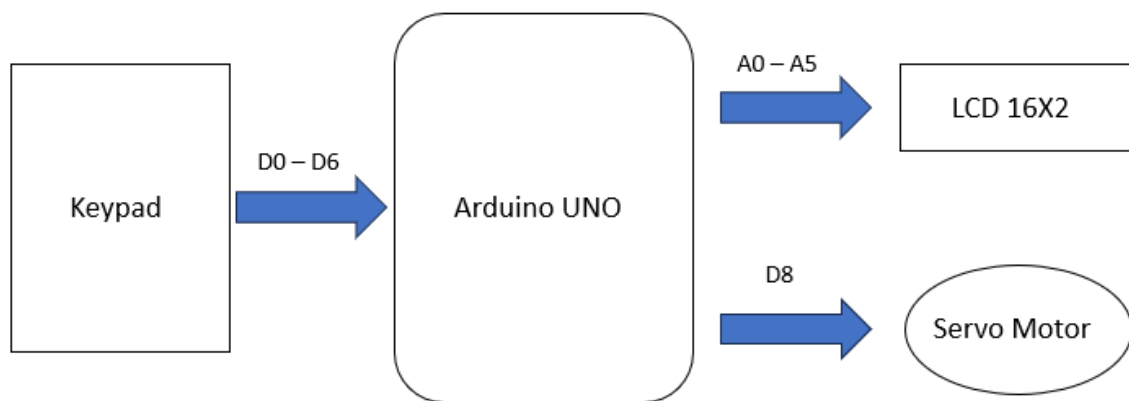


# Door Locking System Using Arduino UNO

## Description:

In this project, we will be representing the passcode-based door locking system using Arduino UNO, Keypad, LCD 16X2, Servo motor. It uses a keypad module to enter the passcode, an LCD to display the status and a servo motor to indicate the locking and unlocking the door. For the correct passcode the door is unlocked, and the LCD displays as “Access granted” and to indicate that the servo motor rotates and after few seconds the starts to re-locking. If the passcode is wrong, the motor does not rotate and the LCD displays as “Access denied”.

## Block Diagram:



## Input and Output:

| Sl.No | Description         | Name | Type | Data Direction | Specification | Remarks     |
|-------|---------------------|------|------|----------------|---------------|-------------|
| 1     | 4X4 KEYPAD(COLUMNS) | 1    | INP  | DI             | Digital       | Active High |
| 2     | 4X4 KEYPAD(COLUMNS) | 2    | INP  | DI             | Digital       | Active High |
| 3     | 4X4 KEYPAD(COLUMNS) | 3    | INP  | DI             | Digital       | Active High |
| 4     | 4X4 KEYPAD(ROW)     | A    | INP  | DI             | Digital       | Active High |
| 5     | 4X4 KEYPAD(ROW)     | B    | INP  | DI             | Digital       | Active High |
| 6     | 4X4 KEYPAD(ROW)     | C    | INP  | DI             | Digital       | Active High |
| 7     | 4X4 KEYPAD(ROW)     | D    | INP  | DI             | Digital       | Active High |
| 8     | SERVO VCC           | VCC  | OUT  | DO             | Digital       | Active High |

|    |              |     |     |    |         |             |
|----|--------------|-----|-----|----|---------|-------------|
| 9  | SERVO GND    | GND | OUT | DO | Digital | Active High |
| 10 | SERVO IN     | 8   | OUT | DO | Digital | Active High |
| 11 | LCD RST      | RS  | OUT | DO | Digital | Active High |
| 12 | LCD EN       | EN  | OUT | DO | Digital | Active High |
| 13 | LCD DATA PIN | D4  | OUT | DO | Digital | Active High |
| 14 | LCD DATA PIN | D5  | OUT | DO | Digital | Active High |
| 15 | LCD DATA PIN | D6  | OUT | DO | Digital | Active High |
| 16 | LCD DATA PIN | D7  | OUT | DO | Digital | Active High |

## Source Code:

```
#include <LiquidCrystal.h>
#include <Servo.h>
#include <Keypad.h>
Servo myservo;
int pos=0; // position of servo motor
LiquidCrystal lcd(A4, A5, A3, A2, A1, A0);
const byte rows=4;
const byte cols=3;

char key[rows][cols]={
  {'1','2','3'},
  {'4','5','6'},
  {'7','8','9'},
  {'*','0','#'}
};
byte rowPins[rows]={0,1,2,3};
byte colPins[cols]={4,5,6};
Keypad keypad= Keypad(makeKeymap(key),rowPins,colPins,rows,cols);
char* password="00000";
int currentposition=0;

void setup()
{

  displayscreen();
  //Serial.begin(9600);
  myservo.attach(8); //Servo motor connection
  lcd.begin(16,2);

}
```

```

void loop()
{
  if( currentposition==0)
  {
    displayscreen();

  }
  int l ;
  char code=keypad.getKey();
  if(code!=NO_KEY)
  {
    lcd.clear();
    lcd.setCursor(0,0);
    lcd.print("PASSWORD:");
    lcd.setCursor(7,1);
    lcd.print(" ");
    lcd.setCursor(7,1);
    for(l=0;l<=currentposition;++l)
    {

      lcd.print("*");
      //keypress();
    }

    if (code==password[currentposition])
    {
      ++currentposition;
      if(currentposition==4)
      {

        unlockdoor();
        currentposition=0;

      }

    }

    else

