# Hashing

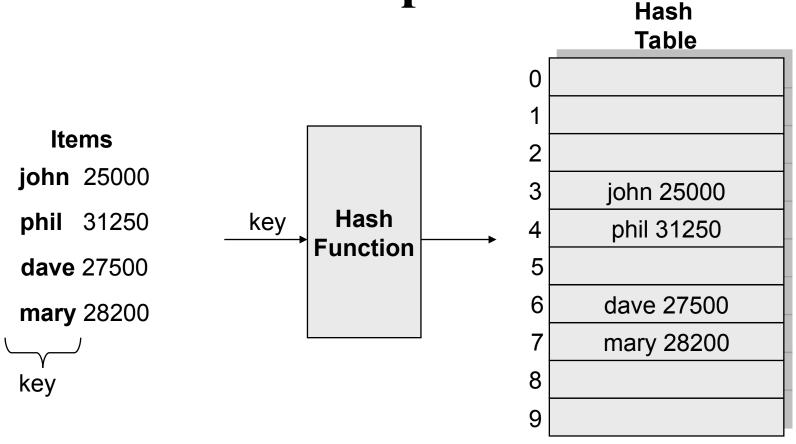
### **Hash Tables**

- We'll discuss the *hash table* ADT which supports only a subset of the operations allowed by binary search trees.
- The implementation of hash tables is called **hashing**.
- Hashing is a technique used for performing insertions, deletions and finds in constant average time (i.e. O(1))
- This data structure, however, is not efficient in operations that require any ordering information among the elements, such as findMin, findMax and printing the entire table in sorted order.

### General Idea

- The ideal hash table structure is merely an array of some fixed size, containing the items.
- A stored item needs to have a data member, called *key*, that will be used in computing the index value for the item.
  - Key could be an *integer*, a *string*, etc
  - e.g. a name or Id that is a part of a large employee structure
- The size of the array is *TableSize*.
- The items that are stored in the hash table are indexed by values from 0 to TableSize 1.
- Each key is mapped into some number in the range 0 to *TableSize* 1.
- The mapping is called a *hash function*.

### Example



- The hash function:
  - must be simple to compute.
  - must distribute the keys evenly among the cells.
- If we know which keys will occur in advance we can write *perfect* hash functions, but we don't.

#### **Problems:**

- Keys may not be numeric.
- Number of possible keys is much larger than the space available in table.
- Different keys may map into same location
  - Hash function is not one-to-one => collision.
  - If there are too many collisions, the performance of the hash table will suffer dramatically.

- If the input keys are integers then simply *Key* mod *TableSize* is a general strategy.
  - Unless key happens to have some undesirable properties. (e.g. all keys end in 0 and we use mod 10)
- If the keys are strings, hash function needs more care.
  - First convert it into a numeric value.

### **Definitions**

- Hash function: maps a key, k, to an index (address) in the table
- Perfect hash function: function that maps each key to a unique index
- Collision: occurs when more than one key maps to the same index

### Some methods

#### • Truncation:

e.g. 123456789 map to a table of 1000 addresses by picking 3 digits of the key.

#### Folding:

- e.g. 123|456|789: add them and take mod.

#### • Key mod N:

N is the size of the table, better if it is prime.

### Squaring:

Square the key and then truncate

#### Radix conversion:

- e.g. 1 2 3 4 treat it to be base 7, truncate if necessary.

# folding

- Hashing by folding
- Idea: divide the key into parts, then combine (fold) the parts to create the index
- Shift folding: parts are placed underneath one another, then added
- Boundary folding: same as shift folding, except that every other part is written backwards
- Usually followed by modulo division.

# Folding - example

- Key is 23459087632
- Divide into parts: 234 590 876 32
- Shift folding: 234 + 590 + 876 + 032 = 1732
- Boundary folding: 234 + 095 + 876 + 23 = 1228

# Computing the mid-square

- Hashing by computing the mid-square
- Idea: square the key, use the middle as the address
- Example: 96012 -> 9218304144 -> 8304 is hash
- Advantage: entire key is used to calculate the address, reducing chances of collisions

• Add up the ASCII values of all characters of the key.

- Simple to implement and fast.
- However, if the table size is large, the function does not distribute the keys well.
  - e.g. Table size =10000, key length <= 8, the hash function can assume values only between 0 and 1016

• Examine only the first 3 characters of the key.

