Assignment 6 Answer Questions 1 to 4. Question 5 is optional.

1. (PCA Via Optimization)

Let $\mathbf{x} = (x_1, \dots, x_d)^{\top}$ denote a d-dimensional random vector with variance-covariance matrix, Σ . Let γ_i be the eigen vector of Σ corresponding to the i^{th} largest eigen value, λ_i . Prove by induction that γ_i solves

$$\begin{aligned} \max_{\mathbf{a}} & \operatorname{Var}(\mathbf{a}^{\top}\mathbf{x}) \\ \text{subject to} & \mathbf{a}^{\top}\mathbf{a} &= 1 \\ & \mathbf{a}^{\top}\boldsymbol{\gamma}_{j} &= 0, \quad j = 1, \dots, i-1. \end{aligned}$$

for i = 1, ..., d.

2. (Missing Data Problems: Barber Section 15.5)
Recall the missing data formulation where we seek to solve

$$\min_{\mathbf{B}, \mathbf{Z}} \sum_{i=1}^{n} \sum_{j=1}^{d} \gamma_{j,i} \left[x_{j,i} - \sum_{k=1}^{M} b_{j,k} z_{k,i} \right]^{2}$$
 (1)

where

$$\gamma_{j,i} := \begin{cases} 1, & \text{if } x_{j,i} \text{ is available} \\ 0, & \text{otherwise.} \end{cases}$$

The problem is not *jointly* convex in \mathbf{B} and \mathbf{Z} and therefore we can only expect to obtain local minima when we attempt to solve (1). Note also, however, that for a fixed \mathbf{B} the objective function in (1) is convex in \mathbf{Z} . Similarly if \mathbf{Z} is fixed then the objective is convex in \mathbf{B} . We will therefore use an iterative algorithm to compute local minima.

- (a) Optimize Z for fixed B: show that the first order conditions for solving this problem amount to solving n linear systems of equations. It may be that one or more of these systems is under-determined. (This occurs when the number of observations in a column of X is less than M.) Does this present any difficulty?
- (b) **Optimize B for fixed Z:** show that the first order conditions for solving this problem amount to solving d linear systems of equations.
- (c) Write a computer program that iterates (a) and (b) until convergence to within a given error tolerance, ϵ . Your code should take as input the number of basis elements, M, the matrixes \mathbf{X} and Γ , the error tolerance, ϵ , and the starting matrix, \mathbf{B}_0 say. You should also decide what "convergence" means in this problem.

Finally, your code should compute the *root-mean-squared error* (RMSE) for the local optimum you have found. The RMSE is calculated as the square-root of: the optimal objective function divided by the total number of observations in the \mathbf{X} matrix. (Note that the number of observations will not be nd if some observations are missing.)

3. (Recommender Systems for Movies)

- (a) Run your code from Problem 2 on the movie database that you worked with in Assignment #5. In particular, you should estimate the missing elements of the ratings matrix \mathbf{X} . You can take M=5 but feel free to try other values as well. You will also need to decide whether d should represent the number of movies (as in the slides) or the number of critics.
 - You can do this in R or Matlab but the linear systems may be too big for your computer so feel free to reduce the number of users and movies to a more manageable size. But also note that the sparse matrix functionality in Matlab may enable you to handle larger matrices. Type help sparse at the Matlab prompt to see how to use this functionality. There is also sparse matrix functionality available in R via the *Matrix* and *SparseM* libraries, for example. They may also be useful.)
- (b) Now run your code from part (a) K times, starting from a randomly generated $d \times M$ matrix, $\hat{\mathbf{B}}$, each time.
 - Compute the RMSE for each of the K runs. What do you notice about the various local minima that you have obtained? (You can choose K yourself so that the problem is manageable on your system.)
- (c) Suppose now that you have a $d \times L$ genre matrix **G** where

$$\mathbf{G}_{ij} = \begin{cases} 1, & \text{if the } i^{th} \text{ movie is in genre } j \\ 0, & \text{otherwise} \end{cases}$$

for the movies $i=1,\ldots,d$ and genres $j=1,\ldots,L$. Explain how you could use your code to recommend movies by genre to users.

4. (Page-Rank)

- (a) Write a computer program to determine the page-rank of a system of web-pages.
- (b) Run your code on Figure 14.47 from HTF with $\epsilon = .15$. Does the resulting pagerank vector make sense? (Note that the page-rank is only unique if the associated Markov chain is irreducible. This is why we must have $\epsilon > 0$.)
- (c) Rerun your code for different values of ϵ . Does the page-rank vector respond in the way you would expect it to?

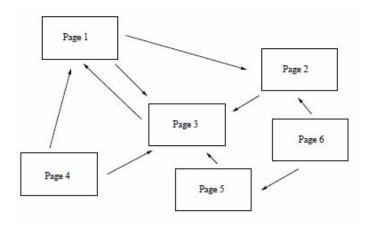


Figure 14.47 from HTF: Example of a small network

5. (Optional! Exercise 14.23 from HTF: Non-Negative Matrix Factorization)

A function g(x,y) is said to minorize a function f(x) if

$$g(x,y) \le f(x), \quad g(x,x) = f(x)$$

for all x, y in the domain. This is useful for maximizing f(x) since it is easy to show that f(x) is nondecreasing under the update

$$x^{s+1} = \underset{x}{\operatorname{argmax}} g(x, x^s).$$

(a) Consider maximization of the function $L(\mathbf{W}, \mathbf{H})$ (as defined in expression (18) in the slides), written here without the matrix notation

$$L(\mathbf{W}, \mathbf{H}) = \sum_{i=1}^{d} \sum_{j=1}^{n} \left[x_{ij} \log \left(\sum_{k=1}^{r} w_{ik} h_{kj} \right) - \sum_{k=1}^{r} w_{ik} h_{kj} \right].$$

Using the concavity of $\log(x)$, show that for any set of r values $y_k \geq 0$ and $0 \leq c_k \leq 1$ with $\sum_{k=1}^r c_k = 1$,

$$\log\left(\sum_{k=1}^r y_k\right) \geq \sum_{k=1}^r c_k \log(y_k/c_k).$$

Hence

$$\log \left(\sum_{k=1}^r w_{ik} h_{kj} \right) \geq \sum_{k=1}^r \frac{a_{ikj}^s}{b_{ij}^s} \log \left(\frac{b_{ij}^s}{a_{ikj}^s} w_{ik} h_{kj} \right)$$

where $a_{ikj}^s = w_{ik}^s h_{kj}^s$ and $b_{ij}^s = \sum_{k=1}^r w_{ik}^s h_{kj}^s$, and s indicates the current iteration.

(b) Hence show that the function

$$g(\mathbf{W}, \mathbf{H} | \mathbf{W}^{s}, \mathbf{H}^{s}) := \sum_{i=1}^{d} \sum_{j=1}^{n} \sum_{k=1}^{r} x_{ij} \frac{a_{ikj}^{s}}{b_{ij}^{s}} \left(\log(w_{ik}) + \log(h_{kj}) + \log\left(\frac{b_{ij}^{s}}{a_{ikj}^{s}}\right) \right)$$
$$- \sum_{i=1}^{d} \sum_{j=1}^{n} \sum_{k=1}^{r} w_{ik} h_{kj}$$

minorizes $L(\mathbf{W}, \mathbf{H})$.

(c) Set the partial derivatives of $g(\mathbf{W}, \mathbf{H} | \mathbf{W}^s, \mathbf{H}^s)$ to zero and hence derive the updating steps (19) and (20) that are also given in the slides.