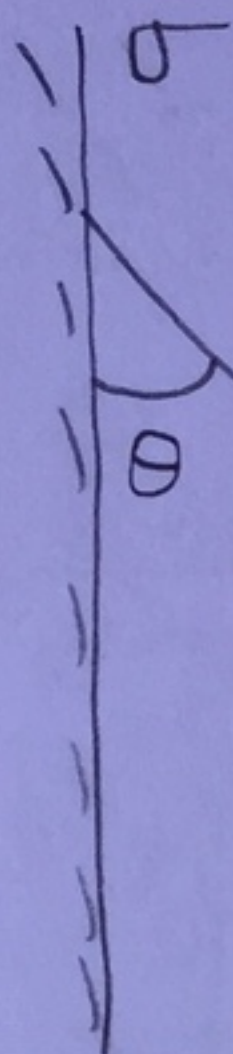


①



$$\theta = 30^\circ$$

$$m = 10^{-3} \text{ g} = 10^{-6} \text{ kg} \quad ; \quad \vec{E} = \frac{\sigma}{2\epsilon_0} \hat{i}$$

$$q = 1 \text{ nC}$$

$$x) T \sin \theta = F_E = qE$$

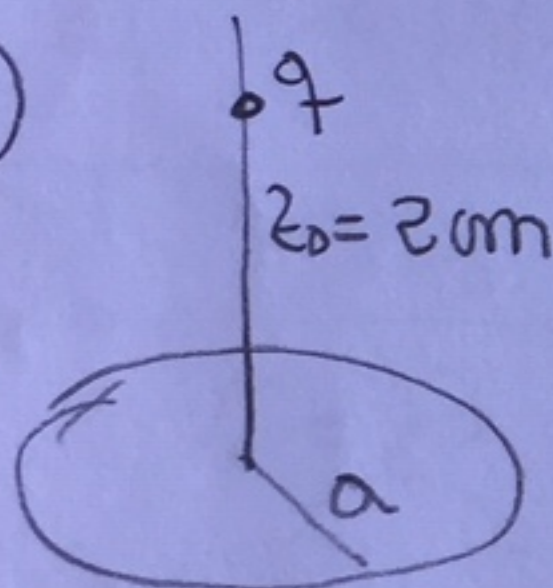
$$T \sin \theta = \frac{\sigma q}{2\epsilon_0}$$

$$y) T \cos \theta = mg$$

$$\tan \theta = \frac{\sigma q}{2\epsilon_0 mg} \Rightarrow$$

$$\sigma = \frac{2\epsilon_0 mg}{q} \tan 30^\circ = 1 \times 10^{-7} \text{ C/m}^2$$

②



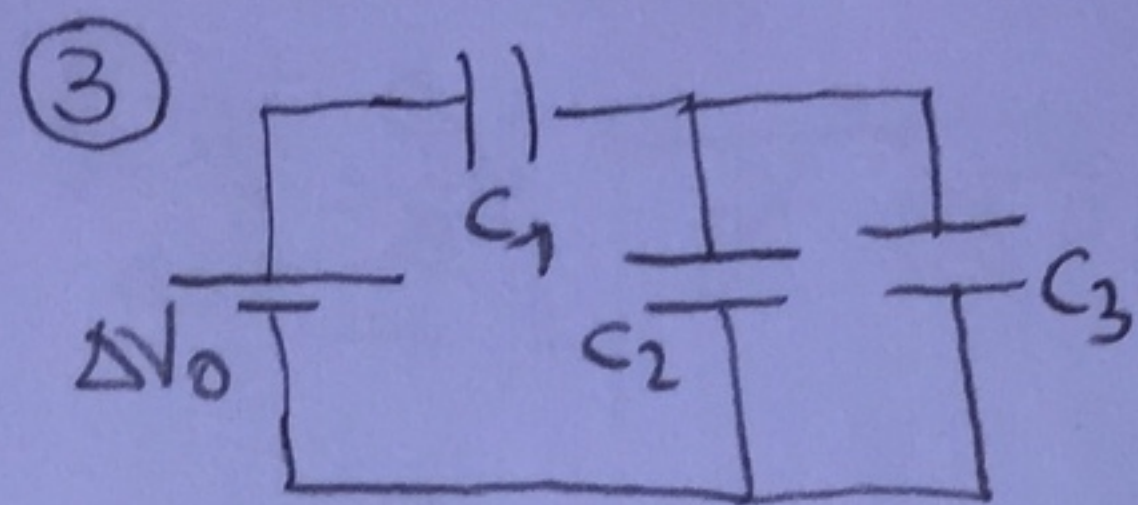
$$a = 10 \text{ m} \quad Q = 1 \text{ nC} \quad q = 1 \text{ nC} \quad m = 10^{-3} \text{ g} = 10^{-6} \text{ kg}$$

