

Total time: 0.050s

File: /Users/rishabhjain/Documents/Masters/SEM 2/Aritificial Intelligence/Program/assignment_1/a_star.py

Function: expand at line 51

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
51					@cpu
52					def expand(board):
53	1540	0.4ms	.	0.8%	for i in range(len(board.data)):
54	3867	1.0ms	.	2.0%	for j in range(len(board.data[i])):
55	3097	0.9ms	.	1.7%	if board.data[i][j] == '*':
56	385	0.1ms	.	0.2%	location = [i,j];
57	385	0.1ms	.	0.2%	break
58					
59	385	0.1ms	.	0.2%	actions = []
60	1427	5.4ms	.	10.8%	for move in possible_actions(constants.board, location):
61	1042	41.9ms	.	84.0%	actions.append([result(location, move, board.data) , move])
62					# prepare all poss
63	385	0.1ms	.	0.2%	return actions
					# After expanding

Total time: 0.003s

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Function: possible_actions at line 67

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
67					@cpu
68					def possible_actions(board, location):
69	385	0.1ms	.	4.7%	actions = ["RIGHT", "LEFT", "UP", "DOWN"]
70	385	0.1ms	.	3.0%	actionstopeform = []
71					
72	1925	0.5ms	.	18.0%	for x in actions:
73					# for moving right
74	1540	0.4ms	.	13.9%	if x == "RIGHT":
75	385	0.2ms	.	5.8%	if location[1]+1 < len(board):
76	252	0.1ms	.	3.5%	actionstopeform.append([x,location[0],location[1]+1])
77					# for moving left
78	1155	0.3ms	.	10.6%	elif x == "LEFT":
79	385	0.1ms	.	4.5%	if location[1]-1 >= 0:
80	269	0.1ms	.	4.1%	actionstopeform.append([x,location[0],location[1]-1])
81					# for moving up
82	770	0.2ms	.	6.7%	elif x == "UP":
83	385	0.1ms	.	4.8%	if location[0]-1 >= 0:
84	268	0.1ms	.	4.3%	actionstopeform.append([x,location[0]-1,location[1]])
85					# for moving down
86	385	0.1ms	.	4.0%	elif x == "DOWN":
87	385	0.1ms	.	4.8%	if location[0]+1 < len(board):
88	253	0.1ms	.	4.2%	actionstopeform.append([x,location[0]+1,location[1]])
89					
90	385	0.1ms	.	3.2%	return actionstopeform

Total time: 0.040s

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Function: result at line 94

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
94					@cpu
95					def result(location,action,board):
96	1042	32.4ms	.	81.7%	newBoard = copy.deepcopy(board)
97	1042	2.4ms	.	6.1%	temp = copy.deepcopy(newBoard[action[1]][action[2]])
98	1042	2.4ms	.	5.9%	newBoard[action[1]][action[2]] = copy.deepcopy('*')
99	1042	2.3ms	.	5.8%	newBoard[location[0]][location[1]] = copy.deepcopy(temp)
100	1042	0.2ms	.	0.5%	return newBoard
					# return new board aft

Total time: 0.000s

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Function: misplaced at line 104

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
104					@cpu
105					def misplaced(puzzle):
106					num_misplaced = 0
107					for i in range(len(puzzle.data)):
108					for j in range(len(puzzle.data)):
109					if puzzle.data[i][j] != constants.goalBoard[i][j] and puzzle.data[i][j] !=
110					num_misplaced += 1
111					return num_misplaced

Total time: 0.015s

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Function: manhattan at line 114

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
114					@cpu
115					def manhattan(state):
116	626	0.2ms	.	1.3%	state = state.data
117	626	0.2ms	.	1.2%	goal_state = constants.goalBoard
118	626	0.2ms	.	1.1%	distance = 0
119					
120					# Create a dictionary that maps each value to its position in the goal state
121	626	0.1ms	.	1.0%	goal_dict = {}

Line #	Hits	Time	Per Hit	% Time	Line Contents
122	2504	0.7ms	.	4.9%	for i in range(len(goal_state)):
123	7512	2.1ms	.	14.0%	for j in range(len(goal_state[0])):
124	5634	1.6ms	.	11.0%	if goal_state[i][j] != '*':
125	5008	1.6ms	.	10.8%	goal_dict[goal_state[i][j]] = (i, j)
126					
127					# Calculate Manhattan distance
128	2504	0.7ms	.	4.5%	for i in range(len(state)):
129	7512	2.1ms	.	14.0%	for j in range(len(state[0])):
130	5634	2.2ms	.	15.1%	if state[i][j] != '*' and state[i][j] != goal_state[i][j]:
131	3278	0.9ms	.	5.7%	value = state[i][j]
132	3278	0.9ms	.	6.3%	row, col = goal_dict[value]
133	3278	1.2ms	.	8.2%	distance += abs(row - i) + abs(col - j)
134					
135	626	0.2ms	.	1.1%	return distance

