

Chapter 2 — Kinematics (NEET 2025)

1. Introduction – The Language of Motion

Everywhere around you, something is moving: cars on the road, planets around the Sun, blood inside your veins, even the electrons in the wires of your phone charger.

Kinematics is the branch of physics that describes *how* things move—without asking *why* they move.

So, we're not yet worrying about forces or energy. We're simply learning to describe and measure motion:

- How far?
- How fast?
- In what direction?
- How the motion changes with time?

Mastering kinematics is like learning the **grammar of motion**—it gives you the vocabulary and equations that later help you understand forces, work, and energy.

2. Types of Motion

1. **Translatory motion** – The entire body moves in the same direction.
→ Example: a car moving on a straight road.
2. **Rotational motion** – The body spins about an axis.
→ Example: the spinning of a ceiling fan.
3. **Oscillatory motion** – Back-and-forth movement about a mean position.
→ Example: pendulum, guitar string.

For now, we'll deal mainly with *translatory motion*, especially **motion along a straight line (1-D)** and **motion in a plane (2-D)**.

3. Basic Quantities of Motion

Quantity	Symbol	Definition	SI Unit
Distance	s	Length of actual path	meter (m)
Displacement	→s	Straight-line change of position	meter (m)
Speed	v	Rate of change of distance	m/s

Quantity	Symbol	Definition	SI Unit
Velocity	$\rightarrow v$	Rate of change of displacement	m/s
Acceleration	$\rightarrow a$	Rate of change of velocity	m/s ²

Distance vs Displacement

Distance only tells *how much ground* you covered, while displacement tells *where you ended up relative to start*.

If you jog 3 km east then 4 km north:

- Distance = 7 km
- Displacement = $\sqrt{(3^2 + 4^2)} = 5$ km northeast

Hence, **displacement** \leq **distance** always.

4. Speed and Velocity

4.1 Average and Instantaneous

Average speed = $\frac{\text{Total distance}}{\text{Total time}}$

Average velocity = $\frac{\text{Net displacement}}{\text{Total time}}$

Instantaneous velocity is the velocity at a particular moment \rightarrow slope of the position–time graph at that point.

5. Graphical Interpretation

Graphs make motion visible.

5.1 Position–Time (x–t) Graph

- Slope = velocity
- Straight line \rightarrow uniform velocity
- Curved line \rightarrow non-uniform velocity

5.2 Velocity–Time (v–t) Graph

- Slope = acceleration
- Area under graph = displacement

5.3 Acceleration–Time (a–t) Graph

- Area under curve = change in velocity

Understanding these graphs gives you an intuitive feel of motion—exactly what NEET loves to test.

6. Equations of Uniformly Accelerated Motion

For motion with constant acceleration (a):

$$v = u + at, \quad s = ut + \frac{1}{2}at^2, \quad v^2 = u^2 + 2as$$

where

u = initial velocity, v = final velocity, s = displacement, t = time.

These hold only when acceleration is constant.

Example:

A car starts from rest ($u = 0$), accelerates at 2 m/s^2 for 5 s .

$$\rightarrow v = 0 + 2 \times 5 = 10 \text{ m/s}$$

$$\rightarrow s = 0 + \frac{1}{2} \times 2 \times 25 = 25 \text{ m}$$

Hence the car moves 25 m and reaches 10 m/s .

7. Motion Under Gravity

Near Earth's surface, all bodies fall with the same **acceleration due to gravity** (g) $\approx 9.8 \text{ m/s}^2$ downward.

Equations of motion become:

$$v = u + gt, \quad s = ut + \frac{1}{2}gt^2, \quad v^2 = u^2 + 2gs$$

When thrown upward, take upward as positive and $g = -9.8 \text{ m/s}^2$.

Example:

A ball thrown upward at 20 m/s :

At highest point $v = 0$

$$\rightarrow 0 = 20 - 9.8t \rightarrow t \approx 2.04 \text{ s}$$

$$\text{Height} = \frac{u^2}{2g} = \frac{20^2}{19.6} \approx 20.4 \text{ m.}$$

8. Relative Velocity in One Dimension

Motion is always *relative*—we measure velocity with respect to some reference.

If object A moves at velocity v_a and object B at v_b (in same line),

$$v_{AB} = v_A - v_B \quad v_{\{AB\}} = v_{\{A\}} - v_{\{B\}} \quad v_{AB} = v_A - v_B$$

is velocity of A relative to B.

Example: Two cars move east at 60 km/h and 40 km/h.

Relative velocity = 20 km/h east.

If opposite directions \rightarrow 100 km/h.

This simple idea becomes vital in river-boat and air-plane problems later.

9. Vector Nature of Motion

In one dimension, direction is shown by sign (+/-).

In two or three dimensions, we use **vectors**.

A vector has both **magnitude** and **direction**, represented as $\rightarrow A$.

Operations on vectors follow geometry rules:

Operation	Expression	Meaning
Addition	$\rightarrow R = \rightarrow A + \rightarrow B$	Combine effects
Subtraction	$\rightarrow A - \rightarrow B = \rightarrow A + (-\rightarrow B)$	Opposite direction
Dot product	$\rightarrow A \cdot \rightarrow B = AB \cos \theta$	Scalar \rightarrow projection
Cross product	$\rightarrow A \times \rightarrow B = AB \sin \theta \hat{n}$	Vector \rightarrow perpendicular

For **2-D motion**, resolve every vector into x- and y-components:

$$A_x = A \cos \theta, A_y = A \sin \theta \quad A_x = A \cos \theta, A_y = A \sin \theta$$

Then apply 1-D equations separately to x and y.

