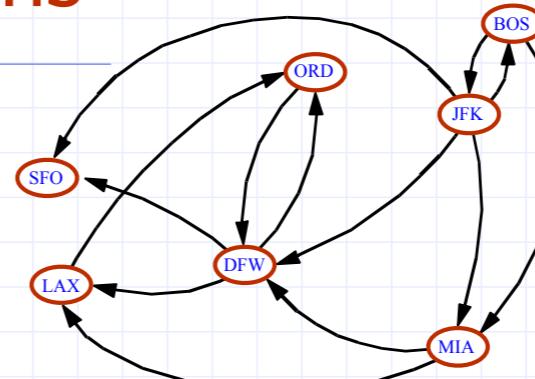


Directed Graphs

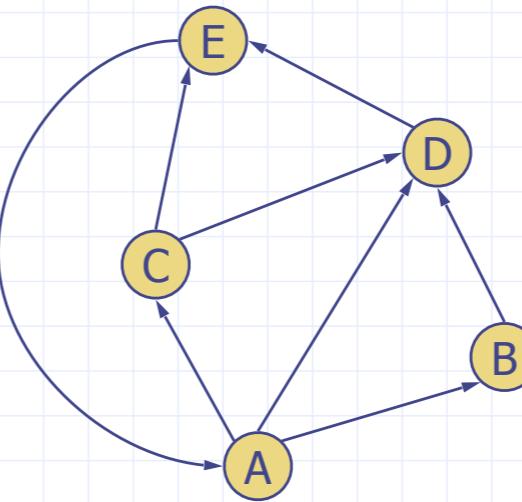


Digraphs

- A **digraph** is a graph whose edges are all directed
 - Short for “directed graph”

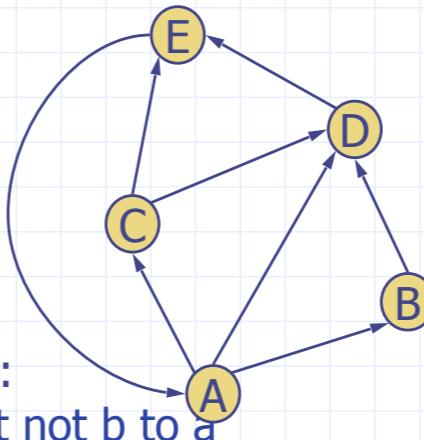
- Applications

- one-way streets
 - flights
 - task scheduling



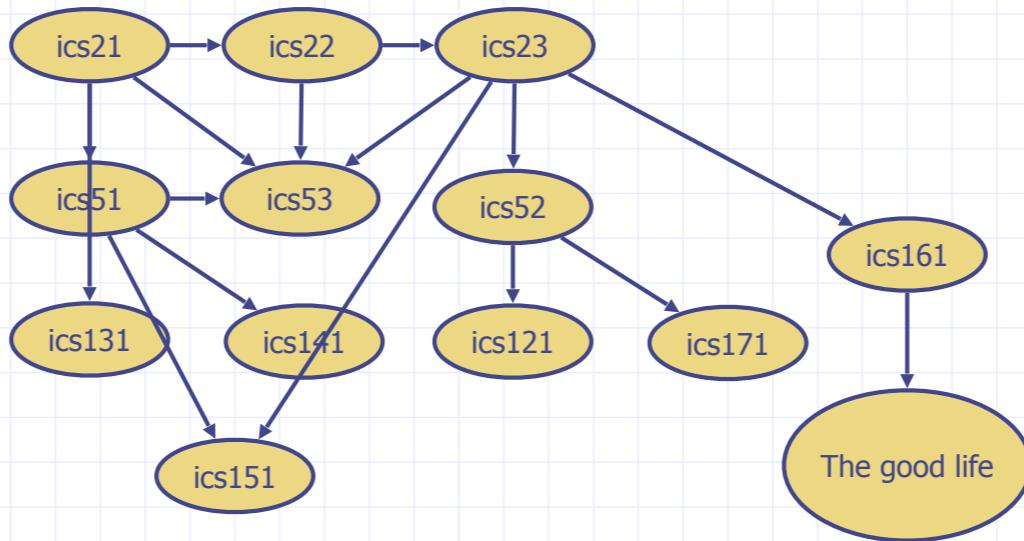
Digraph Properties

- ❑ A graph $G=(V,E)$ such that
 - Each edge goes in **one direction**:
 - Edge (a,b) goes from a to b , but not b to a
- ❑ If G is simple, $m \leq n \cdot (n - 1)$
- ❑ If we keep in-edges and out-edges in separate adjacency lists, we can perform listing of incoming edges and outgoing edges in time proportional to their size



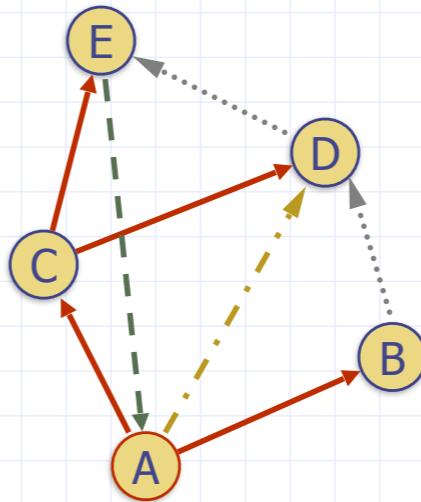
Digraph Application

- **Scheduling:** edge (a,b) means task a must be completed before b can be started



Directed DFS

- We can specialize the traversal algorithms (DFS and BFS) to digraphs by traversing edges only along their direction
- In the directed DFS algorithm, we have four types of edges
 - discovery edges
 - back edges
 - forward edges
 - cross edges
- A directed DFS starting at a vertex s determines the vertices **reachable** from s



Directed DFS

Back edge (v, w)

- w is an ancestor of v in the tree of discovery edges

Forward edge (v, w)

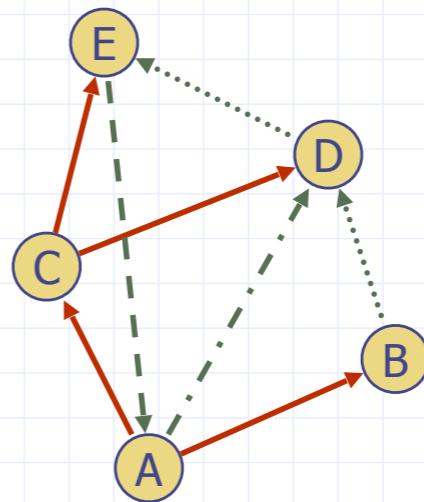
- v is an ancestor (but not the parent) of w in the tree of discovery edges

Cross edge (v, w)

- w is in the same level as v or in the next level in the tree of discovery edges

Discovery edge (v, w)

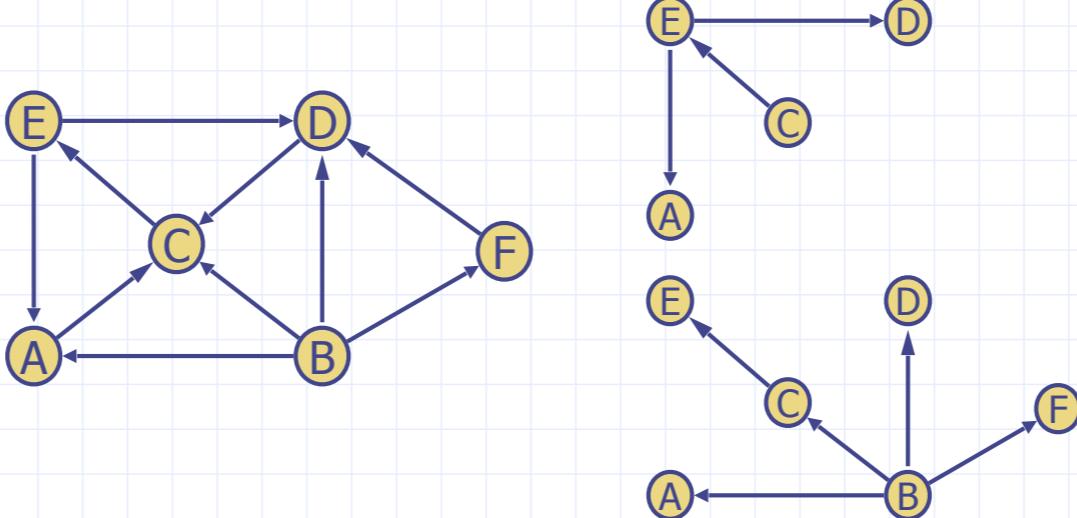
- v is the parent of w in the tree of discovery edges



Reachability



- DFS tree rooted at v : vertices reachable from v via directed paths



© 2010 Goodrich, Tamassia

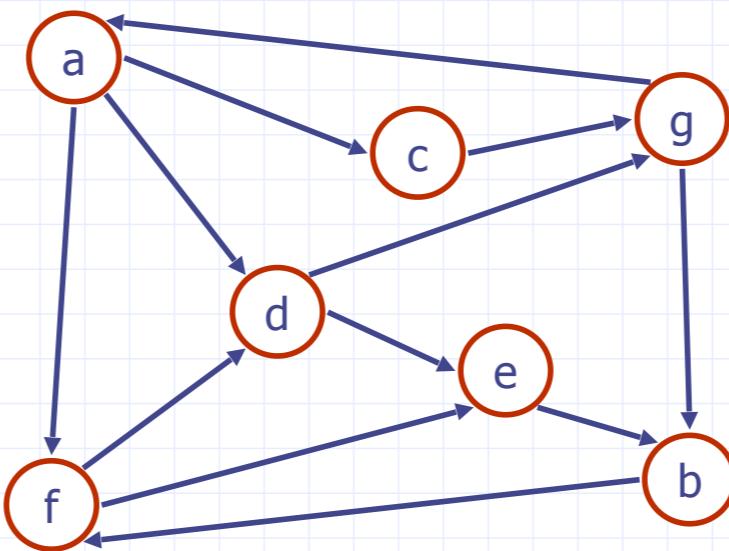
Directed Graphs

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Strong Connectivity



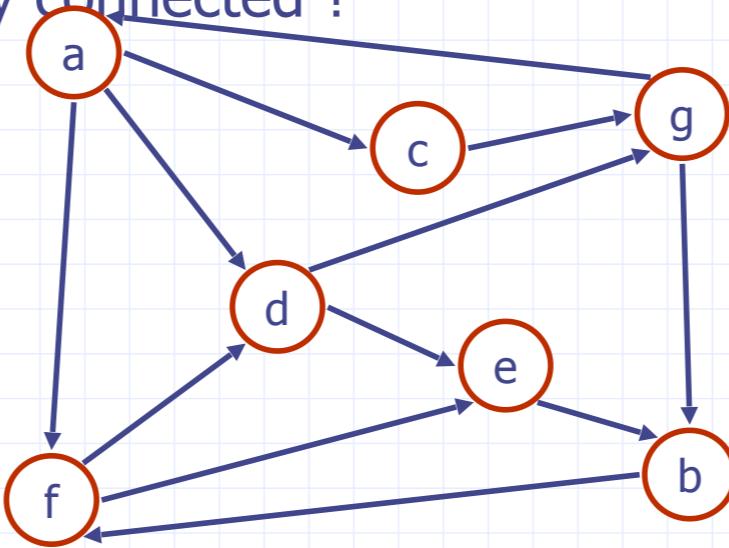
- Each vertex can reach all other vertices



Strong Connectivity



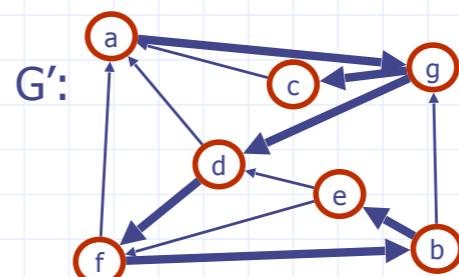
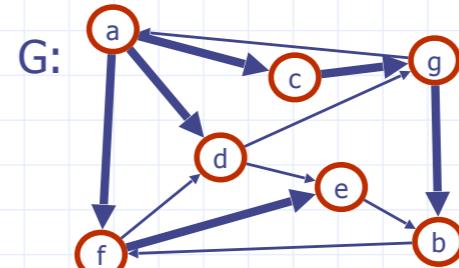
- ❑ How do you determine if a digraph is strongly connected ?



Strong Connectivity Algorithm

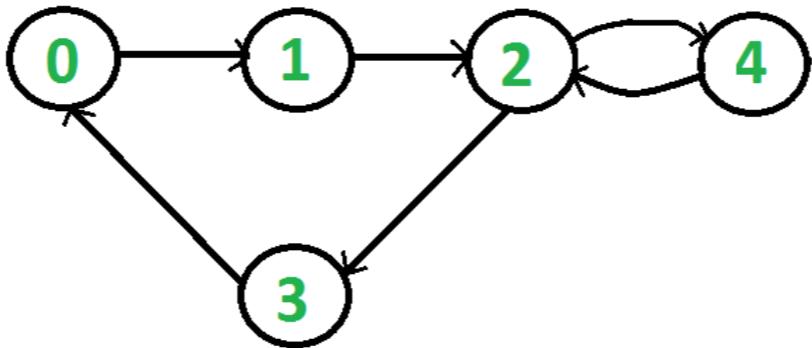


- Pick a vertex v in G
- Perform a DFS from v in G
 - If there's a w not visited, print "no"
- Let G' be G with edges reversed
- Perform a DFS from v in G'
 - If there's a w not visited, print "no"
 - Else, print "yes"
- Running time: $O(n+m)$
- Transpose of Graph G



Graph connectivity

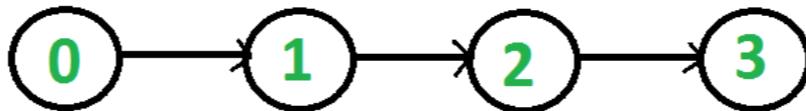
▫ Strongly



Strongly Connected

Graph connectivity

❑ Strongly

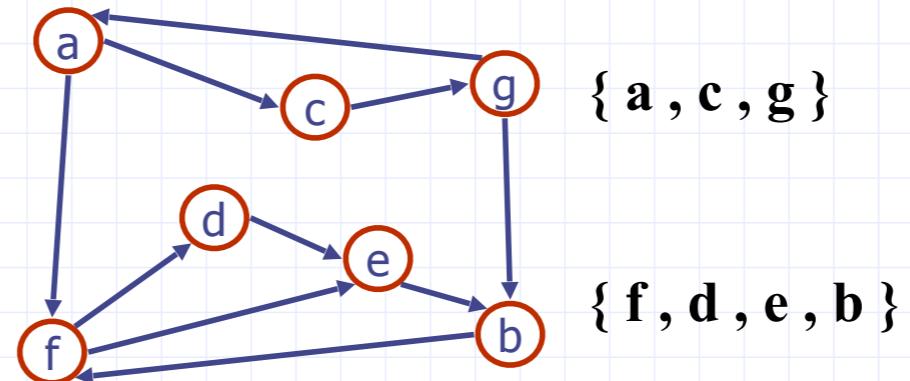


Not Strongly Connected

Strongly Connected Components

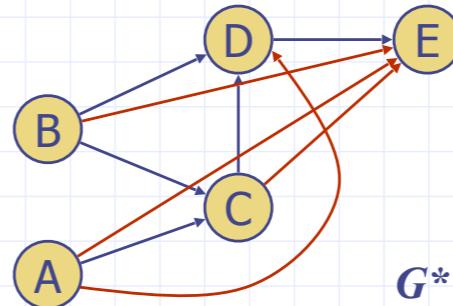
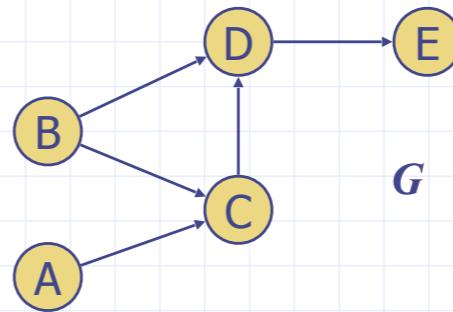


- ❑ Maximal subgraphs such that each vertex can reach all other vertices in the subgraph
- ❑ Can also be done in $O(n+m)$ time using DFS, but is more complicated (similar to biconnectivity).



Transitive Closure

- Given a digraph G , the transitive closure of G is the digraph G^* such that
 - G^* has the same vertices as G
 - if G has a directed path from u to v ($u \neq v$), G^* has a directed edge from u to v
- The transitive closure provides reachability information about a digraph



Computing the Transitive Closure

- We can perform DFS starting at each vertex
 - $O(n(n+m))$

If there's a way to get from **A** to **B** and from **B** to **C**, then there's a way to get from **A** to **C**.

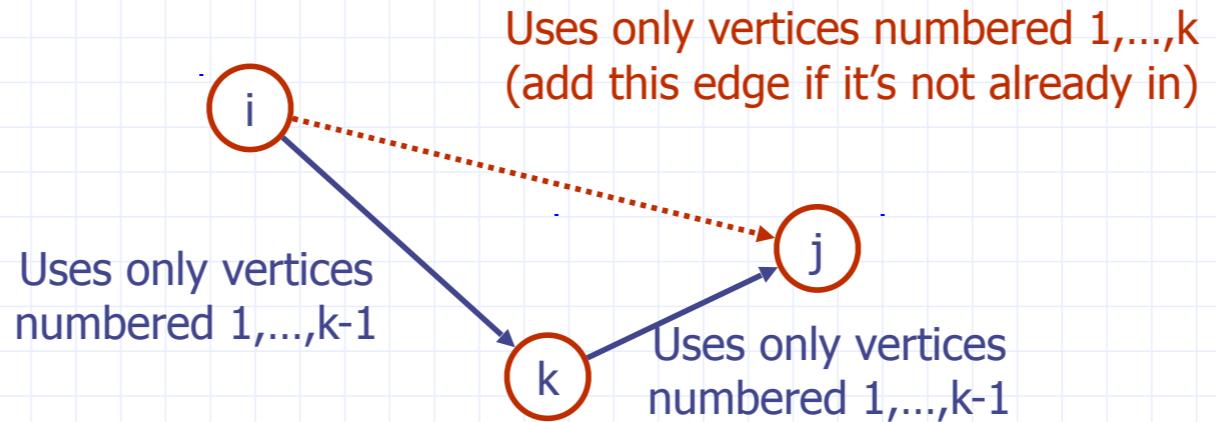


Alternatively ... Use dynamic programming:
The Floyd-Warshall Algorithm

Floyd-Warshall Transitive Closure



- Idea #1: Number the vertices 1, 2, ..., n.
- Idea #2: Consider paths that use only vertices numbered 1, 2, ..., k, as intermediate vertices:



Floyd-Warshall's Algorithm



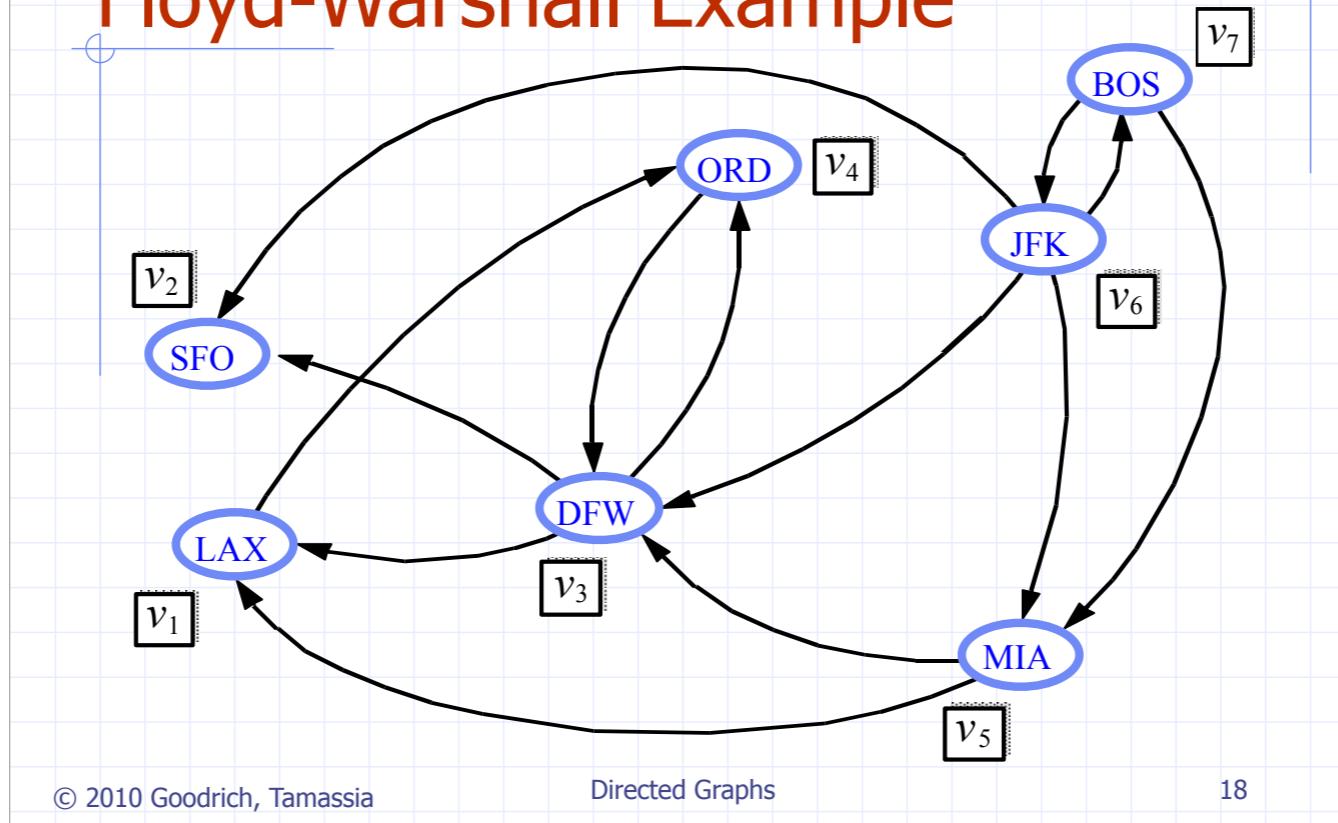
- Number vertices v_1, \dots, v_n
- Compute digraphs G_0, \dots, G_n
 - $G_0 = G$
 - G_k has directed edge (v_i, v_j) if G has a directed path from v_i to v_j with intermediate vertices in $\{v_1, \dots, v_k\}$
- We have that $G_n = G^*$
- In phase k , digraph G_k is computed from G_{k-1}
- Running time: $O(n^3)$, assuming `areAdjacent` is $O(1)$ (e.g., adjacency matrix)

Algorithm *FloydWarshall(G)*

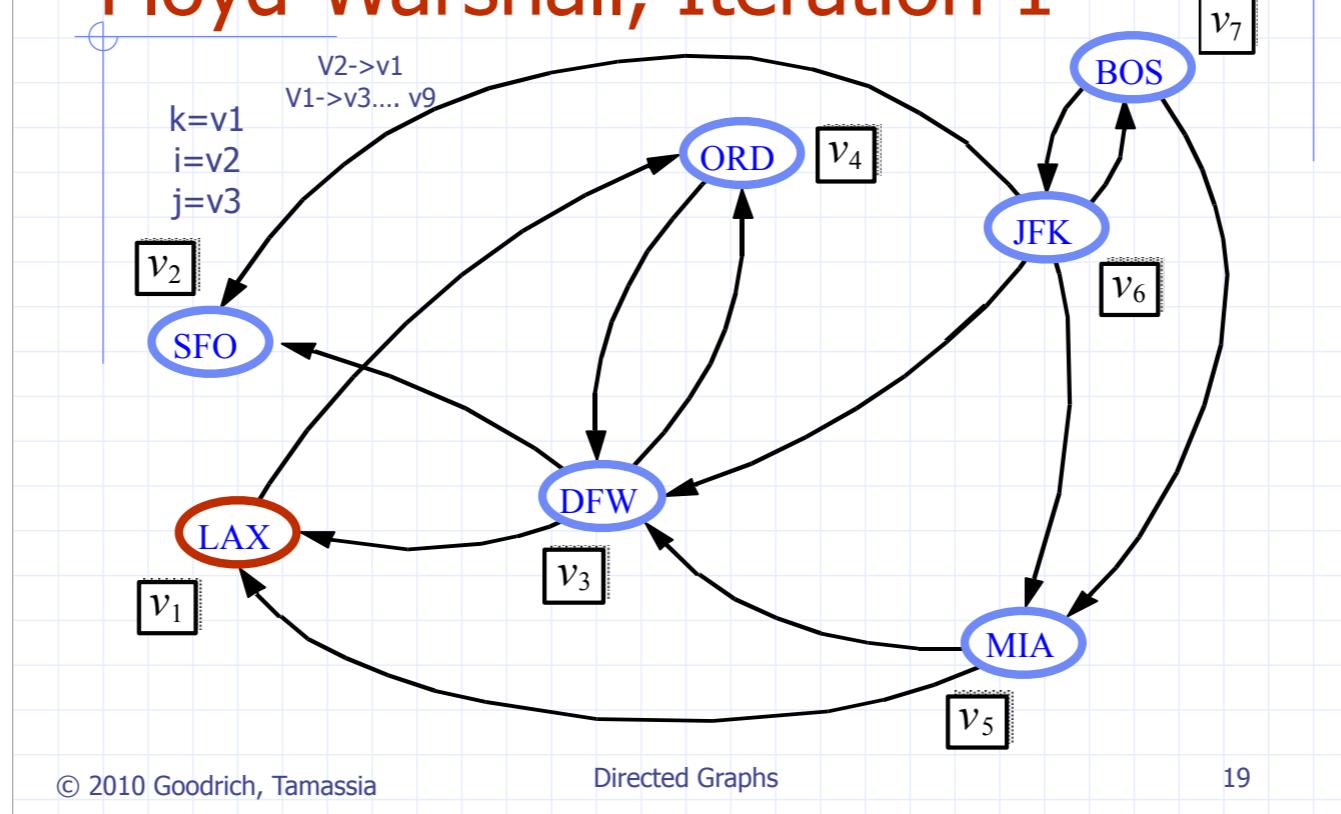
```
Input digraph  $G$ 
Output transitive closure  $G^*$  of  $G$ 
 $i \leftarrow 1$ 
for all  $v \in G.vertices()$ 
    denote  $v$  as  $v_i$ 
     $i \leftarrow i + 1$ 
 $G_0 \leftarrow G$ 
for  $k \leftarrow 1$  to  $n$  do
     $G_k \leftarrow G_{k-1}$ 
    for  $i \leftarrow 1$  to  $n$  ( $i \neq k$ ) do
        for  $j \leftarrow 1$  to  $n$  ( $j \neq i, k$ ) do
            if  $G_{k-1}.areAdjacent(v_i, v_k) \wedge$ 
                 $G_{k-1}.areAdjacent(v_k, v_j)$ 
            if  $\neg G_k.areAdjacent(v_i, v_j)$ 
                 $G_k.insertDirectedEdge(v_i, v_j, k)$ 
return  $G_n$ 
```

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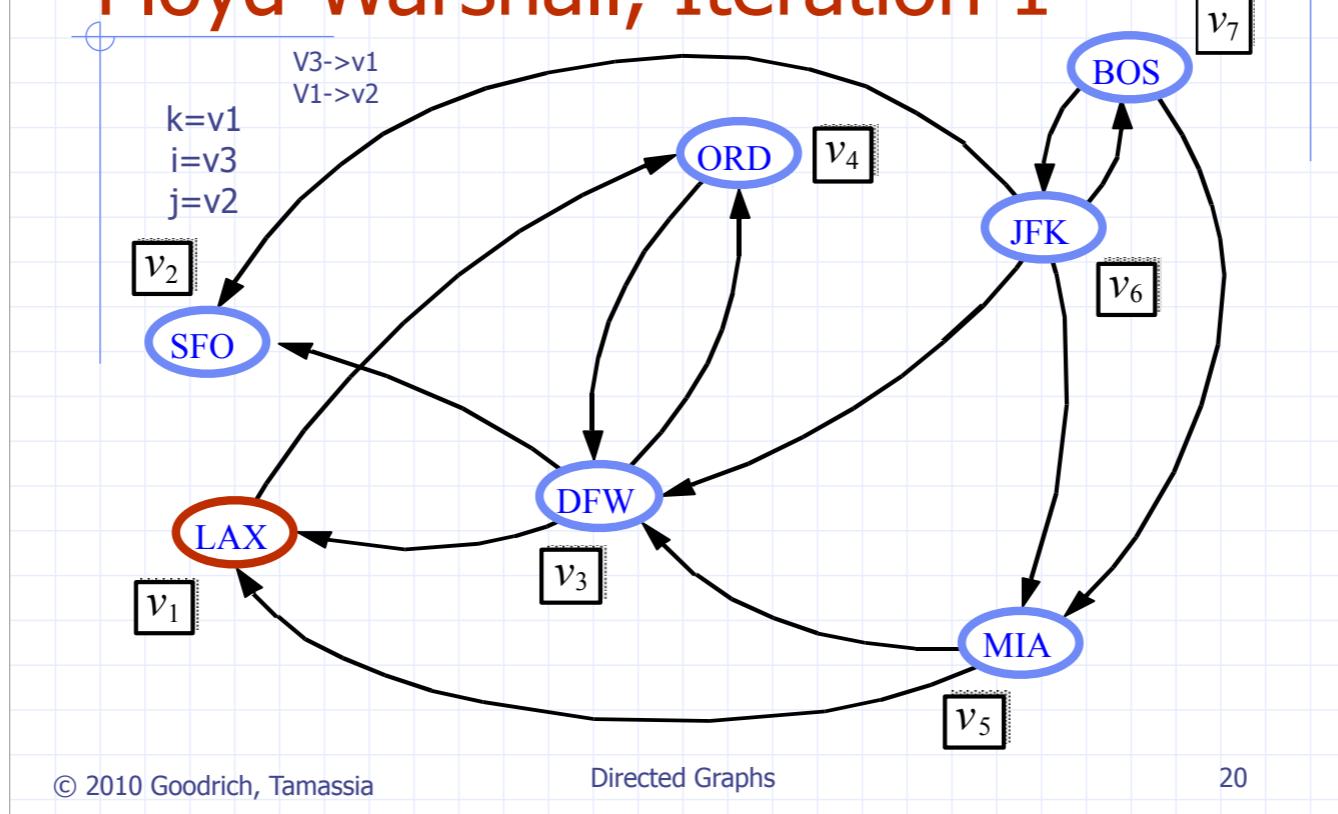
Floyd-Warshall Example



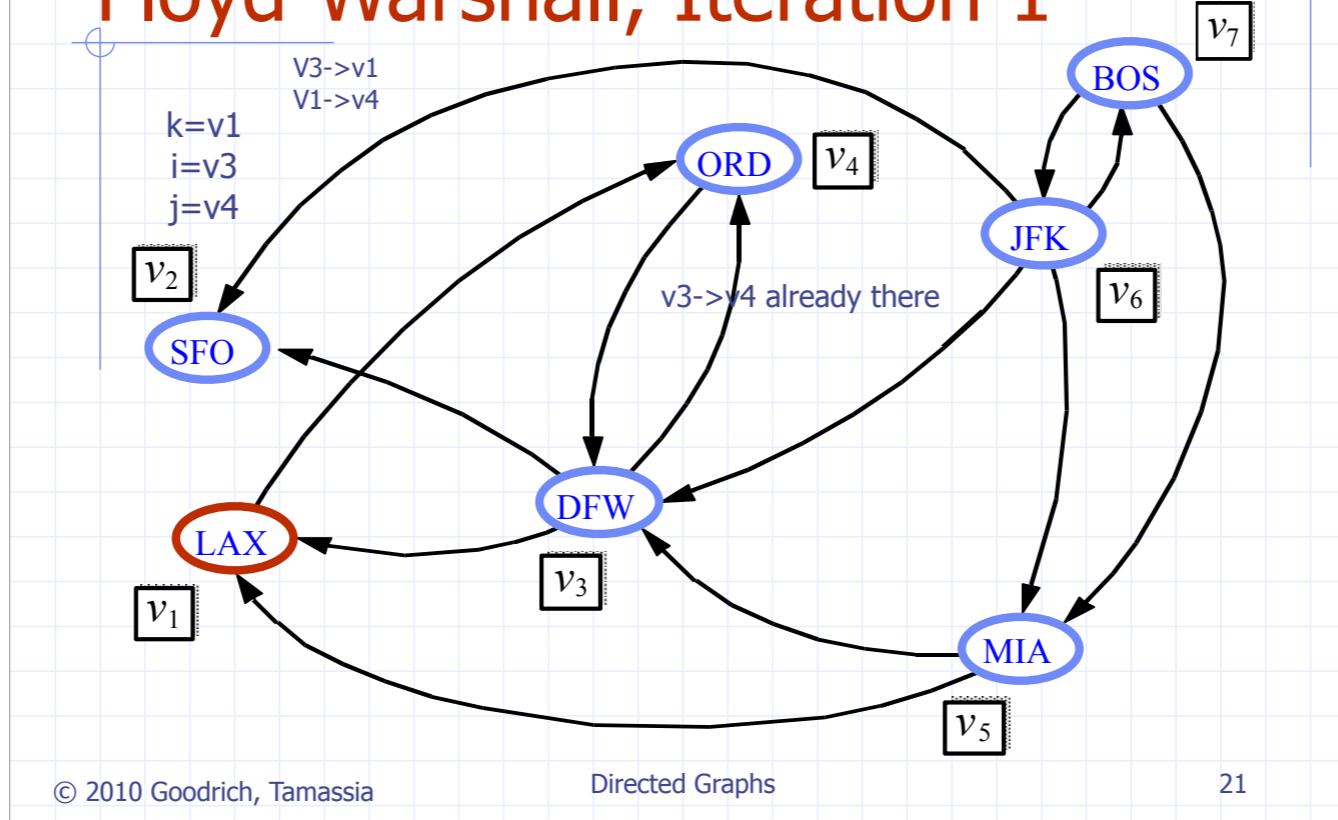
Floyd-Warshall, Iteration 1



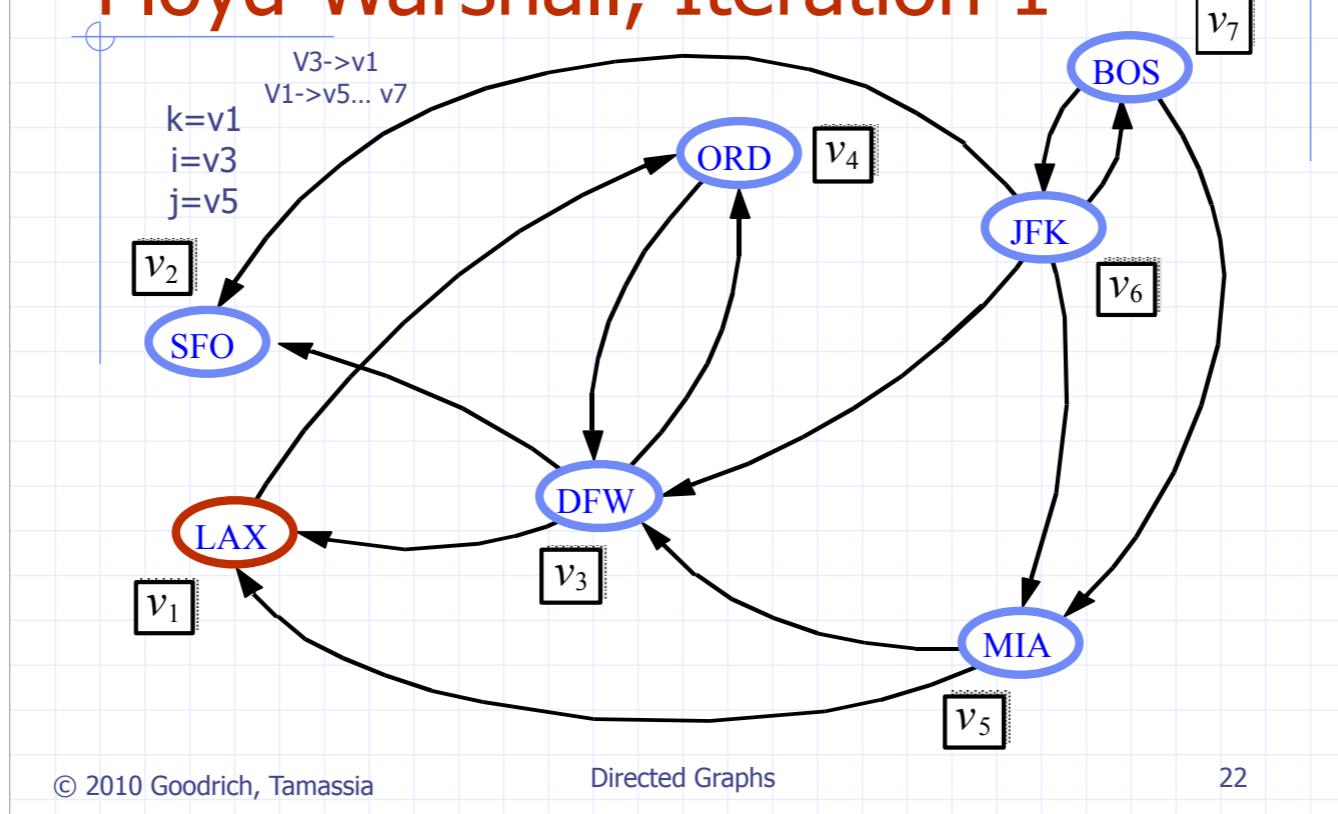
Floyd-Warshall, Iteration 1



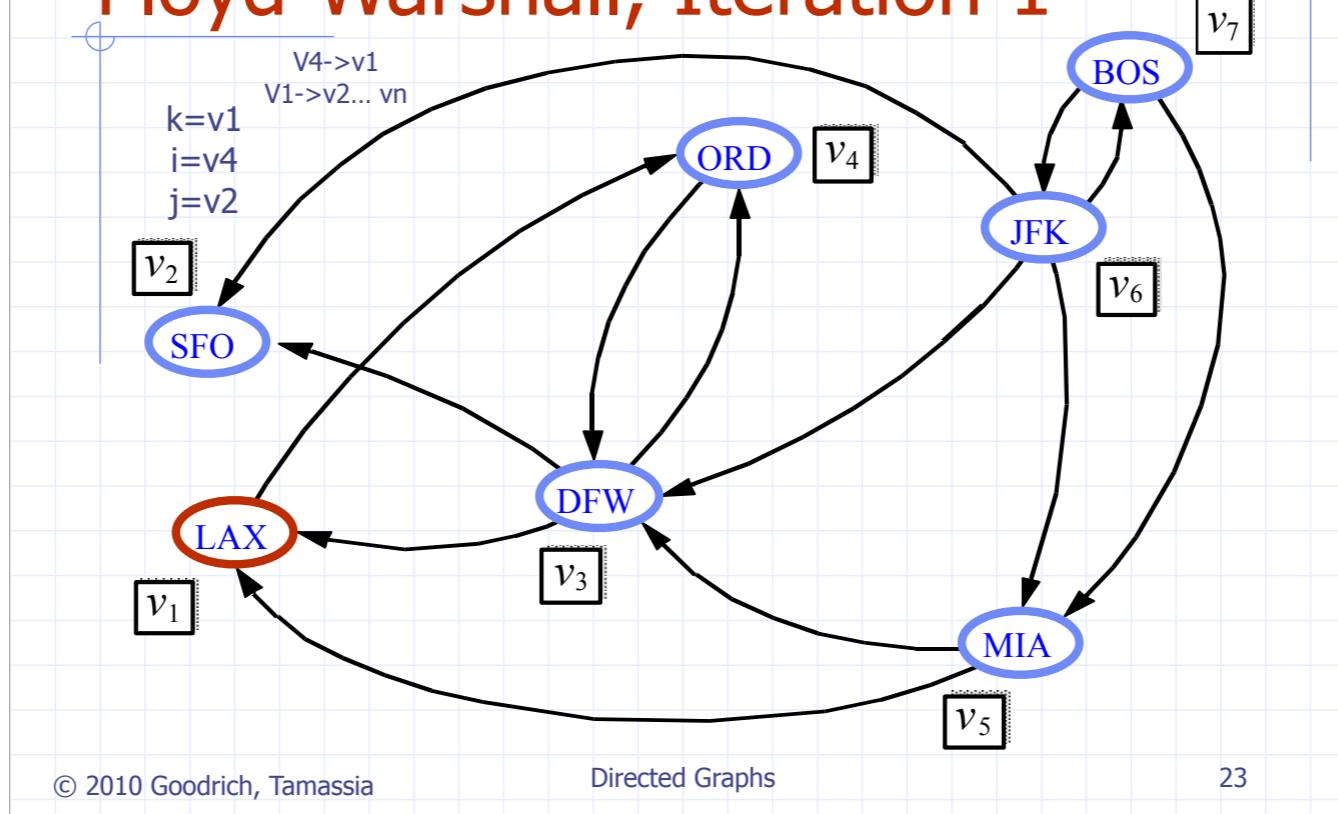
Floyd-Warshall, Iteration 1



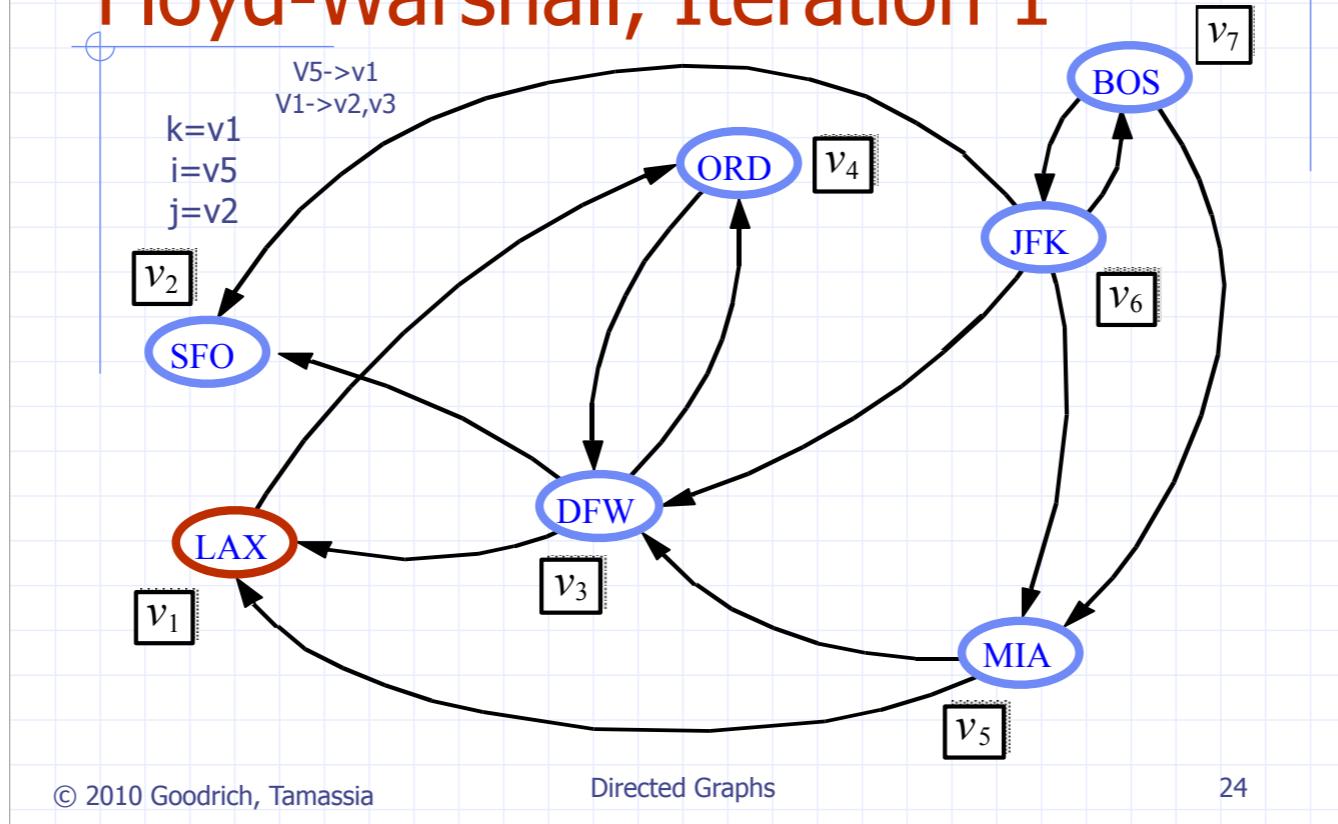
Floyd-Warshall, Iteration 1



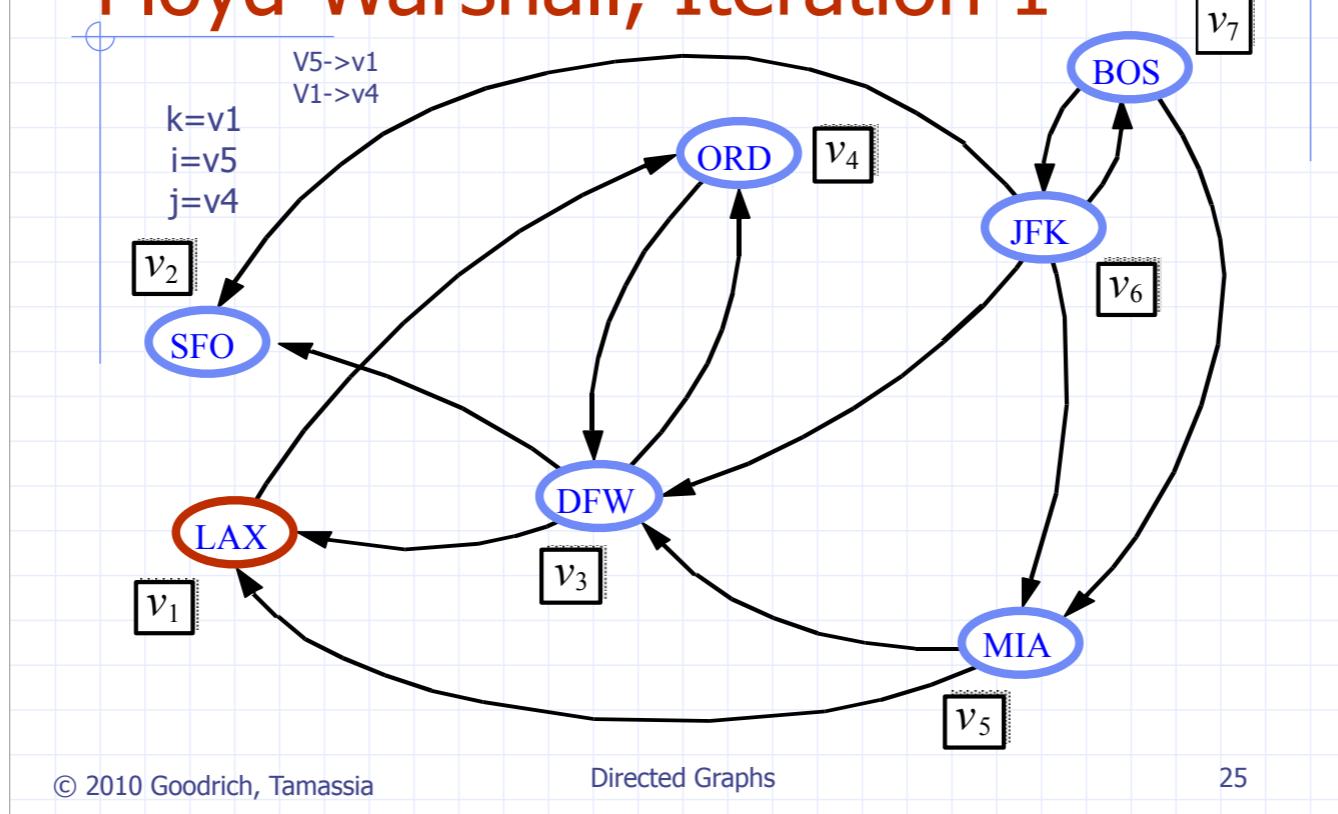
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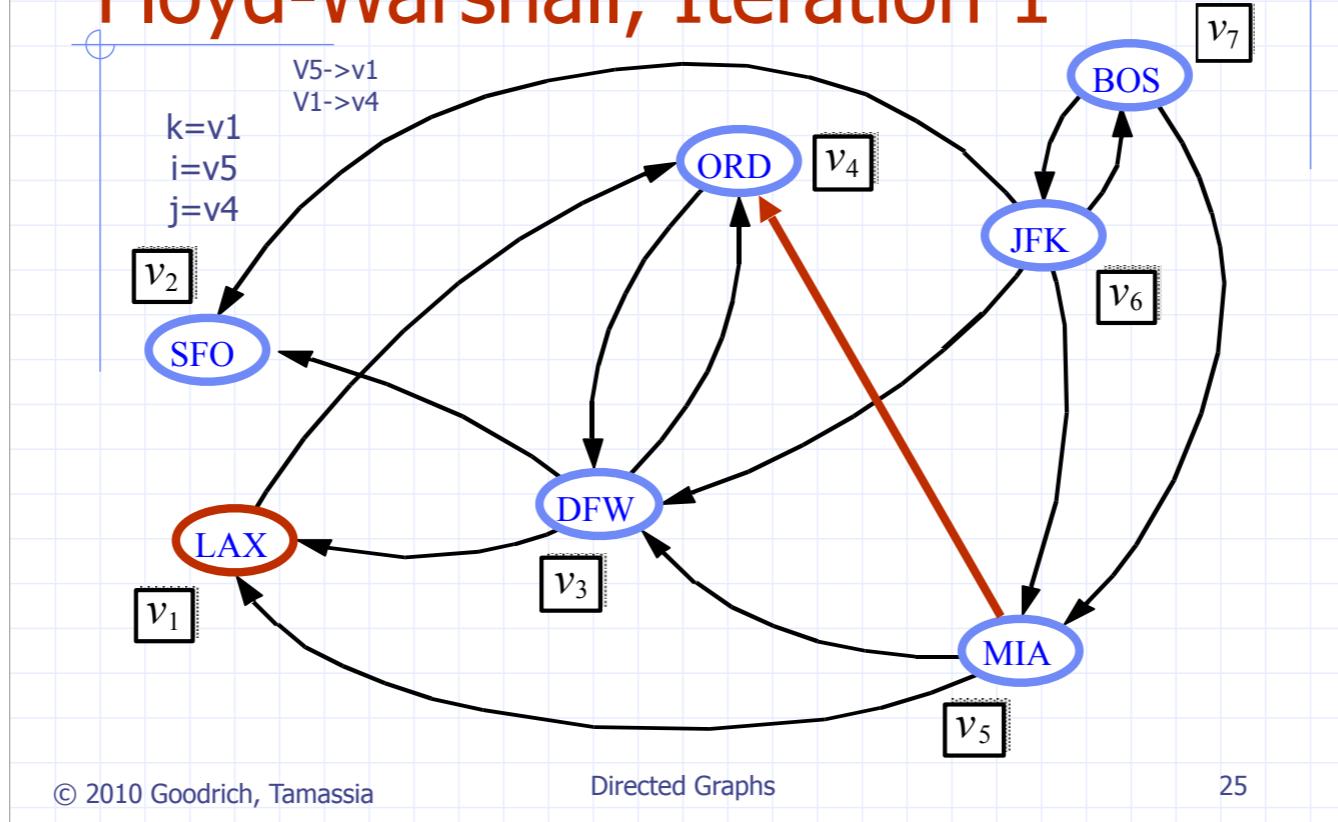
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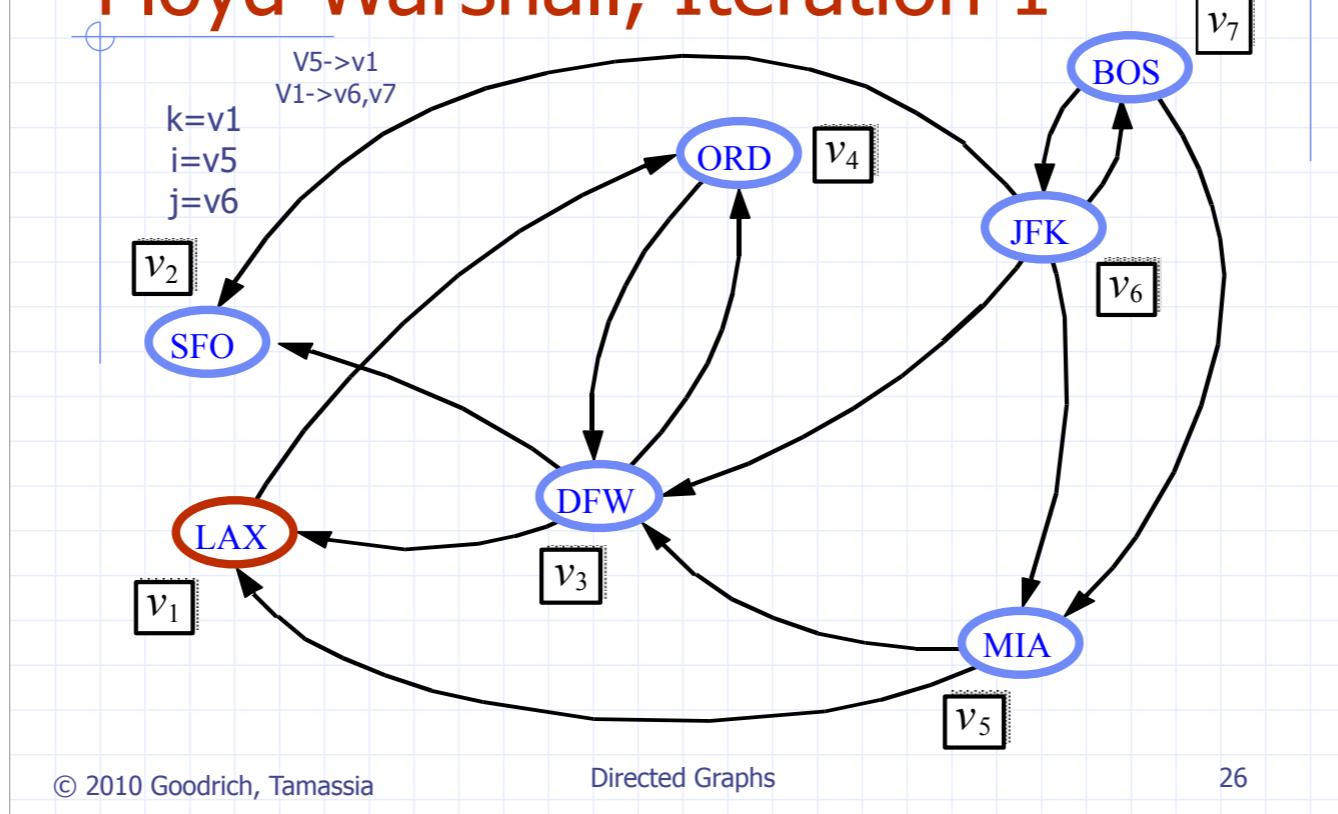
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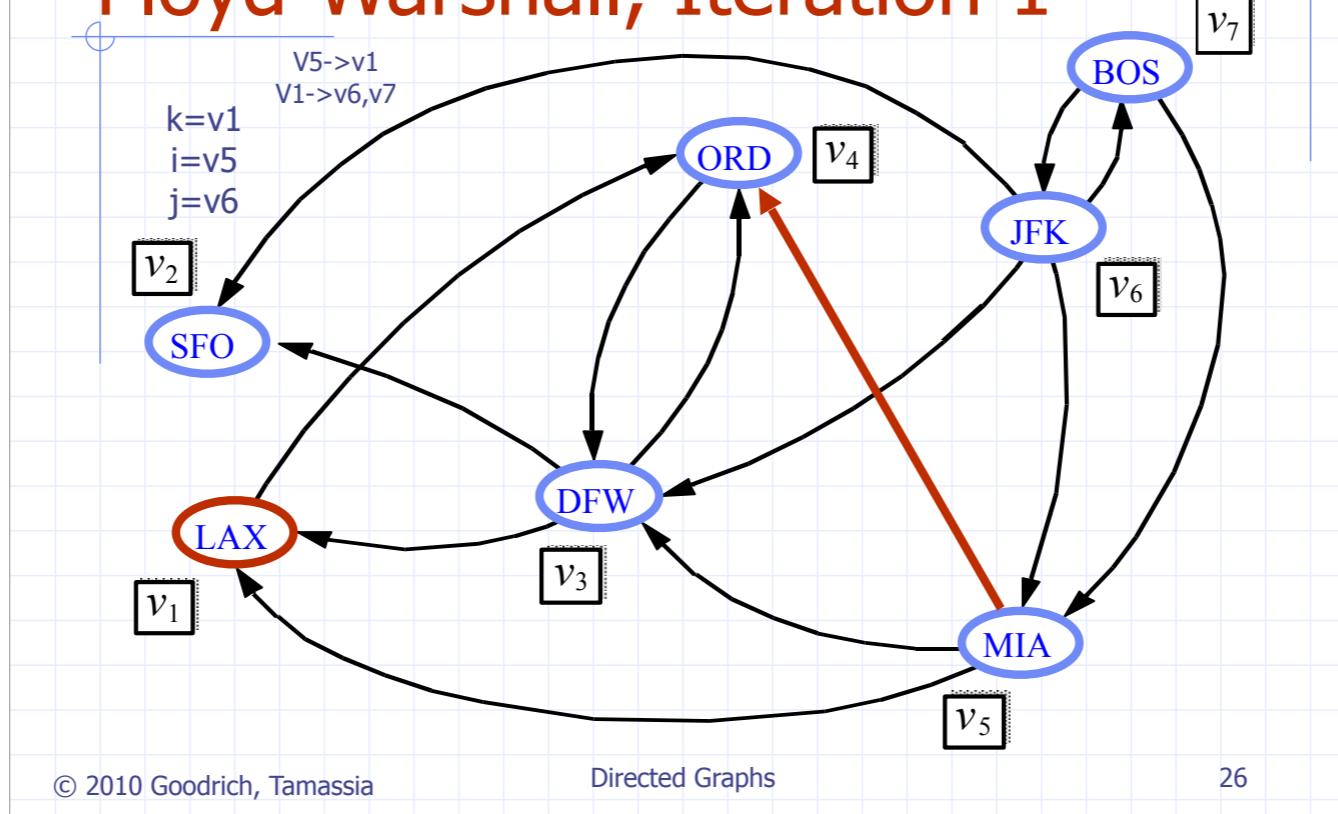
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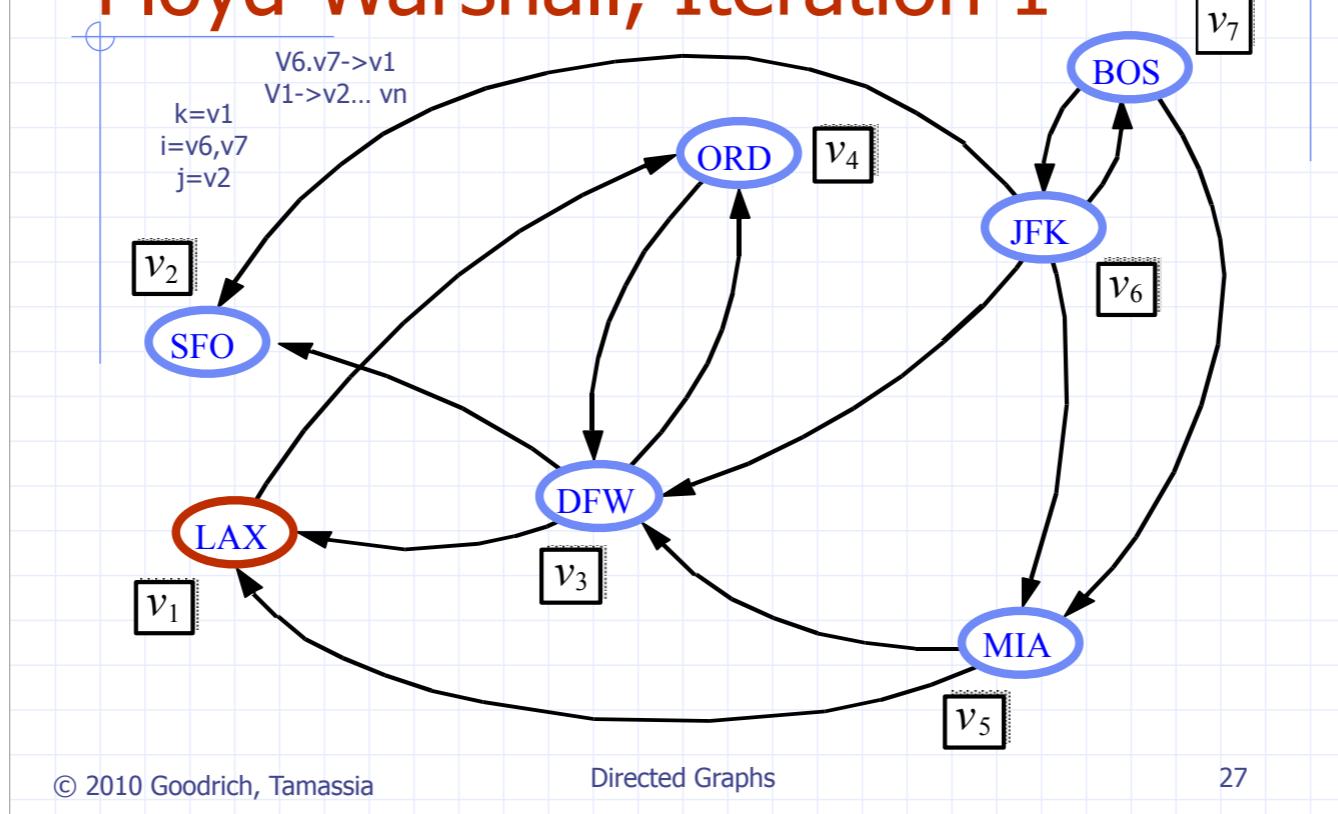
Floyd-Warshall, Iteration 1



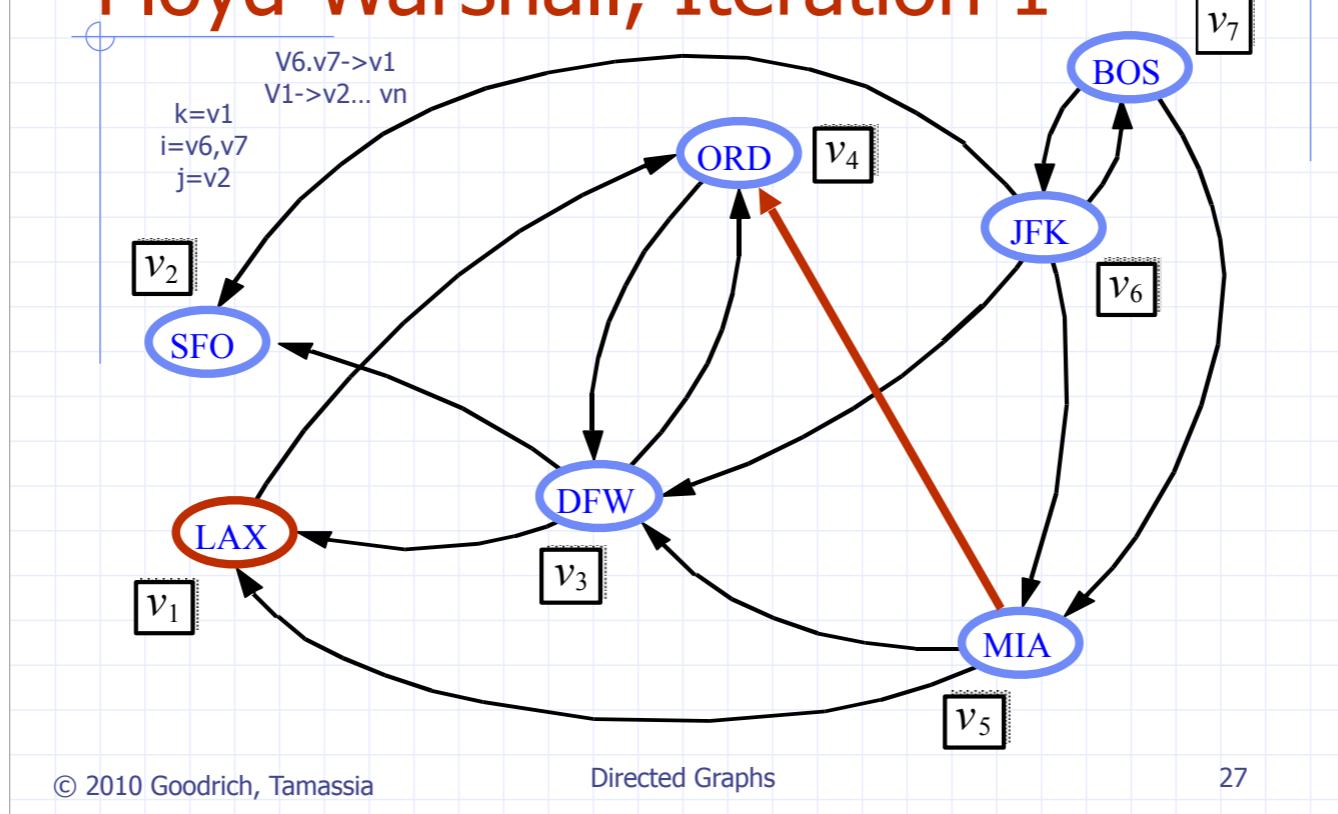
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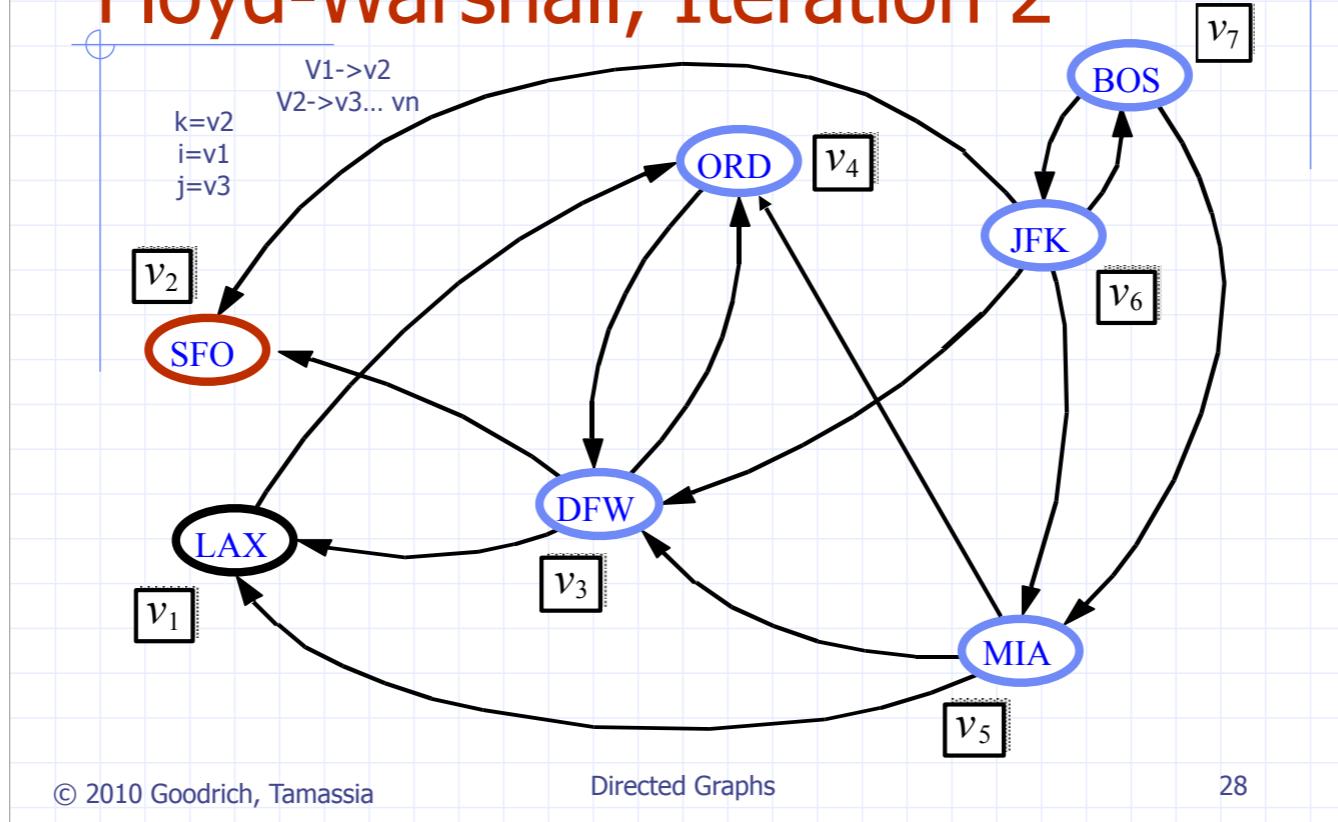
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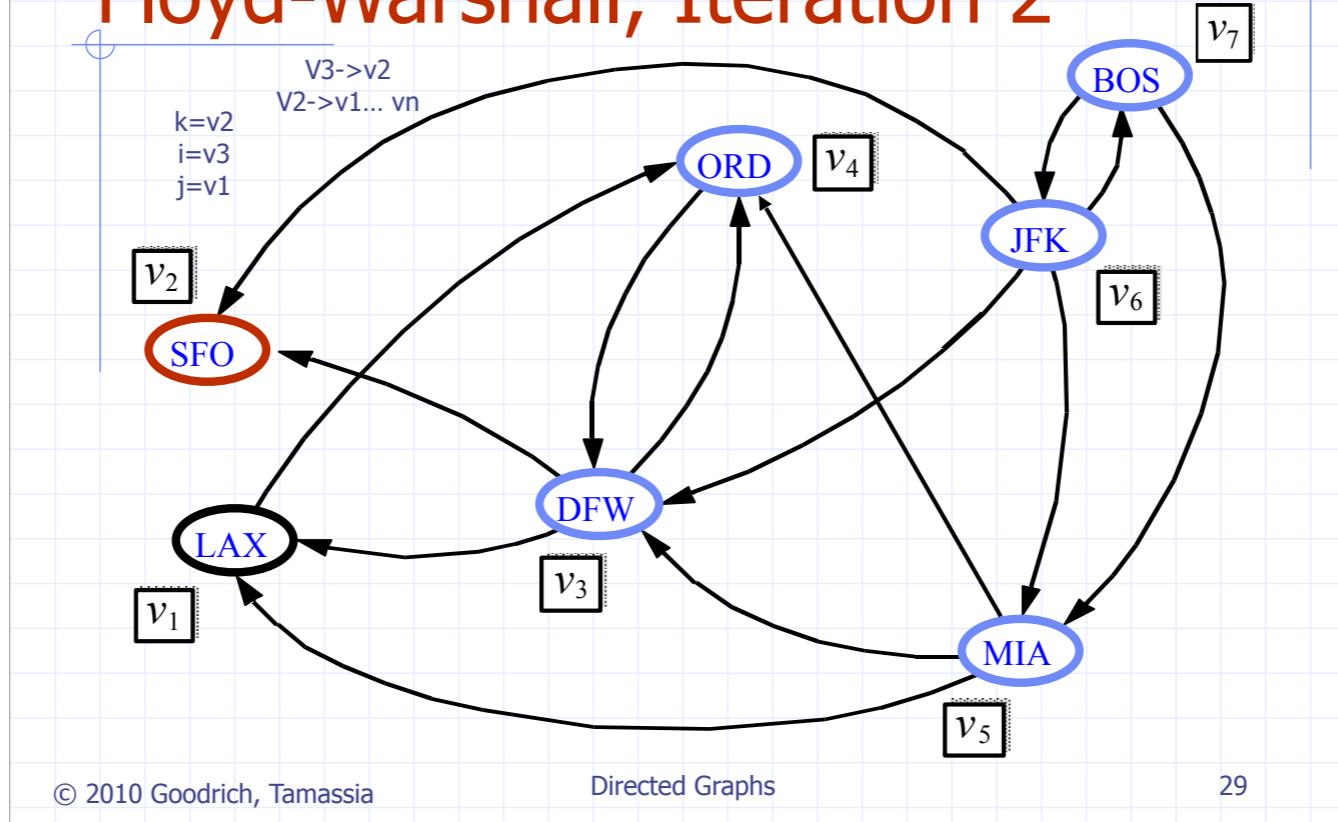
Floyd-Warshall, Iteration 1



