Lab 3

Objective:

- Using **makefile** and compiler optimization
- Introducing the assembly language x86-64
- Introducing the disassembler
- Introducing function call protocol in x86-64
- Debugging assembly code
 - Our textbook lists GDB commands in Figure 3.39 on page 280.

We do not need to hand-in anything in this lab session!

Part 1: Compiling and executing a C program using makefile and optimization

In the first part of this lab, we shall use the files we downloaded for Lab 1, namely, main.c, times.c and makefile. Use the makefile we improved in Part 3 of Lab 1.

- Copy them onto our sfuhome/CMPT295/Lab3 directory.
- Compile the code files using **make** and have a look at the content of our directory. Amongst the files produced by the compilation, we should see the following:
 - main.s and times.s. These files contain the assembly code version of the C program located in the respective files. Have a look at each file using our favourite text editor. Lines that begin with a period are assembler directives: they are not x86-64 instructions, but they help guide the assembler when it creates the object file.

NOTE: Since we have just started learning x86-64 assembly language, it is quite normal that at this point we may not understand all the assembly instructions we see in these files right now.

- main.o and times.o. These files are the object files created by the assembler. Objects files are binary files: they contain the machine code (0's and 1's) version of the C program located in the respective files. These are not text files, so our favourite text editor may have a difficult time displaying their content. It may either display this binary content as text and in this case, we get very interesting display of all sorts of characters, or it may actually be capable of displaying the 0s and 1s as hexadecimal numbers. Try it and see what happens!
- To know what the machine code version of our C program looks like (i.e., the actual 0's and 1's or hexadecimal numbers expressing these 0's and 1's), we can use the disassembler. Try the following commands:

```
objdump -d main.o objdump -d times.o
```

By the way, if we are wandering why the flag -d is used, here is what the man page for the command objdump says

(https://man7.org/linux/man-pages/man1/objdump.1.html):

-d

--disassemble

--disassemble=symbol

Display the assembler mnemonics for the machine instructions from the input file. This option only disassembles those sections which are expected to contain instructions. If the optional symbol argument is given, then display the assembler mnemonics starting at symbol. If symbol is a function name then disassembly will stop at the end of the function, otherwise it will stop when the next symbol is encountered. If there are no matches for symbol then nothing will be displayed.

• As we can see, the output of these commands can be lengthy so we may wish to pipe them (i.e., redirect their output) to files. Try these commands:

```
objdump -d main.o > main.objdump
objdump -d times.o > times.objdump
```

Note that the extension given to these files (.objdump) is arbitrary which means that we can give any extension we wish. Let's remember that using a descriptive extension is always very helpful. However, do not use extensions already used by gcc such as ".s", ".o" and ".c".

- Let's open main.objdump in our favourite text editor. We see three columns below the label main:
 - the rightmost column lists the assembly instructions representing our main function in main.c,
 - the middle column is the machine code representing these assembly instructions (this machine code is expressed as hexadecimal numbers), and
 - the leftmost column (the one with the colon ":") lists the memory address **offsets** (expressed as hexadecimal numbers) corresponding to each of these machine code instructions (i.e., assembly instructions). More on this later.
- Compare the content of main.objdump with the content of main.s. Their assembly instructions should be very similar. However, since the code in the object file main.o

(which was used to create this main.objdump) does not contain comments nor directives, the resulting main.objdump does not either. Furthermore, there are at least four main differences (aside from the lack of comments and directives) between the assembly instructions in main.s and main.objdump. For example, one of these main differences is that in main.objdump all immediate values (Imm) are expressed in hexadecimal numbers (as opposed to being expressed as decimal numbers in main.s). Here is an example where the decimal value 16 is used in main.s, but its hexadecimal representation, i.e., 0x10, is used in main.objdump instead:

```
main.s: movq 16(%rbx),%rdi => main.objdump: mov 0x10(%rbx),%rdi
```

Can we spot the other three main differences?

- Now compare the content of times.objdump with the content of times.s. Do we
 notice similar differences between the assembly instructions listed in these two files?
- Have a look at the leftmost column of times.objdump. As stated above, these hexadecimal numbers do not represent memory addresses (yet), but offsets, i.e., how far away in memory is each instruction from the first instruction of our function times, or more specifically: how many bytes away in memory is each instruction from the first instruction of our function times. (Remember: to be executed, our program must first be loaded, from its executable file stored most likely on some hard disk onto memory.) Let's verify this:
 - Start at byte 0, which is the offset of the byte containing the hexadecimal value £3, i.e., the first byte of our function times, then move rightward to the next byte containing 0£ counting 1 (i.e., this byte is located at offset 1), then move rightward again to the next byte (containing 1e) counting 2 (i.e., this byte is located at offset 2), then move rightward once again to the next byte (containing £a) counting 3 (i.e., this byte is located at offset 3). This signifies that the first assembly instruction of our function times, namely endbr64, is expressed as a machine instruction of 4 bytes: £3 0£ 1e £a. Therefore, the first byte of the next assembly instruction should be at offset 4.
 - Indeed, looking at the offset on line 9, we see **4**. This second machine instruction (mov %edi, %eax) is 2-byte long. Therefore, the offset of the third machine instruction is 4+2 = 6, and indeed it is.
 - Verify the offset of the last machine instruction of our function times.
- Also, how many bytes does the code of the function times occupy in memory? How
 could we answer this question without counting each byte?

