









```
| mesonsy|
| import machine
| import time
| define pin numbers
| PTR_PIN = machine.Pin(27, machine.Pin.IN)
| BUZZER_PIN = machine.Pin(6, machine.Pin.OUT)
| Function to activate the buzzer
| def activate_buzzer():
| BUZZER_PIN.on() # Turn buzzer on for 0.5 seconds
| BUZZER_PIN.on() # Turn buzzer off
| define pin numbers
| Rain loop to detect motion
| while True:
| if PIB_PIN.value(): # PIR sensor detects motion
| print("Motion detected!")
| activate_buzzer() # Activate the buzzer
| time.sleep(0.2) # Small delay to debounce and save CPU
| motion detected
| motion de
```