Exercise 1.5.16

(d)

Think about how your subroutines could be used to calculate the inverse of a positive definite matrix. Calculate  $A^{-1}$ , where

$$A = \begin{bmatrix} 1 & 1/2 & 1/3 \\ 1/2 & 1/3 & 1/4 \\ 1/3 & 1/4 & 1/5 \end{bmatrix}$$

It turns out that the entries of  $A^{-1}$  are all integers. Notice that your computed solution suffers from significant roundoff errors. This is because A is (mildly) ill conditioned. This is the 3x3 member of a famous family of ill-conditioned matrices called Hilbert matrices; the condition gets rapidly worse as the size of the matrix increases. We will discuss ill-conditioned matrices in Chapter 2. Answers

We can calculate a inverse matrix using Cholesky factorization because:

$$A = R^{T}R$$

$$A * A^{-1} = R^{T}R * A^{-1}$$

$$I = R^{T}R * A^{-1}$$

$$\begin{bmatrix} e_{1} \\ e_{2} \\ \vdots \\ e_{n} \end{bmatrix} = R^{T}R * A^{-1}$$

$$\begin{bmatrix} e_{1} \\ e_{2} \\ \vdots \\ e_{n} \end{bmatrix} = R^{T}R * \begin{bmatrix} a_{1}^{-1} & a_{2}^{-1} & \dots & a_{n}^{-1} \end{bmatrix}$$

$$\begin{bmatrix} e_{1} \\ e_{2} \\ \vdots \\ e_{n} \end{bmatrix}$$

Which can be simplified as:

$$\begin{bmatrix} e_1 = R^T R * a_1^{-1} \\ e_2 = R^T R * a_2^{-1} \\ \vdots \\ e_n = R^T R * a_n^{-1} \end{bmatrix}$$

In this way we can find the inverse of a Matrix with n "solves" using Cholesky. Each Cholesky solve makes one backward substitution and one foward substitution. They have the same complexity:  $n^2$ . Which gives us a solution in  $n^3$ .