The reason why these disassembled object files do not contain memory addresses in the leftmost column is because they have not yet been linked together and their instructions,

and various other things (referred to as **tokens**), given addresses by the compiler (more specifically, the linker). Once we link both of our object files and produce our executable mul, we are then able to see the memory address of each instruction of our program when we disassemble it. Let's give this a try!

Enter the following command:

- Open mul.objdump and notice its length. It is rather long. This is because it contains all the code needed to execute our program. This is to say that aside from containing the code for our main and our times functions, it also contains the code implementing all the C functions our C code calls such as atoi (...) and printf (...).
- Now, have a look at the leftmost column. These hexadecimal numbers no longer represent offsets, but actual memory addresses. More specifically, each of them represents the memory address of the first byte of each instruction of the functions contained in our executable mul. For example, the second instruction of our times function, a mov instruction, has two bytes and its memory address is 118d (at least on my computer ©, it may be different on yours), which is the memory address of the mov's first byte, i.e., the byte containing 89.
 - As stated earlier in this lab, the middle column of mul.objdump lists the machine code representing the assembly instructions of the function (expressed as hexadecimal numbers) and the rightmost column, its assembly instructions.

Let's now investigate the effect of the **compiler optimization**.

- Currently our makefile uses the optimization level -Og. What if we did not use the optimizing capability of gcc? What kind of assembly program and machine code would we get? Well, let's try!
 - Recall: The **-Og** flag requests the compiler to perform optimization that promotes the use of the debugger. More on the subject of using the debugger with assembly code later on in this lab.
- Let's remove the optimization flag **-Og** from the SFLAGS in our **makefile**.
 - Notice that using macros such as SFLAGS in our makefile allows us to easily make modifications to the makefile. Here, we only need to make this one change (remove -Og from the macro) only once and it is automatically reflected throughout the makefile.

If we were not using macros in our **makefile**, we would need to make the change a few times throughout the **makefile** and this could be time consuming and very errorprone (what if we were to miss making one of the changes?).

Let's also remove main.s and times.s in order for gcc to remake these files:

rm main.s times.s

- Finally, let's clean our directory by using the command: **make clean**, then remake our executable.
- Have a look at the content of the new times.s. It is much longer than the previous one, i.e., the one we obtained using the optimization flag -Og, and its code seems more complicated. Remember, the previous times.s had four instructions so it seems more efficient as it performs the same task with fewer instructions.
- Now that we have done our investigation, let's put our optimization flag —Og back into our makefile (as part of the SFLAGS variable), let's remove main.s and times.s and let's clean our directory using make clean. Finally, let's rebuild our executable using make in order to be ready for Part 2 of our Lab 3.

We are now ready to get started with the assembly language x86-64.

Part 2: Getting started with the assembly language x86-64

One of the virtues of programming in assembly language is that software developers can often write much shorter, faster assembly language programs than those generated by the compiler, even with some of the higher levels of optimization enabled. Also, systems programmers often write routines initially in C, and then examine the generated assembly language code for opportunities to optimize it.

In this part of our lab, we will implement a new version of times (x,y), which we will save in times.s instead of having the compiler creating times.s for us by compiling the C program times.c. In other words, we shall write our own assembly code version of times.s.

- Let's save our executable mul into a file called mul Og.
- Open times.s and replace its *entire content* with the following:

```
.globl times
times:
   xorl
          %eax,
                 %eax
   movl %edi,
                 %ecx
   movl
          %esi,
                 %edx
   imull %edx,
                 %ecx
          %edx,
   movl
                 %eax
   ret
```

• Tip:

- Labels such as times should usually appear flush left, followed by a colon.
- Assembly instructions and directives are prepended by white space, usually a single tab.
- o Including an empty line at the end of our file prevents the assembler warning "end of file not at end of a line: newline inserted".

• Note:

The directive .glob1 is for the linker. It allows the linker to link (using memory addresses) the code of the called function (for example, times) to the calling function(s) (for example, main). Here is an illustration:

```
In mul.objdump:
```

000000000001189 <times>:

```
1189: f3 Of le fa endbr64
```

where **1189** is the memory address of the first byte of the first instruction of **times**.

```
000000000001193 <main>:
```

...

```
11d5: e8 af ff ff callq 1189 <times>
```

where callq 1189 is how the function main calls the function times.

Note: The memory addresses you see in your **mul.objdump** may be different from the ones displayed in this lab.

