
System-level Analysis and Verification of Mixers

Jaijeet Roychowdhury

ECE Dept, University of Minnesota, Twin Cities

Outline

- The big picture: system-level simulation of portable/RF front-ends
- Automated macromodelling and its role
- Automated macromodelling techniques for mixers (and other linear time-varying systems)

Market and Circuit Trends

Market Trend: Portable Devices

- Proliferation of small, cheap, ubiquitous devices
 - ☞ cellphones, PDAs, wireless LANs, Bluetooth, two-way paging, SMS
 - ☞ 802.11g/a, 2.5G networks
 - ☞ next: 3G, UMTS

Demand for Portable Commns.

- 2 billion users worldwide by 2007
 - ☞ Maximum growth: SE Asia and China
 - ☞ India: 28M users (Dec 2003); 100M projected, 2005
- US: Tenfold growth by 2005 (200x?)
 - ☞ \$22–\$140b (IDC, Merrill-Lynch)
 - ☞ exceed PC growth over last decade: Intel

Drivers for Demand

■ Price

- ☞ India: 2.1M new subscribers, Dec 2003
 - ☞ “*driven by some of the lowest tariffs in the world*”

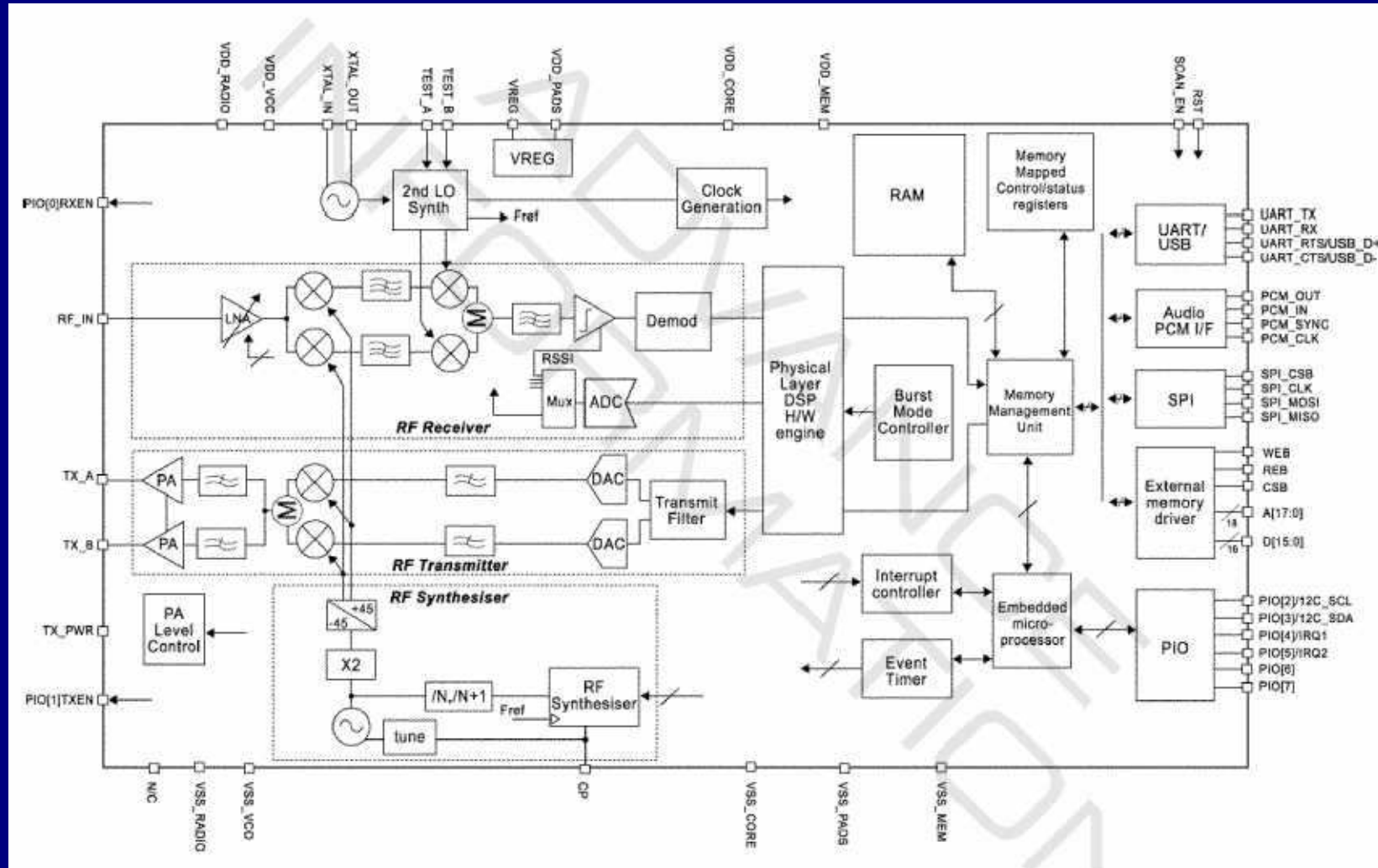
■ Competitive pressures

- ☞ rapid time to market of new designs

■ Design challenge: mixed-signal/RF blocks

- ☞ the *main* design bottleneck