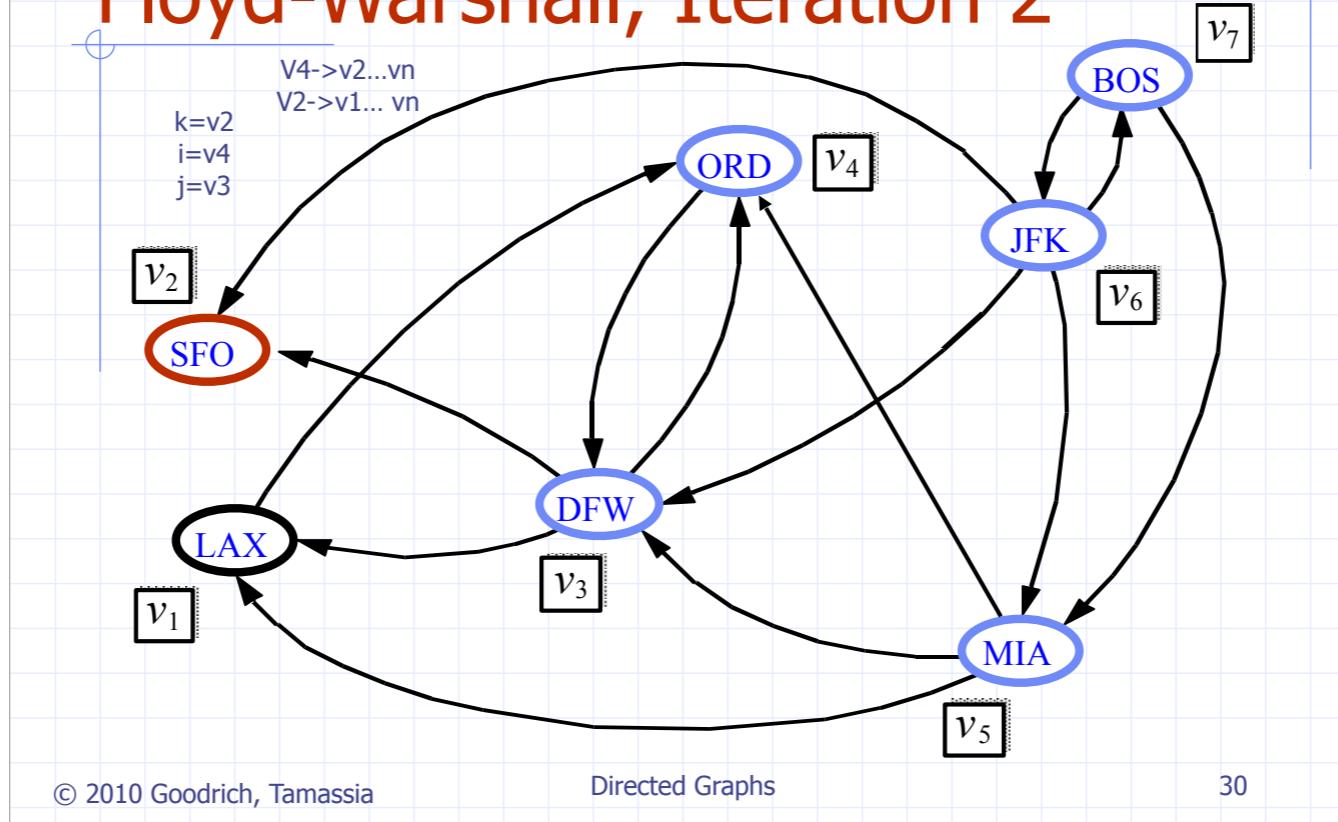
Floyd-Warshall, Iteration 2



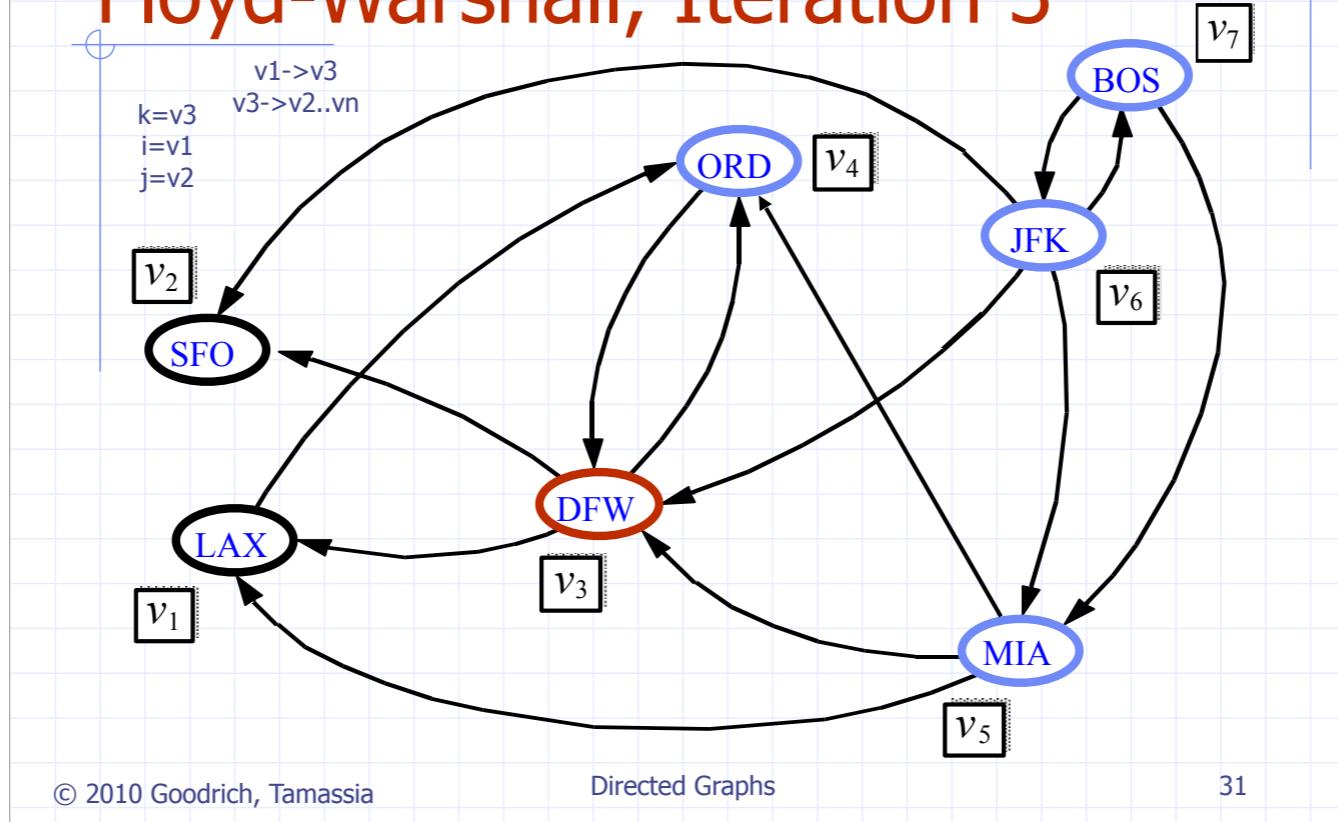
Floyd-Warshall, Iteration 2



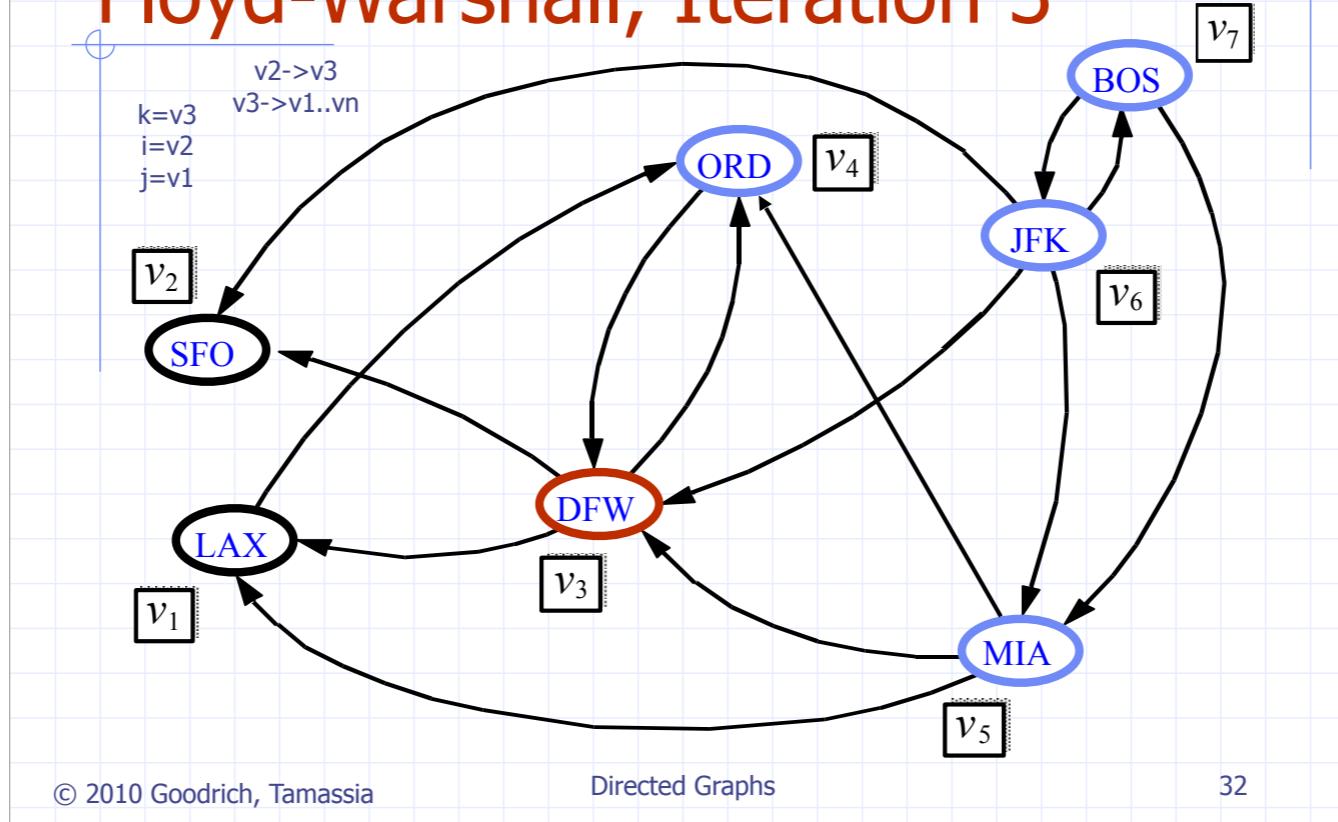
Floyd-Warshall, Iteration 2



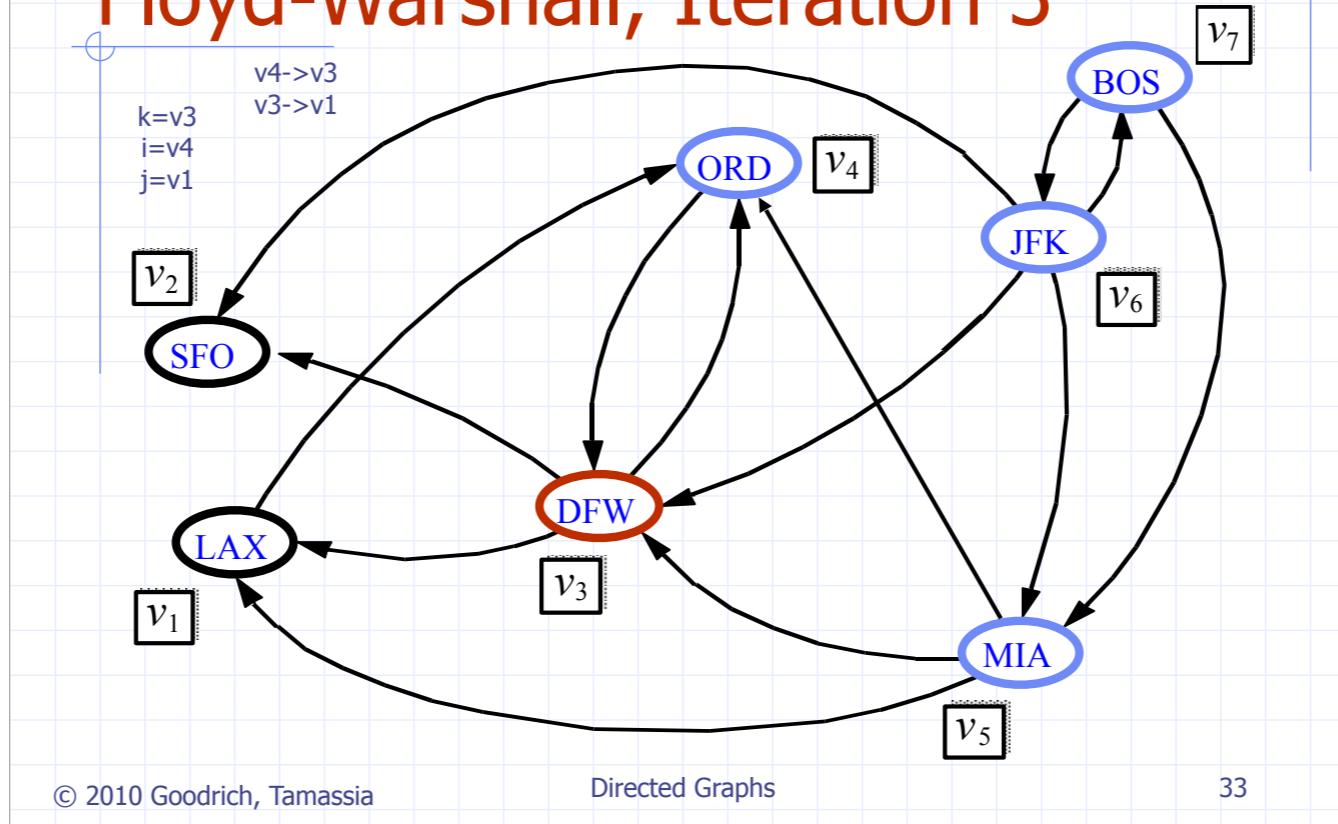
Floyd-Warshall, Iteration 3



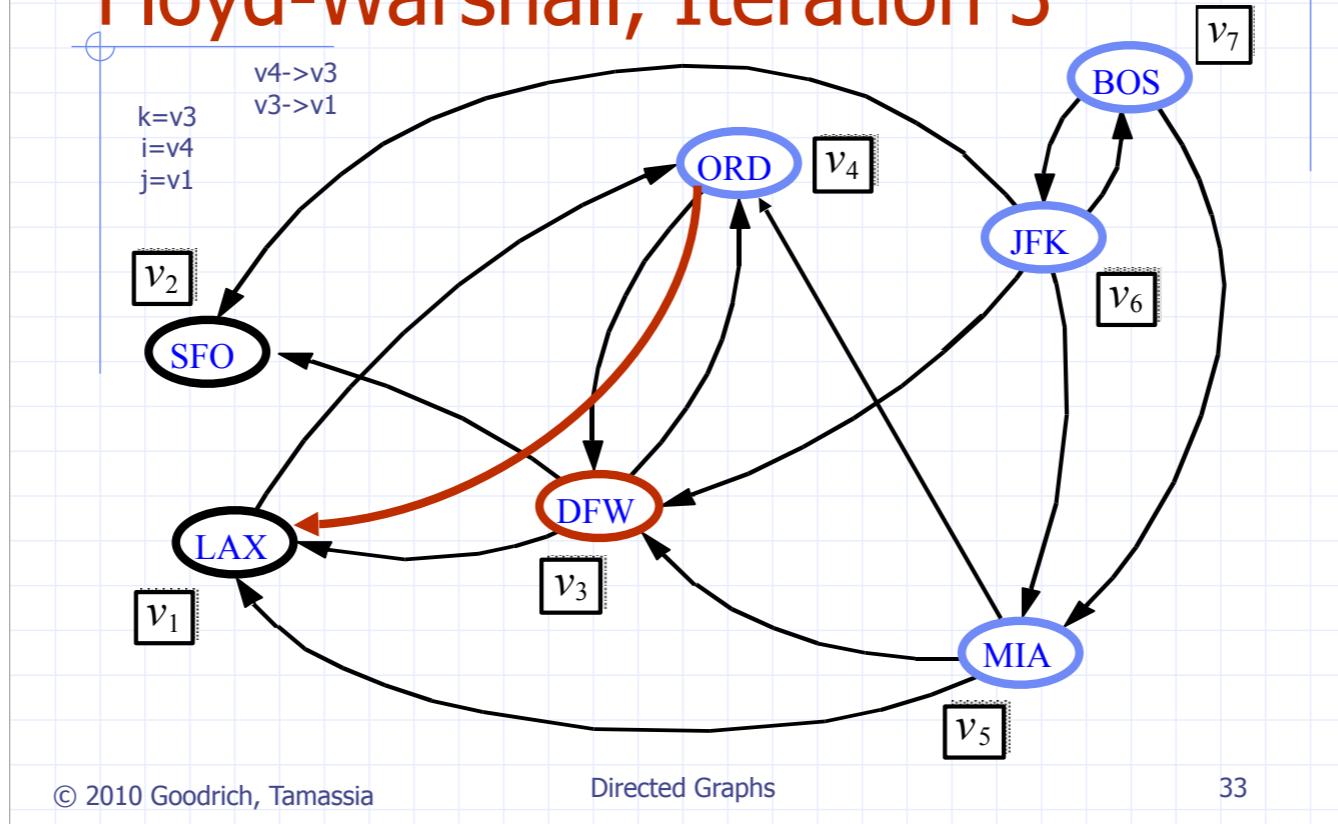
Floyd-Warshall, Iteration 3



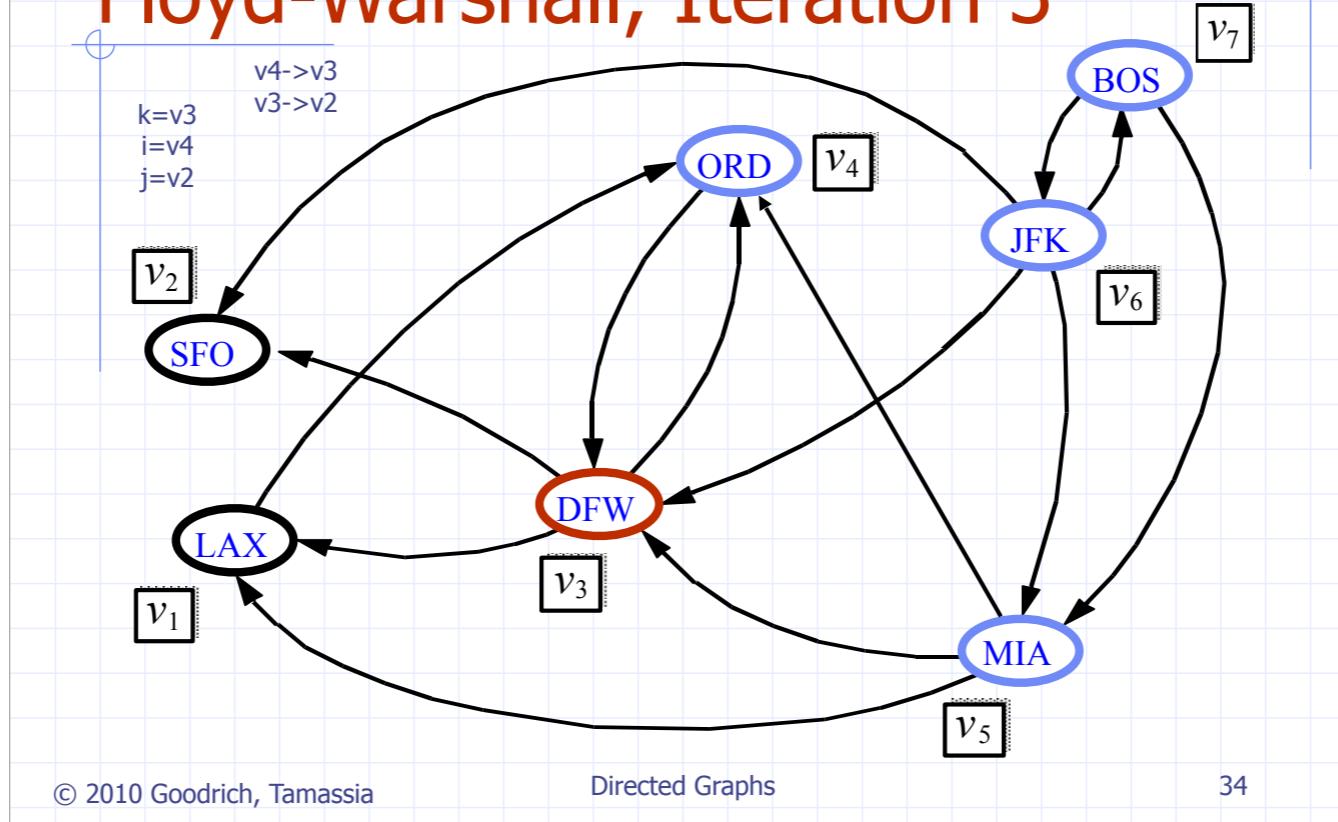
Floyd-Warshall, Iteration 3



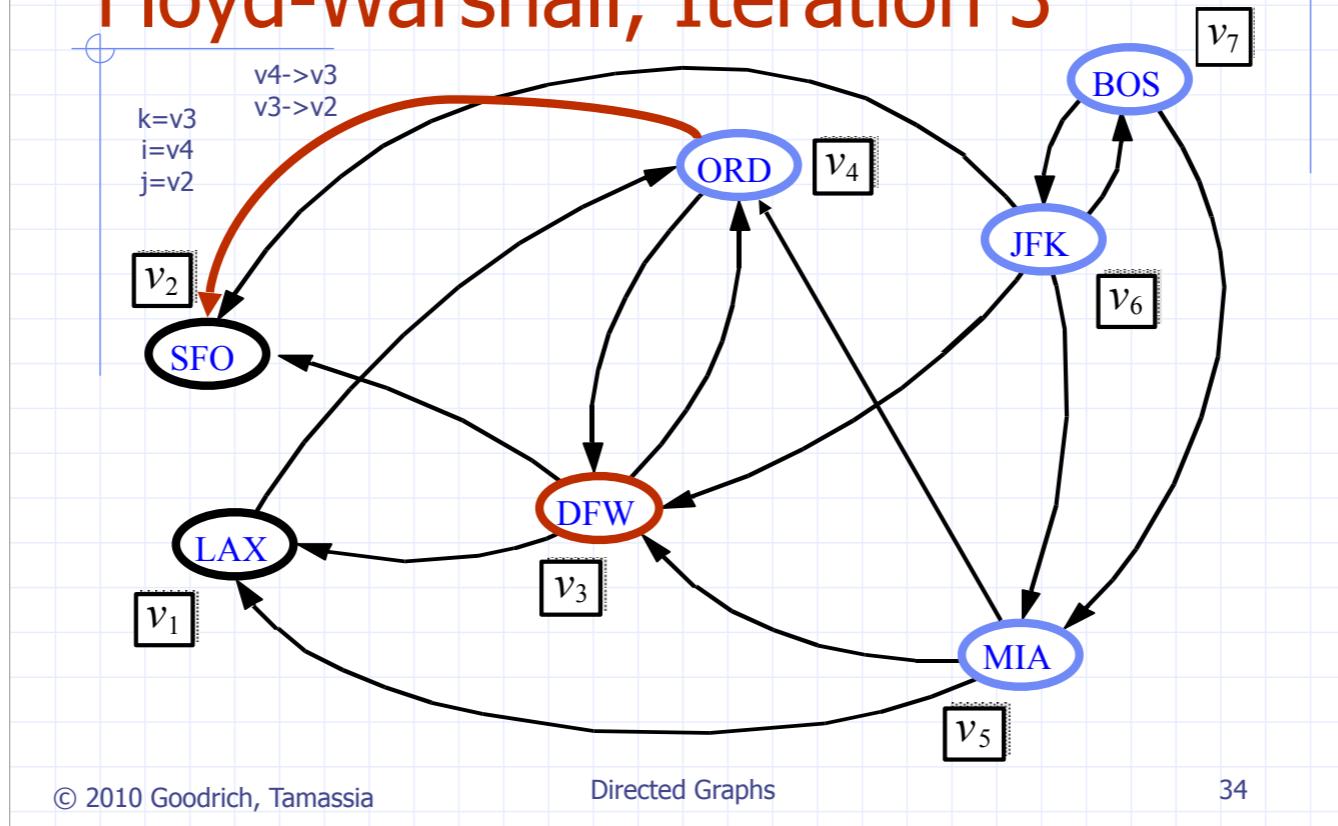
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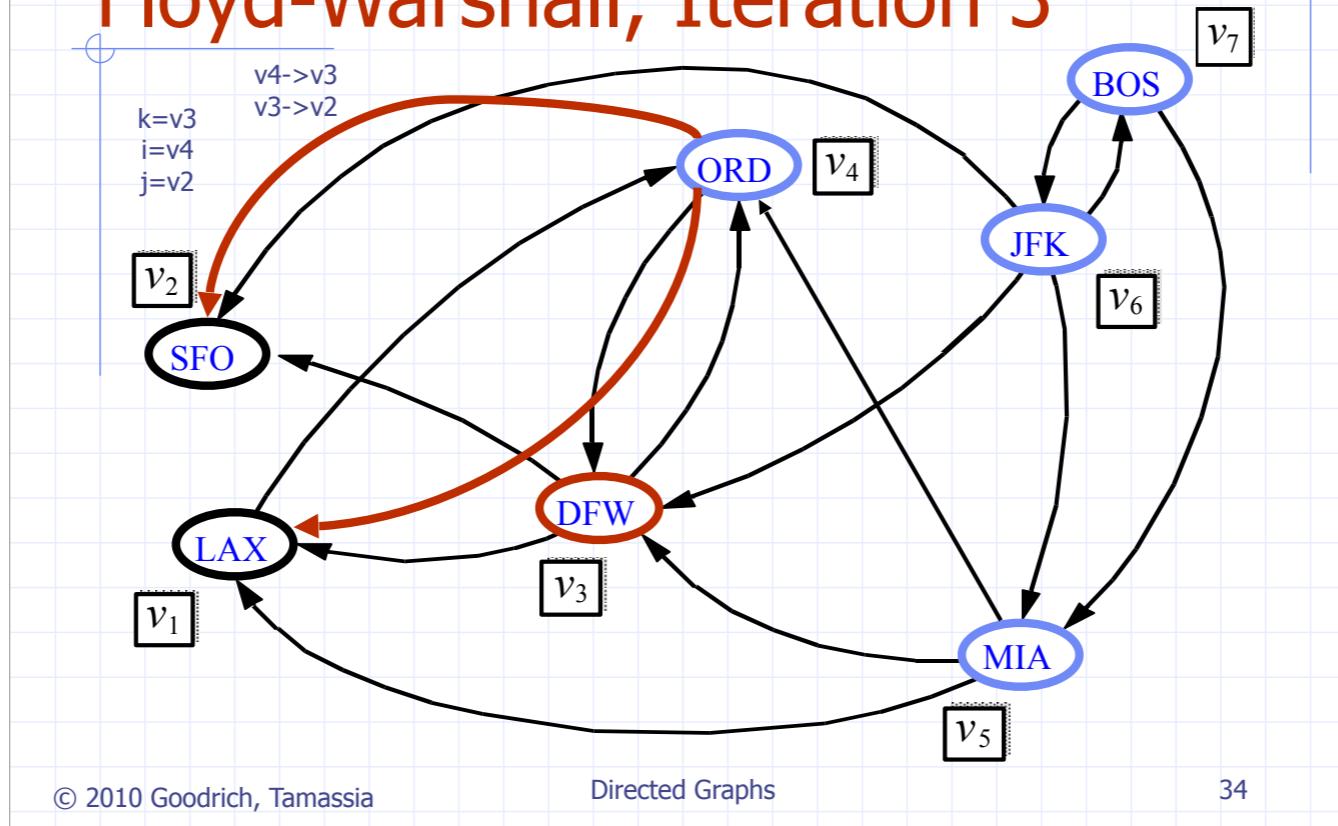
Floyd-Warshall, Iteration 3



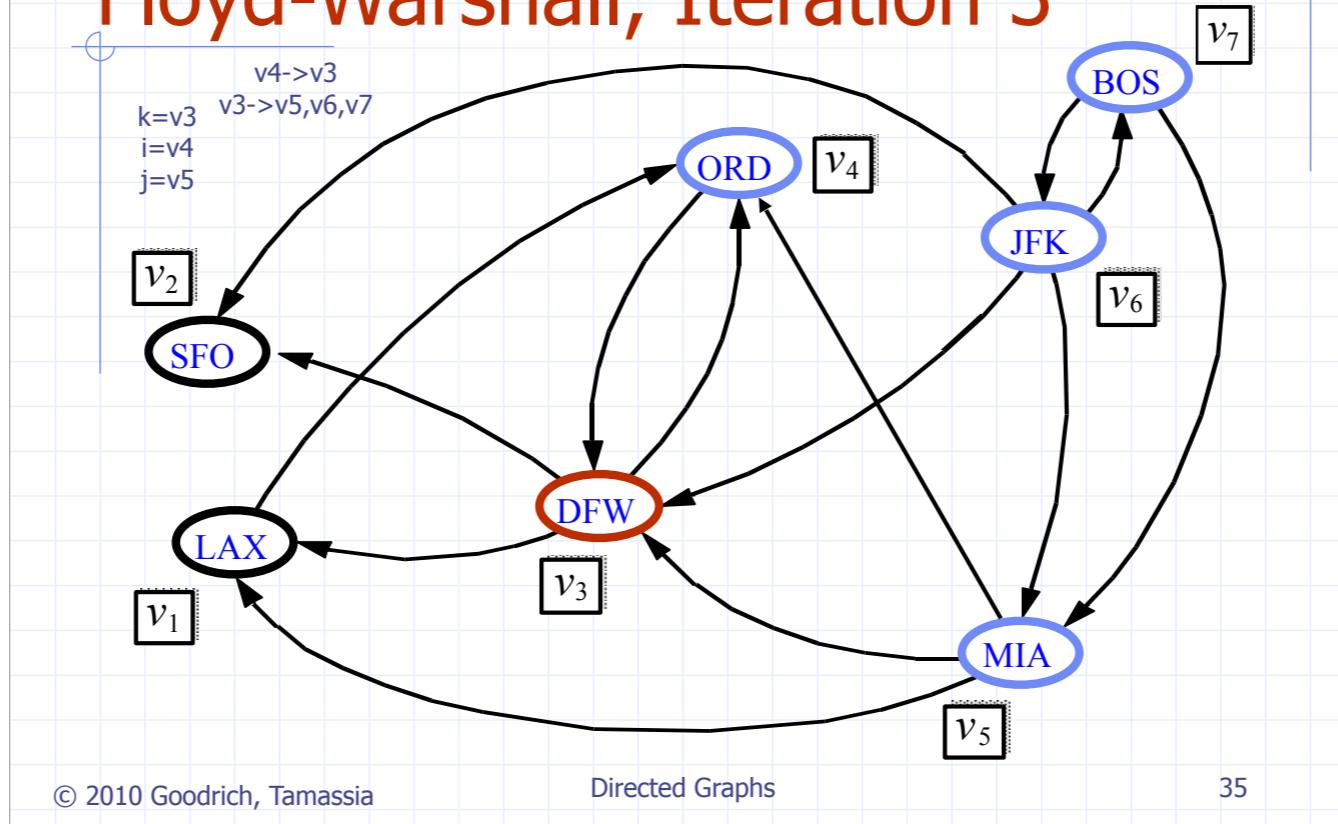
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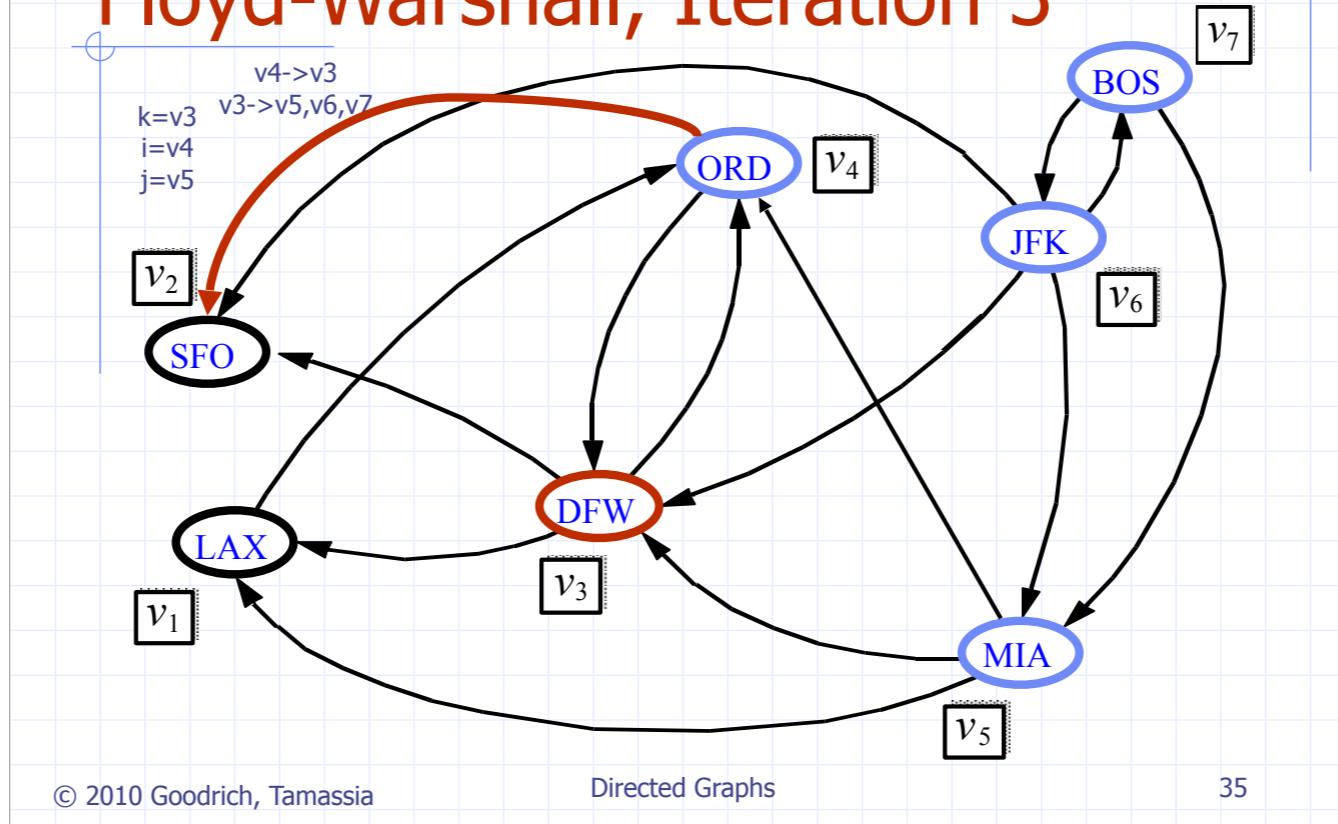
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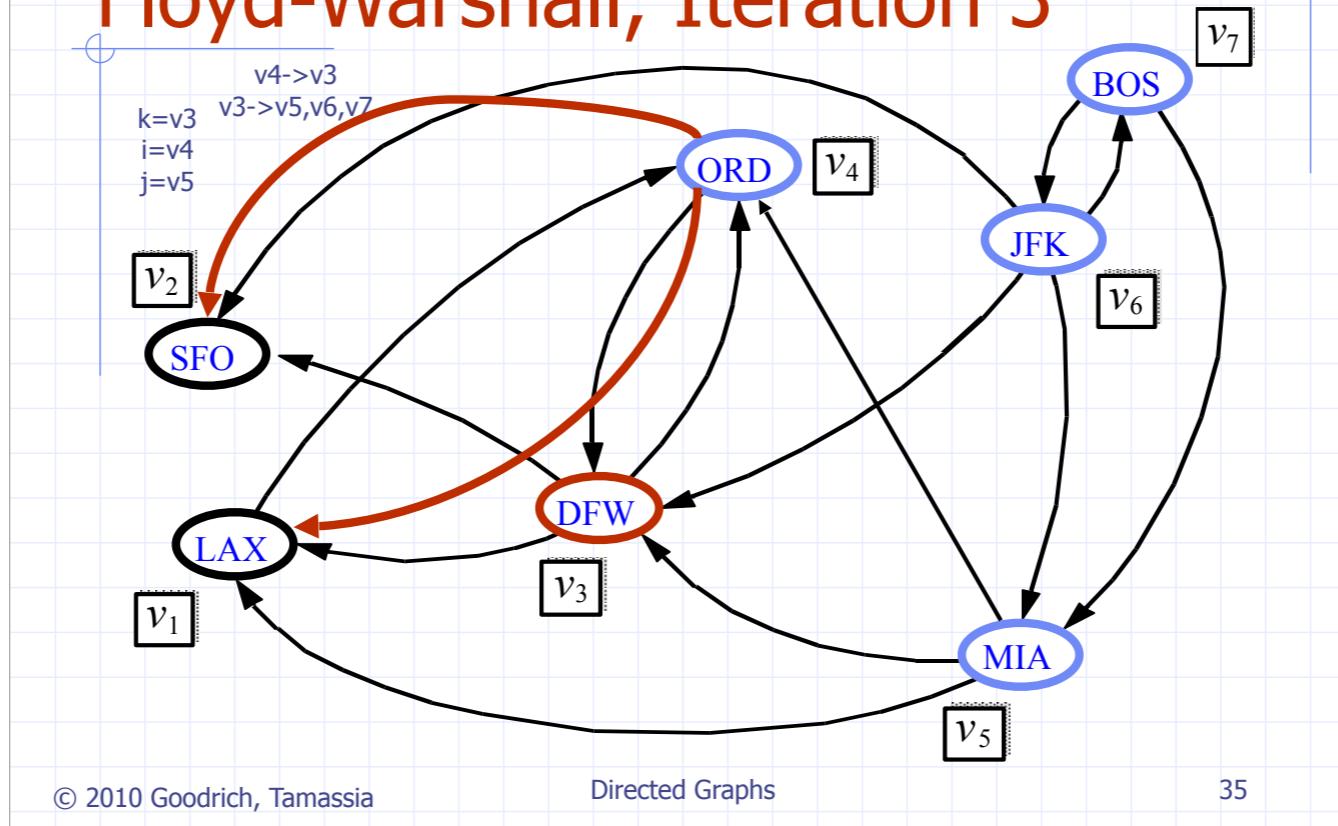
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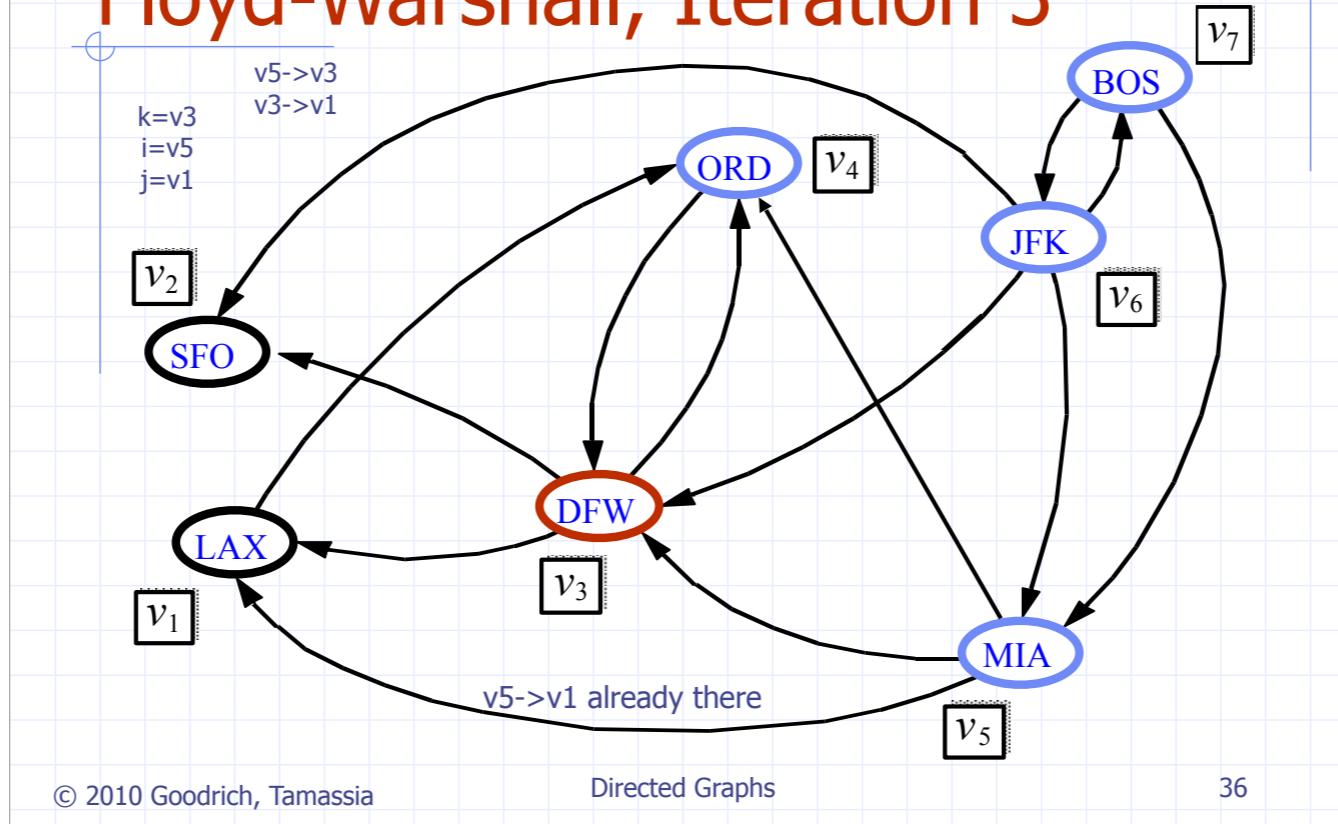
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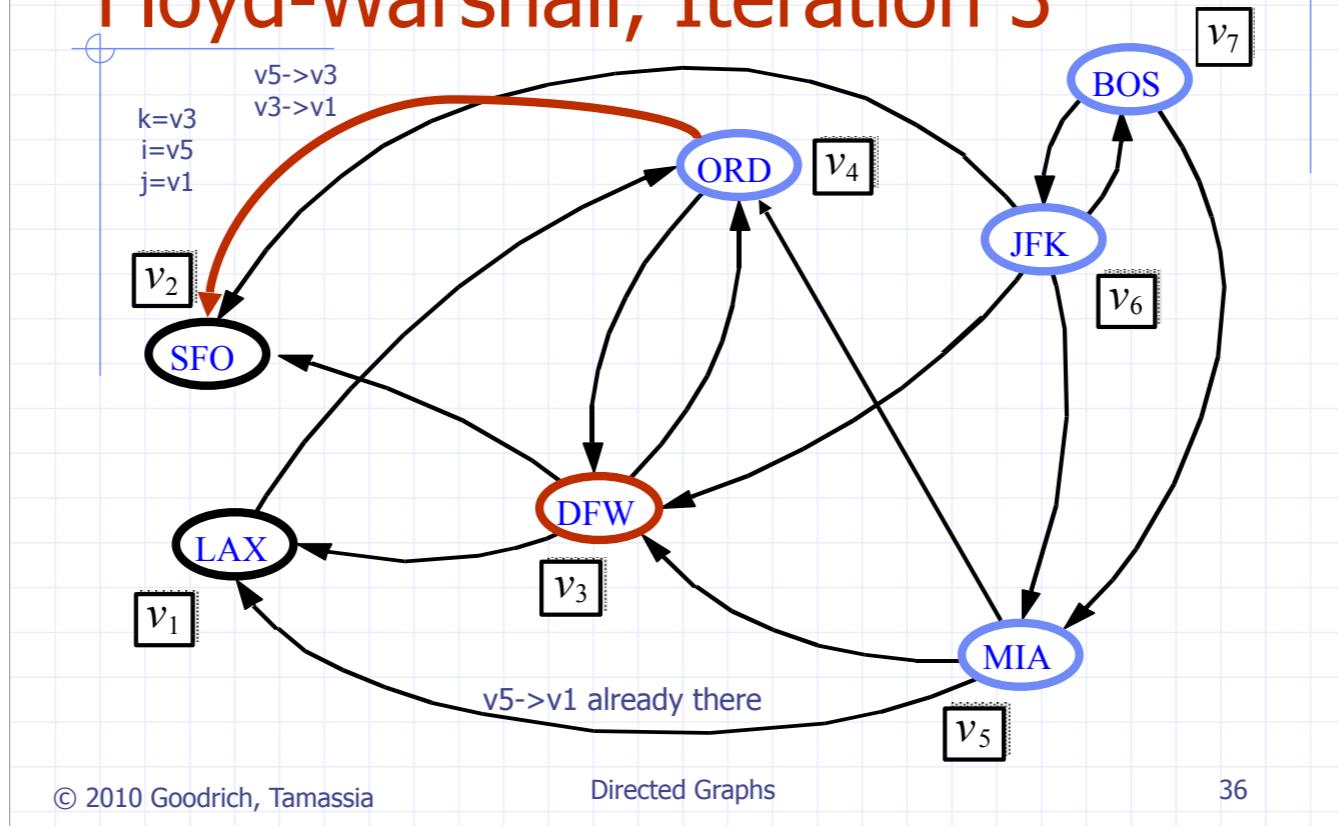
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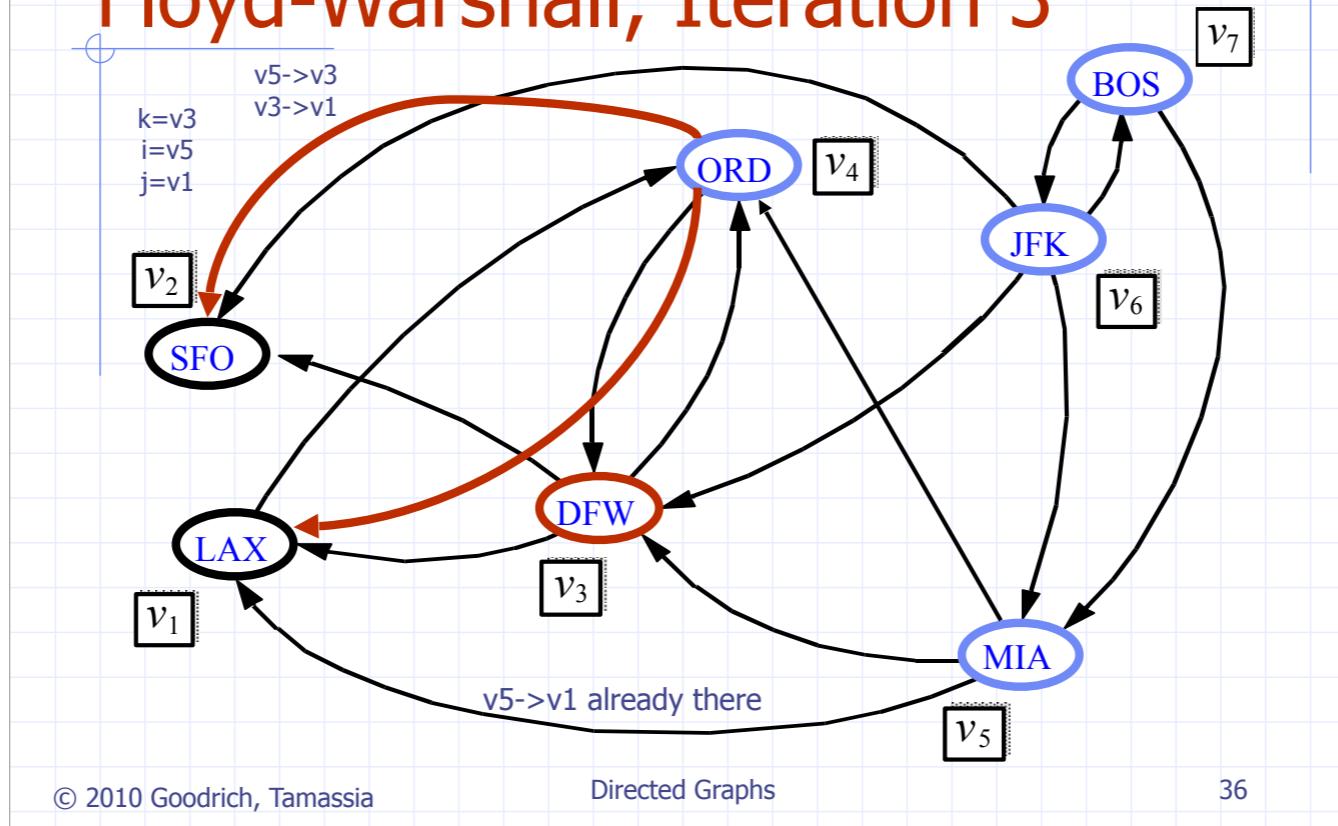
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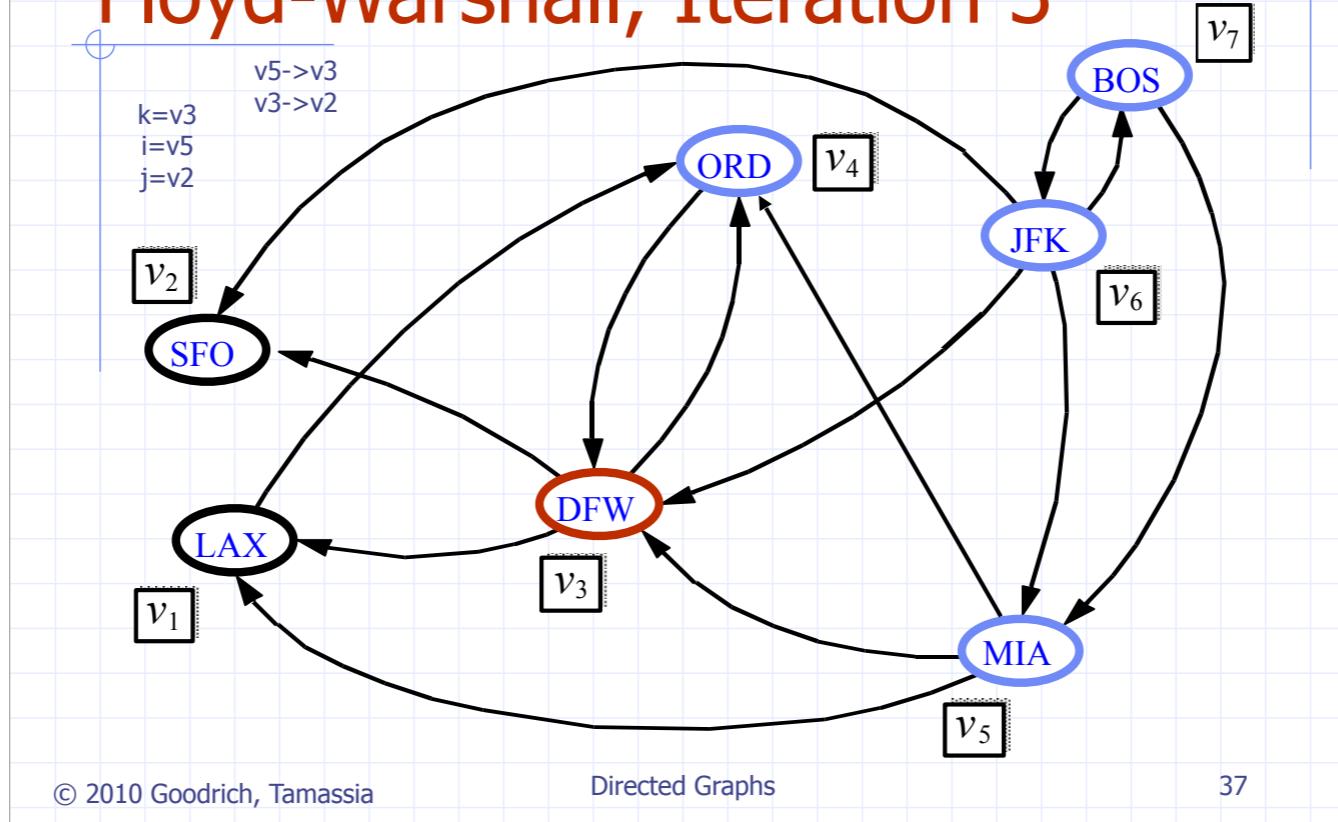
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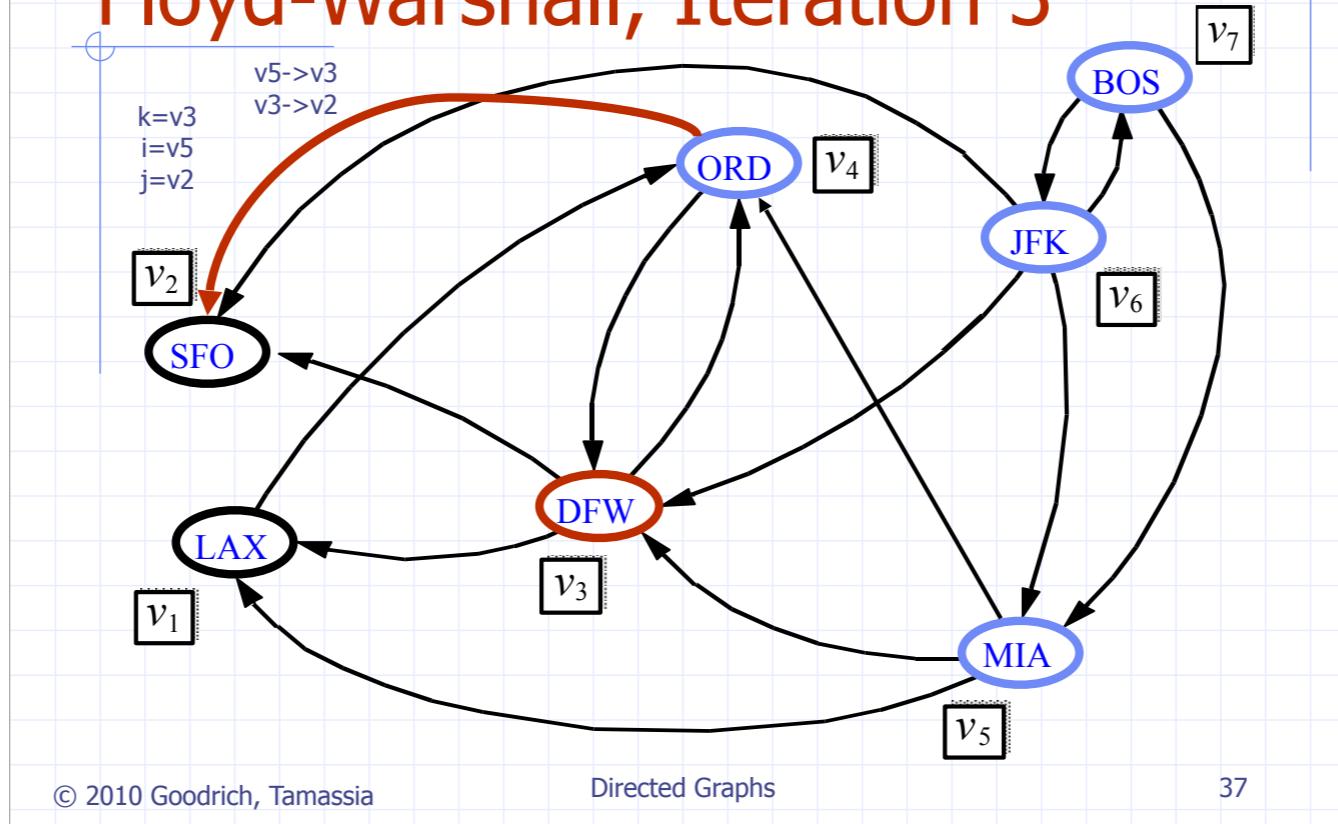
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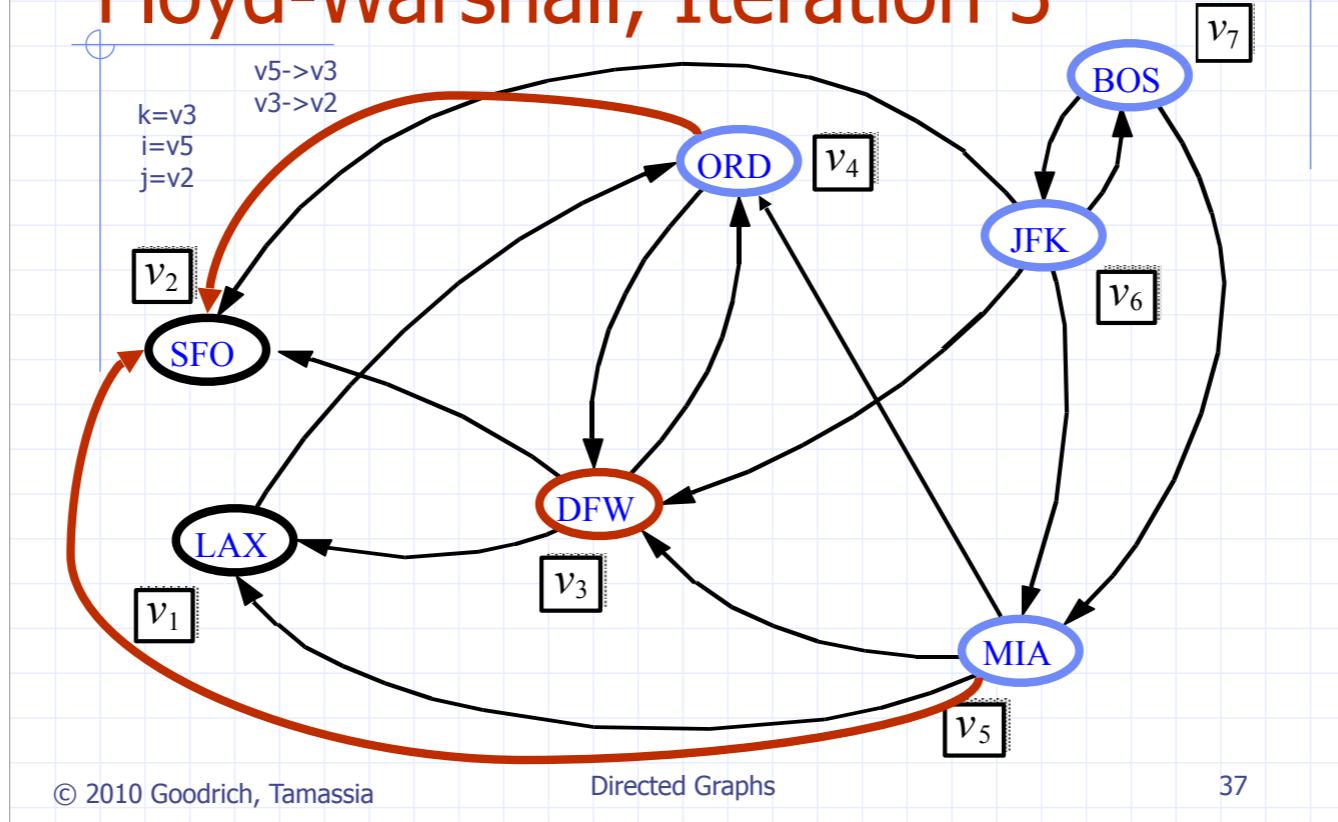
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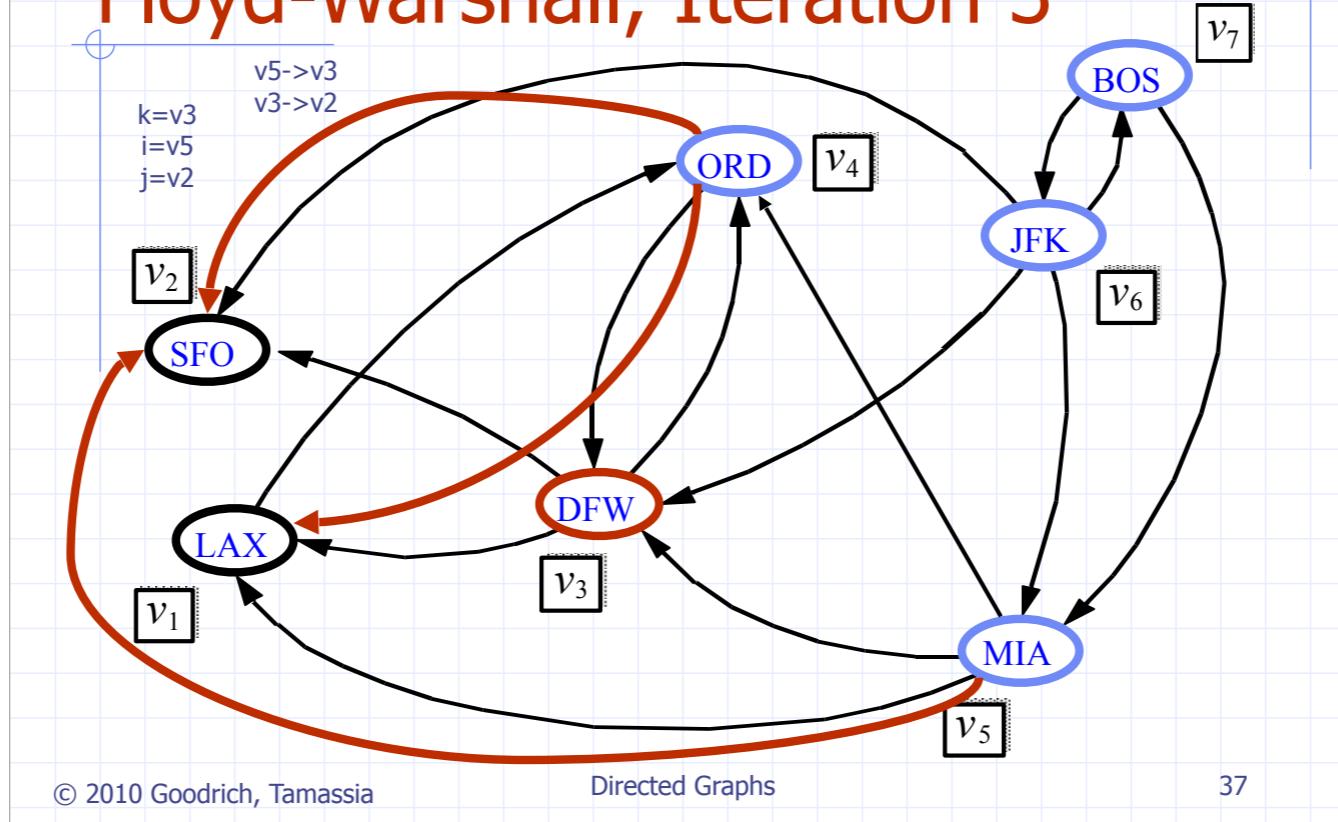
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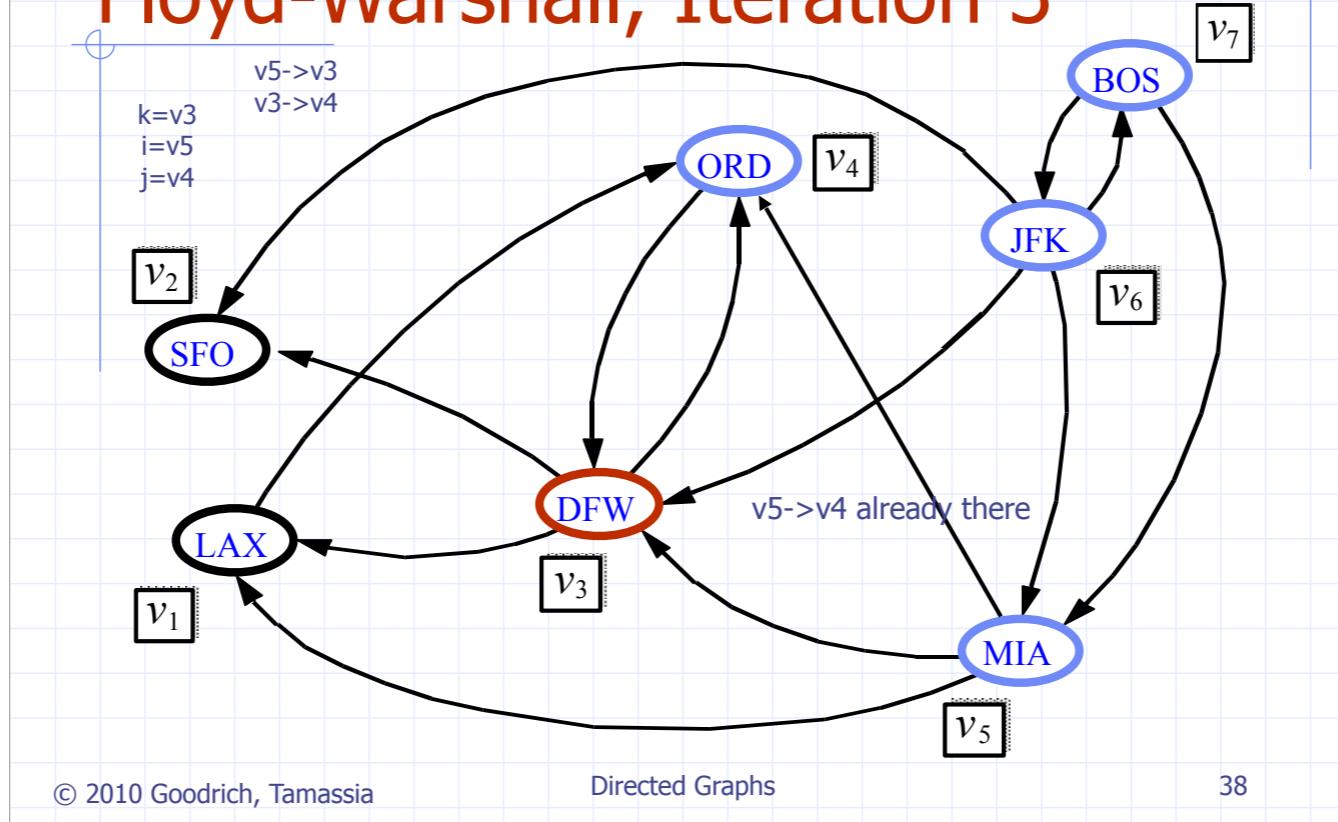
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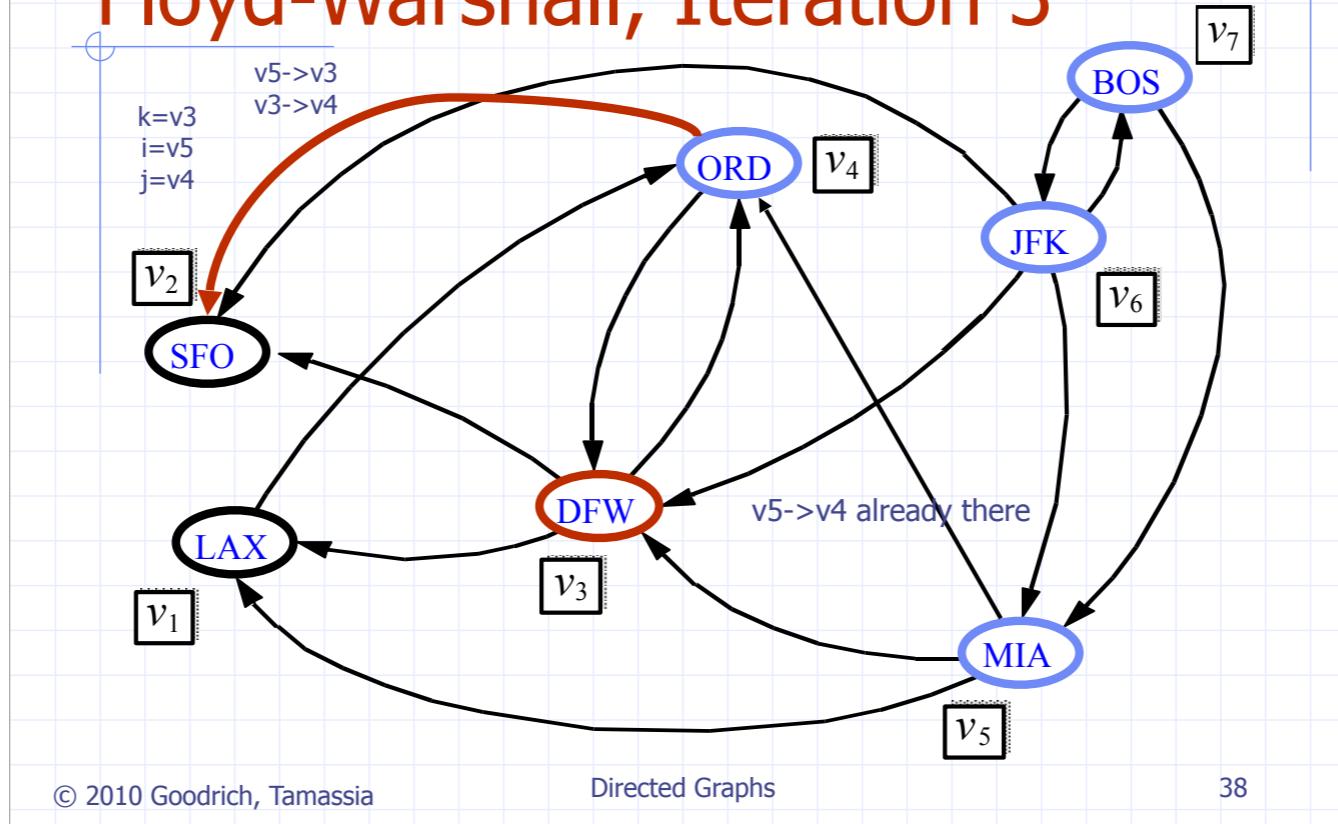
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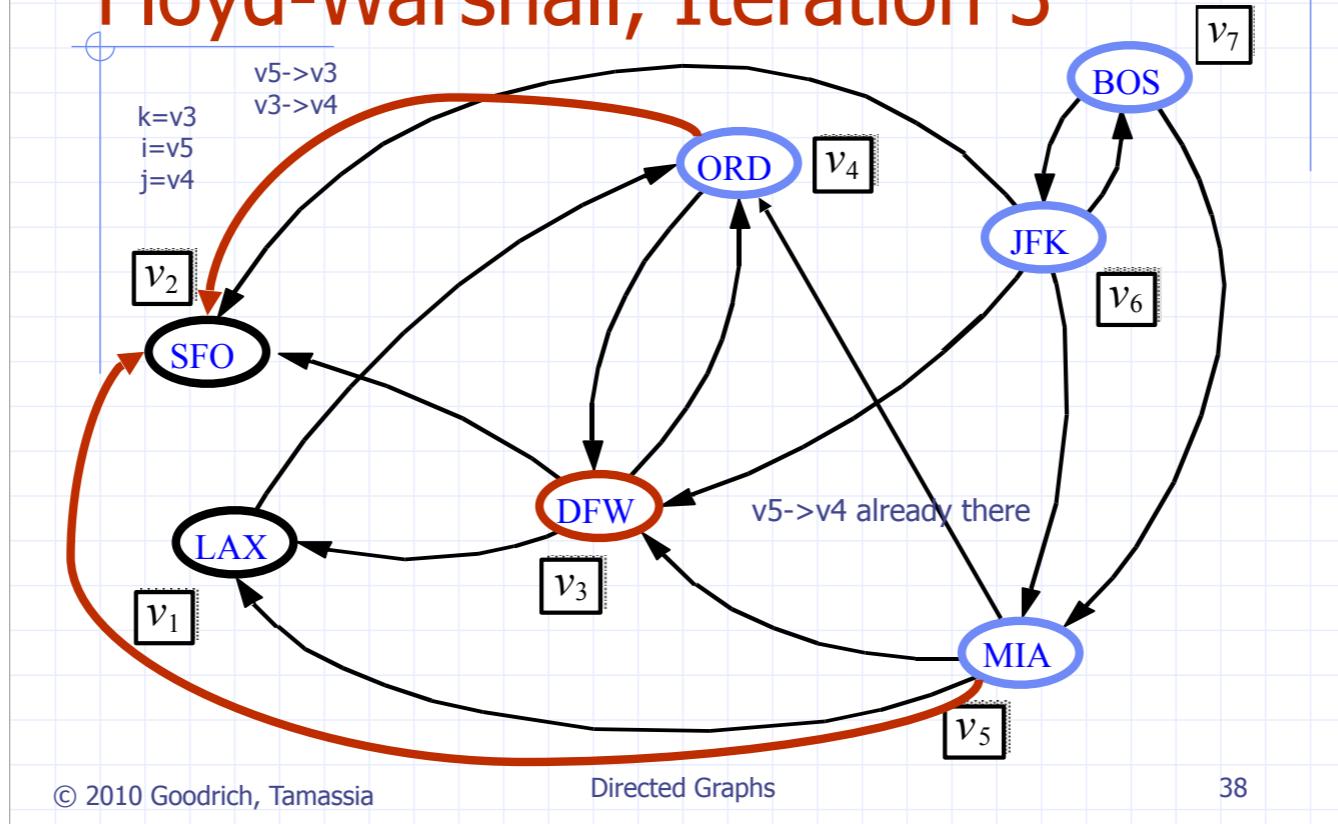
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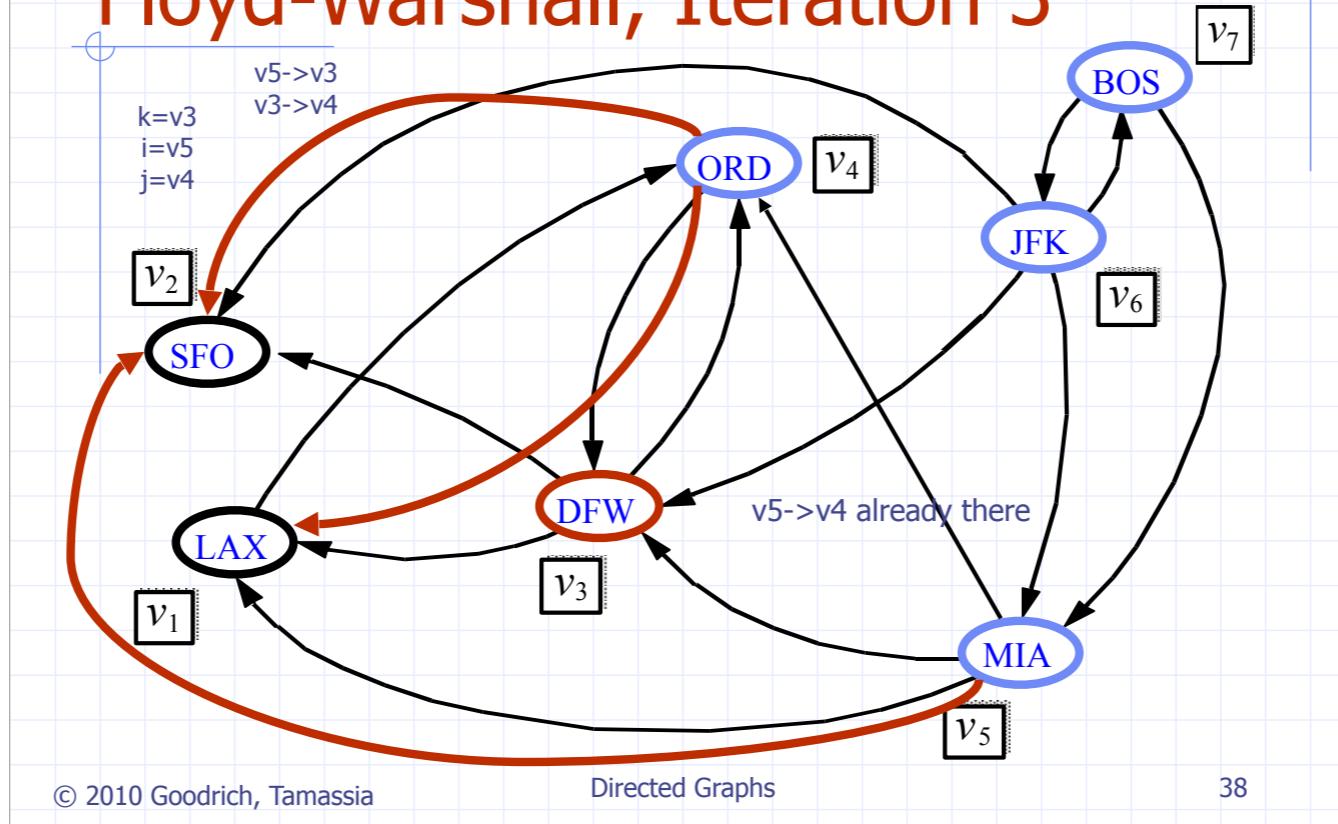
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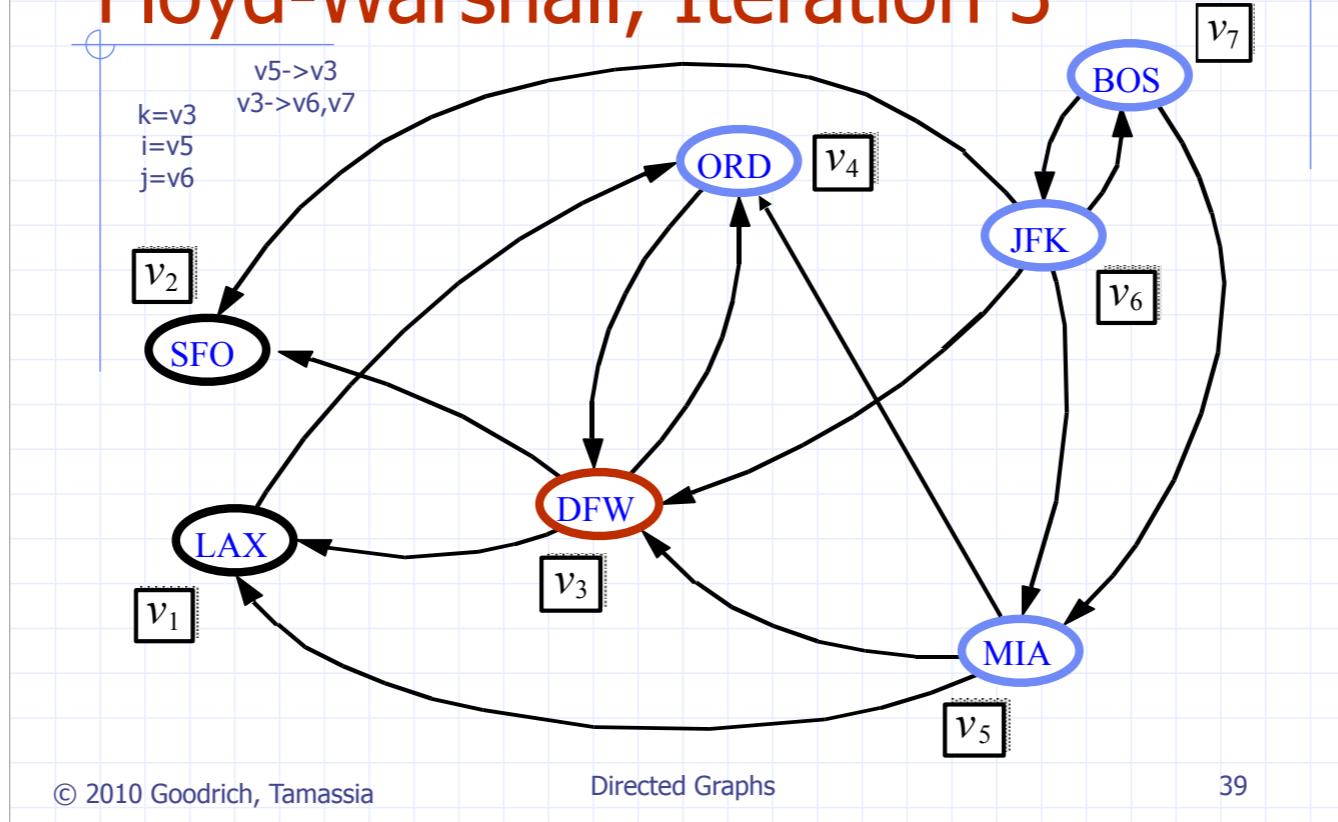
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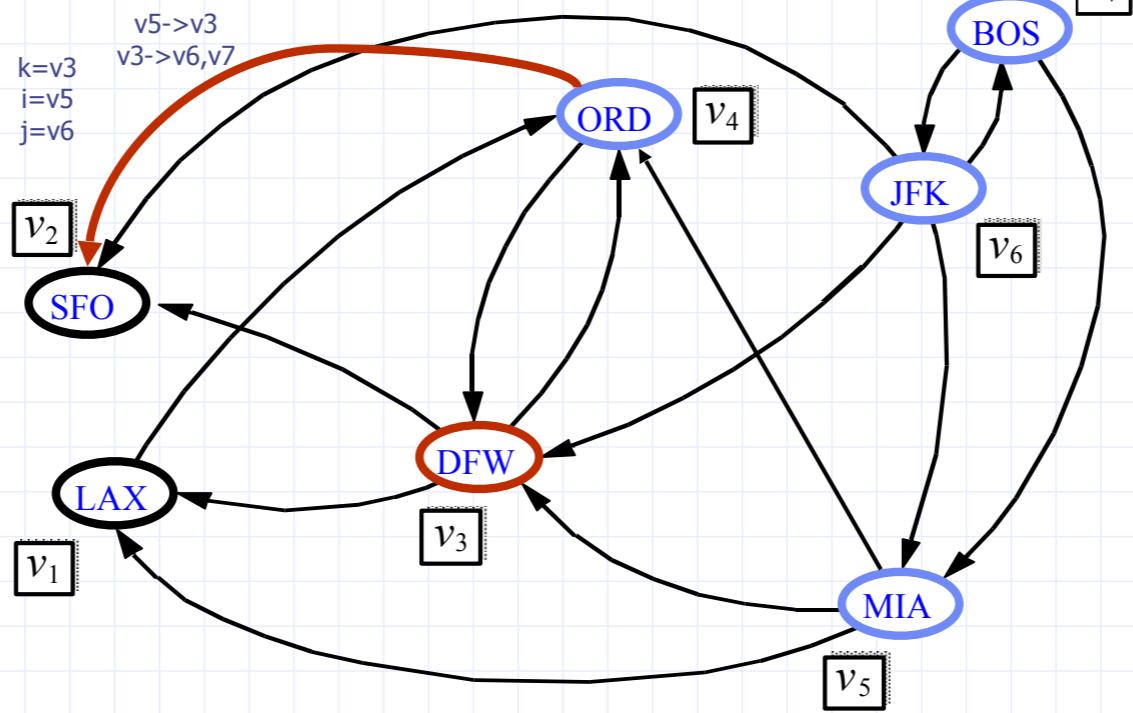
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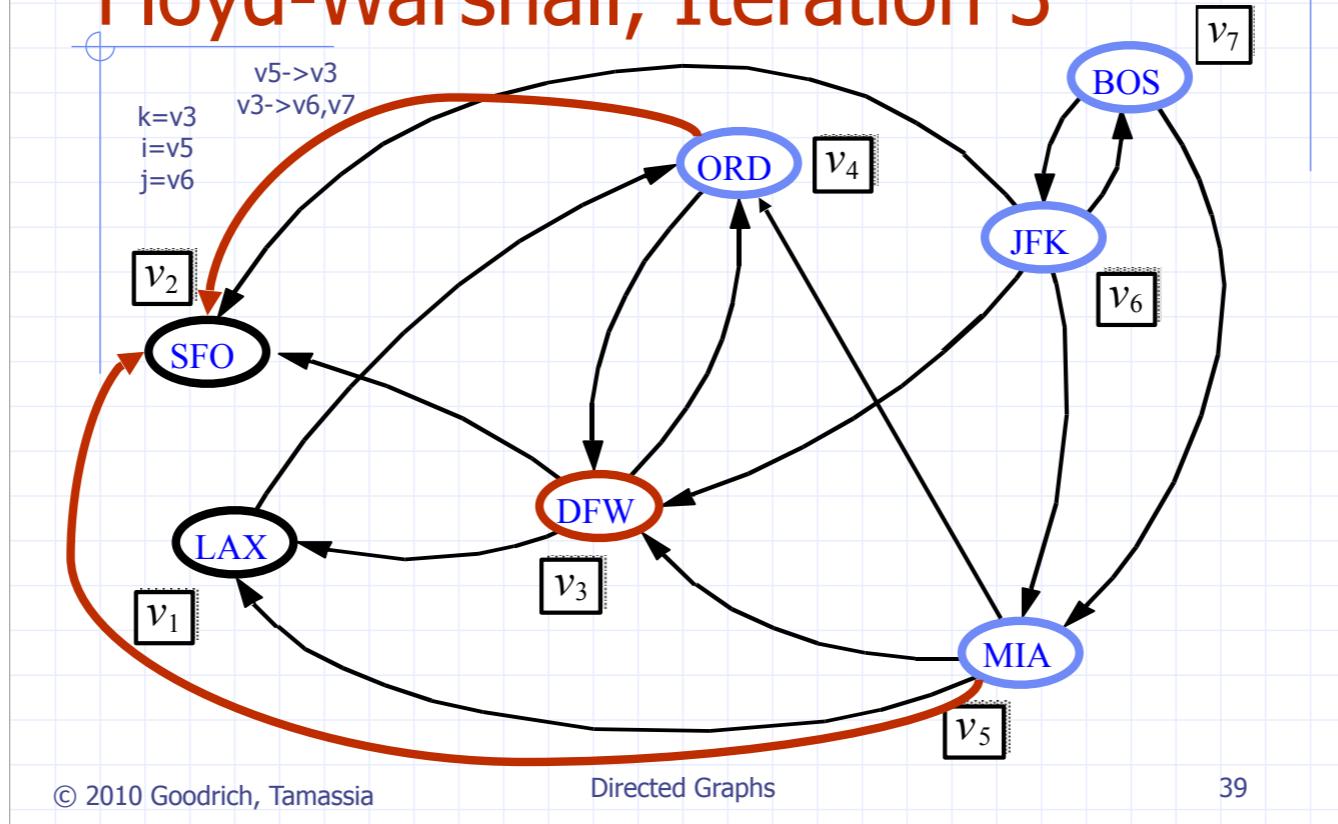
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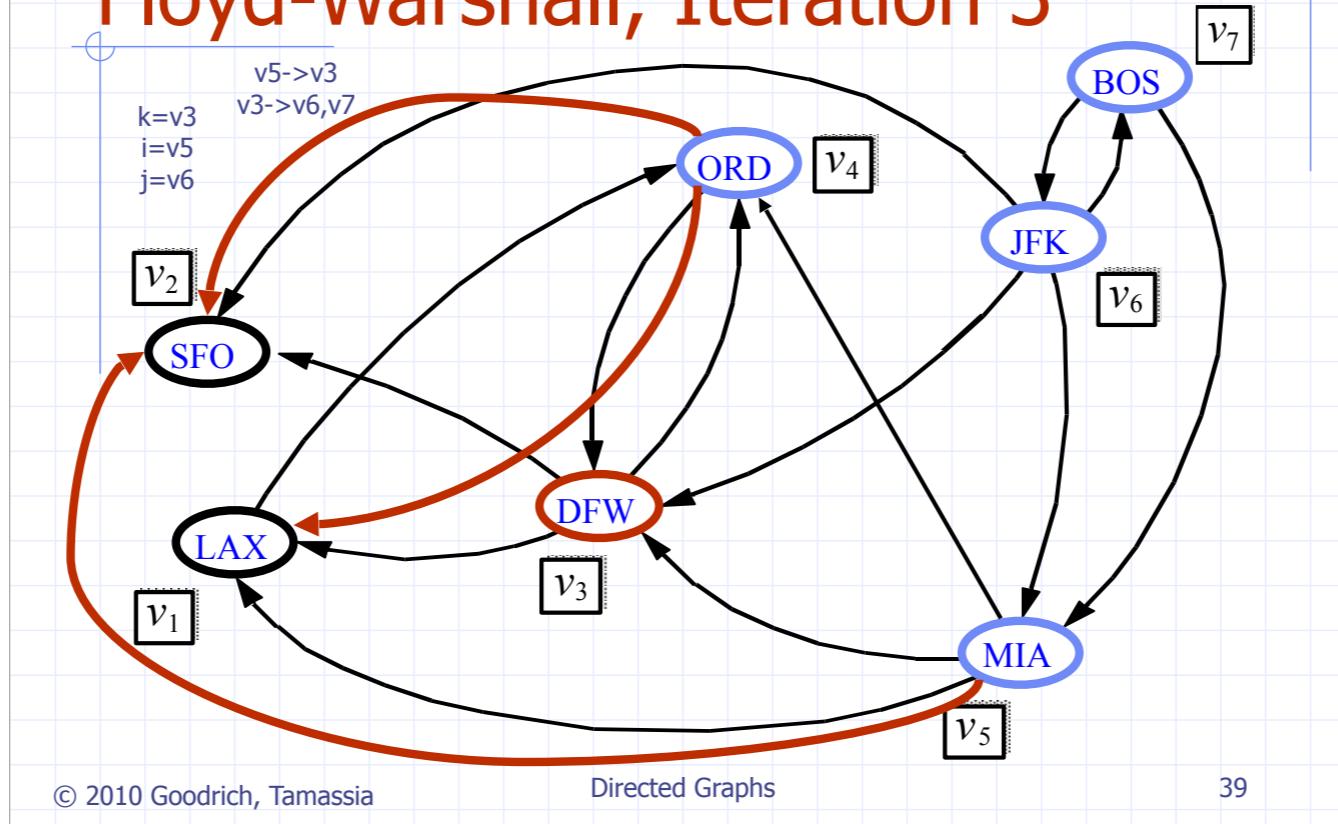
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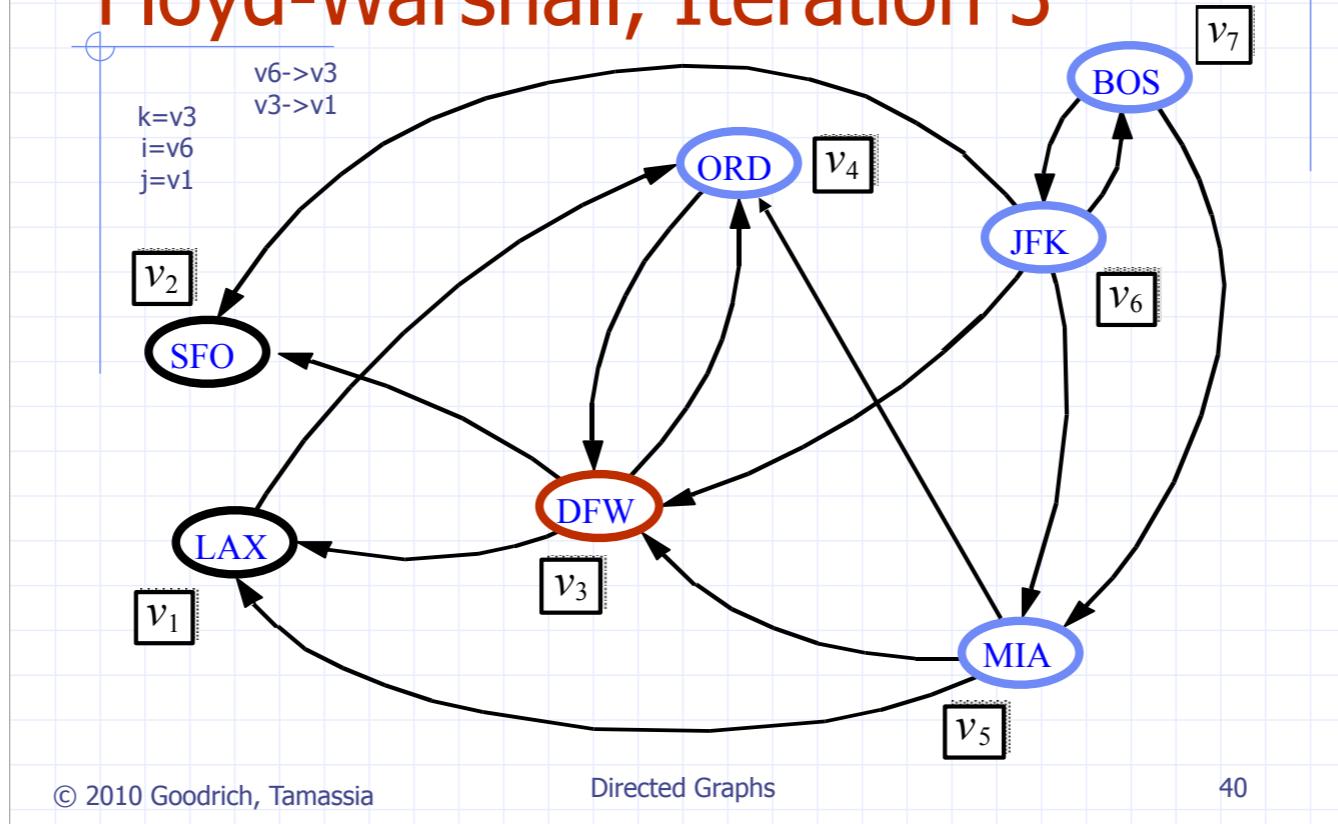
Floyd-Warshall, Iteration 3



