

Total time: 0.001s

File: /Users/rishabhjain/Documents/Masters/SEM 2/Aritificial Intelligence/Program/assignment\_1/a\_star.py

Function: expand at line 51

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
51					@cpu
52					def expand(board):
53	28	.	.	0.8%	for i in range(len(board.data)):
54	66	.	.	1.6%	for j in range(len(board.data[i])):
55	52	.	.	1.6%	if board.data[i][j] == '*':
56	7	.	.	0.2%	location = [i,j];
57	7	.	.	0.2%	break
58					
59	7	.	.	0.2%	actions = []
60	28	0.1ms	.	10.3%	for move in possible_actions(constants.board, location):
61	21	0.9ms	.	85.1%	actions.append([result(location, move, board.data) , move])
62					# prepare all poss
63	7	.	.	0.1%	return actions
					# After expanding

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Function: possible\_actions at line 67

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
67					@cpu
68					def possible_actions(board, location):
69	7	.	.	4.3%	actions = ["RIGHT", "LEFT", "UP", "DOWN"]
70	7	.	.	2.1%	actionstopeform = []
71					
72	35	.	.	23.4%	for x in actions:
73					# for moving right
74	28	.	.	10.6%	if x == "RIGHT":
75	7	.	.	6.4%	if location[1]+1 < len(board):
76	7	.	.	4.3%	actionstopeform.append([x,location[0],location[1]+1])
77					# for moving left
78	21	.	.	14.9%	elif x == "LEFT":
79	7	.	.	6.4%	if location[1]-1 >= 0:
80	3	.	.	2.1%	actionstopeform.append([x,location[0],location[1]-1])
81					# for moving up
82	14	.	.	4.3%	elif x == "UP":
83	7	.	.	2.1%	if location[0]-1 >= 0:
84	6	.	.	2.1%	actionstopeform.append([x,location[0]-1,location[1]])
85					# for moving down
86	7	.	.	8.5%	elif x == "DOWN":
87	7	.	.	2.1%	if location[0]+1 < len(board):
88	5	.	.	6.4%	actionstopeform.append([x,location[0]+1,location[1]])
89					
90	7	.	.	.	return actionstopeform

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Function: result at line 94

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
94					@cpu
95					def result(location,action,board):
96	21	0.7ms	.	81.7%	newBoard = copy.deepcopy(board)
97	21	.	.	5.7%	temp = copy.deepcopy(newBoard[action[1]][action[2]])
98	21	0.1ms	.	6.3%	newBoard[action[1]][action[2]] = copy.deepcopy('*')
99	21	.	.	5.4%	newBoard[location[0]][location[1]] = copy.deepcopy(temp)
100	21	.	.	0.9%	return newBoard
					# return new board aft

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Function: misplaced at line 104

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
104					@cpu
105					def misplaced(puzzle):
106					num_misplaced = 0
107					for i in range(len(puzzle.data)):
108					for j in range(len(puzzle.data)):
109					if puzzle.data[i][j] != constants.goalBoard[i][j] and puzzle.data[i][j] !=
110					num_misplaced += 1
111					return num_misplaced

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Function: manhattan at line 114

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
114					@cpu
115					def manhattan(state):
116	16	.	.	2.1%	state = state.data
117	16	.	.	1.3%	goal_state = constants.goalBoard
118	16	.	.	1.3%	distance = 0
119					
120					# Create a dictionary that maps each value to its position in the goal state
121	16	.	.	0.3%	goal_dict = {}

Line #	Hits	Time	Per Hit	% Time	Line Contents
122	64	.	.	6.5%	for i in range(len(goal_state)):
123	192	0.1ms	.	16.7%	for j in range(len(goal_state[0])):
124	144	.	.	12.8%	if goal_state[i][j] != '*':
125	128	.	.	11.5%	goal_dict[goal_state[i][j]] = (i, j)
126					
127					# Calculate Manhattan distance
128	64	.	.	5.0%	for i in range(len(state)):
129	192	0.1ms	.	14.9%	for j in range(len(state[0])):
130	144	0.1ms	.	14.9%	if state[i][j] != '*' and state[i][j] != goal_state[i][j]:
131	51	.	.	3.4%	value = state[i][j]
132	51	.	.	3.1%	row, col = goal_dict[value]
133	51	.	.	5.5%	distance += abs(row - i) + abs(col - j)
134					
135	16	.	.	0.8%	return distance

