

Total time: 0.004s

File: /Users/rishabhjain/Documents/Masters/SEM 2/Aritificial Intelligence/Program/assignment\_1/a\_star.py

Function: expand at line 51

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
51					@cpu
52					def expand(board):
53	136	.	.	1.2%	for i in range(len(board.data)):
54	338	0.1ms	.	2.2%	for j in range(len(board.data[i])):
55	270	0.1ms	.	1.9%	if board.data[i][j] == '*':
56	34	.	.	0.2%	location = [i,j];
57	34	.	.	0.1%	break
58					
59	34	.	.	0.1%	actions = []
60	119	0.5ms	.	11.2%	for move in possible_actions(constants.board, location):
61	85	3.5ms	.	83.0%	actions.append([result(location, move, board.data) , move])
62					# prepare all poss
63	34	.	.	0.1%	return actions
					# After expanding

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Function: possible\_actions at line 67

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
67					@cpu
68					def possible_actions(board, location):
69	34	.	.	5.1%	actions = ["RIGHT", "LEFT", "UP", "DOWN"]
70	34	.	.	1.4%	actionstopeform = []
71					
72	170	.	.	15.7%	for x in actions:
73					# for moving right
74	136	.	.	17.6%	if x == "RIGHT":
75	34	.	.	5.1%	if location[1]+1 < len(board):
76	22	.	.	4.6%	actionstopeform.append([x,location[0],location[1]+1])
77					# for moving left
78	102	.	.	8.8%	elif x == "LEFT":
79	34	.	.	4.6%	if location[1]-1 >= 0:
80	20	.	.	3.2%	actionstopeform.append([x,location[0],location[1]-1])
81					# for moving up
82	68	.	.	8.8%	elif x == "UP":
83	34	.	.	3.2%	if location[0]-1 >= 0:
84	22	.	.	5.1%	actionstopeform.append([x,location[0]-1,location[1]])
85					# for moving down
86	34	.	.	1.9%	elif x == "DOWN":
87	34	.	.	7.9%	if location[0]+1 < len(board):
88	21	.	.	3.2%	actionstopeform.append([x,location[0]+1,location[1]])
89					
90	34	.	.	3.7%	return actionstopeform

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Function: result at line 94

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
94					@cpu
95					def result(location,action,board):
96	85	2.7ms	.	81.5%	newBoard = copy.deepcopy(board)
97	85	0.2ms	.	6.3%	temp = copy.deepcopy(newBoard[action[1]][action[2]])
98	85	0.2ms	.	5.8%	newBoard[action[1]][action[2]] = copy.deepcopy('*')
99	85	0.2ms	.	5.8%	newBoard[location[0]][location[1]] = copy.deepcopy(temp)
100	85	.	.	0.6%	return newBoard
					# return new board aft

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Function: misplaced at line 104

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
104					@cpu
105					def misplaced(puzzle):
106					num_misplaced = 0
107					for i in range(len(puzzle.data)):
108					for j in range(len(puzzle.data)):
109					if puzzle.data[i][j] != constants.goalBoard[i][j] and puzzle.data[i][j] !=
110					num_misplaced += 1
111					return num_misplaced

Total time: 0.001s

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Function: manhattan at line 114

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
114					@cpu
115					def manhattan(state):
116	53	.	.	1.1%	state = state.data
117	53	.	.	0.9%	goal_state = constants.goalBoard
118	53	.	.	1.2%	distance = 0
119					
120					# Create a dictionary that maps each value to its position in the goal state
121	53	.	.	0.7%	goal_dict = {}

Line #	Hits	Time	Per Hit	% Time	Line Contents
122	212	0.1ms	.	5.4%	for i in range(len(goal_state)):
123	636	0.2ms	.	13.2%	for j in range(len(goal_state[0])):
124	477	0.1ms	.	10.1%	if goal_state[i][j] != '*':
125	424	0.1ms	.	10.4%	goal_dict[goal_state[i][j]] = (i, j)
126					
127					# Calculate Manhattan distance
128	212	0.1ms	.	4.3%	for i in range(len(state)):
129	636	0.2ms	.	11.2%	for j in range(len(state[0])):
130	477	0.2ms	.	15.4%	if state[i][j] != '*' and state[i][j] != goal_state[i][j]:
131	348	0.1ms	.	7.1%	value = state[i][j]
132	348	0.1ms	.	7.3%	row, col = goal_dict[value]
133	348	0.2ms	.	10.9%	distance += abs(row - i) + abs(col - j)
134					
135	53	.	.	0.7%	return distance

