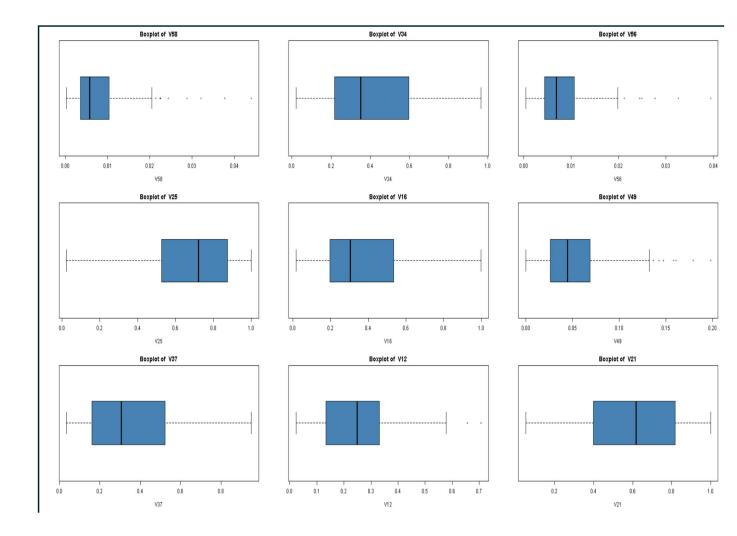
pre_var ← Sonar[, columns]

par(mfrow = c(3,3)) # This produces a 3 by 3 plot of the box plots
60
61
62
63
## 3.7: Show box plots of the predictor variables
for (i in 1:ncol(pre_var)){
boxplot(pre_var[, i], xlab = names(pre_var[i]),
main = paste("Boxplot of ",names(pre_var[i])),
horizontal = TRUE, col = "steelblue")
69 - }
70 -
```

#### "Sonar" dataset:

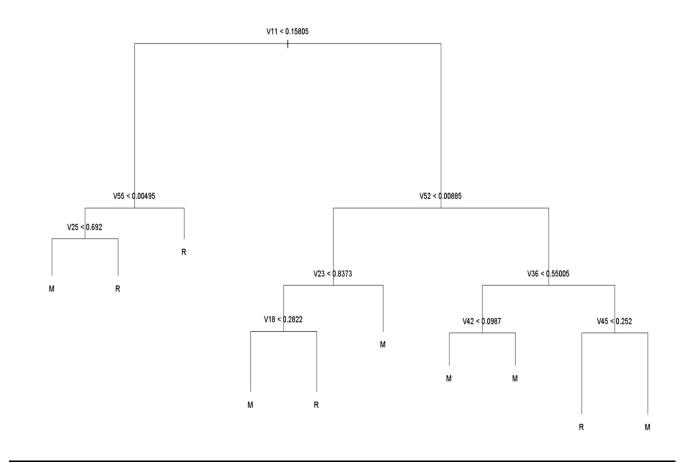


#### Box Plot of predictor variables:



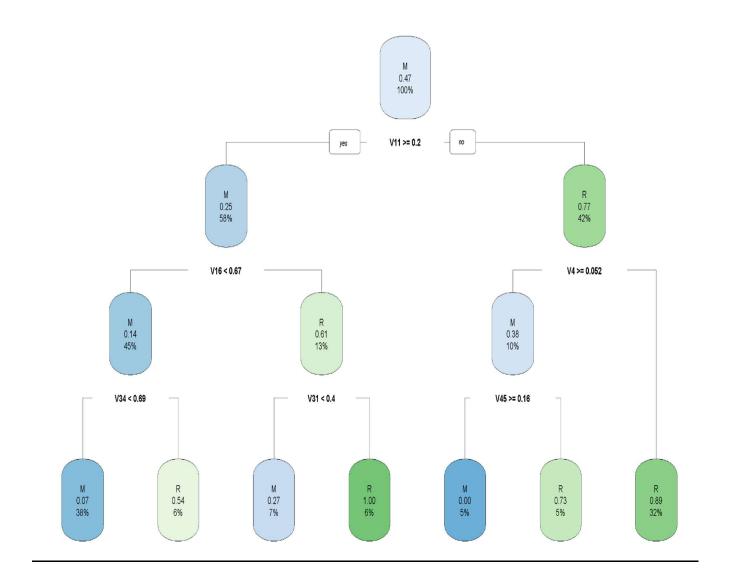
# Training and Visualizing the decision tree model:

```
TOO
101
102
     model \leftarrow tree(
       formula = Class ~ .,
103
104
       data = train_set
105
106
107
     ## Exercise 5.1: Check the summary of the model
108
     summary(model)
109
110
     plot(model)
111
     text(model)
112
```



# Visualizing the new decision tree model using rpart:

```
## 5.3: Fit the model using the rpart function
115
     model1 ← rpart(Class ~ ., data = Sonar, method = "class")
116
117
118
     ## Exercise 5.2: Print the model and the model summary
119
120
     model1
     summary(model1)
121
122
     ## 5.5: Visualize the new decision tree model
123
     rpart.plot(model1)
124
125
```



# **Evaluating Model Performance:**

```
prediction ← predict(model1, newdata = test_set, type = "class")
table(x = prediction, y = test_set$Class)
     М
  M 29 3
  R 4 26
> confusionMatrix(data = prediction,
                   reference = test_set$Class)
Confusion Matrix and Statistics
           Reference
Prediction M R
          M 29 3
          R 4 26
                Accuracy : 0.8871
                   95% CI : (0.7811, 0.9534)
    No Information Rate: 0.5323
    P-Value [Acc > NIR] : 2.418e-09
                    Kappa : 0.7737
 Mcnemar's Test P-Value : 1
             Sensitivity: 0.8788
             Specificity: 0.8966
          Pos Pred Value : 0.9062
Neg Pred Value : 0.8667
              Prevalence: 0.5323
          Detection Rate: 0.4677
   Detection Prevalence : 0.5161
      Balanced Accuracy: 0.8877
        'Positive' Class : M
> F1 ← 2* (0.8788 * 0.8788) / (0.8788 + 0.8788)
> F1
[1] 0.8788
> error_rate ← round(mean(prediction ≠ test_set$Class), 2)
> error_rate
[1] 0.11
```

#### Conclusion:

So, this is how we build, train and visualize the "Decision Tree Classifier" in R programming language.