```

```
{  
incorrect();  
currentposition=0;
```

```
}  
}  
}
```

```
void unlockdoor()  
{  
delay(900);
```

```
lcd.setCursor(0,0);  
lcd.println(" ");  
lcd.setCursor(1,0);  
lcd.print("JAISANJU");  
lcd.setCursor(4,1);  
lcd.println("WELCOME!!");  
lcd.setCursor(15,1);  
lcd.println(" ");  
lcd.setCursor(16,1);  
lcd.println(" ");  
lcd.setCursor(14,1);  
lcd.println(" ");  
lcd.setCursor(13,1);  
lcd.println(" ");
```

```
for(pos = 180; pos>=0; pos-=5)  
{  
myservo.write(pos);  
delay(5);  
}
```

```
delay(1000);  
counterbeep();
```

```
delay(1000);
```

```
for(pos = 0; pos <= 180; pos +=5)  
{
```

```
myservo.write(pos);  
delay(15);  
}
```

```
currentposition=0;
```

```
lcd.clear();  
displayscreen();  
}
```

```
void incorrect()  
{  
  delay(500);  
  lcd.clear();  
  lcd.setCursor(1,0);  
  lcd.print("CODE");  
  lcd.setCursor(6,0);  
  lcd.print("INCORRECT");  
  lcd.setCursor(15,1);  
  lcd.println(" ");  
  lcd.setCursor(4,1);  
  lcd.println("TRY AGAIN !!!");
```

```
  lcd.setCursor(13,1);  
  lcd.println(" ");  
  Serial.println("CODE INCORRECT YOU ARE UNAUTHORIZED");  
  delay(1000);  
  delay(3000);  
  lcd.clear();  
  displayscreen();  
}
```

```
void clearscreen()  
{  
  lcd.setCursor(0,0);  
  lcd.println(" ");  
  lcd.setCursor(0,1);  
  lcd.println(" ");  
  lcd.setCursor(0,2);  
  lcd.println(" ");
```

```
lcd.setCursor(0,3);  
lcd.println(" ");  
}
```

```
void displayscreen()  
{
```

```
lcd.setCursor(0,0);  
lcd.println("ENTER THE CODE");  
lcd.setCursor(1 ,1);
```

```
lcd.println("TO OPEN DOOR!!");  
}
```

```
void counterbeep()  
{  
delay(1200);
```

```
lcd.clear();
```

```
lcd.setCursor(2,15);  
lcd.println(" ");  
lcd.setCursor(2,14);  
lcd.println(" ");  
lcd.setCursor(2,0);  
delay(200);  
lcd.println("GET IN WITHIN:::");
```

```
lcd.setCursor(4,1);  
lcd.print("5");  
delay(200);  
lcd.clear();  
lcd.setCursor(2,0);  
lcd.println("GET IN WITHIN:");  
delay(1000);  
lcd.setCursor(2,0);  
lcd.println("GET IN WITHIN:");
```

```
lcd.setCursor(4,1); //2
lcd.print("4");
delay(100);
lcd.clear();
lcd.setCursor(2,0);
lcd.println("GET IN WITHIN:");
delay(1000);
```

```
lcd.setCursor(2,0);
lcd.println("GET IN WITHIN:");
lcd.setCursor(4,1);
lcd.print("3");
delay(100);
lcd.clear();
lcd.setCursor(2,0);
lcd.println("GET IN WITHIN:");
delay(1000);
```

```
lcd.setCursor(2,0);
lcd.println("GET IN WITHIN:");
lcd.setCursor(4,1);
lcd.print("2");
delay(100);
lcd.clear();
lcd.setCursor(2,0);
lcd.println("GET IN WITHIN:");
delay(1000);
```

```
lcd.setCursor(4,1);
lcd.print("1");
delay(100);
lcd.clear();
lcd.setCursor(2,0);
lcd.println("GET IN WITHIN::");
```

```
delay(1000);
delay(40);
lcd.clear();
lcd.setCursor(2,0);
lcd.print("RE-LOCKING");
```

```

delay(500);
lcd.setCursor(12,0);
lcd.print(".");
delay(500);
lcd.setCursor(13,0);
lcd.print(".");
delay(500);
lcd.setCursor(14,0);
lcd.print(".");
delay(400);
lcd.clear();
lcd.setCursor(4,0);
lcd.print("LOCKED!");
delay(440);

}

```

## Schematic:

