

## Chapter 2 — Kinematics (NEET 2025)

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### 1. Introduction – The Language of Motion

Everywhere around you, something is moving: cars on the road, planets around the Sun, blood inside your veins, even the electrons in the wires of your phone charger.

**Kinematics** is the branch of physics that describes *how* things move—without asking *why* they move.

So, we're not yet worrying about forces or energy. We're simply learning to describe and measure motion:

- How far?
- How fast?
- In what direction?
- How the motion changes with time?

Mastering kinematics is like learning the **grammar of motion**—it gives you the vocabulary and equations that later help you understand forces, work, and energy.

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### 2. Types of Motion

1. **Translatory motion** – The entire body moves in the same direction.  
→ Example: a car moving on a straight road.
2. **Rotational motion** – The body spins about an axis.  
→ Example: the spinning of a ceiling fan.
3. **Oscillatory motion** – Back-and-forth movement about a mean position.  
→ Example: pendulum, guitar string.

For now, we'll deal mainly with *translatory motion*, especially **motion along a straight line (1-D)** and **motion in a plane (2-D)**.

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### 3. Basic Quantities of Motion

Quantity	Symbol	Definition	SI Unit
Distance	s	Length of actual path	meter (m)
Displacement →	s	Straight-line change of position	meter (m)
Speed	v	Rate of change of distance	m/s

Quantity	Symbol Definition	SI Unit
Velocity	$\rightarrow v$	Rate of change of displacement m/s
Acceleration	$\rightarrow a$	Rate of change of velocity m/s <sup>2</sup>

### 👉 Distance vs Displacement

Distance only tells *how much ground* you covered, while displacement tells *where you ended up relative to start*.

If you jog 3 km east then 4 km north:

- Distance = 7 km
- Displacement =  $\sqrt{(3^2 + 4^2)} = 5$  km northeast

Hence, **displacement  $\leq$  distance** always.

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## ⌚ 4. Speed and Velocity

### 4.1 Average and Instantaneous

Average speed=Total distance/Total time  

$$\text{Average speed} = \frac{\text{Total distance}}{\text{Total time}}$$

Average velocity=Net displacement/Total time  

$$\text{Average velocity} = \frac{\text{Net displacement}}{\text{Total time}}$$

**Instantaneous velocity** is the velocity at a particular moment  $\rightarrow$  slope of the position–time graph at that point.

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## 📊 5. Graphical Interpretation

Graphs make motion visible.

### 5.1 Position–Time (x–t) Graph

- Slope = velocity
- Straight line  $\rightarrow$  uniform velocity
- Curved line  $\rightarrow$  non-uniform velocity

### 5.2 Velocity–Time (v–t) Graph

- Slope = acceleration
- Area under graph = displacement

### 5.3 Acceleration–Time (a–t) Graph

- Area under curve = change in velocity

Understanding these graphs gives you an intuitive feel of motion—exactly what NEET loves to test.

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## 6. Equations of Uniformly Accelerated Motion

For motion with constant acceleration (a):

$$\begin{aligned} v = u + at &= u + at = u + at + \frac{1}{2}at^2 \\ s = ut + \frac{1}{2}at^2 &= u^2 + 2as \\ s = (u+v)t &= \frac{(u+v)}{2}t \end{aligned}$$

where

$u$  = initial velocity,  $v$  = final velocity,  $s$  = displacement,  $t$  = time.

These hold only when acceleration is constant.

### Example:

A car starts from rest ( $u = 0$ ), accelerates at  $2 \text{ m/s}^2$  for  $5 \text{ s}$ .

$$\rightarrow v = 0 + 2 \times 5 = 10 \text{ m/s}$$

$$\rightarrow s = 0 + \frac{1}{2} \times 2 \times 25 = 25 \text{ m}$$

Hence the car moves  $25 \text{ m}$  and reaches  $10 \text{ m/s}$ .

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## 7. Motion Under Gravity

Near Earth's surface, all bodies fall with the same **acceleration due to gravity ( $g$ )**  $\approx 9.8 \text{ m/s}^2$  downward.

Equations of motion become:

$$\begin{aligned} v = u + gt, s = ut + \frac{1}{2}gt^2, v^2 = u^2 + 2gs &= u + gt, s = ut + \frac{1}{2}gt^2, v^2 = u^2 + 2gs \\ u^2 + 2gs &= u + gt, s = ut + \frac{1}{2}gt^2, v^2 = u^2 + 2gs \end{aligned}$$

When thrown upward, take upward as positive and  $g = -9.8 \text{ m/s}^2$ .

### Example:

A ball thrown upward at  $20 \text{ m/s}$ :

At highest point  $v = 0$

$$\rightarrow 0 = 20 - 9.8 t \rightarrow t \approx 2.04 \text{ s}$$

$$\text{Height} = \frac{u^2}{2g} = \frac{20^2}{2 \times 9.8} \approx 20.4 \text{ m.}$$


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## 8. Relative Velocity in One Dimension

Motion is always *relative*—we measure velocity with respect to some reference.

If object A moves at velocity  $v_a$  and object B at  $v_b$  (in same line),

$$v_{AB} = v_A - v_B$$

is velocity of A relative to B.

Example: Two cars move east at 60 km/h and 40 km/h.

Relative velocity = 20 km/h east.

If opposite directions → 100 km/h.

This simple idea becomes vital in river-boat and air-plane problems later.

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## 9. Vector Nature of Motion

In one dimension, direction is shown by sign (+/-).

In two or three dimensions, we use **vectors**.

A vector has both **magnitude** and **direction**, represented as →A.

