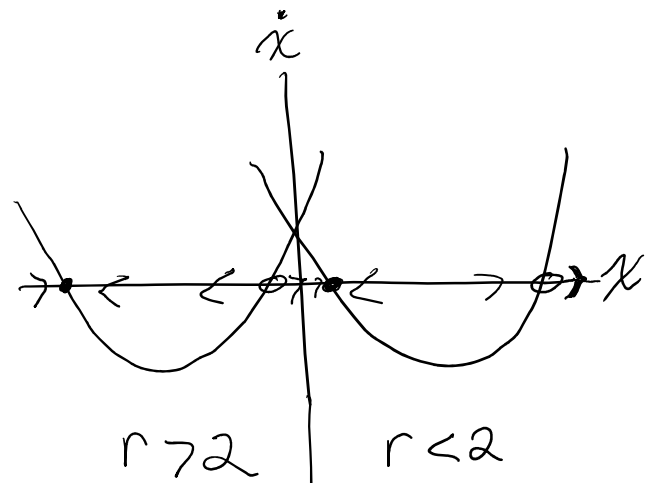
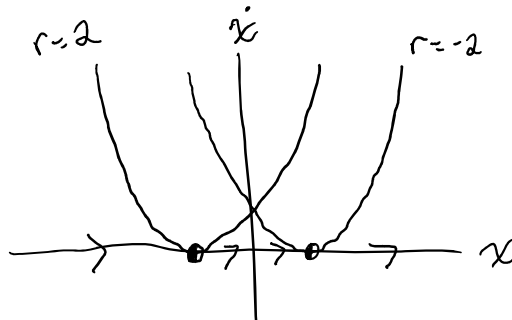


1. **Strogatz 3.1.1:** Sketch the qualitatively different vector fields that occur as r is varied. Show that a saddle-node bifurcation occurs at a critical value of r , to be determined. Finally, sketch the bifurcation diagram of fixed points x^* versus r :

$$\dot{x} = 1 + rx + x^2$$

$$\dot{x} = f(x, r) = 1 + rx + x^2$$

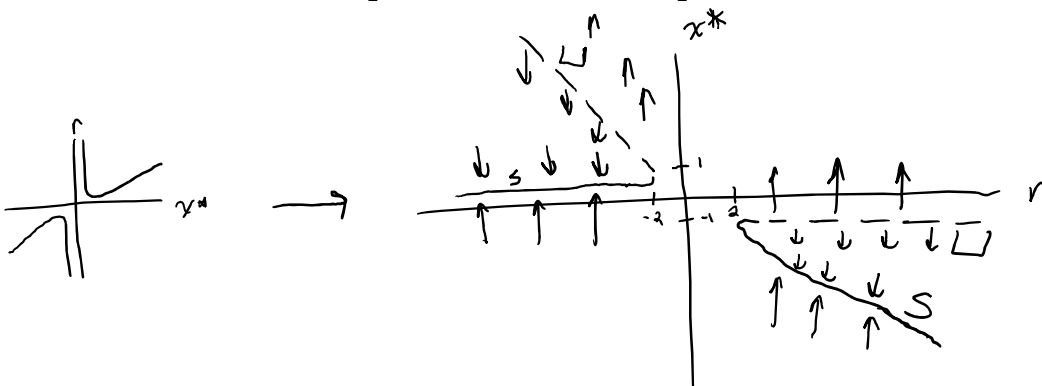


$$1 + rx + x^2 = 0 \rightarrow r = \frac{x^2 + 1}{x}$$

$|r| < 2 \rightarrow$ No Fixed Points

$r = \pm 2 \rightarrow x^* = 1$ is half stable

$|r| > 2 \rightarrow x^* = \frac{-r - \sqrt{r^2 + 4}}{2}$ is stable, $x^* = \frac{-r + \sqrt{r^2 + 4}}{2}$ is unstable

