# Homework 2 Solution PubH 7440: Introduction to Bayesian Analysis Spring 2020

### 1. (Gelman, Chapter 3, Problem 3):

(a).

Since

$$p(\mu_c, \sigma_c^2 | y_c) \propto p(\mu_c, \sigma_c^2) \prod_{i=1}^{32} p(y_{ci} | \mu_c, \sigma_c^2)$$
 and  $p(\mu_t, \sigma_t^2 | y_t) \propto p(\mu_t, \sigma_t^2) \prod_{i=1}^{36} p(y_{ti} | \mu_t, \sigma_t^2)$ .

From the derivations in the lecture notes, the marginal posterior distribution for  $\mu_c$  and  $\mu_t$  follow t-distribution with location-scale parameters to be (1.013, 0.025/ $\sqrt{32.31}$ ) and (1.173, 0.2/6) respectively, and degree of freedom to be 31 and 35 respectively.

(b).

Example R code:

```
mu.c <- 1.013 + (0.025/sqrt(32))*rt(1000,31)

mu.t <- 1.173 + (0.20/sqrt(36))*rt(1000,35)

dif <- mu.t - mu.c

hist (dif, xlab="mu_t - mu_c", yaxt="n",

breaks=seq(-.1,.4,.02), cex=2)

print (sort(dif)[c(25,976)])
```

## 2. (Gelman, Chapter 3, Problem 9):

Let  $\ \overline{y}$  and  $s^2$  be the sample mean and sample variance: Then,

$$p(\mu,\sigma^2|y) \propto p(y|\mu,\sigma^2)p(\mu|\sigma^2)p(\sigma^2)$$

$$\propto \sigma^{-n} \exp\left(-\frac{(n-1)s^2 + n(\mu-\bar{y})^2}{2\sigma^2}\right)\sigma^{-1} \exp\left(-\frac{k(\mu-\mu_0)^2}{2\sigma^2}\right)(\sigma^2)^{-\nu_0-1} \exp\left(-\frac{\sigma_0^2}{\sigma^2}\right)$$

$$\propto \sigma^{-1}(\sigma^2)^{-\left(\frac{n}{2}+\nu_0+1\right)} \exp \left(-\frac{(n+k)\left(\mu-\frac{n\bar{y}+k\mu_0}{n+k}\right)^2+\frac{nk(\mu_0-\bar{y})^2}{n+k}+2\sigma_0^2+(n-1)s^2}{2\sigma^2}\right)$$

Hence

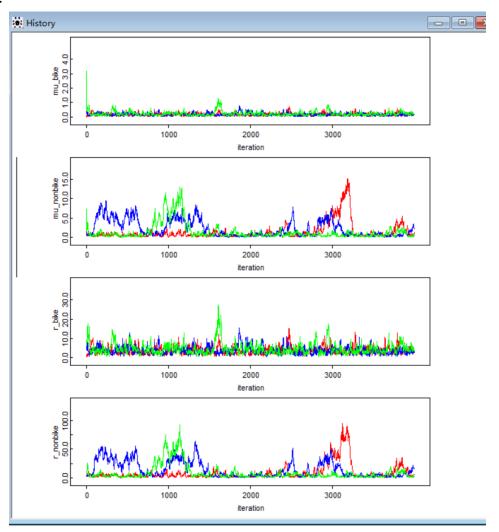
$$\mu, \sigma^2 | y \sim N - Inv(\frac{\mu_0 k_0 + n\bar{y}}{n+k}, n+k; \frac{n}{2} + v_0, 2\sigma_0^2 + (n-1)s^2 + \frac{nk(\mu_0 - \bar{y})^2}{n+k})$$

