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FROM HERE TO THE WORLD

Kinematics of Machine

Project

Submitted to

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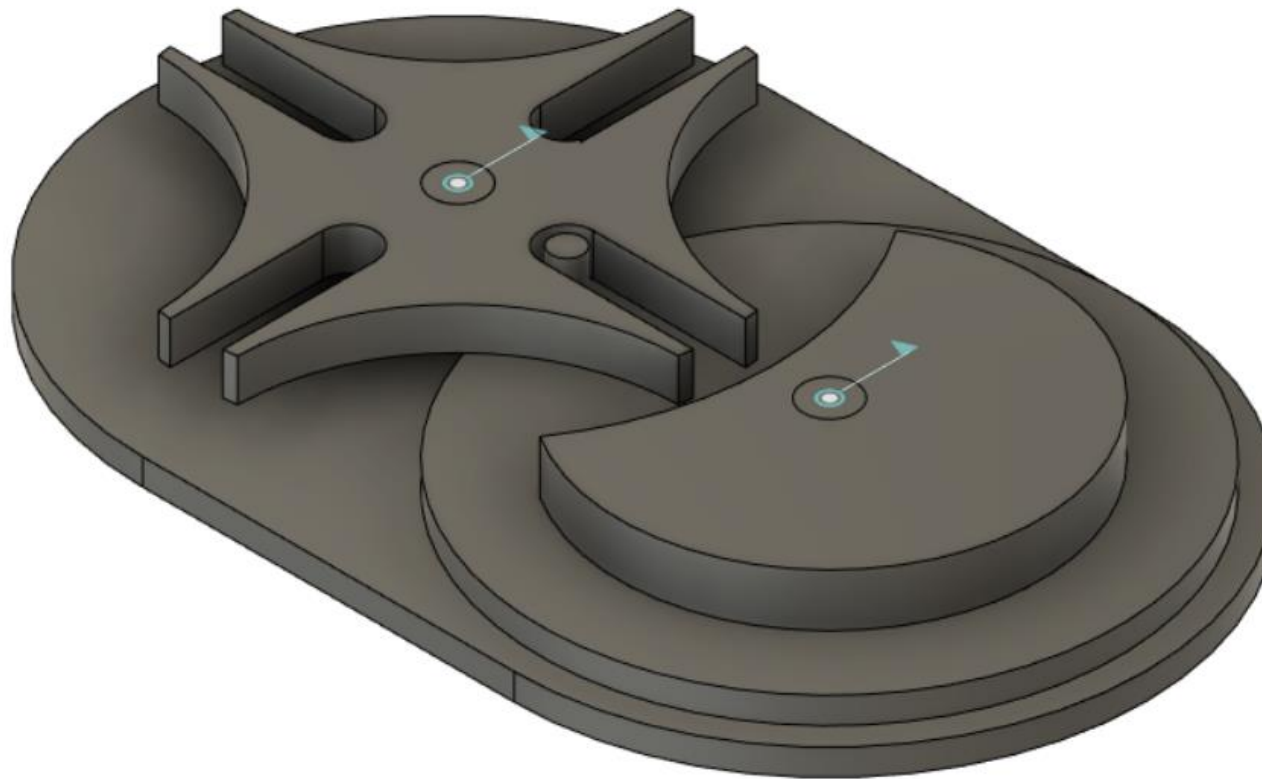
Mr. Tirath Kumar.

Submitted by

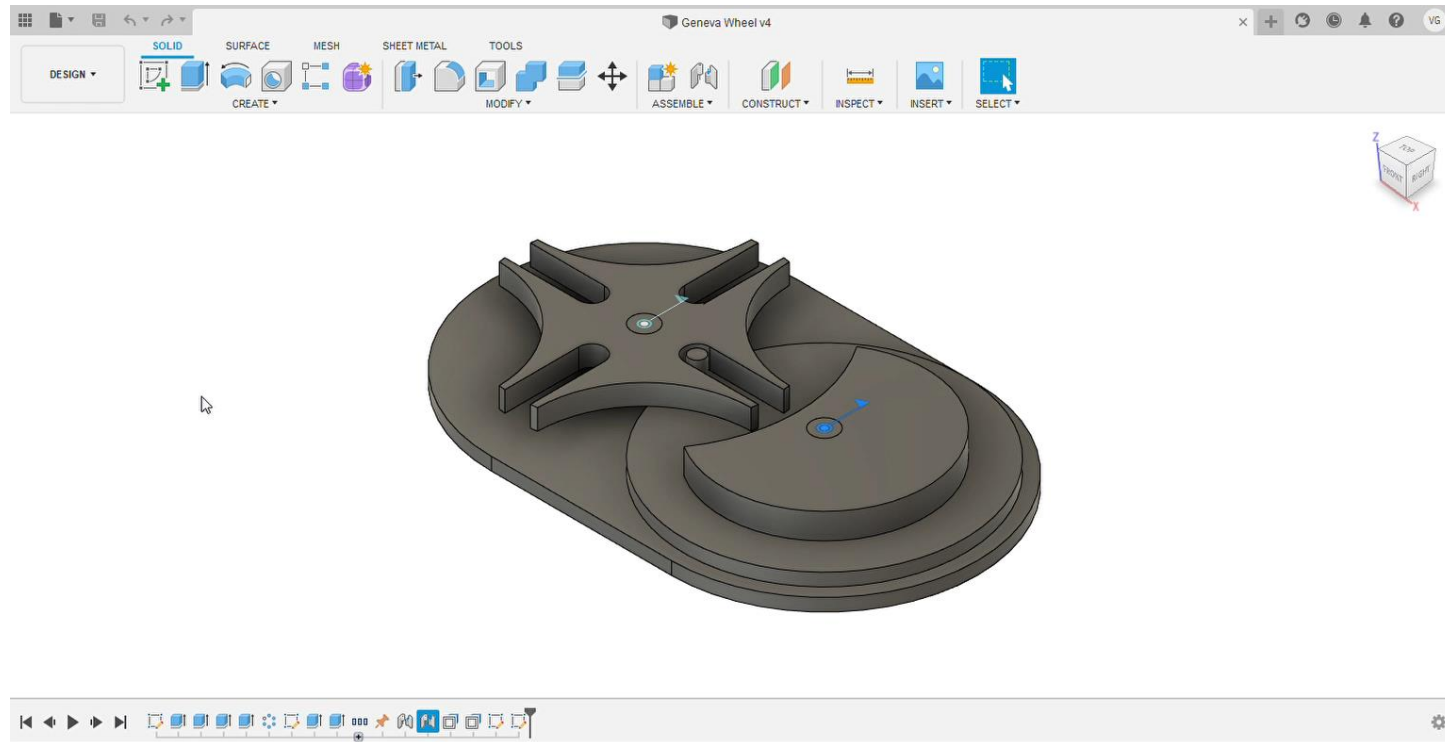
Gunda Venkata Sai Jai Harsha.