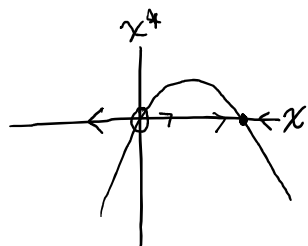


2. Strogatz 3.2.3: Sketch the qualitatively different vector fields that occur as r is varied. Show that a transcritical bifurcation occurs at a critical value of r , to be determined. Finally, sketch the bifurcation diagram of fixed points x^* versus r :

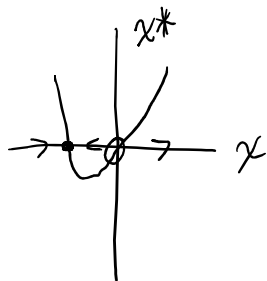
$$\dot{x} = x - rx(1 - x)$$

$$\dot{x} = f(x, r) = x - rx(1 - x)$$

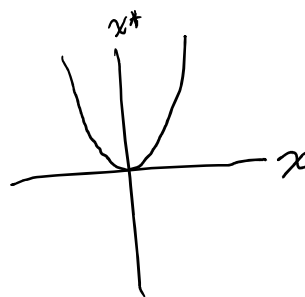
$$x^* \in \left\{1, \frac{r-1}{r}\right\}$$



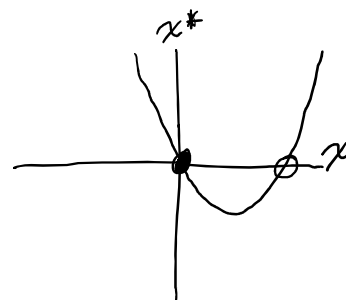
$$r < 0$$



$$0 < r < 1$$



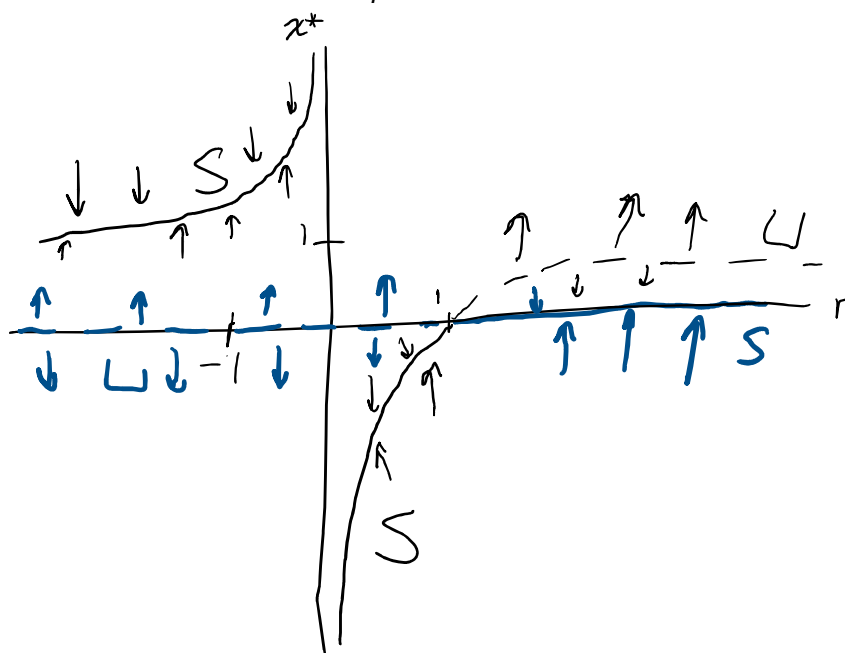
$$r = 1$$



$$r > 1$$

$$r < 1 \rightarrow x^* = 0 \text{ is unstable, } x^* = \frac{r-1}{r} \text{ is stable}$$

$$r > 1 \rightarrow x^* = 0 \text{ is stable, } x^* = \frac{r-1}{r} \text{ is unstable}$$



3. Strogatz 3.3.2

a.