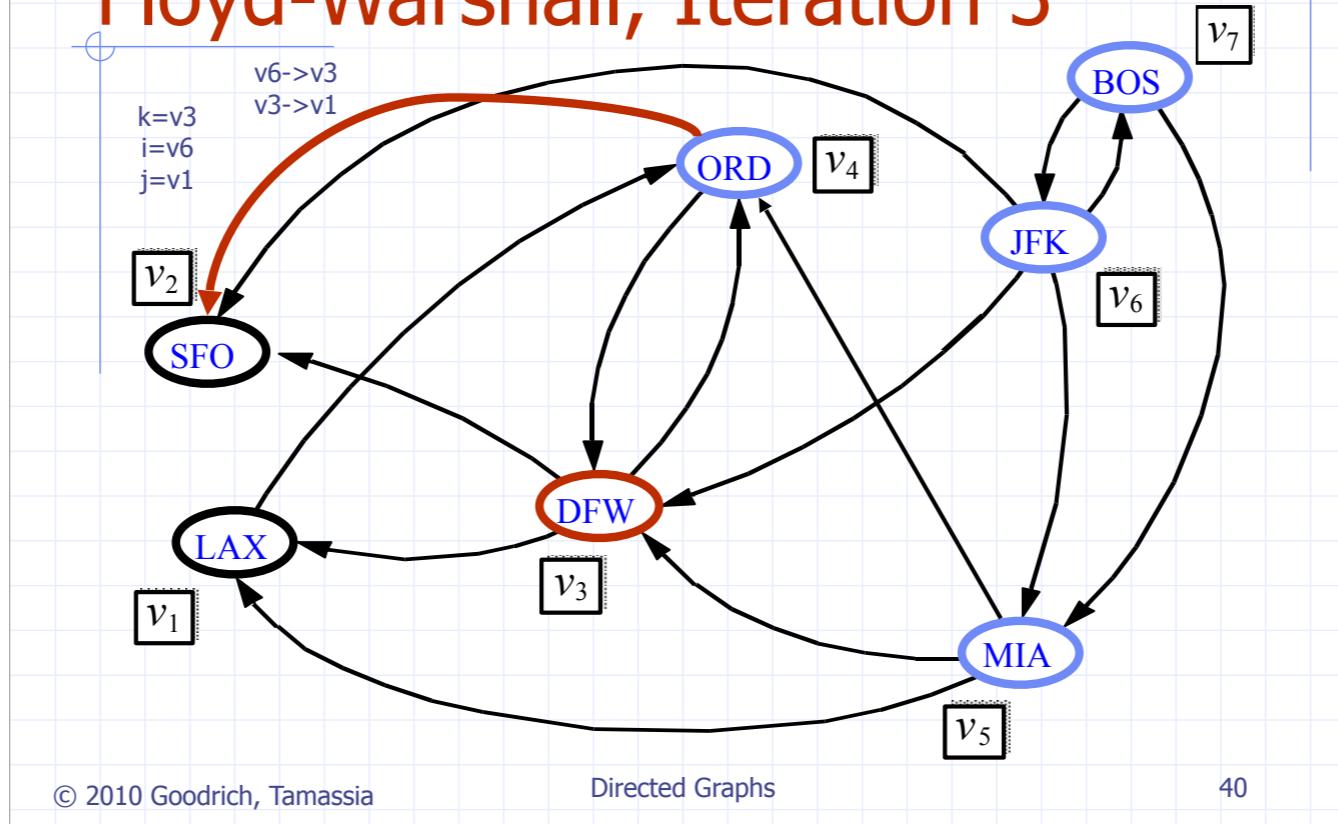
Floyd-Warshall, Iteration 3



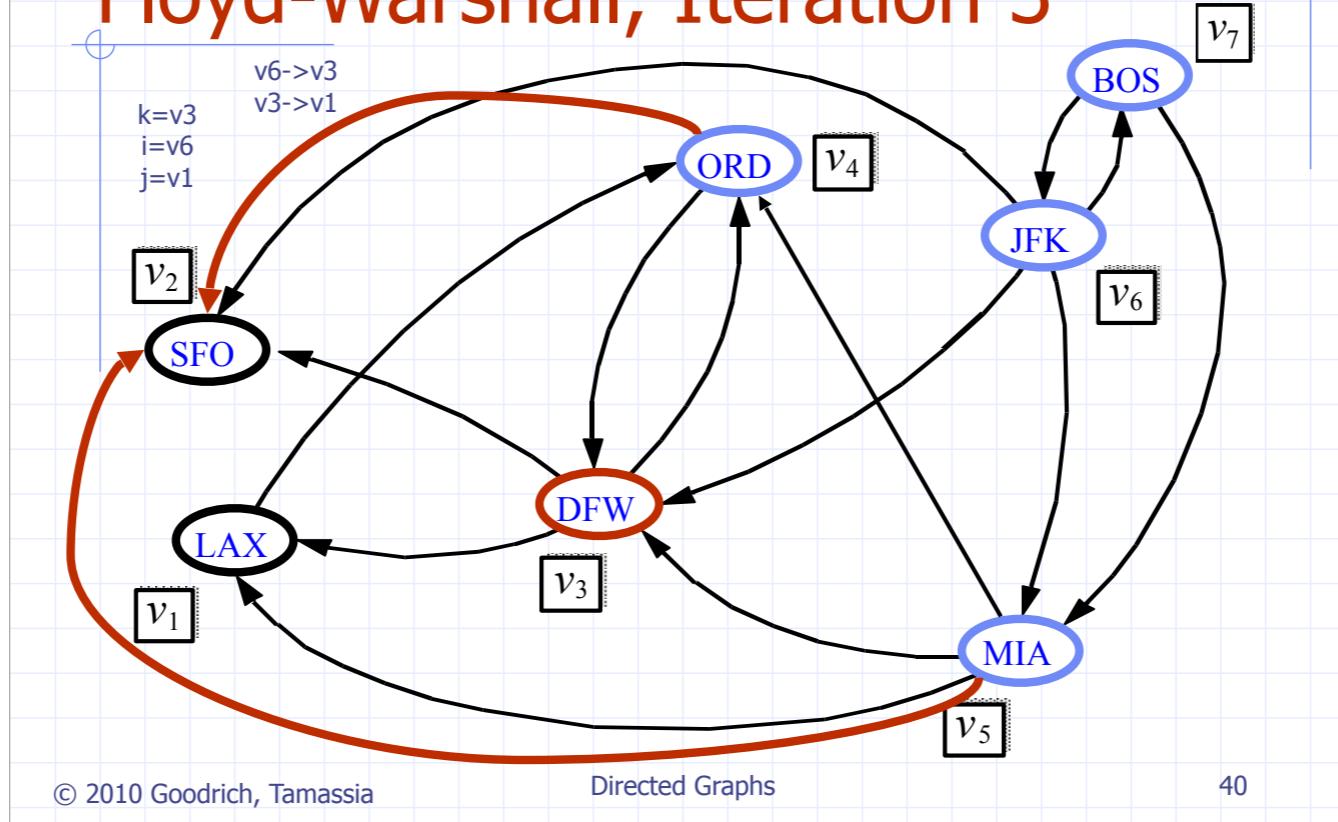
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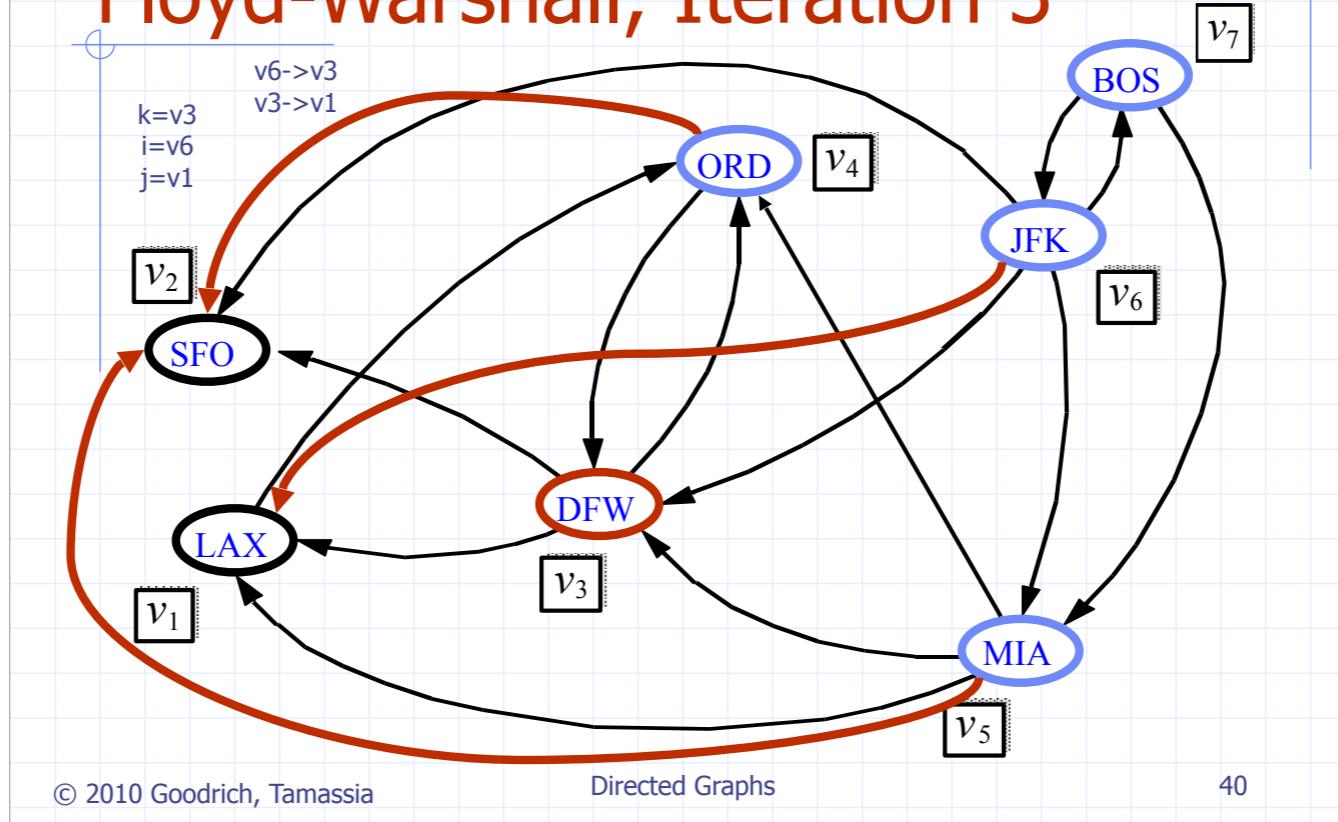
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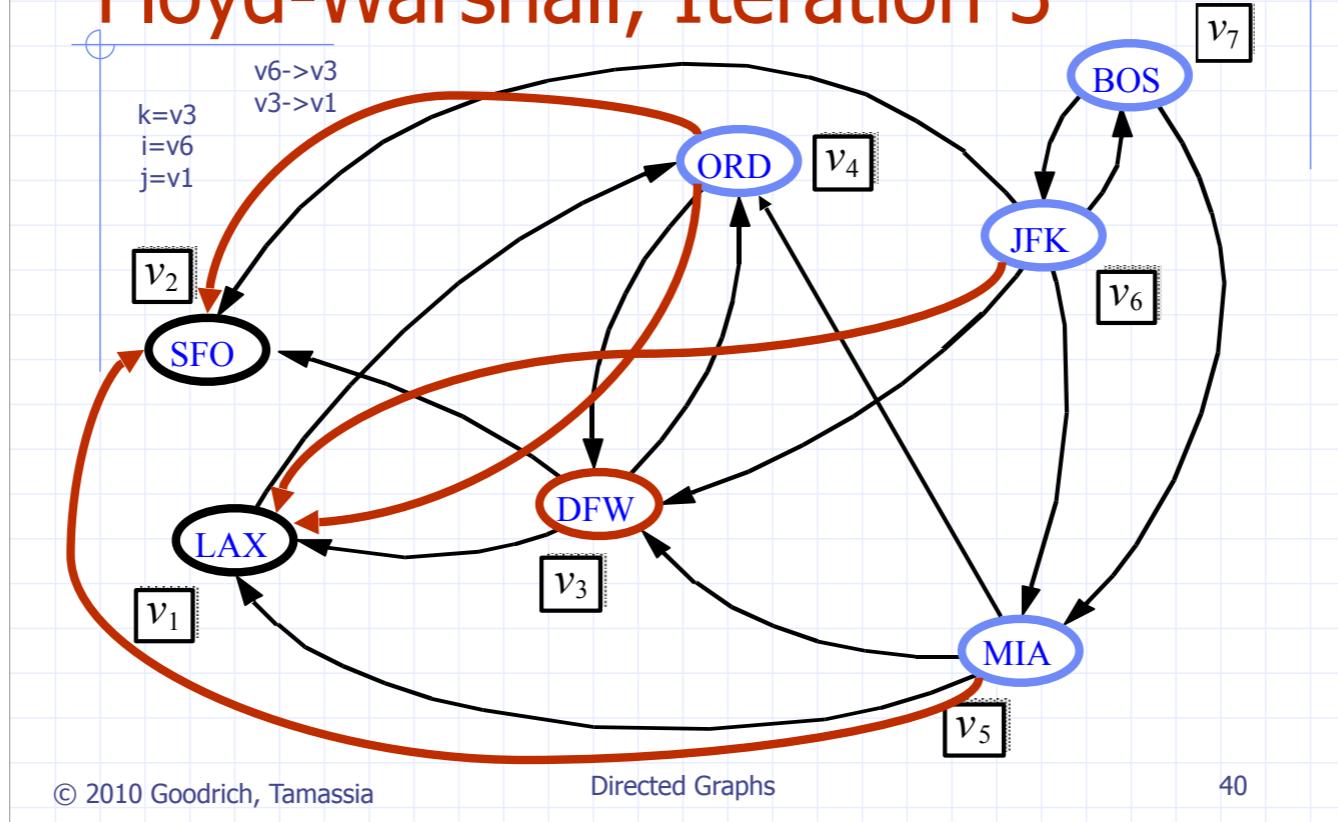
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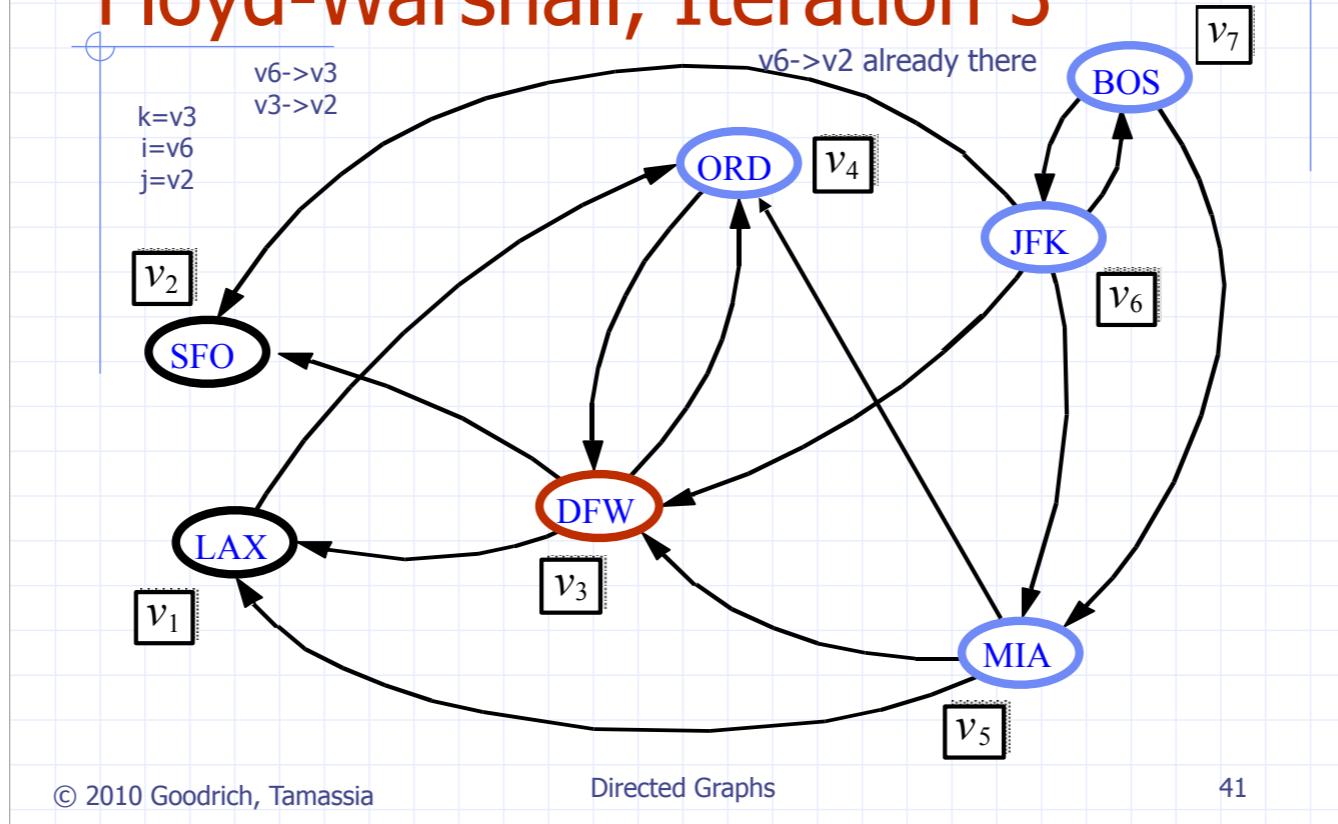
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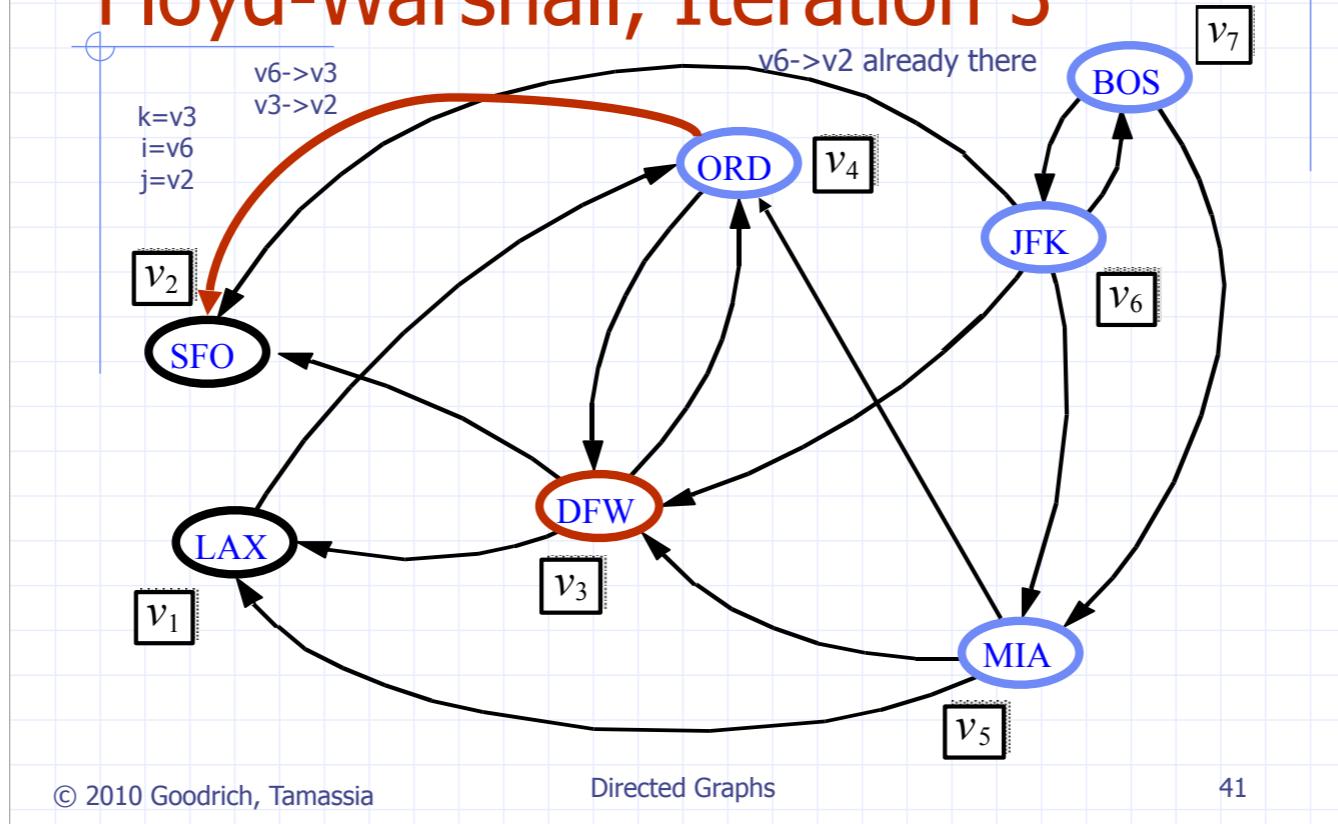
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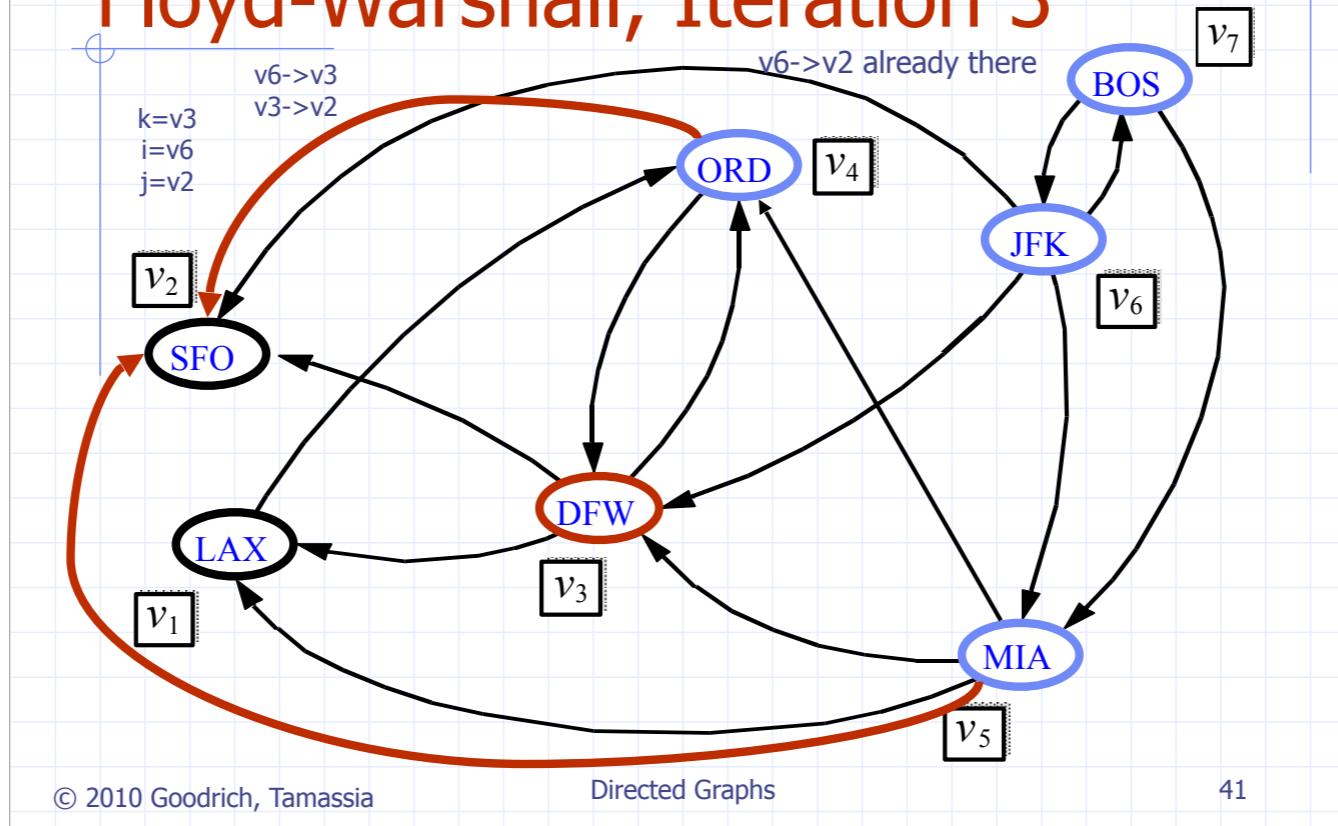
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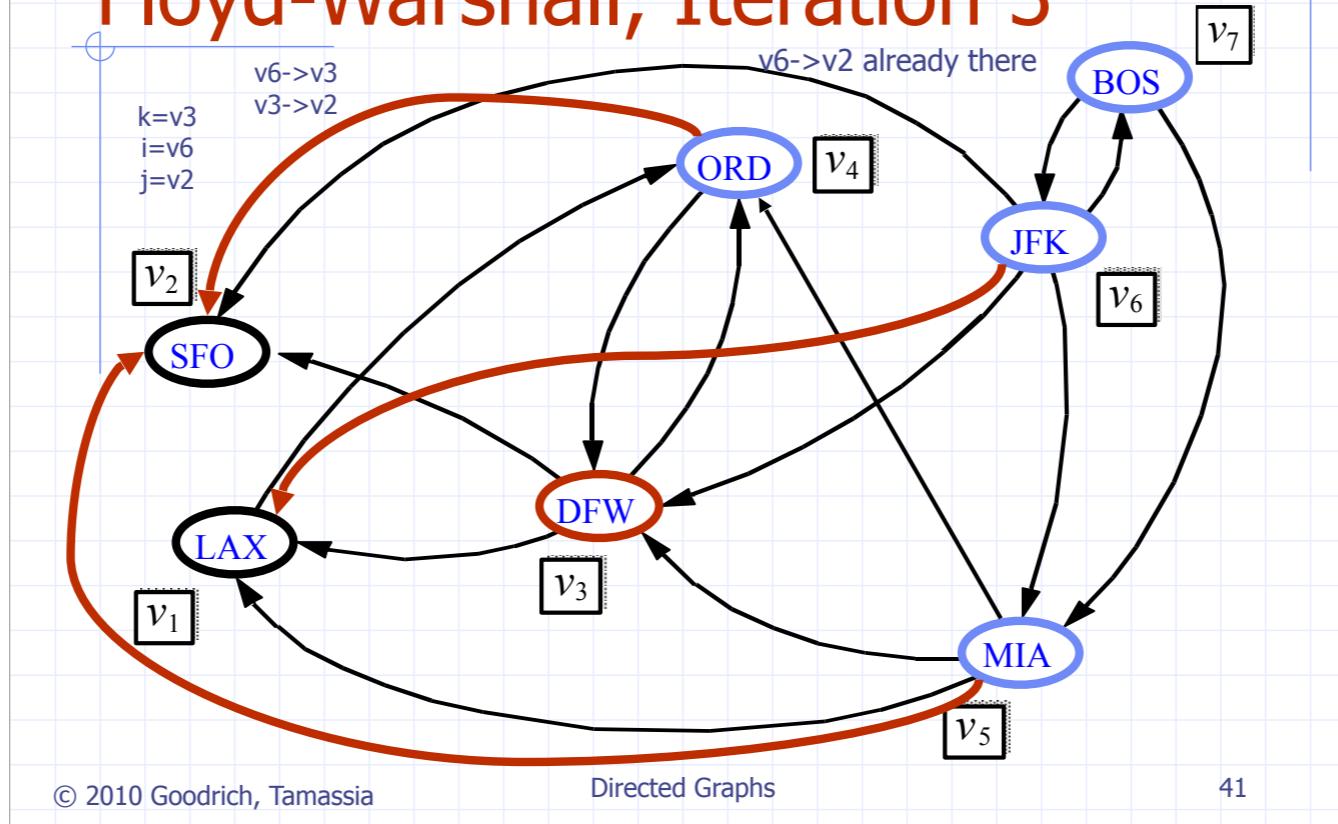
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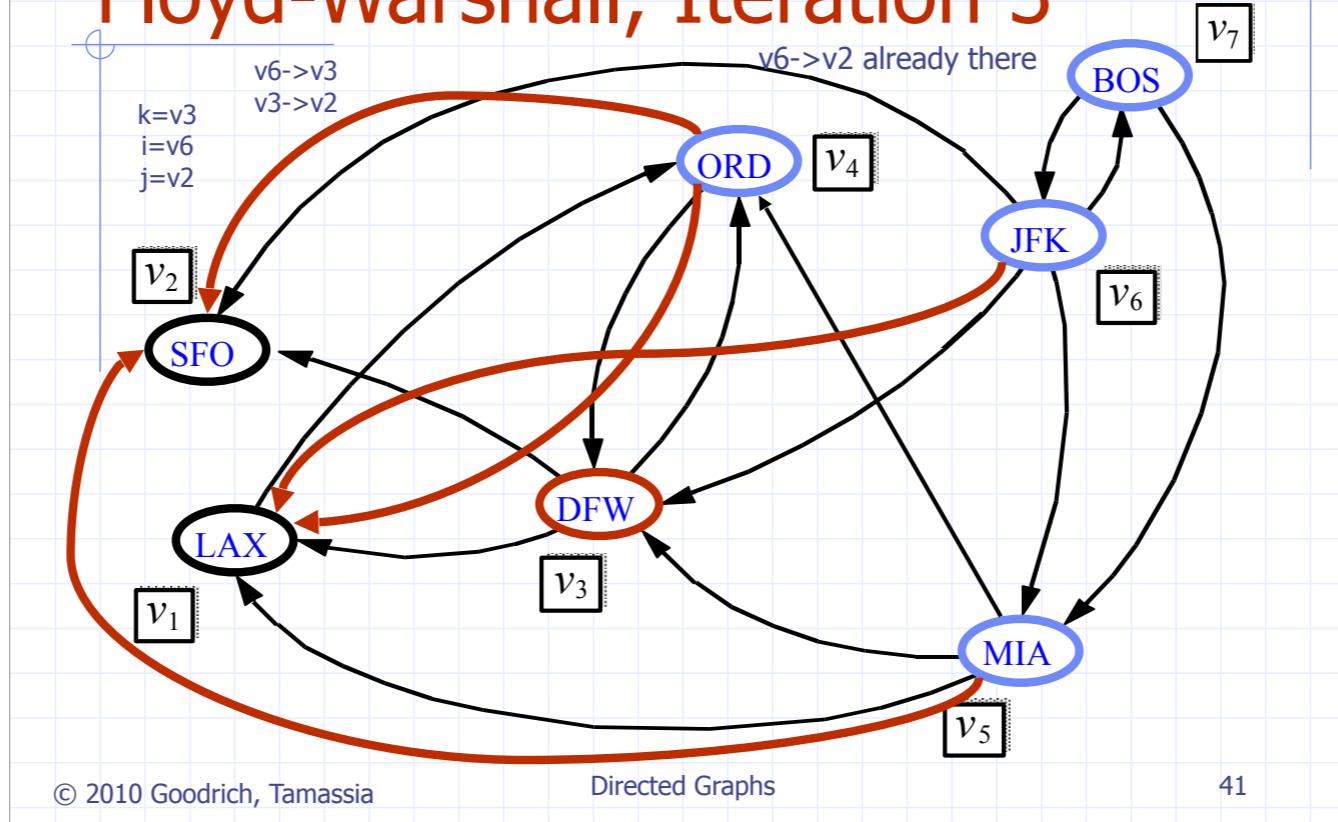
Floyd-Warshall, Iteration 3