- We may have noticed that this new implementation of times is dubious. If we have not, no problem! We shall discover how dubious it is in the next part of this lab.
- Make sure the SFLAGS in our makefile is back to -S -Og.
- Important: Also, comment out the following two lines in our makefile:

 If we don't, the compiler will overwrite our times.s with its own version.

```
times.s: times.c
    gcc $(SFLAGS) times.c
becomes:
# times.s: times.c
# gcc $(SFLAGS) times.c
```

- Let's make our executable.
- Finally, run the new executable as follows: ./mul 1 5. Compare it with our initial executable: ./mul Og 1 5. Both should produce the same correct result:

```
times(1, 5) produces 5 as a result.
```

- Let's try another test case: ./mul 5 6. Oops! The result (6) is incorrect. Let's try this test case with the initial executable: ./mul_Og 5 6. With our initial executable, we do obtain the correct result (i.e., 30) and this confirms the fact that our new implementation of the function times is indeed buggy!
- Let's investigate why the last result is incorrect by using the debugger **gdb**.

Part 3: Function call protocol in x86-64, debugging assembly code and a challenge

Before we proceed, we need to learn a little about function call protocol in x86-64. In this lab, the main function calls the function times. Therefore, main is seen as the caller and times, as the callee. In x86-64, the function call protocol describes how caller and callee functions should behave. Also, because this is a protocol, it is expected that all C compilers executing on our target machine will implement this protocol.

Part of the protocol deals with parameter passing and return value. As a matter of efficiency, these are passed in registers whenever possible. Therefore, the x86-64 function call protocol states the following rules:

- %rax holds the return value.
- %rdi is the first parameter.
- %rsi is the second parameter.
- Parameters 3-6 go in %rdx, %rcx, %r8 and %r9, in that order.
- If more than 6 parameters are required, the stack is used for the 7th, 8th, etc.

We shall cover this protocol in more details over the next few lectures, but for now, the above gives us enough information about this **x86-64 function call protocol** for us to understand the rest of our Lab 3 and to grasp what is happening with our new times.s.

We shall now investigate what is happening with our new times.s using the gdb debugger.

Of course, we do not need to use the **gdb** debugger to figure out how this new implementation of our **times** function works and why it is dubious. We could simply hand trace it with a few test cases. But using the **gdb** debugger in this part of our lab will allow us to gain "debugging assembly programs" skills and these skills will come in very handy when we write our own assembly programs in this course. So, let's give it a go!

• gdb mul

We can use the commands we have already used in the previous lab, namely, run, list, break, continue, display, print, etc... and proceed exploring times.s on our own. Or we can follow the steps below:

- Set a breakpoint for main, then run the program as follows: run 1 5.
 - A note about this test case: in terms of terminology, its test data is 1 5 and its expected result is 1 x 5 = 5.
- Do a list to see where we are in the execution of our program. We are about to execute the first instruction of main, i.e., endbr64 (which we will cover in a few lectures from now).
- Display the relevant registers.

To print the value of a register, name the register with \$ (as opposed to %).

- o For example, to print the value of eax, use print \$eax
- For example, to print the value of eax in hex, use print /x \$eax

To display the value of a register automatically after every step, type **display** \$eax or type **display** /x \$eax.

Determine which registers we need to display.

Note that if we want to display the state of all registers using one command, type info registers. However, we will have to repeat this command at every step we take executing our program.

- Set a breakpoint for times.
- Continue. The function main executes and calls times. According to the x86-64 function call protocol, times' first parameter (here: 1) is stored into the

register **%edi** and **times**' second parameter (here: **5**) is stored into the register **%esi**. Is this the case?

- Then list to figure out where we are in the program. We will then see the content of times.s. Notice the numbers on the left. As we saw in Lab 2, we can use these line numbers to set breakpoints as well.
- Step (command: step or s) into times (3) and notice the values of the displayed registers changing.
 - After issuing our first step command, the following is displayed on the monitor screen:

```
4          movl %edi, %ecx
1: $eax = 0
2: $edi = 1
3: $esi = 5
4: $edx = -5
5: $ecx = 0
```

It lists the content of the registers <code>%eax</code>, <code>%edi</code>, <code>%esi</code>, <code>%edx</code>, and <code>%ecx</code> once the instruction <code>xorl</code> <code>%eax</code>, <code>%eax</code> has executed. Notice <code>%eax</code> now contains <code>0</code>.

Note that the displayed instruction **movl** %**edi**, %**ecx** above has not yet been executed. It is the instruction at which the execution flow has stopped. It will be executed next time we **step**.

- O After our second step: movl %edi, %ecx has executed and \$ecx = 1
- o After our third step: movl %esi, %edx has executed and \$edx = 5
- O After our fourth step: imull %edx, %ecx has executed and \$ecx = 5
- O After the fifth step: movl %edx, %eax has executed and \$eax = 5
- **Continue** once more time to complete the execution of our program. We should be seeing the output of our program on the monitor screen.
- Now, let's try the other test case: **run 5 6**.
 - Our break points should still be set as well as the display commands we issued earlier.
- Repeat the above instructions (the ones we follow for our first test case), i.e.,
 Continue the execution to times, then step into times 5 times.
 - At every step, let's keep an eye on the instruction being executed during this step and the values stored in our registers.

Do the registers contain the value we are expecting them to contain at every step?

Can we see which instruction is incorrect, i.e., which one does not produce the result we are expecting?

Can we fix it? If so, let's fix it, recompile and see whether we have indeed solved the problem!

• That's it, everyone! I hope we have found this lab useful! 🚭