$$\begin{aligned}\dot{P} &= \gamma_1(ED - P) = 0 \therefore D = \frac{P}{E} \\ \dot{D} &= \gamma_2(\lambda + 1 - D - \lambda EP) = 0 \therefore \lambda + 1 = D + \lambda EP \\ \lambda + 1 &= \frac{P}{E} + \lambda EP \rightarrow E(\lambda + 1) = P(1 + \lambda E^2) \\ P &= \frac{E(\lambda + 1)}{1 + \lambda E^2} \\ \dot{E} &= k(P - E) = k\left(\frac{E(\lambda + 1)}{1 + \lambda E^2} - E\right) = kE\left(\frac{\lambda + 1 - 1 - \lambda E^2}{1 + \lambda E^2}\right) \\ \dot{E} &= kE\lambda\left(\frac{1 - E^2}{1 + \lambda E^2}\right)\end{aligned}$$

b.

The fixed points occur when $E = 0$ or $1 - E^2 = 0$

$$E^* \in \{0, \pm 1\}$$

c.

$$f'(E) = -k\lambda * \frac{\lambda E^4 + (\lambda + 3)E^2 - 1}{(1 + \lambda E^2)^2}$$

When $E^* = 0$, $f'(E) = k\lambda$

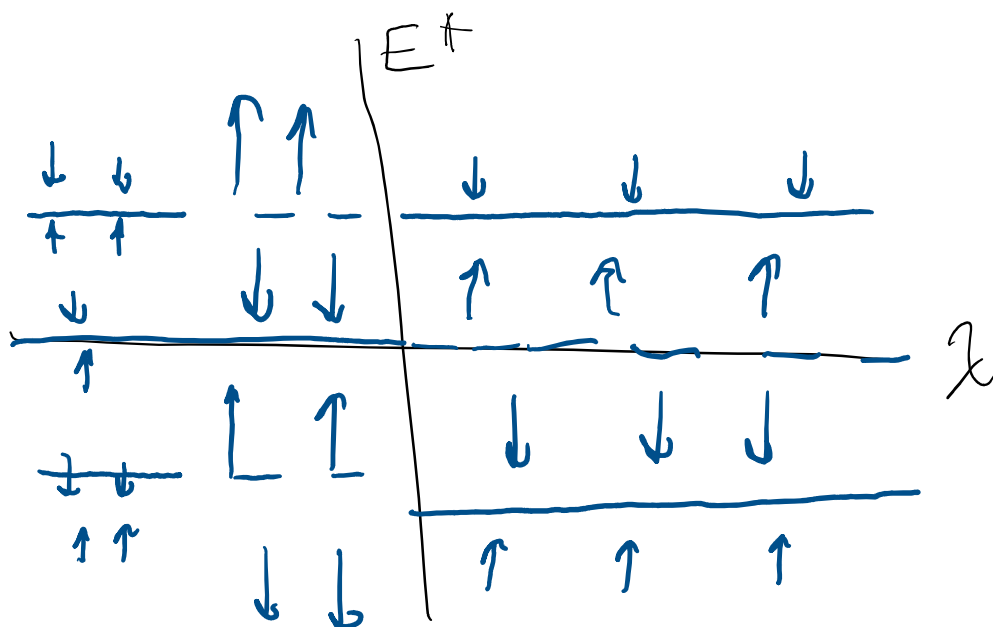
When $E^* = \pm 1$, $f'(E) = -k\lambda * \frac{2(\lambda+1)}{(1+\lambda)(1+\lambda)} = -\frac{2k\lambda}{1+\lambda}$

$\lambda < -1 \rightarrow E^* = 0$ is stable, $E^* = \pm 1$ is stable

$-1 < \lambda < 0 \rightarrow E^* = 0$ is stable, $E^* = \pm 1$ is unstable

$0 < \lambda < 1 \rightarrow E^* = 0$ is unstable, $E^* = \pm 1$ is stable

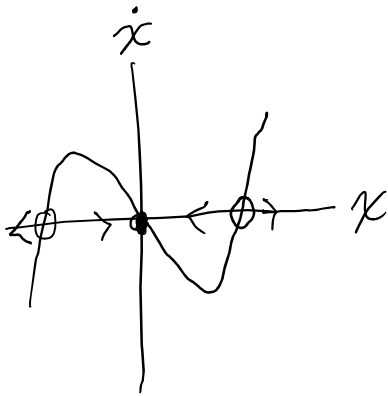
$\lambda > 1 \rightarrow E^* = 0$ is unstable, $E^* = \pm 1$ is stable