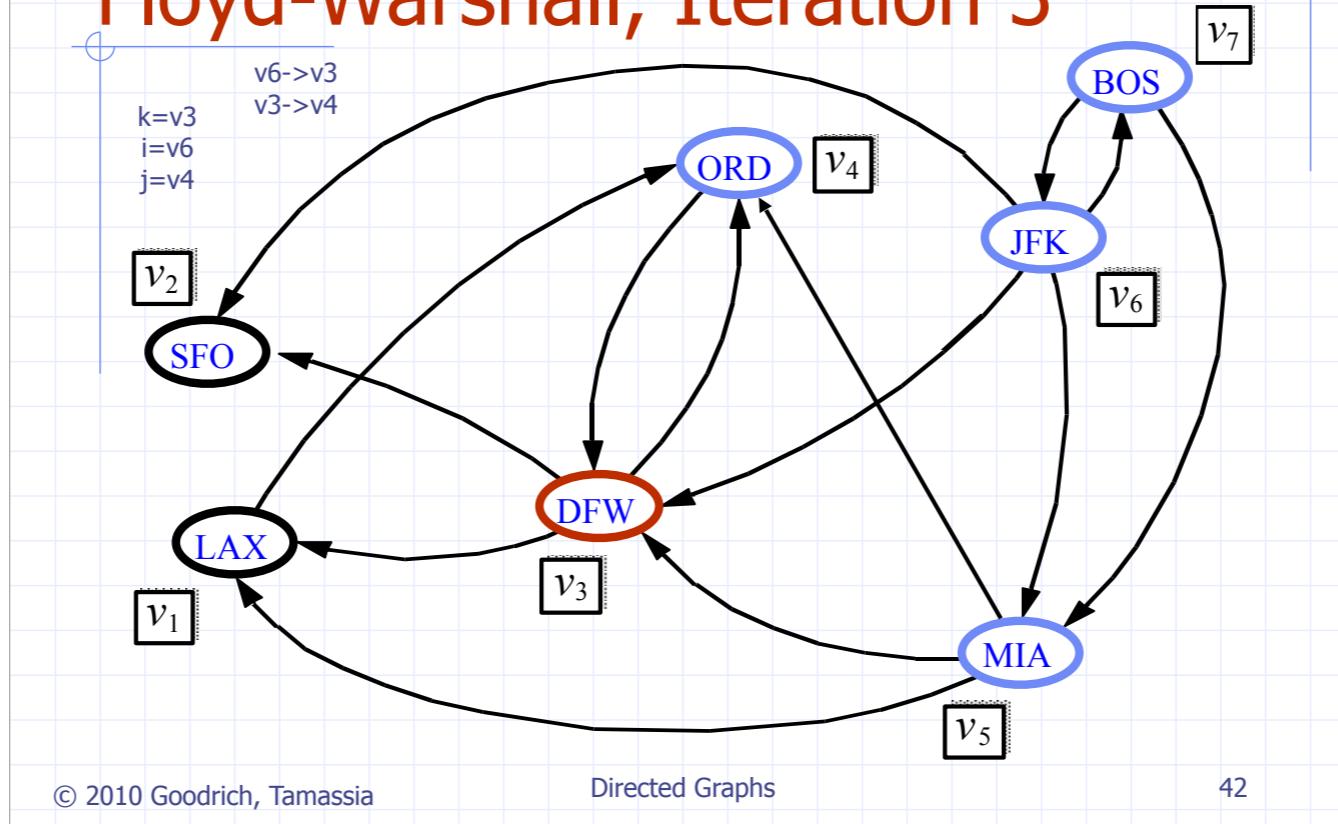
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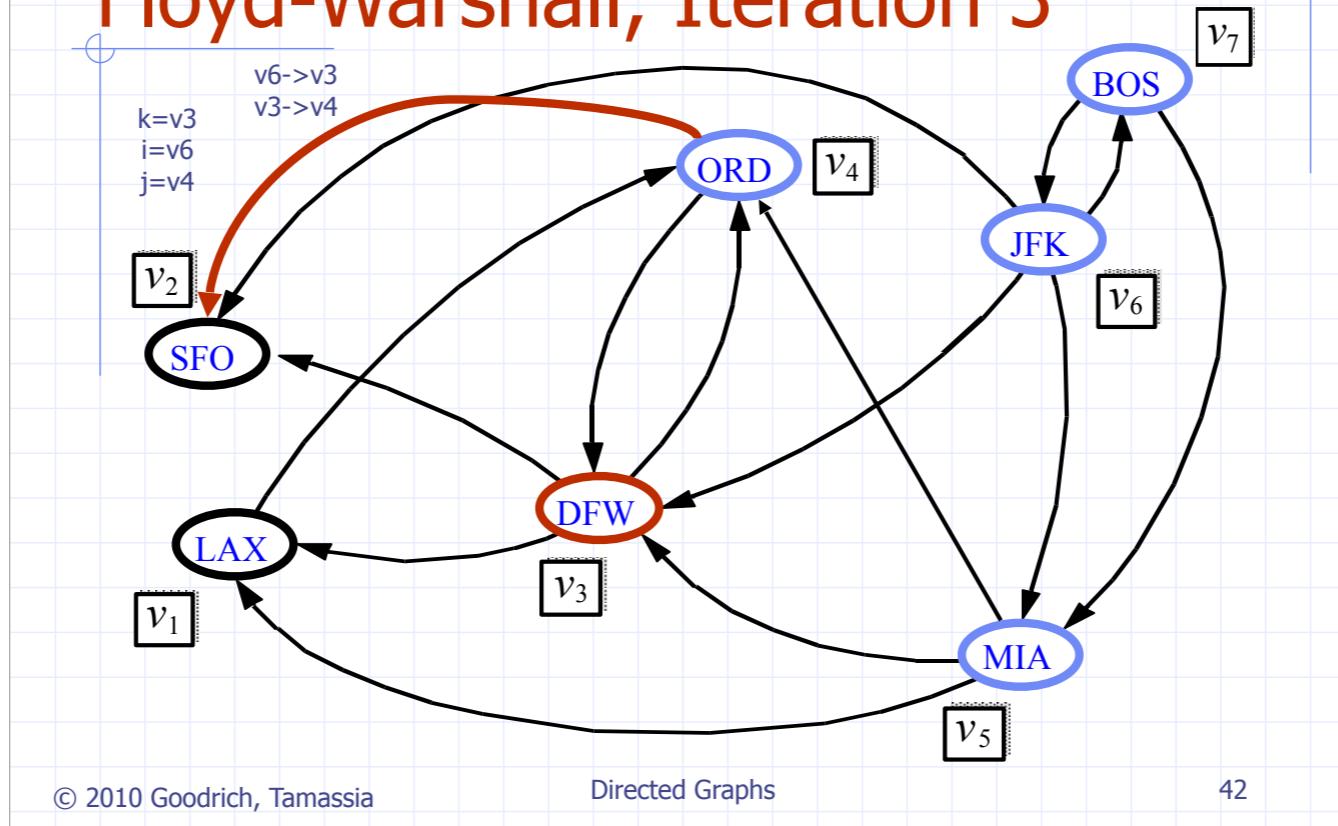
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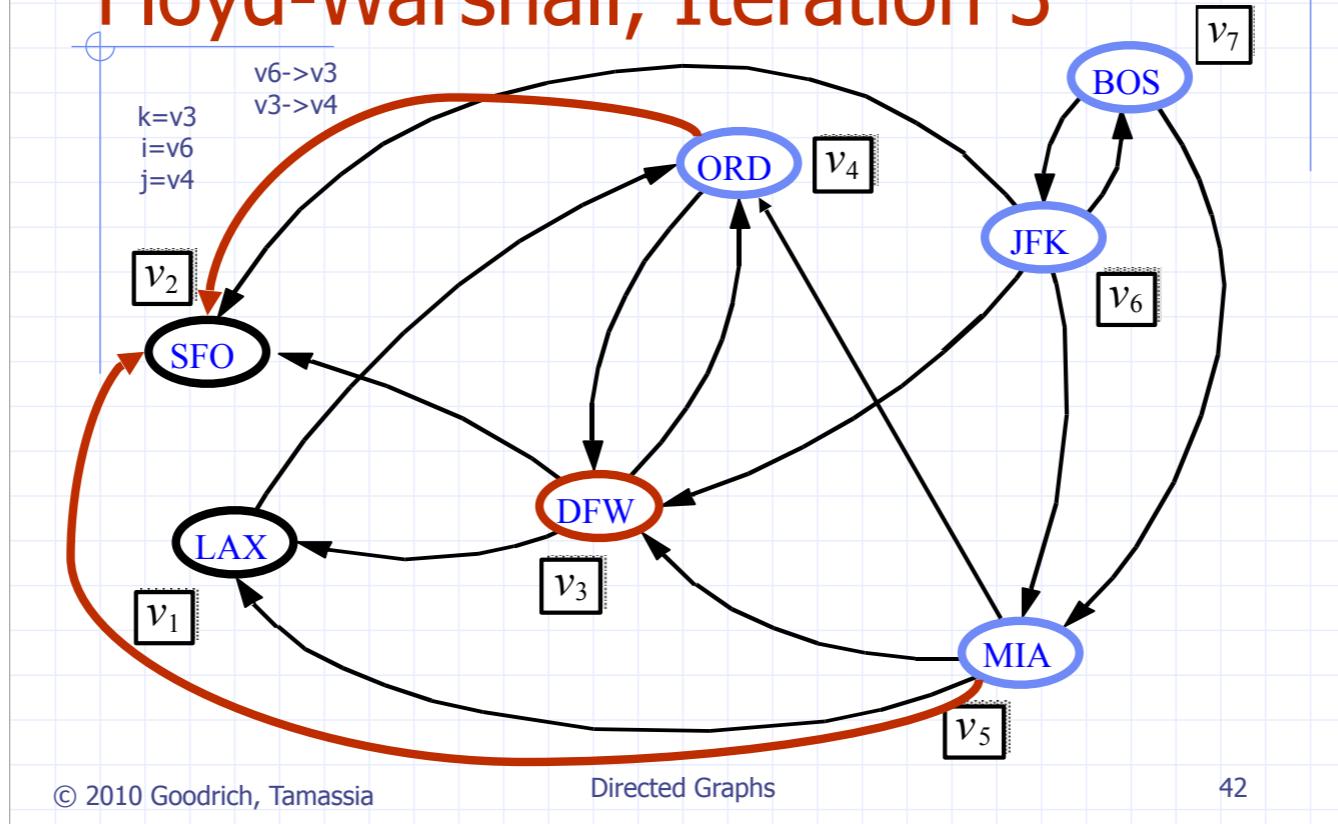
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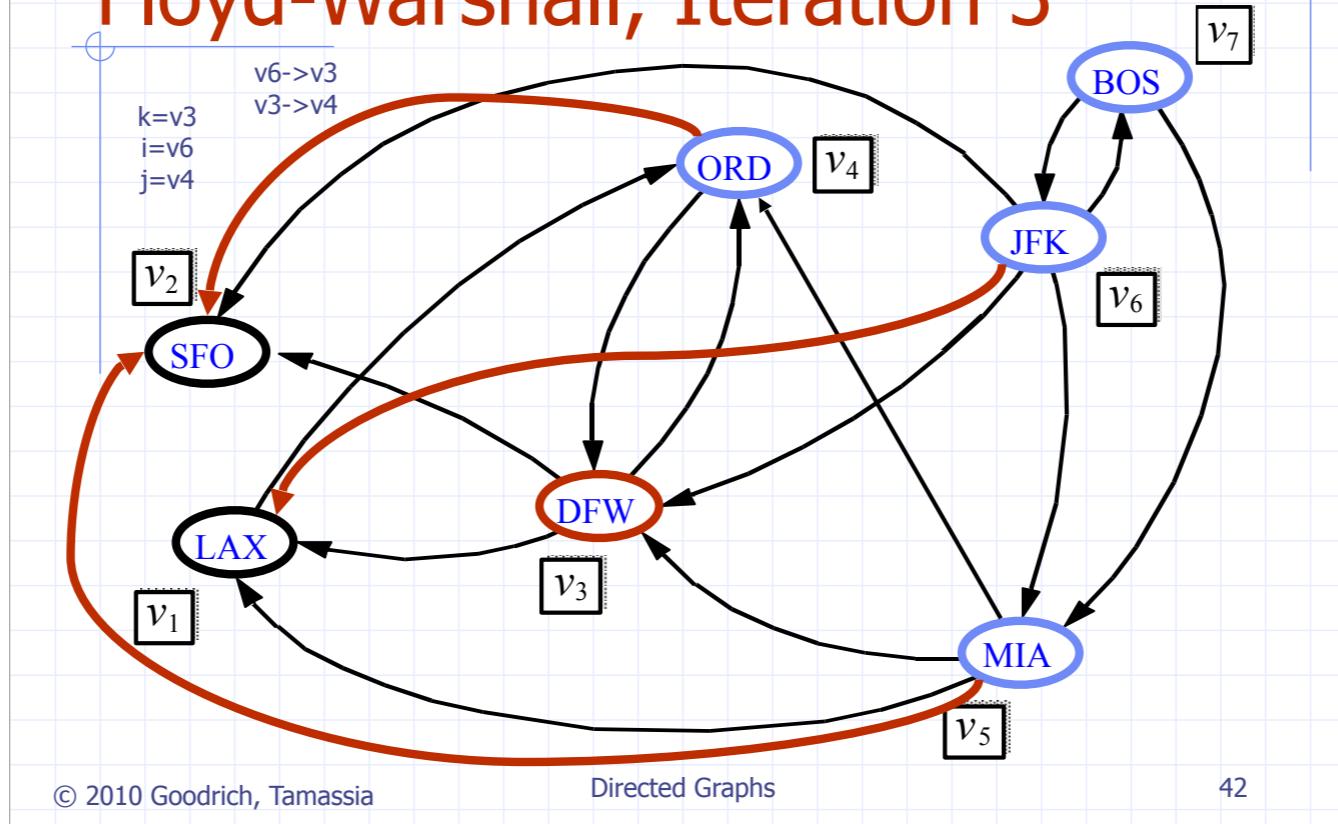
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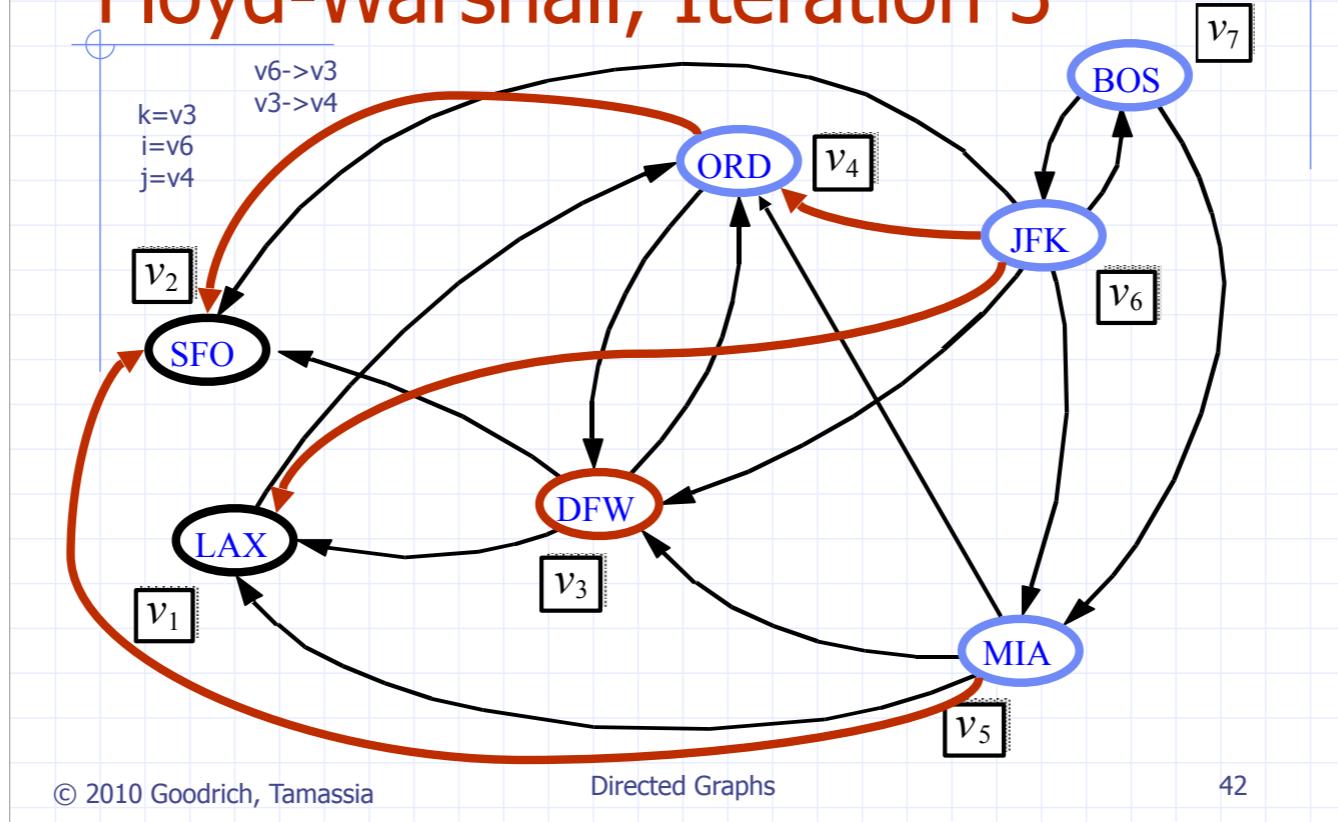
Floyd-Warshall, Iteration 3