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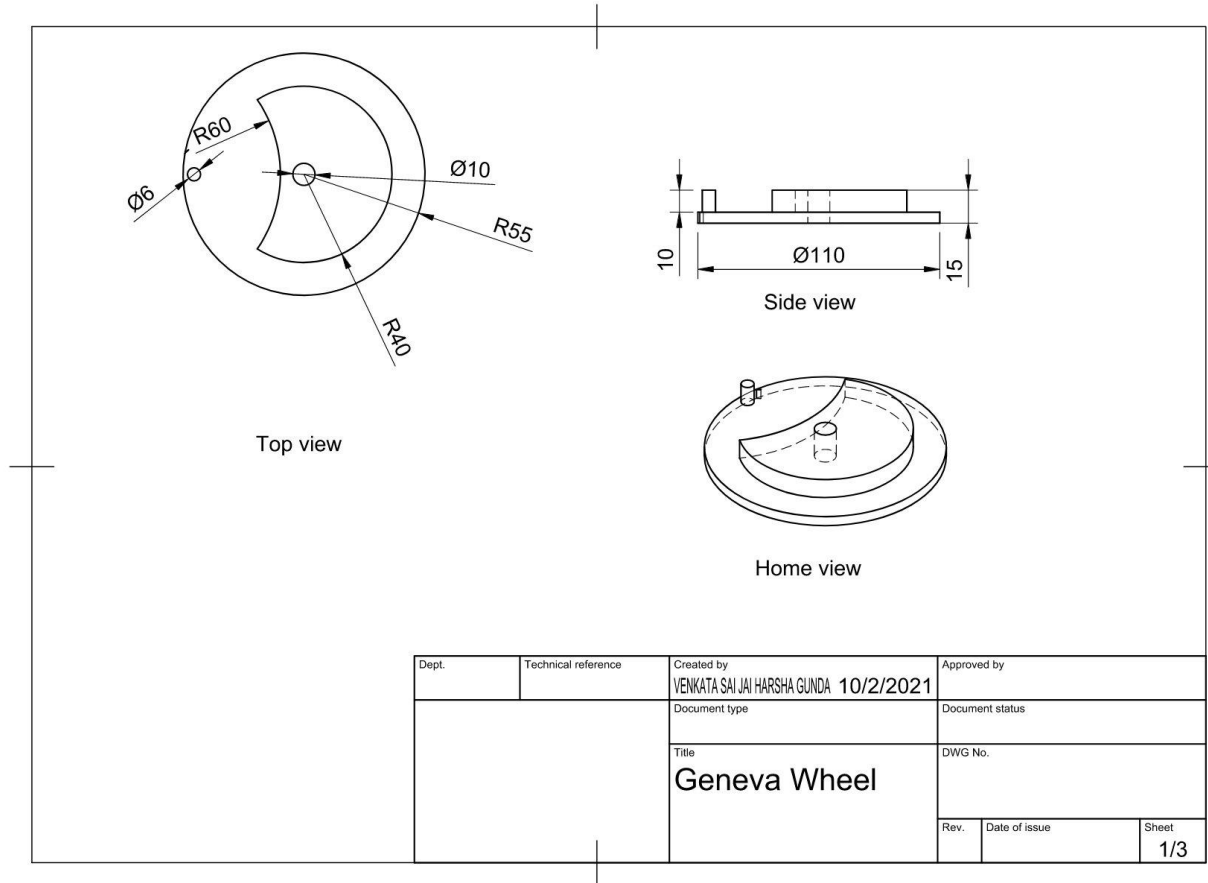
Geneva Mechanism



