

## Chapter 10 – Oscillations and Waves (NEET 2025)

The same tone and structure as before: detailed but readable, formula boxes, examples, and exam focus.

### 1. Introduction – The World of Repetitive Motion

If you pluck a guitar string, the vibration repeats.

If you watch a clock pendulum, it swings back and forth.

If you listen to sound, it's nothing but a pressure wave repeating again and again.

Such repeating motion is called **periodic motion**, and the simplest among them is **simple harmonic motion (SHM)**.

In this chapter we explore the mathematics of oscillations and how they combine to form **waves** that travel through space and matter.

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### 2. Periodic and Oscillatory Motion

- **Periodic motion:** motion that repeats itself after equal time intervals (T).  
Examples: Earth's rotation, AC current, revolution of moon.
- **Oscillatory motion:** periodic motion to and fro about a mean position.  
Every oscillation is periodic, but not every periodic motion is oscillatory (e.g., uniform circular motion is periodic but not linear oscillation).

#### Important terms

##### Symbol      Quantity      Meaning

T      Time period      Time to complete one oscillation

f      Frequency      Number of oscillations per second (  $f = 1/T$  )

A      Amplitude      Maximum displacement from mean

$\phi$       Phase      State of motion at given time

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### 3. Simple Harmonic Motion (SHM)

A motion is **simple harmonic** if acceleration is directly proportional to displacement and always directed toward mean position:

$$a = -\omega^2 x \quad a = -\omega^2 x$$

where  $\omega$  is **angular frequency**.

Integrating gives position and velocity equations:

$$x = A \sin(\omega t + \phi) \quad v = A\omega \cos(\omega t + \phi) \quad a = -A\omega^2 \sin(\omega t + \phi)$$

## Relations

$$v_{max} = \omega A, a_{max} = \omega^2 A \quad v_{avg} = \omega A, a_{avg} = \omega^2 A$$

## Graphs

- $x = A \sin(\omega t + \phi)$  → sine wave
  - $v = A\omega \cos(\omega t + \phi)$  → cosine
  - $a = -A\omega^2 \sin(\omega t + \phi)$  → -sine
- All are **periodic** with period  $T = 2\pi/\omega$ .
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## 4. Energy in SHM

- **Kinetic Energy:**  $K = \frac{1}{2}mv^2 = \frac{1}{2}m\omega^2(A^2-x^2)$
- **Potential Energy:**  $U = \frac{1}{2}m\omega^2x^2$
- **Total Energy:**  $E = \frac{1}{2}m\omega^2A^2 = \frac{1}{2}m\omega^2(A^2-x^2)$  (constant)

Hence energy oscillates between kinetic and potential but the total remains constant — a neat physical model of energy conservation.

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## 5. Mass-Spring System

When a mass  $m$  is attached to a spring of force constant  $k$ , displacement  $x$  from equilibrium produces restoring force  $F = -kx$ .

Equation of motion:

$$md^2x/dt^2 = -kx \Rightarrow \omega = \sqrt{k/m}$$

Time period:

$$T = 2\pi\sqrt{m/k}$$

This is a **linear SHM**, frequently asked in NEET numericals.

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## 6. Simple Pendulum

For small angular displacement  $\theta$ , restoring torque  $\tau = -mg l \sin\theta \approx -mg l \theta$ .

Equation:

$$d^2\theta/dt^2 + g/l = 0 \quad \text{or} \quad d^2\theta/dt^2 + \frac{g}{l}\theta = 0$$

$$\omega = \sqrt{\frac{g}{l}}, T = 2\pi\sqrt{\frac{l}{g}}$$

### Effect of factors

- $T \propto \sqrt{l}$  → longer pendulum, slower swing.
  - $T \propto 1/\sqrt{g}$  → on Moon ( $1/6 g$ ), period  $\approx \sqrt{6}$  times longer.
  - Independent of mass and amplitude (for small  $\theta$ ).
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## 7. Combination of SHMs

When two SHMs of same frequency act along same line:

$$x = A_1 \sin(\omega t) + A_2 \sin(\omega t + \phi) = A_1 \sin \omega t + A_2 \sin(\omega t + \phi) = A_1 \sin \omega t + A_2 \sin(\omega t + \phi)$$

Resultant amplitude:

$$A = \sqrt{A_1^2 + A_2^2 + 2A_1 A_2 \cos \phi} = \sqrt{A_1^2 + A_2^2 + 2A_1 A_2 \cos \phi}$$

This explains **interference** in wave motion later.

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## 8. Damped and Forced Oscillations

### Damped Oscillation

Due to friction or air resistance, amplitude decreases exponentially:

$$A = A_0 e^{-bt/2m} = A_0 e^{-bt/2m}$$

Energy falls as  $e^{(-bt/m)}$ .

### Forced Oscillation

External periodic force  $F = F_0 \sin \omega t$  acts on system.

