

Total time: 8.433s

File: /Users/rishabhjain/Documents/Masters/SEM 2/Aritificial Intelligence/Program/Program 1/program_1.py

Function: expand at line 48

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
48					@cpu
49					def expand(board):
50	232876	99.9ms	.	1.2%	for i in range(len(board.data)):
51	582167	169.0ms	.	2.0%	for j in range(len(board.data[i])):
52	465729	143.8ms	.	1.7%	if board.data[i][j] == '*':
53	58219	16.2ms	.	0.2%	location = [i,j];
54	58219	12.7ms	.	0.2%	break
55					
56	58219	12.6ms	.	0.1%	actions = []
57	214012	937.0ms	.	11.1%	for move in possible_actions(constants.board, location):
58	155793	7.03s	.	83.3%	actions.append([result(location, move, board.data) , move])
59					
60	58219	13.5ms	.	0.2%	return actions

Total time: 0.440s

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Function: possible_actions at line 62

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
62					@cpu
63					def possible_actions(board, location):
64	58219	20.6ms	.	4.7%	actions = ["RIGHT", "LEFT", "UP", "DOWN"]
65	58219	14.8ms	.	3.4%	actionstopeform = []
66					
67	291095	74.4ms	.	16.9%	for x in actions:
68					# for moving right
69	232876	60.6ms	.	13.8%	if x == "RIGHT":
70	58219	21.4ms	.	4.9%	if location[1]+1 < len(board):
71	39012	29.6ms	.	6.7%	actionstopeform.append([x,location[0],location[1]+1])
72					# for moving left
73	174657	46.9ms	.	10.7%	elif x == "LEFT":
74	58219	19.1ms	.	4.3%	if location[1]-1 >= 0:
75	38989	23.4ms	.	5.3%	actionstopeform.append([x,location[0],location[1]-1])
76					# for moving up
77	116438	29.5ms	.	6.7%	elif x == "UP":
78	58219	18.9ms	.	4.3%	if location[0]-1 >= 0:
79	38894	16.0ms	.	3.6%	actionstopeform.append([x,location[0]-1,location[1]])
80					# for moving down
81	58219	14.4ms	.	3.3%	elif x == "DOWN":
82	58219	19.7ms	.	4.5%	if location[0]+1 < len(board):
83	38898	16.6ms	.	3.8%	actionstopeform.append([x,location[0]+1,location[1]])
84					
85	58219	13.9ms	.	3.2%	return actionstopeform

Total time: 6.632s

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Function: result at line 87

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
87					@cpu
88					def result(location,action,board):
89					# copy of a board so that we can modify it
90	155793	5.48s	.	82.6%	newBoard = copy.deepcopy(board)
91	155793	384.1ms	.	5.8%	temp = copy.deepcopy(newBoard[action[1]][action[2]])
92	155793	371.9ms	.	5.6%	newBoard[action[1]][action[2]] = copy.deepcopy('*')
93	155793	362.5ms	.	5.5%	newBoard[location[0]][location[1]] = copy.deepcopy(temp)
94					# return new board after moving * - NIL to the new location
95	155793	33.2ms	.	0.5%	return newBoard

Total time: 190.421s

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Function: bfs at line 139

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
139					@cpu
140					def bfs(board):
141	1	.	.	.	frontier = queue.Queue()
142	1	.	.	.	node = Node(data = board)
143	1	.	.	.	frontier.put(node)
144	1	.	.	.	maxQueueSize = 1
145	1	.	.	.	if constants.goalBoard == node.data:
146					print('mill gya:', maxQueueSize)
147					return node
148					
149	1	.	.	.	reached = []
150	1	.	.	.	reached.append(board)
151					
152	58219	194.7ms	.	0.1%	while not frontier.empty():
153	58219	374.5ms	.	0.2%	val = frontier.get()
154	214010	9.12s	.	4.8%	for child in expand(val):
155	155792	414.2ms	.	0.2%	s = Node(data=child[0], depth = val.depth + 1, move= child[1] , prev=val)
156					
157	155792	97.2ms	.	0.1%	if goalBoard == s.data:
158	1	0.1ms	0.1ms	.	print('Max queue size:', maxQueueSize)
159	1	.	.	.	return s
160	155791	179.20s	1.2ms	94.1%	if s.data not in reached:

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161      76968      122.1ms      .      0.1%      reached.append(s.data)
162      76968      872.1ms      .      0.5%      frontier.put(s)
163      76968      32.1ms      .      .      maxQueueSize+=1
164
165      print('Max queue size:', maxQueueSize)
166
167      return failure

```

Total time: 0.001s

File: /Users/rishabhjain/Documents/Masters/SEM 2/Aritificial Intelligence/Program/Program 1/program_1.py

Function: printStatistics at line 258

Line #	Hits	Time	Per Hit	% Time	Line Contents
258					@cpu
259					def printStatistics(solution):
260	1	.	.	0.7%	pathCost = 0
261	1	.	.	0.2%	stateSequence = []
262	1	.	.	.	actionSequence = []
263					
264	23	.	.	3.1%	while solution.prev != None:
265	22	.	.	2.2%	stateSequence.insert(0, solution.data)
266	22	.	.	2.0%	actionSequence.insert(0, solution.move)
267	22	.	.	1.1%	solution = solution.prev
268	22	.	.	1.3%	pathCost += 1
269					
270	1	.	.	8.6%	print('Action sequence:')
271	1	0.1ms	0.1ms	18.0%	print(*actionSequence, sep='\n')
272					
273	1	.	.	0.5%	print('\nState sequence:')
274	1	0.3ms	0.3ms	53.2%	print(*stateSequence, sep='\n')
275					
276	1	0.1ms	0.1ms	9.2%	print('\nPath cost:', pathCost)