Integrated Bluetooth Transceiver



- Cheap
- Low margins
- Must work first time

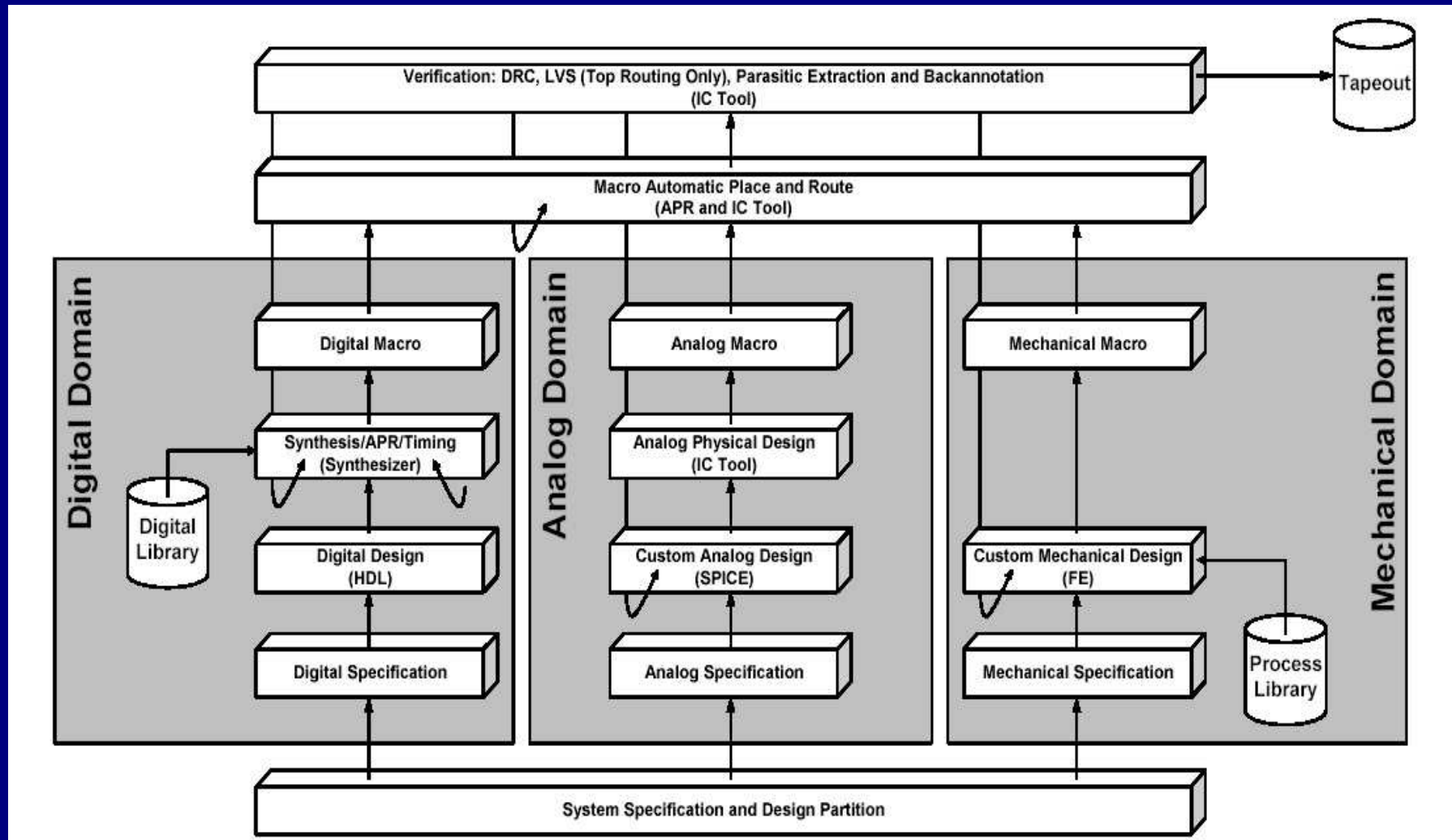
Important Mixed-Signal Blocks

- **Mixers**, phase detectors, frequency dividers, VCOs, PLLs
- LNAs, power amps
- ADCs, $\Sigma\Delta$ s, DACs
- z-domain switched-capacitor ckts: baseband filtering
- DC-DC power converters
- System focus: deliver everything working together

Mixed-Signal Simulation Needs

- Correct, speedy noise simulation
 - ☞ mixers, oscillators, PLLs
 - ☞ issues: nonlinearity, cyclostationarity
- Faster basic time- and frequency-domain simulation
 - ☞ VCOs, PLLs, mixers, ...
 - ☞ issues: fast-slow dynamics, strong nonlinearities
- Research to production tool: “Time-to-market”
 - ☞ need effective transition path
 - ☞ issue: traditionally extremely slow
- **Automated macromodelling techniques**
 - ☞ enabler for effective hierarchical system verification
 - ☞ issues: nonlinearity, **time-variation**; oscillator dynamics

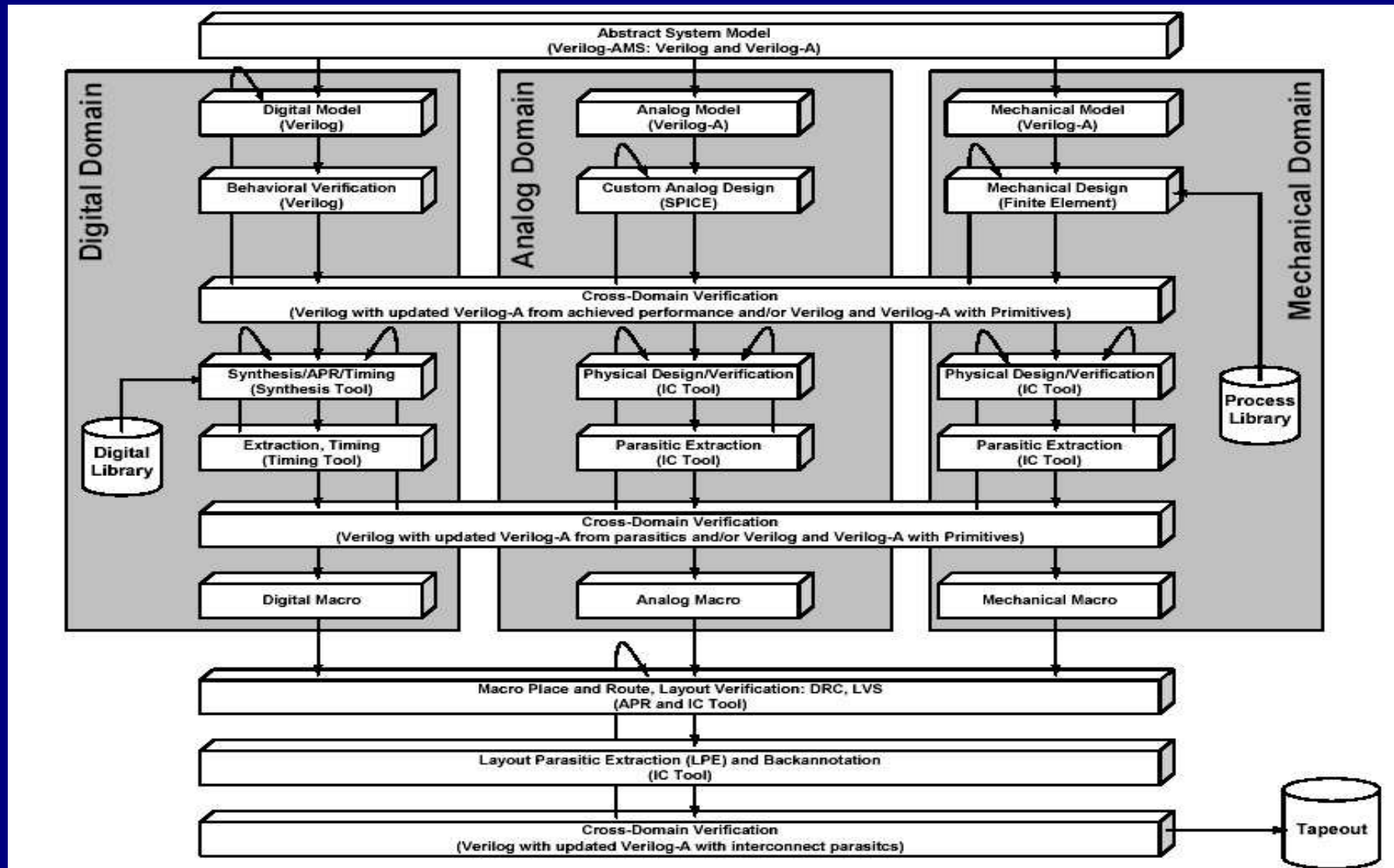
Today's Design Flow



Credits: McCorquodale et al, Univ Michigan • 3-5 spins = cutting edge; (10 at Lucent)

