

# Computer Vision

## Teacher Activity: Edge Detection

### Importing Packages

Packages are imported in following manner.

```
import package_name
```

In the next cell we have imported the following packages.

1. cv2 . It is a part of openCV library of Python which helps in solving computer vision problems.
2. numpy . It adds support for arrays, along with a collection of mathematical functions to operate on these arrays.
3. matplotlib . It is a plotting library for python. .pyplot is a sub-package or set of functions available in matplotlib which we'll be using.

np , plt are all aliases for their corresponding packages. Alias are second name assigned to values or variables.

%matplotlib inline is a "magic function" renders plots

```
In [1]: import cv2
import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
```

### Creating edge\_detection function

The function takes image as the argument .Canny() function has been used on image . It accepts a gray scale image as input and it uses a min and max threshold values as additional arguments. Canny Edge Detection is used to detect the edges in an image.

images is a list of variables image , edges\_detected .

location is the list created for subplot, it takes a 3-digit input to create subplots. Digits are mapped as nrows, ncols, index.

Applying the for loop for the elements in the zip

.subplots method provides a way to plot multiple plots on a single figure.

.imshow displays image specifying the display range as a two-element vector. The other parameter is a colormap we have assigned it a value "gray scale"

plt. show() starts an event loop, looks for all currently active figure objects, and opens one or more interactive windows that display your figure or figures.

```
In [2]: def edge_detection(image):
edges_detected = cv2.Canny(image , 100, 200)
images = [image , edges_detected]
```

```
location = [121, 122]
for loc, edge_image in zip(location, images):
    plt.subplot(loc)
    plt.imshow(edge_image, cmap='gray')
    plt.show()
```

## Creating a grayscale image

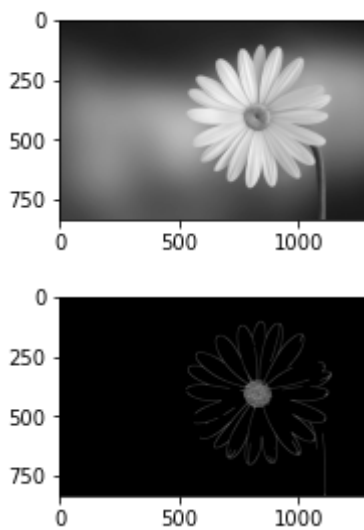
`cv2.imread()` method loads an image from the specified file and converts it based on second parameter i.e., 0 .

```
In [13]: img = cv2.imread('1.jpeg', 0)
```

## Calling function edge\_detection

Function call using `img` as parameter

```
In [14]: edge_detection(img)
```



```
In [ ]:
```