$$V(z) = \frac{kQq}{\sqrt{a^2 + z^2}}$$

$$E_i = \frac{1}{2} m v_0^2 + \frac{kQq}{\sqrt{a^2 + z_0^2}} = \frac{kqQ}{a}$$

$$v_0 \approx 0.9975 \text{ m/s} \text{ hacia el centro del anillo}$$





$$\Delta V_0 = 10V$$

$$C_1 = 1\mu F$$

$$C_2 = 2\mu F$$

$$C_3 = 3\mu F$$

$$C_{23} = C_2 + C_3 = 5\mu F ; \quad \frac{1}{C_{eq}} = \frac{1}{C_1} + \frac{1}{C_{23}} ; \quad C_{eq} = \frac{C_1 C_{23}}{C_1 + C_{23}}$$

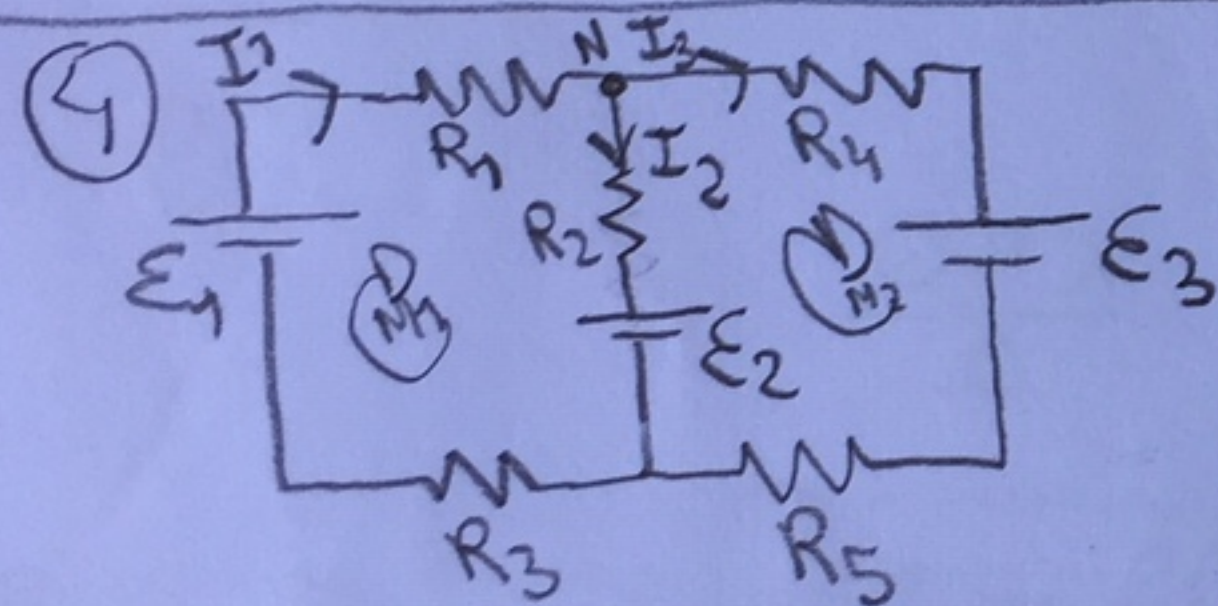
$$C_{eq} = \frac{5}{6} \approx 0.833\mu F$$

$$Q_T = C_{eq} \Delta V_0 = 8.33\mu C ; \quad \boxed{Q_1 = Q_T = 8.33\mu C}$$

$$Q_{23} = Q_T \Rightarrow \Delta V_{23} = \frac{Q_{23}}{C_{23}} = \frac{8.33\mu C}{5\mu F} = 1.666V$$

$$Q_2 = C_2 \Delta V_{23} = \boxed{3.332\mu C = Q_2}$$

$$Q_3 = C_3 \Delta V_{23} = \boxed{4.998\mu C = Q_3}$$



$$\varepsilon_1 = 2V \quad \varepsilon_2 = 4V \quad \varepsilon_3 = 2V$$

$$R_1 = R_3 = R_4 = R_5 = 1\Omega ; \quad R_2 = 4\Omega$$

$$\underline{N)} \quad I_1 = I_2 + I_3$$

$$\underline{M_1)} \quad \varepsilon_1 - I_1 R_1 - I_2 R_2 - \varepsilon_2 - I_1 R_3 = 0$$

$$\underline{M_2)} \quad \varepsilon_2 + I_2 R_2 - I_3 R_4 - \varepsilon_3 - I_3 R_5 = 0$$

$$\underline{N)} \quad I_1 = I_2 + I_3 ; \quad \underline{M_1)} \quad 2 - 2I_1 - 4I_2 = 0 ; \quad \underline{M_2)} \quad 2 + 4I_2 - 2I_3 = 0$$

$$\underline{M_1)} \quad 2 + 2I_2 + 2I_3 + 4I_2 = 0 ; \quad 2 + 6I_2 + 2I_3 = 0 ; \quad I_3 = -1 - 3I_2$$

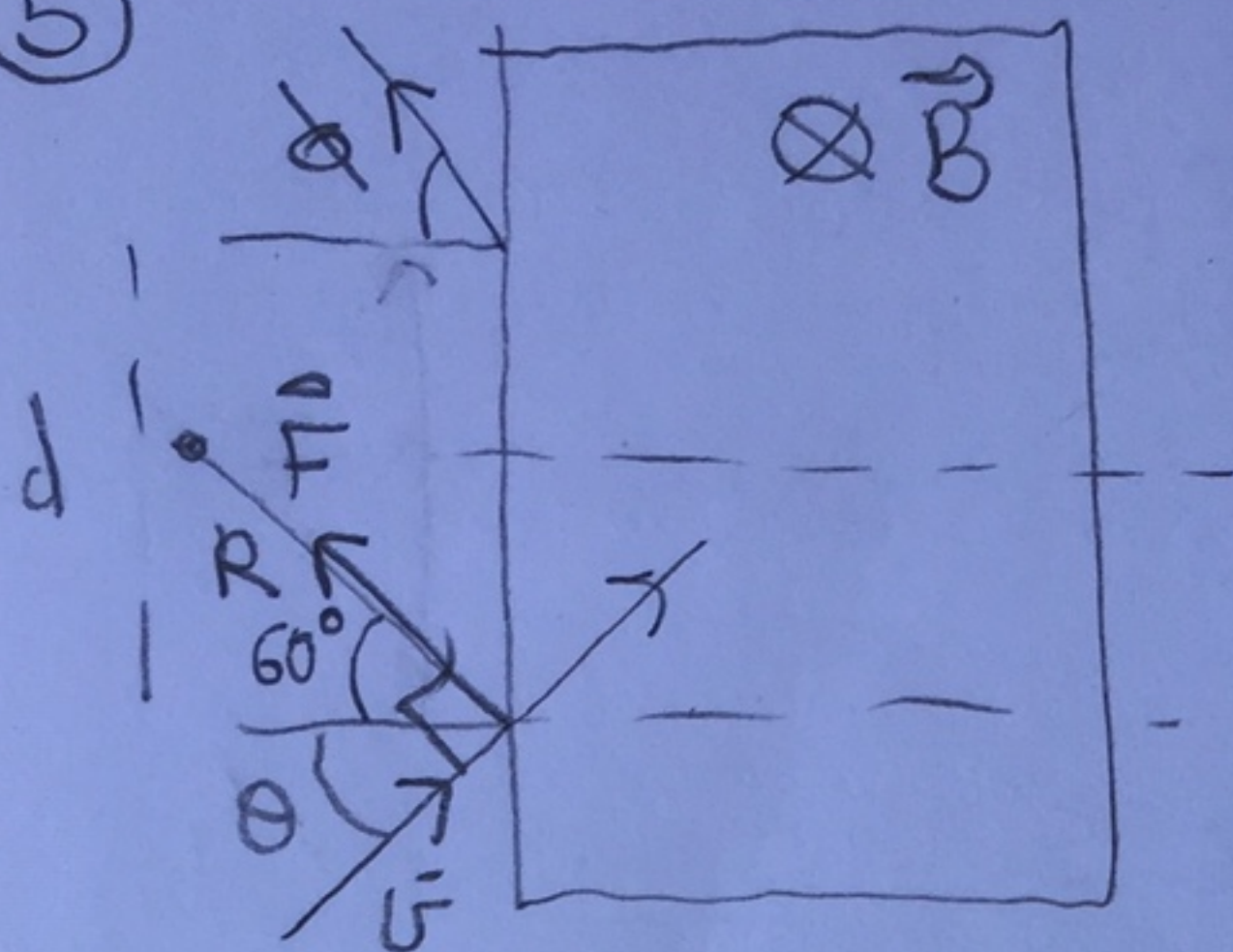
$$\underline{M_2)} \quad 2 + 4I_2 + 2 + 6I_2 = 0 ; \quad 4 + 10I_2 = 0 ; \quad \boxed{I_2 = -\frac{4}{10} = \frac{2}{5} = -0.4A}$$

$$\boxed{I_3 = -1 - 3I_2 = -1 + 1.2 = 0.2A}$$

$$\boxed{I_1 = I_2 + I_3 = -0.4 + 0.2 = -0.2A}$$



⑤



$$q = 1.6 \times 10^{-19} \text{ C}$$

$$m = 1.67 \times 10^{-27} \text{ kg}$$

$$B = 1 \text{ T}$$

$$v = 10^6 \text{ m/s}$$

$$\theta = 30^\circ$$

$$\vec{F} = q \vec{v} \wedge \vec{B} \Rightarrow F = q v B$$

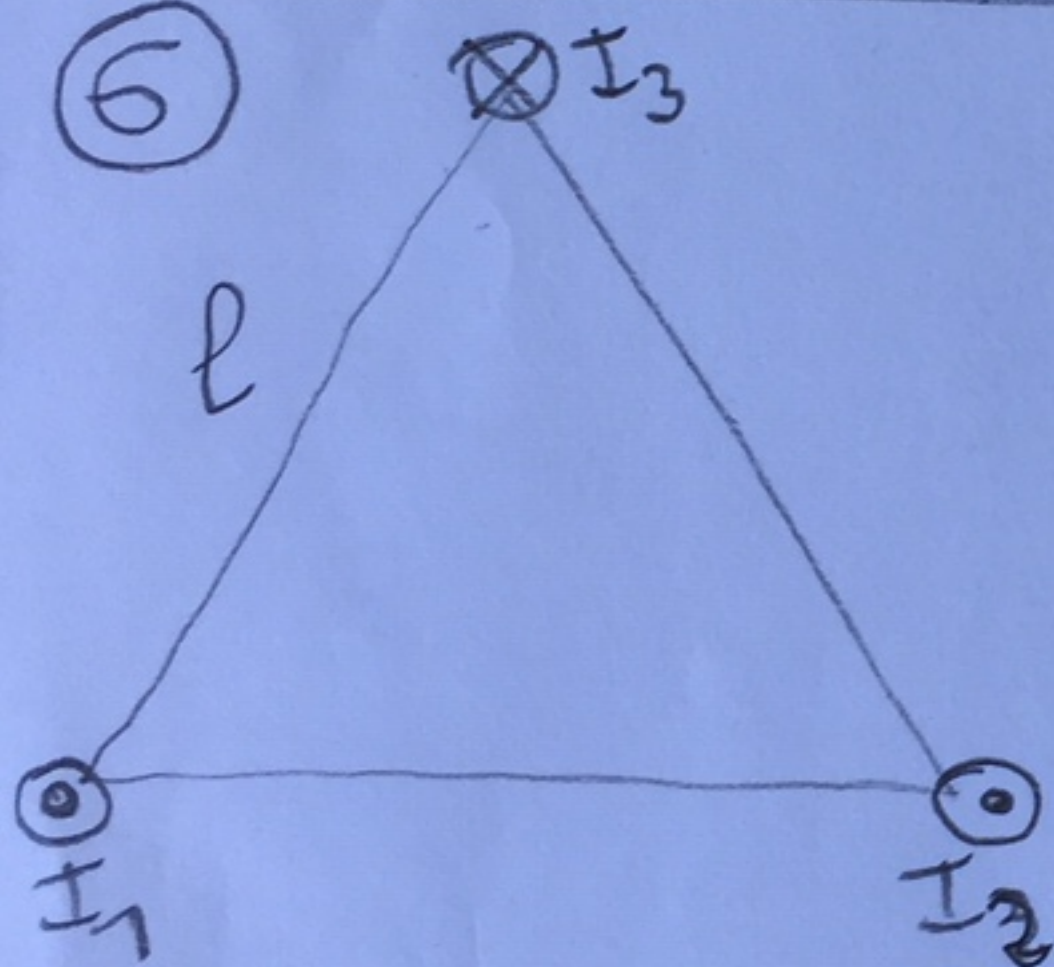
$$\text{Por simetria } \phi = \theta = 30^\circ$$