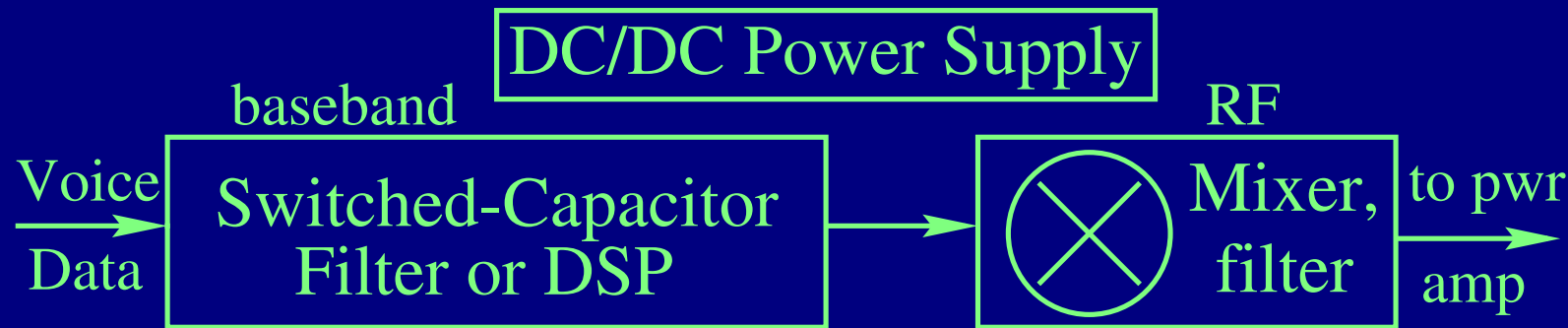
System-Verification-Based Design Flow

Credits: McCorquodale et al, Univ Michigan



Automated Macromodel Generation

Macromodelling Mixed-Signal Blocks



■ Substitute big block by small

- preserve I/O relationship

■ Speed system verification

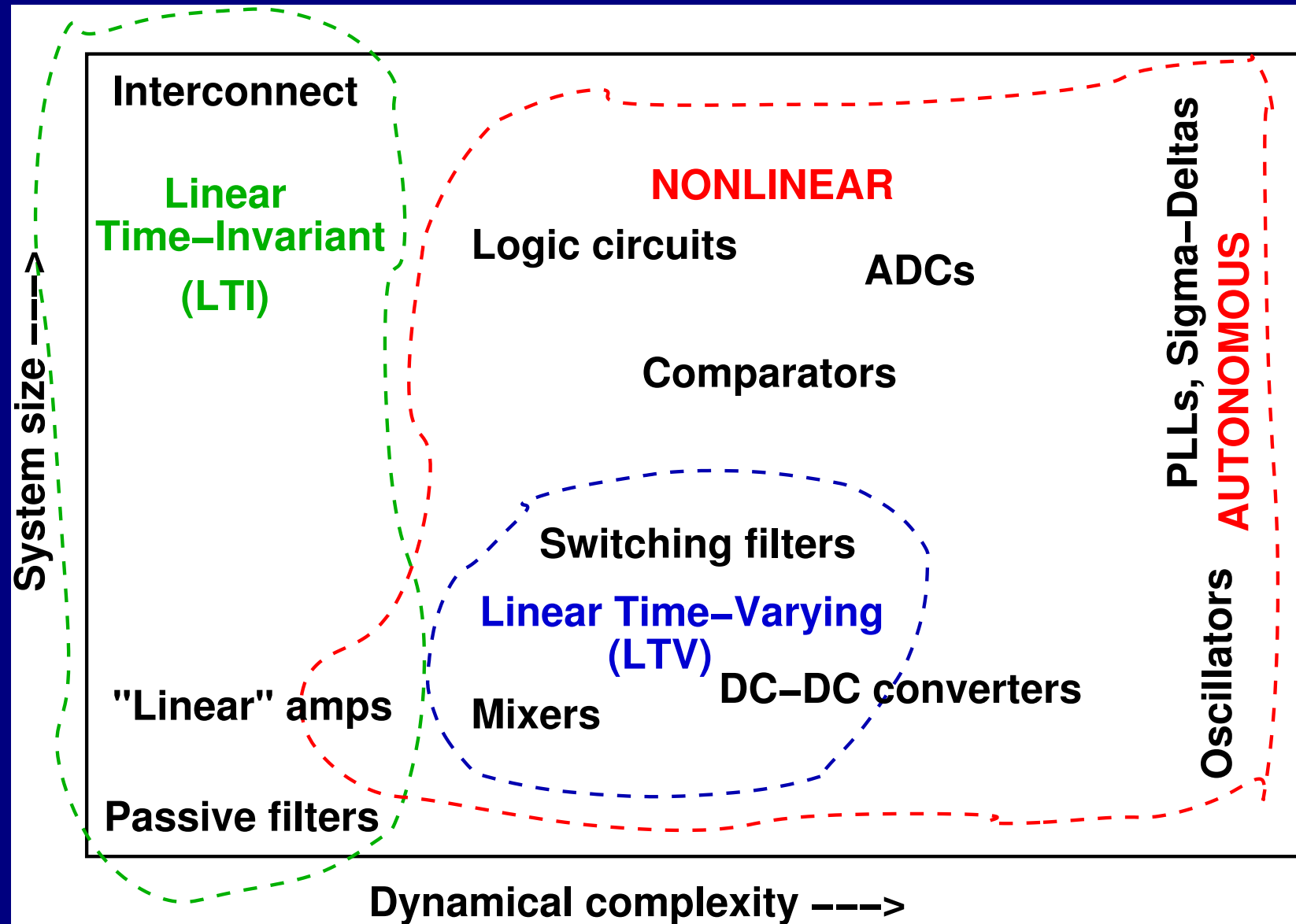
- simulate connection of macromodels

■ Automated macromodel generation

- Input: (large) SPICE deck
- Output: (small) SPICE/Matlab macromodel
- Fast/convenient: “Computers made of iron, let them work”^a
- Applicable to general classes of circuits

^aVladimir Rokhlin, ~1997

Classifying systems for Macromodelling



Types of Algorithmic Macromodelling

■ Linear Time Invariant (LTI) macromodelling

- ☞ application: interconnect networks (delay, crosstalk)
- ☞ AWE, PVL, PRIMA: moment-matching, Krylov subspace methods

■ Linear Time Varying (LTV) macromodelling

- ☞ mixers, sampling/switching circuits
- ☞ TVP (Time-Varying Padé)