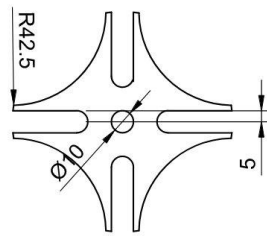
Animation



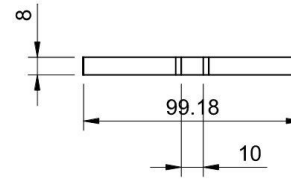
2D sketch's-Driver



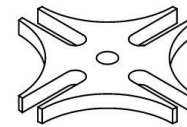
Geneva Wheel



Top View



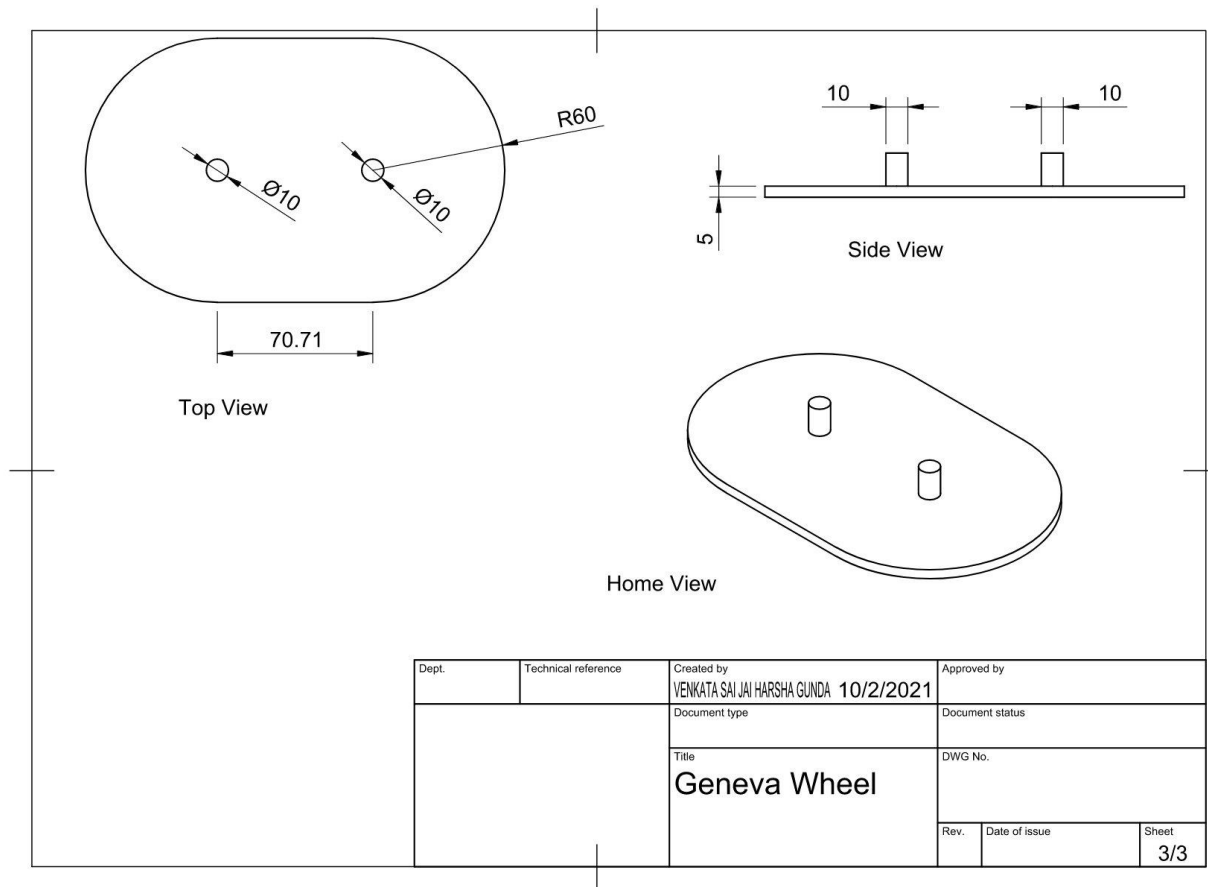
Side View



Home View

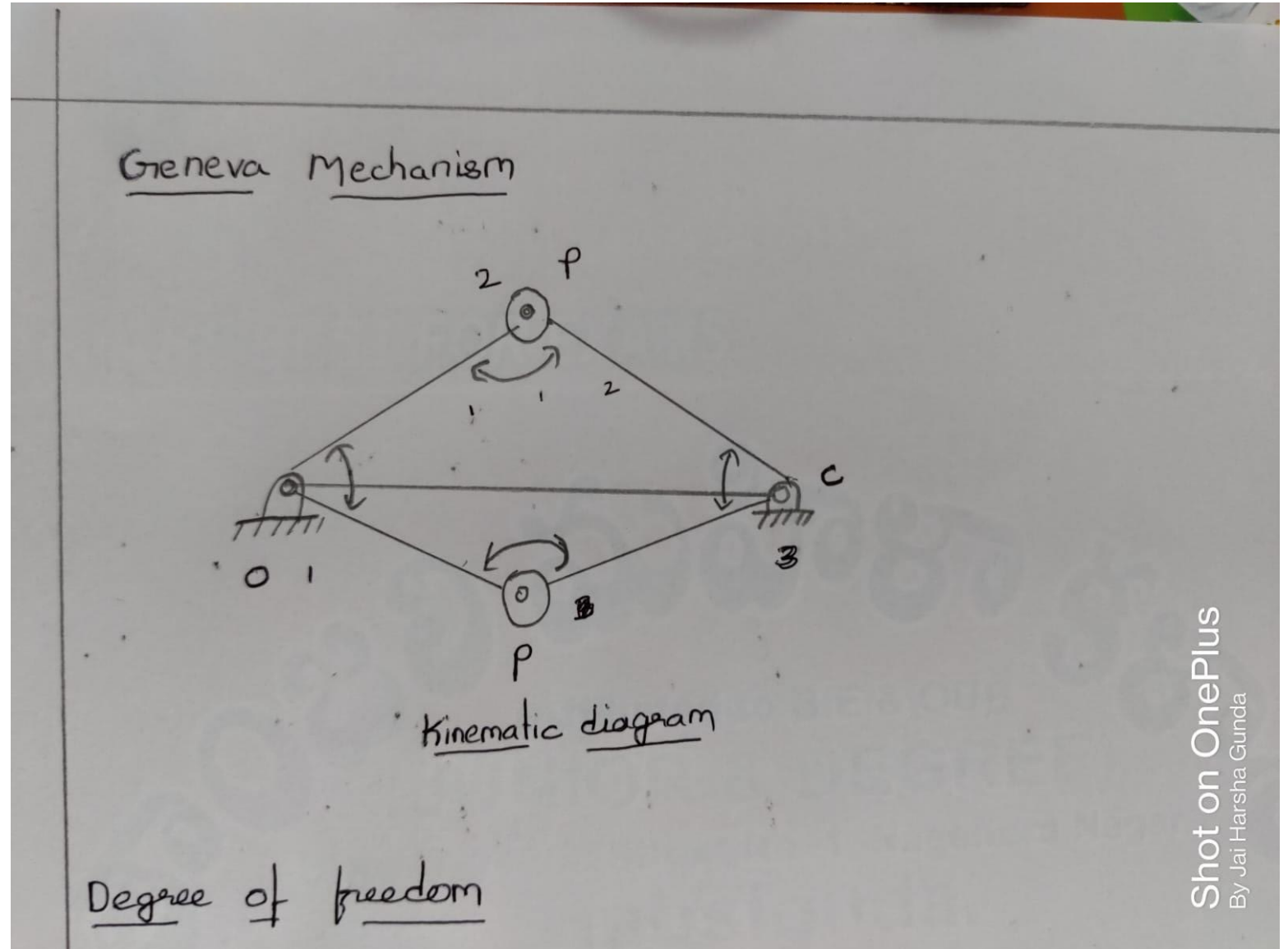
| | | | |
|-------|---------------------|--|-----------------|
| Dept. | Technical reference | Created by VENKATA SAI JAI HARSHA GUNDA 10/2/2021 | Approved by |
| | | Document type | Document status |
| | | Title Geneva Wheel | DWG No. |
| | | Rev. | Date of issue |
| | | Sheet | 2/3 |

Base Part



Kinematic Diagram.

Link 1 is the driver.
Link 2 is the Geneva wheel.
Link 3 is ground.



