Patrick Grady

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Education

Georgia Institute of Technology <div align="right">**Atlanta, GA**</div>
PhD Robotics <div align="right">*2018-Dec 2023 est.*</div>

Georgia Institute of Technology <div align="right">**Atlanta, GA**</div>
MS Computer Science - Machine Learning <div align="right">*2018-2020*</div>

Duke University <div align="right">**Durham, NC**</div>
BS Computer Science, BS Electrical and Computer Engineering <div align="right">*2014-2018*</div>

Publications

○ *Visual Contact Pressure Estimation for Grippers in the Wild* - Jeremy A. Collins, Cody Houff, **Patrick Grady**, Charles C. Kemp, *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2023*

○ *Visual Estimation of Fingertip Pressure on Diverse Surfaces using Easily Captured Data* - **Patrick Grady**, Jeremy A. Collins, Chengcheng Tang, Christopher D. Twigg, James Hays, Charles C. Kemp, *arXiv 2023*

○ *Force/Torque Sensing for Soft Grippers using an External Camera* - Jeremy A. Collins, **Patrick Grady**, Charles C. Kemp, *IEEE International Conference on Robotics and Automation (ICRA) 2023*

○ *BodyPressure - Inferring Body Pose and Contact Pressure from a Depth Image* - Henry M. Clever, **Patrick Grady**, Greg Turk, Charles C. Kemp, *IEEE Transactions on Pattern Analysis and Machine Intelligence (T-PAMI) 2023*

○ *Visual Pressure Estimation and Control for Soft Robotic Grippers* - **Patrick Grady**, Jeremy A. Collins, Samarth Brahmbhatt, Christopher D. Twigg, Chengcheng Tang, James Hays, Charles C. Kemp, *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2022*

○ *PressureVision: Estimating Hand Pressure from a Single RGB Image* - **Patrick Grady**, Chengcheng Tang, Samarth Brahmbhatt, Christopher D. Twigg, Chengde Wan, James Hays, Charles C. Kemp, *European Conference on Computer Vision (ECCV) 2022*, **Oral**

○ *ContactOpt: Optimizing Contact to Improve Grasps* - **Patrick Grady**, Chengcheng Tang, Christopher D. Twigg, Minh Vo, Samarth Brahmbhatt, Charles C. Kemp, *Conference on Computer Vision and Pattern Recognition (CVPR) 2021*, **Oral**

○ *Masked Reconstruction based Self-Supervision for Human Activity Recognition* - Harish Haresamudram, Apoorva Beedu, Varun Agrawal, **Patrick Grady**, Irfan Essa, Judy Hoffman, Thomas Ploetz, *Ubiquitous Computing/International Semantic Web Conference (UbiComp/ISWC) 2020*

○ *Learning to Collaborate from Simulation for Robot-Assisted Dressing* - Alexander Clegg, Zackory Erickson, **Patrick Grady**, Greg Turk, Charles Kemp, C. Karen Liu, *IEEE Robotics and Automation Letters (RA-L) 2020*

○ *A Study of Energy Losses in the World's Most Fuel Efficient Vehicle* - **Patrick Grady**, Gerry Chen, Shomik Verma, Aniruddh Marellapudi, Nico Hotz, *IEEE Vehicle Power and Propulsion Conference (VPPC) 2019*, **Oral**

Technical Experience

Meta Reality Labs
Research Intern with Chengcheng Tang <div align="right">*Summer 2020, Summer 2021, Summer 2022*</div>

○ Developed methods for estimating hand pressure from single RGB images. Designed multi-view camera cages, collected a dataset of diverse participants manipulating force-sensitive objects, developed deep models

○ Developed methods for inferring hand-object contact for grasps and optimization methods to enforce physical

consistency and achieve high-quality poses

Healthcare Robotics Lab
Graduate Research Assistant with Dr. Charlie Kemp *2019 - cur*

- Developed closed-loop robotic grasping and manipulation algorithms using visually inferred tactile information
- Collected data and developed methods for visual inference of contact and pressure for human hands
- Generated high-quality 3D human mesh model fits from depth imagery
- Transferred deep RL policies from sim-to-real for robot-assisted dressing

