

Variables:

green = initial, determined constant values

blue = initial values pulled from Hummel Thesis

D = magnitude of drag force

ρ = density of air

v = magnitude of velocity

A = area of frisbee top

C_D = 'coefficient' of drag (not really a coefficient)

C_{D0} = form drag

$C_{D\alpha}$ = induced drag

α_0 = ideal angle of attack

α = angle of attack

C_L = 'coefficient' of lift (not really a coefficient)

C_{L0} = form lift

$C_{L\alpha}$ = induced lift

\vec{F}_L = Lift Force Vector

\vec{F}_D = Drag Force Vector

\vec{F}_g = Gravitational Force Vector

r = radius

m = mass

\vec{n} = normal vector of frisbee plane

Drag:

[1] Drag Force Magnitude:

$$D = \frac{\rho v^2 A C_D}{2}$$

[2] Coefficient of Drag:

$$C_D = C_{D0} + C_{D\alpha}(\alpha - \alpha_0)^2$$

[3] Drag Direction:

$$\vec{F}_D = D * -\hat{v}$$

Lift:

[4] Lift Force Magnitude:

$$L = \frac{\rho v^2 A C_L}{2}$$

[5] Coefficient of Lift:

$$C_L = C_{L0} + C_{L\alpha} * \alpha$$

[6] Lift Direction:

$$\vec{F}_L = L * \hat{n}$$

Gravity:

$$\vec{F}_g = m * -9.81 * \hat{k}$$

General Equations Used in the code:

[7] Area:

$$A = \pi r^2$$

[8] N2L:

$$\sum \vec{F} = m\vec{a} \quad \vec{a} = \frac{\sum \vec{F}}{m}$$

[9] Dot & Cross Product:

$$\vec{u} \cdot \vec{v} = u_1 v_1 + u_2 v_2 + u_3 v_3 \quad \vec{u} \times \vec{v} = \begin{bmatrix} u_2 v_3 - u_3 v_2 \\ u_3 v_1 - u_1 v_3 \\ u_1 v_2 - u_2 v_1 \end{bmatrix}$$

[10] Projection (a onto v):

$$\text{proj}_{\vec{v}} \vec{a} = \frac{\vec{a} \cdot \vec{v}}{\|\vec{v}\|^2} \vec{v}$$

[11] Projection onto a plane:

$$\text{proj}_{\text{plane}} \vec{a} = \vec{a} - \frac{\vec{a} \cdot \vec{n}}{\|\vec{n}\|^2} \vec{n}$$

[12] Angle between two vectors:

$$\theta = \arccos\left(\frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| * \|\vec{v}\|}\right)$$

[13] Position and its derivatives:

$$\overline{p(t)} = \int \overline{v(t)} dt \stackrel{[b]}{=} \iint \overline{a(t)} dt = \text{position}$$

$$\overline{p'(t)} = \overline{v(t)} = \int \overline{a(t)} dt \stackrel{[a]}{=} \text{velocity}$$

$$\overline{p''(t)} = \overline{v'(t)} = \overline{a(t)} = \text{acceleration}$$

What the code does:

1. Prompts user for input on Initial Velocity (vector), height thrown (float), mass(float), tilt angle above Y-axis (float, degrees), tilt angle above X-axis (float, degrees). (Note that angle on Z doesn't matter because that would be the spin of the frisbee)
2. Cycles the loop until 3 minutes is up or the frisbee hits the floor. Does this by making a for loop on 0 up to 180000 milliseconds (1 cycle = 1 ms), and breaks the loop if the height of the frisbee goes below 0 m.