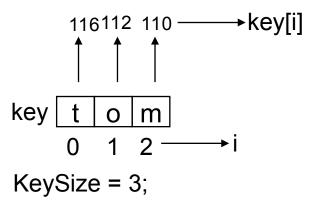
```
int hash (const string &key, int tableSize)
{
    return (key[0]+27 * key[1] + 729*key[2]) % tableSize;
}
```

- In theory, 26 \* 26 \* 26 = 17576 different words can be generated. However, English is not random, only 2851 different combinations are possible.
- Thus, this function although easily computable, is also not appropriate if the hash table is reasonably large.

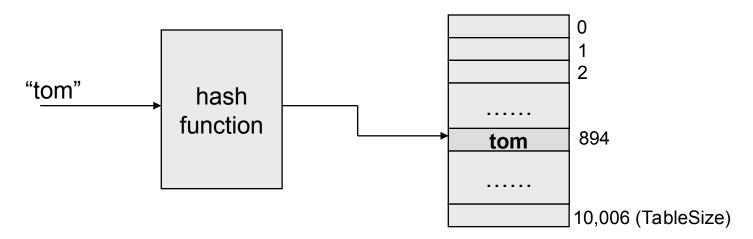
 $hash(key) = \sum_{i=0}^{KeySize-1} Key[KeySize-i-1] \cdot 37^{i}$ 

```
int hash (const string &key, int tableSize)
   int hashVal = 0;
   for (int i = 0; i < \text{key.length}(); i++)
      hashVal = 37 * hashVal + key[i];
   hashVal %=tableSize;
   if (hashVal < 0) /* in case overflows occurs */
      hashVal += tableSize;
   return hashVal;
```

### Hash function for strings:



hash("tom") = 
$$(110 * 1 + 112*37 + 116*37^2)$$
 %  $10,007 = 894$ 



### **Collision Resolution**

- If, when an element is inserted, it hashes to the same value as an already inserted element, then we have a collision and need to resolve it.
- There are several methods for dealing with this:
  - Separate chaining
  - Open addressing
    - Linear Probing
    - Quadratic Probing
    - Double Hashing

# Separate Chaining

- The idea is to keep a list of all elements that hash to the same value.
  - The array elements are pointers to the first nodes of the lists.
  - A new item is inserted to the front of the list.

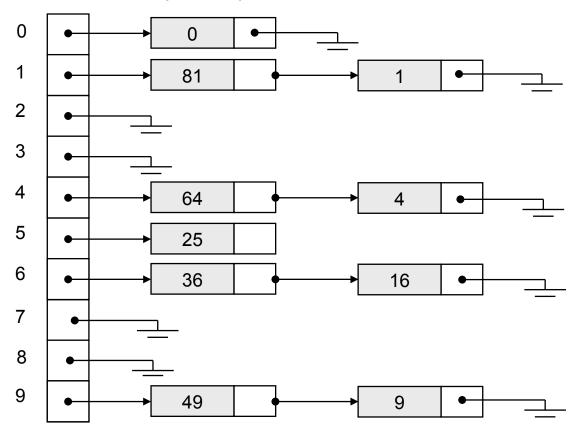
#### • Advantages:

- Better space utilization for large items.
- Simple collision handling: searching linked list.
- Overflow: we can store more items than the hash table size.
- Deletion is quick and easy: deletion from the linked list.

### Example

Keys: 0, 1, 4, 9, 16, 25, 36, 49, 64, 81

hash(key) = key % 10.



### **Operations**

• Initialization: all entries are set to NULL

#### • Find:

- locate the cell using hash function.
- sequential search on the linked list in that cell.

#### • Insertion:

- Locate the cell using hash function.
- (If the item does not exist) insert it as the first item in the list.

#### • Deletion:

- Locate the cell using hash function.
- Delete the item from the linked list.

# **Analysis of Separate Chaining**

- Collisions are very likely.
  - How likely and what is the average length of lists?
- Load factor λ definition:
  - Ratio of number of elements (N) in a hash table to the hash *TableSize*.
    - i.e.  $\lambda = N/TableSize$
  - The average length of a list is also  $\lambda$ .
  - For chaining  $\lambda$  is not bound by 1; it can be > 1.