$$q v B = \frac{m v^2}{R} ; R = \frac{m v}{q B} = \frac{(1.67 \times 10^{-27})(10^6)}{(1.6 \times 10^{-19})(1)}$$

$$R = 0.01044 \text{ m} ; \sin 60^\circ = \frac{d/2}{R}$$

$$d = 2 R \sin 60^\circ = 2 \times 0.01044 \times \frac{\sqrt{3}}{2} = 0.018 \text{ m}$$

⑥



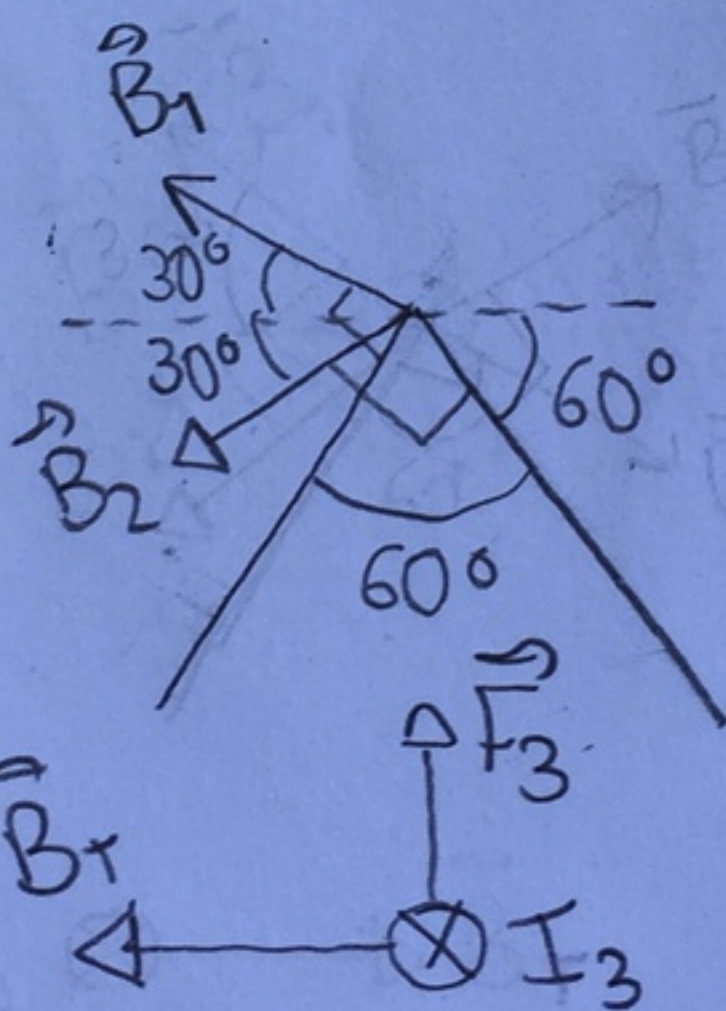
$$l = 0.1 \text{ m}$$

$$I_i = 15 \text{ A}$$

$$d\vec{B} \propto d\vec{L} \wedge \vec{r}$$

$$F_3 ?$$

$$B_1 = B_2 = \frac{\mu_0 I}{2\pi l}$$



$$\vec{B}_T = -2 B_1 \cos 30^\circ \hat{i}$$

$$\vec{B}_T = -\frac{2 \mu_0 I}{2\pi l} \frac{\sqrt{3}}{2} \hat{i}$$

$$\vec{B}_T = -\frac{\sqrt{3} \mu_0 I}{2\pi l} \hat{i}$$

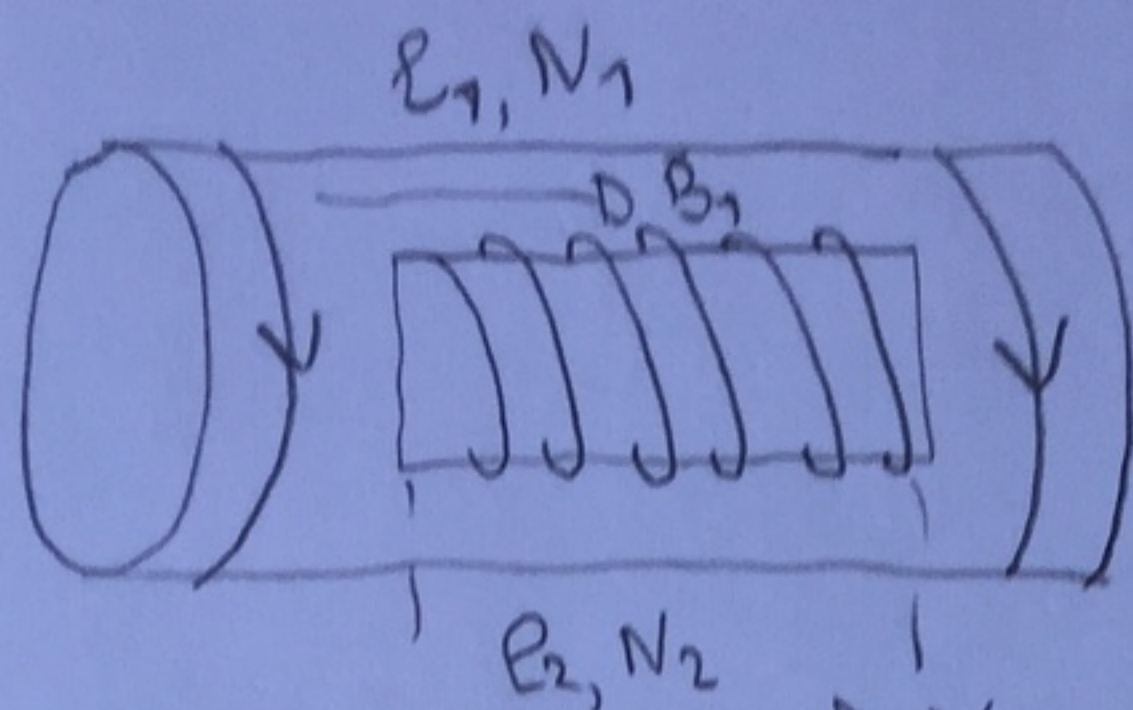
$$\vec{F}_3 = I_3 \vec{L}_3 \wedge \vec{B}_T$$

$$\vec{F}_3 = I_3 L_3 |B_T| \hat{j} \Rightarrow \frac{\vec{F}_3}{L_3} = I |B_T| \hat{j} \text{ hacia arriba}$$