Degree of Freedom

Degree of freedom

$$DOF = 3(n-1) - 2J_p - \sum f_i$$

$$\text{Total no of links } n = 3$$

$$\text{Total no of joints } = J_p = 2$$

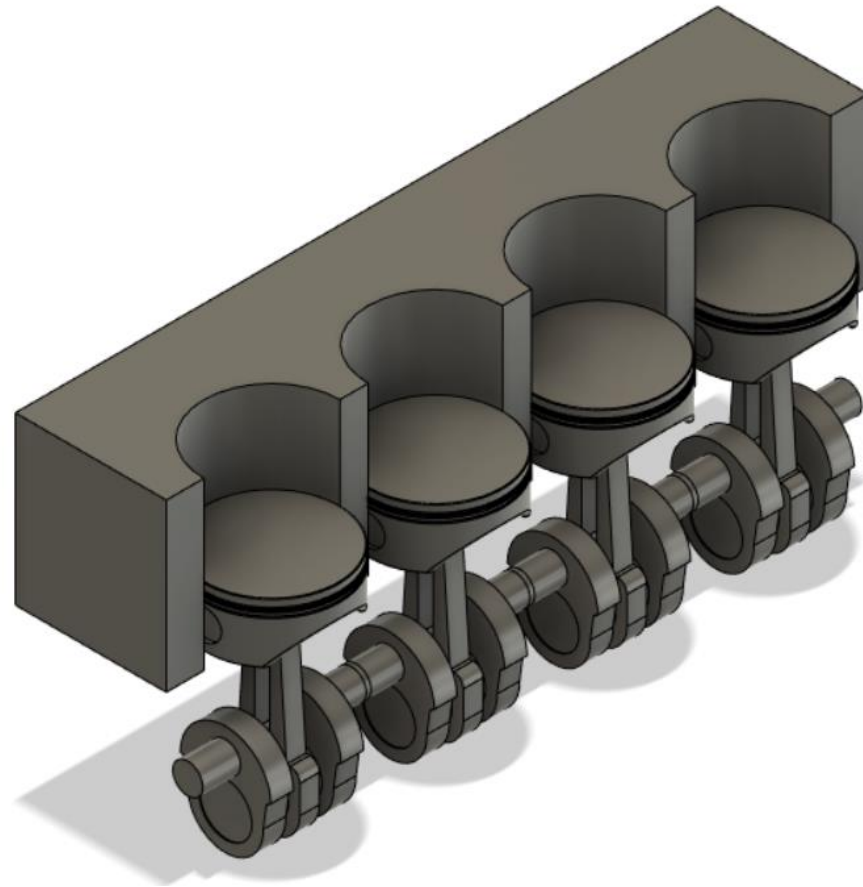
$$\sum f_i = 0$$

$$\begin{aligned}\text{Degree of freedom} &= 3(3-1) - 2(2) - 0 \\ &= 5 - 4\end{aligned}$$