### Cost of searching

Cost = Constant time to evaluate the hash function
 + time to traverse the list.

#### Unsuccessful search:

- We have to traverse the entire list, so we need to compare  $\lambda$  nodes on the average.

#### Successful search:

 List contains the one node that stores the searched item + 0 or more other nodes.

# Summary

- The analysis shows us that the table size is not really important, but the load factor is.
- TableSize should be as *large* as the number of expected elements in the hash table.
  - To keep load factor around 1.
- TableSize should be *prime* for even distribution of keys to hash table cells.

# Hashing: Open Addressing

# Collision Resolution with Open Addressing

- Separate chaining has the disadvantage of using linked lists.
  - Requires the implementation of a second data structure.
- In an open addressing hashing system, all the data go inside the table.
  - Thus, a bigger table is needed.
    - Generally the load factor should be below 0.5.
  - If a collision occurs, alternative cells are tried until an empty cell is found.

# **Open Addressing**

- More formally:
  - Cells  $h_0(x)$ ,  $h_1(x)$ ,  $h_2(x)$ , ... are tried in succession where  $h_i(x) = (hash(x) + f(i)) \mod TableSize$ , with f(0) = 0.
  - The function f is the collision resolution strategy.
- There are three common collision resolution strategies:
  - Linear Probing
  - Quadratic probing
  - Double hashing

# **Linear Probing**

- In linear probing, collisions are resolved by sequentially scanning an array (with wraparound) until an empty cell is found.
  - i.e. f is a linear function of i, typically f(i) = i.
- Example:
  - Insert items with keys: 89, 18, 49, 58, 9 into an empty hash table.
  - Table size is 10.
  - Hash function is  $hash(x) = x \mod 10$ .
    - f(i) = i;

#### Figure 20.4

Linear probing hash table after each insertion

After insert 89 After insert 18 After insert 49 After insert 58 After insert 9

0			49	49	49
1				58	58
2					9
3					
4					
5					
6					
7					
8		18	18	18	18
9	89	89	89	89	89

### Find and Delete

- The find algorithm follows the same probe sequence as the insert algorithm.
  - A find for 58 would involve 4 probes.
  - A find for 19 would involve 5 probes.
- We must use *lazy deletion* (i.e. marking items as deleted)
  - Standard deletion (i.e. physically removing the item) cannot be performed.
  - e.g. remove 89 from hash table.

# **Clustering Problem**

- As long as table is big enough, a free cell can always be found, but the time to do so can get quite large.
- Worse, even if the table is relatively empty, blocks of occupied cells start forming.
- This effect is known as primary clustering.
- Any key that hashes into the cluster will require several attempts to resolve the collision, and then it will add to the cluster.

# **Quadratic Probing**

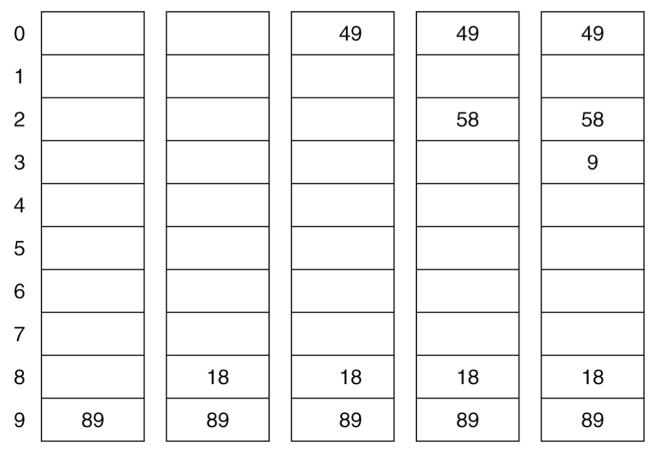
- Quadratic Probing eliminates primary clustering problem of linear probing.
- Collision function is quadratic.
  - The popular choice is  $f(i) = i^2$ .
- If the hash function evaluates to h and a search in cell h is inconclusive, we try cells  $h + 1^2$ ,  $h+2^2$ , ...  $h + i^2$ .
  - i.e. It examines cells 1,4,9 and so on away from the original probe.
- Remember that subsequent probe points are a quadratic number of positions from the *original* probe point.