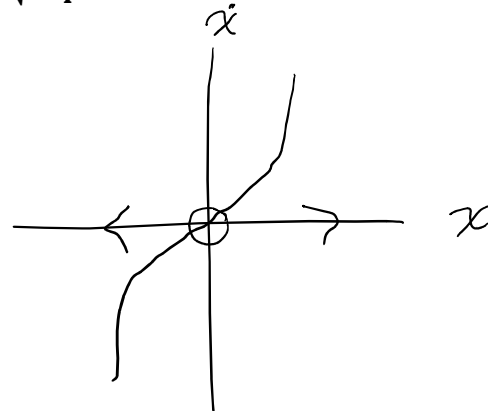
4. Strogatz 3.4.1: Sketch the qualitatively different vector fields that occur as r is varied. Show that a pitchfork bifurcation occurs at a critical value of r , to be determined, and classify the bifurcation as supercritical or subcritical. Finally, sketch the bifurcation diagram of fixed points x^* versus r :

$$\dot{x} = rx + 4x^3$$

$$x^* \in \{0, \pm\sqrt{-\frac{r}{4}}\}$$



$$r < 0$$

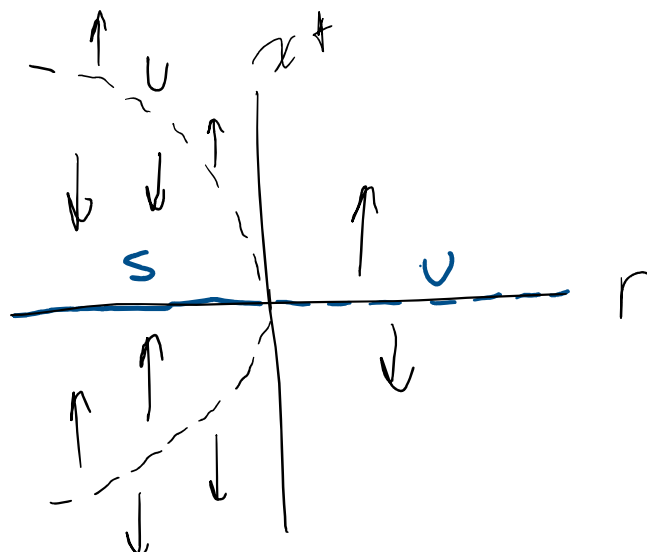


$$r > 0$$

$r < 0 \rightarrow x^* = 0$ is stable, $x^* = \pm\sqrt{-r}$ is unstable
 $r > 0 \rightarrow x^* = 0$ is unstable

$$\dot{x} = f(x^*) = 0 \rightarrow x^* = 0 \text{ or } r = -(x^*)^2$$

This is a subcritical pitchfork bifurcation



5. Strogatz 3.5.8

$$\frac{du}{dt} = au + bu^3 + cu^5$$

$$x = \frac{u}{U} \text{ and } \tau = \frac{t}{T} \therefore u = xU \text{ and } t = \tau T$$

$$\frac{du}{dt} = \frac{dx}{d\tau} \frac{U}{T} = axU + bx^3U^3 - cx^5U^5$$

$$\frac{dx}{d\tau} = axT + bx^3U^2T - cx^5U^4T$$

Now, need to find a, b, c such that $r = aT, bU^2T = 1$ and $cU^4T = 1$

$$bU^2T = cU^4T \rightarrow bU^2 = cU^4 \rightarrow U^2 = \frac{b}{c} \rightarrow$$