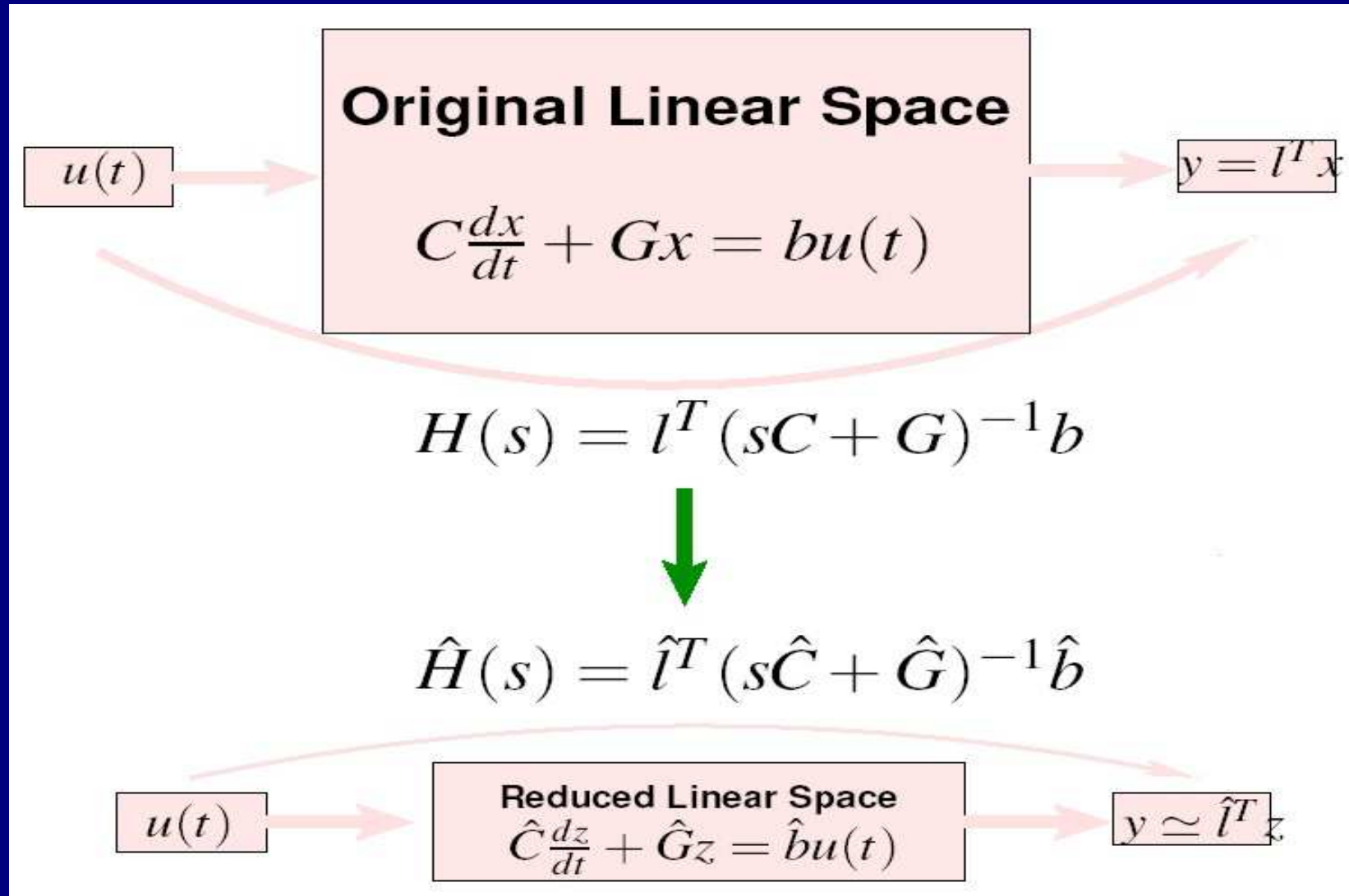
■ Weakly nonlinear macromodelling

- ☞ companding circuits, amplifier/mixer gain compression
- ☞ Low-order polynomial-based reduction

■ Strongly nonlinear macromodelling

- ☞ Piecewise polynomial (PWP): comparators, switching

Linear Time-Invariant MM



Macromodelling LTV Systems

- First obtain time-varying transfer function
- Problem: interaction of “system” and “input” time variations
- Solution: separate using multiple time scales

$$\frac{\partial[C(t)x(t)]}{\partial t} + G(t)x(t) = bu(t)$$
$$y(t) = d^T x(t)$$

\rightsquigarrow

$$\left[\frac{\partial}{\partial t_1} + \frac{\partial}{\partial t_2} \right] (C(t_1)\hat{x}) + G(t_1)\hat{x} = bu(t_2)$$
$$\hat{y}(t_1, t_2) = d^T \hat{x}(t_1, t_2)$$

- Time-varying operator form of transfer function

$$H(t_1, s) = d^T \left(\frac{\partial}{\partial t_1} C(t_1) + sC(t_1) + G(t_1) \right)^{-1} [b]$$

From LTV to Artificial MIMO LTI System

- Expand t_1 dependence in basis (eg, Fourier)
 - operator expression \rightsquigarrow MIMO LTI form
 - $H_{FD}(s) = D^T (sC_{FD} + J_{FD})^{-1} B_{FD}$
- Apply any (eg, Krylov-subspace-based) LTI model reduction method
 - Arnoldi, Lanczos methods reduce to size q system
- Map reduced LTI system back to LTV form
 - reduced model: $-T_q \frac{\partial x_q}{\partial t} + x_q = r_q u(t), \quad y(t) \approx l_q^T(t) x_q(t)$
 - $u(t) \mapsto y(t)$ relation approximated well

TVP: Time-Varying Padé

■ Prerequisites

- any SPICE-type circuit description, can be large
- nonlinear periodic steady-state (by HB or shooting)

■ Main steps and features

- choice of model-reduction algorithm (explicit/Arnoldi/Lanczos)
- choice of time-domain / frequency-domain computations
- solve $Jx = b$ (J = steady-state Jacobian)
- iterative methods essential for linear solution
- size of macromodel = q = # of solns
- macromodel in LTI + memoryless form
- poles/residues/transfer-plots produced

Application to RF mixer block

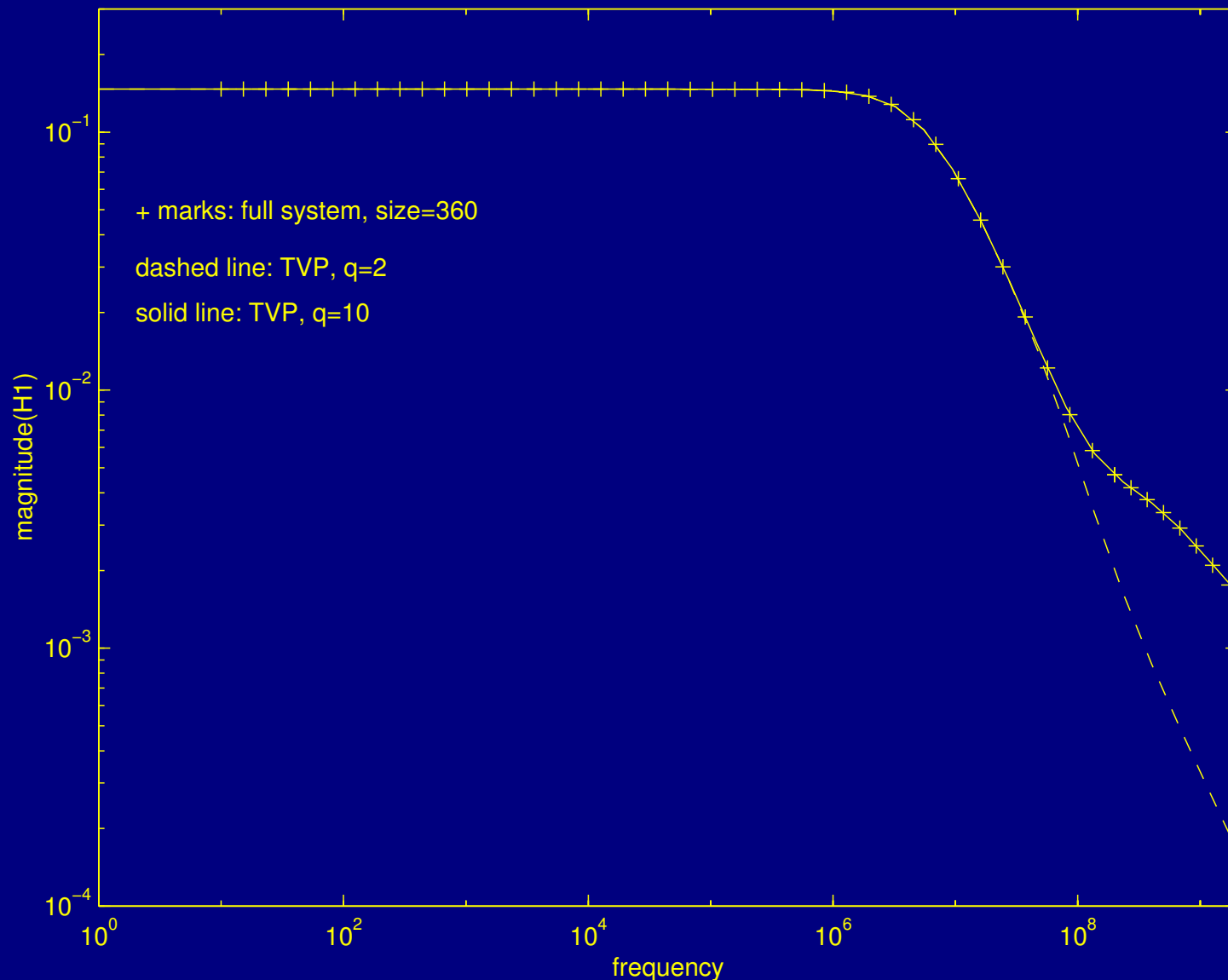
■ I-channel mixer and buffer block (Lucent ME W2013 RFIC)

