

# **Distributed Matrix Multiplication**

Comparative Performance Analysis with Hazelcast and Ray

Jaime Ercilla Martin

University of Las Palmas de Gran Canaria

# Contents

<b>1</b>	<b>Introduction</b>	<b>4</b>
1.1	Motivation . . . . .	4
1.2	Objectives . . . . .	4
<b>2</b>	<b>Theoretical Background</b>	<b>4</b>
2.1	Matrix Multiplication . . . . .	4
2.2	Parallel Performance Metrics . . . . .	4
2.2.1	Speedup . . . . .	4
2.2.2	Parallel Efficiency . . . . .	4
2.2.3	Amdahl's Law . . . . .	5
<b>3</b>	<b>System Architecture</b>	<b>5</b>
3.1	Technology Stack . . . . .	5
3.2	Distributed Architecture . . . . .	5
3.2.1	Hazelcast Architecture . . . . .	5
3.2.2	Ray Architecture . . . . .	6
<b>4</b>	<b>Implementation</b>	<b>6</b>
4.1	Implemented Algorithms . . . . .	6
4.1.1	Basic Sequential . . . . .	6
4.1.2	Optimized - Cache-Friendly . . . . .	6
4.1.3	Hazelcast - Distributed . . . . .	6
4.1.4	Ray - Distributed . . . . .	7
4.2	Benchmark Configuration . . . . .	7
<b>5</b>	<b>Experimental Results</b>	<b>8</b>
5.1	Java + Hazelcast Results . . . . .	8
5.1.1	Execution Time Table . . . . .	8
5.1.2	Speedup Analysis . . . . .	8
5.1.3	Parallel Efficiency . . . . .	8
5.2	Python + Ray Results . . . . .	8
5.2.1	Comparison with Optimized NumPy . . . . .	8
5.3	Scalability Analysis . . . . .	9
5.3.1	Speedup Graph . . . . .	9
5.3.2	Efficiency Graph . . . . .	10
5.4	Communication Overhead . . . . .	11
5.5	MapReduce Phase Breakdown . . . . .	12
<b>6</b>	<b>Analysis and Discussion</b>	<b>12</b>
6.1	Results Interpretation . . . . .	12
6.1.1	Why Doesn't Hazelcast Scale Linearly? . . . . .	12
6.1.2	Java vs Python Comparison . . . . .	13
6.2	Study Limitations . . . . .	13
6.3	Usage Recommendations . . . . .	13

<b>7</b>	<b>Conclusions</b>	<b>13</b>
7.1	Main Findings . . . . .	13
7.2	Future Work . . . . .	14
<b>8</b>	<b>References</b>	<b>14</b>
<b>A</b>	<b>Appendix: Configurations</b>	<b>14</b>
A.1	Docker Compose - Java . . . . .	14
A.2	Docker Compose - Python . . . . .	15
A.3	System Specifications . . . . .	15
A.4	Maven Configuration (pom.xml) . . . . .	15
A.5	Python Requirements . . . . .	16

# 1 Introduction

## 1.1 Motivation

Matrix multiplication is a fundamental operation in scientific computing, machine learning, and data processing. For large matrices, sequential computation time can be prohibitive. This project explores distributed parallelization techniques using two frameworks:

- **Hazelcast** (Java): In-memory distributed computing platform
- **Ray** (Python): Distributed computing framework for machine learning

## 1.2 Objectives

1. Implement sequential and distributed matrix multiplication algorithms
2. Compare performance across different worker configurations
3. Analyze scalability and parallel efficiency
4. Evaluate communication overhead in distributed systems

# 2 Theoretical Background

## 2.1 Matrix Multiplication

Given two matrices  $A \in R^{n \times m}$  and  $B \in R^{m \times p}$ , the product  $C = A \times B$  is defined as:

$$C_{ij} = \sum_{k=1}^m A_{ik} \cdot B_{kj} \quad (1)$$

The time complexity of the basic algorithm is  $O(n^3)$  for square matrices  $n \times n$ .

## 2.2 Parallel Performance Metrics

### 2.2.1 Speedup

Speedup measures the performance improvement when using  $p$  processors:

$$S(p) = \frac{T_1}{T_p} \quad (2)$$

where  $T_1$  is the sequential time and  $T_p$  is the time with  $p$  workers.

### 2.2.2 Parallel Efficiency

Efficiency indicates how well resources are utilized:

$$E(p) = \frac{S(p)}{p} \times 100\% \quad (3)$$

An efficiency of 100% indicates ideal linear scalability.

