# **IOT LAB INTERNAL -2(II)**

**AIM**: To Design IOT based Fire Alerting system to give alert message to the fire department.

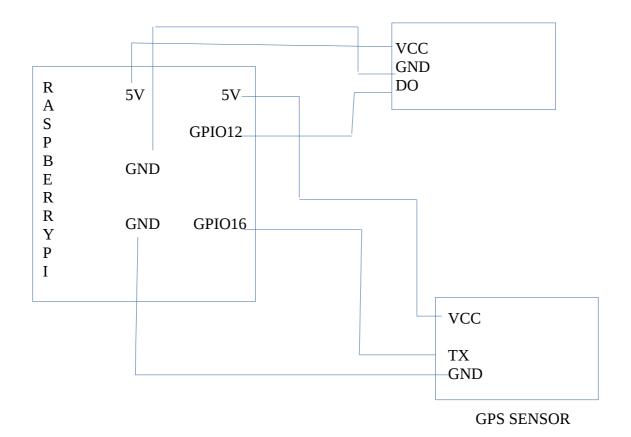
**DESCRIPTION:** The Fire Alerting system detects the presence of flame and sends alerts to mobile when a fire occurs. The embedded system used to develop this fire alarm system is Raspberry Pi . A feature of the system is the ability to remotely send an alert when a fire is detected. The system will report the event to the Fire Department using (SMS). The advantage of using this system is it will reduce the possibility of false alert reported to the Fire Department.

## HARDWARE AND SOFTWARE REQIREMENTS:

- RaspberryPi
- Thonny Python IDE
- Jumper wires

- GPS Sensor
- LED
- Flame Sensor

## **CIRCUIT DIAGRAM:**



### CODE:

```
#!/usr/bin/python
import serial, os, time, sys, datetime, csv
import RPi.GPIO as GPIO
from gpiozero import Buzzer, InputDevice
from time import sleep
import webbrowser
import sys
port1=2
GPIO.setmode(GPIO.BCM)
GPIO.setup(2,GPIO.IN)
GPIO.setup(23, GPIO.OUT,initial=GPIO.LOW)
def GPS_Info():
  global NMEA_buff
  global lat_in_degrees
  global long_in_degrees
  nmea time = []
  nmea latitude = []
  nmea_longitude = []
  nmea_time = NMEA_buff[0]
                                         #extract time from GPGGA
string
  nmea_latitude = NMEA_buff[1]
                                         #extract latitude from
GPGGA string
  nmea_longitude = NMEA_buff[3]
                                          #extract longitude from
GPGGA string
  print("NMEA Time: ", nmea_time,'\n')
```

```
print ("NMEA Latitude:", nmea_latitude,"NMEA Longitude:",
nmea longitude,'\n')
  lat = float(nmea_latitude)
                                     #convert string into float for
calculation
  longi = float(nmea_longitude)
                                        #convertr string into float for
calculation
  lat_in_degrees = convert_to_degrees(lat) #get latitude in degree
decimal format
  long_in_degrees = convert_to_degrees(longi) #get longitude in degree
decimal format
#convert raw NMEA string into degree decimal format
def convert_to_degrees(raw_value):
  decimal_value = raw_value/100.00
  degrees = int(decimal value)
  mm_mmm = (decimal_value - int(decimal_value))/0.6
  position = degrees + mm_mmmm
  position = "%.4f" %(position)
  return position
gpgga_info = "$GPGGA,"
ser = serial.Serial ("/dev/ttyS0")
                                       #Open port with baud rate
GPGGA buffer = 0
NMEA buff = 0
lat_in_degrees = 0
long in degrees = 0
#print("before if cond\n",lat in degrees,":, lat_in_degrees,", long in
degree ," long_in_degrees")
print("lat in degrees:", lat_in_degrees," long in degree: ", long_in_degrees,
'\n')
try:
  while True:
```

```
print("in while loop")
    result1=GPIO.input(2)
    print(" Fire reading is ;->",result1)
    if result1==0:
       print(" Fire reading is ;->",result1)
    received_data = (str)(ser.readline())
    sleep(2)
    print(received_data)#read NMEA string received
    print("RECEIVED DATA ",)
    GPGGA data available = received data.find(gpgga info) #check
for NMEA GPGGA string
    print("AVAILABLE DATA ",GPGGA_data_available)
    print("lat in degrees:", lat_in_degrees," long in degree: ",
long_in_degrees, '\n')
    if (GPGGA data available>=0):
       GPGGA_buffer = received_data.split("$GPGGA,",1)[1] #store
data coming after "$GPGGA," string
       NMEA_buff = (GPGGA_buffer.split(','))
                                                         #store comma
separated data in buffer
       GPS_Info()
                                             #get time, latitude, longitude
       print("latitude in degrees:", lat_in_degrees," longitude in degrees:
", long_in_degrees, '\n')
       map_link = 'http://maps.google.com/?q=' + str(lat_in_degrees) + ','
+ str(long in degrees) #create link to plot location on Google map
       print("<<<<<<pre>rint("<<<<<<<pre>print("<<<<<<<<<<<pre>print("<<<<<<<<<<<>>press ctrl+c to plot location on google
maps>>>>\n")
                          #press ctrl+c to plot on map and exit
       print("-----\n")
       print("after latitude in degrees:", str(lat_in_degrees)," longitude in
degrees: ", str(long_in_degrees), '\n')
```

except KeyboardInterrupt:
 webbrowser.open(map\_link) #open current position information in
google map
 sys.exit(0)

## **OUTPUT:**