Here's the loop:

- a. Computes angle of attack. Does this by finding the angle between the frisbee plane and frisbee velocity (initial velocity or velocity from last cycle) [11] -> [12]
- b. Computes drag coefficient (as angle of attack changed) [2]
- c. Computes drag force magnitude (as coefficient changed) [1]
- d. Multiplies this magnitude by negative normal vector of velocity (initial velocity or from last cycle) [3]
- e. Computes lift coefficient [5]
- f. Computes lift force magnitude [4]
- g. Multiplies this magnitude by normal vector of frisbee plane [6]
- h. Sums up force vectors (Lift, Drag, Gravity) [8]
- i. Divides sum of vectors by mass of frisbee to get acceleration vector [8]
- j. Takes current velocity and adds the product of the acceleration and time change ($v = v + a * 0.001s = v + a dt$) [13a]

- k. Takes the current position and adds the product of the velocity and time change ($p = p + v * 0.001s = p + vdt$) **[13b]**
- l. Appends the current time (i in the loop) to a time array, appends current position to position a position tracking loop (x, y and z) and appends current velocity magnitude to a velocity array. These are used for the plotting.
- m. Checks if the frisbee height is less than or equal to 0. If it is, breaks the loop
- n. If not, restarts from a)

3. Plots the data

The ODE:

Calculating Drag:

$$\overline{F_D} = -D * \hat{v}$$

$$\overline{F_D} = -D * \frac{\bar{v}}{\|\bar{v}\|}$$

$$\overline{F_D} = -\frac{1}{2} \rho \|\bar{v}\|^2 AC_D * \frac{\bar{v}}{\|\bar{v}\|} = -\frac{1}{2} \rho \|\bar{v}\|^2 AC_D * \frac{\bar{v}}{\|\bar{v}\|}$$

$$\overline{F_D} = -\frac{\rho \|\bar{v}\| AC_D}{2} * \bar{v}$$

$$\overline{F_D} = \underbrace{-\frac{\rho A}{2}}_{constant} * \underbrace{C_D \overline{v(t)} \|\overline{v(t)}\|}_{variable}$$

Calculating Lift:

$$\overline{F_L} = L * \hat{n}$$

$$\overline{F_L} = \frac{\rho \|\bar{v}\|^2 AC_L}{2} * \hat{n}$$

$$\overline{F_L} = \underbrace{\frac{\rho A}{2}}_{constant} * \underbrace{C_L \|\bar{v}\|^2}_{variable}$$

Gravity:

$$\overline{F_g} = \underbrace{m * -9.81 * \hat{k}}_{constant}$$

Grouping together and coming up with the ODE:

$$\overline{p(t)} = \int \overline{v(t)} dt = \iint \overline{a(t)} dt = position$$

$$\overline{p'(t)} = \overline{v(t)} = \int \overline{a(t)} dt = velocity$$

$$\overline{p''(t)} = \overline{v'(t)} = \overline{a(t)} dt = acceleration$$

$$\overline{a(t)} = \frac{\Sigma \overline{F}}{m} = \left(\frac{1}{m}\right) \Sigma \overline{F}$$

$$\overline{a(t)} = \left(\frac{1}{m}\right) (\overline{F_D} + \overline{F_L} + \overline{F_g})$$

$$\overline{a(t)} = \left(\frac{1}{m}\right) \left(-\frac{\rho A}{2} * C_D \overline{v(t)} \|\overline{v(t)}\| + \frac{\rho A}{2} \hat{n} * C_L \|\bar{v}\|^2 + m * -9.81 * \hat{k}\right)$$

$$\overline{a(t)} = -\frac{\rho A}{2m} * C_D \overline{v(t)} \|\overline{v(t)}\| + \frac{\rho A}{2m} \hat{n} * C_L \|\bar{v}\|^2 - 9.81 * \hat{k}$$

$$\overline{p''(t)} = -\frac{\rho A}{2m} * C_D \overline{p'(t)} \|\overline{p'(t)}\| + \frac{\rho A}{2m} \hat{n} * C_L \|\overline{p'(t)}\|^2 - 9.81 * \hat{k}$$

Assumptions:

- Constant air distribution
- Center of mass and center of pressure are the same:
 - o No moments will occur
 - o Angle of attack remains the same due to the lack of moments
- Gyroscopic effects are strong enough to keep the frisbee in the same orientation
- The frisbee stops as soon as it hits the floor