CODE AND PLOTS

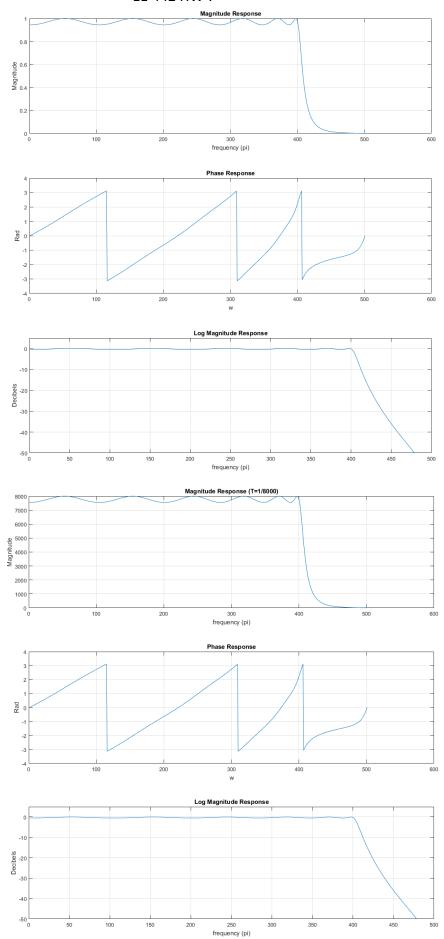
%% Question 1

```
%Impulse Invariance
% Initialize
T = [1 \ 1/8000]; % part 1 and part 2
fs = 8000;
wp = 3200*2*pi/fs;
ws = 3800*2*pi/fs;
Rp = 0.5;
As = 45;
% loop through different T values
for i = 1:length(T)
   Op = wp/T(i);
   Os = ws/T(i);
   % Build cheb filter and bilinear transformation
   [cs, ds] = afd chb1(Op, Os, Rp, As);
   [b, a] = imp invr(cs, ds, T(i));
    [db, mag, pha, grd, w] = freqz m(b, a);
    % Plot
   figure;
   subplot(3,1,1); plot(mag);
   title('Magnitude Response'); grid;
   xlabel('frequency (pi)'); ylabel('Magnitude');
    subplot(3,1,2); plot(pha);
   title('Phase Response'); grid
    xlabel('w'); ylabel('Rad')
    subplot(3,1,3);plot(db); axis([0 500 -50 5]); grid;
    title('Log Magnitude Response'); xlabel('frequency (pi)');
    ylabel('Decibels');
end
```

Q1 Part 3:

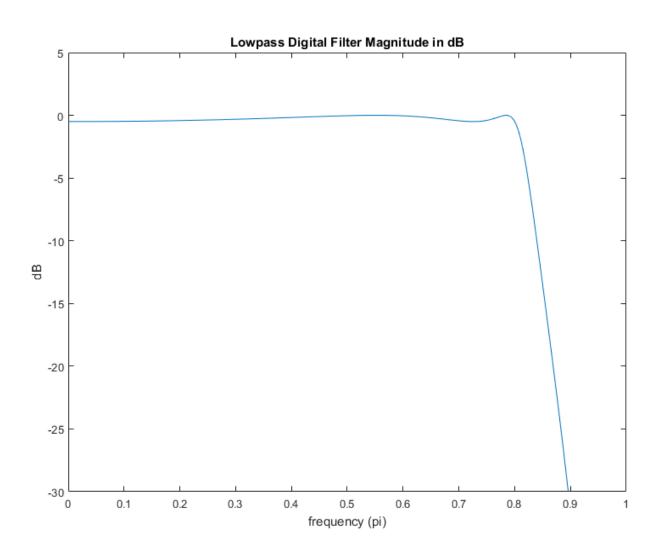
Using a T value smaller than one increased the magnitude of the filter significantly. This is not surprising as T is the numerical integration step size for trapezoidal integration, and a smaller T results in more partitioning of the data