#### Figure 20.6

A quadratic probing hash table after each insertion (note that the table size was poorly chosen because it is not a prime number).

```
hash (89, 10) = 9
hash (18, 10) = 8
hash (49, 10) = 9
hash (58, 10) = 8
hash (9, 10) = 9
```

After insert 89 After insert 18 After insert 49 After insert 58 After insert 9



# **Quadratic Probing**

#### • Problem:

- We may not be sure that we will probe all locations in the table (i.e. there is no guarantee to find an empty cell if table is more than half full.)
- If the hash table size is not prime this problem will be much severe.
- However, there is a theorem stating that:
  - If the table size is *prime* and load factor is not larger than 0.5, all probes will be to different locations and an item can always be inserted.

### Some considerations

- How efficient is calculating the quadratic probes?
  - Linear probing is easily implemented.
     Quadratic probing appears to require \* and % operations.
  - However by the use of the following trick, this is overcome:
    - $H_i = H_{i-1} + 2i 1 \pmod{M}$

### **Some Considerations**

- What happens if load factor gets too high?
  - Dynamically expand the table as soon as the load factor reaches 0.5, which is called rehashing.
  - Always double to a prime number.
  - When expanding the hash table, reinsert the new table by using the new hash function.

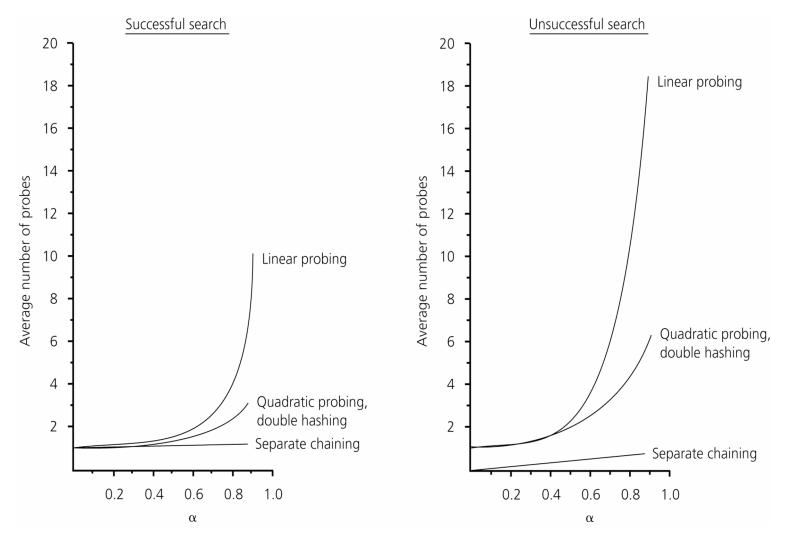
# **Analysis of Quadratic Probing**

- Quadratic probing has not yet been mathematically analyzed.
- Although quadratic probing eliminates primary clustering, elements that hash to the same location will probe the same alternative cells. This is know as *secondary clustering*.
- Techniques that eliminate secondary clustering are available.
  - the most popular is *double hashing*.

# **Double Hashing**

- A second hash function is used to drive the collision resolution.
  - $-f(i) = i * hash_2(x)$
- We apply a second hash function to x and probe at a distance  $hash_2(x)$ ,  $2*hash_2(x)$ , ... and so on.
- The function  $hash_2(x)$  must never evaluate to zero.
  - e.g. Let  $hash_2(x) = x \mod 9$  and try to insert 99 in the previous example.
- A function such as  $hash_2(x) = R (x \mod R)$  with R a prime smaller than TableSize will work well.
  - e.g. try R = 7 for the previous example.(7 x mode 7)

# The relative efficiency of four collision-resolution methods



# **Hashing Applications**

- Compilers use hash tables to implement the *symbol table* (a data structure to keep track of declared variables).
- Game programs use hash tables to keep track of positions it has encountered (*transposition table*)
- Online spelling checkers.

# Summary

- Hash tables can be used to implement the insert and find operations in constant average time.
  - it depends on the load factor not on the number of items in the table.
- It is important to have a prime TableSize and a correct choice of load factor and hash function.
- For separate chaining the load factor should be close to 1.
- For open addressing load factor should not exceed 0.5 unless this is completely unavoidable.
  - Rehashing can be implemented to grow (or shrink) the table.