- 360 nodes, $RF \approx 80\text{kHz}$, $LO = 178\text{MHz}$
- Steady-state: Harmonic Balance with 10 LO harmonics, zero RF input

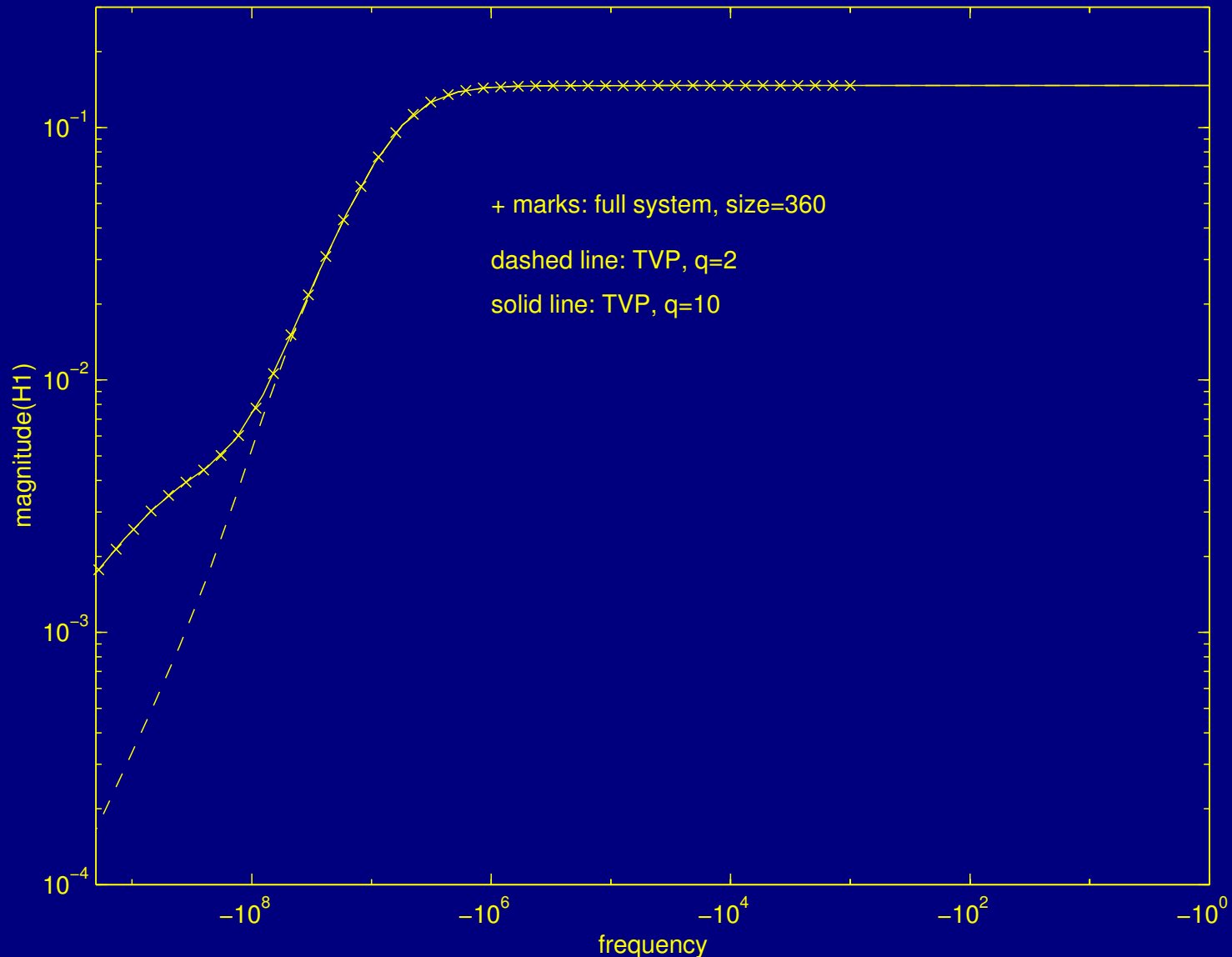
■ TVP: Lanczos process on frequency-domain Jacobian

- $q = 2$: provides reasonable macromodel
- $q = 10$: matches xfer fn upto twice LO frequency
- size reduction: 30–100; macromodel evaluation speedup: > 500