$$U = \sqrt{\frac{b}{c}}$$

$$cU^4 = \frac{1}{T} \rightarrow c \left(\frac{b}{c}\right)^2 = \frac{1}{T} \rightarrow T = \frac{1}{c * \left(\frac{b}{c}\right)^2} = \frac{1}{\frac{b^2}{c}} \rightarrow$$

$$T = \frac{c}{b^2}$$

$$r = aT \rightarrow r = \frac{ac}{b^2}$$

6. Strogatz 3.7.3

$$\dot{N} = rN \left(1 - \frac{N}{k}\right) - H$$

$$x = \frac{N}{k} \rightarrow \frac{kdx}{dt} = rkx(1-x) - H$$

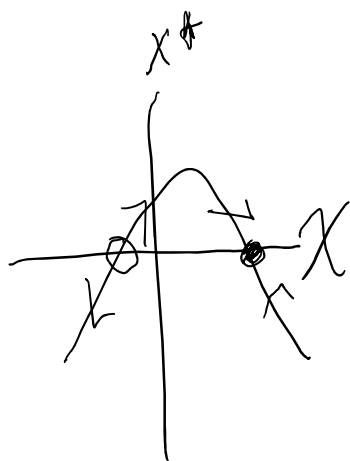
$$\left(\frac{1}{rk}\right) \frac{kdx}{dt} = \frac{rkx(1-x) - H}{rk} = \frac{dx}{rdt} = x(1-x) - \frac{H}{rk}$$

$$\tau = rt$$

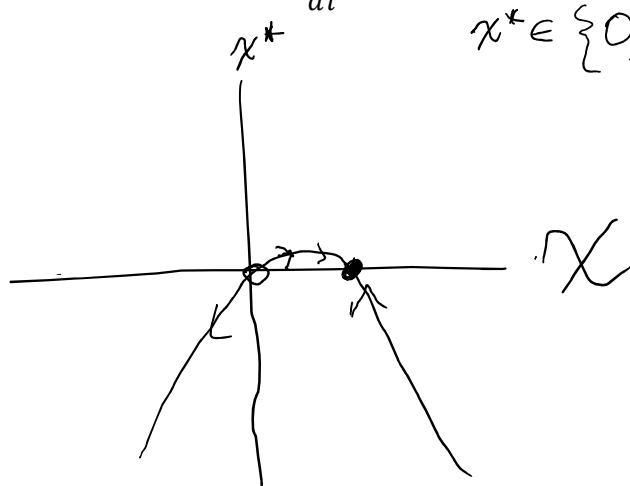
$$\frac{dx}{d\tau} = x(1-x) - \frac{H}{\tau k}, h = \frac{H}{\tau k} \rightarrow$$

$$\frac{dx}{d\tau} = x(1-x) - h$$

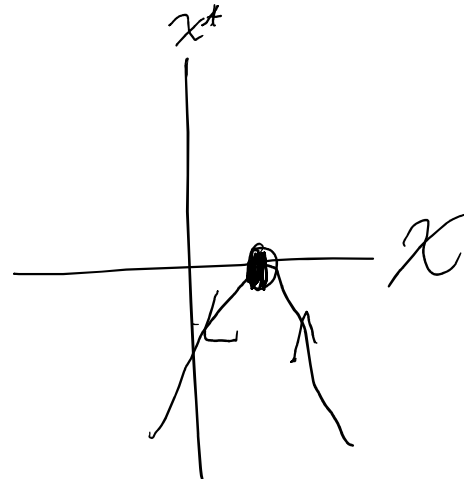
$$x^* \in \{0, 1\}$$



$$h = -1/4$$



$$h = 0$$



$$h = 1/4$$

$$x(1-x) - h = 0 \Rightarrow h = x(1-x)$$

Any value of $h > \frac{1}{4}$ does not have a fixed point. When h is $< \frac{1}{4}$ there are two fixed points as seen in the graphs above. This is similar to the first problem in this homework set which was **saddle-node bifurcation**