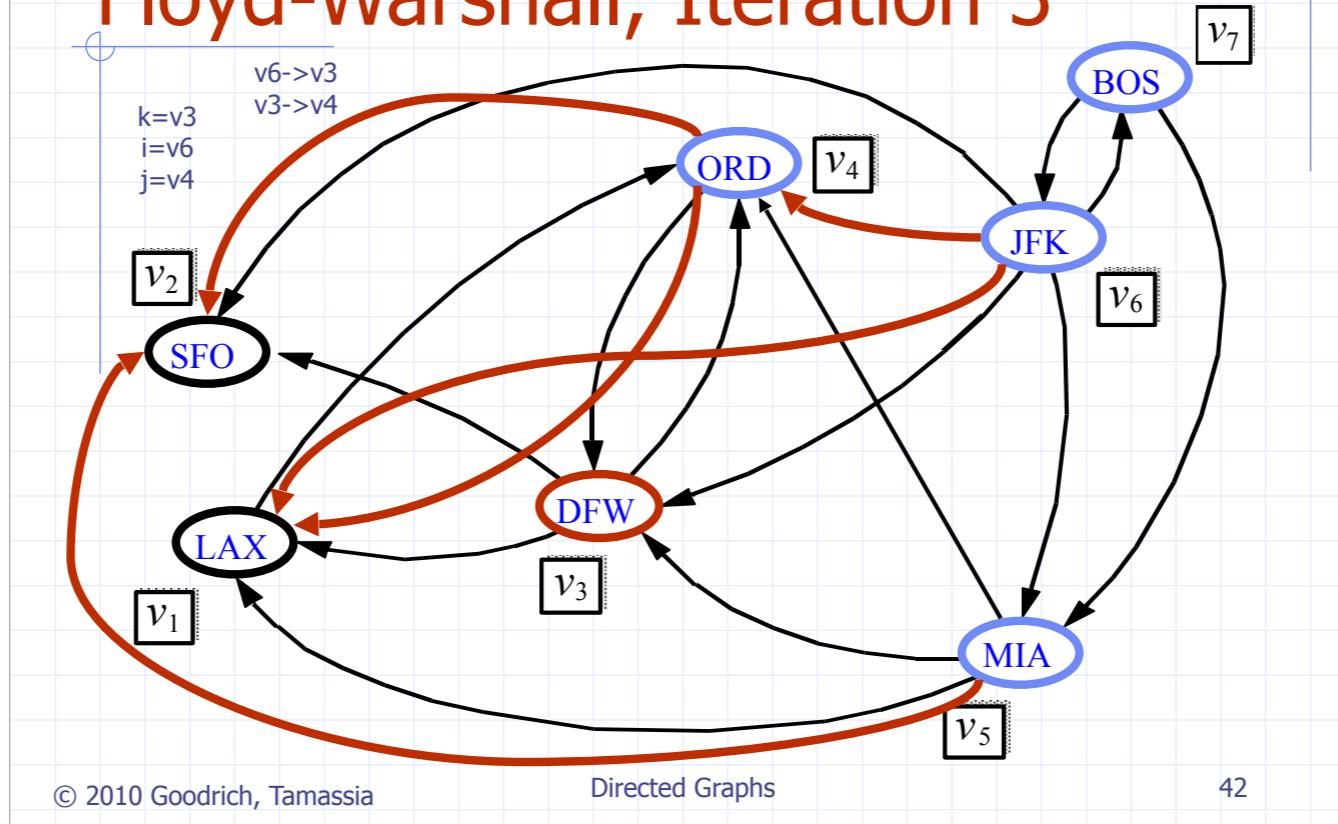
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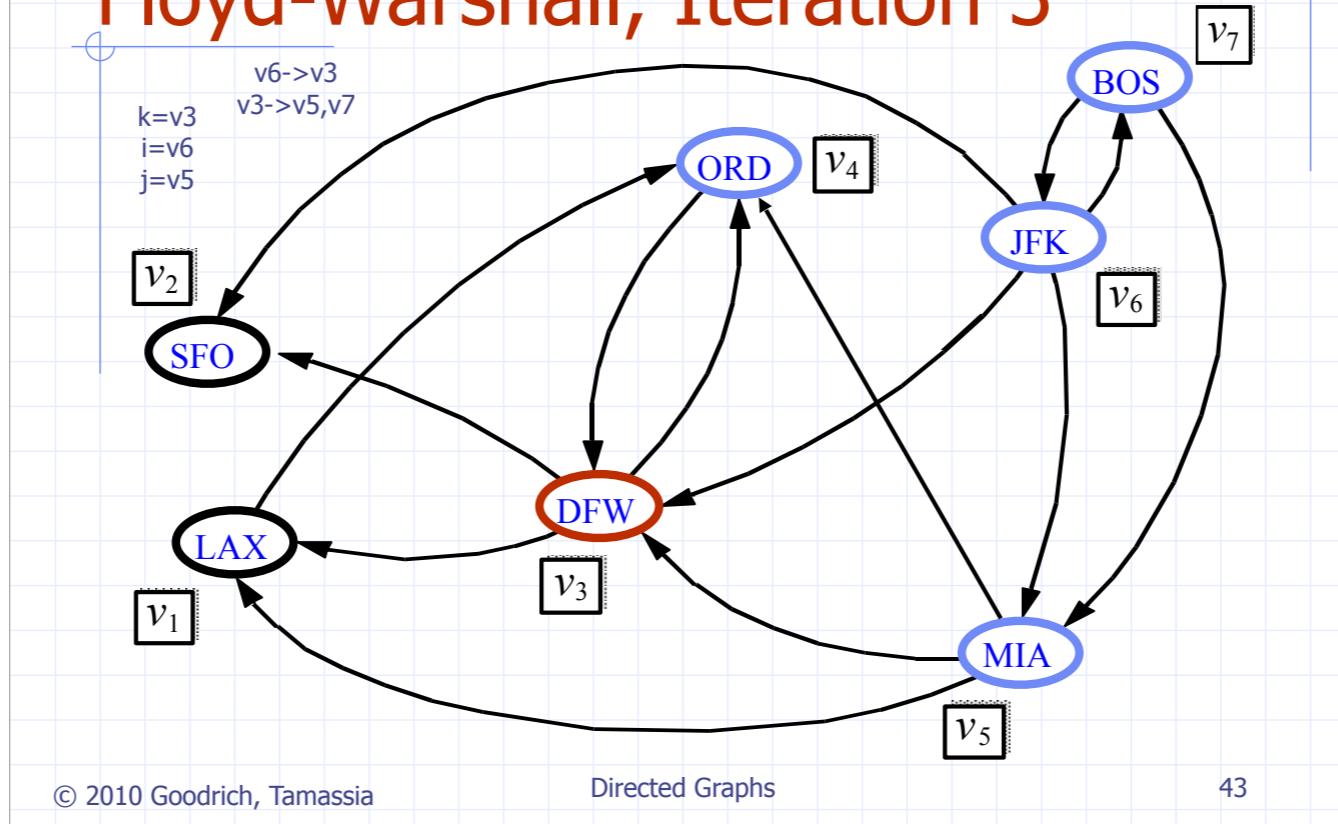
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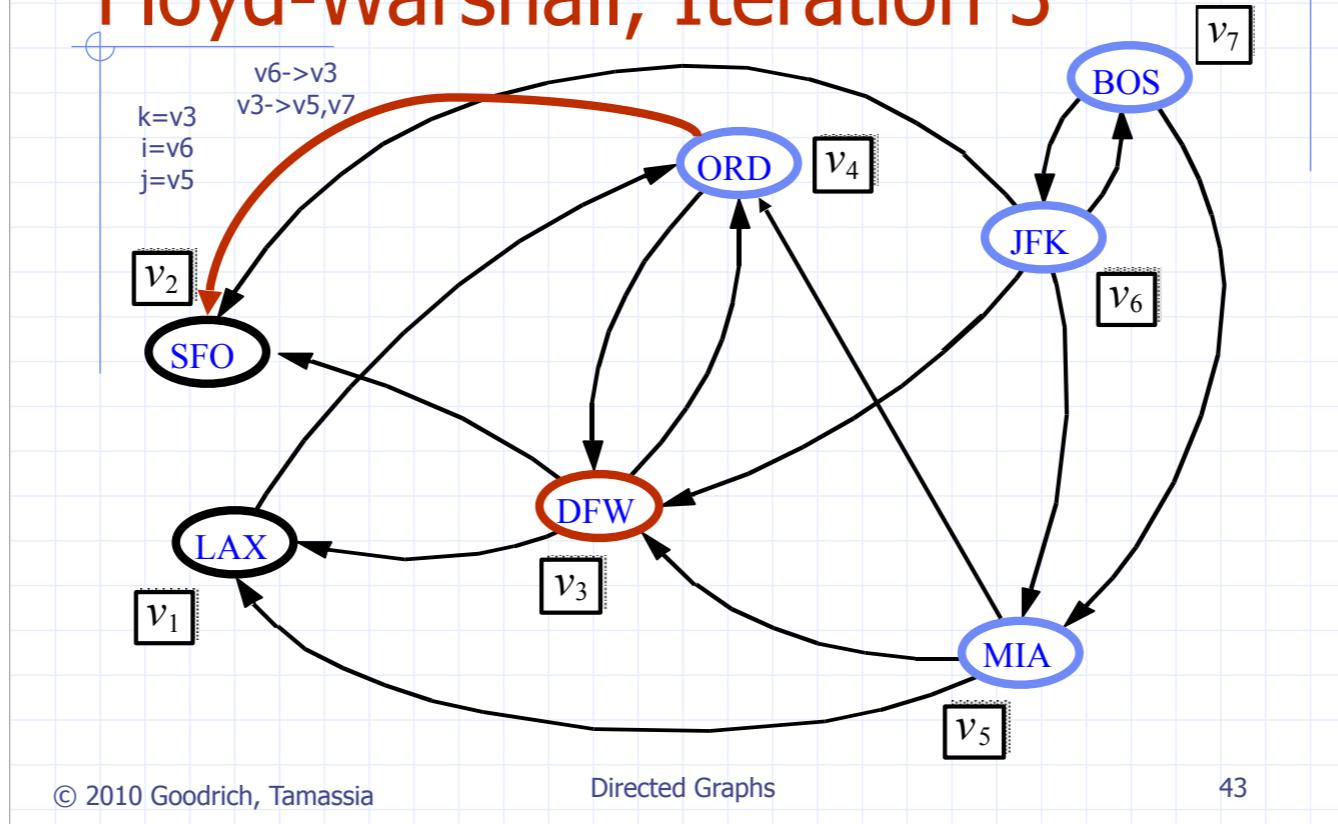
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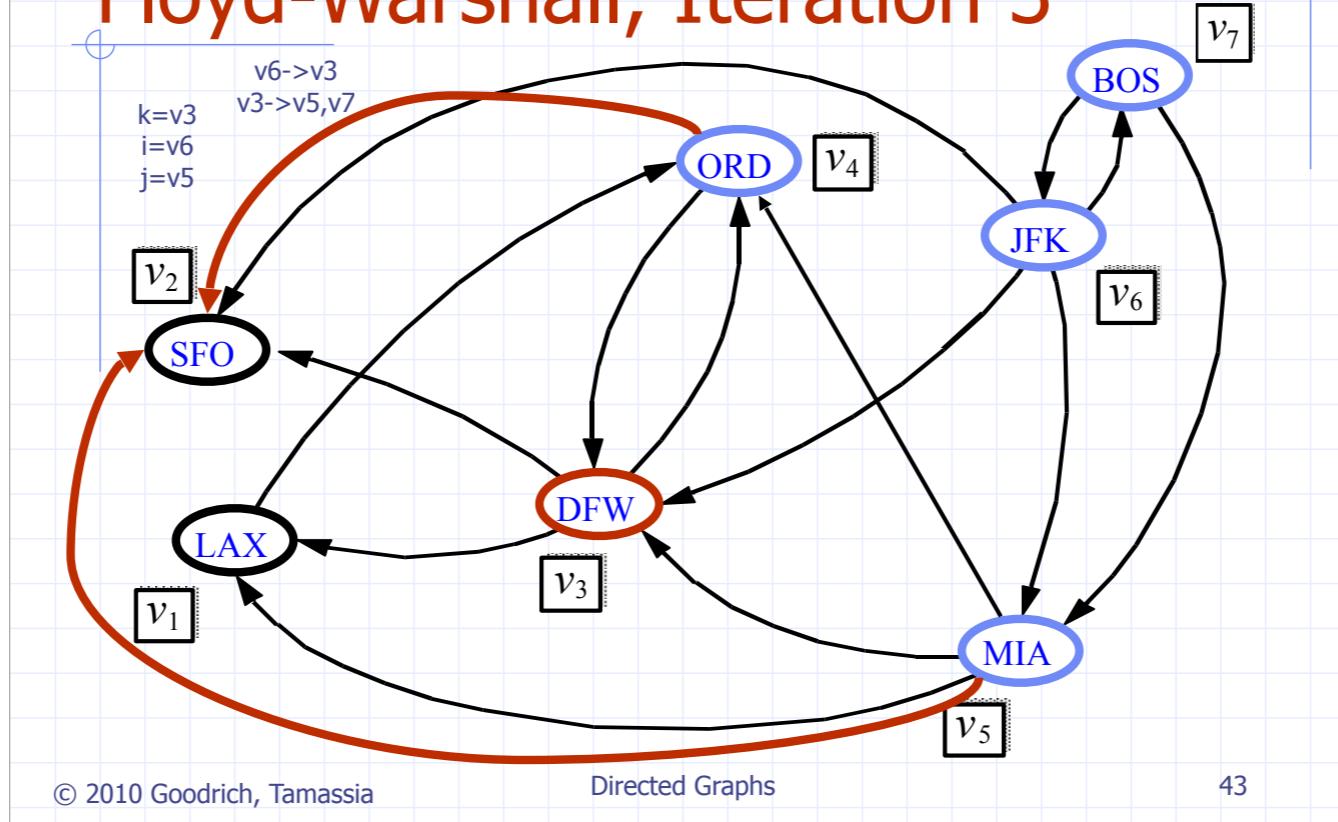
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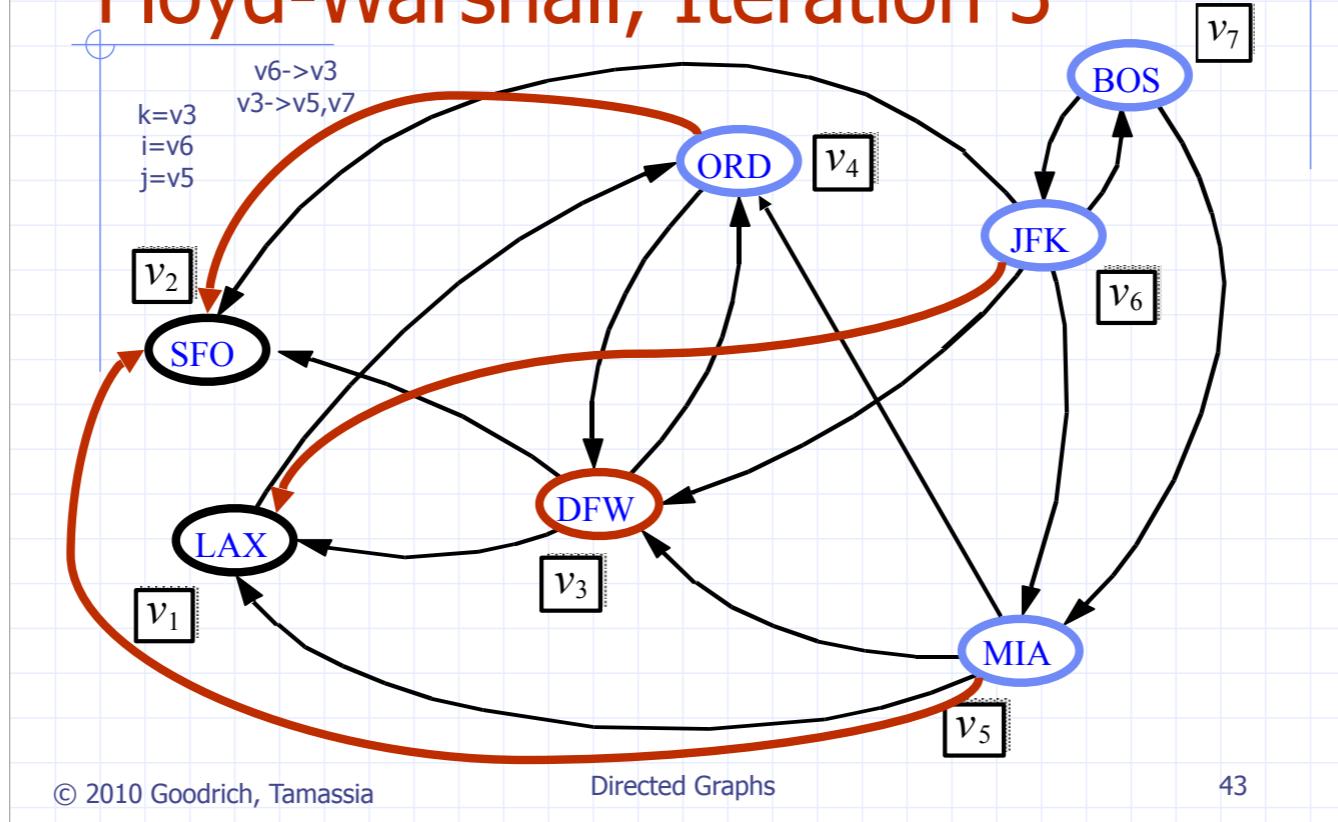
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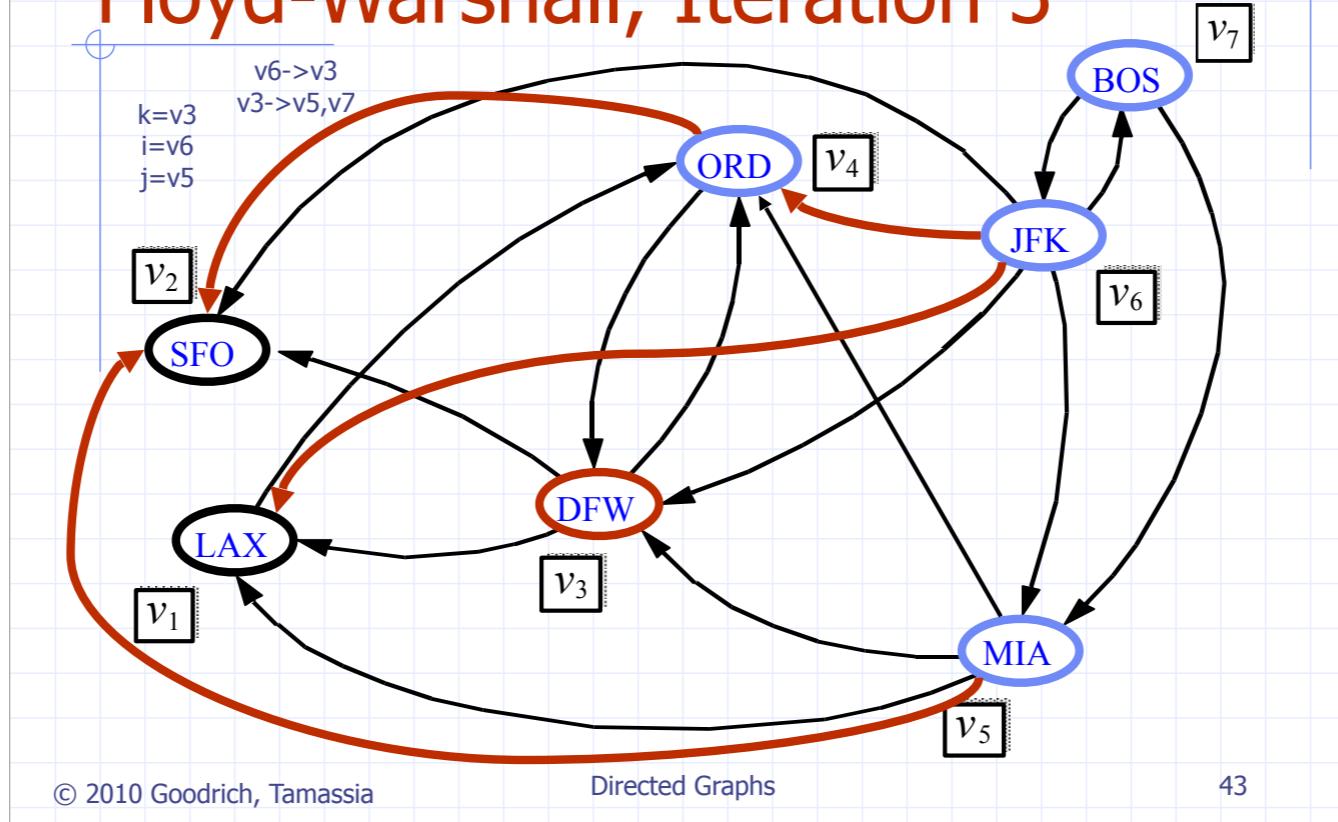
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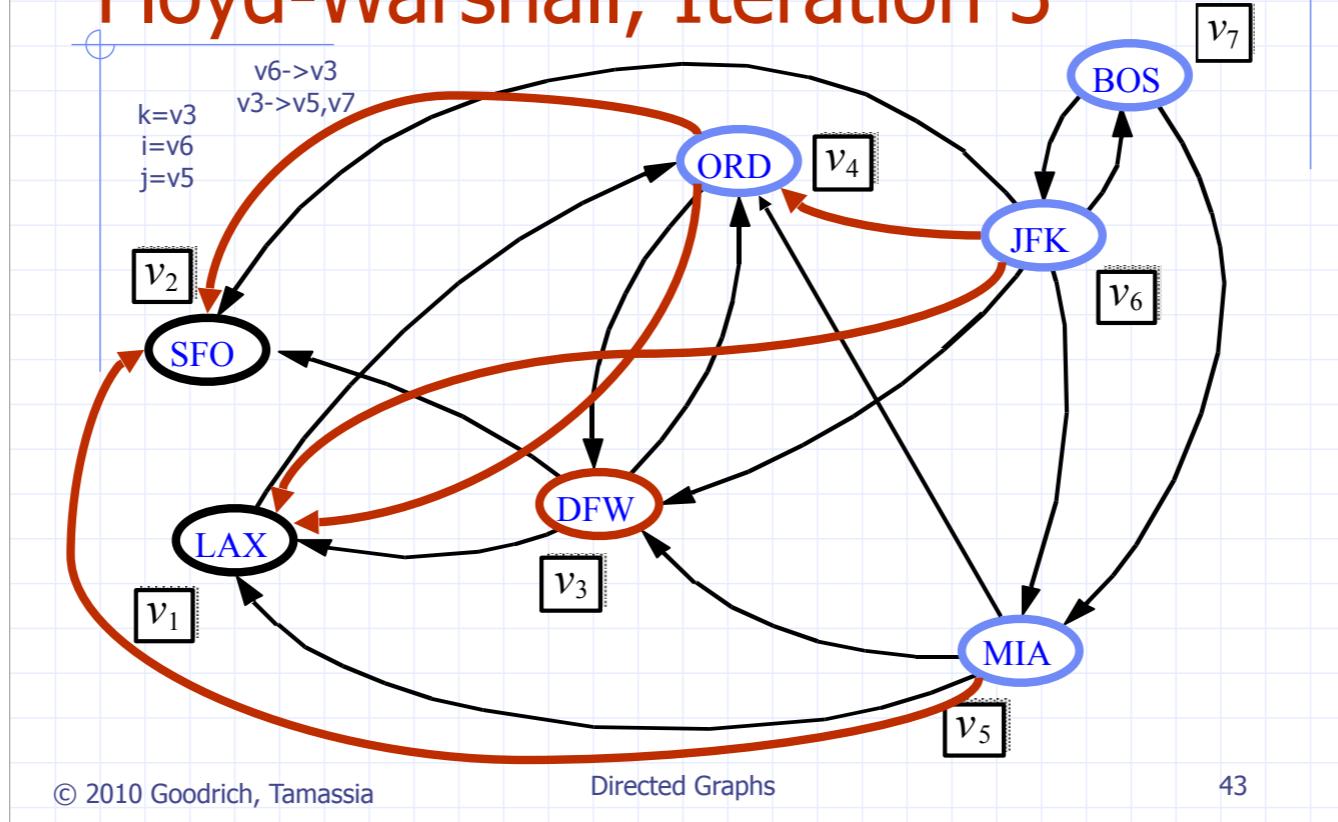
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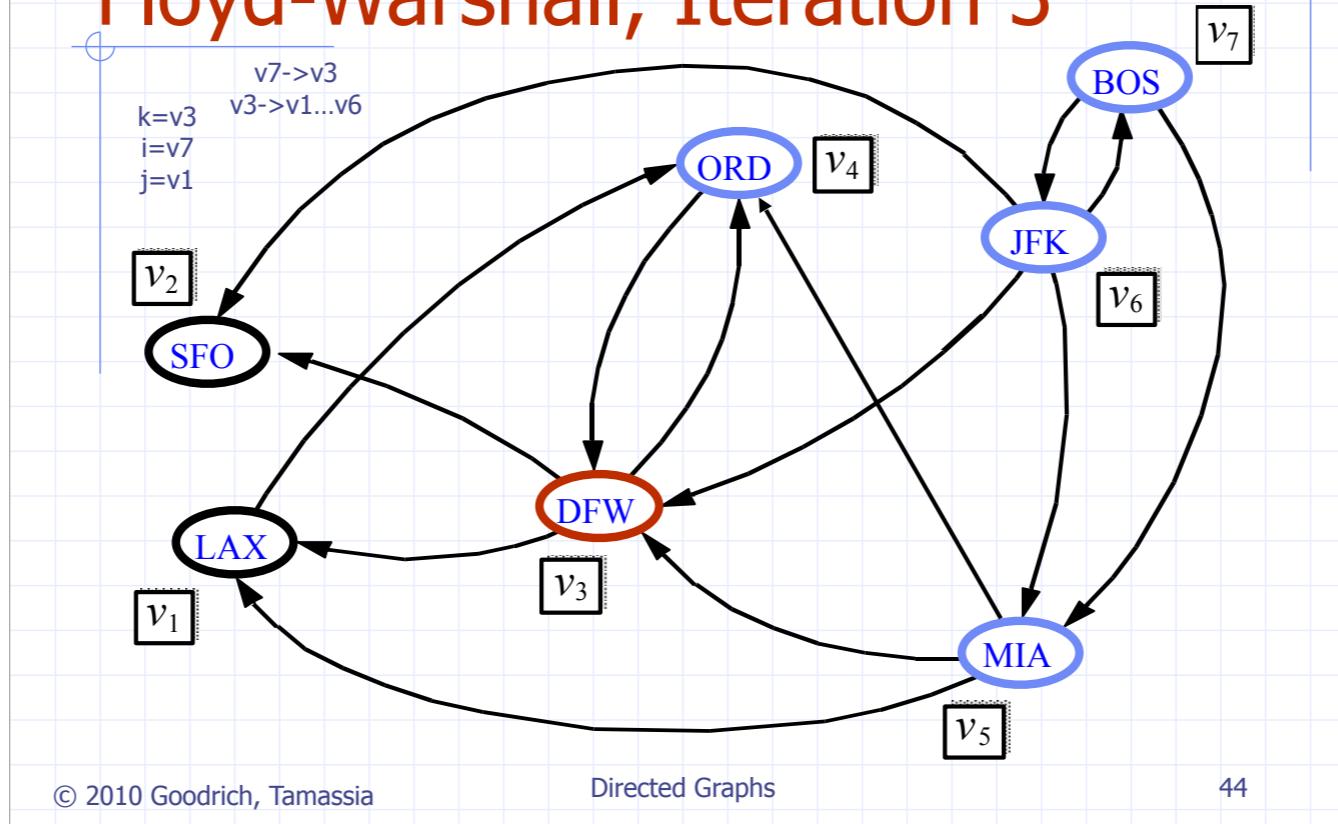
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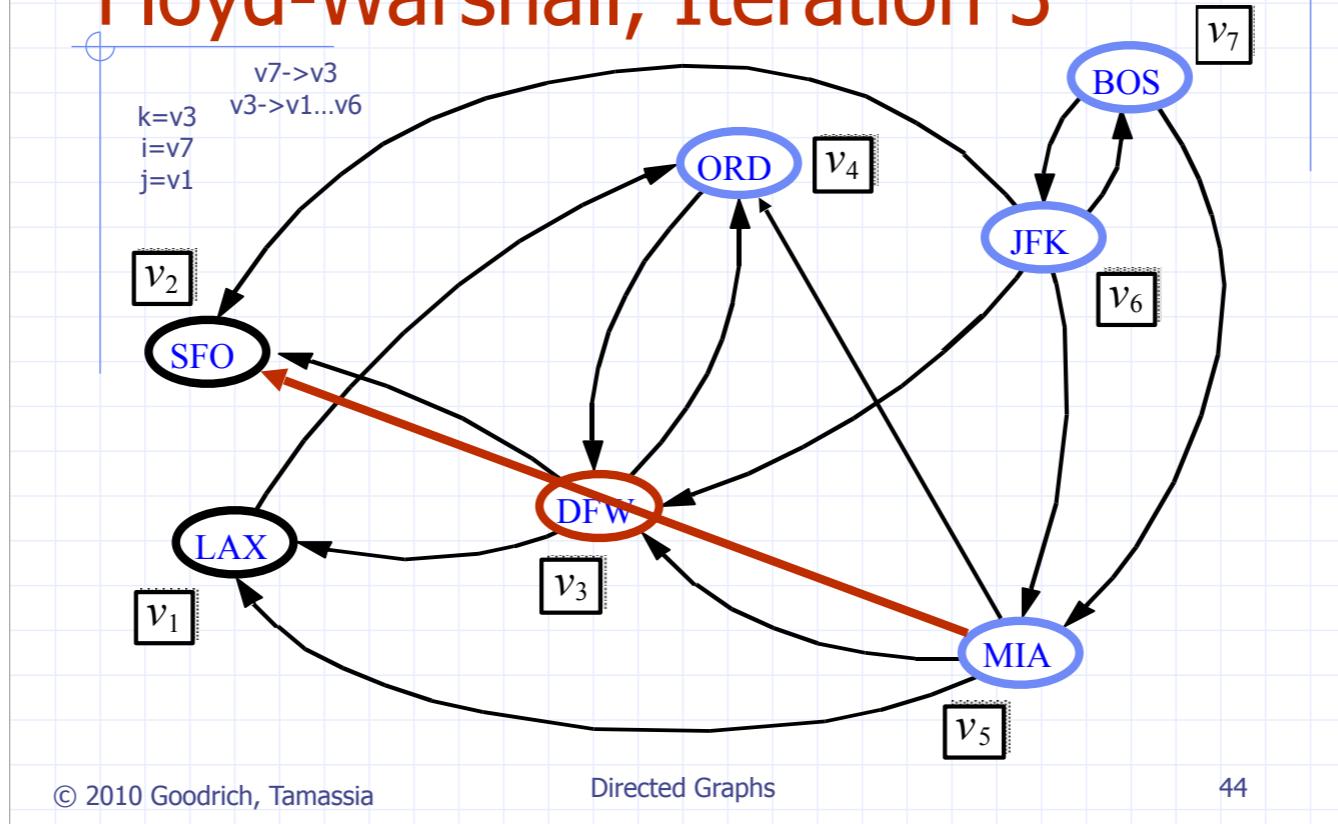
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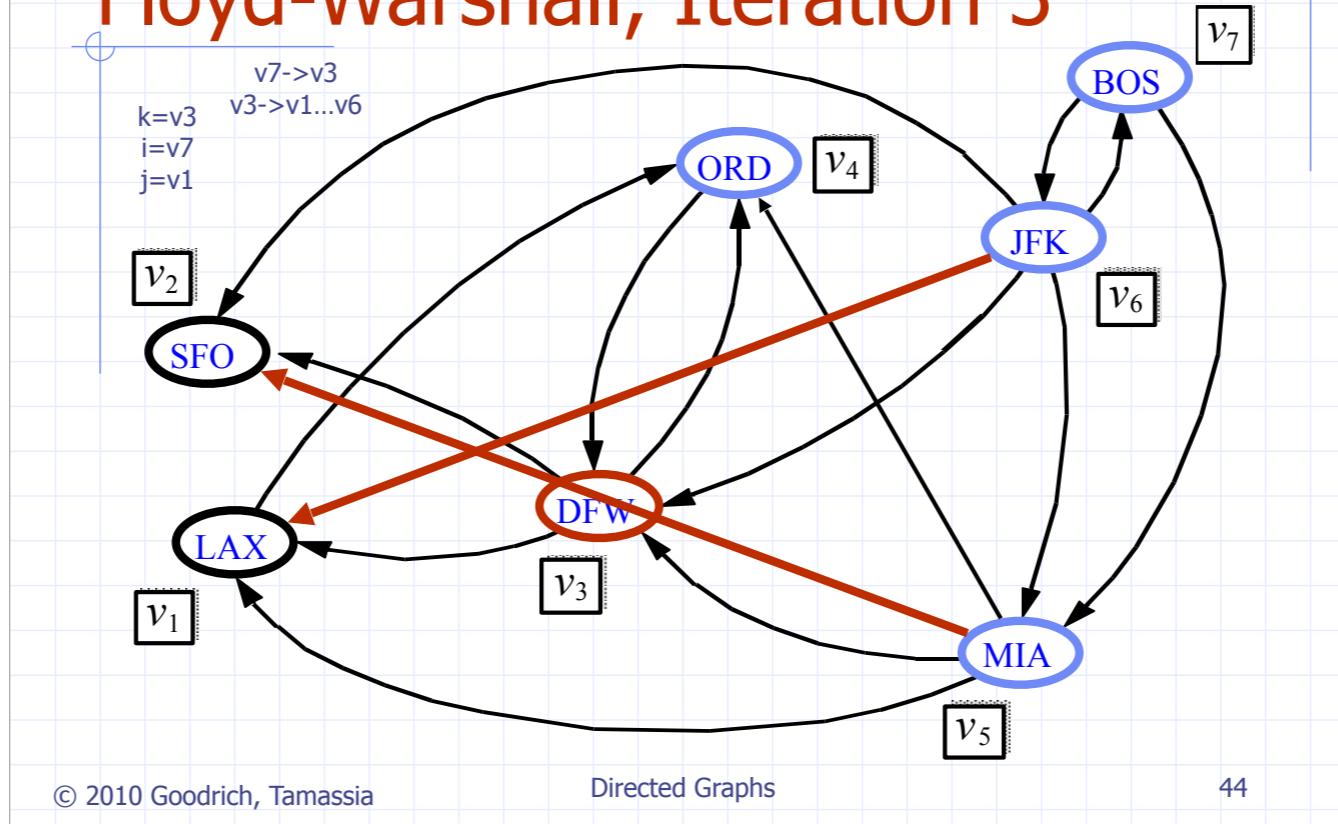
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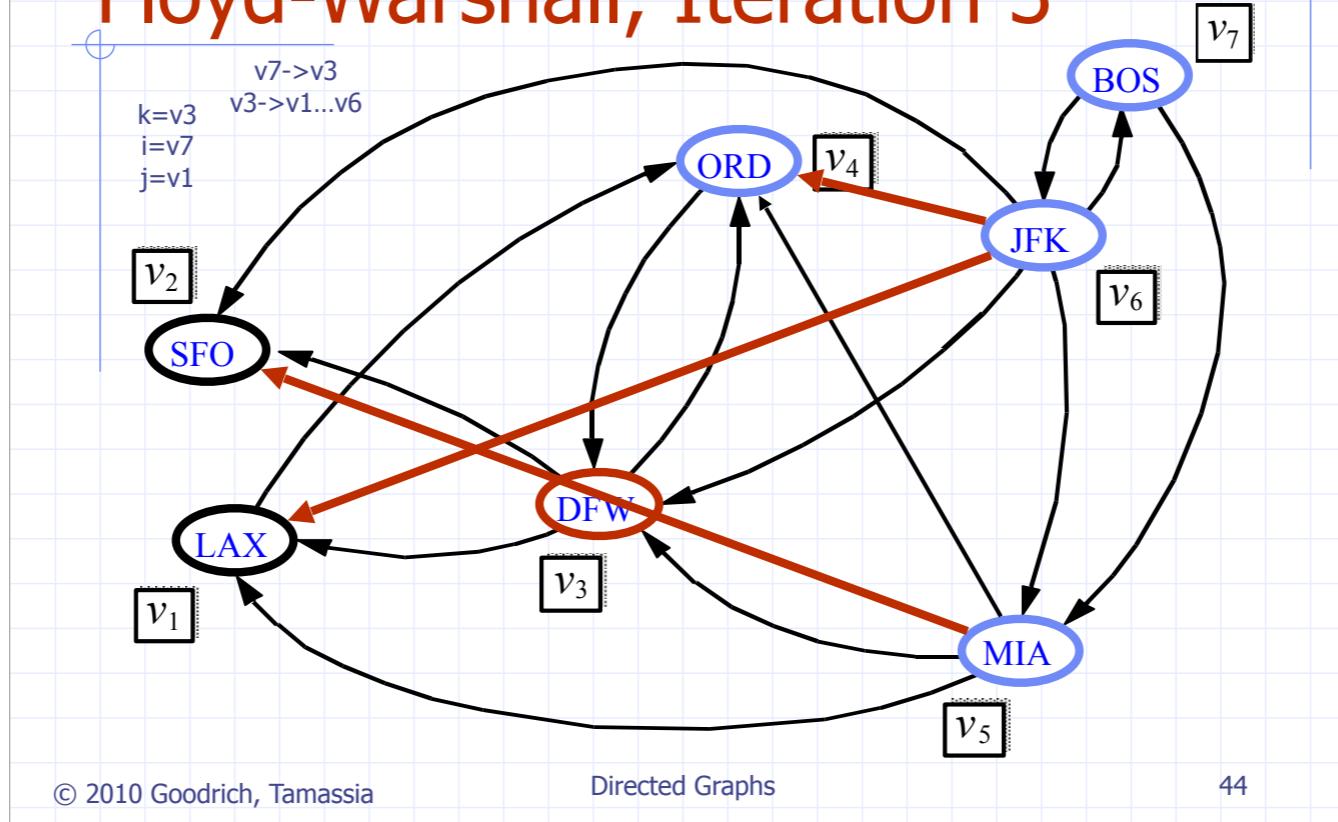
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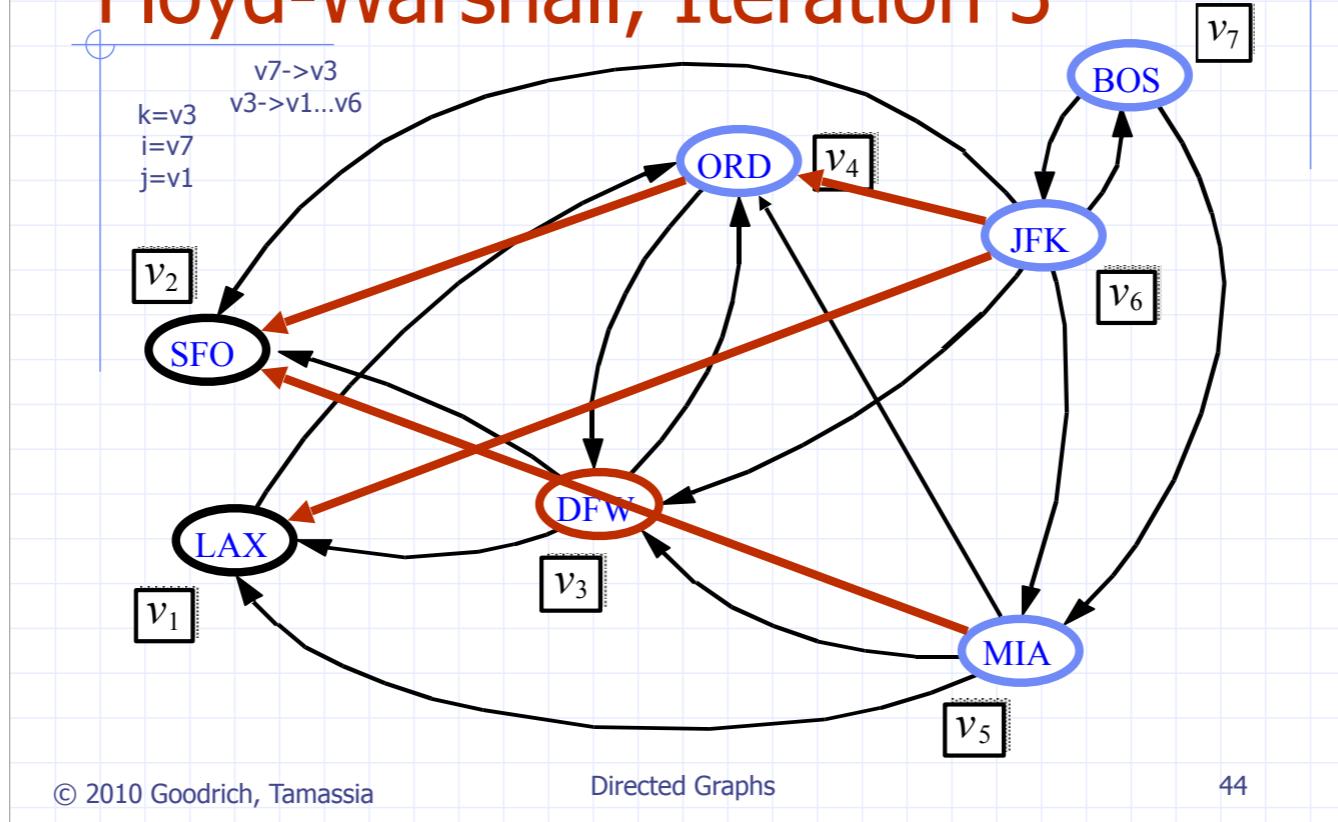
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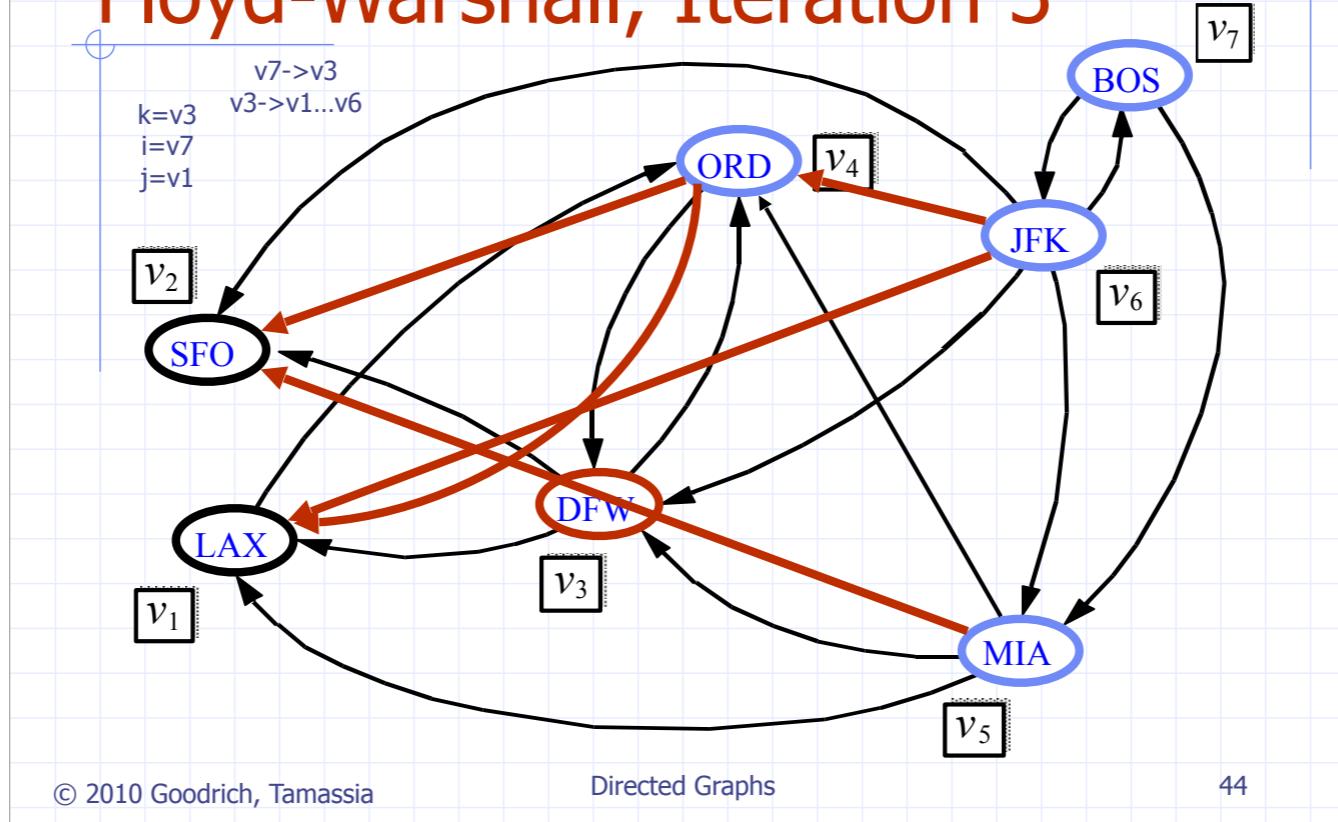
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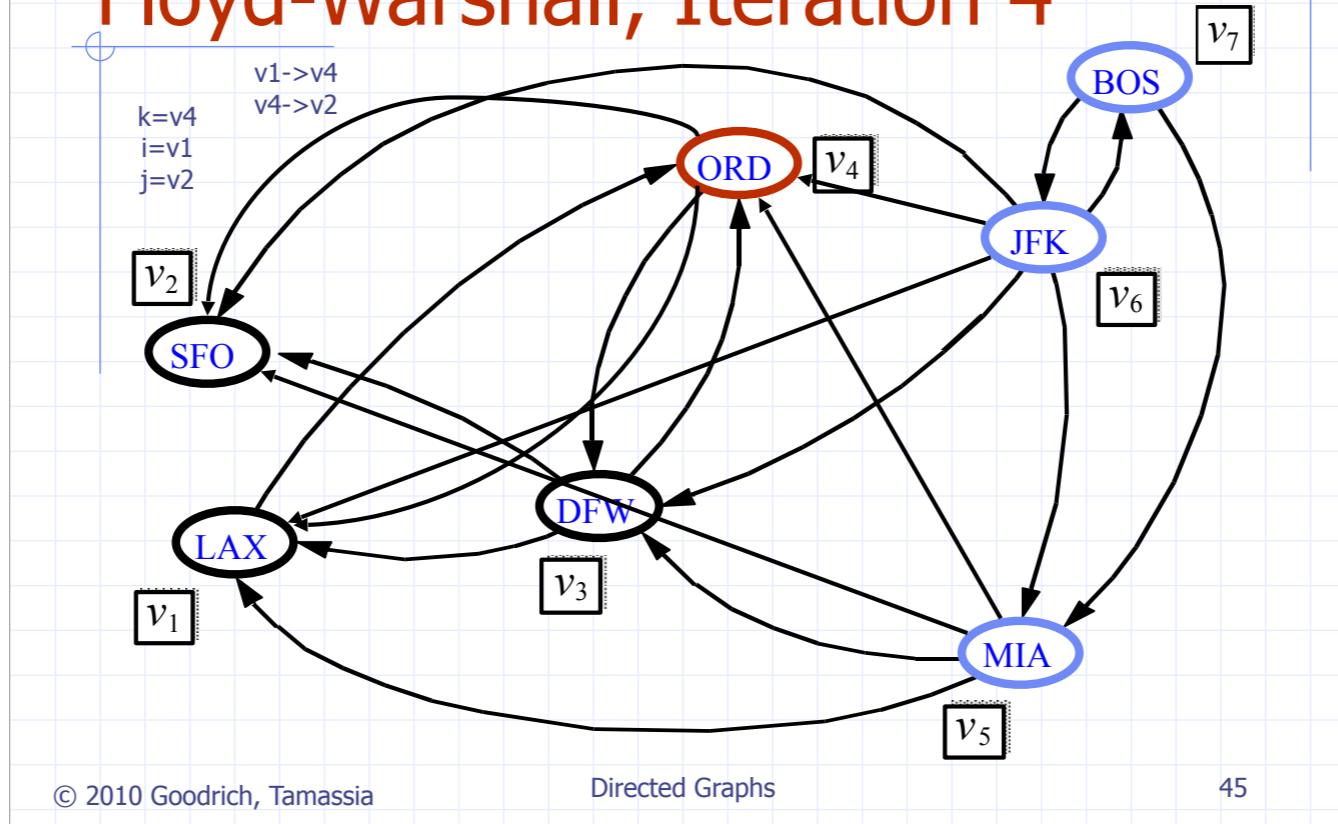
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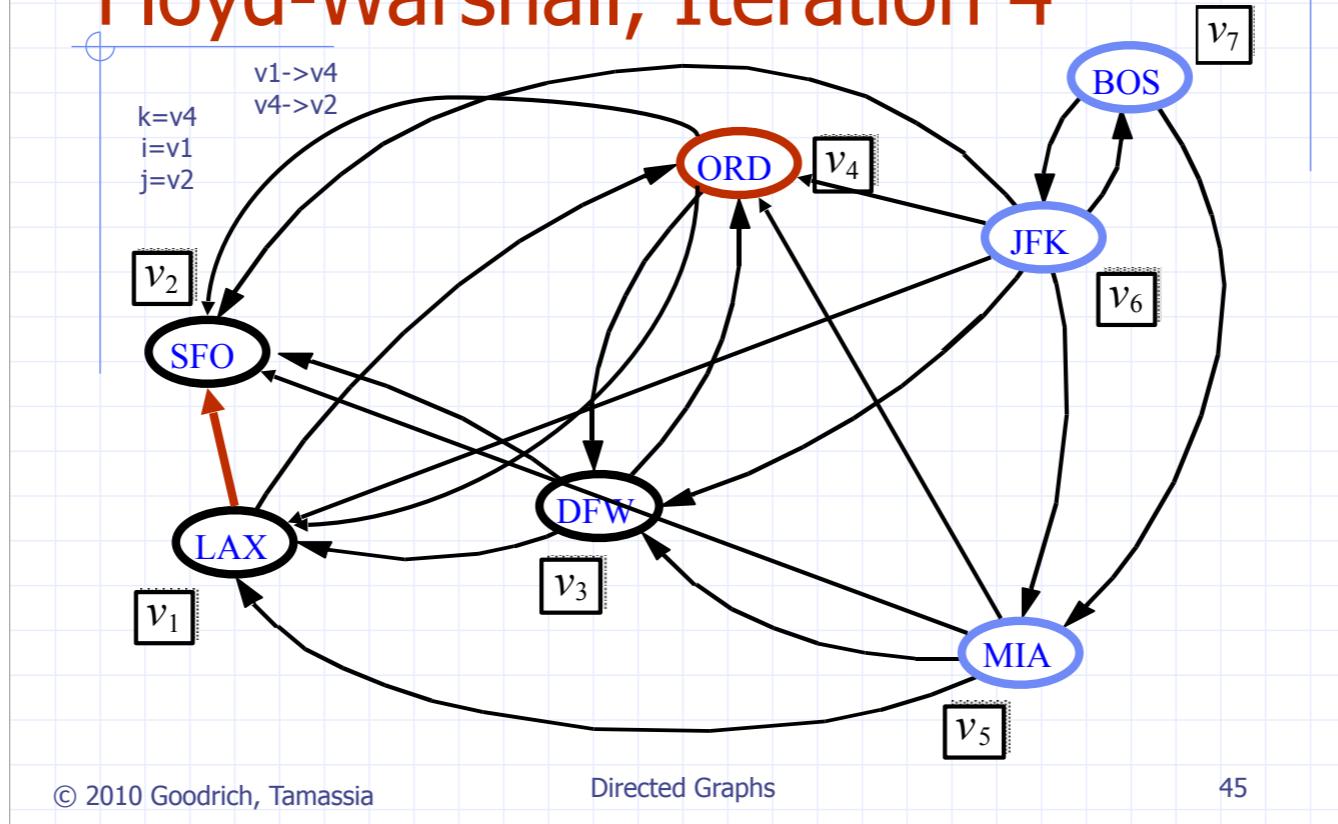
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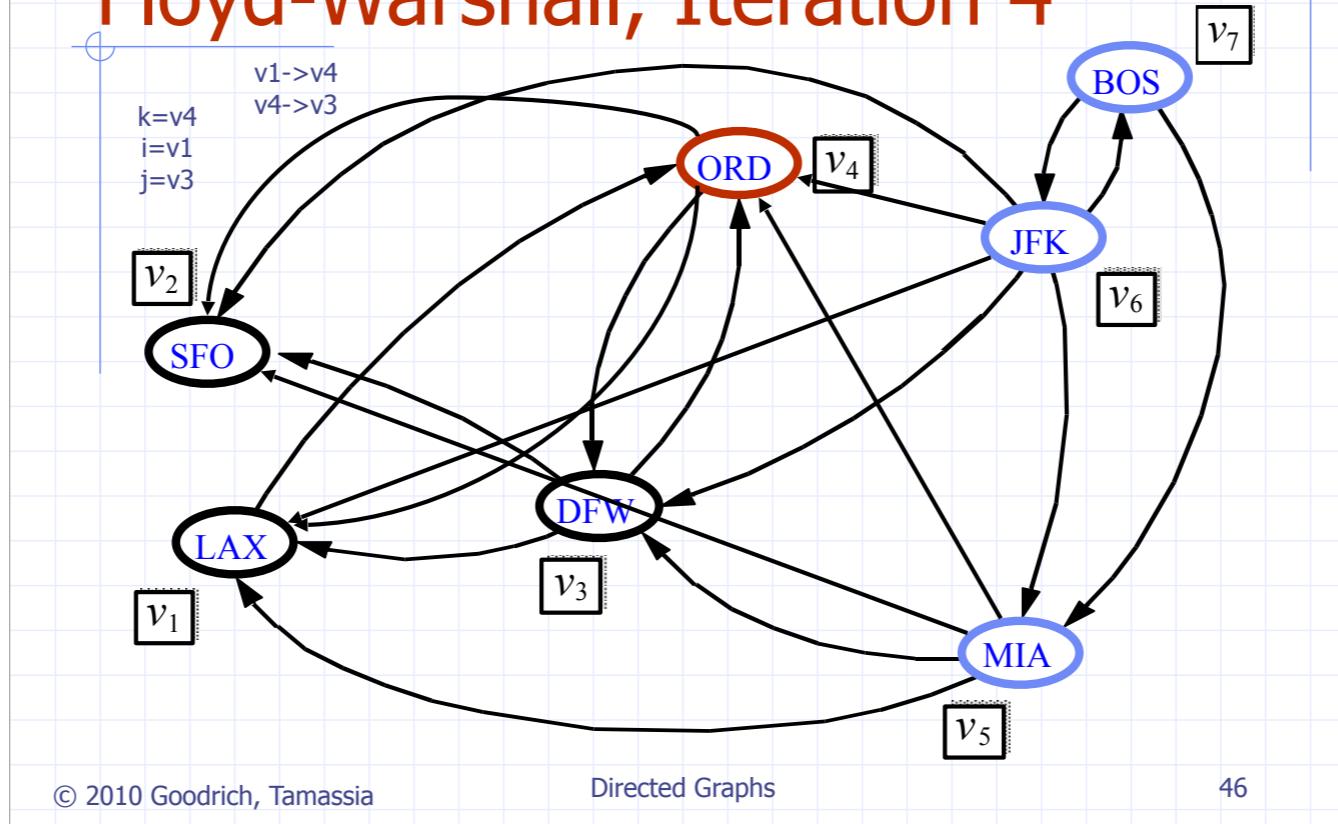
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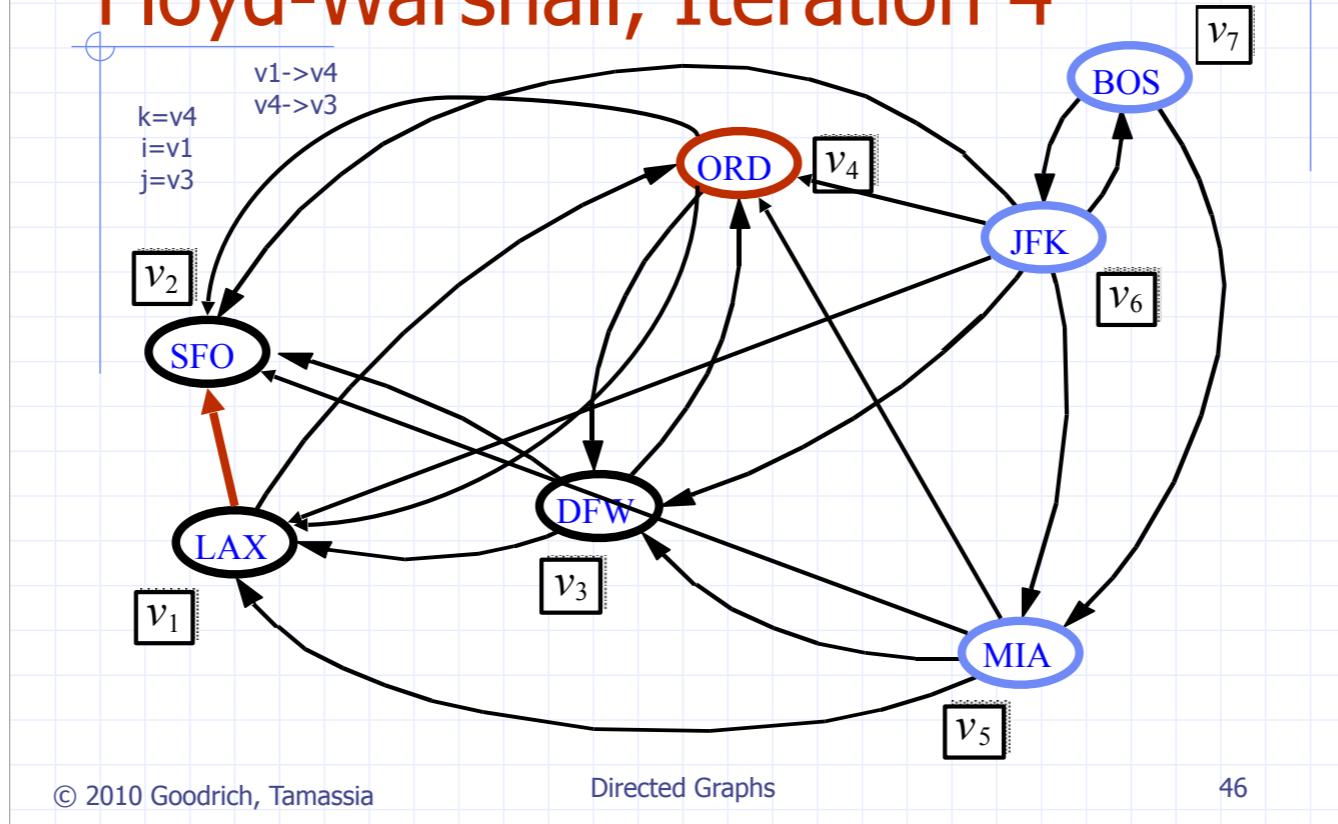
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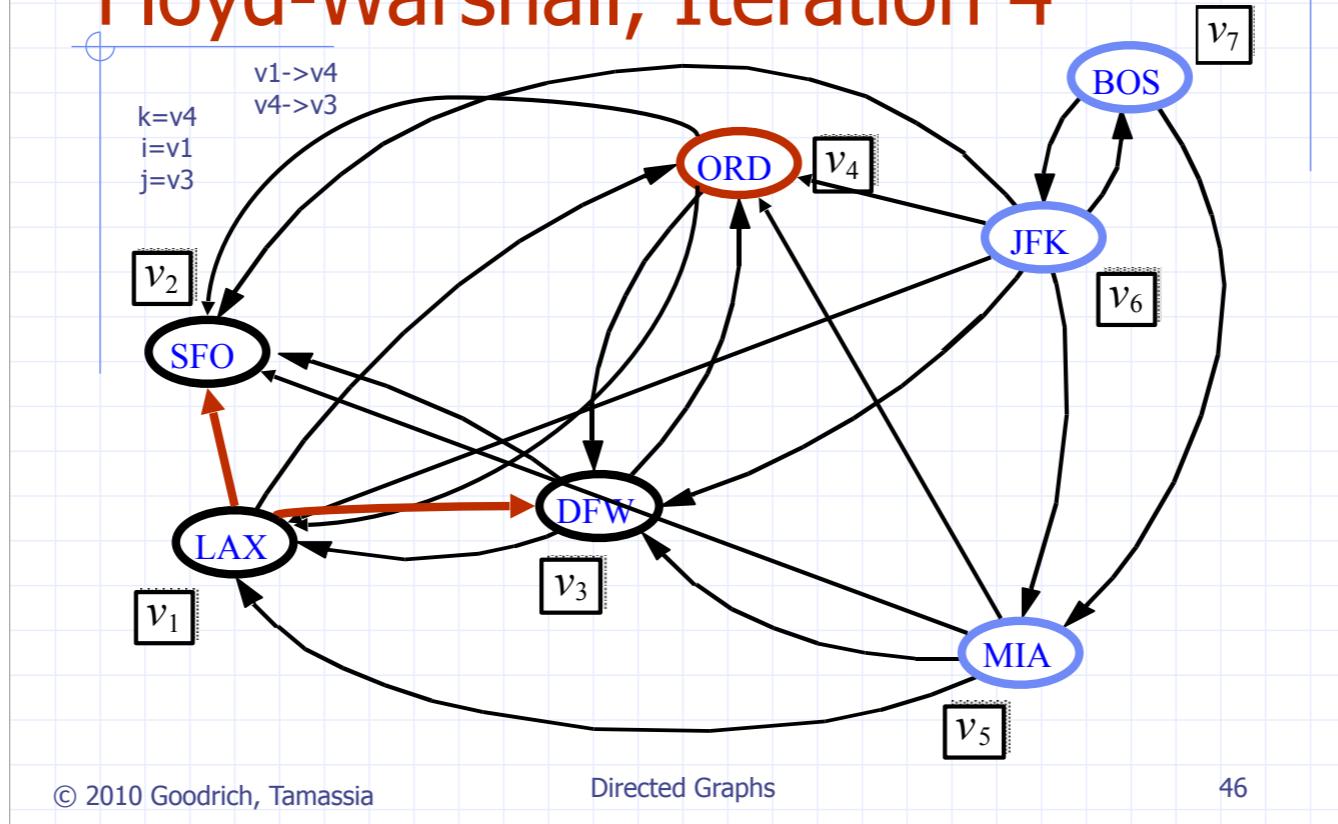
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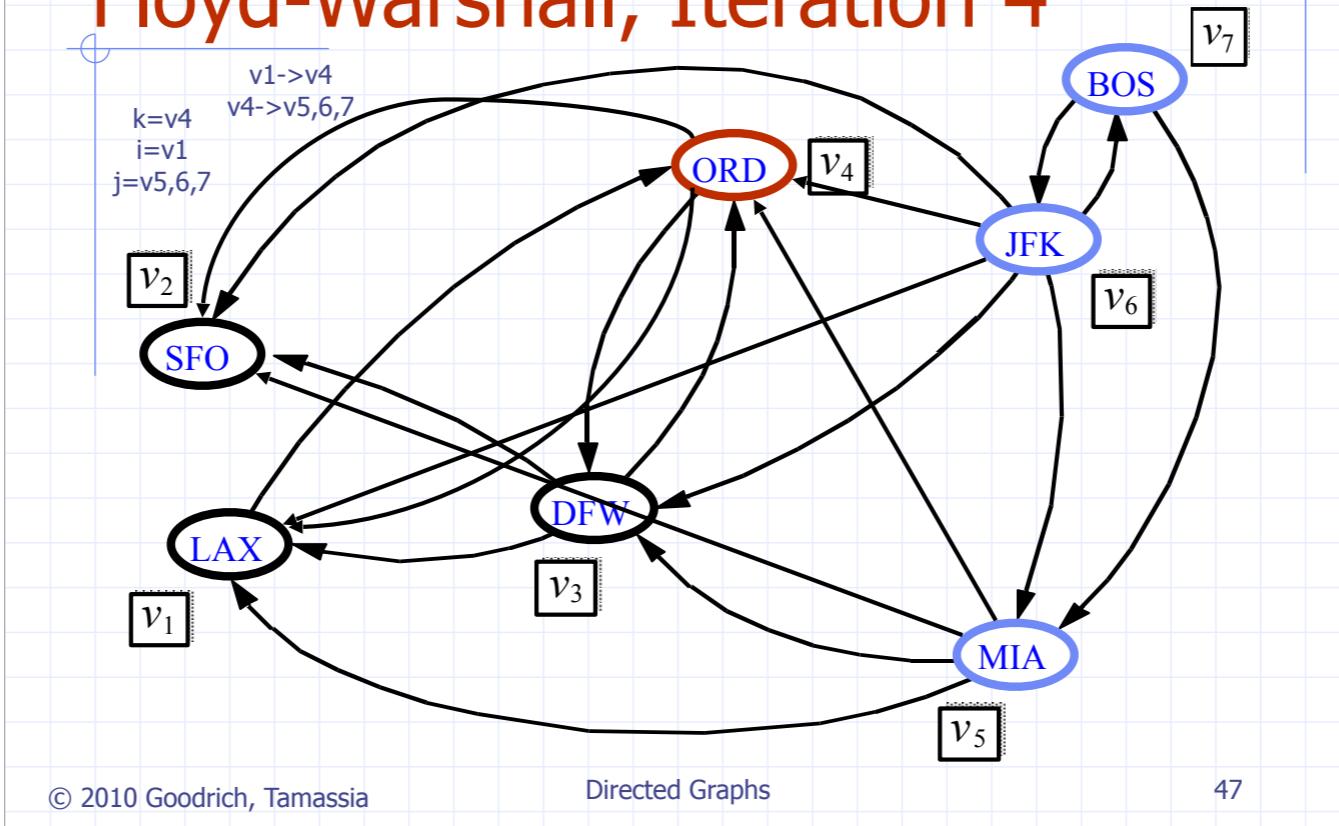
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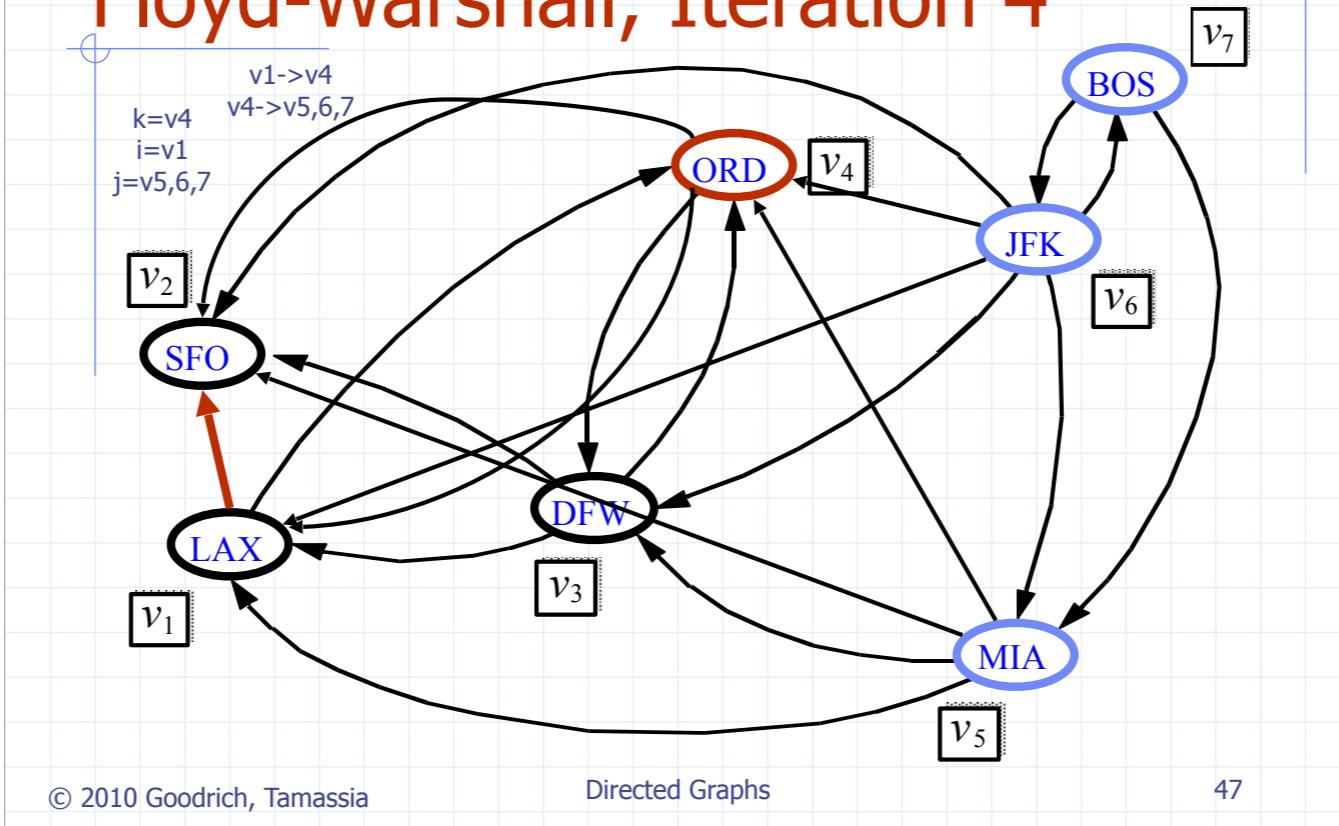
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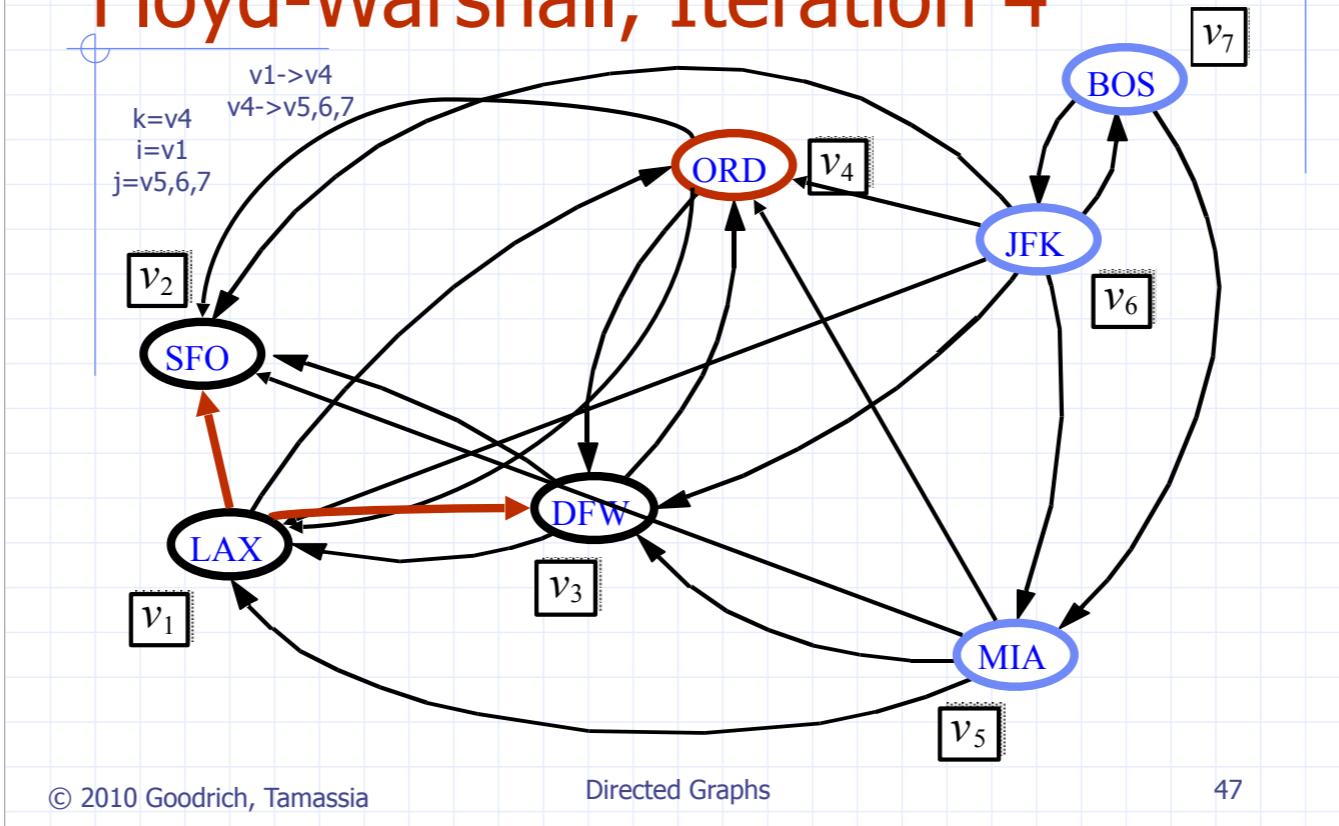
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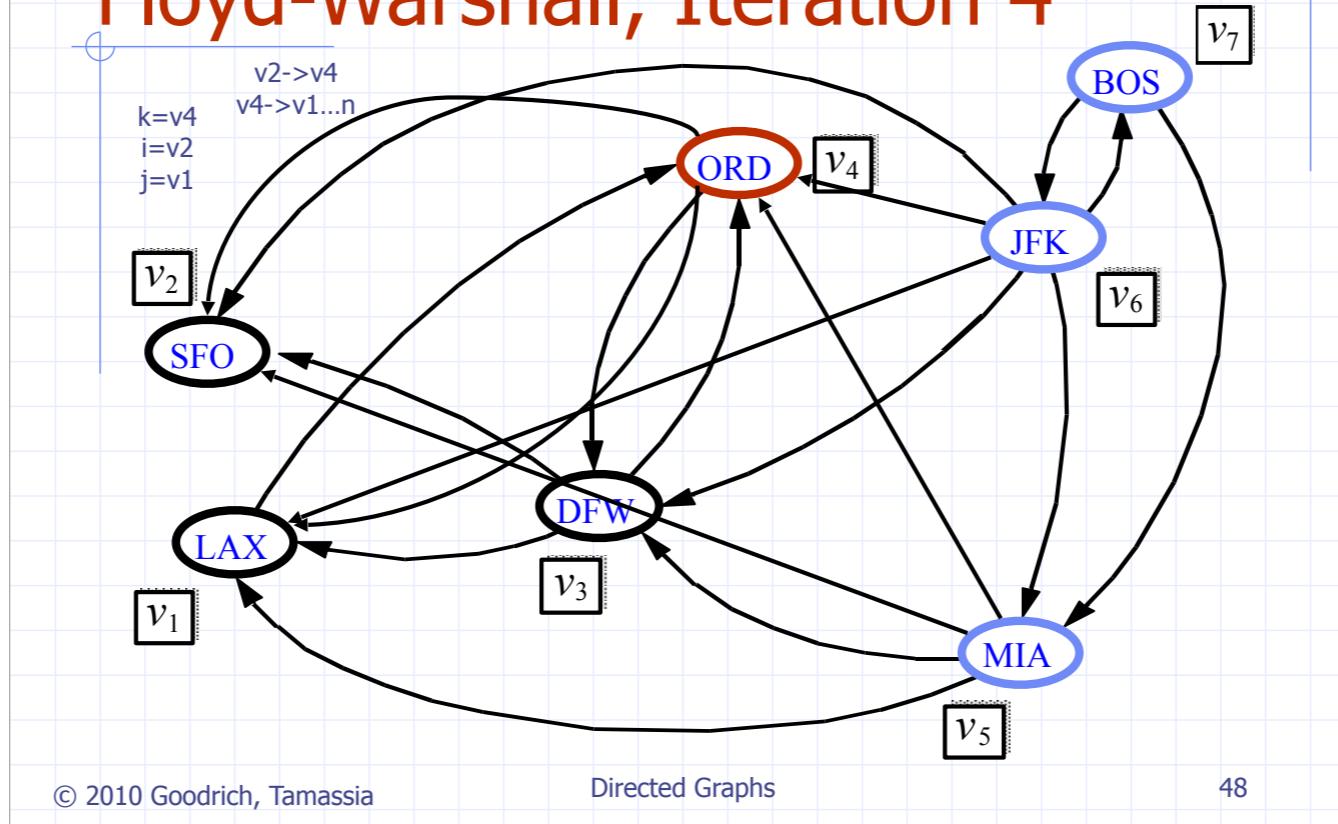
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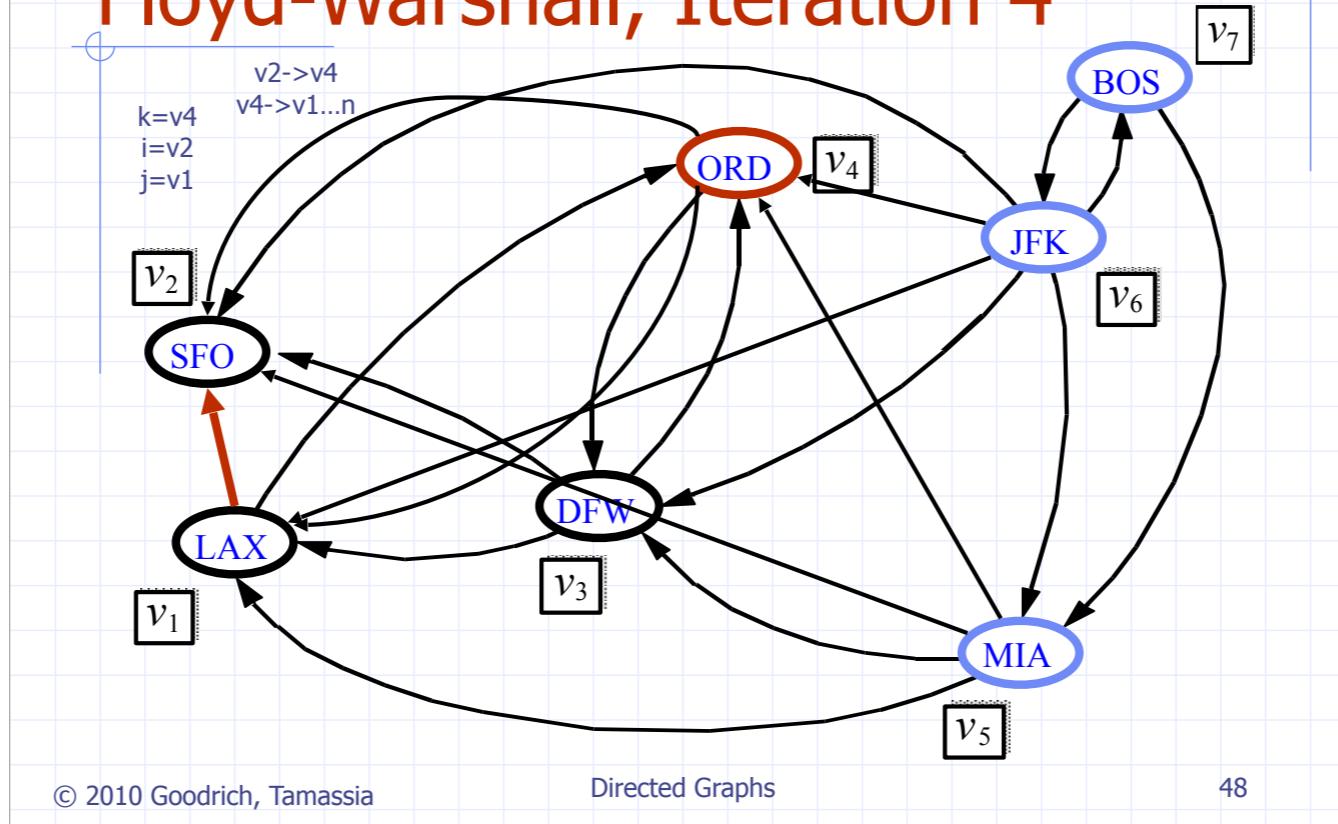
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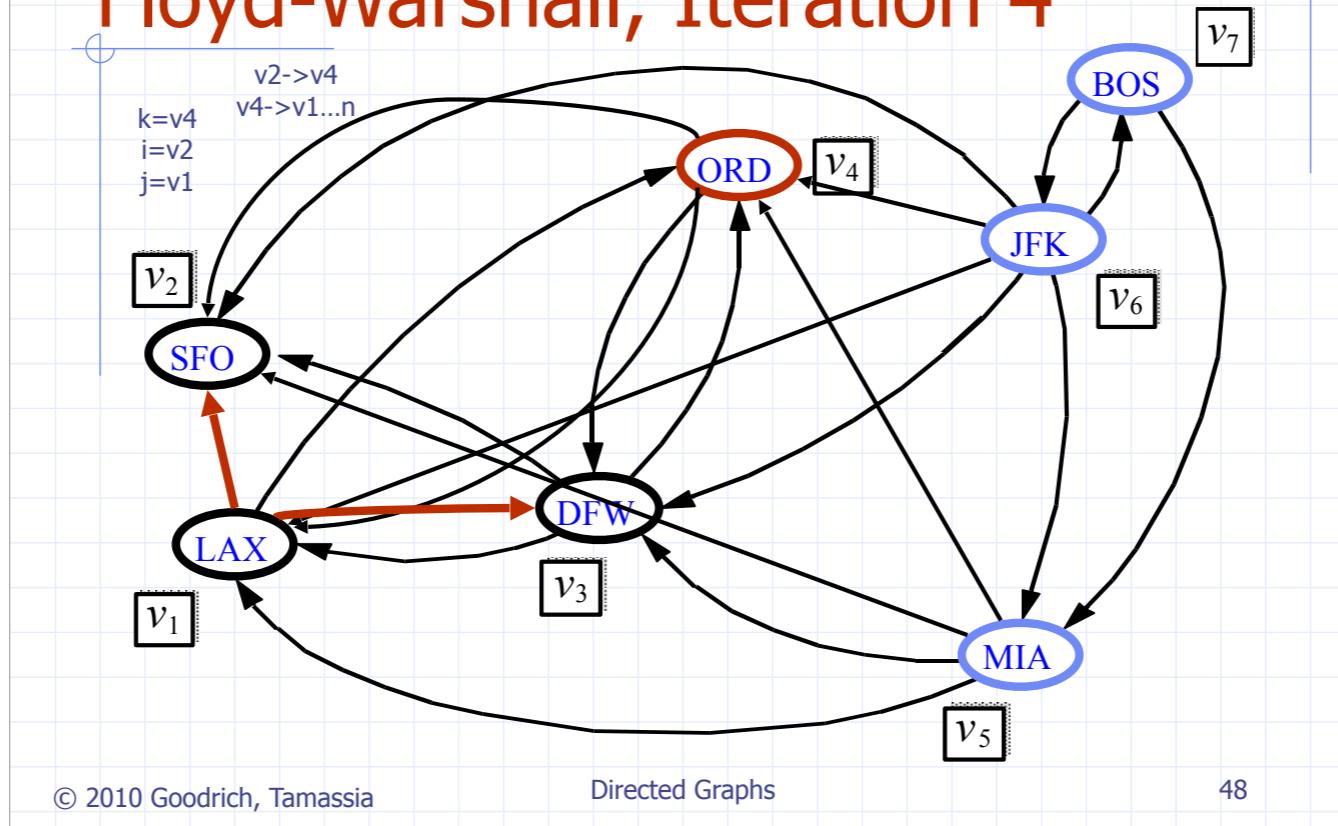
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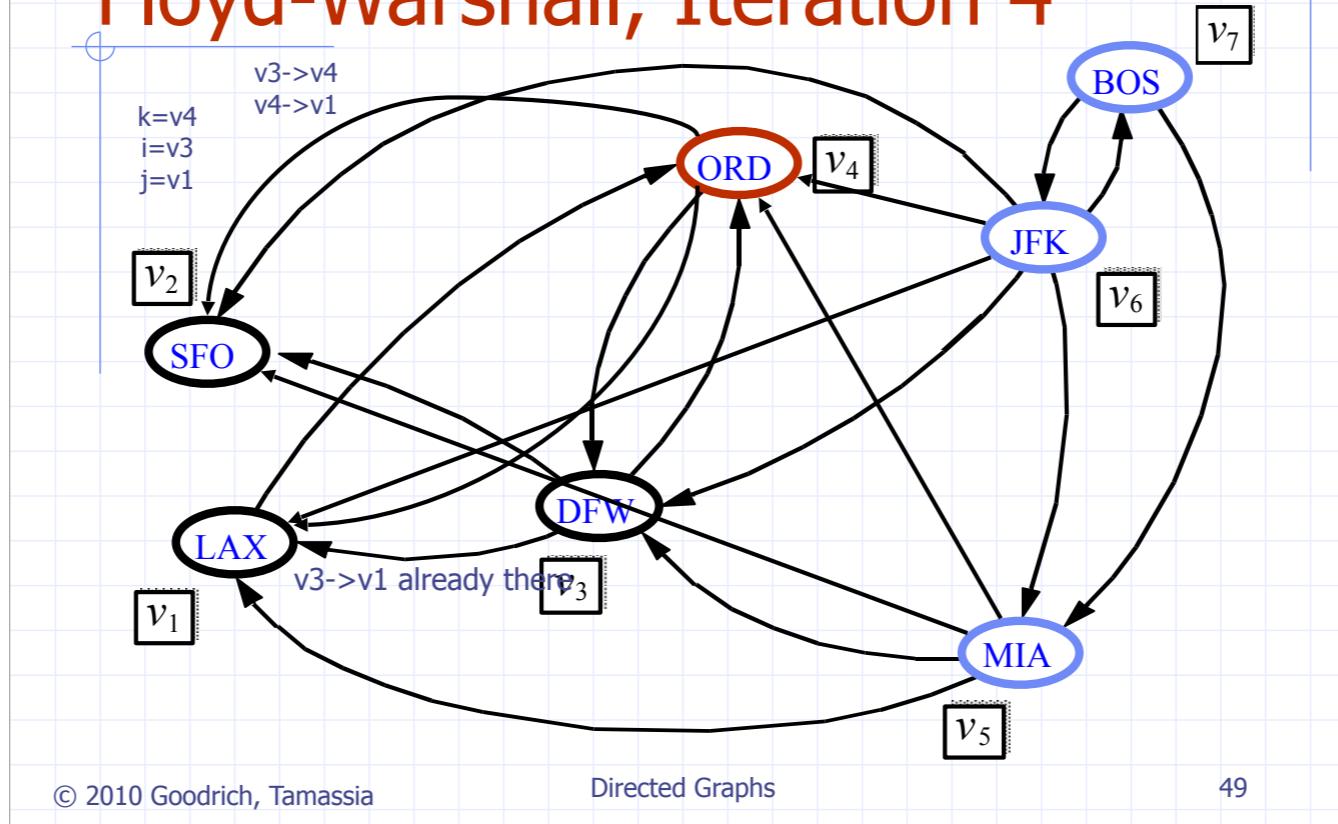
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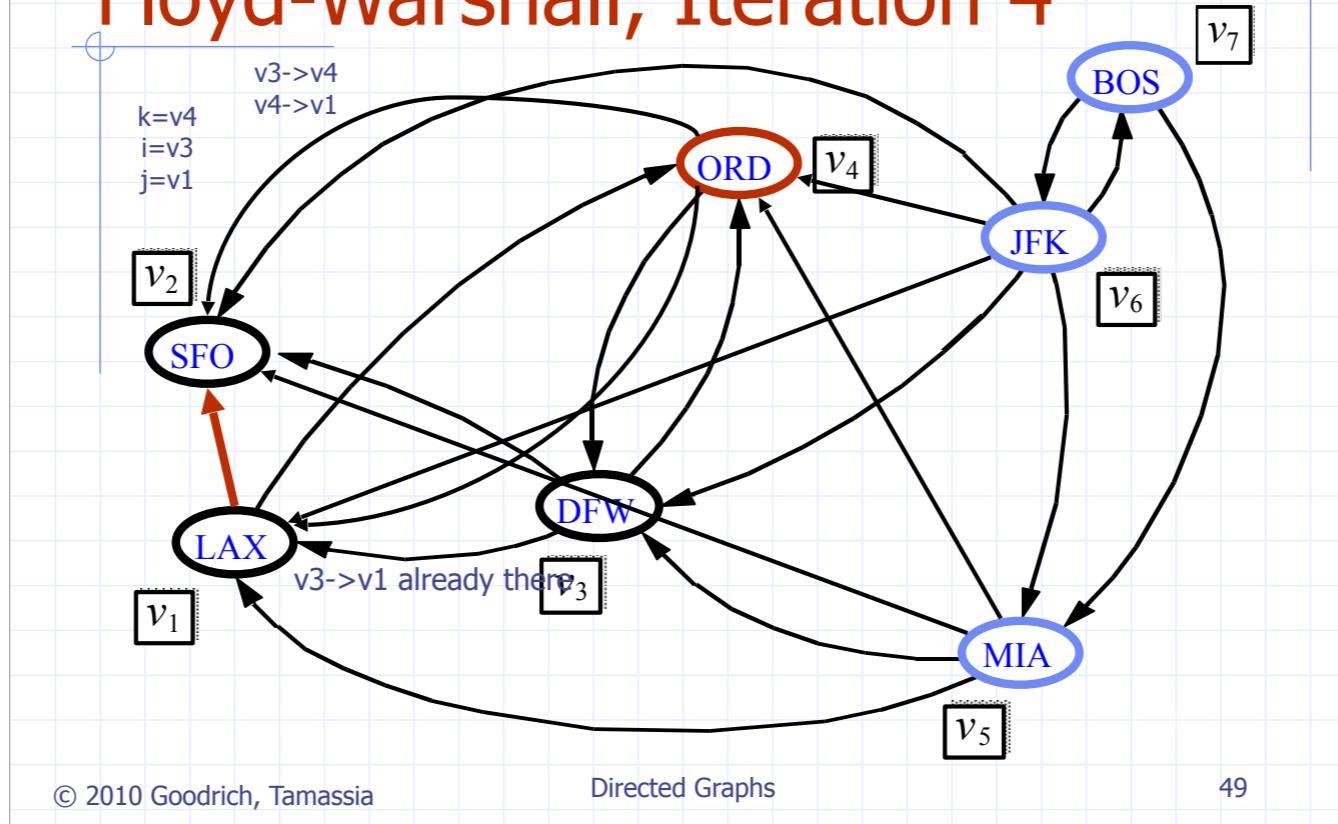
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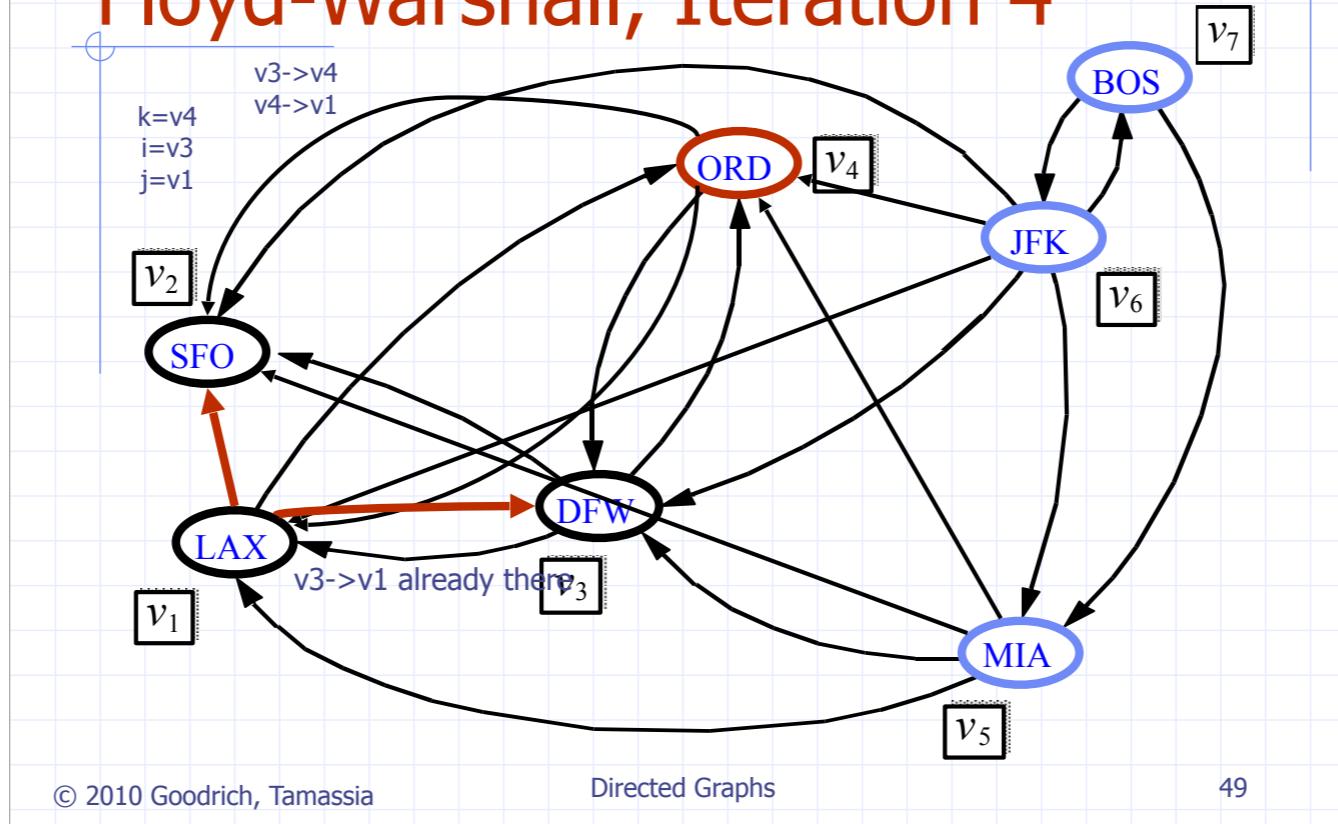
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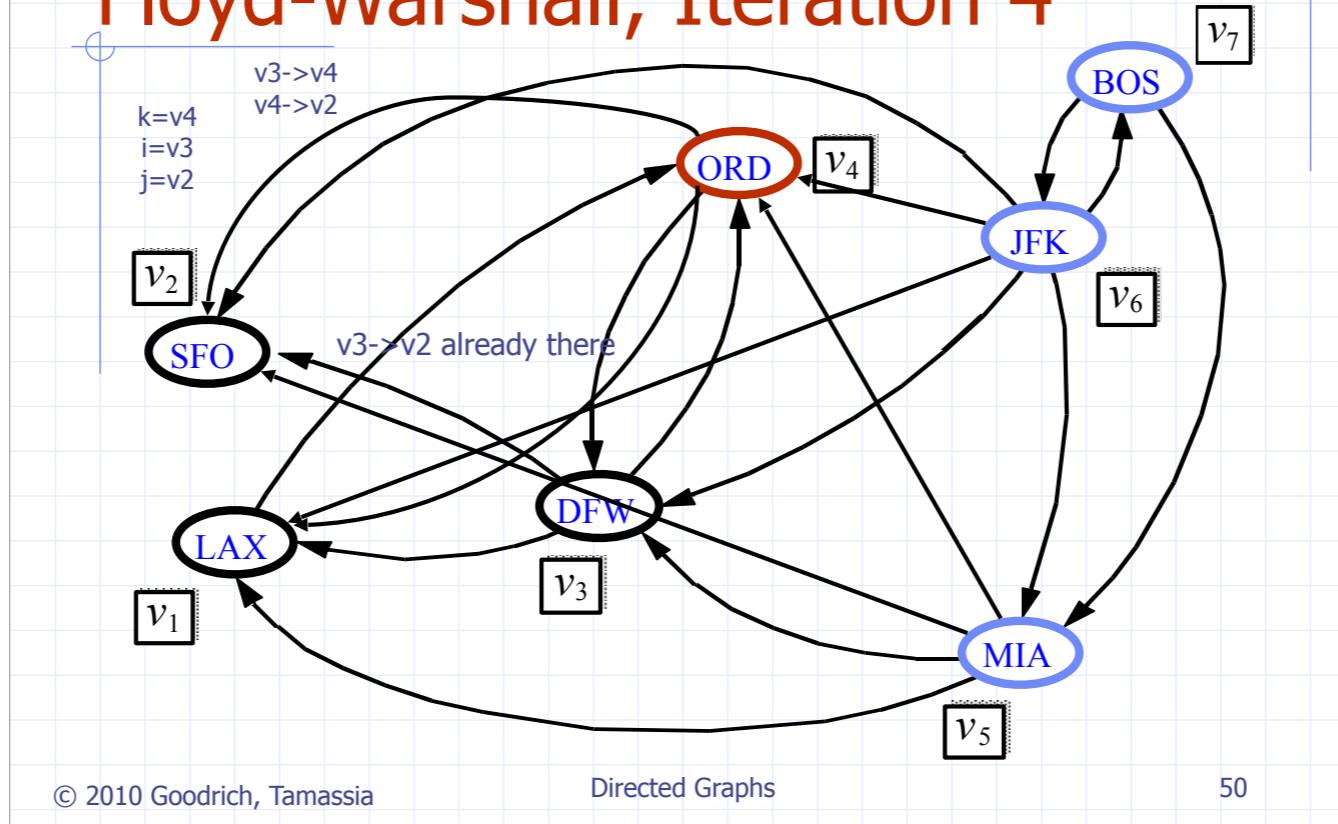
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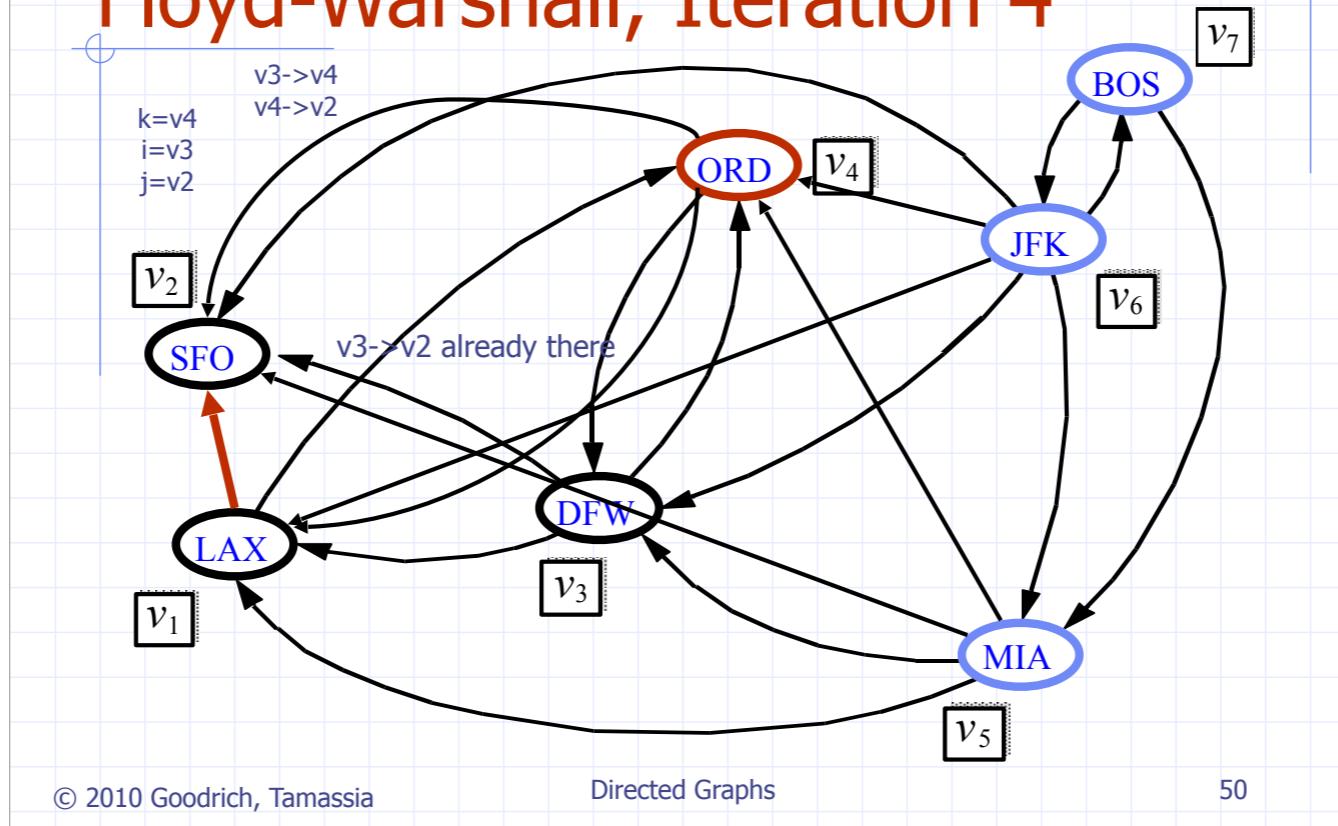
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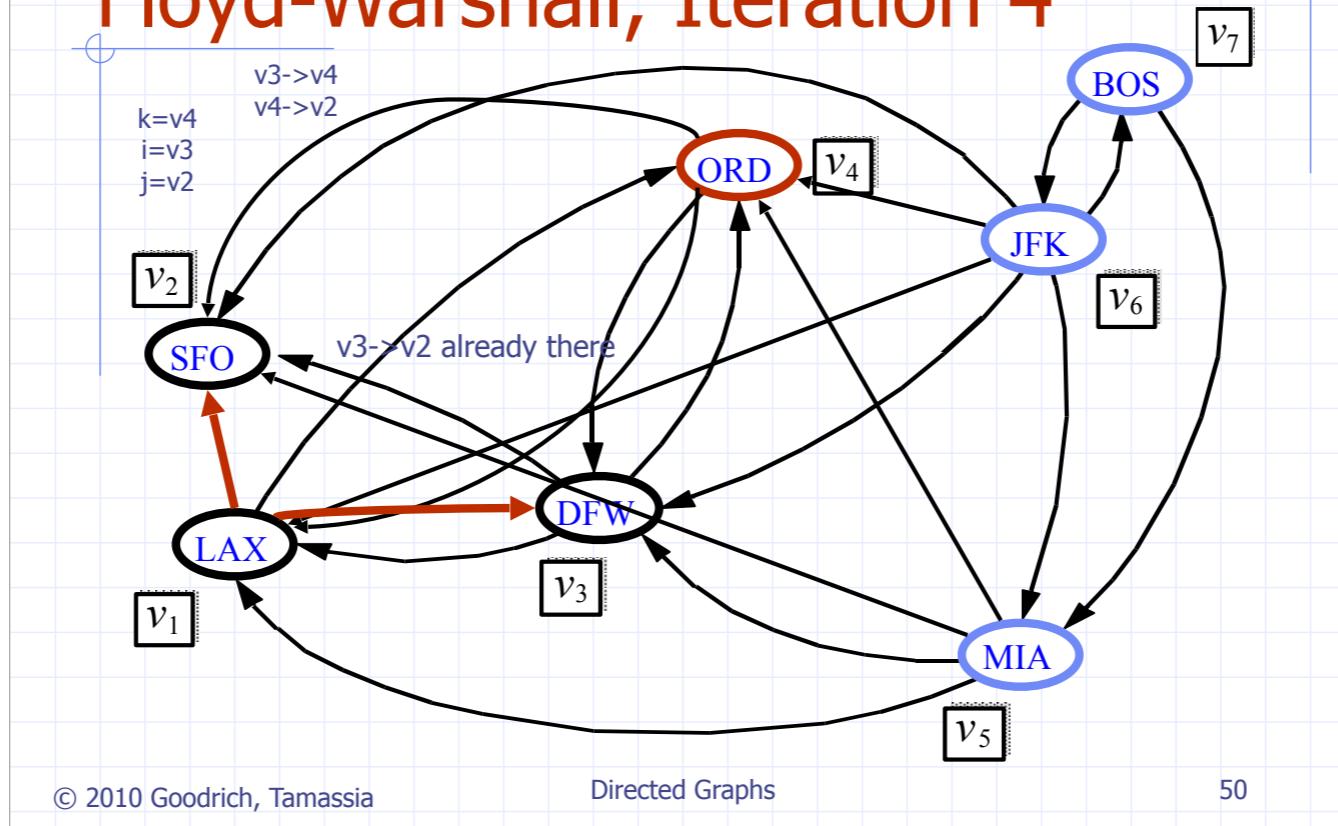
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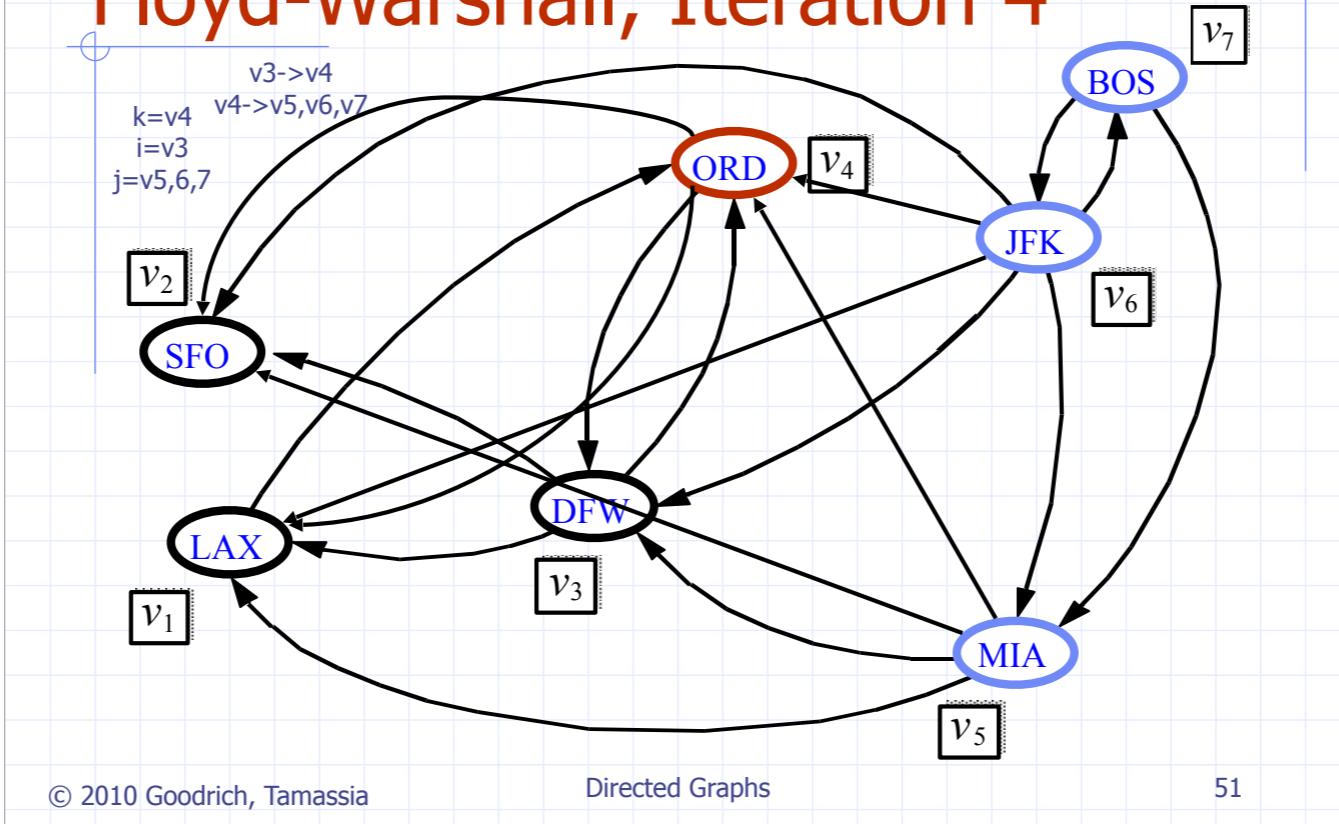
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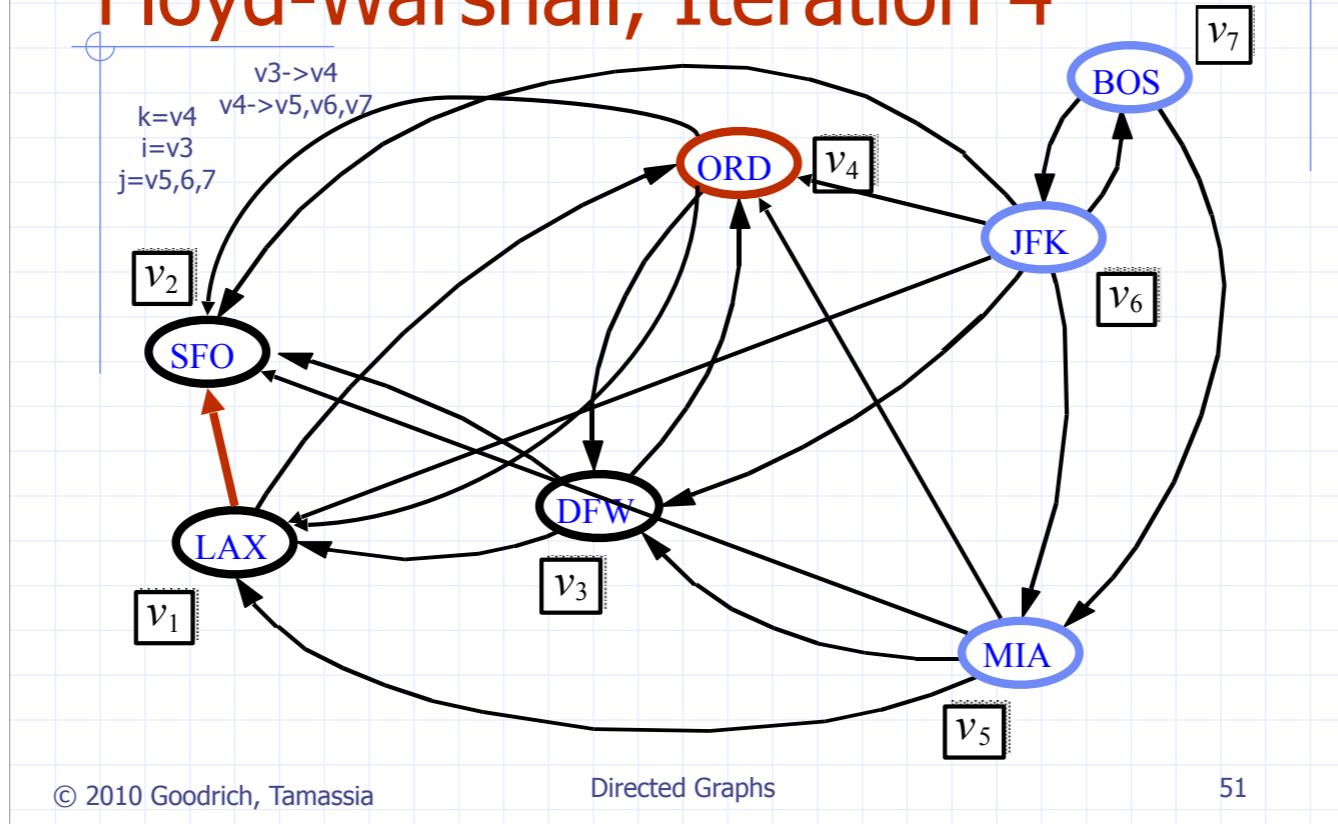
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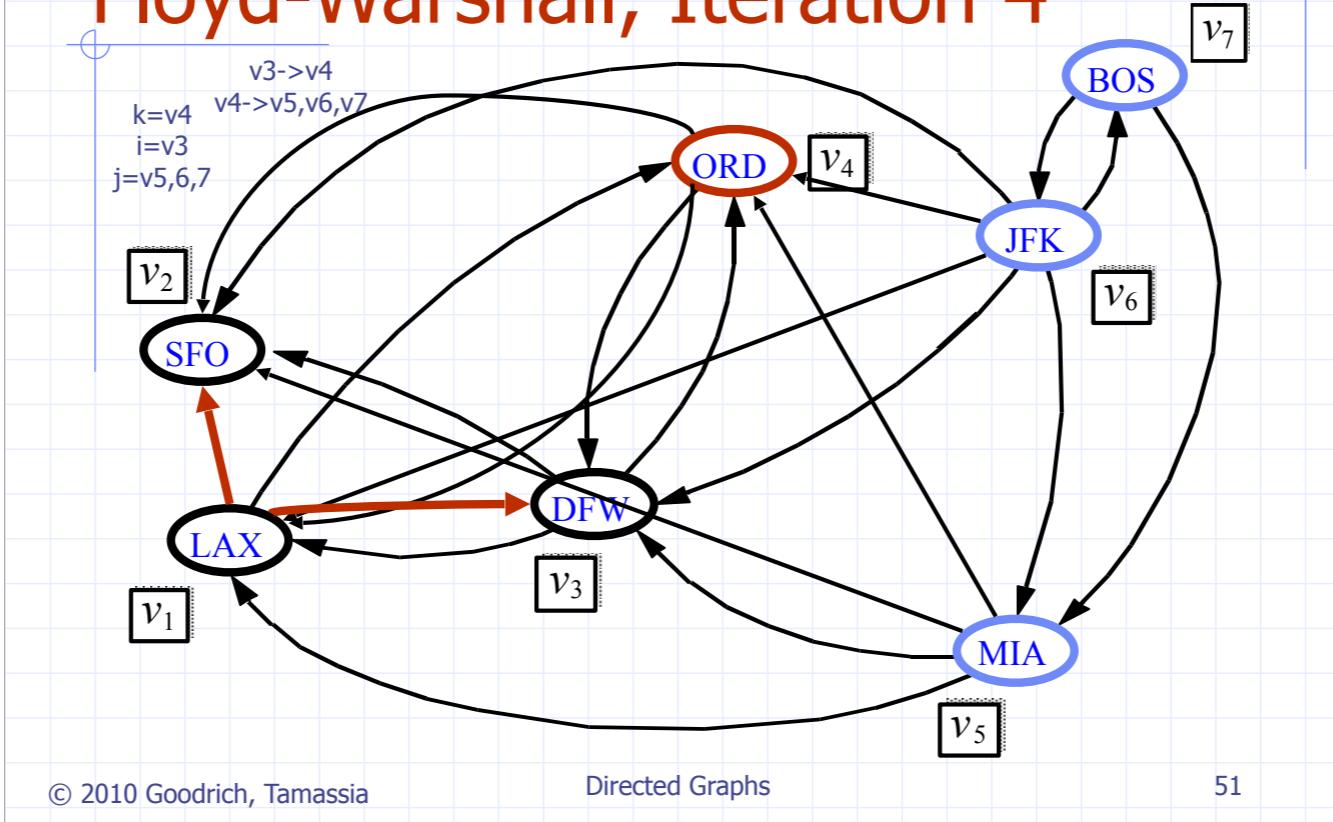
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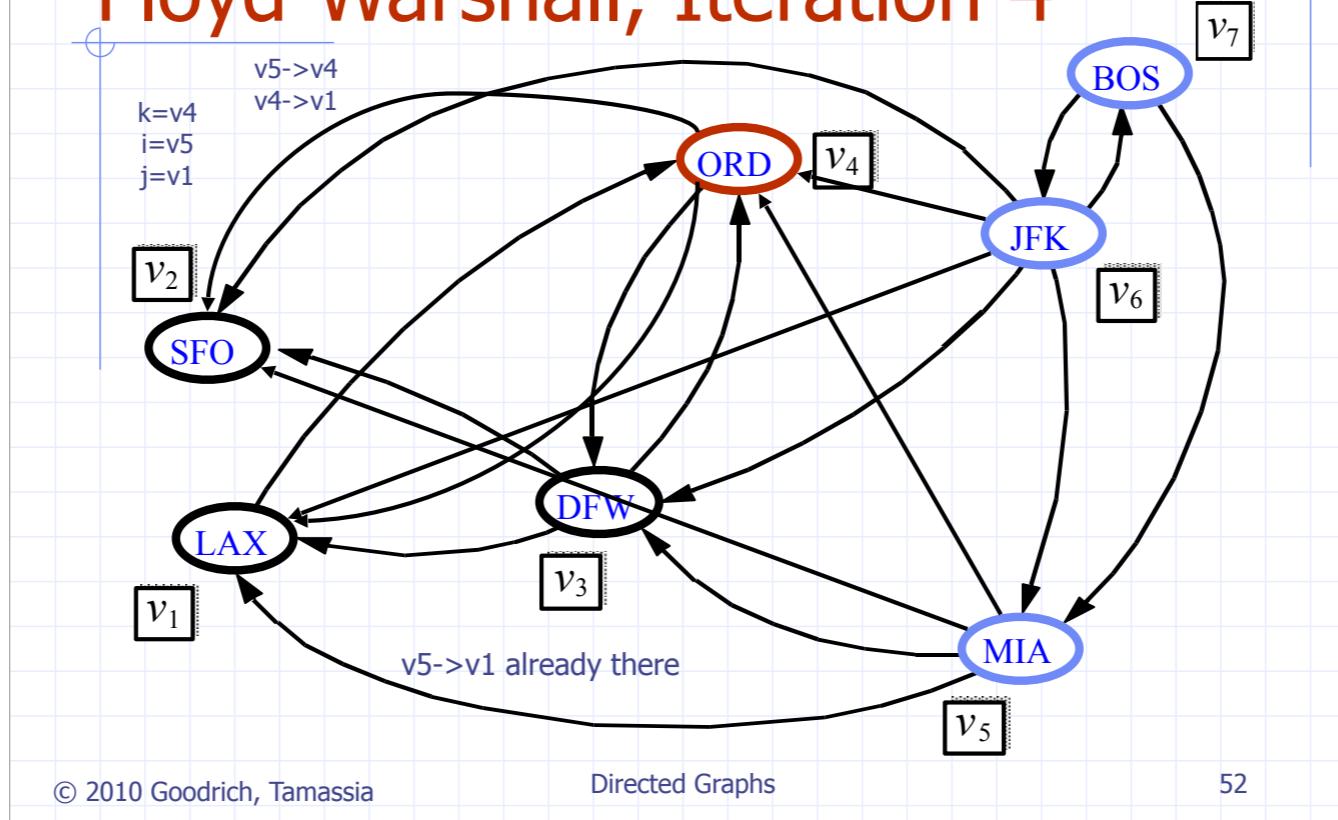
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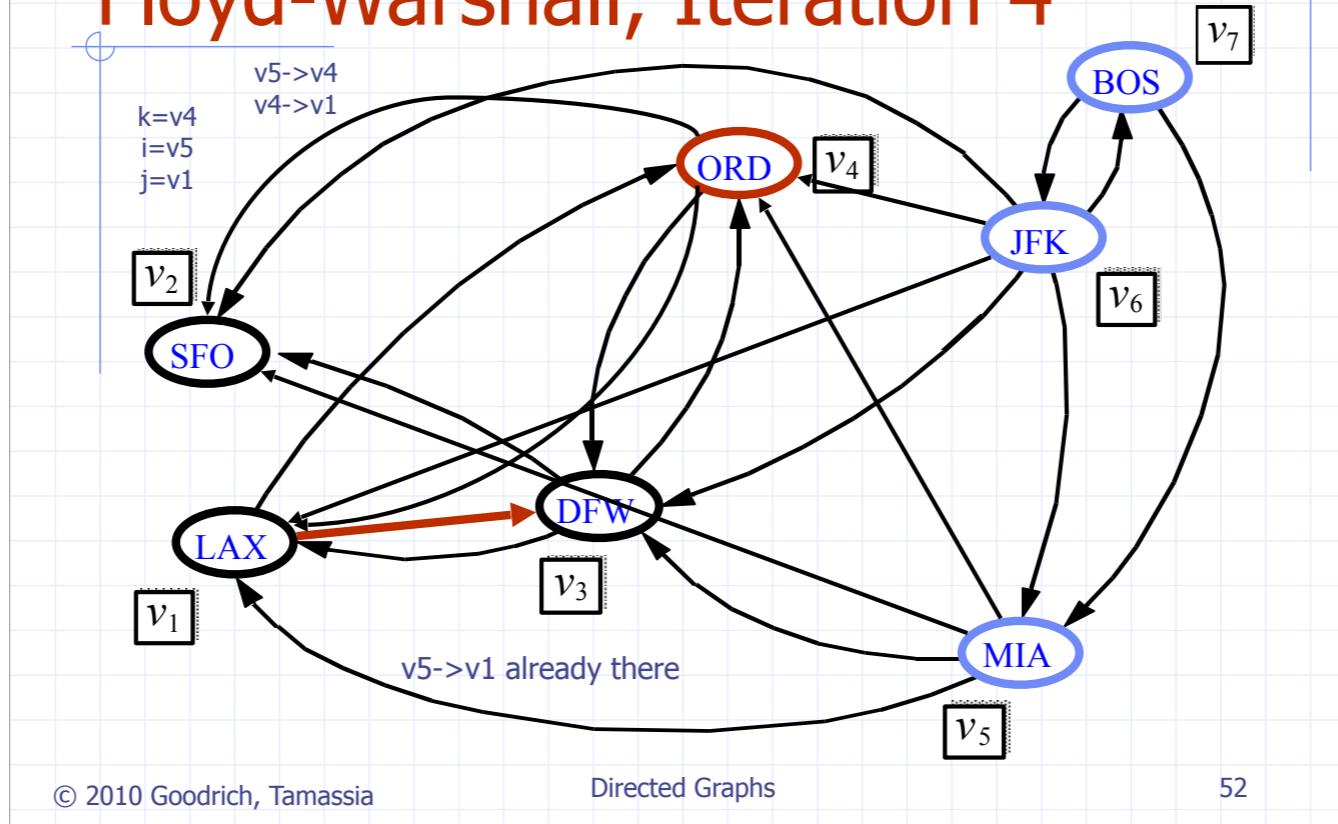
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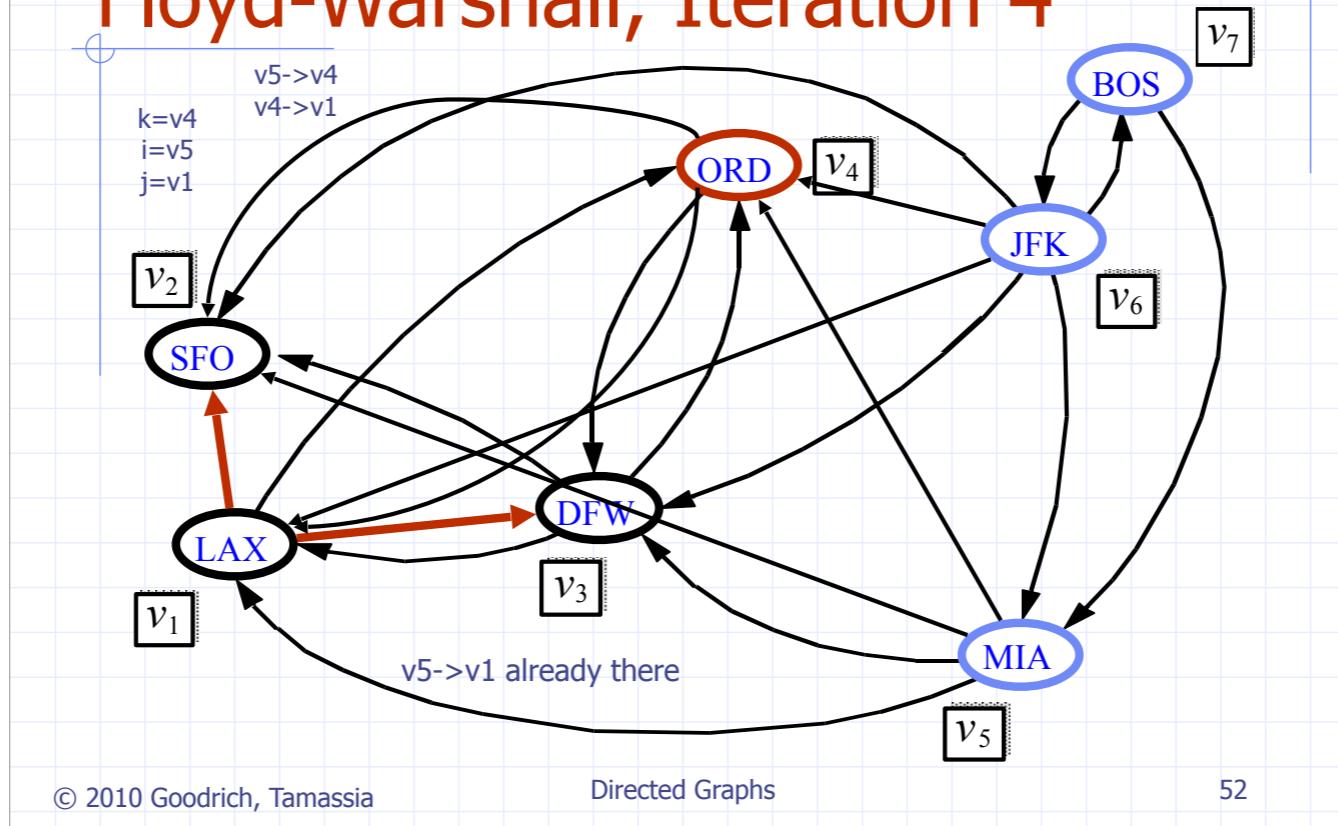
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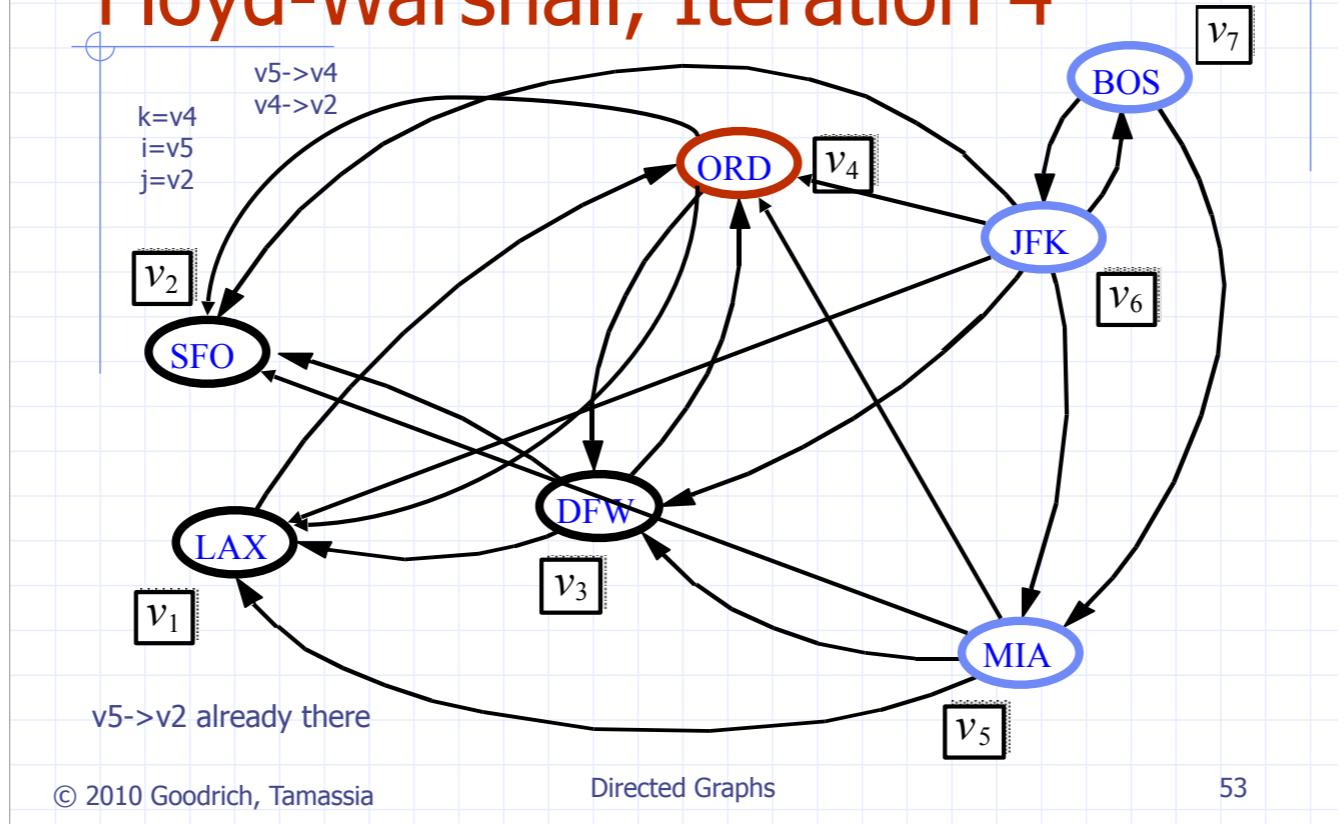
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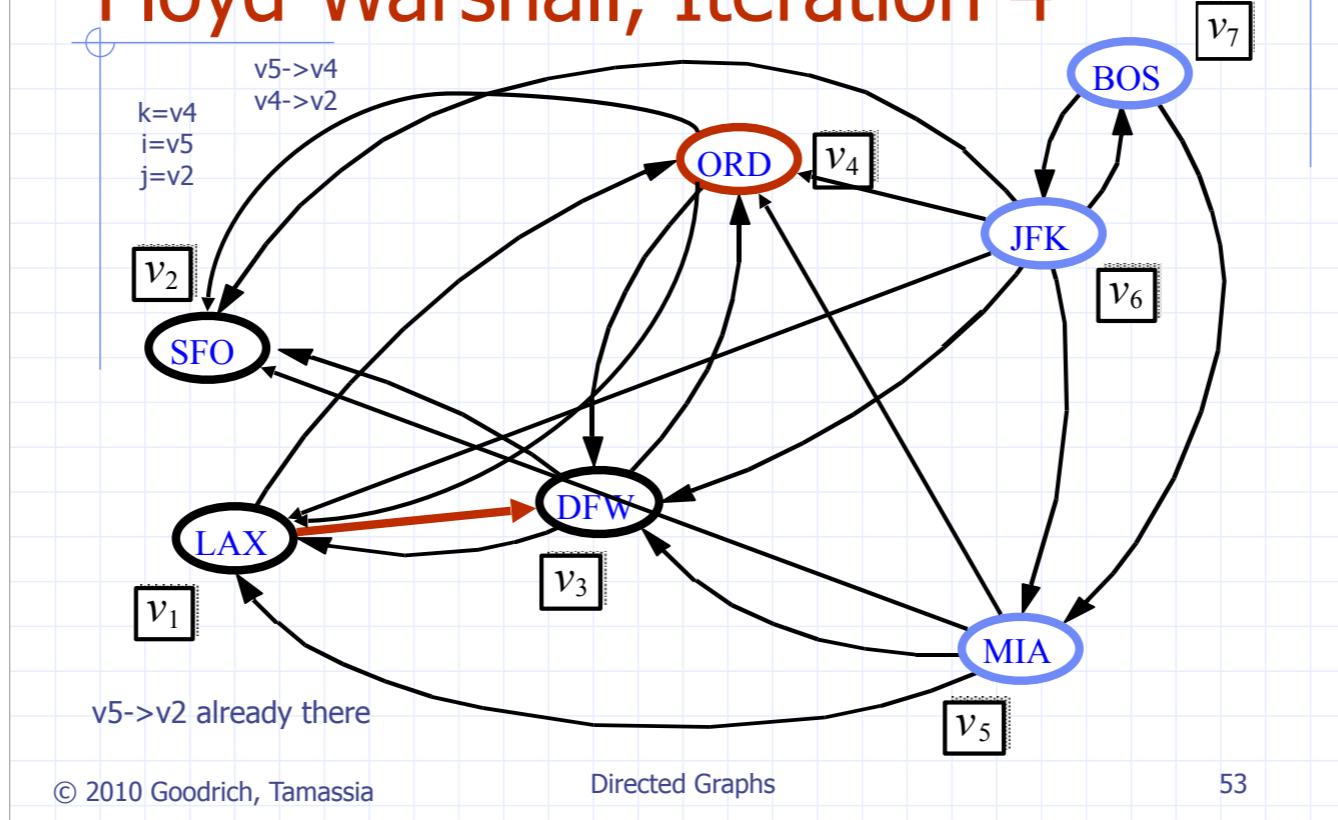
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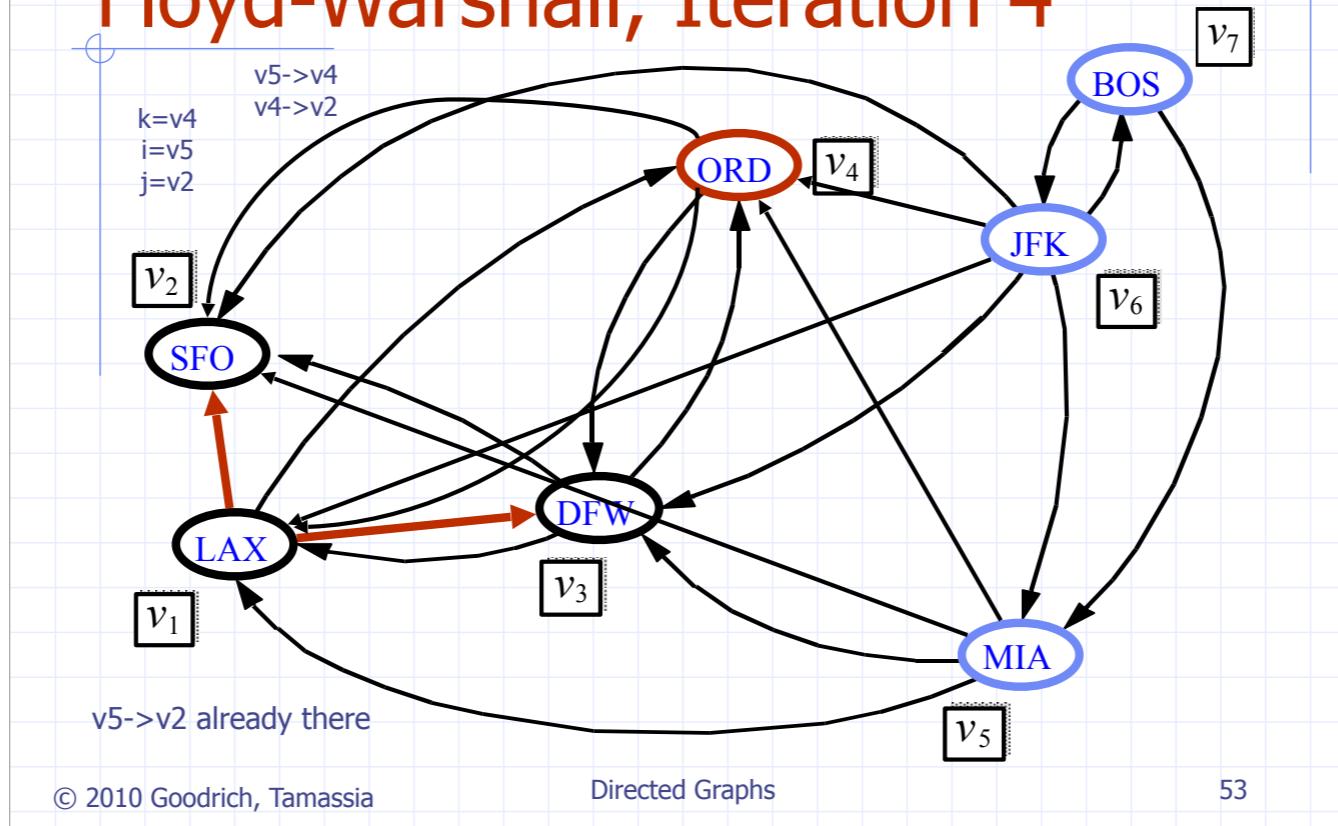
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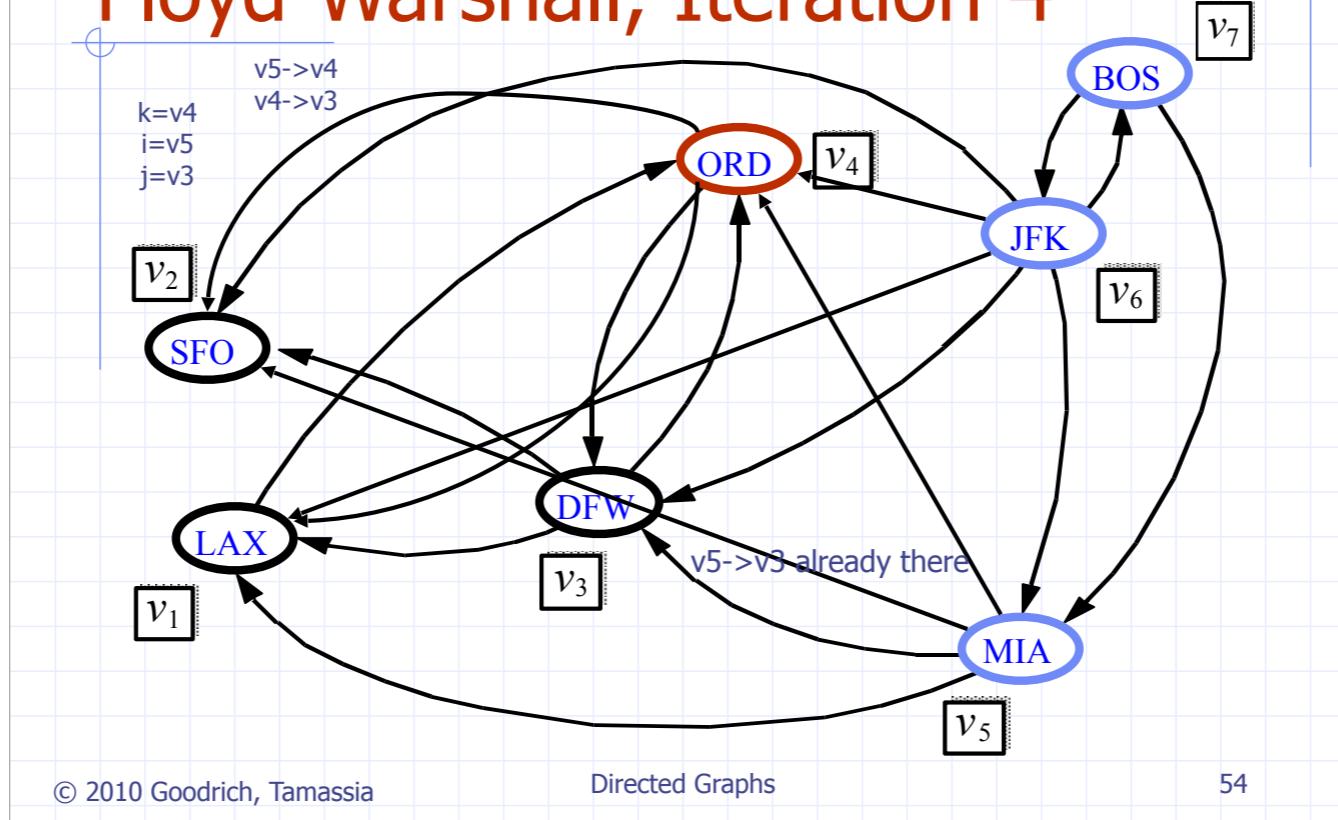
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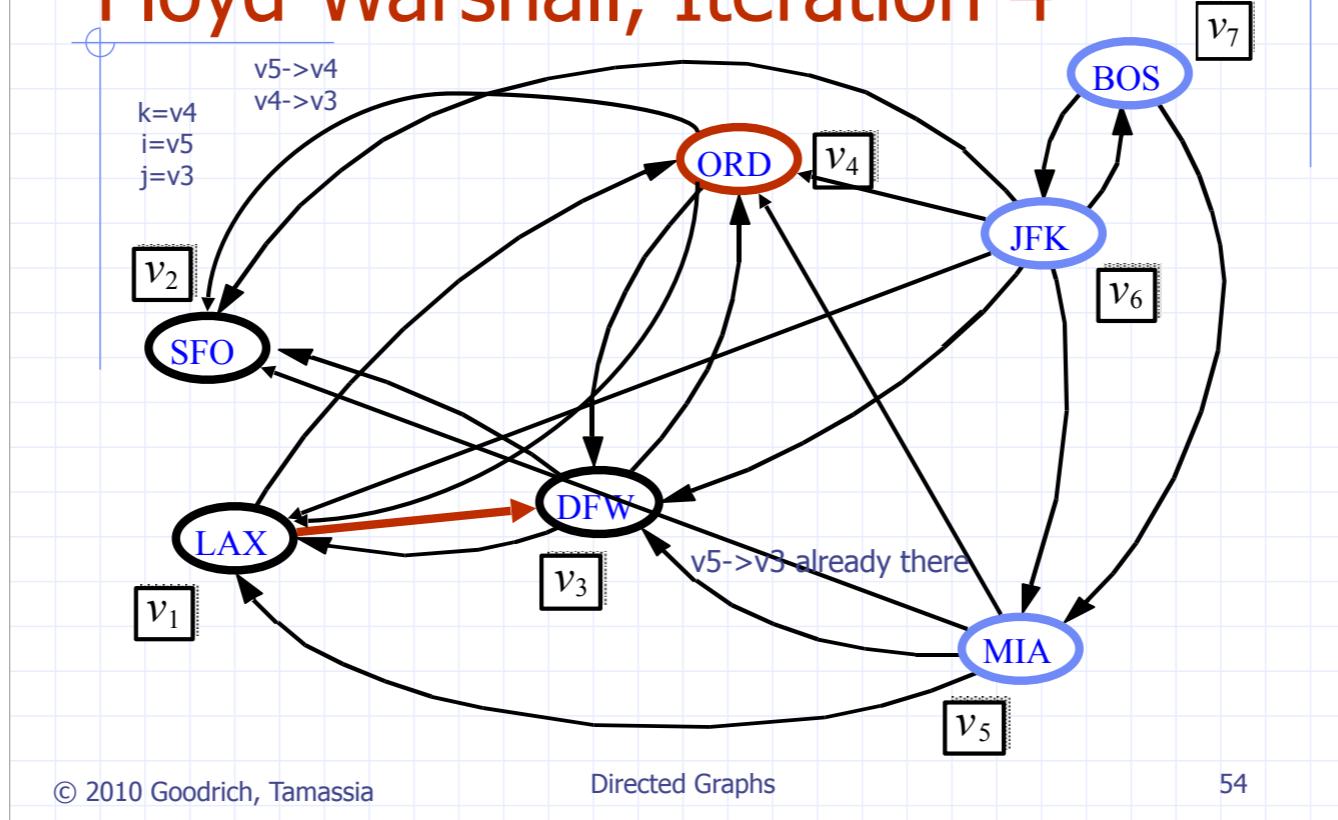
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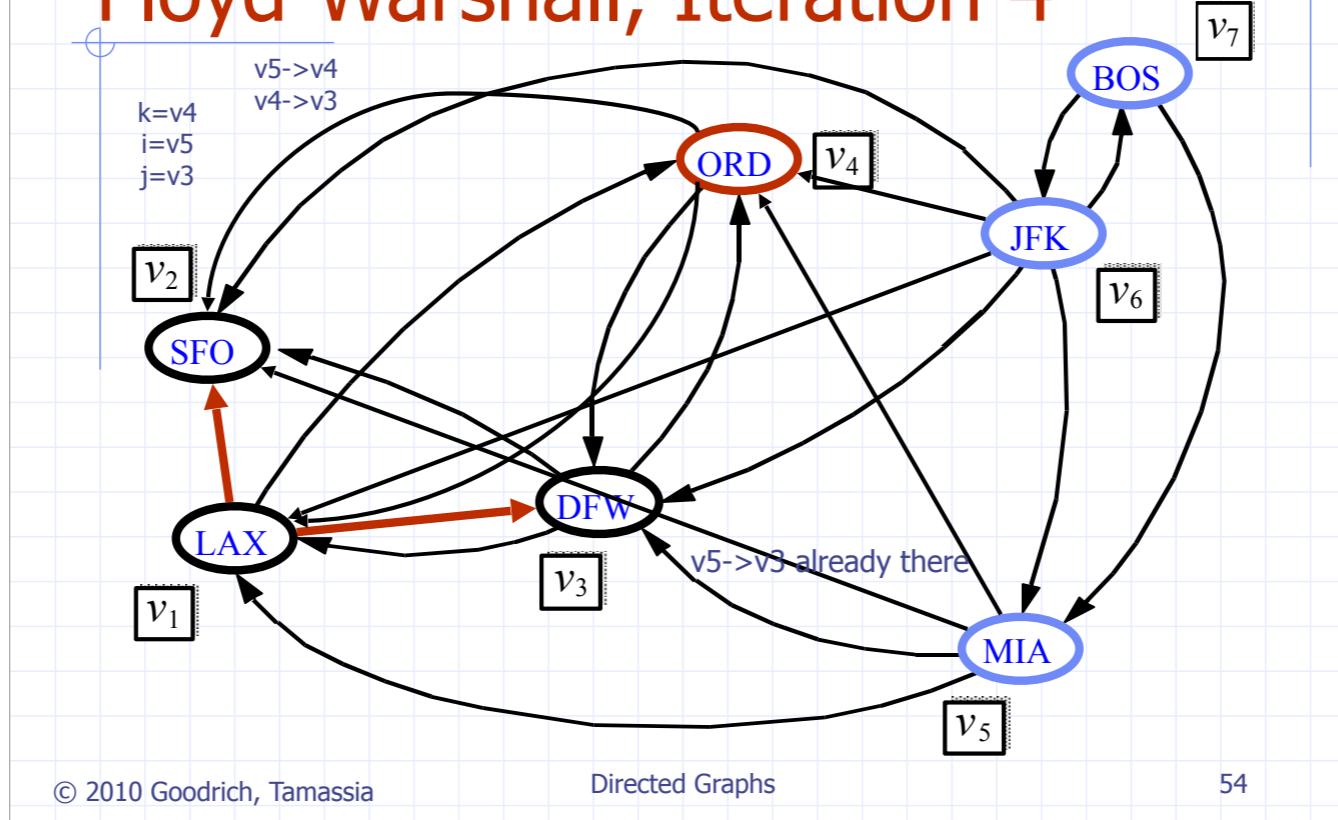