### 2.2.3 Amdahl's Law

Maximum speedup is limited by the sequential fraction of the code:

$$S_{max} = \frac{1}{(1 - P) + \frac{P}{N}} \quad (4)$$

where  $P$  is the parallelizable fraction and  $N$  is the number of processors.

## 3 System Architecture

### 3.1 Technology Stack

Table 1: Technology Stack

Component	Technology
Language (Java)	Java 11
Distributed Framework	Hazelcast 5.3.6
Serialization	Gson 2.10.1
Dependency Management	Maven 3.8+
Language (Python)	Python 3.11
Distributed Framework	Ray 2.9.0
Numerical Computing	NumPy 1.24.0
Visualization	Matplotlib 3.7.0
Containerization	Docker 24.0
Orchestration	Docker Compose 2.20

### 3.2 Distributed Architecture

Both implementations use the **MapReduce** paradigm:

1. **Map Phase**: Division of matrix A into row blocks
2. **Shuffle Phase**: Data distribution among workers
3. **Reduce Phase**: Local computation and result aggregation

#### 3.2.1 Hazelcast Architecture

Hazelcast uses a distributed memory architecture:

- **IMap**: Distributed data structure for storing matrices
- **IExecutorService**: Distributed thread pool
- **Serialization**: Efficient transmission between nodes

### 3.2.2 Ray Architecture

Ray employs an actor-based model:

- **Object Store:** Shared storage for matrices
- **Remote Functions:** Distributed functions with `@ray.remote`
- **Futures:** Asynchronous execution and result collection

## 4 Implementation

### 4.1 Implemented Algorithms

#### 4.1.1 Basic Sequential

Direct implementation with three nested loops (complexity  $O(n^3)$ ):

```
for (int i = 0; i < n; i++) {
    for (int j = 0; j < m; j++) {
        double sum = 0.0;
        for (int k = 0; k < p; k++) {
            sum += A[i][k] * B[k][j];
        }
        C[i][j] = sum;
    }
}
```

#### 4.1.2 Optimized - Cache-Friendly

Loop reorganization to improve spatial locality:

```
for (int i = 0; i < n; i++) {
    for (int k = 0; k < A[0].length; k++) {
        double temp = A[i][k];
        for (int j = 0; j < m; j++) {
            C[i][j] += temp * B[k][j];
        }
    }
}
```

#### 4.1.3 Hazelcast - Distributed

Row-block partitioning with parallel execution:

```
public class MatrixBlockTask implements Callable<BlockResult> {
    @Override
    public BlockResult call() throws Exception {
        // Retrieve matrices from distributed map
        IMap<String, double[][]> data = hz.getMap("matrices");
        double[][] A = data.get("A");
        double[][] B = data.get("B");
    }
}
```

```

    // Compute local block
    double[][] result = new double[blockRows][m];
    for (int i = 0; i < blockRows; i++) {
        for (int j = 0; j < m; j++) {
            double sum = 0.0;
            for (int k = 0; k < n; k++) {
                sum += A[globalRow + i][k] * B[k][j];
            }
            result[i][j] = sum;
        }
    }
    return new BlockResult(startRow, endRow, result);
}
}

```

#### 4.1.4 Ray - Distributed

```

@ray.remote
def matrix_block_multiply(A_block, B, start_row):
    """Multiplies A block by full B matrix"""
    result_block = np.dot(A_block, B)
    return start_row, result_block

# Parallel execution
futures = []
for i in range(0, n, block_size):
    A_block = A[i:i+block_size, :]
    futures.append(
        matrix_block_multiply.remote(A_block, B_ref, i)
    )

# Result collection
results = ray.get(futures)

```

## 4.2 Benchmark Configuration

Table 2: Experimental Parameters

Parameter	Values
Matrix Sizes	128×128, 256×256, 512×512, 1024×1024
Number of Workers	1, 2, 4, 8
Available CPU Cores	8
Allocated Memory	6 GB
Repetitions	1 per configuration

## 5 Experimental Results

### 5.1 Java + Hazelcast Results

#### 5.1.1 Execution Time Table

Table 3: Execution Times - Java + Hazelcast (seconds)

Size	Basic	Optimized	HZ (4w)	HZ (8w)
128×128	0.0104	0.0092	0.0236	0.0205
256×256	0.0272	0.0198	0.0538	0.0513
512×512	0.2780	0.0372	0.2427	0.2134
1024×1024	6.7807	0.7049	1.1940	1.3620