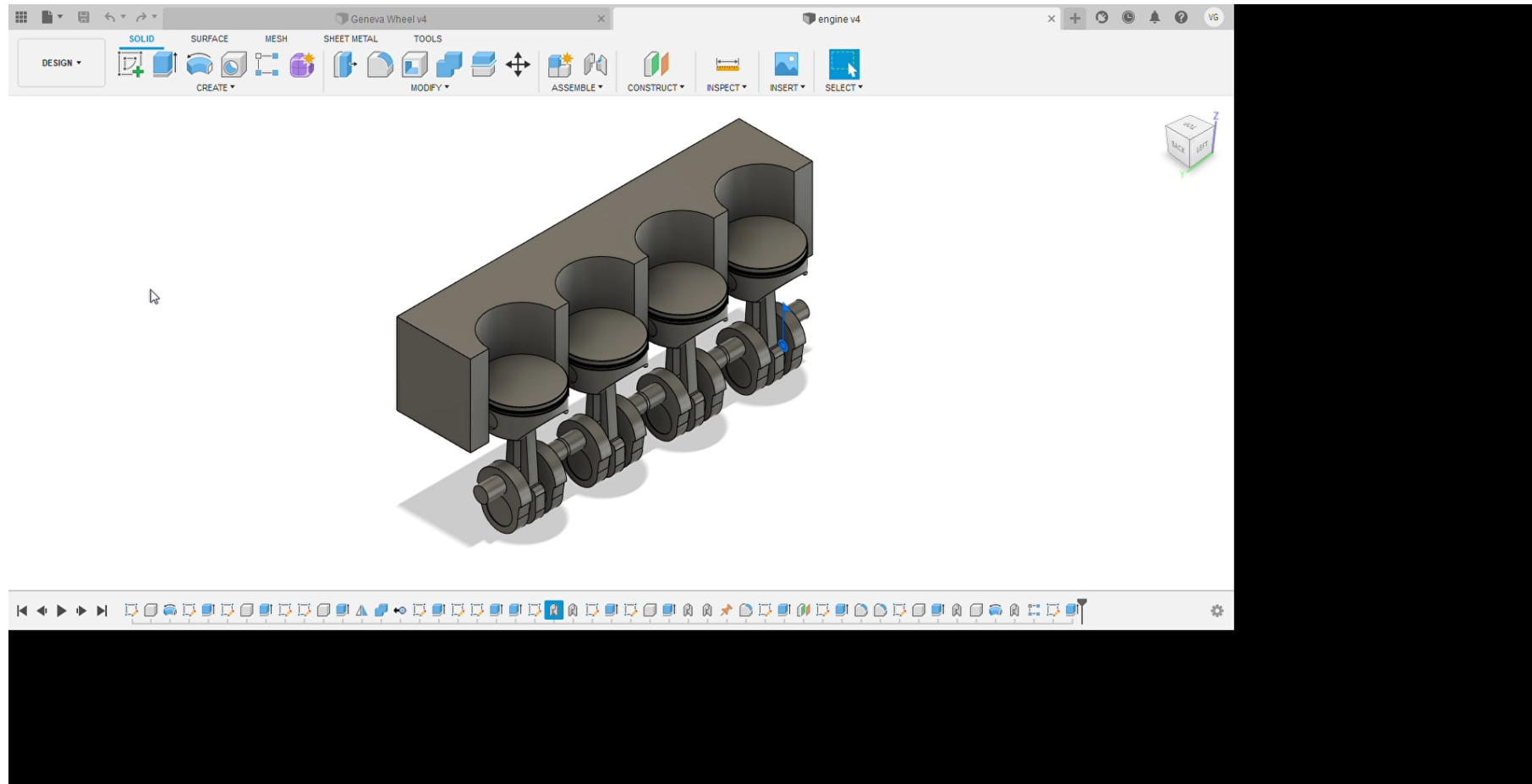
$$DOF = 1$$

∴ It is 4 bar mechanism so the degree of freedom is 1

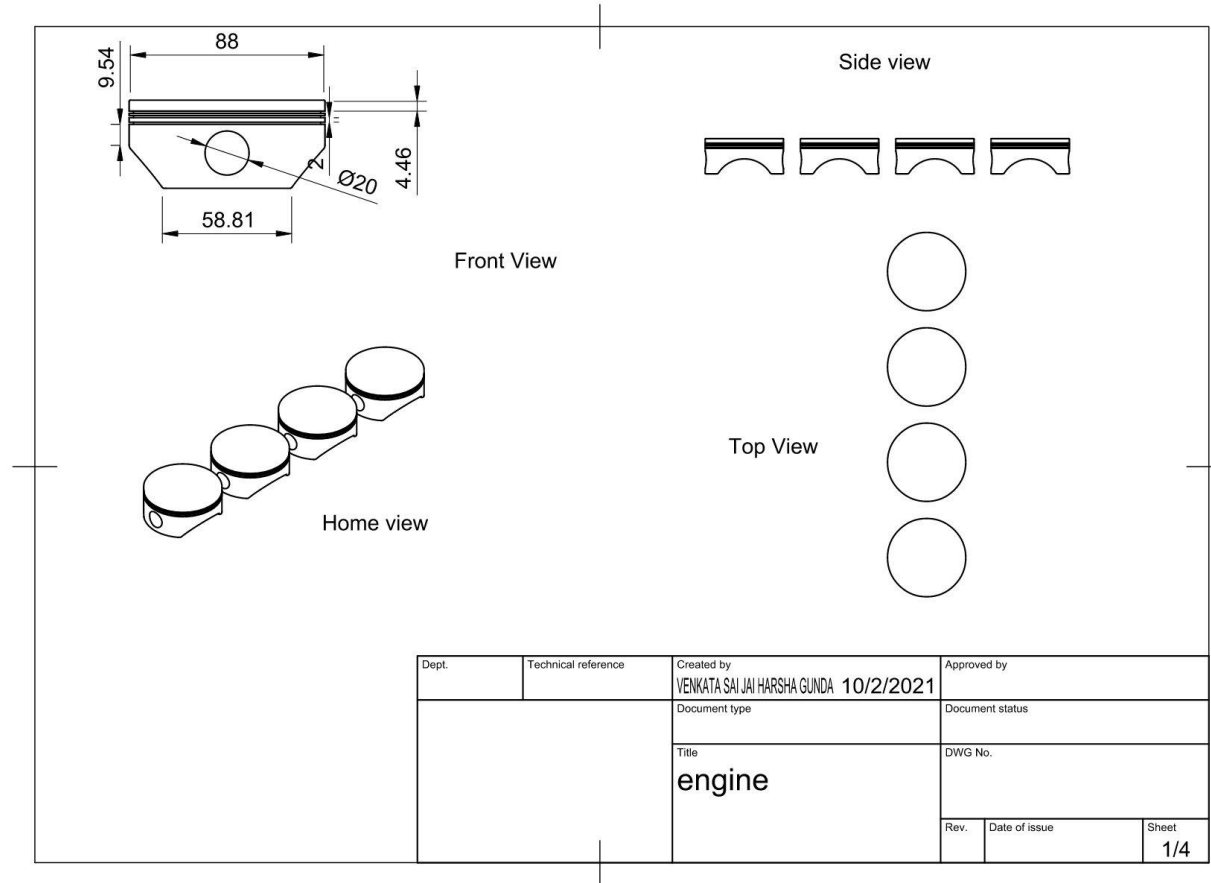
Multi Cylinder Engine



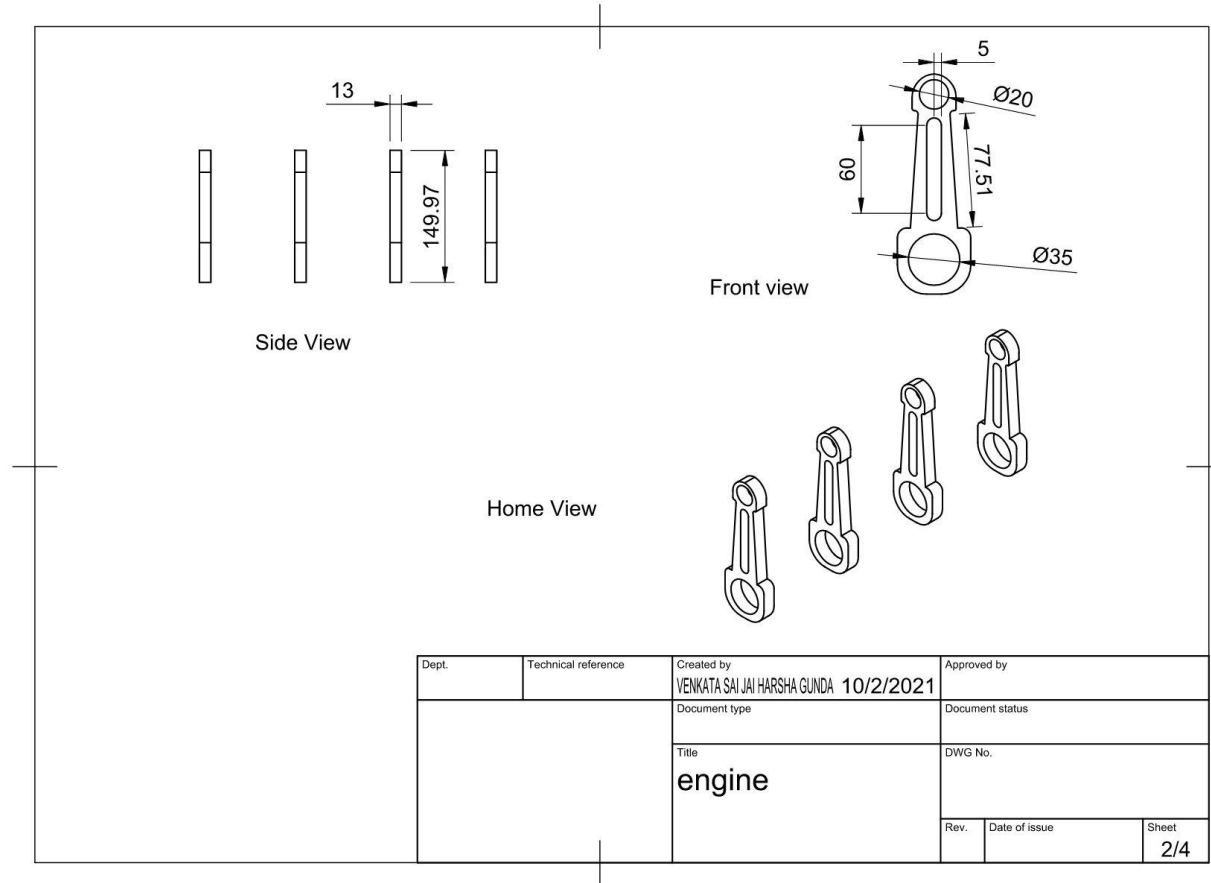
Animation