$$\frac{\vec{F}_3}{L_3} = \frac{15 \times 4\pi \times 10^{-7} \times 15 \times \sqrt{3}}{2\pi \times 0.1} \hat{j} = +7.8 \times 10^{-4} \hat{j} \text{ N/m}$$



7



$$S_1 = 20 \text{ cm}^2 \quad S_2 = 10 \text{ cm}^2$$

$$\ell_1 = 50 \text{ cm} \quad \ell_2 = 25 \text{ cm}$$

$$N_1 = 2000 \quad N_2 = 1000$$

$$I_1(t) = 2 \sin(100\pi t) \quad R_2 = 10 \text{ }\Omega$$

$$\vec{B}_1 = \frac{\mu_0 I_1(t) N_1}{\ell_1} ; \quad \Phi_2 = N_2 B_1 S_2 = \frac{\mu_0 N_1 N_2 S_2}{\ell_1} I_1(t)$$

$$\mathcal{E}_2 = - \frac{d\Phi_2}{dt} = + \frac{\mu_0 N_1 N_2 S_2}{\ell_1} 2 \times 100\pi \cos(100\pi t)$$

$$I_2 = \frac{\mathcal{E}_2}{R} = \frac{\mu_0 N_1 N_2 S_2}{\ell_1 R} 200\pi \cos(100\pi t)$$

$$I_2(t) \approx 0.316 \cos(100\pi t) \text{ A} \quad \text{Correct}$$

$$I_2(t) \approx 0.00502 \cos(100\pi t) \text{ A}$$