10. Projectile Motion (2-D Motion)

Projectile motion is the classic NEET favorite: a particle thrown obliquely near Earth moves along a curved path called a **parabola**.

Let the projectile be thrown with velocity u at an angle θ above the horizontal.

Horizontal component = $u_x = u \cos \theta$

Vertical component = $u_y = u \sin \theta$

Equations of motion:

$$x = u \cos \theta t, y = u \sin \theta t - \frac{1}{2} g t^2 \quad x = u \cos \theta t, \quad y = u \sin \theta t - \frac{1}{2} g t^2$$

Eliminate t to get trajectory:

$$y = x \tan \theta - \frac{g x^2}{2 u^2 \cos^2 \theta} \quad y = x \tan \theta - \frac{g x^2}{2 u^2 \cos^2 \theta}$$

— a parabola.

Key Results

- **Time of flight:** $T = \frac{2u \sin \theta}{g}$ $T = \frac{2u \sin \theta}{g}$
- **Maximum height:** $H = \frac{u^2 \sin^2 \theta}{2g}$ $H = \frac{u^2 \sin^2 \theta}{2g}$
- **Range:** $R = \frac{u^2 \sin 2\theta}{g}$ $R = \frac{u^2 \sin 2\theta}{g}$
- For same u , R is maximum at $\theta = 45^\circ$.

Example:

$$u = 20 \text{ m/s}, \theta = 45^\circ$$

$$\rightarrow T = (2 \times 20 \times 0.707) / 9.8 \approx 2.89 \text{ s}$$

$$\rightarrow R = 20^2 \sin 90^\circ / 9.8 \approx 40.8 \text{ m}.$$

11. Motion in a Circle

When an object moves in a circle of radius r at speed v , it changes direction continuously, meaning it has **centripetal acceleration** toward the center.

$$a_c = \frac{v^2}{r} \quad a_c = \frac{v^2}{r}$$

and **centripetal force** needed:

$$F_c = m \frac{v^2}{r} \quad F_c = m \frac{v^2}{r}$$

This keeps planets in orbit, cars turning safely, and electrons circling nuclei (conceptually).

Example:

A 1000 kg car turns a curve of radius 50 m at 10 m/s.

Required $F = (1000 \times 10^2) / 50 = 2 \times 10^4 \text{ N}$ toward center.

12. Relative Velocity in Two Dimensions

When two motions occur in perpendicular directions (like a boat crossing a river), combine them as vector components.

If river flows east with velocity v_r and boat velocity relative to water is v_b north,

Resultant velocity relative to ground:

$$v = \sqrt{v_b^2 + v_r^2} \quad v = \sqrt{v_b^2 + v_r^2}$$

Direction: $\tan \theta = v_r / v_b$.

If you want the boat to go straight north, aim *against* the current by angle θ so $\tan \theta = v_r/v_b$.

These are typical NEET conceptual numericals.

13. Relative Motion Between Two Projectiles

If two projectiles are fired simultaneously, their relative motion is itself a projectile.

Time of flight remains same, relative velocity determines path difference.

This concept builds intuition for “collision in air” and “meeting point” problems.

14. Derivation Recap and Dimensional Check

Formula	Dimensional Check
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$s = ut + \frac{1}{2}at^2$	$[L] = [L T^{-1} T] + [L T^{-2} T^2] \checkmark$
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$v^2 = u^2 + 2as$	$[L^2 T^{-2}]$ both sides \checkmark
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$R = u^2 \sin 2\theta / g$	$[L]$ both sides \checkmark
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Always check dimensions → a good NEET trick to catch wrong options quickly.

15. Common Conceptual Questions

1. *Can velocity be zero when acceleration isn't?*
 \checkmark Yes—at highest point of projectile, velocity = 0 vertically but acceleration = g.
 2. *Can acceleration be zero when velocity isn't?*
 \checkmark Yes—uniform motion (constant velocity).
 3. *Why does a coin fall slower in air than in vacuum?*
 \checkmark Air resistance → additional upward acceleration reduces net g.
 4. *When are average speed and average velocity equal?*
 \checkmark When motion is in a straight line in one direction.
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16. Application of Kinematics in Real Life

- **Automotive design:** acceleration, braking distance, turning radius.
- **Sports:** trajectory of cricket ball, long-jump, basketball shot.
- **Aerospace:** rocket launch angles and escape velocity.

- **Medical:** blood-flow measurement (Doppler effect uses velocity).
- **Meteorology:** predicting projectile debris or rainfall patterns.

Everywhere something moves, kinematics silently governs it.

17. Summary – Key Takeaways

1. **Kinematics** describes motion without forces.
2. **Scalar quantities** have only magnitude; **vectors** have magnitude + direction.
3. **Displacement \leq distance.**
4. **Velocity–time graphs** give displacement; **slope = acceleration.**
5. **Equations of motion** apply only for constant acceleration.
6. **Projectile motion** \rightarrow parabolic; maximum range at 45° .
7. **Circular motion** \rightarrow centripetal force $= mv^2/r$.
8. **Relative velocity** helps solve river-boat, rain-man, and airplane problems.
9. Always check **units & dimensions** for validity.
10. Kinematics builds foundation for all mechanics — master it to breeze through the next chapters.