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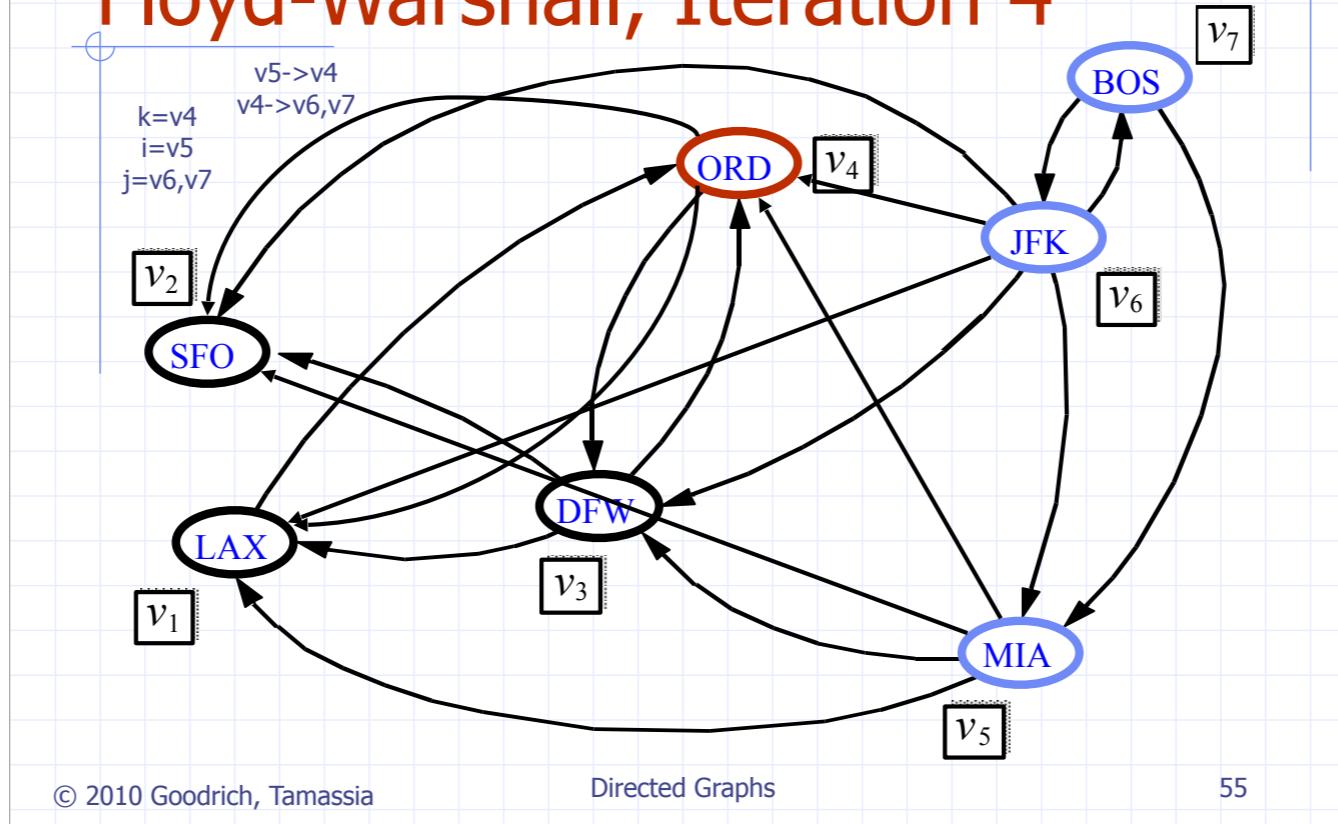
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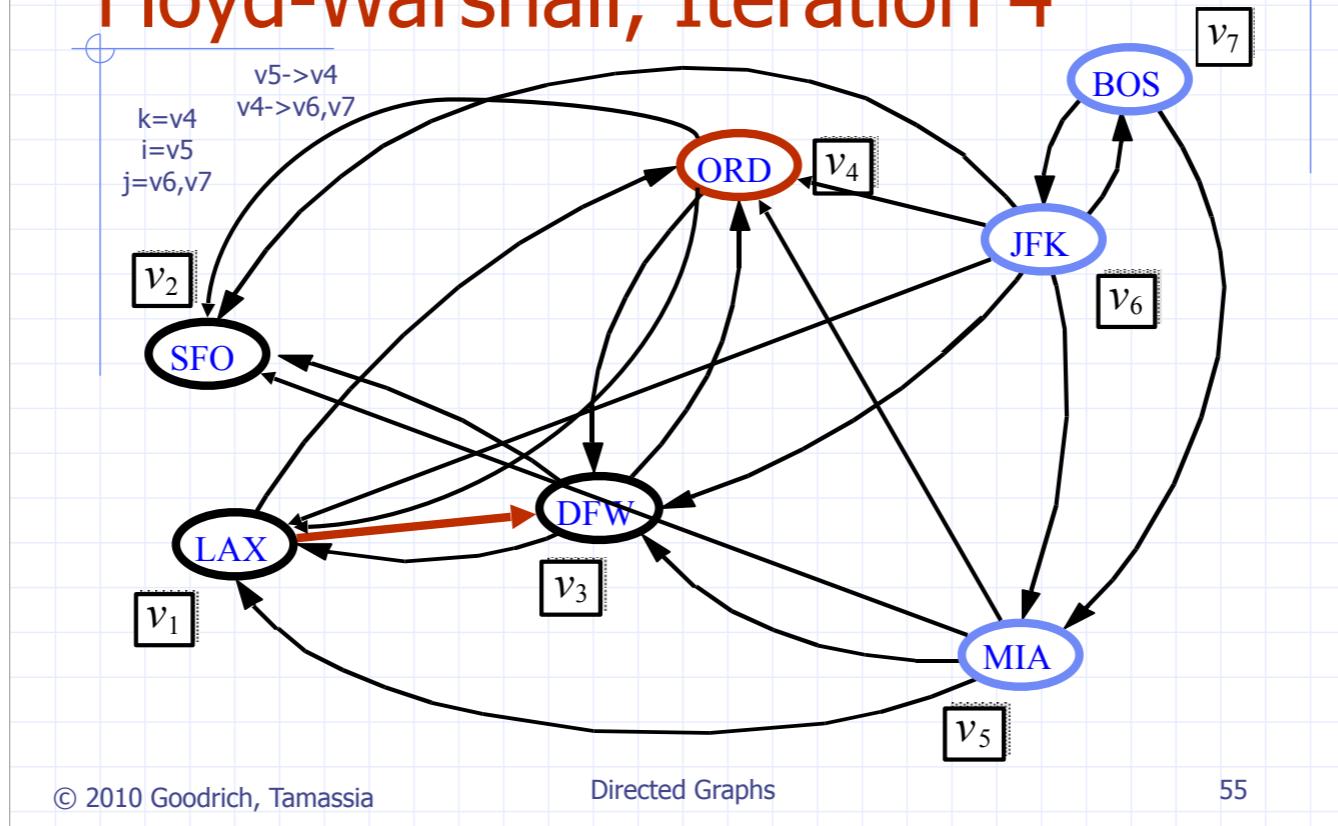
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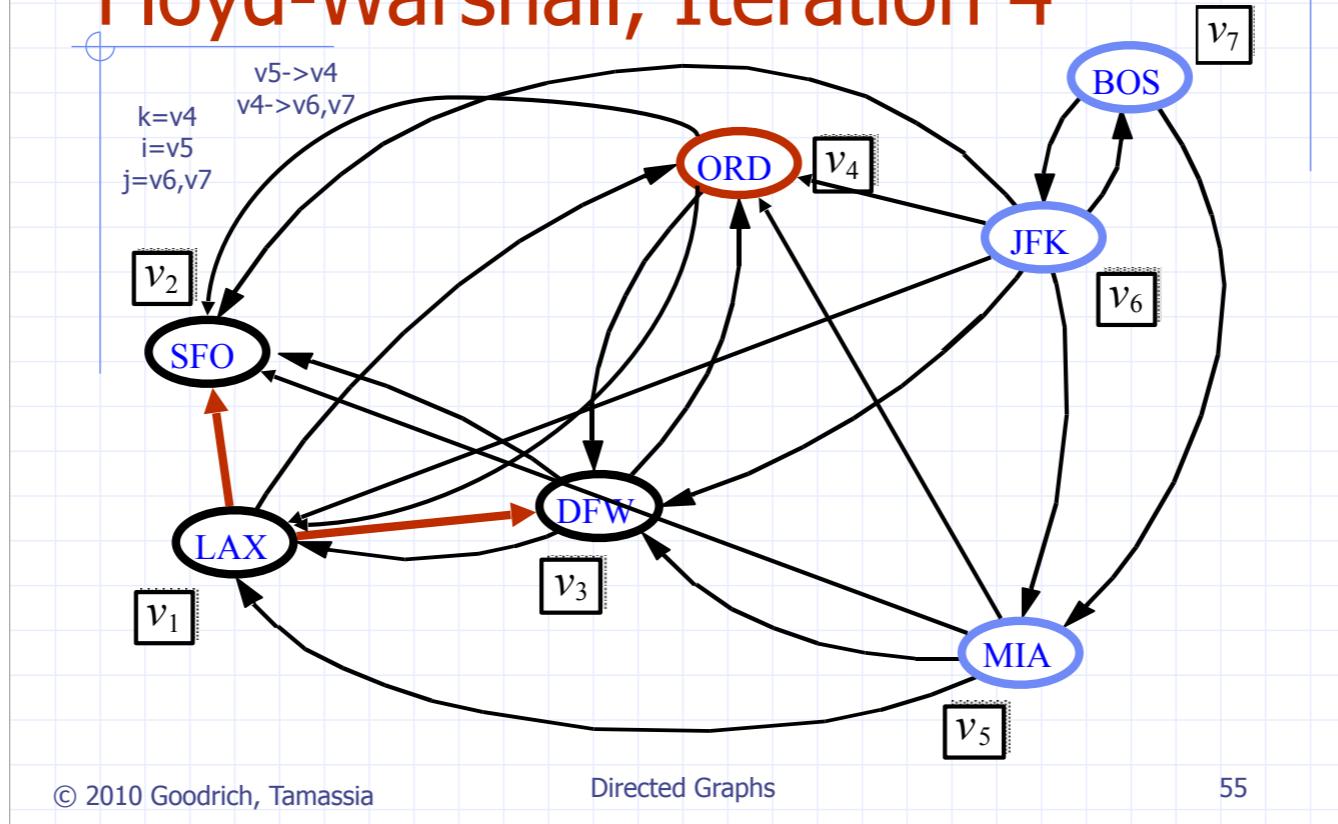
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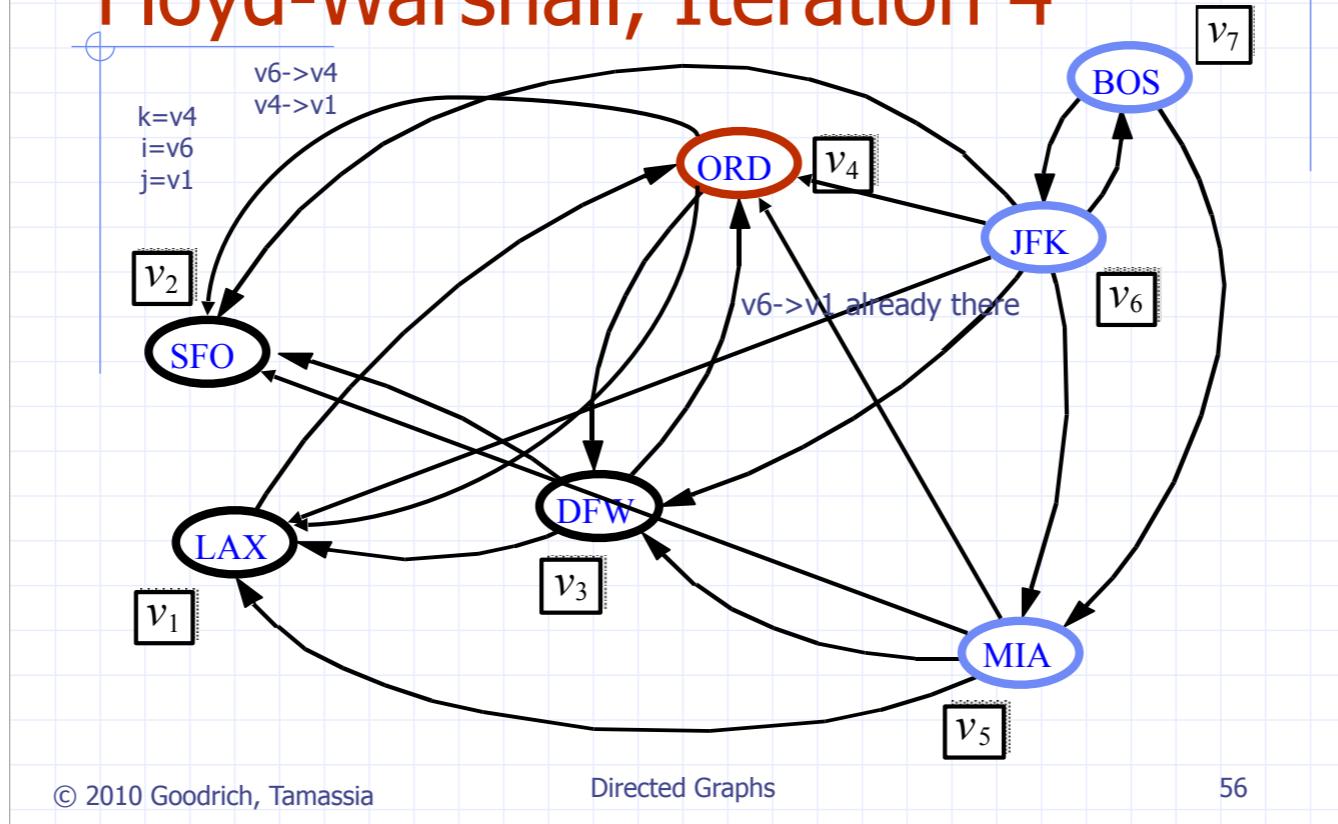
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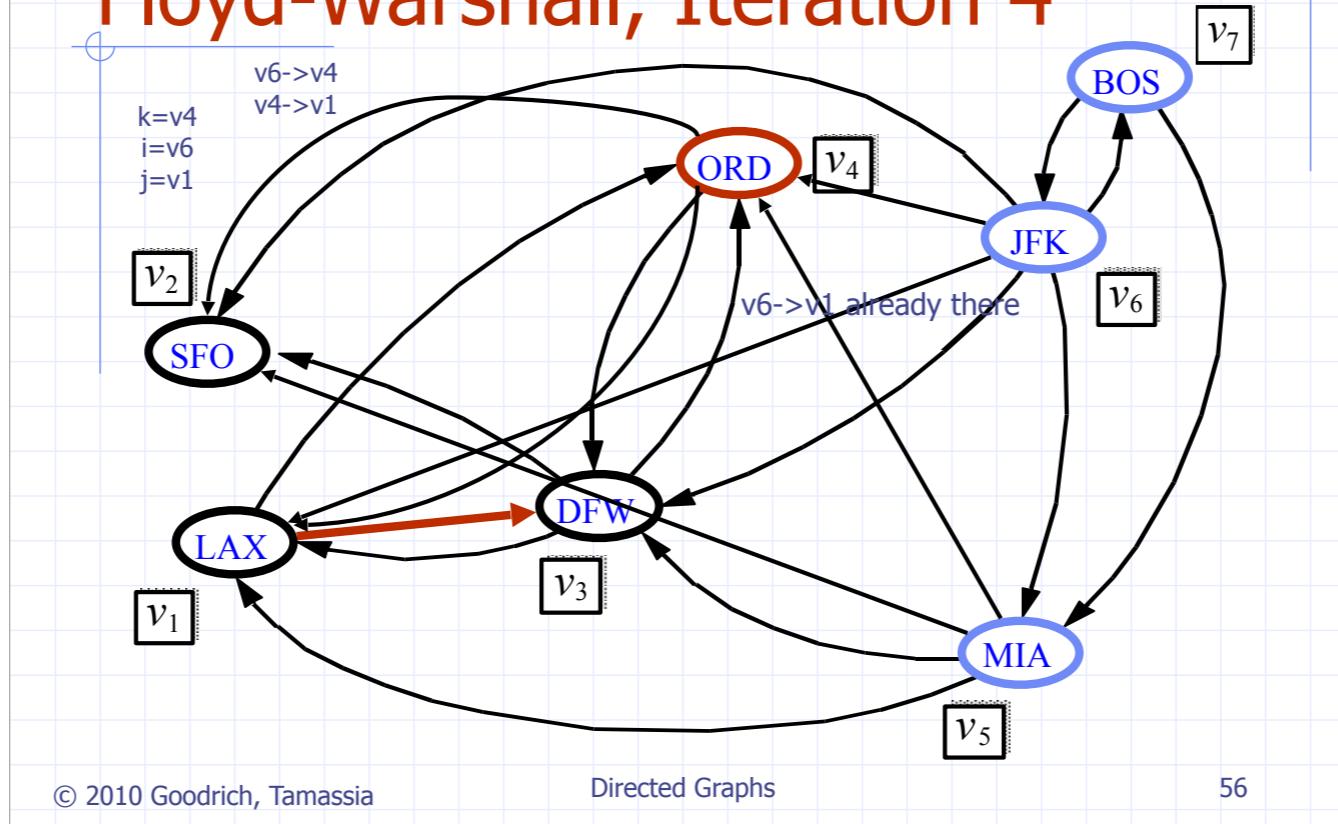
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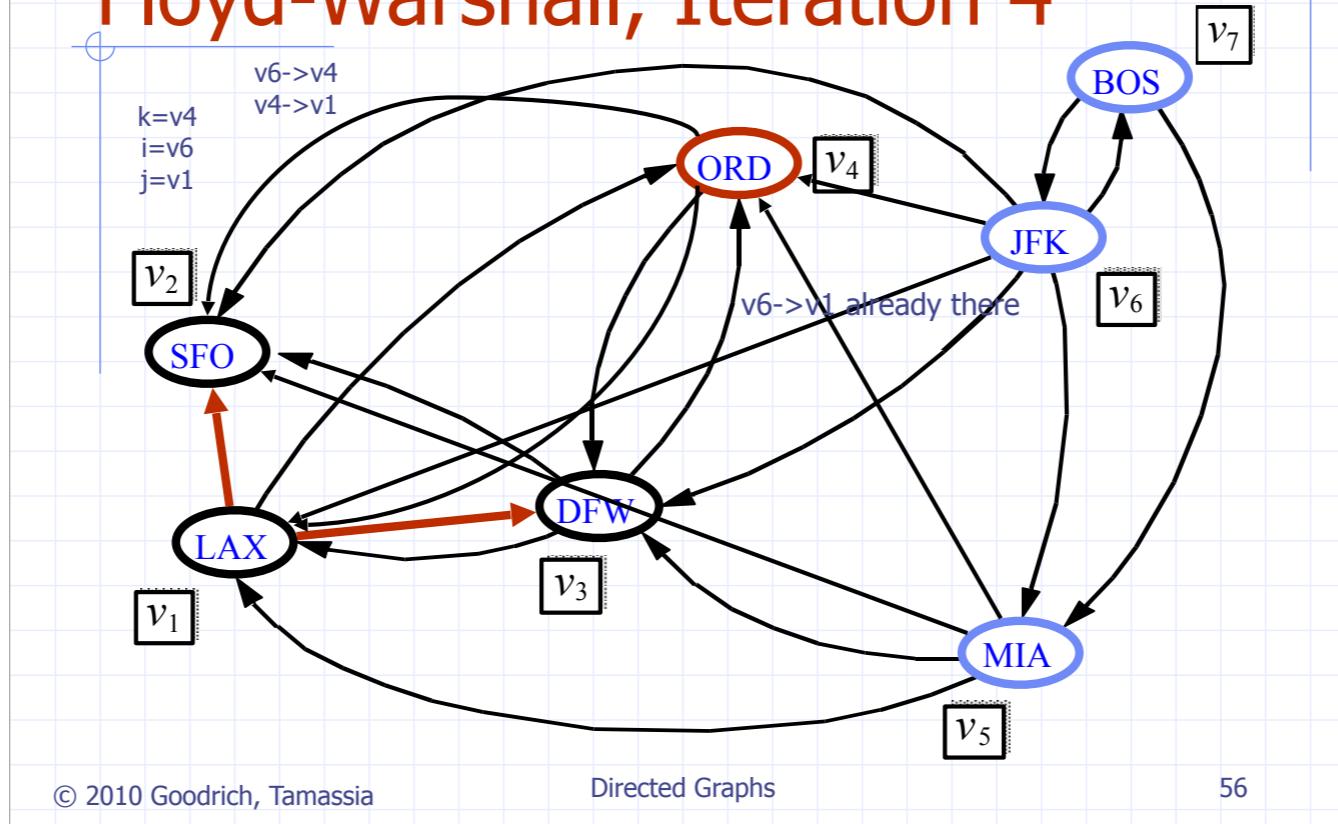
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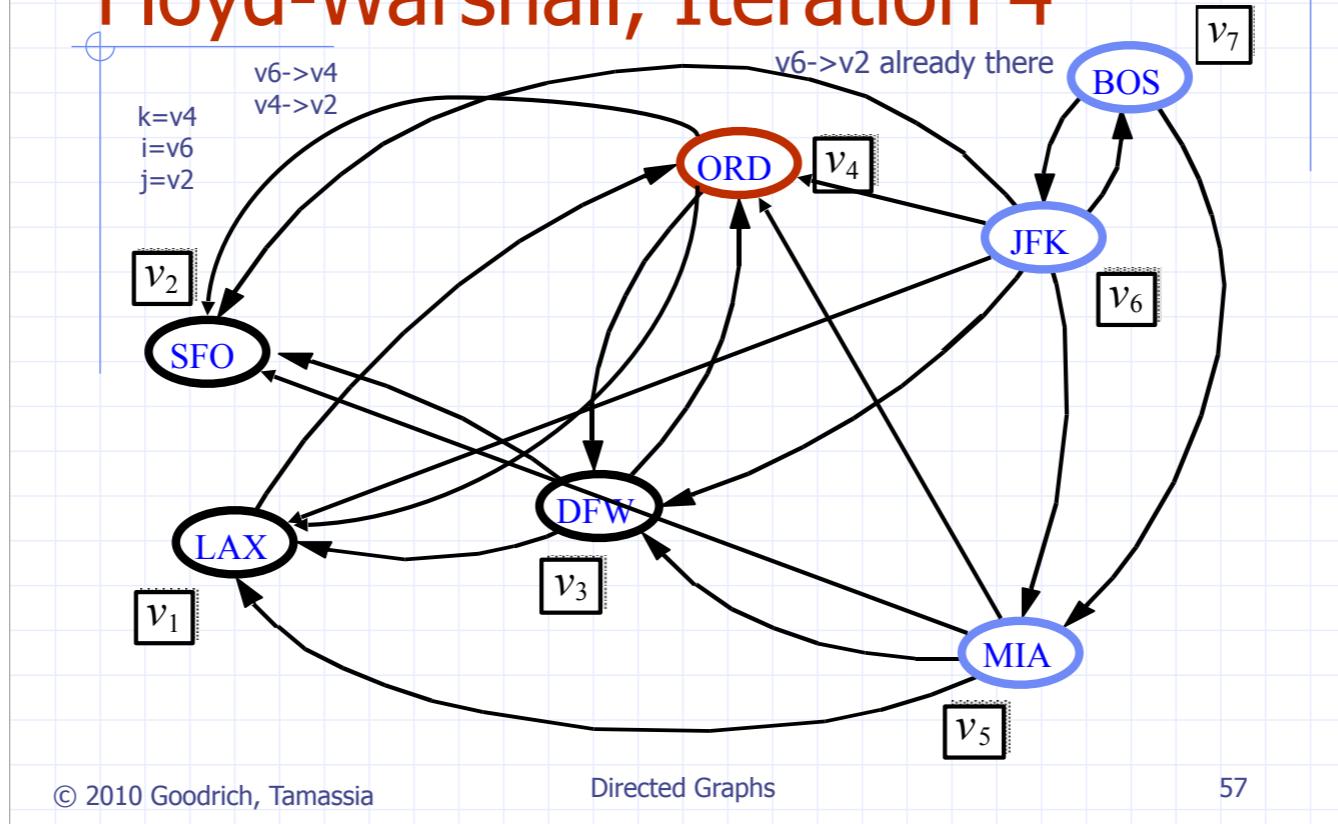
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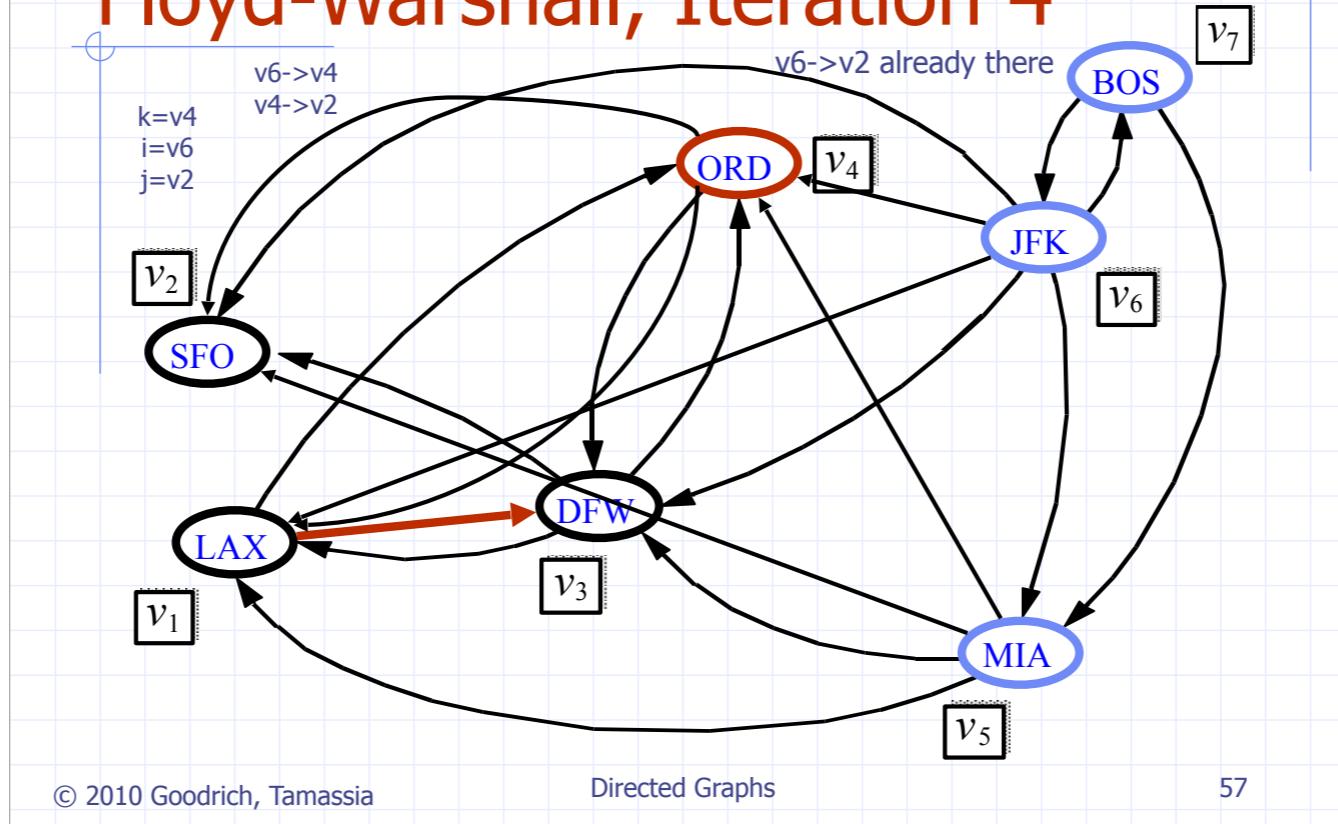
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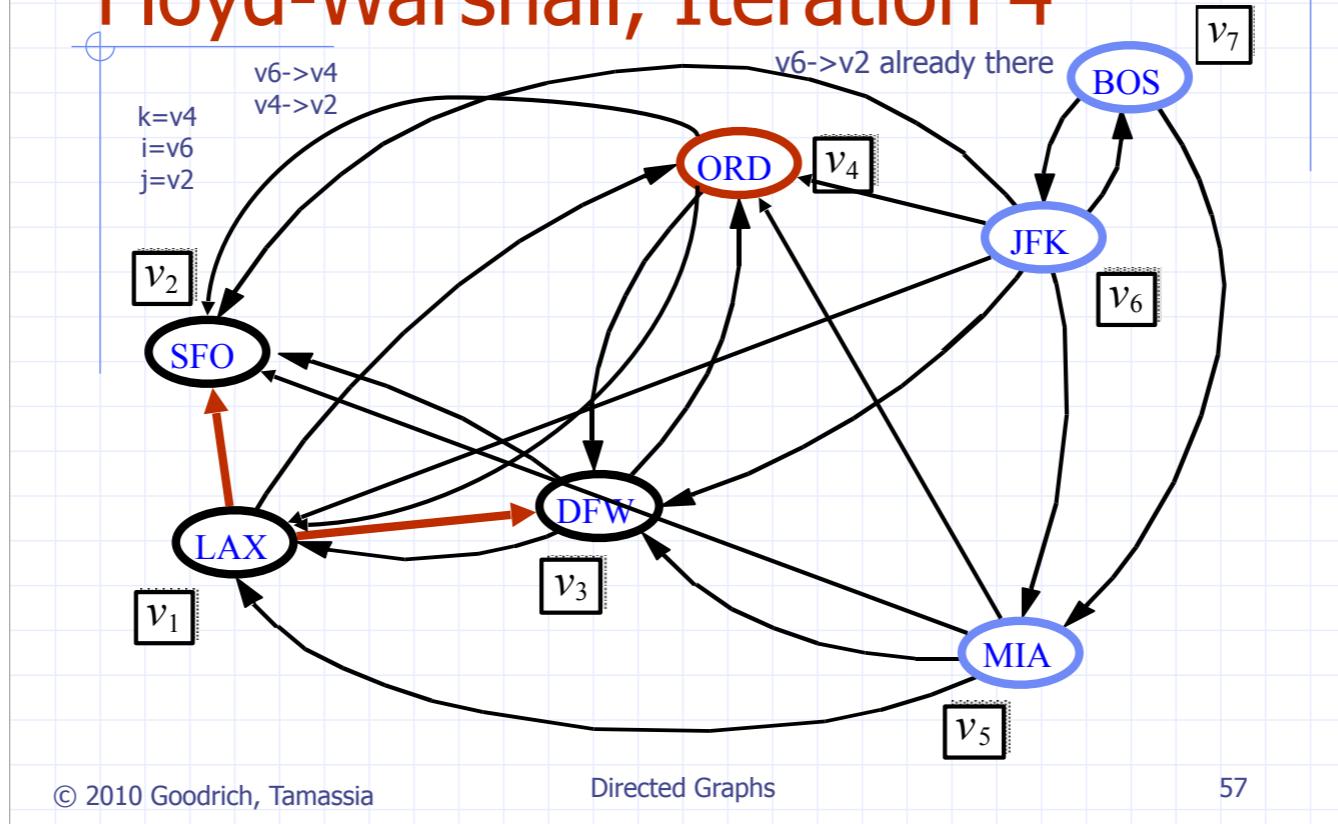
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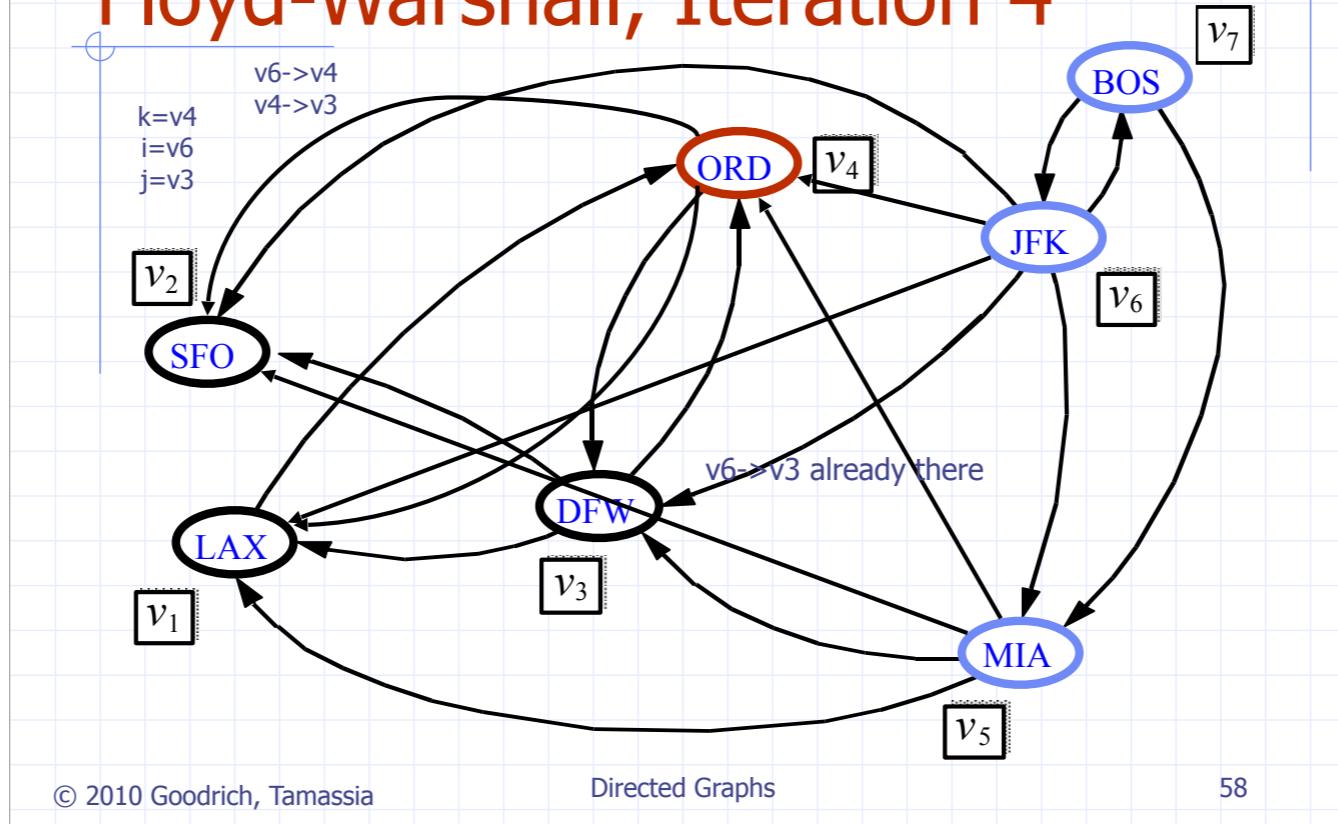
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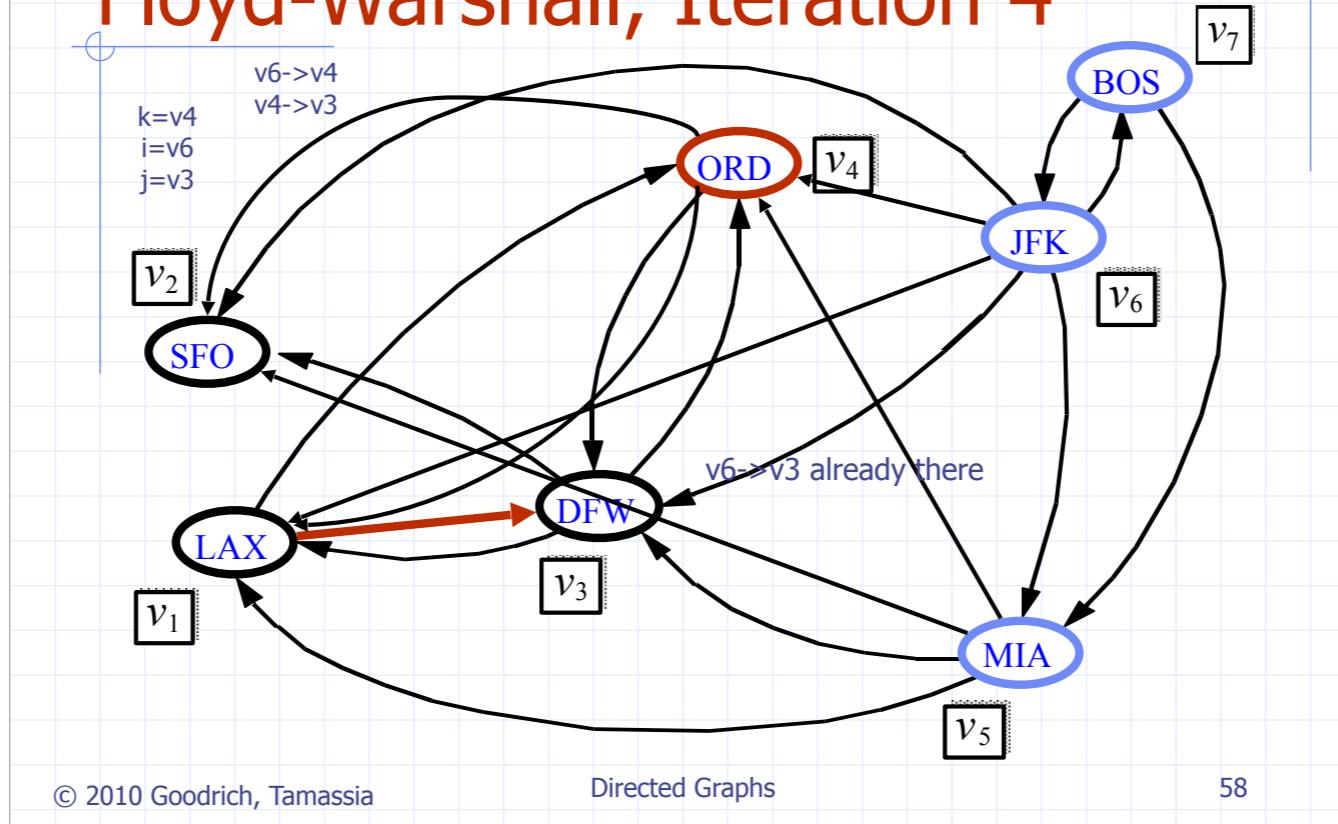
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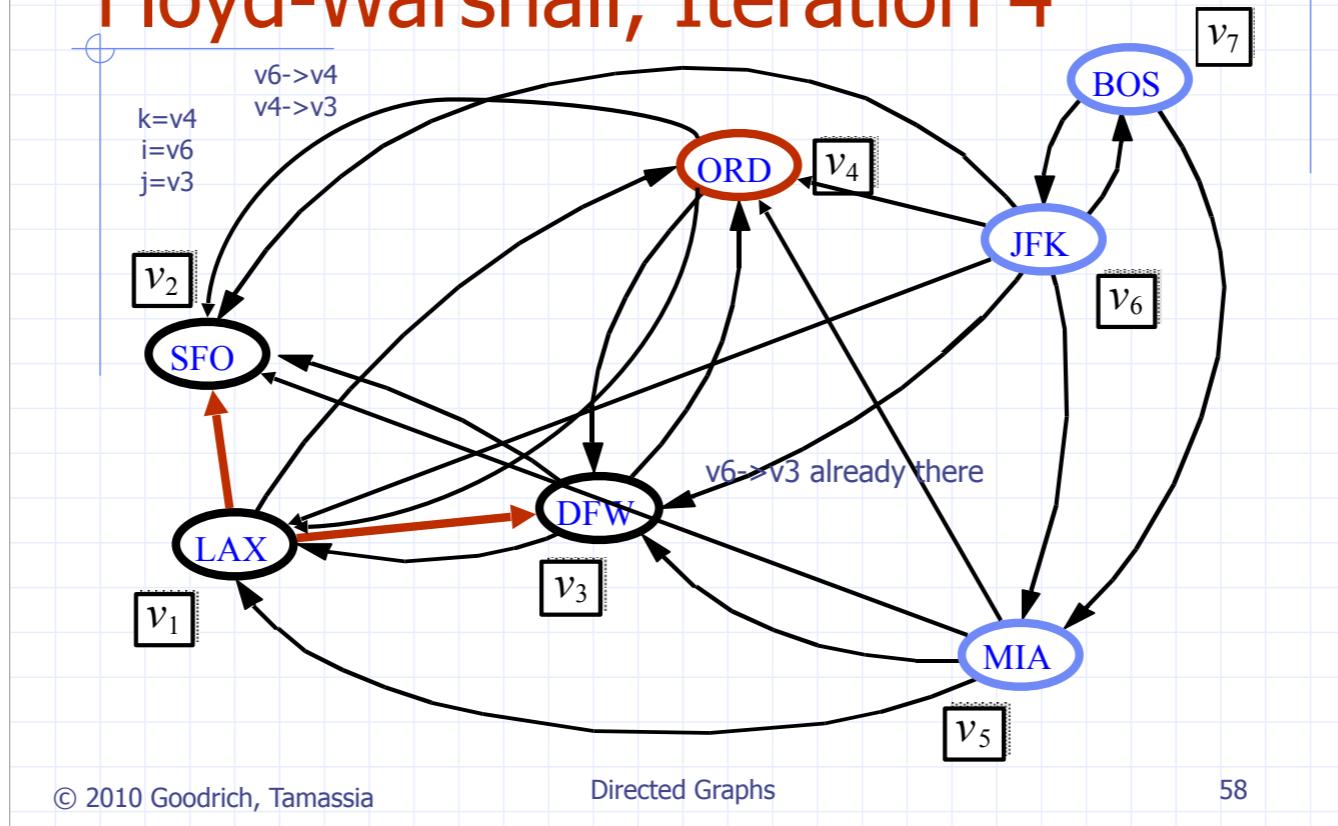
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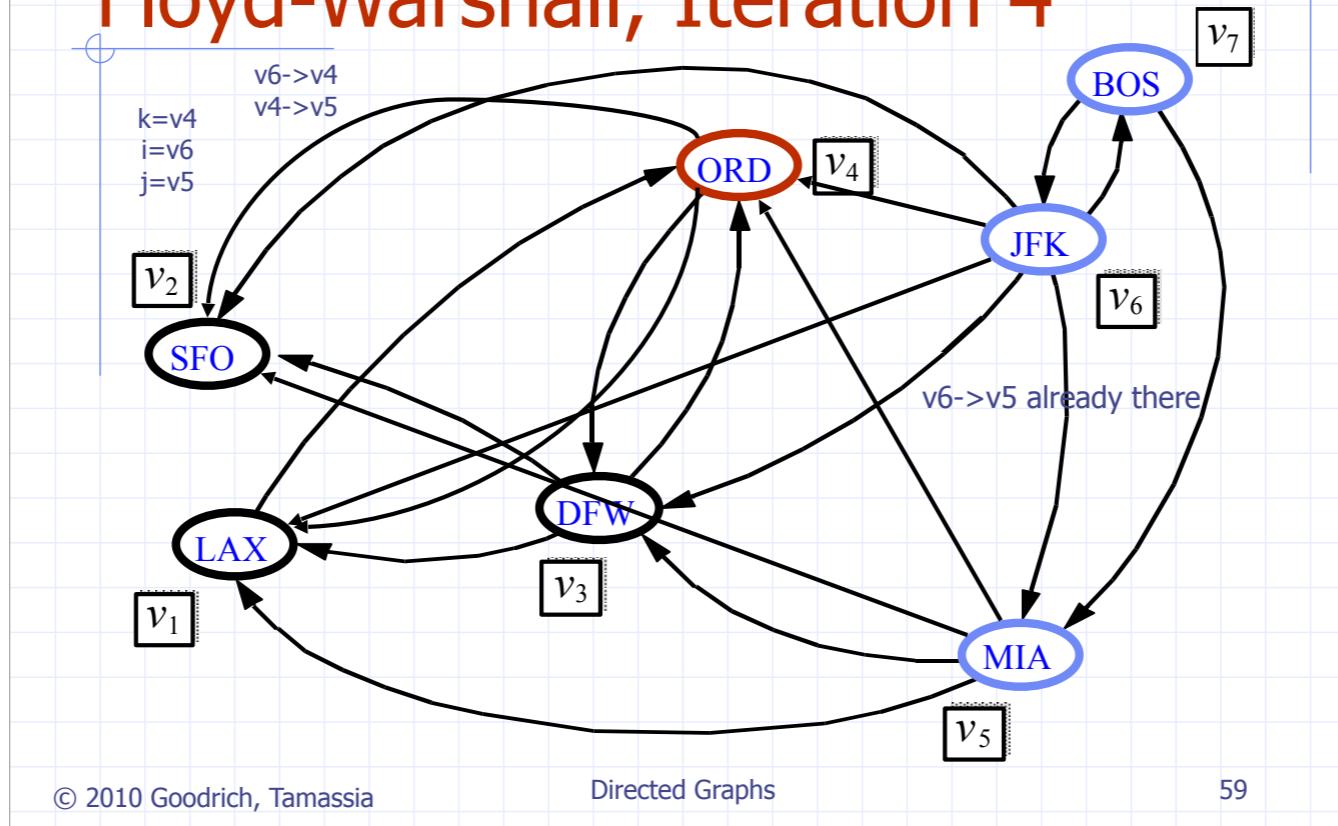
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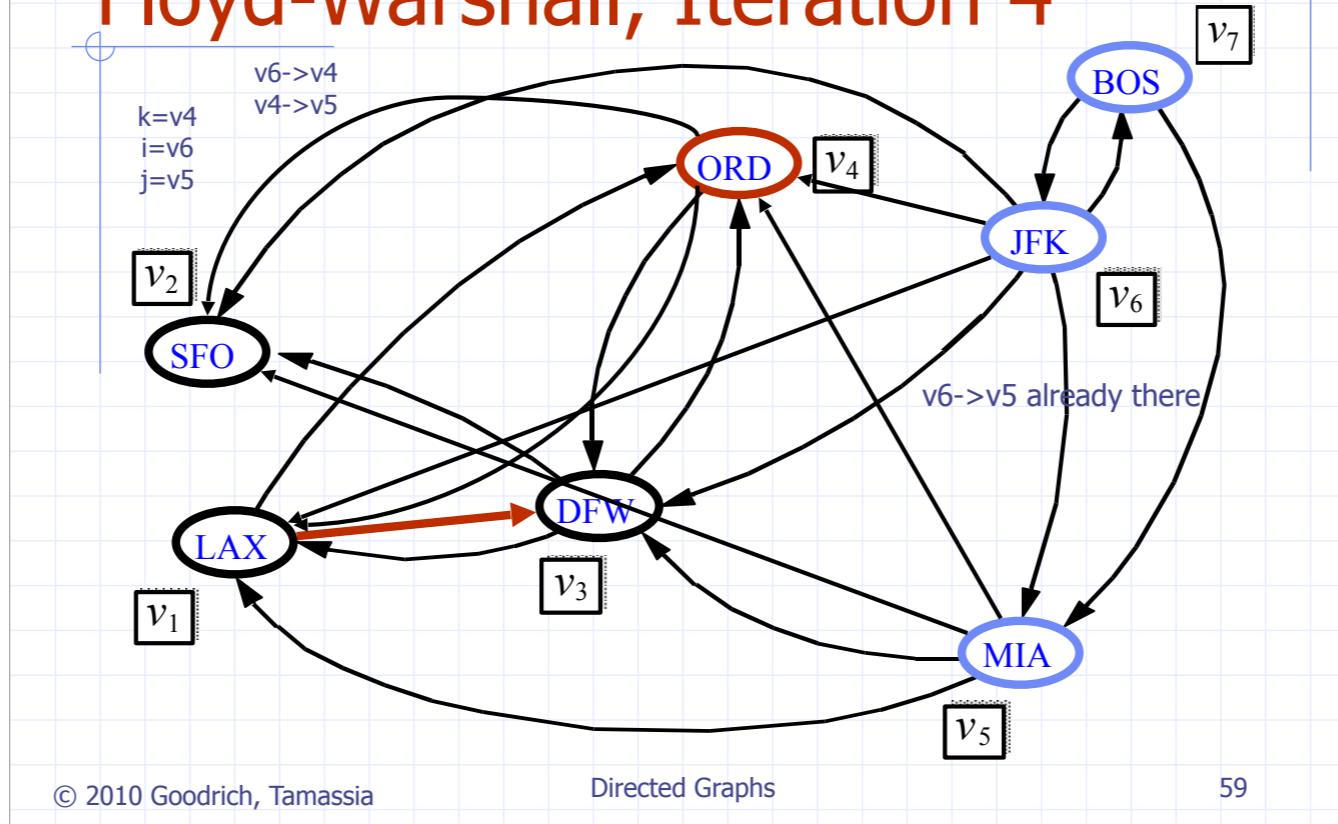
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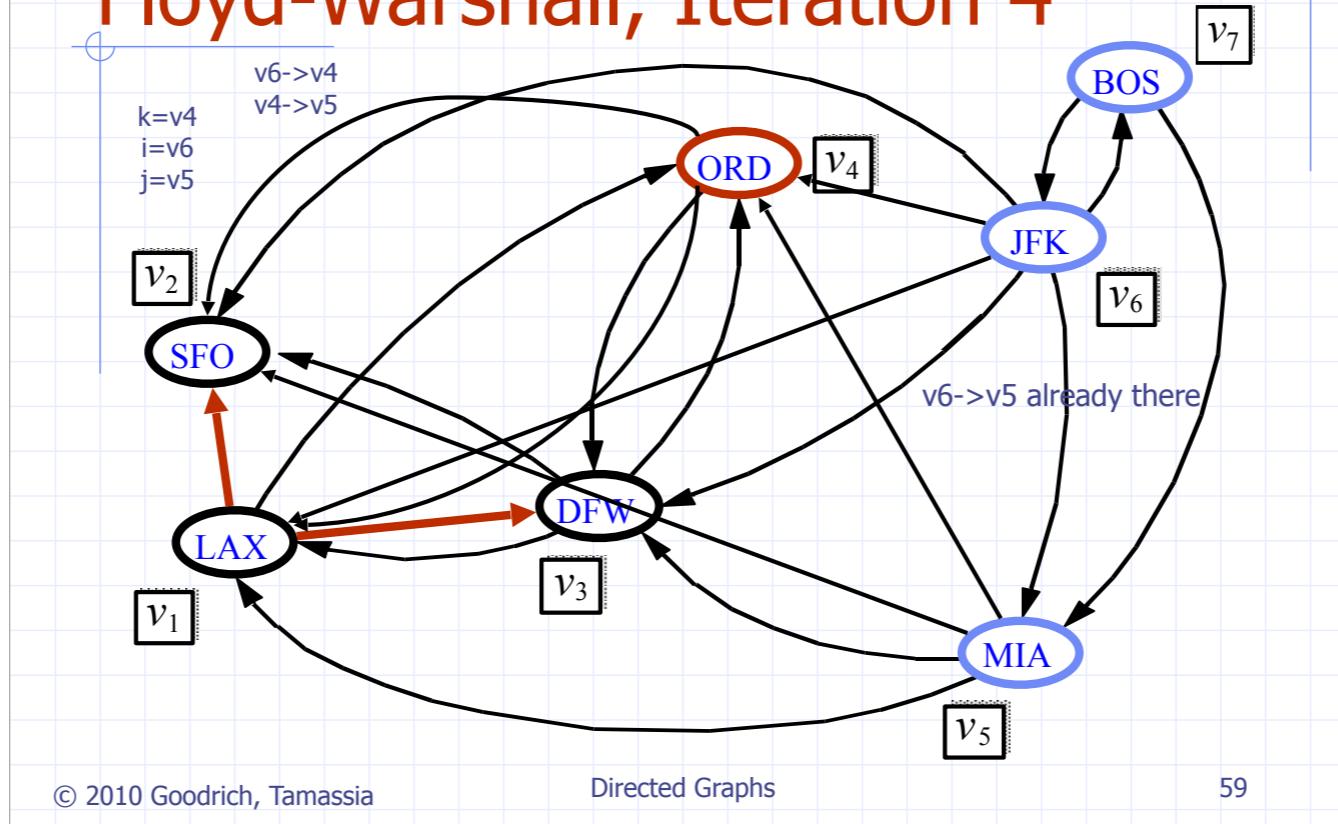
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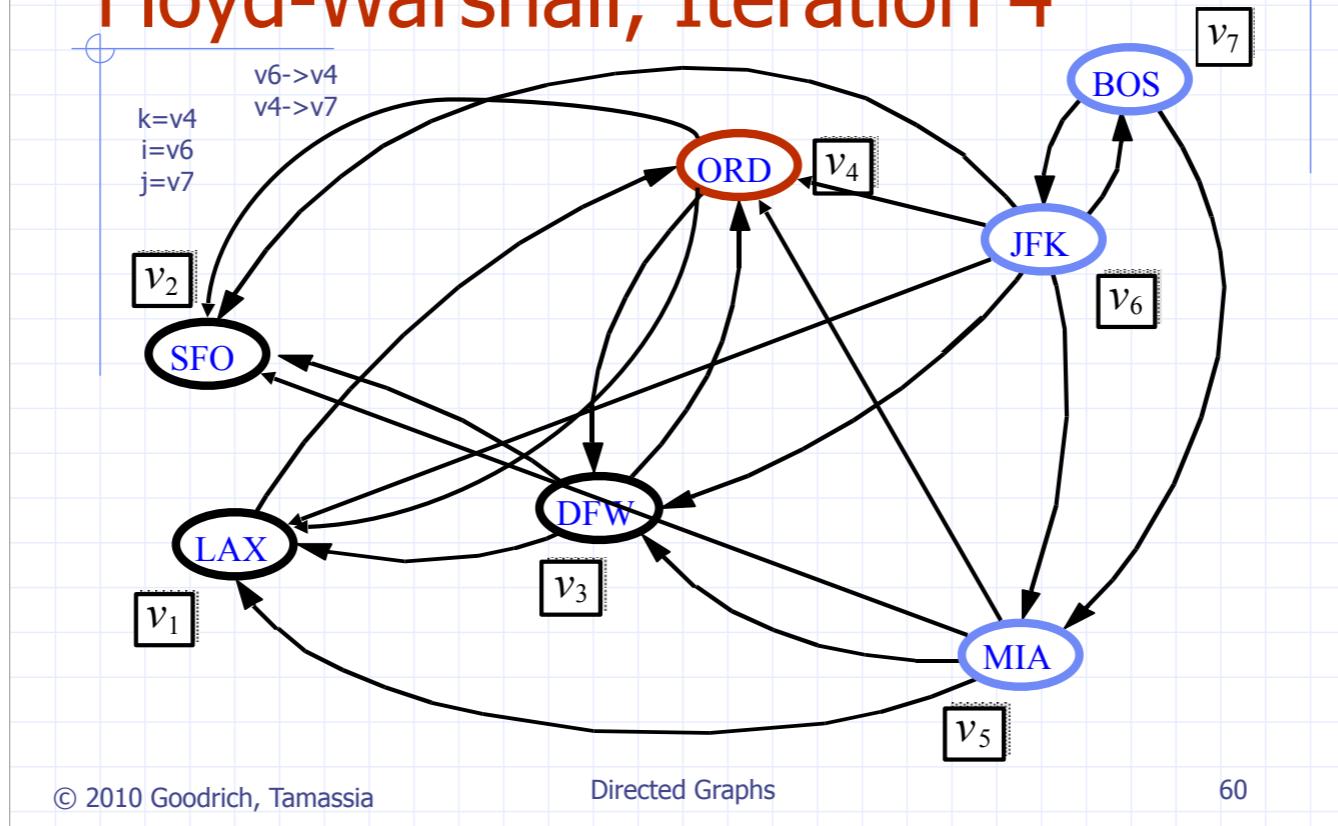
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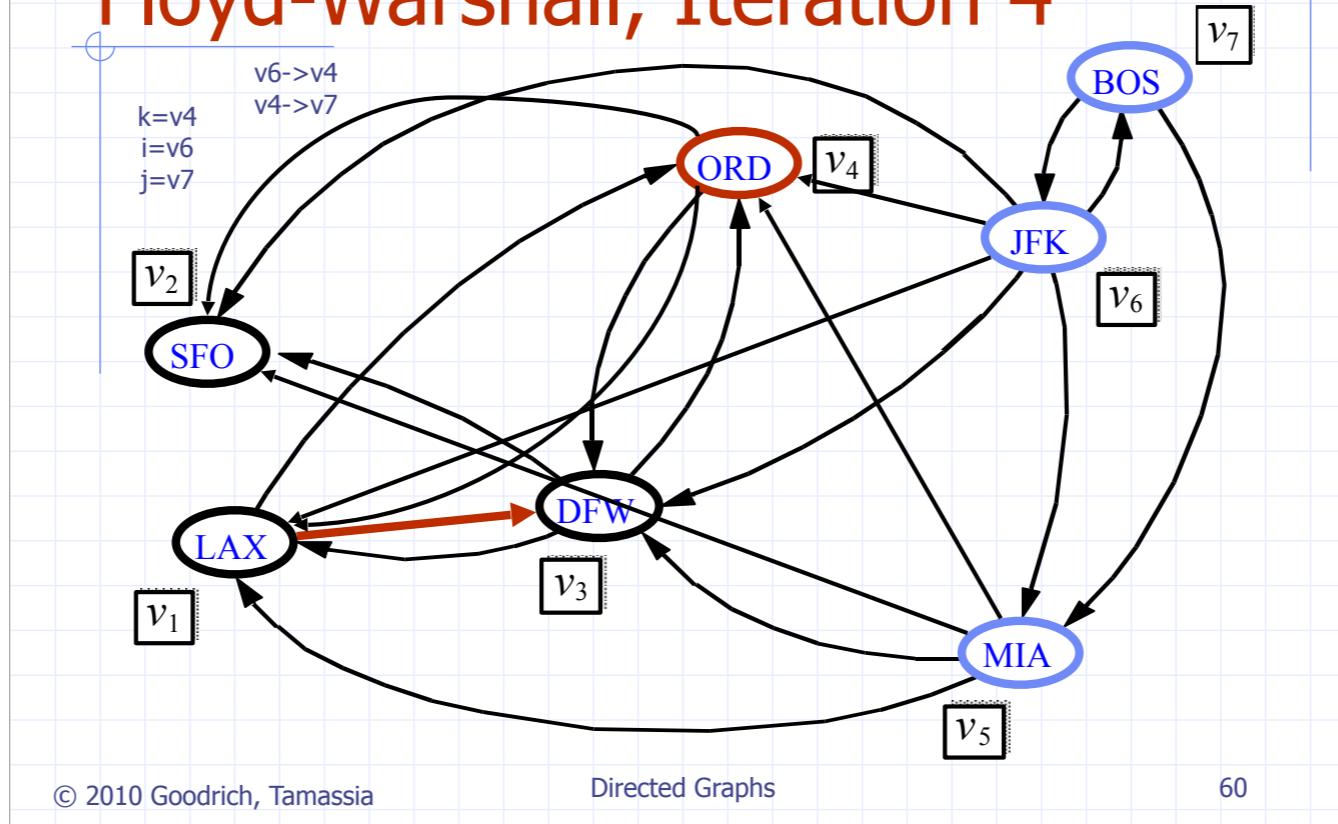
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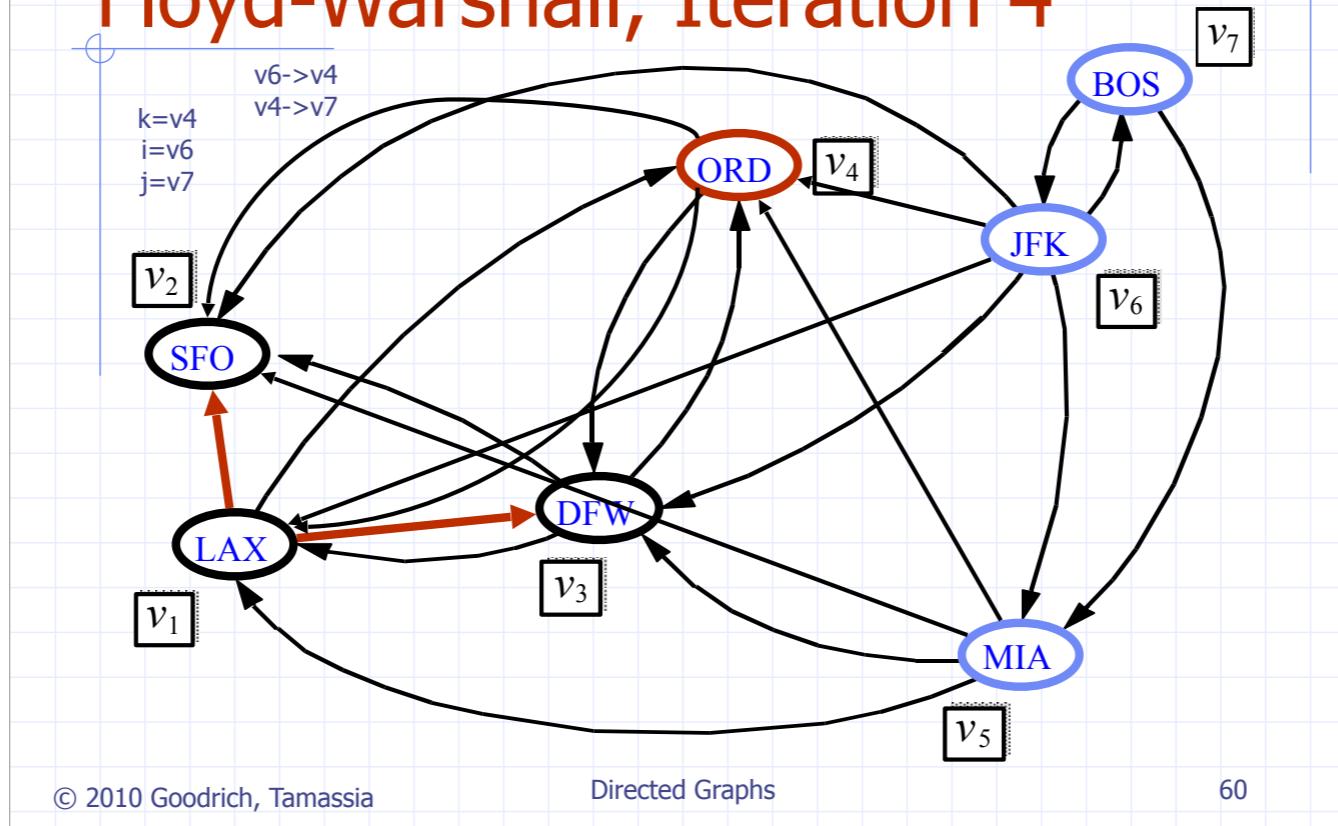
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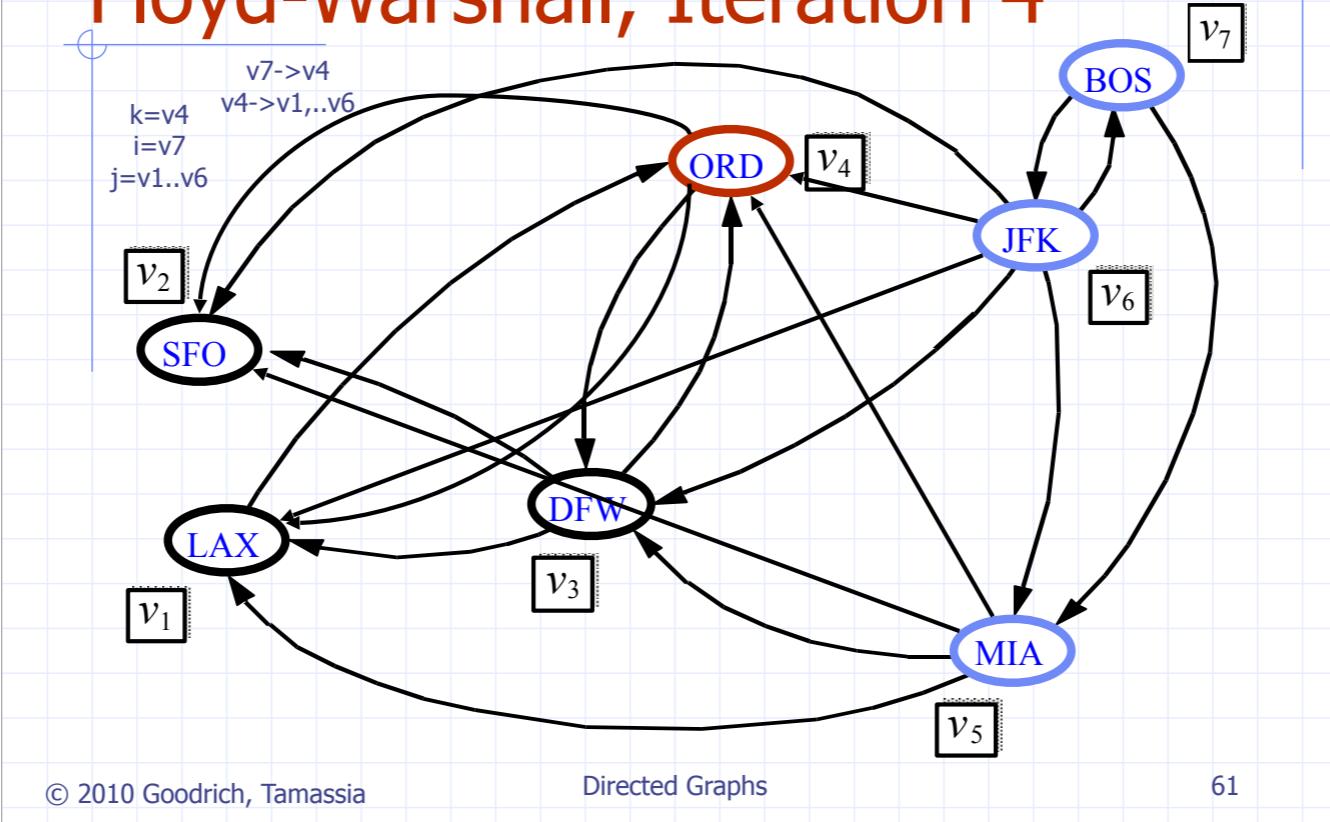
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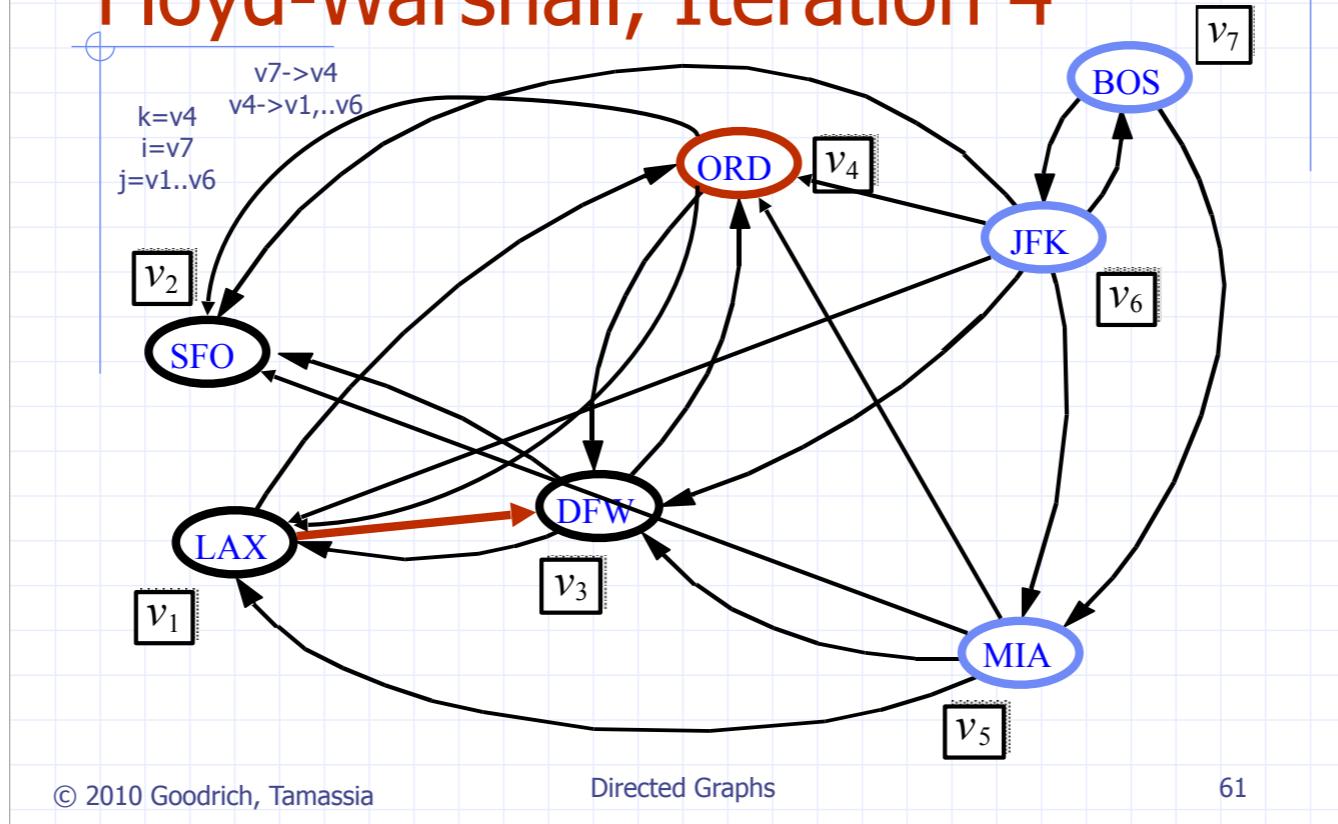
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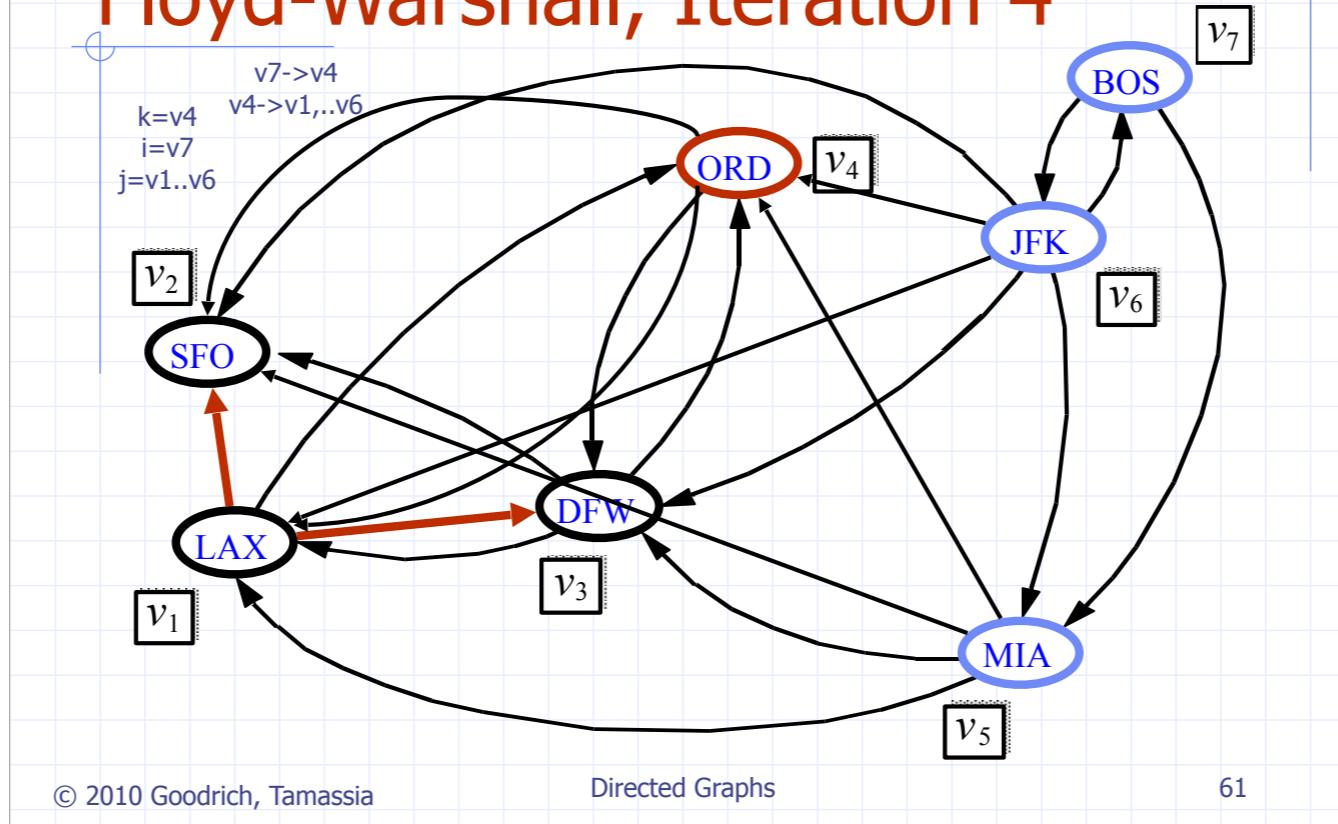
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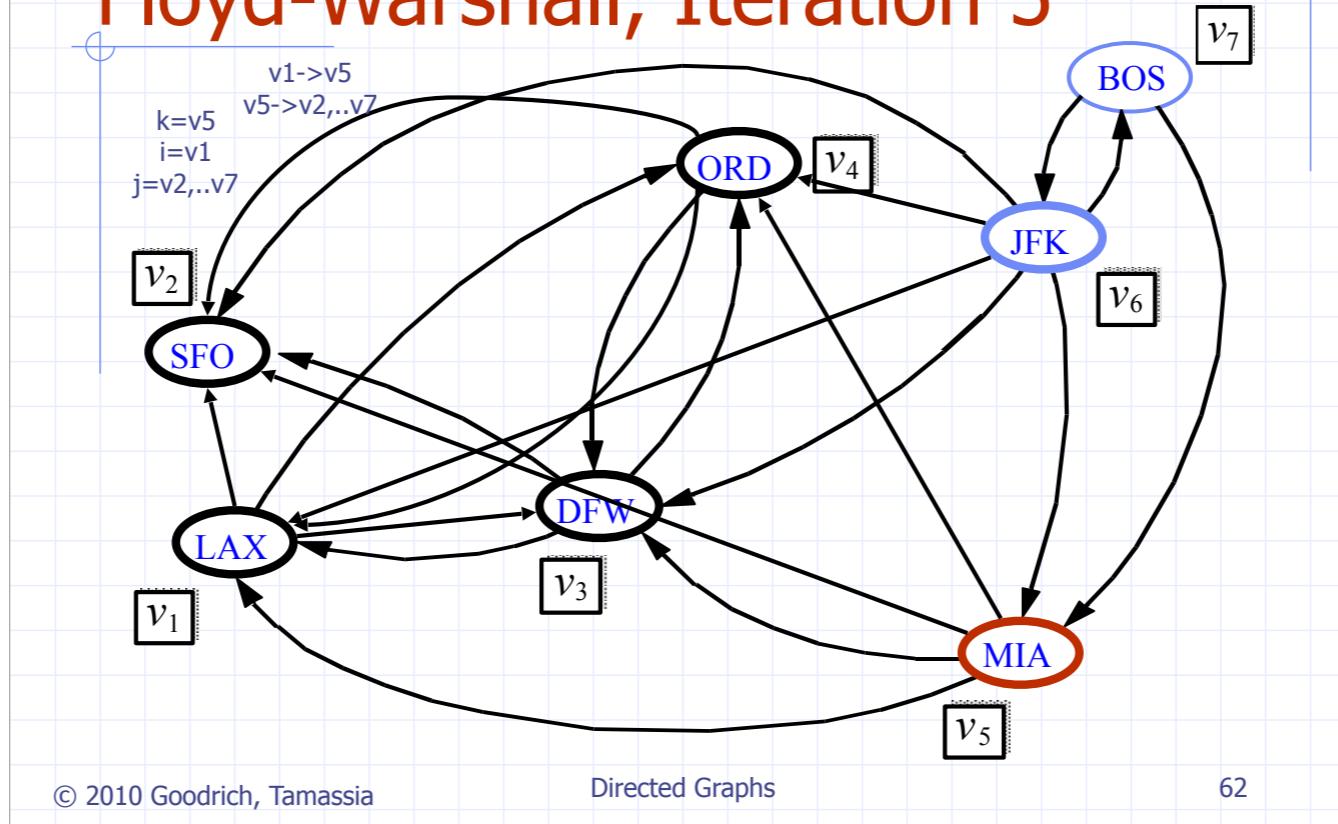
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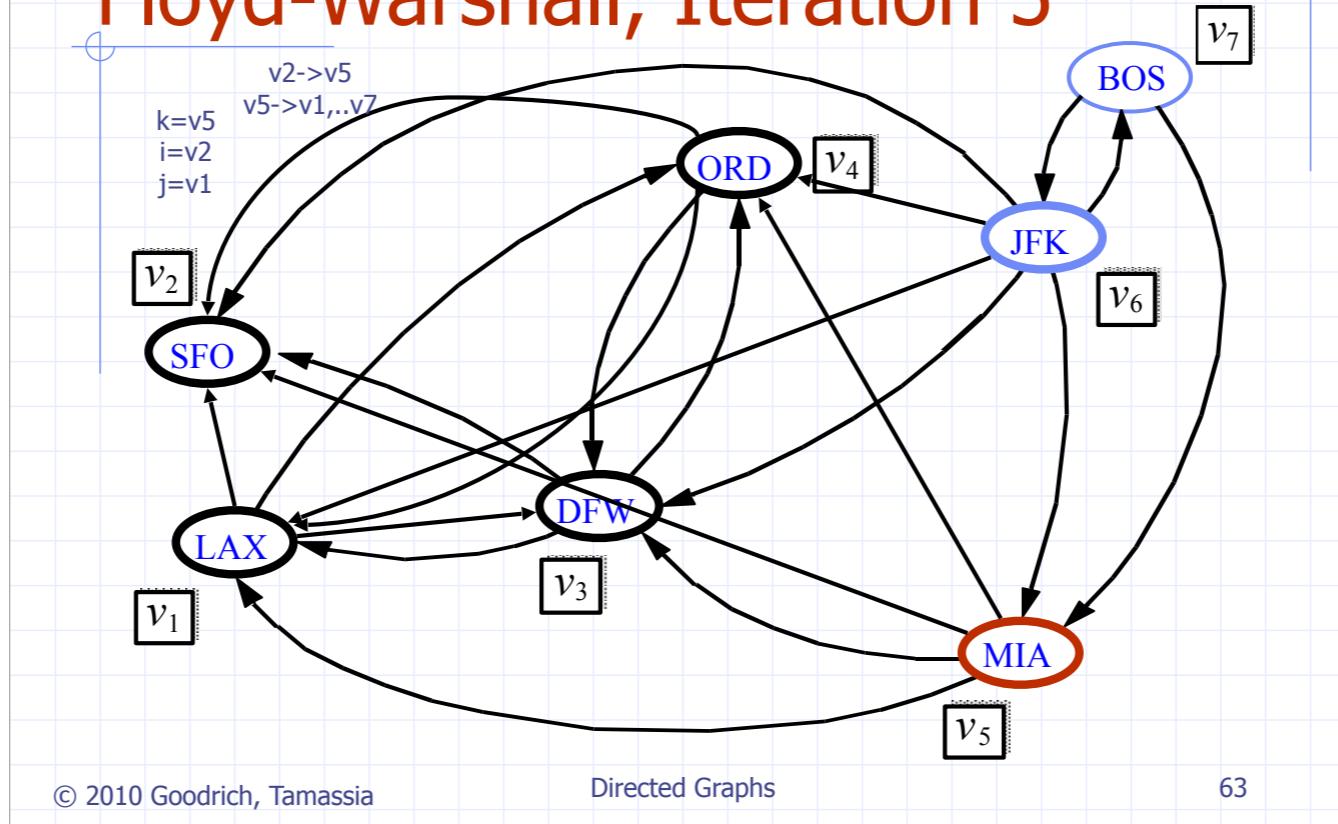
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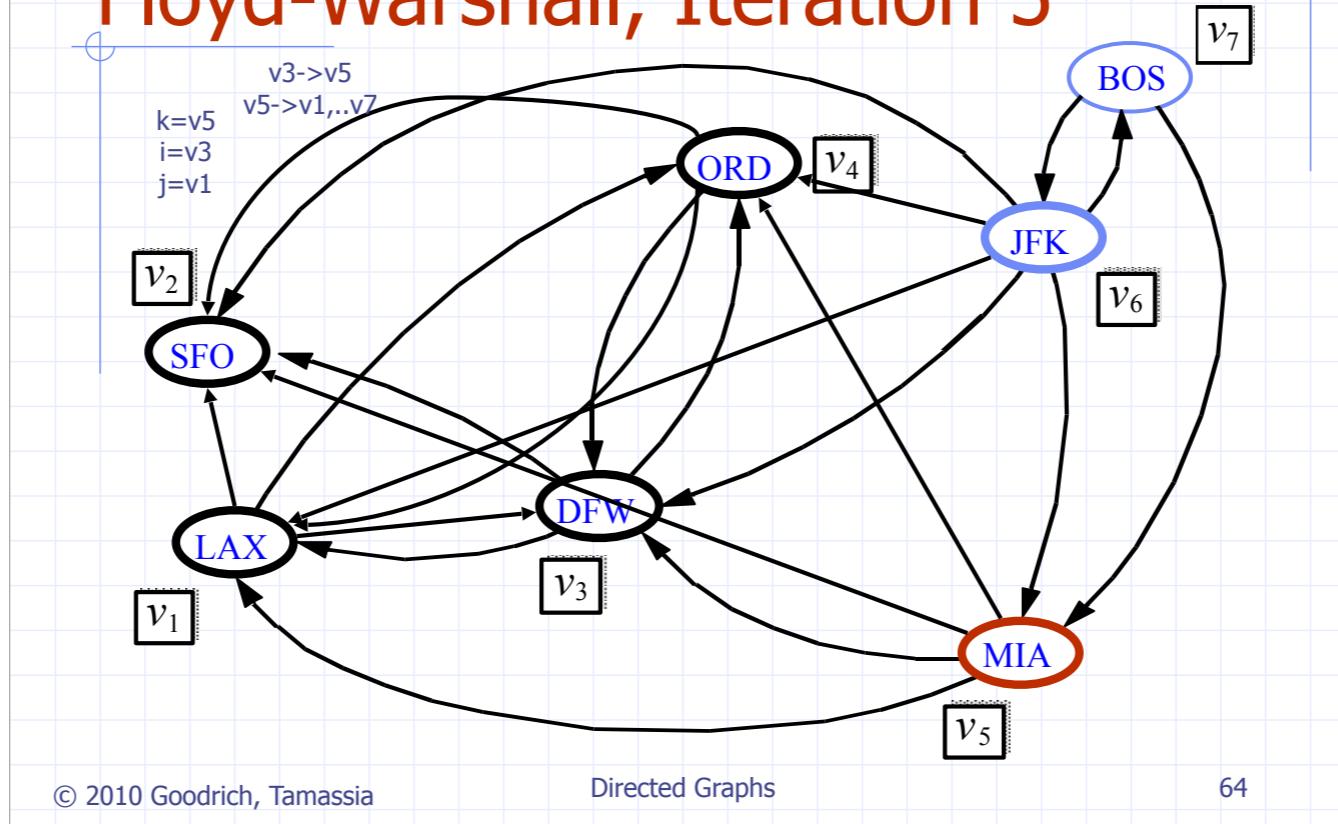
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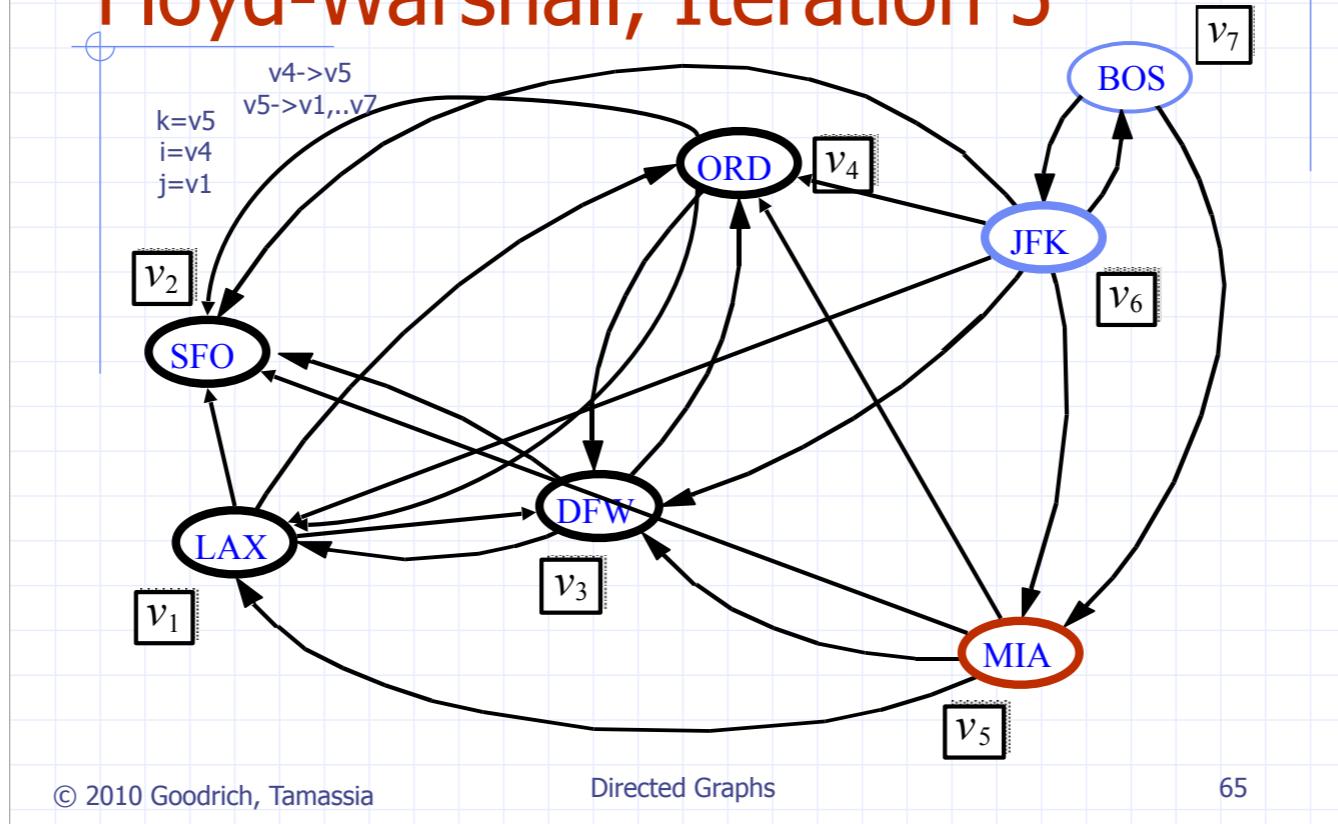
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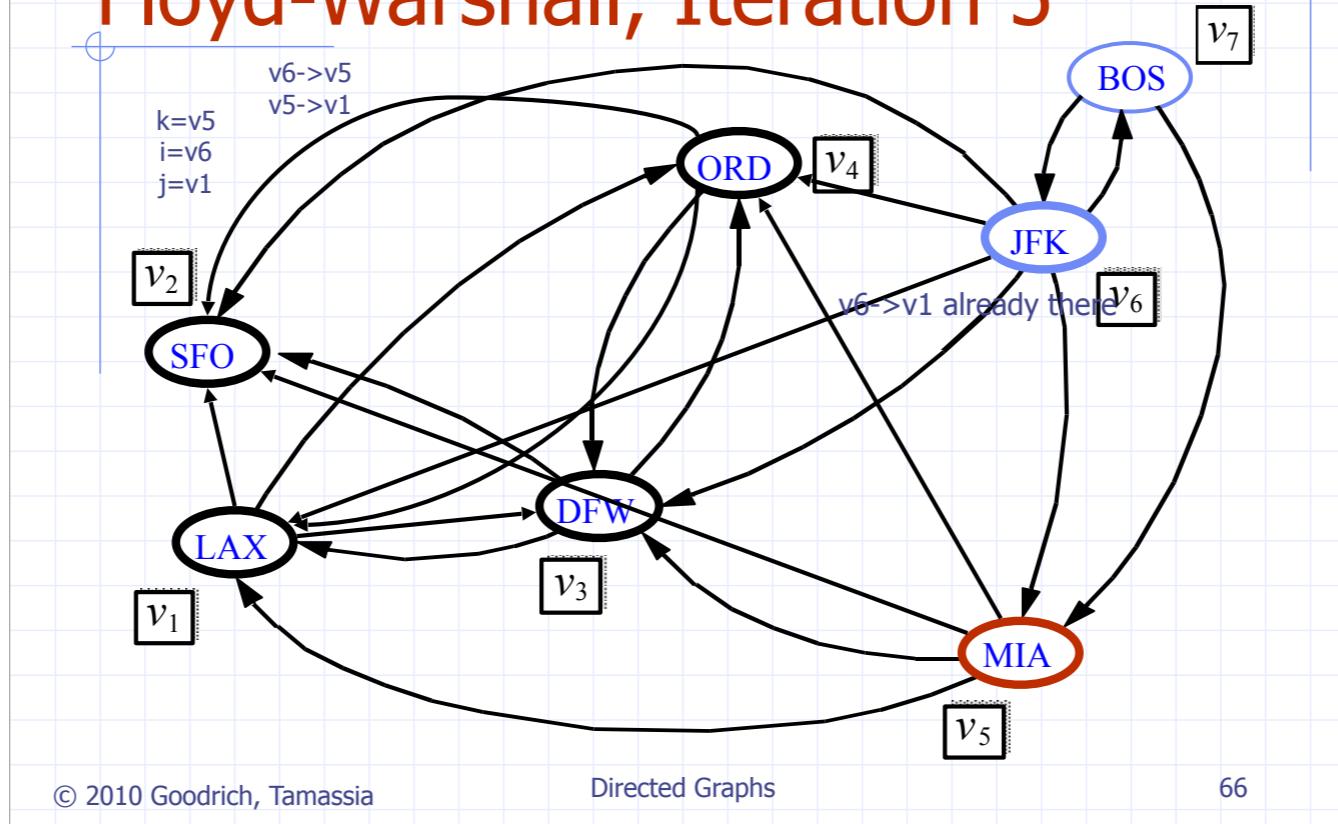
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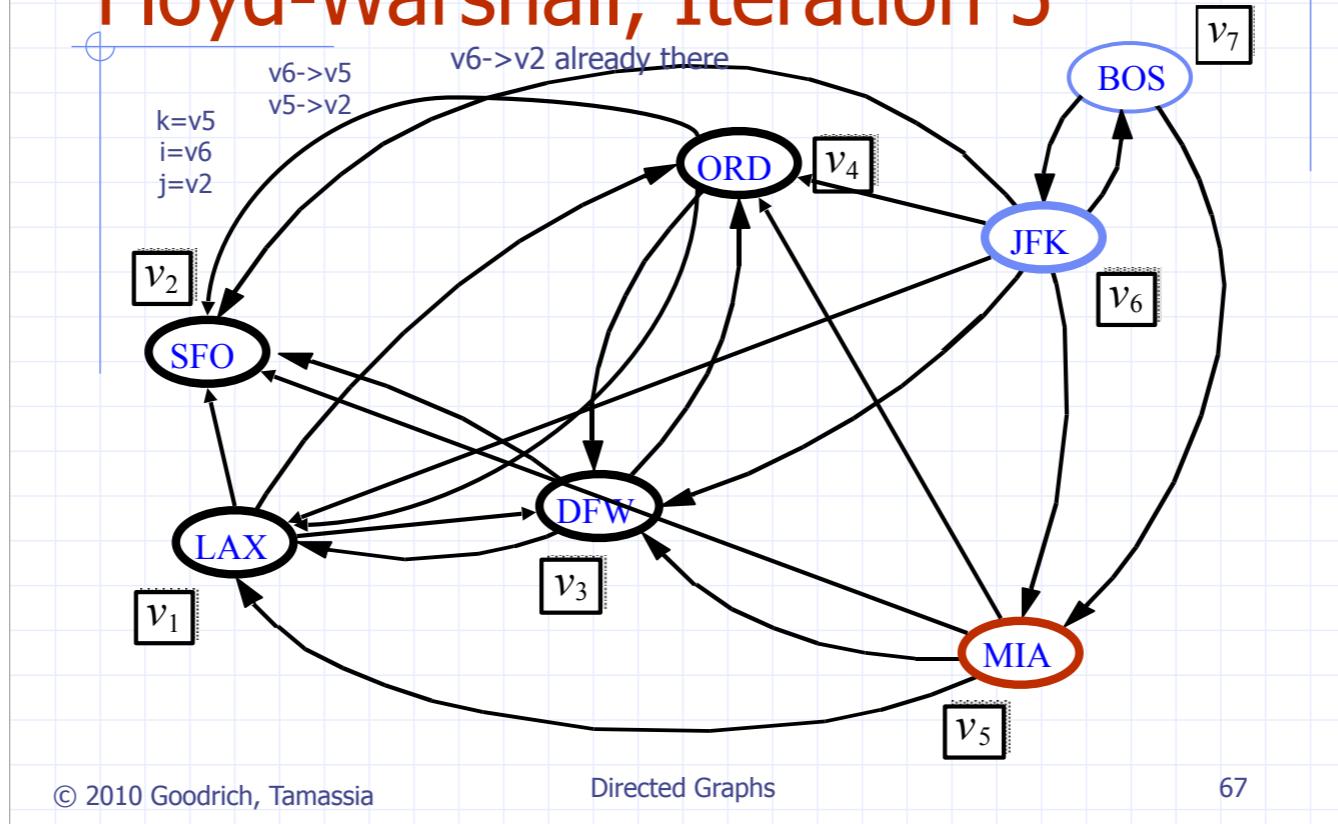
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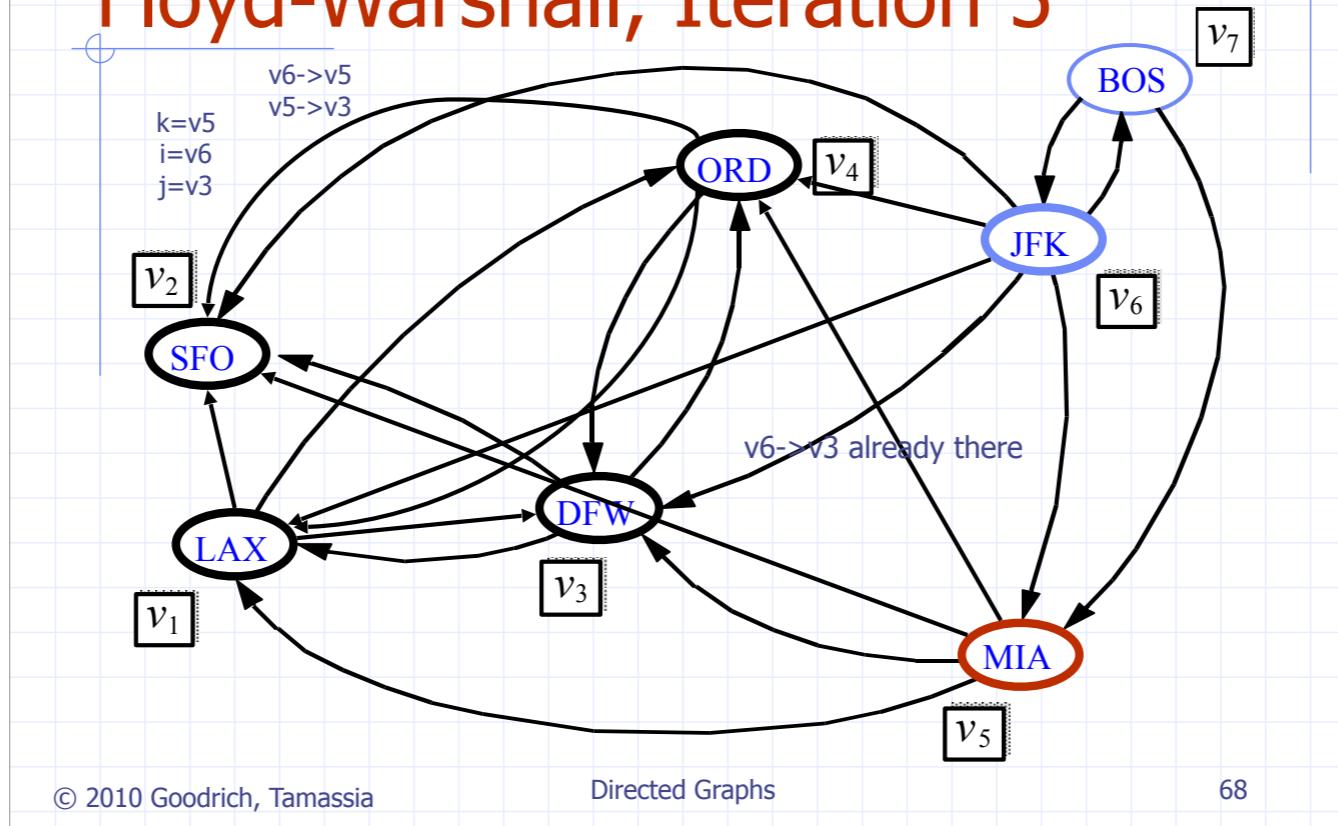
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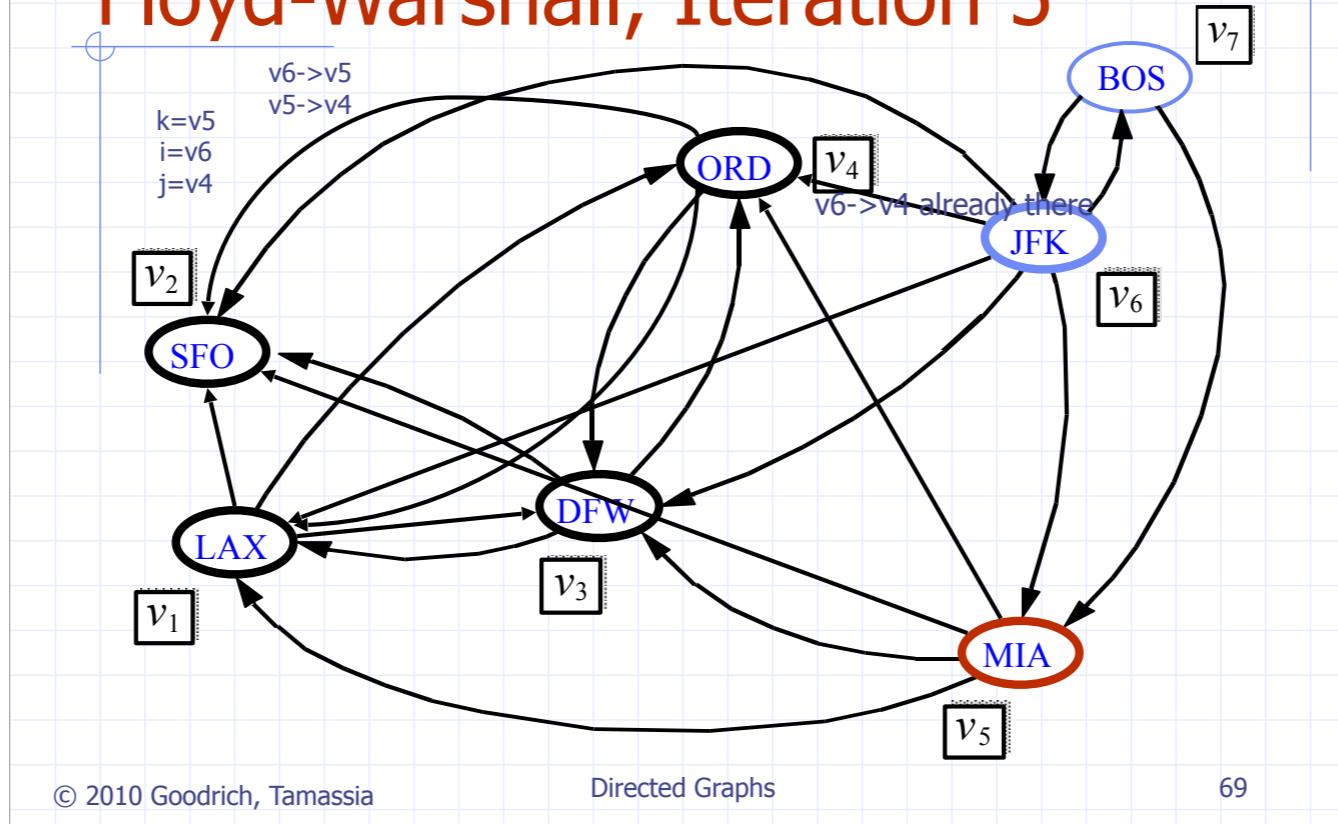
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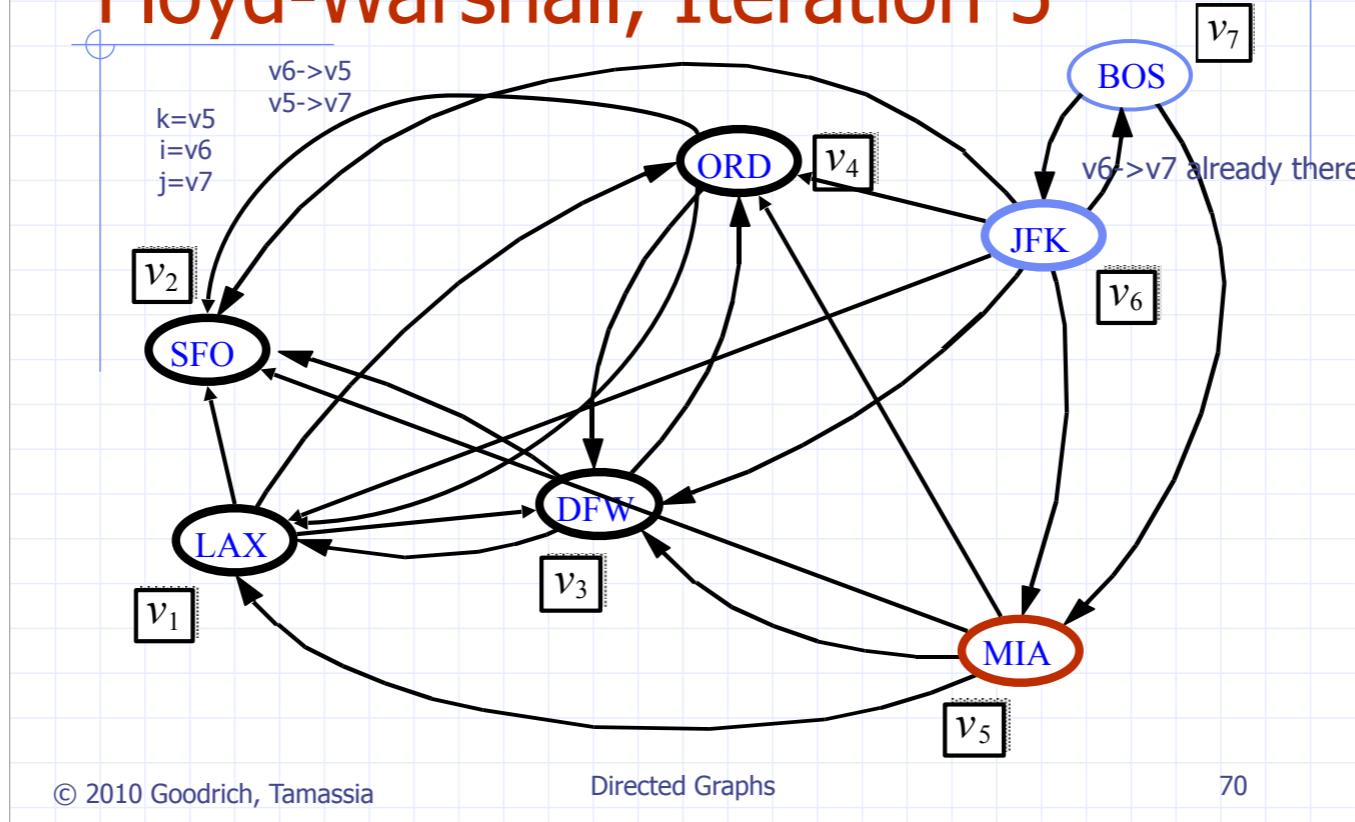
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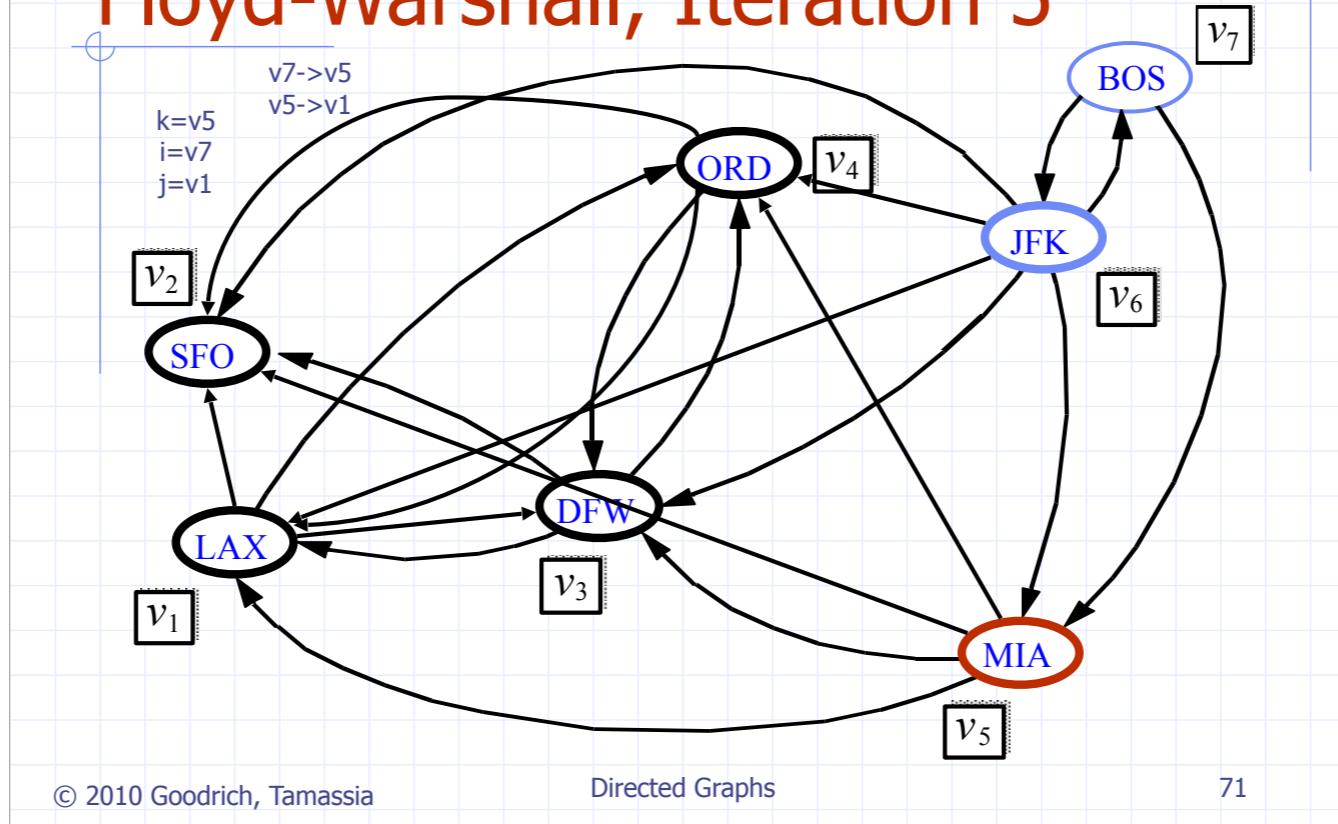
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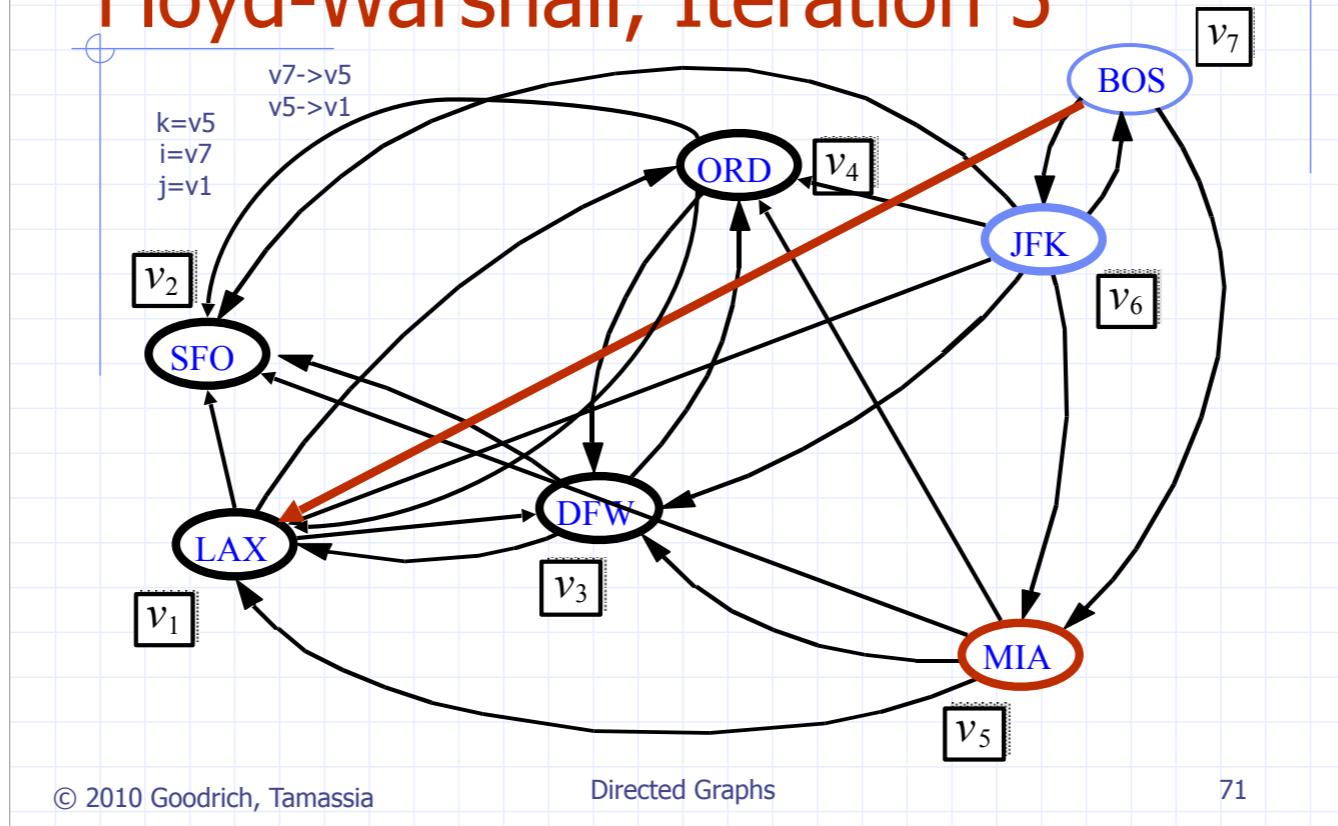
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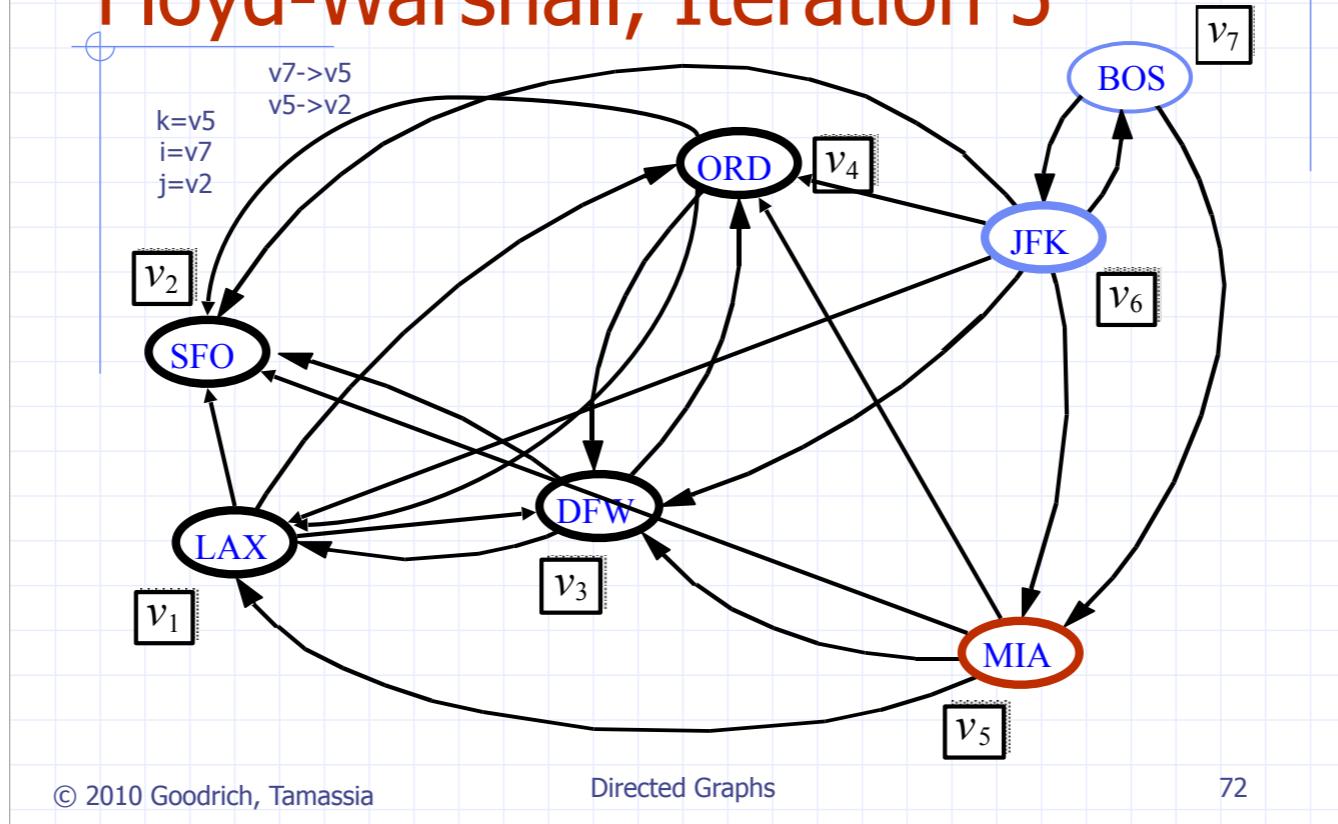
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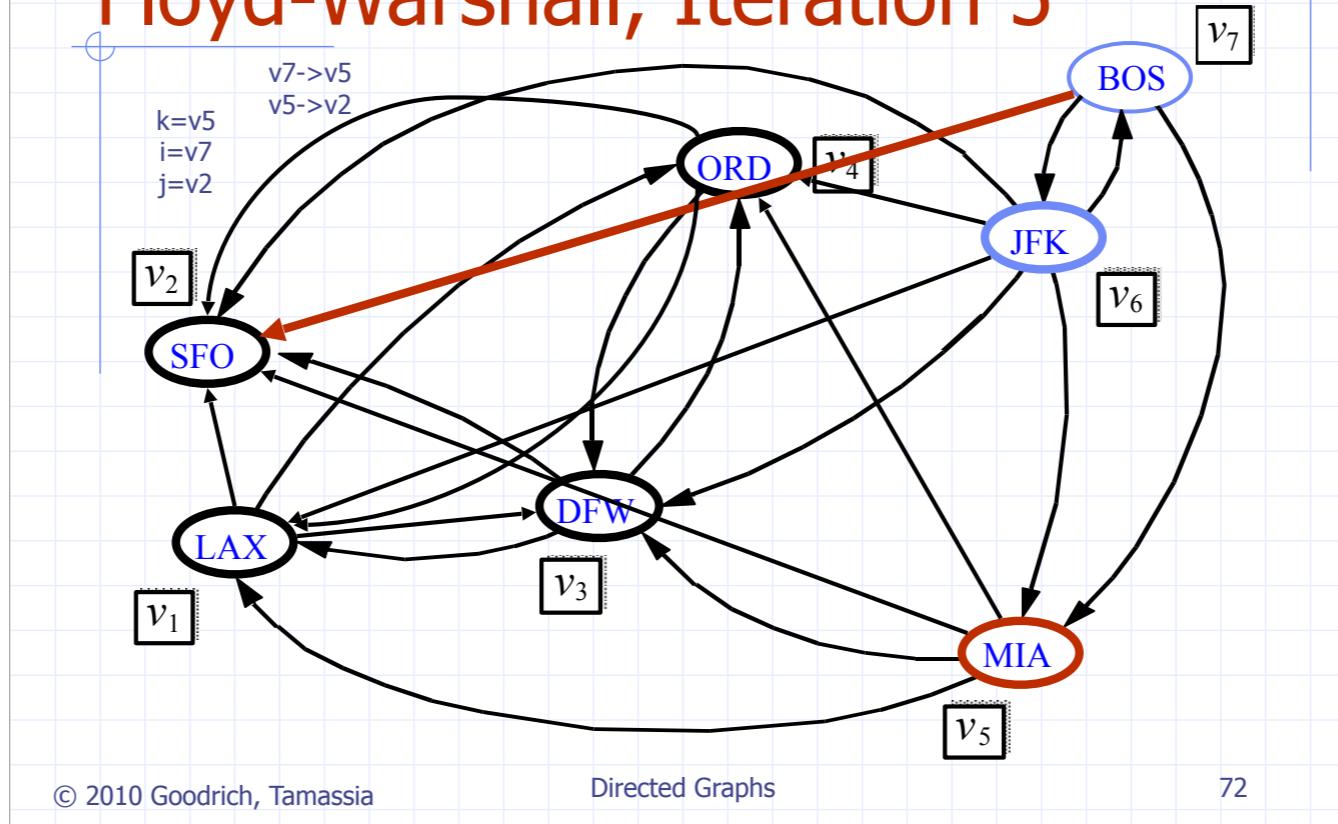
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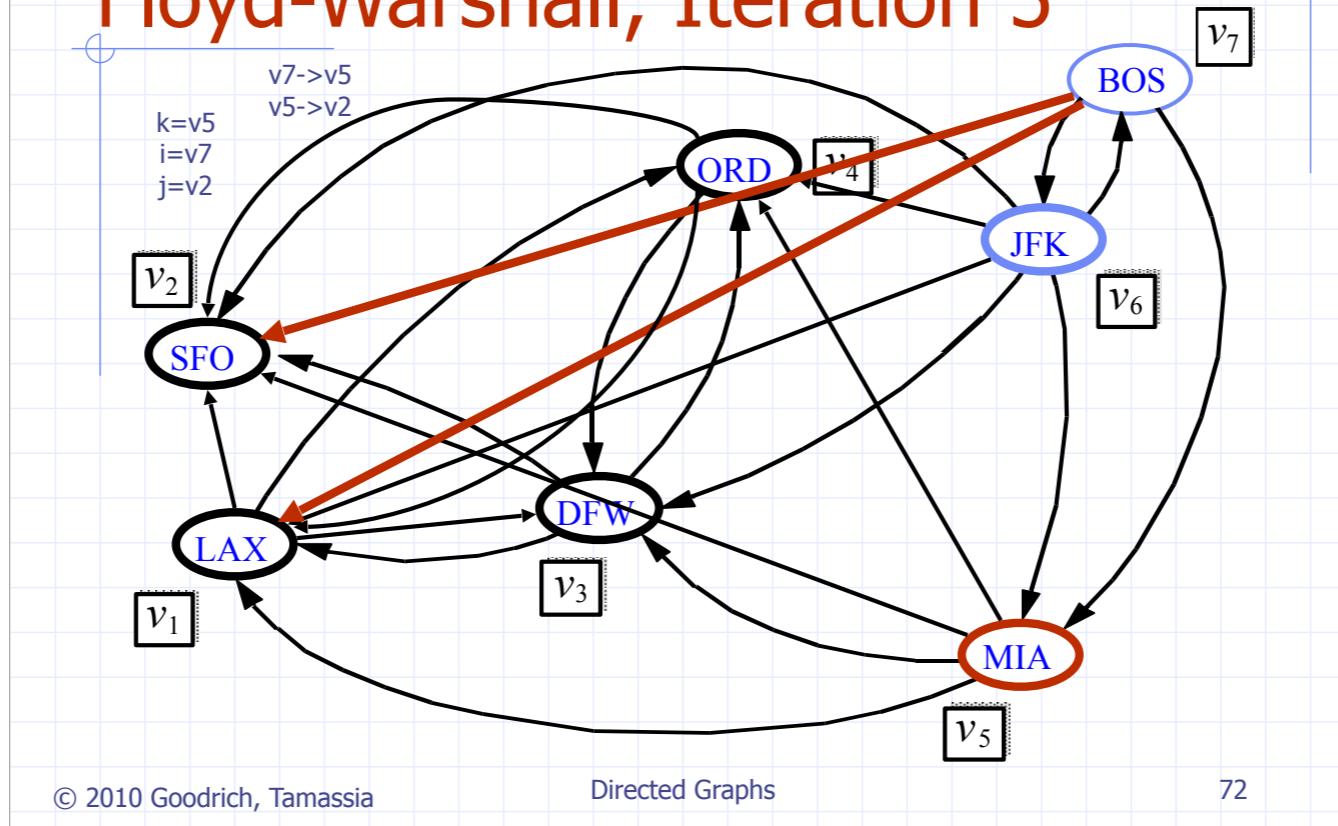
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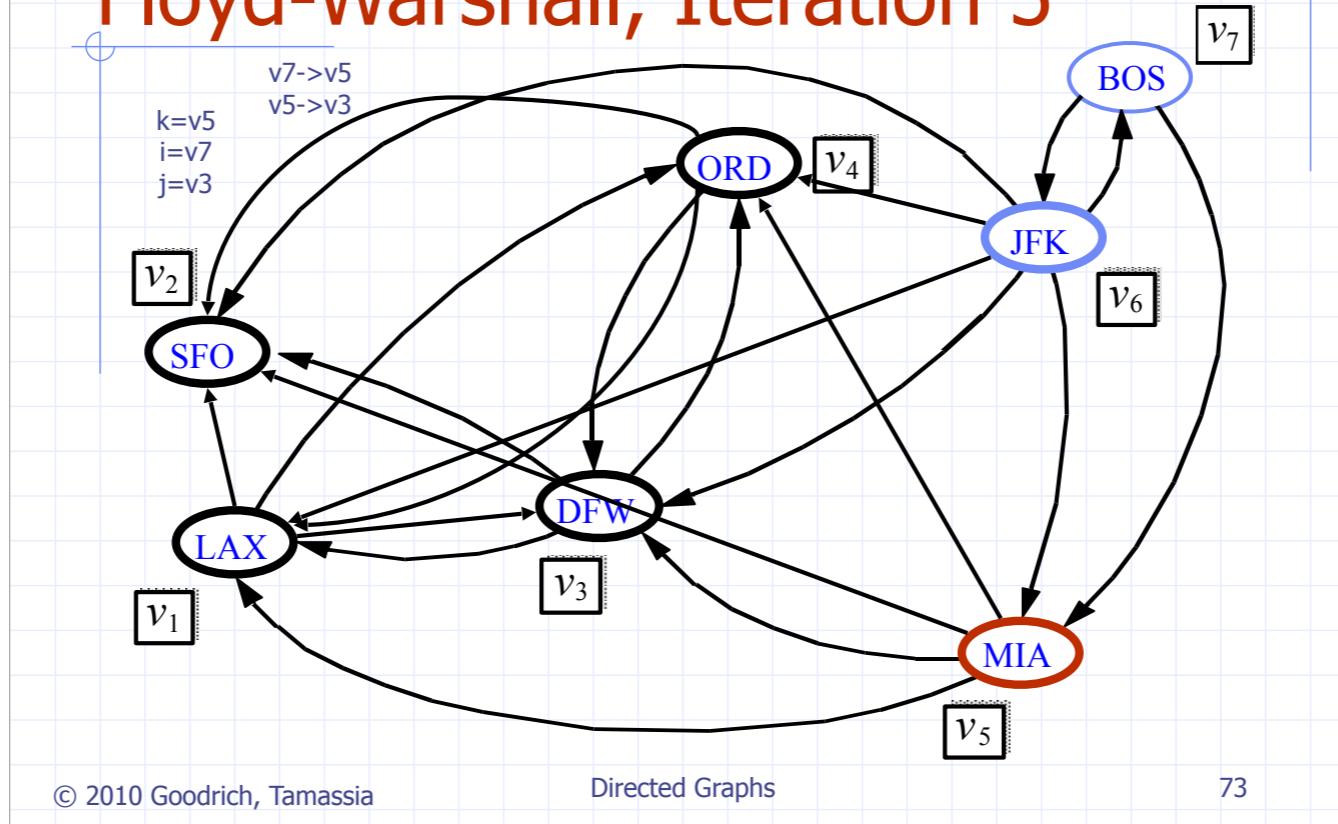
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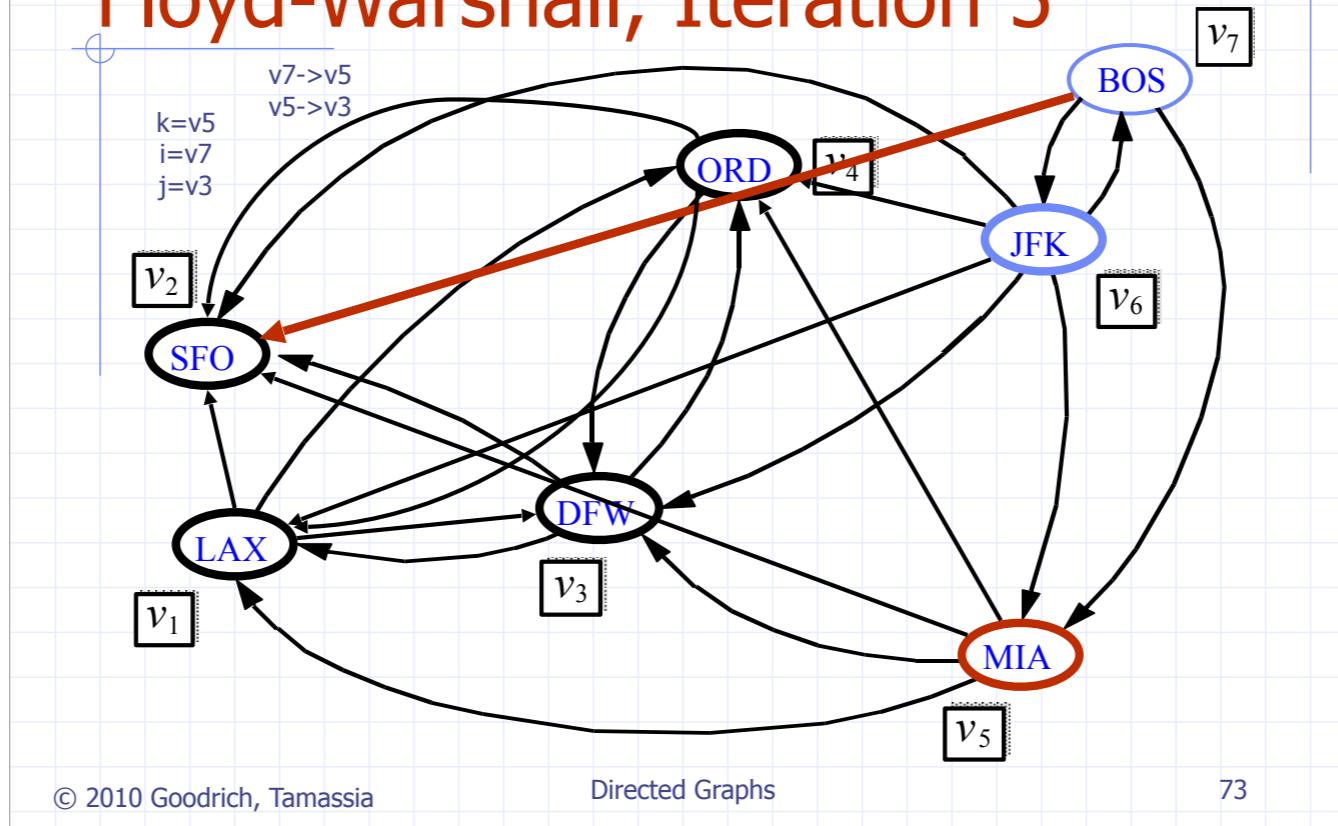
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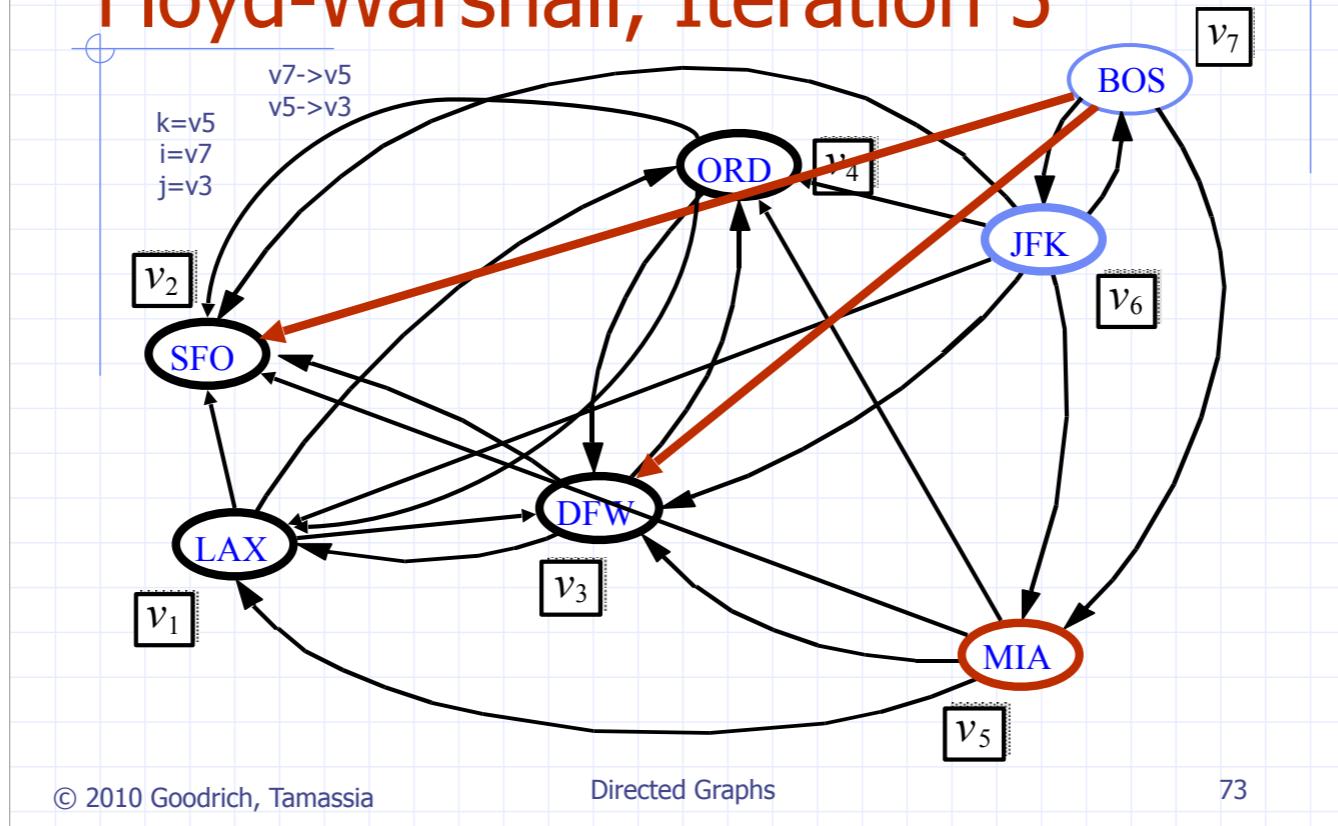
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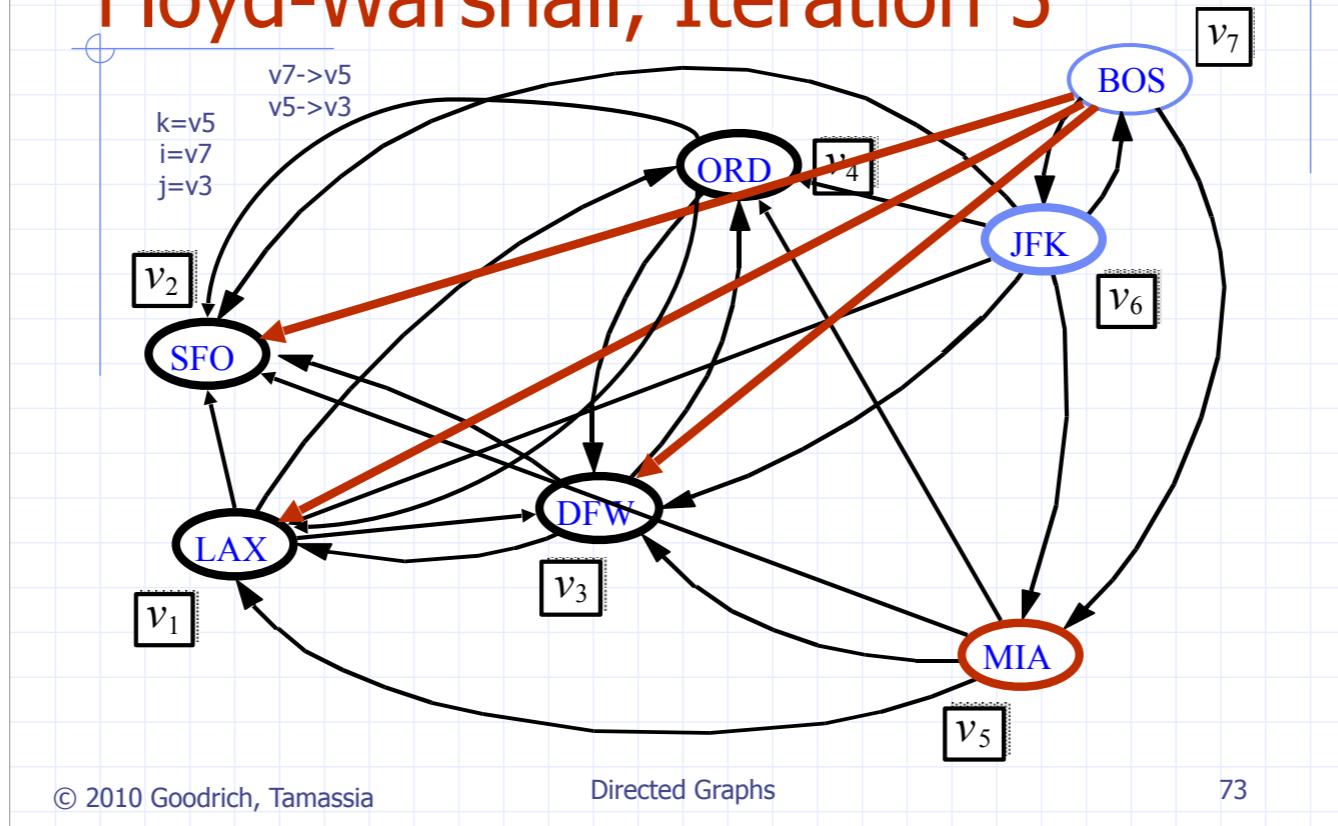
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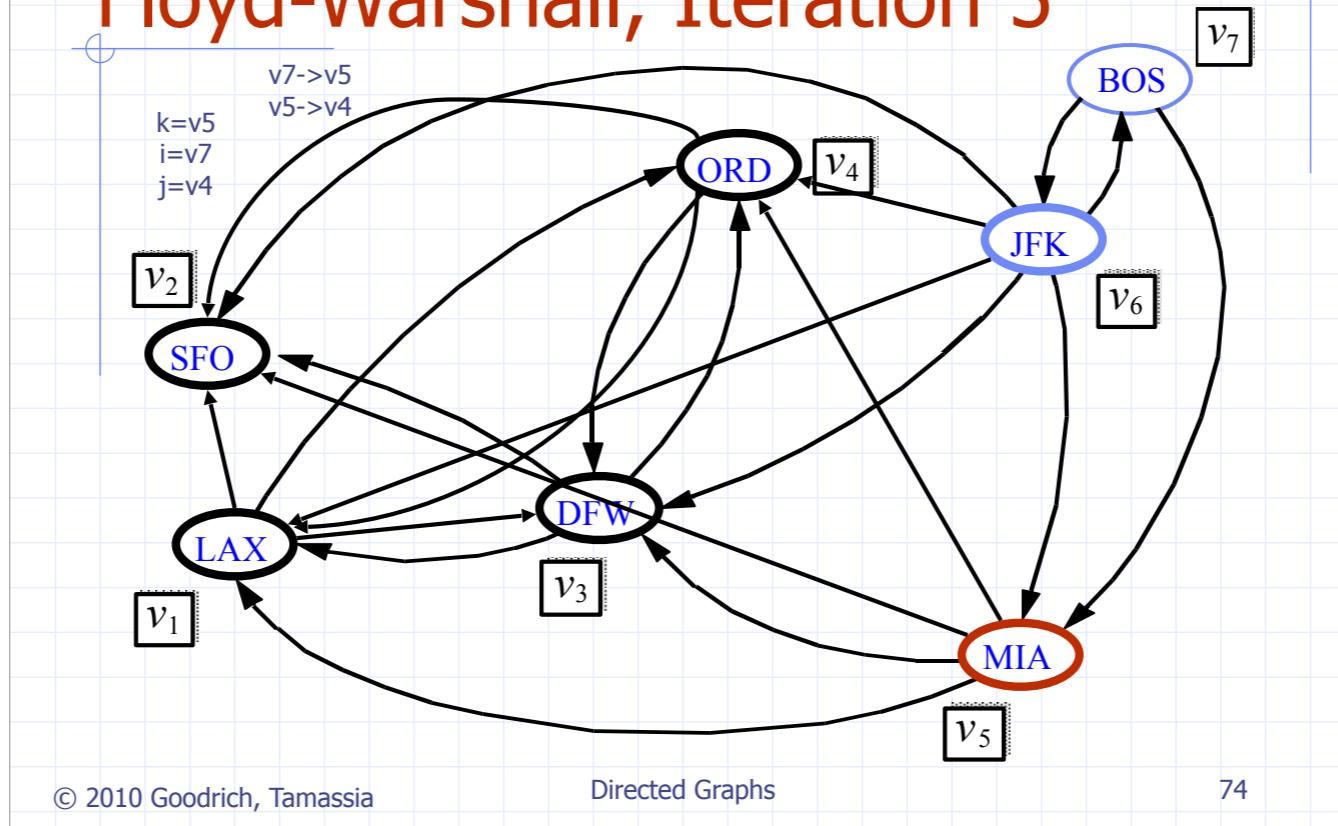
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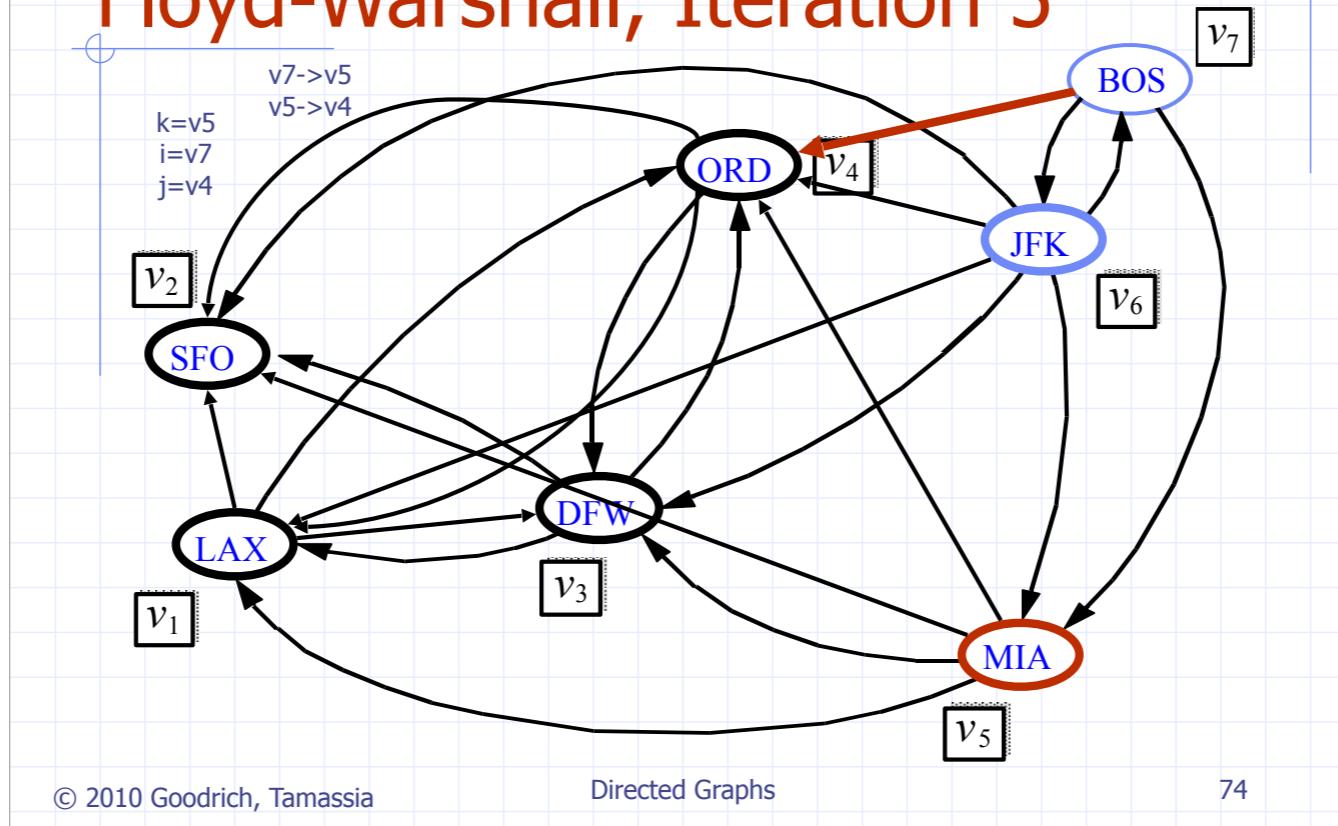
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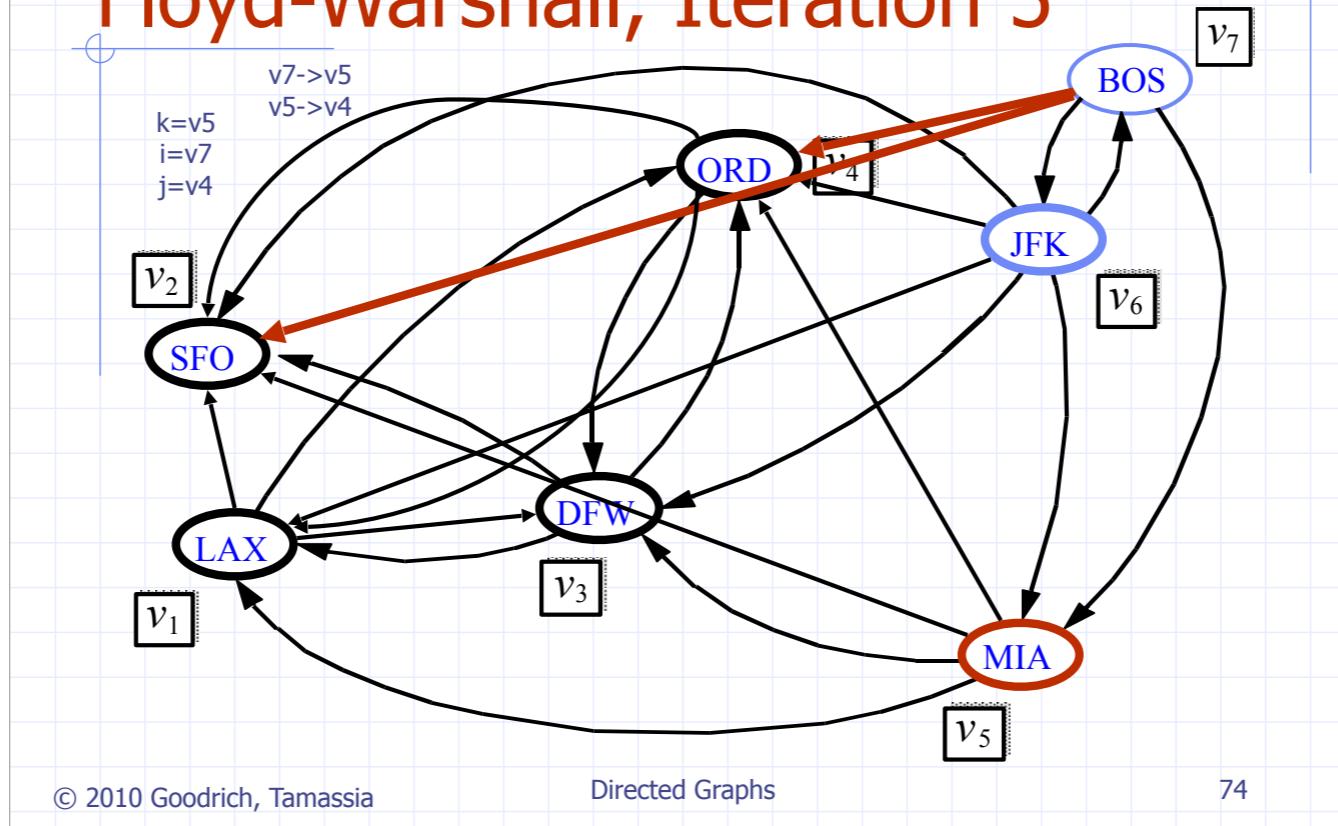
Floyd-Warshall, Iteration 5



