

Total time: 16.092s

File: /Users/rishabhjain/Documents/Masters/SEM 2/Aritificial Intelligence/Program/Program 1/program_1.py

Function: expand at line 48

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
48					@cpu
49					def expand(board):
50	449564	202.4ms	.	1.3%	for i in range(len(board.data)):
51	1123859	314.7ms	.	2.0%	for j in range(len(board.data[i])):
52	899077	265.2ms	.	1.6%	if board.data[i][j] == '*':
53	112391	34.5ms	.	0.2%	location = [i,j];
54	112391	23.2ms	.	0.1%	break
55					
56	112391	23.9ms	.	0.1%	actions = []
57	416708	1.73s	.	10.7%	for move in possible_actions(constants.board, location):
58	304317	13.48s	.	83.7%	actions.append([result(location, move, board.data) , move])
59					
60	112391	24.8ms	.	0.2%	return actions

Total time: 0.805s

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Function: possible_actions at line 62

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
62					@cpu
63					def possible_actions(board, location):
64	112391	39.0ms	.	4.8%	actions = ["RIGHT", "LEFT", "UP", "DOWN"]
65	112391	28.2ms	.	3.5%	actionstopeform = []
66					
67	561955	140.9ms	.	17.5%	for x in actions:
68					# for moving right
69	449564	113.0ms	.	14.0%	if x == "RIGHT":
70	112391	41.6ms	.	5.2%	if location[1]+1 < len(board):
71	76061	40.6ms	.	5.0%	actionstopeform.append([x,location[0],location[1]+1])
72					# for moving left
73	337173	90.5ms	.	11.2%	elif x == "LEFT":
74	112391	35.6ms	.	4.4%	if location[1]-1 >= 0:
75	76010	35.8ms	.	4.5%	actionstopeform.append([x,location[0],location[1]-1])
76					# for moving up
77	224782	54.4ms	.	6.8%	elif x == "UP":
78	112391	35.0ms	.	4.3%	if location[0]-1 >= 0:
79	76063	30.4ms	.	3.8%	actionstopeform.append([x,location[0]-1,location[1]])
80					# for moving down
81	112391	26.8ms	.	3.3%	elif x == "DOWN":
82	112391	36.6ms	.	4.5%	if location[0]+1 < len(board):
83	76183	30.8ms	.	3.8%	actionstopeform.append([x,location[0]+1,location[1]])
84					
85	112391	25.7ms	.	3.2%	return actionstopeform

Total time: 12.736s

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Function: result at line 87

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
87					@cpu
88					def result(location,action,board):
89					# copy of a board so that we can modify it
90	304317	10.54s	.	82.8%	newBoard = copy.deepcopy(board)
91	304317	731.4ms	.	5.7%	temp = copy.deepcopy(newBoard[action[1]][action[2]])
92	304317	707.2ms	.	5.6%	newBoard[action[1]][action[2]] = copy.deepcopy('*')
93	304317	693.5ms	.	5.4%	newBoard[location[0]][location[1]] = copy.deepcopy(temp)
94					# return new board after moving * - NIL to the new location
95	304317	64.1ms	.	0.5%	return newBoard

Total time: 651.005s

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Function: bfs at line 139

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
139					@cpu
140					def bfs(board):
141	1	.	.	.	frontier = queue.Queue()
142	1	.	.	.	node = Node(data = board)
143	1	.	.	.	frontier.put(node)
144	1	.	.	.	maxQueueSize = 1
145	1	.	.	.	if constants.goalBoard == node.data:
146					print('mill gya:', maxQueueSize)
147					return node
148					
149	1	.	.	.	reached = []
150	1	.	.	.	reached.append(board)
151					
152	112391	412.8ms	.	0.1%	while not frontier.empty():
153	112391	753.2ms	.	0.1%	val = frontier.get()
154	416706	17.44s	.	2.7%	for child in expand(val):
155	304316	896.6ms	.	0.1%	s = Node(data=child[0], depth = val.depth + 1, move= child[1] , prev=val)
156					
157	304316	234.2ms	.	.	if goalBoard == s.data:
158	1	0.1ms	0.1ms	.	print('Max queue size:', maxQueueSize)
159	1	.	.	.	return s
160	304315	629.45s	2.1ms	96.7%	if s.data not in reached:

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161      136150      229.0ms      .      .      reached.append(s.data)
162      136150      1.53s      .      0.2%      frontier.put(s)
163      136150      57.6ms      .      .      maxQueueSize+=1
164
165                                     print('Max queue size:', maxQueueSize)
166
167                                     return failure

```

Total time: 0.000s

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Function: printStatistics at line 258

Line #	Hits	Time	Per Hit	% Time	Line Contents
258					@cpu
259					def printStatistics(solution):
260	1	.	.	0.6%	pathCost = 0
261	1	.	.	0.3%	stateSequence = []
262	1	.	.	.	actionSequence = []
263					
264	25	.	.	3.6%	while solution.prev != None:
265	24	.	.	2.1%	stateSequence.insert(0, solution.data)
266	24	.	.	3.3%	actionSequence.insert(0, solution.move)
267	24	.	.	1.8%	solution = solution.prev
268	24	.	.	2.1%	pathCost += 1
269					
270	1	.	.	9.9%	print('Action sequence:')
271	1	0.1ms	0.1ms	19.2%	print(*actionSequence, sep='\n')
272					
273	1	.	.	0.9%	print('\nState sequence:')
274	1	0.2ms	0.2ms	54.5%	print(*stateSequence, sep='\n')
275					
276	1	.	.	1.8%	print('\nPath cost:', pathCost)