

Total time: 0.051s

File: /Users/rishabhjain/Documents/Masters/SEM 2/Aritificial Intelligence/Program/Program 1/program_1.py

Function: expand at line 48

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
48					@cpu
49					def expand(board):
50	1540	0.4ms	.	0.8%	for i in range(len(board.data)):
51	3867	1.1ms	.	2.2%	for j in range(len(board.data[i])):
52	3097	0.8ms	.	1.7%	if board.data[i][j] == '*':
53	385	0.1ms	.	0.2%	location = [i,j];
54	385	0.1ms	.	0.2%	break
55					
56	385	0.1ms	.	0.2%	actions = []
57	1427	5.4ms	.	10.6%	for move in possible_actions(constants.board, location):
58	1042	42.9ms	.	84.1%	actions.append([result(location, move, board.data) , move])
59					
60	385	0.1ms	.	0.2%	return actions

Total time: 0.003s

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Function: possible_actions at line 62

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
62					@cpu
63					def possible_actions(board, location):
64	385	0.1ms	.	4.5%	actions = ["RIGHT", "LEFT", "UP", "DOWN"]
65	385	0.1ms	.	2.9%	actionstopeform = []
66					
67	1925	0.5ms	.	17.6%	for x in actions:
68					# for moving right
69	1540	0.4ms	.	14.7%	if x == "RIGHT":
70	385	0.1ms	.	5.5%	if location[1]+1 < len(board):
71	252	0.1ms	.	3.5%	actionstopeform.append([x,location[0],location[1]+1])
72					# for moving left
73	1155	0.3ms	.	10.5%	elif x == "LEFT":
74	385	0.1ms	.	4.7%	if location[1]-1 >= 0:
75	269	0.1ms	.	4.7%	actionstopeform.append([x,location[0],location[1]-1])
76					# for moving up
77	770	0.2ms	.	6.9%	elif x == "UP":
78	385	0.1ms	.	4.4%	if location[0]-1 >= 0:
79	268	0.1ms	.	4.2%	actionstopeform.append([x,location[0]-1,location[1]])
80					# for moving down
81	385	0.1ms	.	3.5%	elif x == "DOWN":
82	385	0.1ms	.	4.9%	if location[0]+1 < len(board):
83	253	0.1ms	.	4.0%	actionstopeform.append([x,location[0]+1,location[1]])
84					
85	385	0.1ms	.	3.4%	return actionstopeform

Total time: 0.041s

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Function: result at line 87

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
87					@cpu
88					def result(location,action,board):
89					# copy of a board so that we can modify it
90	1042	33.1ms	.	81.6%	newBoard = copy.deepcopy(board)
91	1042	2.5ms	.	6.3%	temp = copy.deepcopy(newBoard[action[1]][action[2]])
92	1042	2.4ms	.	5.9%	newBoard[action[1]][action[2]] = copy.deepcopy('*')
93	1042	2.3ms	.	5.7%	newBoard[location[0]][location[1]] = copy.deepcopy(temp)
94					# return new board after moving * - NIL to the new location
95	1042	0.2ms	.	0.5%	return newBoard

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Function: manhattan at line 204

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
204					@cpu
205					def manhattan(state):
206	626	0.2ms	.	1.3%	state = state.data
207	626	0.2ms	.	1.4%	goal_state = constants.goalBoard
208	626	0.1ms	.	1.0%	distance = 0
209					
210					# Create a dictionary that maps each value to its position in the goal state
211	626	0.1ms	.	1.0%	goal_dict = {}
212	2504	0.7ms	.	4.9%	for i in range(len(goal_state)):
213	7512	2.1ms	.	14.2%	for j in range(len(goal_state[0])):
214	5634	1.6ms	.	10.7%	if goal_state[i][j] != '*':
215	5008	1.5ms	.	10.6%	goal_dict[goal_state[i][j]] = (i, j)
216					
217					# Calculate Manhattan distance
218	2504	0.7ms	.	4.6%	for i in range(len(state)):
219	7512	2.0ms	.	13.9%	for j in range(len(state[0])):
220	5634	2.2ms	.	14.8%	if state[i][j] != '*' and state[i][j] != goal_state[i][j]:
221	3278	0.9ms	.	5.9%	value = state[i][j]
222	3278	0.8ms	.	5.7%	row, col = goal_dict[value]
223	3278	1.3ms	.	8.8%	distance += abs(row - i) + abs(col - j)
224					

Line #	Hits	Time	Per Hit	% Time	Line Contents
225	626	0.2ms	.	1.1%	return distance

Total time: 0.094s

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Function: a_star at line 234

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
234					@cpu
235					def a_star(initialProblem, f):
236	1	.	.	.	initialNode = Node(data = initialProblem) # node=NODE(STATE=problem.INITIAL)
237	1	.	.	.	frontier = PriorityQueue()
238	1	0.1ms	0.1ms	0.1%	frontier.append((f(initialNode), initialNode)) # frontier-a priority queue
239					
240	1	.	.	.	reached = {str(initialProblem): initialNode} # reached-a lookup table, w
241					
242	386	0.2ms	.	0.3%	while not frontier.empty(): # while not IS-EMPTY(fronti
243	386	0.3ms	.	0.3%	node = frontier.get() # node=POP(frontier)
244					
245	386	0.2ms	.	0.3%	if constants.goalBoard == node[1].data: # if problem.IS-GOAL(node.s
246	1	.	.	.	print('Max queue size:', frontier.getSize())
247	1	.	.	.	return node[1] # then return node
248					
249	1427	54.2ms	.	57.7%	for child in expand(node[1]): # for each child in EXPAND(problem
250					# s=child.STATE
251	1042	1.3ms	.	1.4%	s = Node(data = child[0], depth = node[1].depth + 1, move = child[1], pr
252					
253					# if s is not in reached or child.PATH-COST < reached[s].PATH-COST then
254	1042	2.1ms	.	2.2%	if str(s.data) not in reached or s.depth < reached[str(s.data)].depth:
255	625	0.8ms	.	0.9%	reached[str(s.data)] = s # reached[s]=child
256	625	34.7ms	0.1ms	37.0%	frontier.append((f(s), s)) # add child to frontier
257					
258					return constants.failure # return failure

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Function: printStatistics at line 260

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
260					@cpu
261					def printStatistics(solution):
262	1	.	.	0.6%	pathCost = 0
263	1	.	.	0.6%	stateSequence = []
264	1	.	.	.	actionSequence = []
265					
266	29	.	.	5.7%	while solution.prev != None:
267	28	.	.	7.6%	stateSequence.insert(0, solution.data)
268	28	.	.	7.0%	actionSequence.insert(0, solution.move)
269	28	.	.	5.1%	solution = solution.prev
270	28	.	.	5.7%	pathCost += 1
271					
272	1	.	.	1.9%	print('Action sequence:')
273	1	.	.	27.4%	print(*actionSequence, sep='\n')
274					
275	1	.	.	1.9%	print('\nState sequence:')
276	1	0.1ms	0.1ms	34.4%	print(*stateSequence, sep='\n')
277					
278	1	.	.	1.9%	print('\nPath cost:', pathCost)