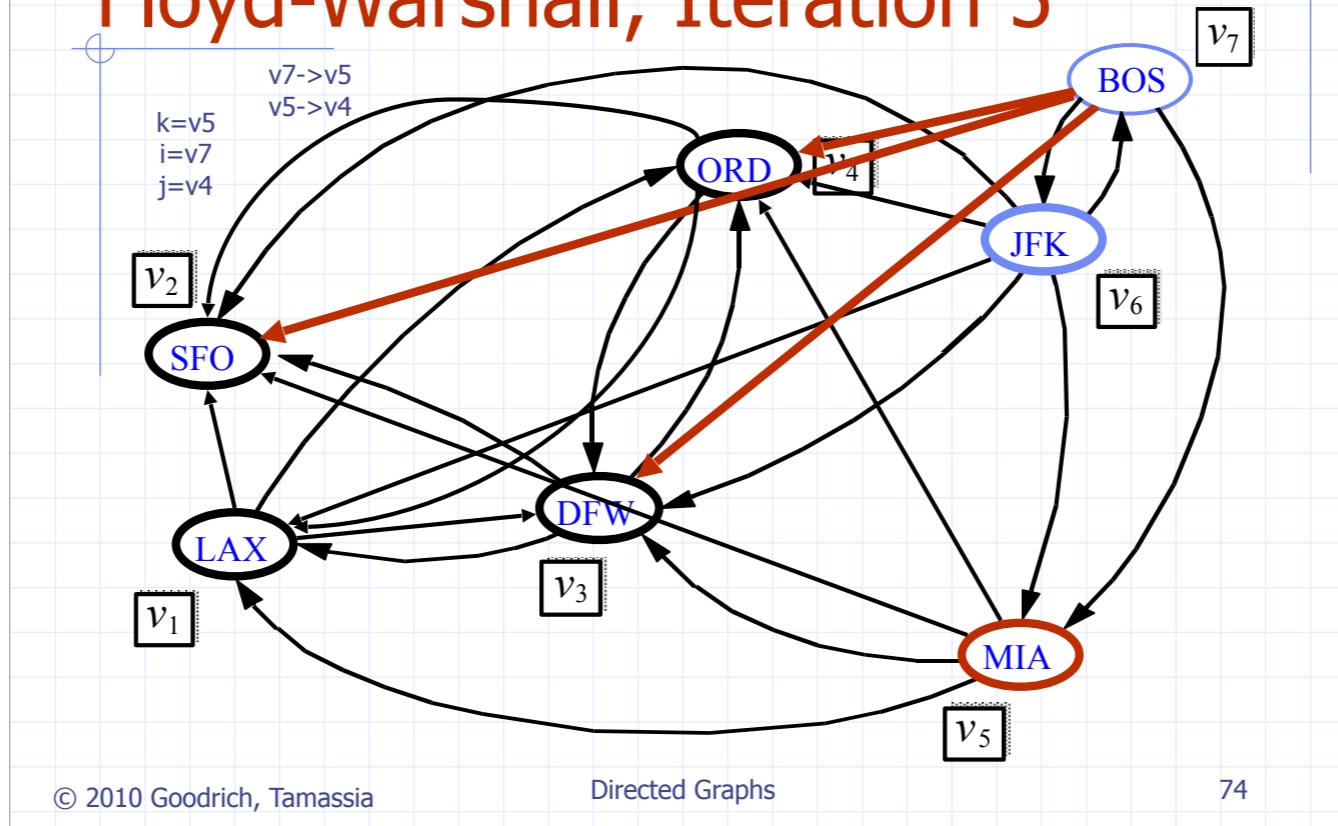
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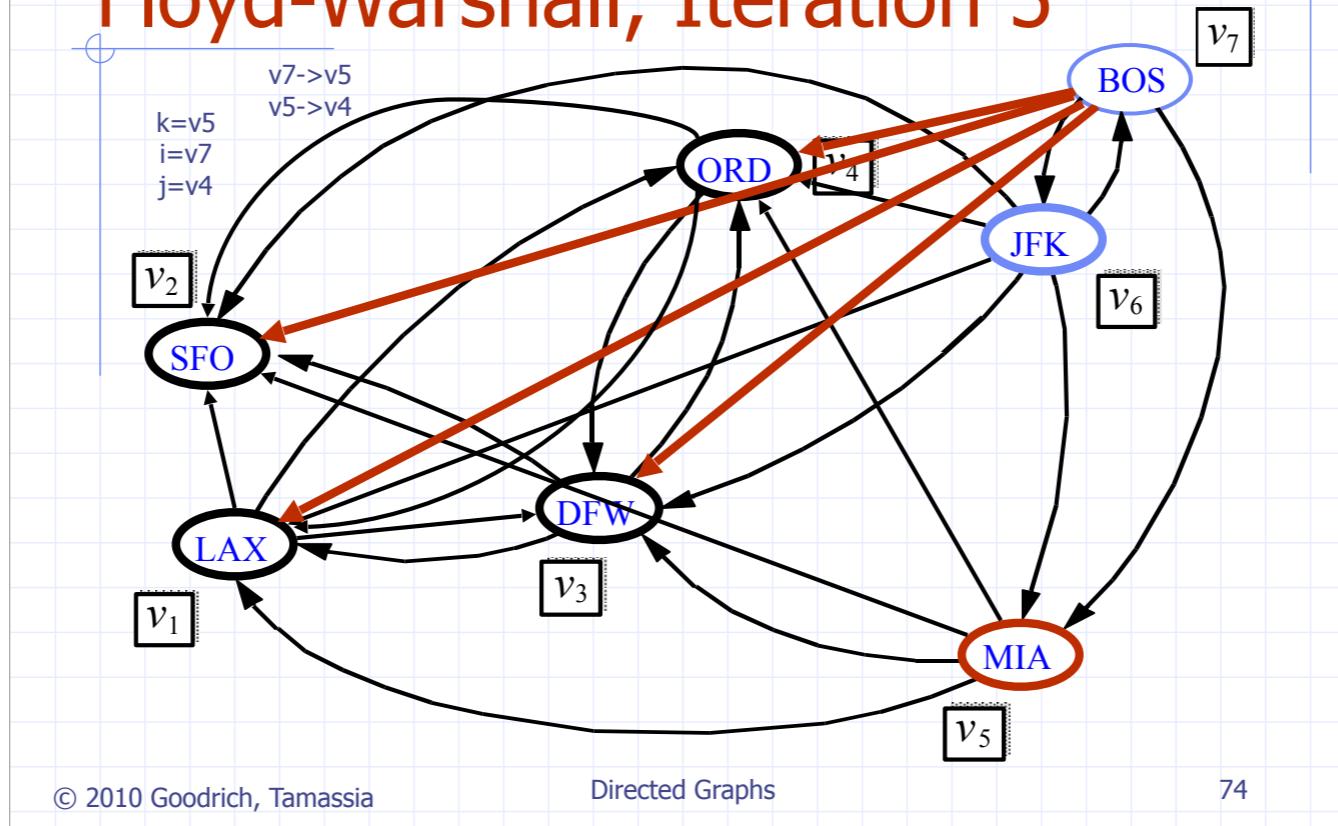
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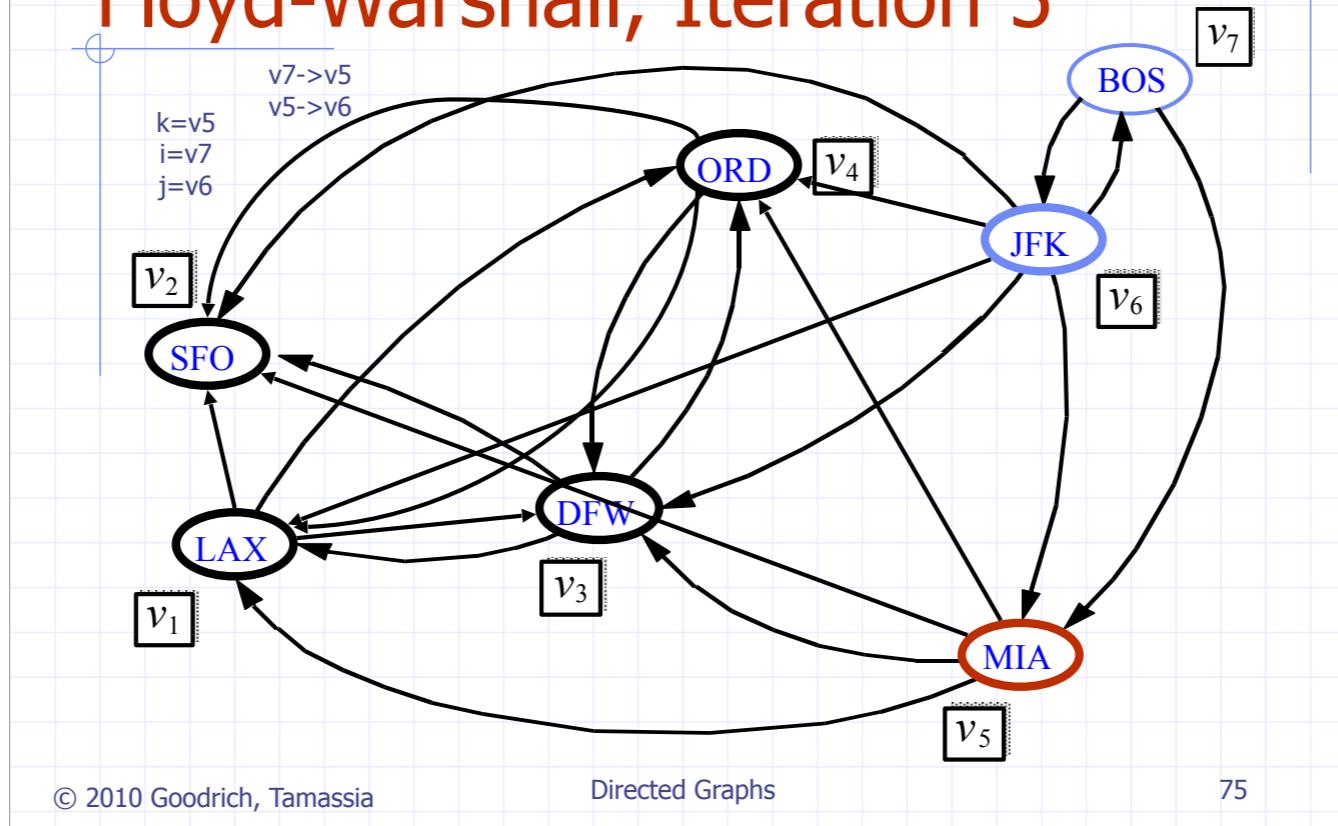
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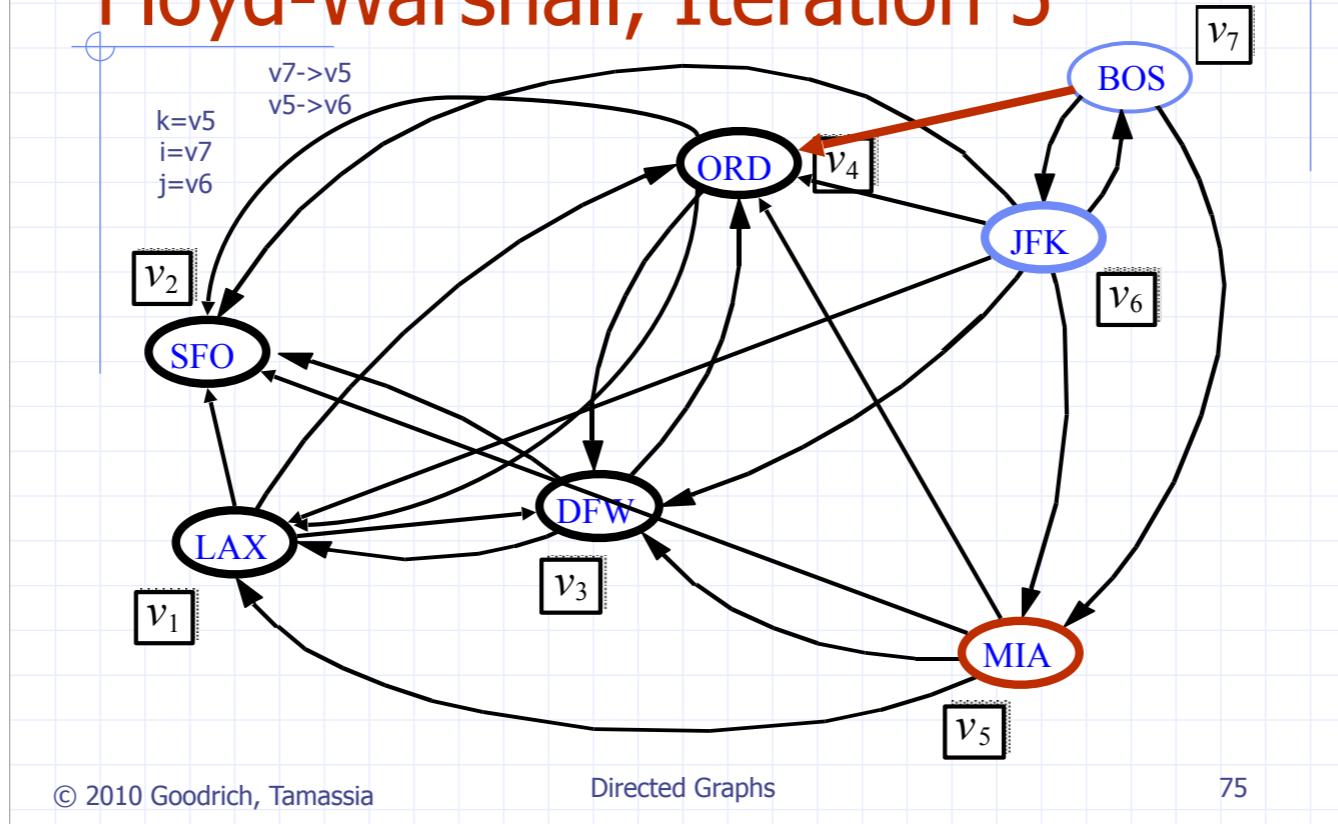
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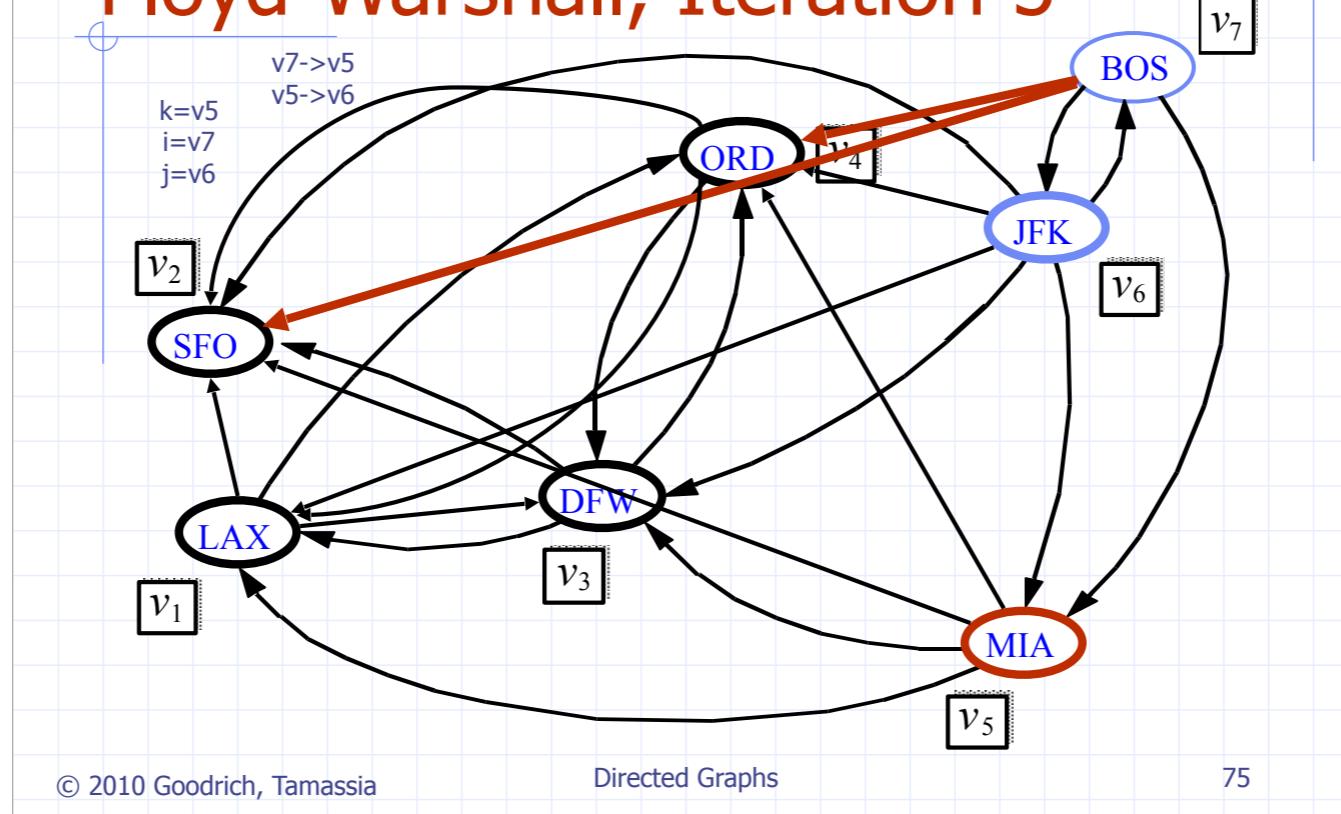
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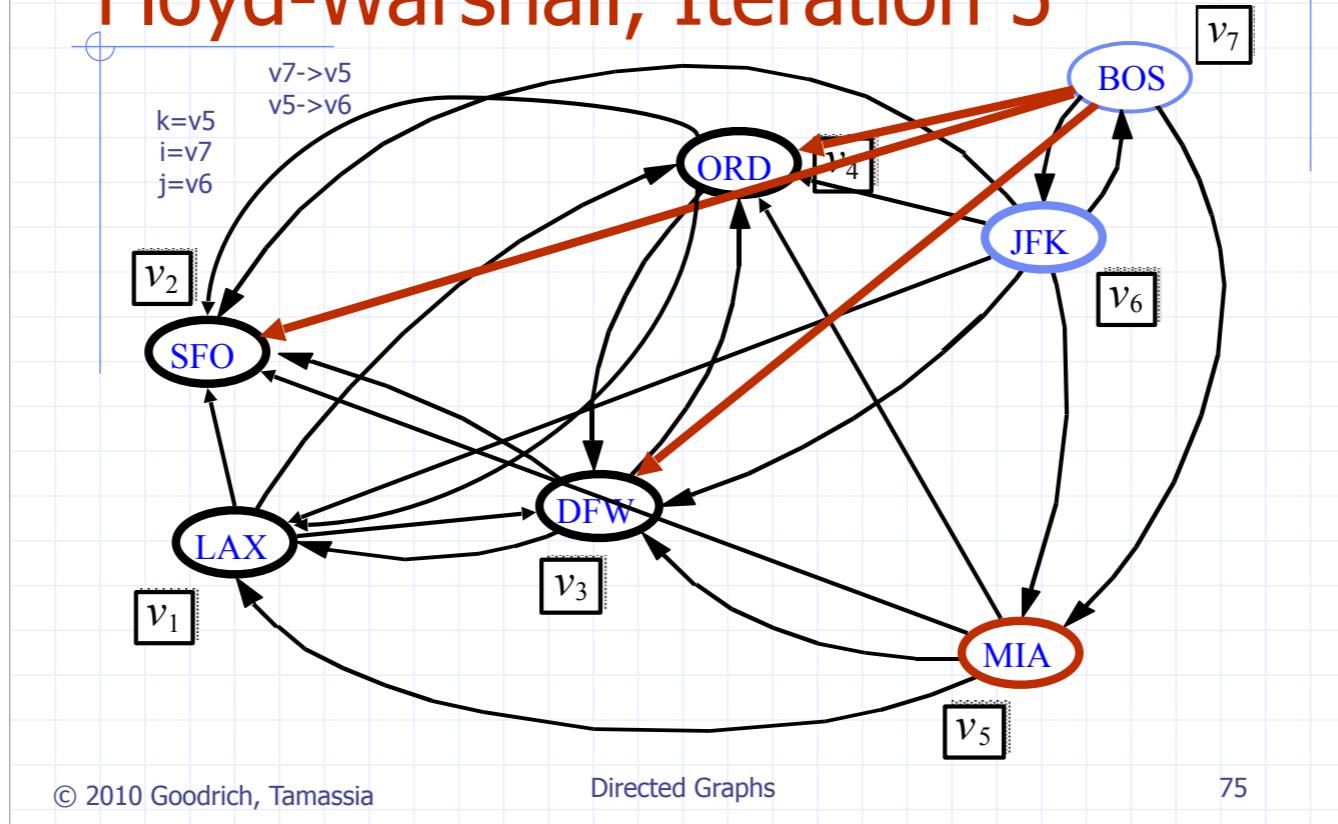
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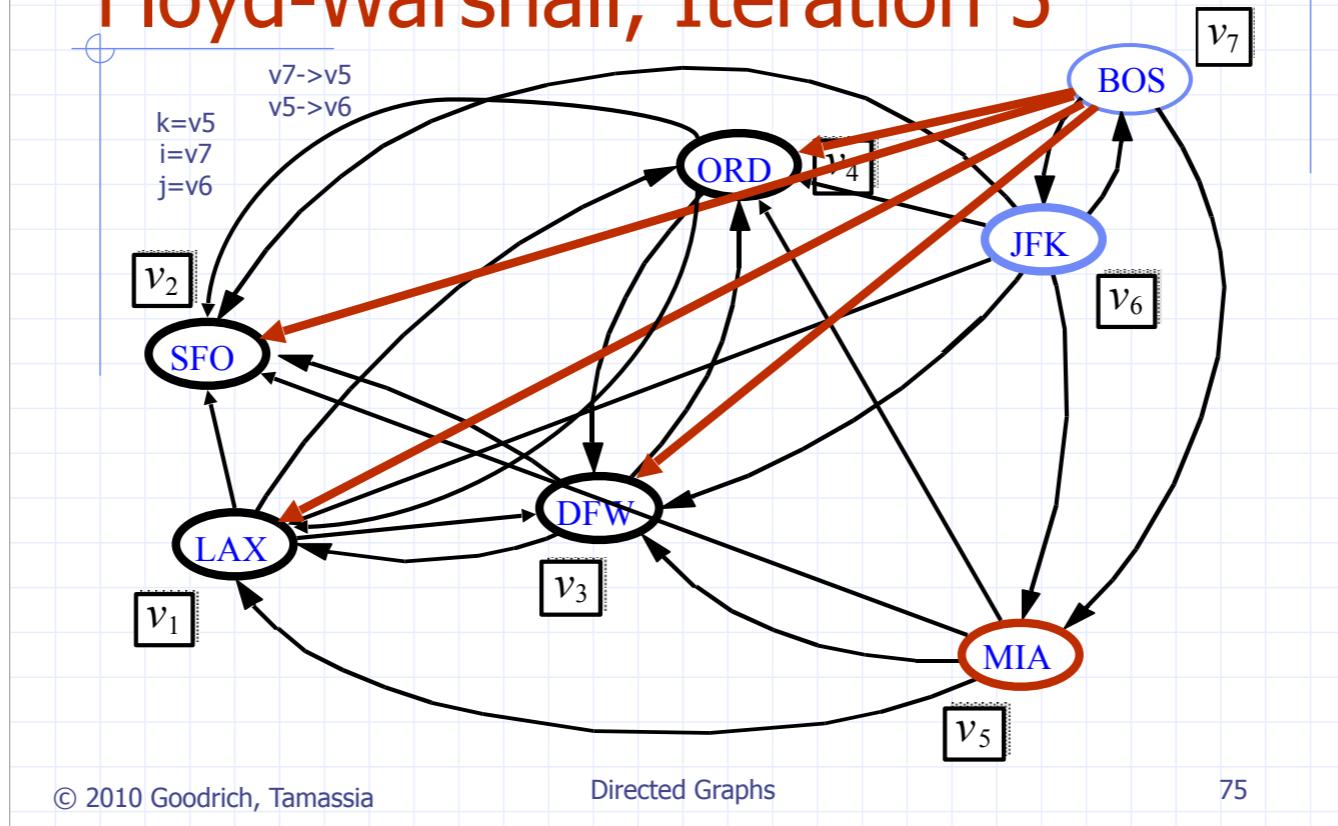
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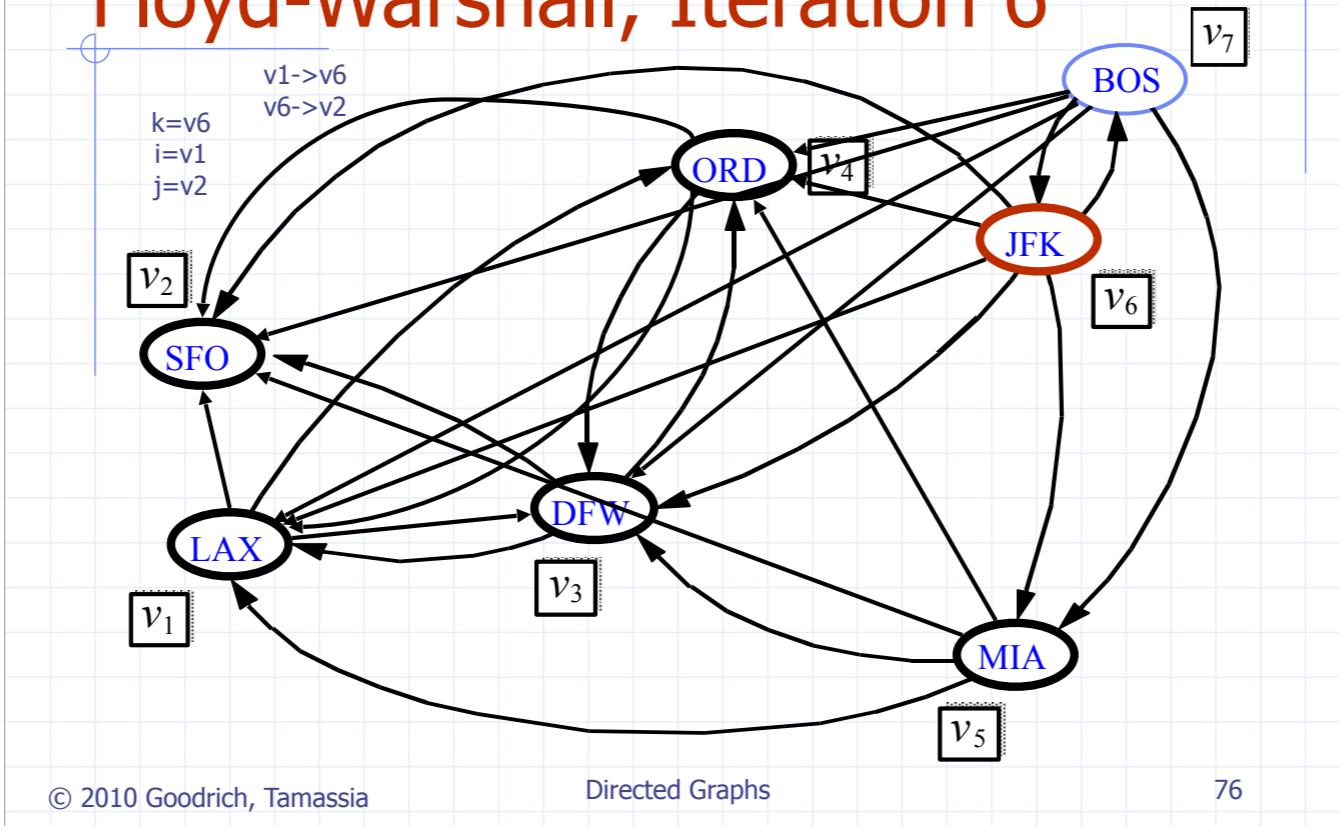
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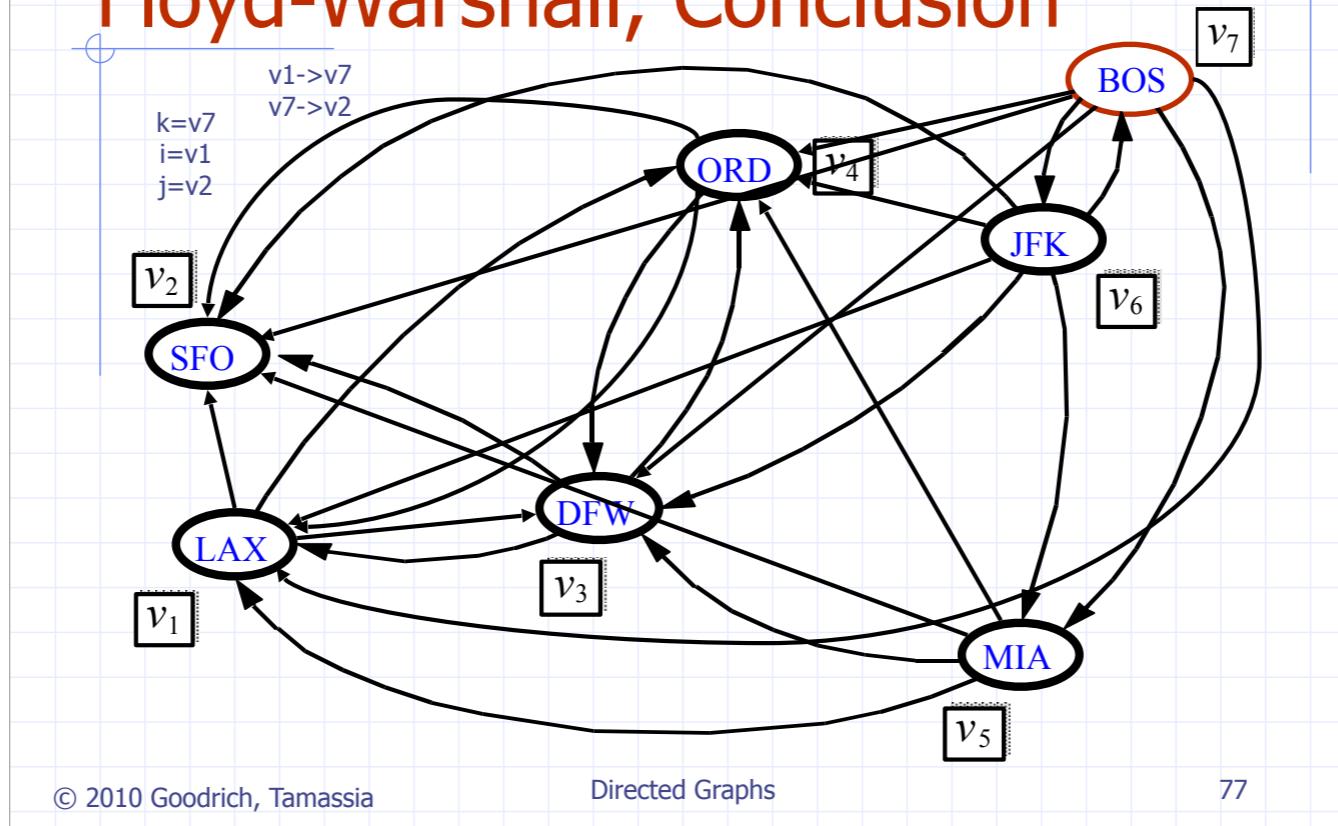
Floyd-Warshall, Iteration 5