Duke Electric Vehicles
President (2016-2018), Electrical Lead (2014-2016) *2014 - 2018*

- **Guinness World Record**: Most efficient electric vehicle: 27,482 MPGe (battery-electric). Previous record, 2016 TU Munich
- **Guinness World Record**: Most fuel-efficient vehicle: 14,573 MPG (hydrogen fuel cell). Previous record, 2005 ETH Zurich
- Led team of 15 undergraduates to design battery and fuel cell powered vehicles for the Shell Eco-Marathon
- Led two year initiative to push the team past Eco-Marathon competition, to seek and achieve two World Records
- Vehicle designer, high level architect of vehicle powertrain and aerodynamics. Justified with extensive simulation and real-world testing

NVIDIA Circuits Research Group
Research Intern *Summer 2017*

- Benchmarked high-speed signalling test chips for for next-gen memory-to-GPU communications
- Developed automatic optimization to minimize bit error-rate of 25 Gbps ground-referenced link
- Designed setup for characterization of SRAM devices in high-radiation environments

Teaching Experience

Invited Talks
- *Sensing Touch from Vision for Humans and Robots.* Amazon Lab126 *August 2023*
- *Sensing Touch from Vision for Humans and Robots.* Carnegie Mellon University *May 2023*
- *14,500 MPG: Design of the World's Most Fuel Efficient Vehicle.* Duke University *Feb 2019*

Visiting Lecturer
Politeknik Brunei, Brunei *Mar 2019*

- Invited to host tutorial on design and integration of BLDC motor drives

Graduate Teaching Assistant
- CS 6601 - Artificial Intelligence *Fall 2020*
- CS 7463 - Deep Learning *Spring 2020*
- CS 6476 - Computer Vision *Fall 2019*
- ECE 3072 - Electrical Energy *Fall 2018*

Undergraduate Teaching Assistant
- ECE 110 - Fundamentals of Electrical and Computer Engineering *Spring 2016*
- ECE 230 - Microelectronic Devices and Circuits, Projects Lab *Fall 2016*

Selected Projects

Inertial Variometers for Glider Aircraft
Mid-Georgia Soaring Association *2020*

- Developed RTK-INS for high-precision sensing of aircraft orientation and velocity
- Integrated INS into a high-performance glider, collected 30 hours of flight data
- Designed sensor fusion filters to exceed performance of current-gen barometric variometers

Online Imitation Learning for Warm-Starting of DQN
CS 8803 Class Project [Link] *2019*

- Developed RL agent to play OpenAI Gym car racing environment
- Leveraged experience of an oracle agent to accelerate training of Deep Q Network
- Achieved human-level performance with 6x fewer training episodes

EasyController2 BLDC Motor Drive
Duke Electric Vehicles *2019*

- Released open source design of BLDC motor controller, PCB and code
- Supported 7 international teams using the EasyController2 as a reference design

Awards

Reviewer: CVPR, ECCV, ICCV, ICRA, IROS, TPAMI	
Finalist: Meta PhD Research Fellowship	*2022*
Guinness World Record: Most efficient electric vehicle, 27,482 MPG	*2019*
Guinness World Record: Most fuel efficient vehicle, 14,573 MPG	*2018*
Shell Eco-Marathon: First place battery-electric prototype. Best of 25 teams	*2018*
Shell Eco-Marathon: First place hydrogen prototype. Best of 7 teams	*2018*
Shell Eco-Marathon: First place battery-electric prototype. Best of 30 teams	*2017*
Georgia Tech CreateX: Idea2Prototype grant	*2019*
HackMIT: Winner	*2016*
HackDuke: Winner	*2015*
Microsoft Code Competition: Winner. Best of 30 teams	*2015, 2017*
ACM IC Programming Contest: 5th of 180 teams in Mid-Atlantic conference	*2015*
FAA Private Pilot: Glider, Airplane	*2014, 2021*
Soaring Records: Holder of 11 Georgia state soaring records	
Media Coverage: [Clean Technica] [News and Observer] [Killer Innovations] [Duke Chronicle]	