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Function: linear_conflict at line 137

Line #	Hits	Time	Per Hit	% Time	Line Contents
137					@cpu
138					def linear_conflict(board, goal):
139					n = len(board)
140					linear_conflicts = 0
141					
142					# Find the linear conflicts in rows
143					for i in range(n):
144					row = board[i]
145					goal_row = goal[i]
146					for j in range(n):
147					if row[j] != '*' and row[j] in goal_row:
148					for k in range(j+1, n):
149					if row[k] != '*' and row[k] in goal_row and goal_row.index(row[j])
150					linear_conflicts += 2
151					
152					# Find the linear conflicts in columns
153					for j in range(n):
154					column = [board[i][j] for i in range(n)]
155					goal_column = [goal[i][j] for i in range(n)]
156					for i in range(n):
157					if column[i] != '*' and column[i] in goal_column:
158					for k in range(i+1, n):
159					if column[k] != '*' and column[k] in goal_column and goal_column.i
160					linear_conflicts += 2
161					
162					return linear_conflicts

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Function: f at line 165

Line #	Hits	Time	Per Hit	% Time	Line Contents
165					@cpu
166					# Heuristic Function to calculate hueristic value f(x) = h(x) + g(x)
167					def f(board):
168					manhattan_distance = manhattan(board)
169					manhattan_distance += linear_conflict(board.data, constants.goalBoard) # Add l
170					return manhattan_distance + board.depth

Total time: 0.000s

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Function: zero_function at line 174

Line #	Hits	Time	Per Hit	% Time	Line Contents
174					@cpu
175					def zero_function(board):
176					return 0

Total time: 0.095s

File: /Users/rishabhjain/Documents/Masters/SEM 2/Aritificial Intelligence/Program/assignment_1/a_star.py

Function: a_star at line 179

Line #	Hits	Time	Per Hit	% Time	Line Contents
179					@memory_profiler.profile
180					@cpu
181					def a_star(initialProblem, f):
182	1	.	.	.	initialNode = Node(data = initialProblem) # node=NODE(STATE=problem.
183	1	.	.	.	frontier = PriorityQueue() # frontier←a priority queu
184	1	0.1ms	0.1ms	0.1%	frontier.append((f(initialNode), initialNode))
185					
186	1	.	.	.	reached = {str(initialProblem): initialNode} # reached←a lookup table,
187					
188	386	0.2ms	.	0.2%	while not frontier.empty(): # while not IS-EMPTY(front
189	386	0.2ms	.	0.2%	node = frontier.get() # node=POP(frontier)
190					
191	386	0.2ms	.	0.2%	if constants.goalBoard == node[1].data: # if problem.IS=GOAL(node.
192					#print('Max queue size:', frontier.getSize()) # only for debug
193	1	.	.	.	return node[1] # then return node
194					
195	1427	53.1ms	.	55.9%	for child in expand(node[1]): # for each child in EXPAN

196					# s←child.STATE
197	1042	1.2ms	.	1.3%	s = Node(data = child[0], depth = node[1].depth + 1, move = child[1], pr
198					
199					# if s is not in reached or child.PATH-COST < reached[s].PATH-COST then
200	1042	1.9ms	.	2.0%	if str(s.data) not in reached or s.depth < reached[str(s.data)].depth:
201	625	0.8ms	.	0.8%	reached[str(s.data)] = s # reached[s]←child
202	625	37.2ms	0.1ms	39.1%	frontier.append((f(s) ,s)) # add child to frontier
203					
204					return constants.failure # return failure

Total time: 0.000s
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Function: printStatistics at line 207

Line #	Hits	Time	Per Hit	% Time	Line Contents
207					@cpu
208					def printStatistics(solution):
209	1	.	.	0.4%	pathCost = 0
210	1	.	.	0.4%	stateSequence = []
211	1	.	.	.	actionSequence = []
212					
213	29	.	.	4.3%	while solution.prev != None:
214	28	.	.	4.3%	stateSequence.insert(0, solution.data)
215	28	.	.	4.3%	actionSequence.insert(0, solution.move)
216	28	.	.	3.8%	solution = solution.prev
217	28	.	.	3.0%	pathCost += 1
218					
219	1	.	.	3.0%	print('Action sequence:')
220	1	.	.	17.9%	print(*actionSequence, sep='\n')
221					
222	1	.	.	1.3%	print('\nState sequence:')
223	1	0.1ms	0.1ms	55.1%	print(*stateSequence, sep='\n')
224					
225	1	.	.	2.1%	print('\nPath cost:', pathCost)