Operations on vectors follow geometry rules:

Operation	Expression	Meaning
Addition	→R = →A + →B	Combine effects
Subtraction	→A - →B = →A + (-→B)	Opposite direction
Dot product	→A · →B = AB cosθ	Scalar → projection
Cross product	→A × →B = AB sinθ n̂	Vector → perpendicular

For **2-D motion**, resolve every vector into x- and y-components:

$$Ax = A \cos[\theta], Ay = A \sin[\theta] \quad A_x = A \cos\theta, A_y = A \sin\theta$$

Then apply 1-D equations separately to x and y.

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## 10. Projectile Motion (2-D Motion)

Projectile motion is the classic NEET favorite: a particle thrown obliquely near Earth moves along a curved path called a **parabola**.

Let the projectile be thrown with velocity u at an angle θ above the horizontal.

$$\text{Horizontal component} = u_x = u \cos\theta$$

$$\text{Vertical component} = u_y = u \sin\theta$$

### Equations of motion:

$$x = u \cos[\theta] t, y = u \sin[\theta] t - \frac{1}{2} g t^2$$

Eliminate t to get trajectory:

$$y = x \tan \theta - g x^2 u^2 \cos^2 \theta$$
$$y = x \tan \theta - \frac{g}{2} u^2 \cos^2 \theta x^2$$

— a parabola.

## Key Results

- **Time of flight:**  $T = 2u \sin \theta / g$
- **Maximum height:**  $H = u^2 \sin^2 \theta / (2g)$
- **Range:**  $R = u^2 \sin 2\theta / g$
- For same  $u$ ,  $R$  is maximum at  $\theta = 45^\circ$ .

## Example:

$u = 20 \text{ m/s}$ ,  $\theta = 45^\circ$

$$\rightarrow T = (2 \times 20 \times 0.707) / 9.8 \approx 2.89 \text{ s}$$

$$\rightarrow R = 20^2 \sin 90^\circ / 9.8 \approx 40.8 \text{ m.}$$

## 11. Motion in a Circle

When an object moves in a circle of radius  $r$  at speed  $v$ , it changes direction continuously, meaning it has **centripetal acceleration** toward the center.

$$a_c = v^2 / r$$

and **centripetal force** needed:

$$F_c = m v^2 / r$$

This keeps planets in orbit, cars turning safely, and electrons circling nuclei (conceptually).

## Example:

A 1000 kg car turns a curve of radius 50 m at 10 m/s.

$$\text{Required } F_c = (1000 \times 10^2) / 50 = 2 \times 10^4 \text{ N toward center.}$$

## 12. Relative Velocity in Two Dimensions

When two motions occur in perpendicular directions (like a boat crossing a river), combine them as vector components.

If river flows east with velocity  $v_r$  and boat velocity relative to water is  $v_b$  north,  
Resultant velocity relative to ground:

$$v = \sqrt{v_b^2 + v_r^2}$$

Direction:  $\tan \theta = v_r / v_b$ .

If you want the boat to go straight north, aim *against* the current by angle  $\theta$  so  $\tan \theta = v_r/v_b$ .

These are typical NEET conceptual numericals.

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### 13. Relative Motion Between Two Projectiles

If two projectiles are fired simultaneously, their relative motion is itself a projectile.  
Time of flight remains same, relative velocity determines path difference.  
This concept builds intuition for “collision in air” and “meeting point” problems.

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### 14. Derivation Recap and Dimensional Check

#### Formula      Dimensional Check

$$s = ut + \frac{1}{2}at^2 \quad [L] = [L T^{-1} T] + [L T^{-2} T^2] \checkmark$$

$$v^2 = u^2 + 2as \quad [L^2 T^{-2}] \text{ both sides } \checkmark$$

$$R = u^2 \sin 2\theta / g \quad [L] \text{ both sides } \checkmark$$

Always check dimensions → a good NEET trick to catch wrong options quickly.

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### 15. Common Conceptual Questions

1. *Can velocity be zero when acceleration isn't?*  
✓ Yes—at highest point of projectile, velocity = 0 vertically but acceleration = g.
  2. *Can acceleration be zero when velocity isn't?*  
✓ Yes—uniform motion (constant velocity).
  3. *Why does a coin fall slower in air than in vacuum?*  
✓ Air resistance → additional upward acceleration reduces net g.
  4. *When are average speed and average velocity equal?*  
✓ When motion is in a straight line in one direction.
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### 16. Application of Kinematics in Real Life

- **Automotive design:** acceleration, braking distance, turning radius.
- **Sports:** trajectory of cricket ball, long-jump, basketball shot.
- **Aerospace:** rocket launch angles and escape velocity.

- **Medical:** blood-flow measurement (Doppler effect uses velocity).
- **Meteorology:** predicting projectile debris or rainfall patterns.

Everywhere something moves, kinematics silently governs it.

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## 17. Summary – Key Takeaways

1. **Kinematics** describes motion without forces.
2. **Scalar quantities** have only magnitude; **vectors** have magnitude + direction.
3. **Displacement  $\leq$  distance.**
4. **Velocity–time graphs** give displacement; **slope = acceleration.**
5. **Equations of motion** apply only for constant acceleration.
6. **Projectile motion** → parabolic; maximum range at  $45^\circ$ .
7. **Circular motion** → centripetal force =  $mv^2/r$ .
8. **Relative velocity** helps solve river-boat, rain-man, and airplane problems.
9. Always check **units & dimensions** for validity.
10. Kinematics builds foundation for all mechanics — master it to breeze through the next chapters.