

POU: Right_Exit_Station

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1  PROGRAM Right_Exit_Station
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```
2  VAR
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```
3      Box_At_Right_Convey          : BOOL ;
4      Onsl3_Right_Entry            : R_TRIG ;
5      Onsl4_Exit_Right             : R_TRIG ;
6      Onsl5_Re_Energize            : F_TRIG ;
7      Onsl6_Counter                : R_TRIG ;
```

```
8  END_VAR
```

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9
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```
1  (*
2  * File: Right Exit Conveyor
3  * Author: Jaime Calvente Mieres
4  * Date: 13-08-2022
5  * Description: Program to control the right exit path of the boxes.
6  *)
7
8
9  (*
10 * If the systme is active and sensor at left entry
11 * fires up, activate the conveyor and count one box.
12 * If the Exit sensor Negative edge detects a box,
13 * decrease the counter by one and check if conveyor
14 * needs to be stopped or not.
15 *)
16 IF System_Active THEN
17
18     // One shot call
19     Onsl3_Right_Entry ( CLK := At_Right_Entry ) ;
20     Onsl4_Exit_Right ( CLK := At_Exit_Right ) ;
21     Onsl6_Counter ( CLK := At_Right_Entry ) ;
22
23     // Convey Activation conditions
24     IF Onsl5_Re_Energize . Q AND ( Right_Counter <> 0 OR At_Right_Entry )
25 OR Onsl3_Right_Entry . Q THEN
26         M_Right_Convey := TRUE ;
27     END_IF
28
29     // Set box at scale and increment counter
30     IF Onsl6_Counter . Q THEN
31         //Box_At_Right_Convey := TRUE;
32         Right_Count := Right_Count + 1 ;
33         Right_Counter := Right_Counter + 1 ;
34     END_IF
35
36     // Counter decrement and Box at convey deactivation
37     IF Onsl4_Exit_Right . Q THEN
38         //Box_At_Right_Convey := FALSE;
39         // Check the counter to decrease it
40         IF Right_Counter <> 0 THEN
41             Right_Counter := Right_Counter - 1 ;
42         // Check the counter to deactivate the Convey
43         ELSEIF Right_Counter = 0 THEN
44             M_Right_Convey := FALSE ;
45         END_IF
46     END_IF
```

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46
47     END_IF
48
49
50     (* Conditions to Re-Start the program after
51        a soft stop *)
52     Onsl5_Re_Energize ( CLK := Soft_Stop_Active );
53     IF Soft_Stop_Active THEN
54         M_Right_Convey := FALSE;
55     END_IF
56
```