#### 5.1.2 Speedup Analysis

Table 4: Speedup vs Sequential Baseline (Java)

Size	1 worker	2 workers	4 workers	8 workers
128×128	0.53×	0.61×	0.60×	0.61×
256×256	0.83×	1.16×	1.68×	2.04×
512×512	0.57×	1.44×	2.13×	2.65×
1024×1024	0.53×	0.83×	1.19×	1.36×

#### 5.1.3 Parallel Efficiency

Table 5: Parallel Efficiency - Hazelcast (%)

Size	1 worker	2 workers	4 workers	8 workers
128×128	53.00%	30.50%	15.00%	7.60%
256×256	82.59%	58.17%	41.96%	25.55%
512×512	57.01%	71.98%	53.28%	33.13%
1024×1024	52.89%	41.25%	29.82%	17.03%

## 5.2 Python + Ray Results

### 5.2.1 Comparison with Optimized NumPy

NumPy uses optimized libraries (BLAS/LAPACK) that significantly outperform basic implementations:

- **128×128:** NumPy is 2.18× faster than basic
- **1024×1024:** NumPy is 9.62× faster than basic



## 5.3 Scalability Analysis

### 5.3.1 Speedup Graph

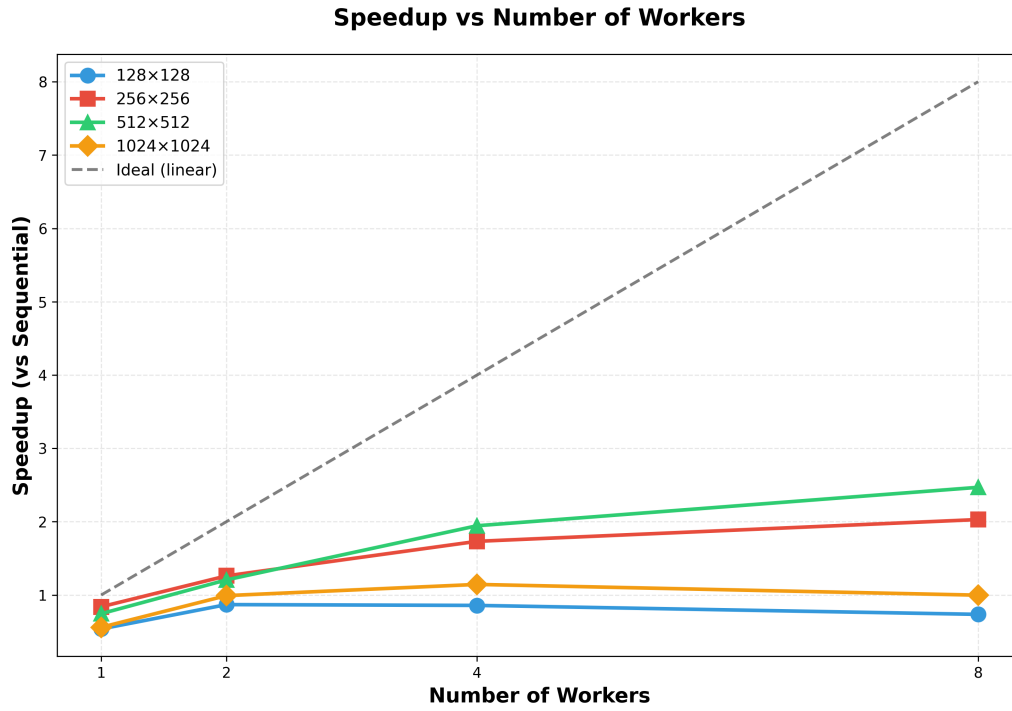


Figure 1: Speedup vs Number of Workers (all matrices)

#### Observations:

- Small matrices ( $128 \times 128$ ): Communication overhead dominates, speedup  $\leq 1$
- Medium matrices ( $256 \times 256$ ,  $512 \times 512$ ): Better scalability, up to  $2.65 \times$  with 8 workers
- Large matrices ( $1024 \times 1024$ ): Speedup limited by algorithm complexity