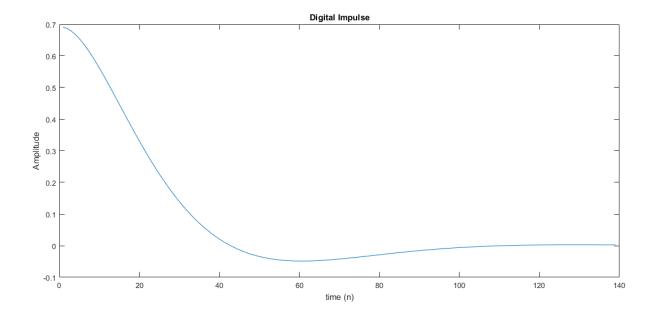


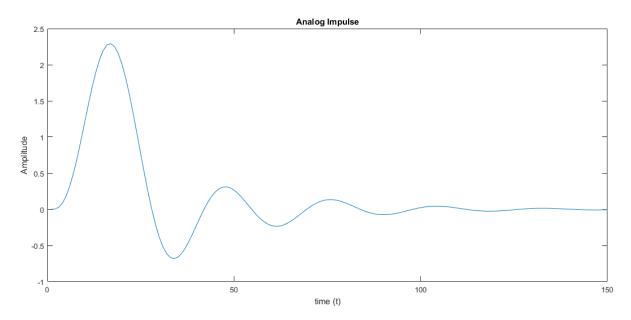


%% Question 2

```
% Bilinear Transform
% Initialize
Op = (2/T(1))*tan(wp/2);
Os = (2/T(1))*tan(ws/2);
% Build cheb filter and bilinear transformation
[cs, ds] = afd chb1(Op, Os, Rp, As);
[b, a] = bilinear(cs, ds, T(1));
[dbl,magl,phal,grdl,w] = freqz m(b,a);
% Plots
figure;
plot(w/pi,dbl); title('Lowpass Digital Filter Magnitude in dB');
xlabel('frequency (pi)'); ylabel('dB'); axis([0 1 -30 5]);
figure; subplot(2, 1, 1); plot(impulse(tf(b, a))); title('Digital Impulse')
xlabel('time (n)'); ylabel('Amplitude');
subplot(2, 1, 2); plot(impulse(tf(cs, ds))); title('Analog Impulse')
xlabel('time (t)'); ylabel('Amplitude');
```



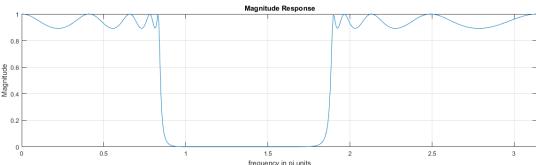


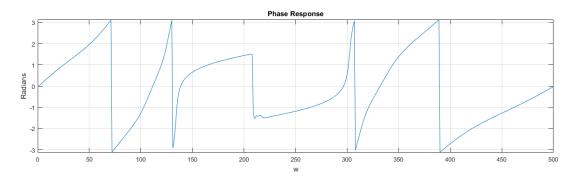


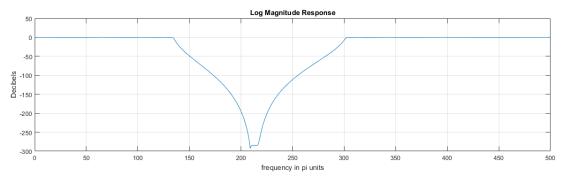
Compared to the analog impulse response, the digital one seems to be missing peaks. I suppose this may be due to the sampling time being too slow such that certain peaks are missed. It almost looks like the digital version is a smoother version of the analog equivalent.

%% Question 3

```
% Initialize
w1p = 0.2*pi; w1s = 0.3*pi;
w2s = 0.7*pi; w2p = 0.8*pi;
w0 = (w1s + w2s)/2; bw = w2p - w1p; % bandwidth and center
Rp = 1; As = 50;
% Build cheb filter
[N, Wc] = cheblord([0.2 0.8], [0.3 0.7], Rp, As, 's');
[Z, P, K] = cheblap(N, Rp);
[num, den] = zp2tf(Z, P, K);
[numt, dent] = lp2bs(num, den, w0, bw);
% Bilinear transformation
[nt, dt] = bilinear(numt, dent, 1);
[db,mag,pha,grd,w] = freqz m(nt,dt);
% Plot
figure;
subplot(3,1,1); plot(w, mag); axis([0 pi 0 1]);
title('Magnitude Response'); grid;
xlabel('frequency (pi)'); ylabel('Magnitude');
subplot(3,1,2); plot(pha); axis([0 500 -pi pi]);
title('Phase Response'); grid
xlabel('w'); ylabel('Rad')
subplot(3,1,3); plot(db); grid; axis([0 500 -300 50]);
title('Log Magnitude Response'); xlabel('frequency (pi)');
ylabel('dB');
```







(4)
$$P_1 = -3$$
 $P_2 = -5$ $I = -8$ $H(J_0) = I$ $F_5 = 10$

(a) $H(S) = \frac{5+8}{(5+3)(5+5)} = \frac{A}{5+3} + \frac{B}{5+5} = \frac{5/2}{5+3} - \frac{3/2}{5+5}$

Impulse

Invariance

A $\rightarrow -3/2$ $B \rightarrow 5/2$

H(z) = $\frac{5/2}{I-e^{-0.3}z^{-1}} - \frac{3/2}{I-e^{-0.5}z^{-1}} \rightarrow \frac{(-0.4 - \frac{1}{2})^{-1}}{(-0.4 - \frac{1}{2})^{-1}}$

(b) $H(S) = \frac{5+8}{(5+3)(5+5)} = \frac{5+8}{3^2+8+15} = \frac{1}{3^2+8+15}$

H(z) = $H(S) = \frac{1-2}{3}$

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Invariance

 $H(S) = \frac{5+8}{(5+3)(5+5)} = \frac{1-2}{3}$
 $H(S) = \frac{1-2}{3}$
 H