W2013 mixer: upconversion transfer function, +ve frequencies



W2013 mixer: upconversion transfer function, -ve frequencies



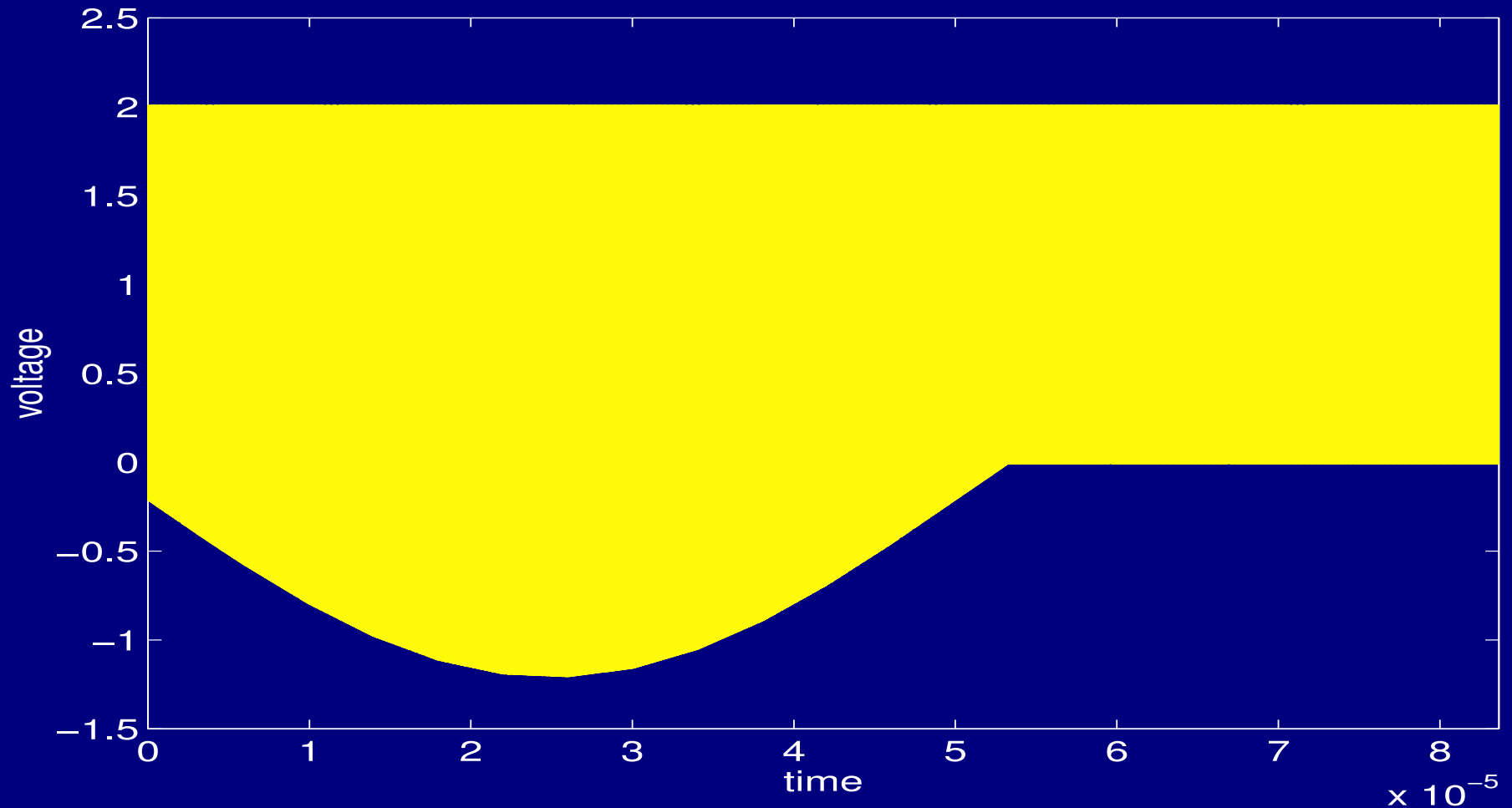
W2013 mixer: poles of macromodel

TVP, $q = 2$	TVP, $q = 10$
-5.3951e+06	-5.3951e+06
-6.9196e+07 - j 3.0085e+05	-9.4175e+06
	-1.5588e+07 - j 2.5296e+07
	-1.5588e+07 + j 2.5296e+07
	-6.2659e+08 - j 1.6898e+06
	-1.0741e+09 - j 2.2011e+09
	-1.0856e+09 + j 2.3771e+09
	-7.5073e+07 - j 1.4271e+04
	-5.0365e+07 + j 1.8329e+02
	-5.2000e+07 + j 7.8679e+05

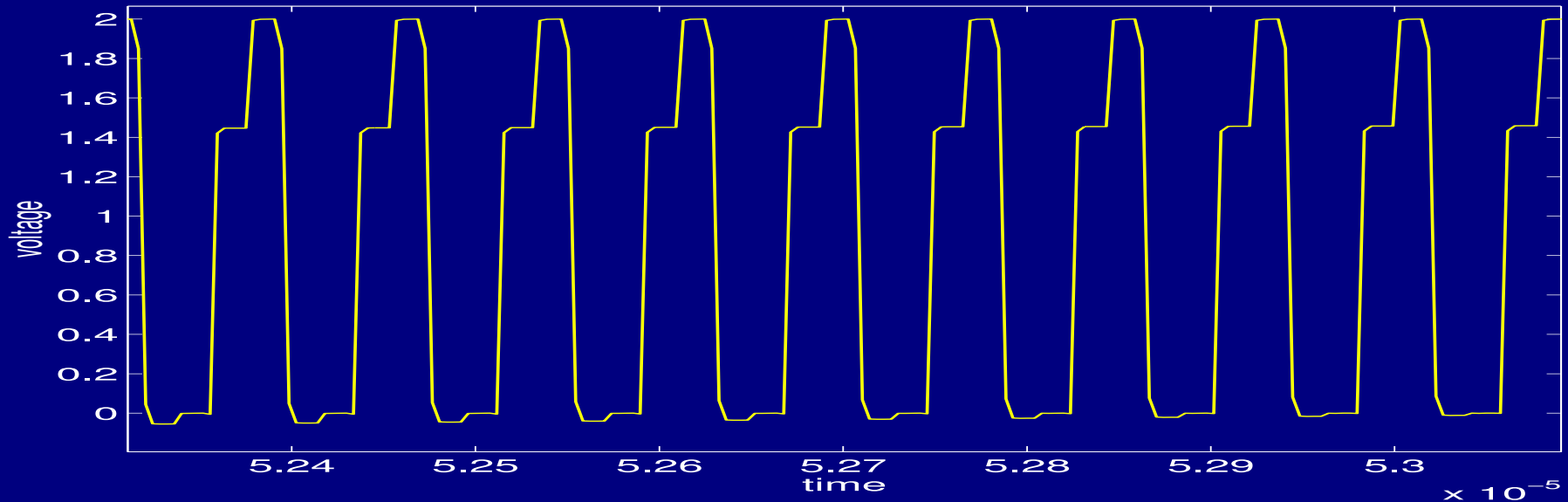
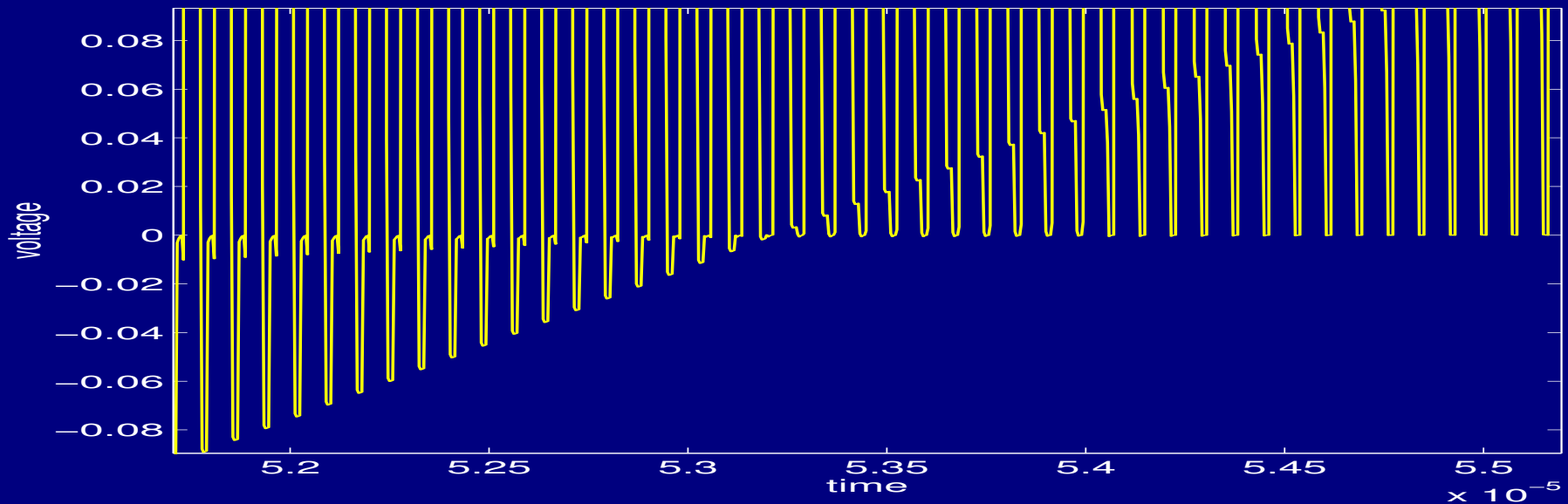
Switched-Capacitor Integrator