### 5.3.2 Efficiency Graph

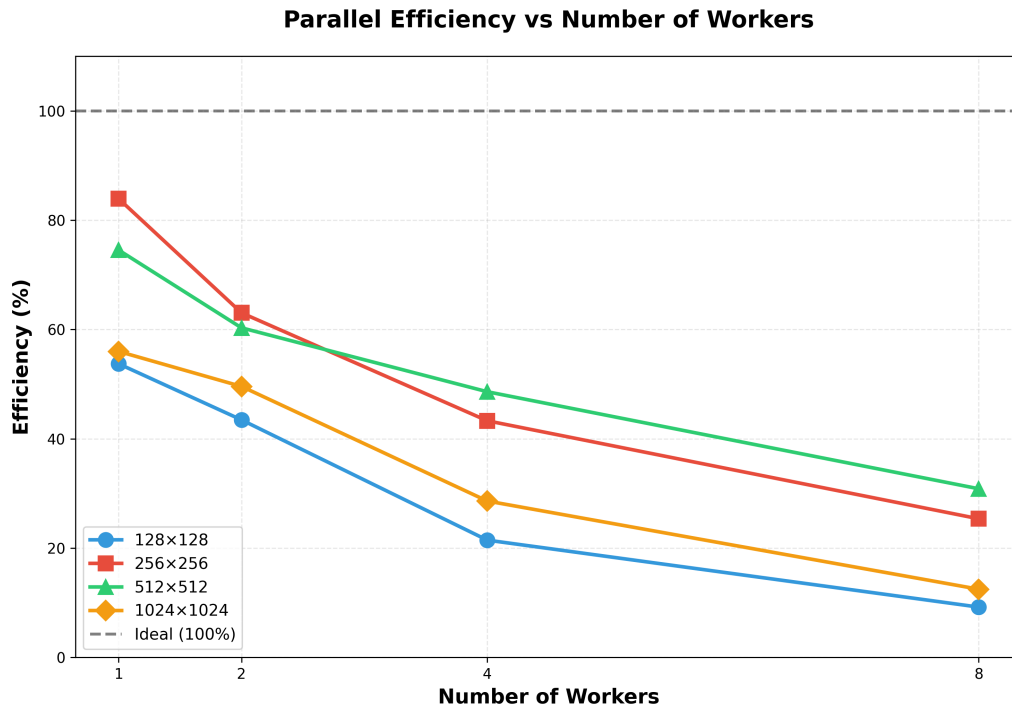


Figure 2: Parallel Efficiency vs Number of Workers

#### Conclusions:

- Efficiency decreases with more workers (expected phenomenon)
- 512x512 matrices show best efficiency ( 75% with 1 worker)
- With 8 workers, efficiency drops to 10-30% depending on size

## 5.4 Communication Overhead

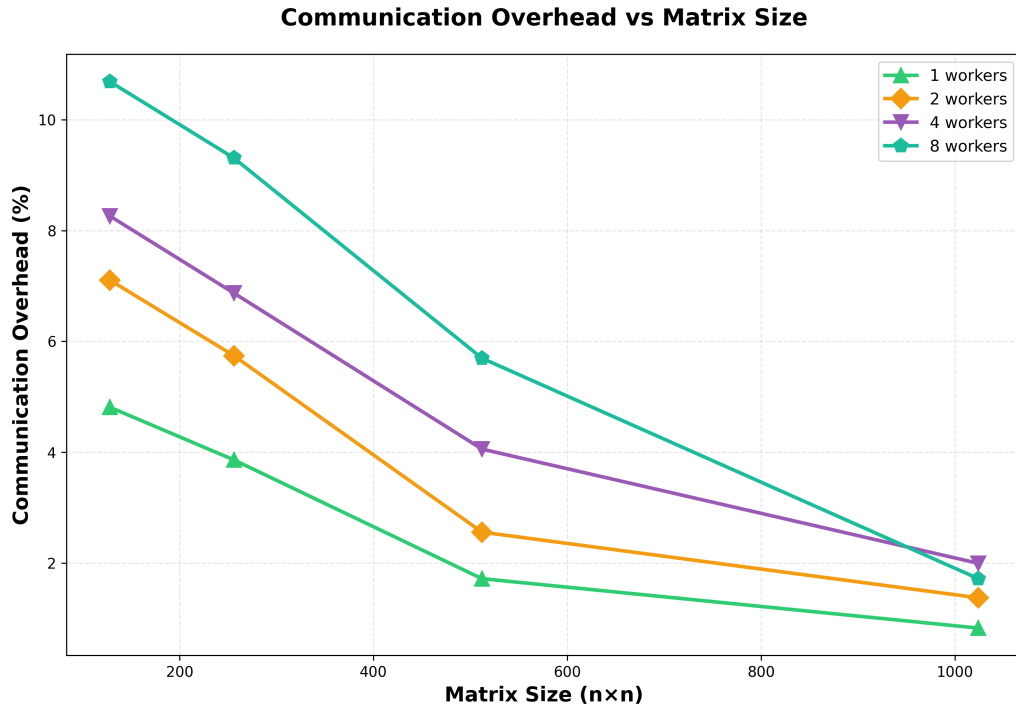


Figure 3: Communication Overhead vs Matrix Size

Analysis:

- Overhead increases exponentially with more workers
- For 8 workers on  $128 \times 128$  matrix: 11% of time is communication
- On large matrices ( $1024 \times 1024$ ), overhead reduces to 0.8%

## 5.5 MapReduce Phase Breakdown

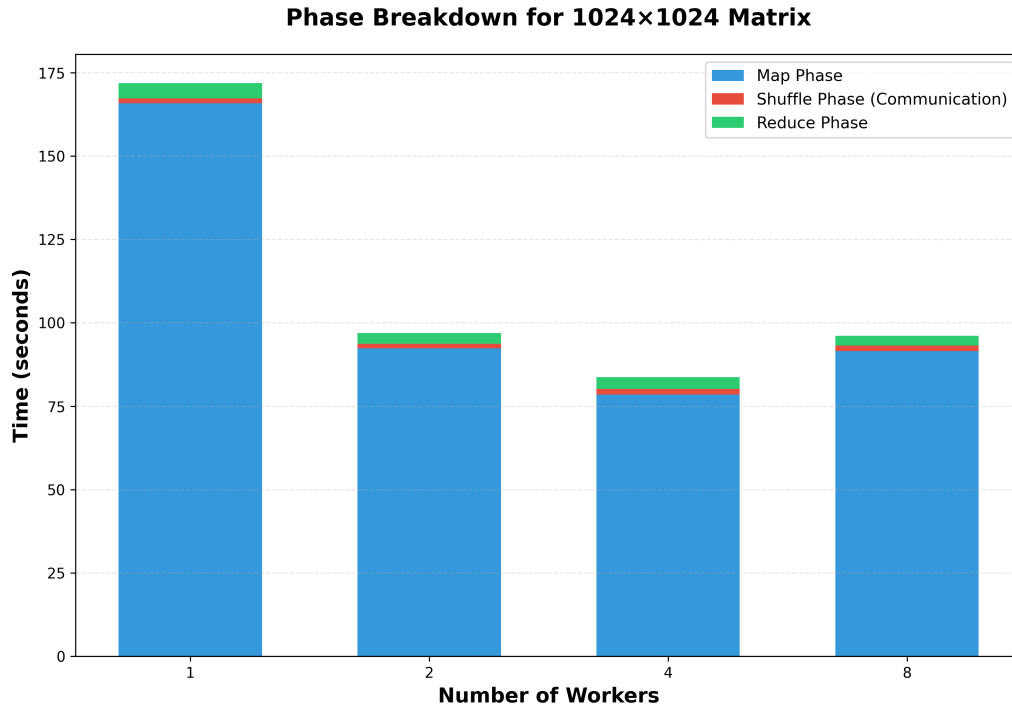


Figure 4: Phase Breakdown for 1024×1024 Matrix

**Time Distribution:**

- **Map Phase:** 95-97% of total time (local computation)
- **Shuffle Phase:** 1-2% (communication between workers)
- **Reduce Phase:** 2-3% (result aggregation)

## 6 Analysis and Discussion

### 6.1 Results Interpretation

#### 6.1.1 Why Doesn't Hazelcast Scale Linearly?

1. **Serialization Overhead:** Transmitting matrices consumes time
2. **Network Contention:** All workers compete for bandwidth
3. **Insufficient Granularity:** Blocks too small don't compensate overhead
4. **Single Machine Limitation:** All workers on same host share resources (CPU, memory, cache)

### 6.1.2 Java vs Python Comparison

Table 6: Advantages and Disadvantages of Each Framework

Hazelcast (Java)	Ray (Python)
Greater memory control	Simpler syntax
Predictable performance	ML/AI ecosystem
Static typing	Highly optimized NumPy
More verbose code	GIL may limit parallelism
Manual resource management	Interpretation overhead