If driving frequency  $\approx$  natural frequency → **resonance**, large amplitude.

Examples: breaking of glass by sound, tuning fork resonance.

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## 9. Wave Motion – Energy on the Move

When oscillations travel through a medium, a **wave** is produced.

Type	Direction of vibration vs propagation	Example
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Transverse	⊥	String waves, light
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Type	Direction of vibration vs propagation	Example
Longitudinal		Sound in air
Wave transports energy without transporting matter.		

## 10. Wave Equation

A progressive wave along +x:

$$y(x,t) = A \sin(kx - \omega t + \phi) y(x,t) = A \sin(kx - \omega t + \phi)$$

where  $k = 2\pi/\lambda$  is wave number.

Velocity of wave:

$$v = \omega k = f \lambda v = \frac{\omega}{f} k = f \lambda v = k \omega = f \lambda$$

## 11. Principle of Superposition

When two or more waves overlap, resultant displacement equals algebraic sum of individual displacements:

$$y = y_1 + y_2 \quad y = y_{-1} + y_{-2} \quad y = y_1 + y_2$$

Leads to interference, standing waves, beats — foundation of wave physics.

## 12. Standing Waves and Resonance

When two identical waves travelling in opposite directions meet:

$$y=2A\sin(\frac{f_0}{k}x)\cos(\omega t) \quad y = 2A \sin(kx) \cos(\omega t) \quad y=2A\sin(kx)\cos(\omega t)$$

Nodes → zero displacement; antinodes → maximum.

In strings and organ pipes, standing waves form harmonics:

$$\lambda_n = \frac{2L}{n}, f_n = n f_1 \lambda_n = \frac{2L}{n}, f_n = n f_1$$

$$n = 1, 2, 3\dots$$

## 13. Sound Waves

Sound = longitudinal mechanical wave of compressions and rarefactions.

## **Speed of Sound in Gas:**

$$v = \sqrt{\gamma RT} = \sqrt{\frac{\gamma RT}{M}} = \sqrt{\frac{\gamma P}{\rho}} v = M\gamma RT = \rho\gamma P$$

Depends on T,  $\gamma$ , and molecular mass.

### Effect of temperature:

$v \propto \sqrt{T}$  → increases about 0.6 m/s per  $^{\circ}\text{C}$ .

### In solids and liquids:

$v = \sqrt{E/\rho}$  (Young's modulus E).

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## 14. Beats and Interference of Sound

When two waves of slightly different frequencies  $f_1, f_2$  superpose:

$$f_{\text{beats}} = |f_1 - f_2| f_{\text{beats}} = |f_1 - f_2|$$

Used to tune musical instruments.

**Interference:** constructive when path difference =  $n\lambda$ ; destructive =  $(2n+1)\lambda/2$ .

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## 15. Doppler Effect

Apparent change in frequency when source or observer moves:

$$f = f(v \pm v_o) f = f(v \mp v_s)$$

‘+’ when moving toward, ‘-’ when away.

Applications: radar, medical imaging, astronomy.

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## 16. Energy Transmission in Waves

Energy density of wave:

$$u = \frac{1}{2} \rho \omega^2 A^2 u = \frac{1}{2} \rho \omega^2 A^2$$

Power transmitted:

$$P = uv = \frac{1}{2} \rho v \omega^2 A^2 P = u v = \frac{1}{2} \rho v \omega^2 A^2$$

So energy  $\propto A^2$ . Double amplitude → quadruple energy.

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## 17. Speed of Transverse Wave on String

$$v = \sqrt{T/\mu} v = \sqrt{\mu T}$$

T = tension,  $\mu$  = mass per length.

Used to design musical instruments and bridges.

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## 18. Quality and Intensity of Sound

- **Loudness:** related to amplitude.
- **Pitch:** depends on frequency.
- **Quality or Timbre:** distinguishes sources with same pitch/loudness (due to harmonics).
- **Intensity:**  $I = P/AI = P/AI = P/A$ , measured in  $\text{W m}^{-2}$ .

Human ear range: 20 Hz – 20 kHz.

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## 19. Summary

1. SHM:  $a = -\omega^2 x$ ,  $x = A \sin(\omega t + \varphi)$ .
2. Energy of SHM =  $\frac{1}{2} m \omega^2 A^2$ .
3.  $T = 2\pi\sqrt{m/k}$  for spring,  $2\pi\sqrt{l/g}$  for pendulum.
4. Damping reduces amplitude; resonance gives max amplitude.
5. Wave equation  $y = A \sin(kx - \omega t)$ .
6.  $v = f\lambda$ .
7. Standing waves have nodes and antinodes.
8.  $v_{\text{sound}} = \sqrt{\gamma P/\rho}$ .
9. Doppler effect → apparent frequency shift.
10. Energy  $\propto A^2$  in waves.