- Lossy balanced design;
350 MOSFETs
- clock: 12.8 MHz; test
signal: 10 kHz

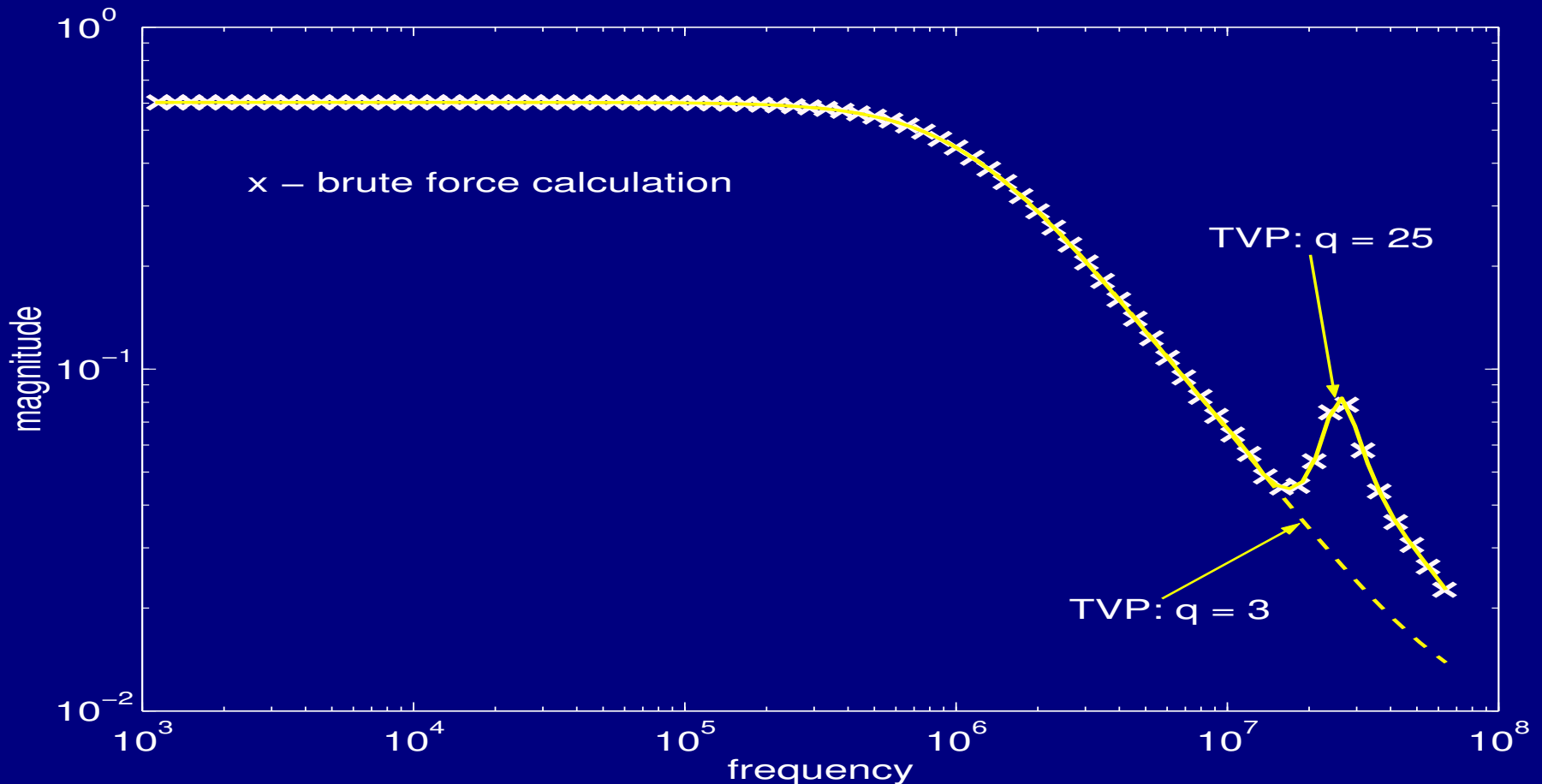
Switched-Capacitor Integrator



SC Integrator: transient detail

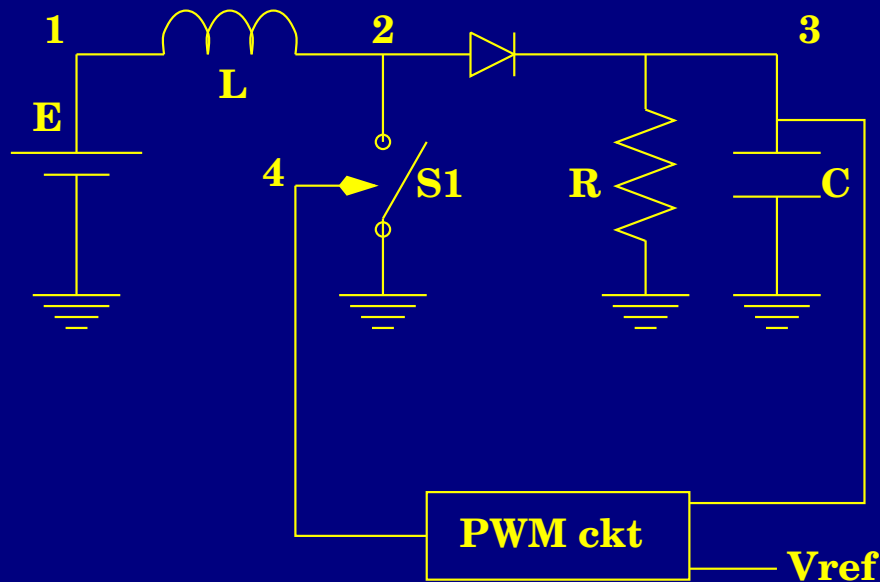


TVP on SC Integrator



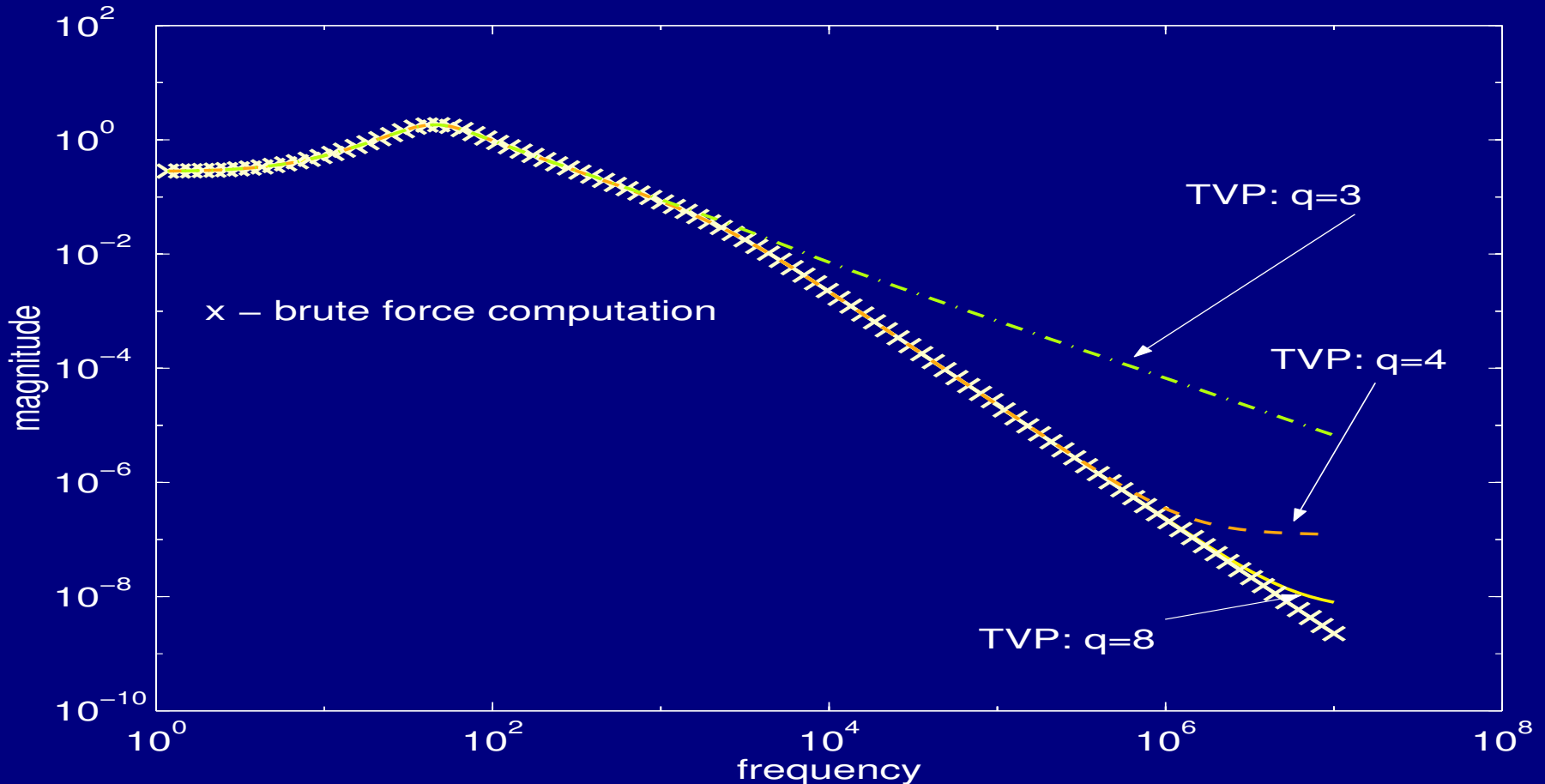
$$\frac{0.613}{j2\pi f - (-1.1e6)} + \frac{1.02e-4}{j2\pi f - (-1.68e5)} + \frac{9.81e-3}{j2\pi f - (-1.2e9)}$$

DC/DC Switching Power Converter



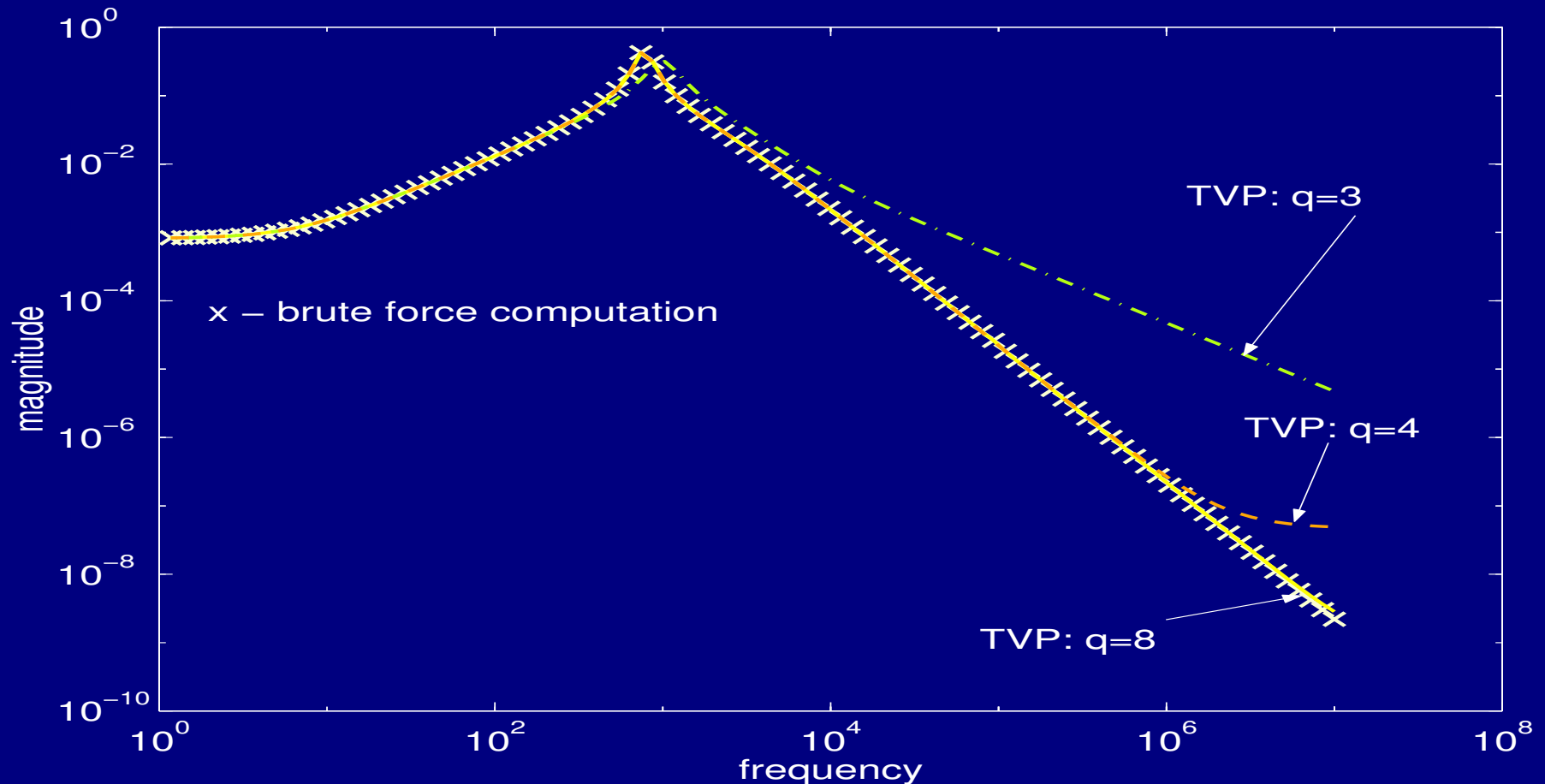
- clock: 100 kHz; PWM gain: 10
- V_{ref} : 1.4V; RC pole \approx 20 Hz
- Steady-state: Shooting (\approx 200 points)

TVP: Switching Converter, gain=10



$$\frac{-0.147 \mp 1.1j}{j2\pi f - (-24.66 \mp 38.36j)} + \frac{0.0366}{j2\pi f - (-250.74)} + \text{small}$$

Switching Converter, gain=1000



$$\frac{-0.0124 \mp 0.0455j}{j2\pi f - (+80.32 \mp 773.4j)} + \frac{0.0239}{j2\pi f - (-2854.9)} + \text{small}$$

Conclusion

- TVP - automated macromodelling for mixers and other LTV systems
 - weak signal-path nonlinearities also incorporated
- Automated nonlinear macromodelling: coming soon (?)
 - oscillators, VCOs (phase/amplitude domain)
 - LNAs, mixers, switching filters, op-amps, comparators
 - large digital aggressor blocks: interference macromodels
 - from research idea \Rightarrow designer tool: open-source prototypes
- Automated MM: critical enabler for first-time-correct SoC design methodologies