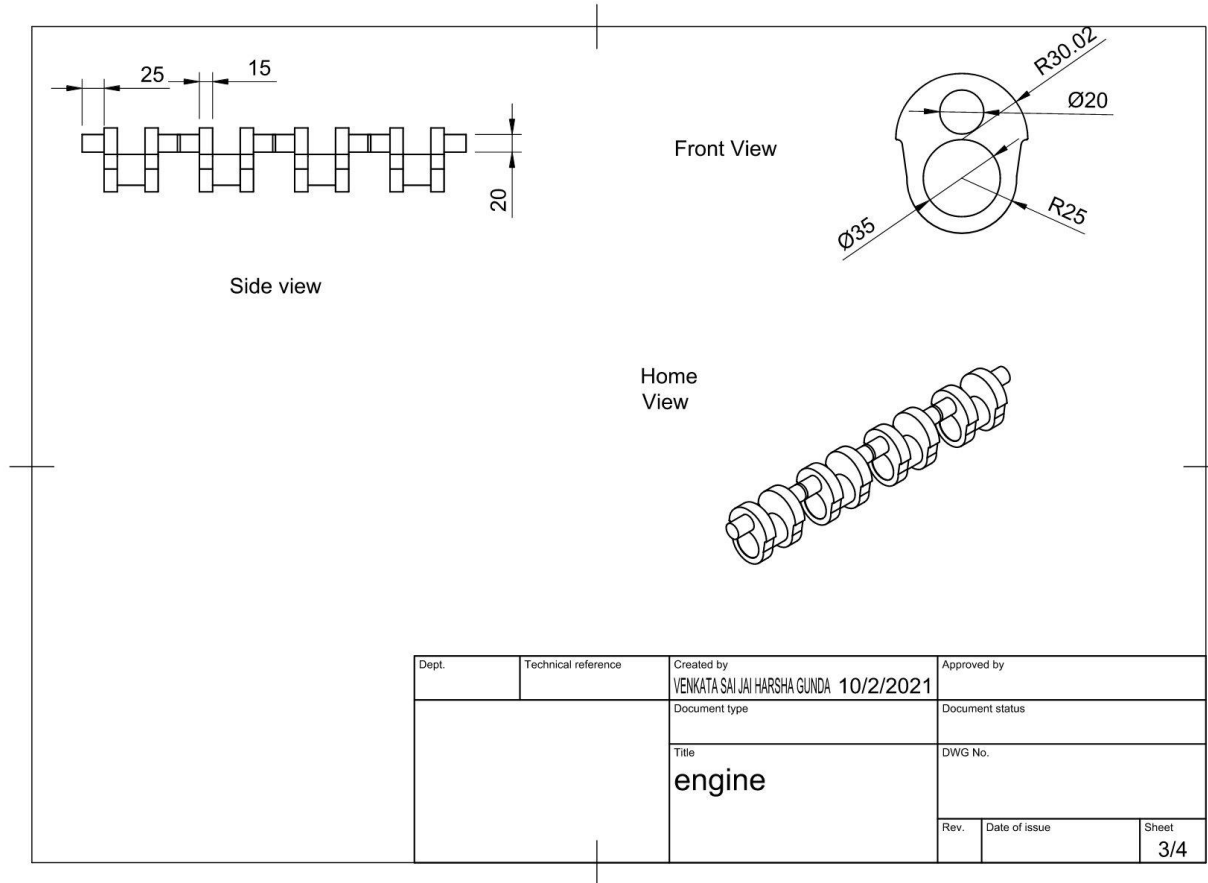
2D sketch's- Piston



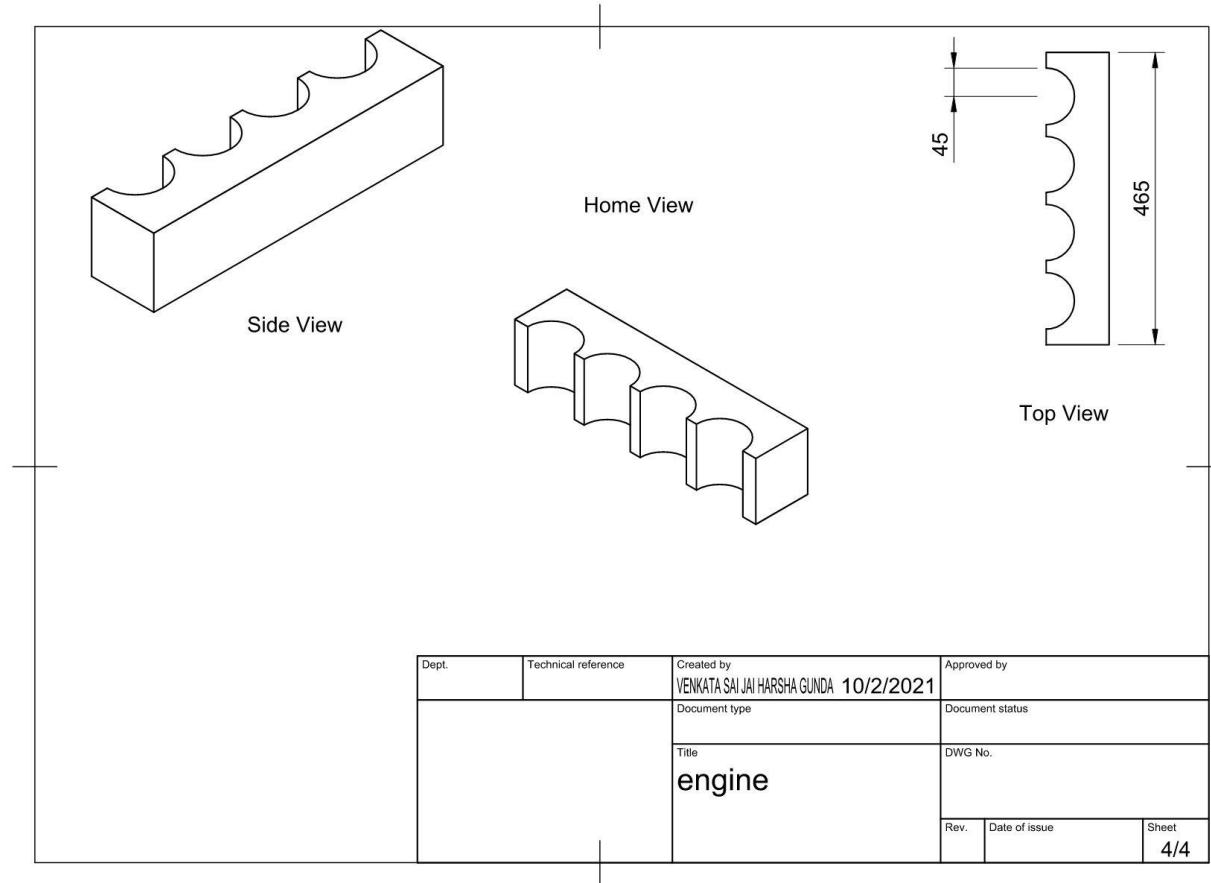
Crank Shaft



Connecting Rods



Back Case



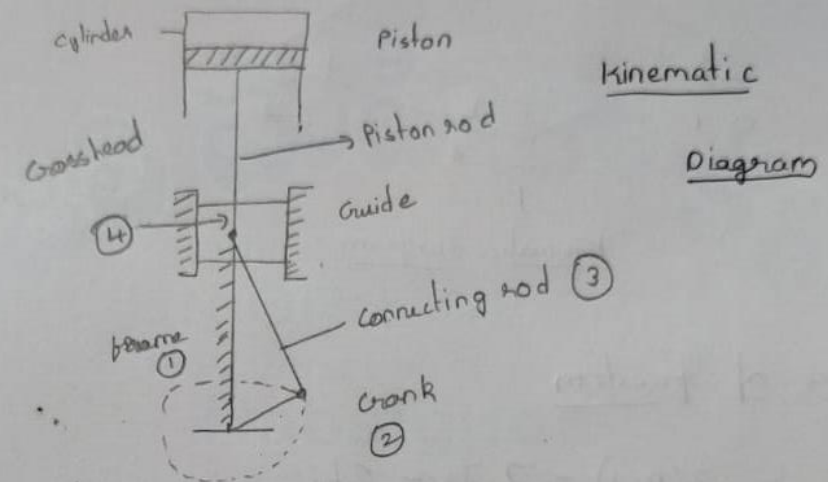
Kinematic Diagram

Shot on Omdia

Multi cylinder engine

* It is basic four bar chain mechanism.

* It has one sliding pair & 3 turning pairs.



* In this mechanism converts rotary motion into reciprocating motion & vice versa.

Degree of freedom

No of links $n_L = 4$

No of joints $n_J = 4$

$$\sum f_i = 0$$

Degree of freedom $F = 3(n_L - 1) - 2n_J - \sum f_i$

$$F = 3(4 - 1) - 2(4)$$

$$F = 9 - 8$$

$$\text{Dof } (F) = 1.$$

\therefore Degree of freedom of single cylinder engine = 1.

Degree of Freedom

Thank You