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Function: linear\_conflict at line 137

Line #	Hits	Time	Per Hit	% Time	Line Contents
137					@cpu
138					def linear_conflict(board, goal):
139					n = len(board)
140					linear_conflicts = 0
141					
142					# Find the linear conflicts in rows
143					for i in range(n):
144					row = board[i]
145					goal_row = goal[i]
146					for j in range(n):
147					if row[j] != '*' and row[j] in goal_row:
148					for k in range(j+1, n):
149					if row[k] != '*' and row[k] in goal_row and goal_row.index(row[j])
150					linear_conflicts += 2
151					
152					# Find the linear conflicts in columns
153					for j in range(n):
154					column = [board[i][j] for i in range(n)]
155					goal_column = [goal[i][j] for i in range(n)]
156					for i in range(n):
157					if column[i] != '*' and column[i] in goal_column:
158					for k in range(i+1, n):
159					if column[k] != '*' and column[k] in goal_column and goal_column.i
160					linear_conflicts += 2
161					
162					return linear_conflicts

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Function: f at line 165

Line #	Hits	Time	Per Hit	% Time	Line Contents
165					@cpu
166					# Heuristic Function to calculate hueristic value f(x) = h(x) + g(x)
167					def f(board):
168	16	0.6ms	.	99.7%	manhattan_distance = manhattan(board)
169					# manhattan_distance += linear_conflict(board.data, constants.goalBoard) # Add
170	16	.	.	0.3%	return manhattan_distance + board.depth

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Function: zero\_function at line 174

Line #	Hits	Time	Per Hit	% Time	Line Contents
174					@cpu
175					def zero_function(board):
176					return 0

Total time: 0.002s

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Function: a\_star at line 179

Line #	Hits	Time	Per Hit	% Time	Line Contents
179					@memory_profiler.profile
180					@cpu
181					def a_star(initialProblem, f):
182	1	.	.	0.2%	initialNode = Node(data = initialProblem)
183	1	.	.	0.1%	frontier = PriorityQueue()
184	1	.	.	2.7%	frontier.append((f(initialNode), initialNode))
185					
186	1	.	.	0.2%	reached = {str(initialProblem): initialNode}
187					
188	8	.	.	0.4%	while not frontier.empty():
189	8	.	.	0.3%	node = frontier.get()
190					
191	8	.	.	0.2%	if constants.goalBoard == node[1].data:
192					#print('Max queue size:', frontier.getSize())
193	1	.	.	.	return node[1]
194					
195	28	1.1ms	.	57.7%	for child in expand(node[1]):

196					# s←child.STATE
197	21	.	.	1.5%	s = Node( data = child[0], depth = node[1].depth + 1, move = child[1], pr
198					
199					# if s is not in reached or child.PATH-COST < reached[s].PATH-COST then
200	21	.	.	1.9%	if str(s.data) not in reached or s.depth < reached[str(s.data)].depth:
201	15	.	.	1.1%	reached[str(s.data)] = s # reached[s]←child
202	15	0.6ms	.	33.8%	frontier.append((f(s) ,s)) # add child to frontier
203					
204					return constants.failure # return failure

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Function: printStatistics at line 207

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
207					@cpu
208					def printStatistics(solution):
209	1	.	.	.	pathCost = 0
210	1	.	.	.	stateSequence = []
211	1	.	.	2.4%	actionSequence = []
212					
213	7	.	.	4.9%	while solution.prev != None:
214	6	.	.	4.9%	stateSequence.insert(0, solution.data)
215	6	.	.	2.4%	actionSequence.insert(0, solution.move)
216	6	.	.	2.4%	solution = solution.prev
217	6	.	.	7.3%	pathCost += 1
218					
219	1	.	.	7.3%	print('Action sequence:')
220	1	.	.	26.8%	print(*actionSequence, sep='\n')
221					
222	1	.	.	4.9%	print('\nState sequence:')
223	1	.	.	29.3%	print(*stateSequence, sep='\n')
224					
225	1	.	.	7.3%	print('\nPath cost:', pathCost)