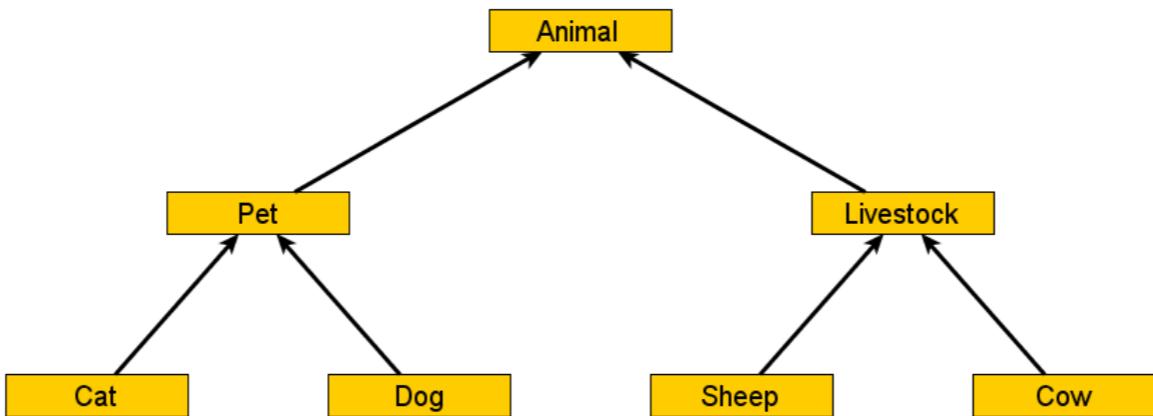
Floyd-Warshall, Iteration 6



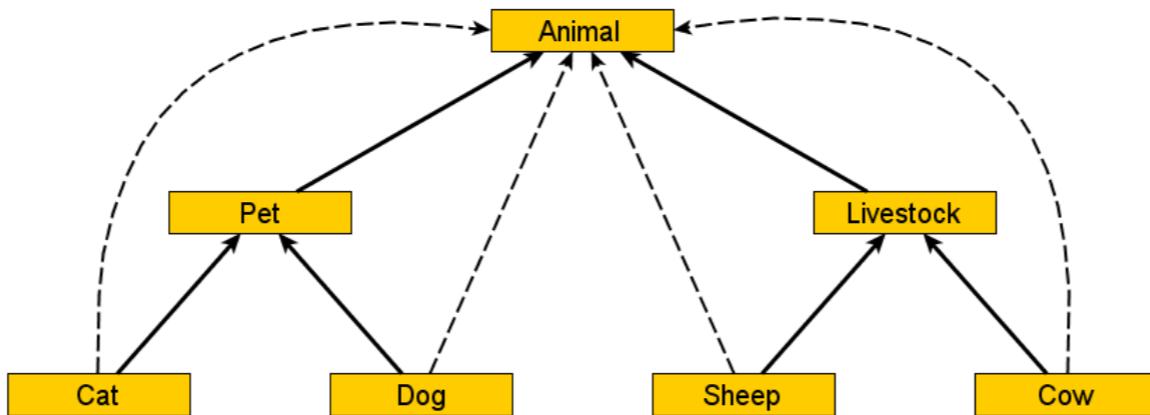
Floyd-Warshall, Conclusion



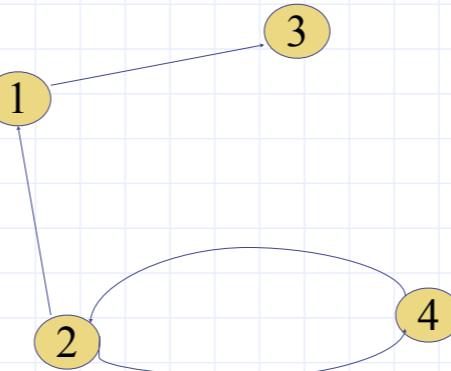
□ Transitive closure



□ Transitive closure



□ Transitive closure



□ Transitive closure

