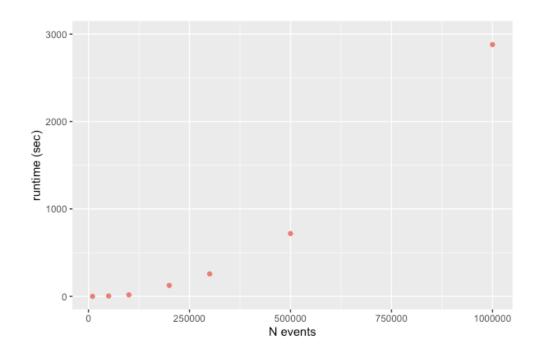
Jamie Goodin 12/17/22 SST Challenge Algorithm Rationale

Starting off (Method 1)

When first approaching this problem, I just wanted to get it sorting accurately, and sorted the events using nested for loops. For every event, it iterated through each existing level until it found a match (or not). But as the number of levels grew, performance spiraled, and by 250,000 inputs, it was clearly too slow. To start off, I was sorting with $O(n^2)$ complexity.



Method 1 performance

Interval tree

I then wondered if there was in answer in tracking each event's neighbors and leveraging a different data structure. I researched such approaches, and found the "interval tree" data structure. When applied appropriately, it can produce an algorithmic complexity of O(n*log(n)).

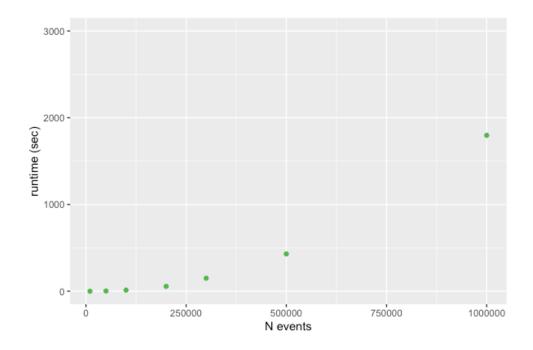
Rather than start from scratch, I tried out an Interval Tree <u>node package</u>. While it did sort events correctly, it was unfortunately much slower than my first solution—so much that I did not wait for it to complete larger jobs. Perhaps there was more complexity in the package's search and insert functions than I realized, or I had implemented it imperfectly. Regardless, I was unable to achieve a more efficient result using an interval tree.

Recursion and binary search

Recursion's best use cases are not performance-oriented, but I wanted to see I could use it to make searching more efficient. My implementation was functional, but only up to about 100,000 events. After that, I encountered memory issues and call stack limitations. I also tried a binary search that utilized recursion, but encountered the same issues.

A level-forward approach (Method 2)

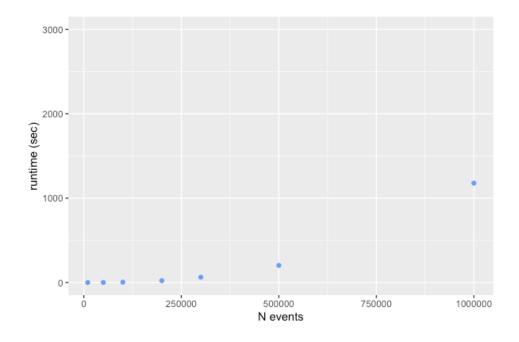
The recursive method introduced an important shift in my approach. Rather than iterating through each event and finding a level for it in a growing pool of levels, the algorithm instead filled a base level with as many events as possible. It then created and fills new levels until each event is sorted. I refactored the method to a while loop, and though it still had a complexity of $O(n^2)$, it was by far the fastest solution yet.



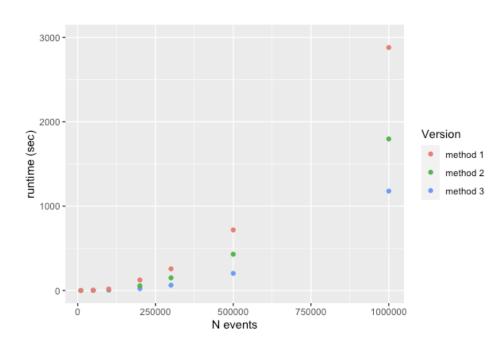
Method 2 performance

Sorted approach (Method 3)

The final and fastest method improves on the last one by taking a more intentional approach to packing the levels, an as of yet untapped source of improvement. It first sorts the inputs by endTime. It then compares the first event in the list's endTime to the next event's startTime, pushing the next event to the current level if it starts before the first event ends. This resulted in significantly better scaling, and a result I could be happy with.



Method 3 performance



All three methods' performance

Conclusion

After a lot of work and research, I have produced an algorithm that sorts correctly, and much more efficiently than some other options. This was a fun and interesting technical problem to analyze, and it's easy to see how it's relevant to Surgical Safety Technology's products. I look forward to discussing this challenge with your team, and learning more ways to approach it.