# Assignment 3: Image Mosaic or Panorama Creation

Results from the execution of main program is as follows:

# CollegeMain:



# **Construction:**



# NearMinar:



## Room:

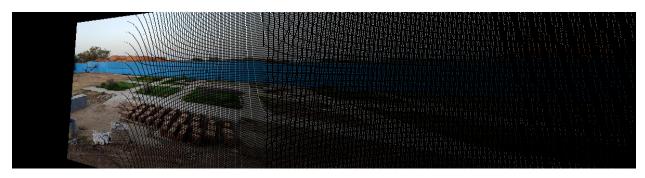


#### SolarPath:



### Remarks:

Simply using the homography to transform points created holes in the transformation. So, I used the bilinear interpolation to fill those gaps. (cv2.INTER\_AREA)



All the references are enlisted in the codes and are as follows:

### **References:**

- https://medium.com/@iamhatesz/random-sample-consensus-bd2bb7b1be75
- https://docs.opencv.org/2.4/doc/tutorials/features2d/feature homography/feature homography.html
- https://medium.com/analytics-vidhya/image-stitching-with-opency-and-python-1ebd9e0a6d78
- <a href="https://math.stackexchange.com/questions/494238/how-to-compute-homography-matrix-h-from-corresponding-points-2d-2d-planar-homog">https://math.stackexchange.com/questions/494238/how-to-compute-homography-matrix-h-from-corresponding-points-2d-2d-planar-homog</a>
- https://docs.opencv.org/master/d9/dab/tutorial homography.html
- https://www.pyimagesearch.com/2018/12/17/image-stitching-with-opency-and-python/
- https://github.com/hughesj919/HomographyEstimation/blob/master/Homography.py
- https://pysource.com/2018/03/21/feature-detection-sift-surf-obr-opency-3-4-with-python-3-tutorial-25/
- <a href="https://opencv-python-tutroals.readthedocs.io/en/latest/py\_tutorials/py\_feature2d/py\_matcher/py\_matcher.html">https://opencv-python-tutroals.readthedocs.io/en/latest/py\_tutorials/py\_feature2d/py\_matcher/py\_matcher.html</a>

### References for the perspective\_warp method:

- https://docs.opencv.org/2.4/modules/imgproc/doc/geometric transformations.html
- https://stackoverflow.com/questions/46520123/how-do-i-use-opencys-remap-function
- https://en.wikipedia.org/wiki/Bilinear interpolation#Application in image processing