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Function: linear\_conflict at line 137

Line #	Hits	Time	Per Hit	% Time	Line Contents
137					@cpu
138					def linear_conflict(board, goal):
139					n = len(board)
140					linear_conflicts = 0
141					
142					# Find the linear conflicts in rows
143					for i in range(n):
144					row = board[i]
145					goal_row = goal[i]
146					for j in range(n):
147					if row[j] != '*' and row[j] in goal_row:
148					for k in range(j+1, n):
149					if row[k] != '*' and row[k] in goal_row and goal_row.index(row[j])
150					linear_conflicts += 2
151					
152					# Find the linear conflicts in columns
153					for j in range(n):
154					column = [board[i][j] for i in range(n)]
155					goal_column = [goal[i][j] for i in range(n)]
156					for i in range(n):
157					if column[i] != '*' and column[i] in goal_column:
158					for k in range(i+1, n):
159					if column[k] != '*' and column[k] in goal_column and goal_column.i
160					linear_conflicts += 2
161					
162					return linear_conflicts

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Function: f at line 165

Line #	Hits	Time	Per Hit	% Time	Line Contents
165					@cpu
166					# Heuristic Function to calculate hueristic value f(x) = h(x) + g(x)
167					def f(board):
168					manhattan_distance = manhattan(board)
169					manhattan_distance += linear_conflict(board.data, constants.goalBoard) # Add 1
170					return manhattan_distance + board.depth

Total time: 0.000s

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Function: zero\_function at line 174

Line #	Hits	Time	Per Hit	% Time	Line Contents
174					@cpu
175					def zero_function(board):
176					return 0

Total time: 0.008s

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Function: a\_star at line 179

Line #	Hits	Time	Per Hit	% Time	Line Contents
179					@memory_profiler.profile
180					@cpu
181					def a_star(initialProblem, f):
182	1	.	.	.	initialNode = Node(data = initialProblem) # node=NODE(STATE=problem.
183	1	.	.	.	frontier = PriorityQueue() # frontier←a priority queu
184	1	0.1ms	0.1ms	0.8%	frontier.append((f(initialNode), initialNode))
185					
186	1	.	.	0.1%	reached = {str(initialProblem): initialNode} # reached←a lookup table,
187					
188	35	.	.	0.3%	while not frontier.empty(): # while not IS-EMPTY(front
189	35	.	.	0.3%	node = frontier.get() # node=POP(frontier)
190					
191	35	.	.	0.2%	if constants.goalBoard == node[1].data: # if problem.IS=GOAL(node.
192					#print('Max queue size:', frontier.getSize()) # only for debug
193	1	.	.	.	return node[1] # then return node
194					
195	119	4.4ms	.	58.8%	for child in expand(node[1]): # for each child in EXPAN

```

196                                     # s←child.STATE
197      85      0.1ms      .      1.3%      s = Node( data = child[0], depth = node[1].depth + 1, move = child[1], pr
198
199                                     # if s is not in reached or child.PATH-COST < reached[s].PATH-COST then
200      85      0.1ms      .      2.0%      if str(s.data) not in reached or s.depth < reached[str(s.data)].depth:
201      52      0.1ms      .      0.9%      if str(s.data) not in reached or s.depth < reached[str(s.data)].depth:
202      52      2.7ms      0.1ms      35.3%      reached[str(s.data)] = s      # reached[s]←child
203                                     frontier.append((f(s) ,s))      # add child to frontier
204                                     return constants.failure      # return failure

```

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Function: printStatistics at line 207

Line #	Hits	Time	Per Hit	% Time	Line Contents
207					@cpu
208					def printStatistics(solution):
209	1	.	.	0.3%	pathCost = 0
210	1	.	.	0.3%	stateSequence = []
211	1	.	.	.	actionSequence = []
212					
213	29	.	.	2.8%	while solution.prev != None:
214	28	.	.	2.8%	stateSequence.insert(0, solution.data)
215	28	.	.	3.4%	actionSequence.insert(0, solution.move)
216	28	.	.	1.9%	solution = solution.prev
217	28	.	.	3.1%	pathCost += 1
218					
219	1	.	.	1.2%	print('Action sequence:')
220	1	.	.	12.0%	print(*actionSequence, sep='\n')
221					
222	1	.	.	0.6%	print('\nState sequence:')
223	1	0.2ms	0.2ms	70.1%	print(*stateSequence, sep='\n')
224					
225	1	.	.	1.5%	print('\nPath cost:', pathCost)