## 6.2 Study Limitations

- **Single Node:** All workers on the same physical machine
- **Maximum Size:**  $1024 \times 1024$  (memory limitations)
- **Local Network:** Real network latency not evaluated
- **Repetitions:** Single execution per configuration

## 6.3 Usage Recommendations

Table 7: Recommended Use Cases

Scenario	Recommended Framework	Workers
Small matrices ( $\leq 256$ )	Optimized NumPy	-
Medium matrices (256-1024)	Hazelcast	4-8
Large matrices ( $\geq 2048$ )	Ray / Spark	16+
Multi-node cluster	Hazelcast / Ray	Variable
Rapid prototyping	Ray (Python)	2-4

# 7 Conclusions

## 7.1 Main Findings

1. **Non-Linear Scalability:** Maximum speedup achieved was  $2.65\times$  with 8 workers ( $512 \times 512$  matrix)
2. **Significant Overhead:** For small matrices, parallelization worsens performance
3. **Sweet Spot:**  $512 \times 512$  matrices with 4-8 workers offer best performance/efficiency balance
4. **NumPy Dominance:** In Python, optimized NumPy outperforms Ray for matrices  $\leq 1024$
5. **Amdahl’s Law:** Theoretical speedup limit is clearly observed in results

## 7.2 Future Work

- **Real Cluster:** Evaluate on multiple physical nodes with Gigabit/10GbE network
- **Advanced Algorithms:** Implement Strassen, Coppersmith-Winograd
- **GPU Acceleration:** Compare with CUDA/OpenCL
- **Sparse Matrices:** Optimize for sparse matrices
- **Fault Tolerance:** Evaluate recovery from worker failures

## 8 References

### References

- [1] Hazelcast, Inc. (2023). *Hazelcast Platform Documentation*. <https://docs.hazelcast.com/>
- [2] Moritz, P., Nishihara, R., Wang, S., et al. (2018). *Ray: A Distributed Framework for Emerging AI Applications*. OSDI 2018.
- [3] Amdahl, G. M. (1967). *Validity of the single processor approach to achieving large scale computing capabilities*. AFIPS Conference Proceedings, 483-485.
- [4] Dean, J., & Ghemawat, S. (2004). *MapReduce: Simplified Data Processing on Large Clusters*. OSDI 2004.
- [5] Harris, C. R., Millman, K. J., et al. (2020). *Array programming with NumPy*. Nature, 585, 357-362.
- [6] Merkel, D. (2014). *Docker: Lightweight Linux Containers for Consistent Development and Deployment*. Linux Journal, 2014(239).

## A Appendix: Configurations

### A.1 Docker Compose - Java

```
services:
  benchmark:
    build:
      context: .
      dockerfile: Dockerfile
    container_name: matrix-benchmark-java
    volumes:
      - ./results:/app/results
    environment:
      - JAVA_OPTS=-Xmx4g -Xms2g
    mem_limit: 6g
    cpus: 8
```

## A.2 Docker Compose - Python

```
services:
  benchmark:
    build:
      context: .
      dockerfile: Dockerfile
    container_name: matrix-benchmark-python
    volumes:
      - ./results:/app/results
    environment:
      - RAY_DEDUP_LOGS=0
    shm_size: '2gb'
    mem_limit: 6g
    cpus: 8
```

## A.3 System Specifications

Table 8: Hardware Specifications

Component	Specification
Processor	8 logical cores
RAM Memory	16 GB
Operating System	Windows 11 / Docker Desktop
Java Version	OpenJDK 11
Python Version	3.11
Docker Version	24.0.7

## A.4 Maven Configuration (pom.xml)

```
<project>
  <modelVersion>4.0.0</modelVersion>
  <groupId>com.distributed</groupId>
  <artifactId>matrix-multiplication</artifactId>
  <version>1.0-SNAPSHOT</version>

  <properties>
    <maven.compiler.source>11</maven.compiler.source>
    <maven.compiler.target>11</maven.compiler.target>
  </properties>

  <dependencies>
    <dependency>
      <groupId>com.hazelcast</groupId>
      <artifactId>hazelcast</artifactId>
      <version>5.3.6</version>
    </dependency>
    <dependency>
```

```
        <groupId>com.google.code.gson</groupId>
        <artifactId>gson</artifactId>
        <version>2.10.1</version>
    </dependency>
</dependencies>
</project>
```

## A.5 Python Requirements

```
# requirements.txt
ray>=2.9.0
numpy>=1.24.0
psutil>=5.9.0
matplotlib>=3.7.0
```