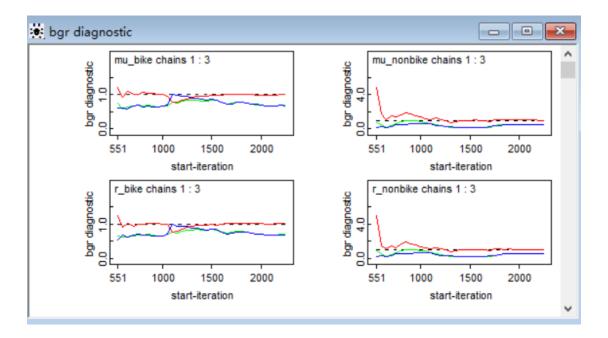
3.

```
(a).
   model
   {
    for( i in 1 : k bike ) {
```

```
y_bike[i] ~ dpois(lambda_bike[i])
lambda_bike[i] ~ dgamma(r_bike, mu_bike)
}
for( i in 1 : k_nonbike ) {
  y_nonbike[i] ~ dpois(lambda_nonbike[i])
lambda_nonbike[i] ~ dgamma(r_nonbike, mu_nonbike)
}
  r_bike ~ dgamma(0.01, 0.01)
  mu_bike ~ dgamma(0.01, 0.01)
  r_nonbike ~ dgamma(0.01, 0.01)
  mu_nonbike ~ dgamma(0.01, 0.01)
}
```

(b).





The trace plots and Gelman-Rubin statistic for the bike intersections show clear convergence. It is less clear for the non-bike data. The trace plots suggest that the chains may not have converged, whereas the Gelman-Rubin statistic is consistent with convergence.

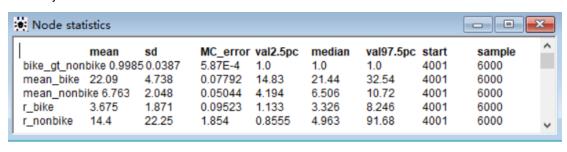
(c).

```
- - X
Node statistics
             mean
                        sd
                                  MC error val2.5pc
                                                       median
                                                                 val97.5pc start
                                                                                      sample
 lambda_bike[1] 16.8
                        3.821
                                  0.04567
                                             10.11
                                                       16.49
                                                                  25.09
                                                                            4001
                                                                                      6000
                                  0.05455
                                             5.57
                                                       10.51
                                                                  17.58
                                                                            4001
                                                                                      6000
 lambda_bike[2] 10.8
                        3.101
 lambda_bike[3] 11.6
                        3.236
                                  0.04985
                                             6.198
                                                       11.26
                                                                  18.82
                                                                            4001
                                                                                      6000
 lambda_bike[4] 14.23
                        3.518
                                  0.0509
                                             8.069
                                                       13.93
                                                                 21.88
                                                                            4001
                                                                                      6000
                                                                                      6000
 lambda_bike[5] 19.36
                        4.058
                                  0.05995
                                             12.26
                                                       19.0
                                                                 28.0
                                                                            4001
 lambda_bike[6] 20.15
                        4.158
                                  0.05826
                                             12.79
                                                       19.89
                                                                 29.07
                                                                            4001
                                                                                      6000
                        4.005
                                  0.05725
                                                       18.27
                                                                 26.93
                                                                            4001
                                                                                      6000
 lambda_bike[7] 18.51
                                             11.48
 lambda_bike[8] 17.6
                        3.867
                                  0.04935
                                             10.85
                                                       17.3
                                                                  25.9
                                                                            4001
                                                                                      6000
                                                                  44.52
                                                                                      6000
 lambda_bike[9] 33.0
                                  0.08499
                                             23.31
                                                       32.72
                                                                            4001
                        5.42
 lambda bike[10] 50.22 6.932
                                             37.59
                                                       49.86
                                                                 64.87
                                                                                      6000
                                  0.1526
                                                                            4001
 lambda_nonbike[1] 9.297 2.712
                                  0.1153
                                             5.323
                                                       8.87
                                                                  15.67
                                                                            4001
                                                                                      6000
                                             0.6373
                                                       3.522
                                                                 7.512
                                                                            4001
                                                                                      6000
 lambda_nonbike[2] 3.669 1.878
                                  0.1069
 lambda_nonbike[3] 4.191 1.826
                                  0.08966
                                             1.052
                                                       4.094
                                                                 7.979
                                                                            4001
                                                                                      6000
 lambda_nonbike[4] 5.216 1.758
                                  0.05202
                                             2.082
                                                       5.153
                                                                 8.93
                                                                            4001
                                                                                      6000
 lambda nonbike[5] 7.779 2.216
                                                                                      6000
                                  0.06465
                                             4.357
                                                       7.464
                                                                  12.98
                                                                            4001
 lambda_nonbike[6] 6.753 1.98
                                  0.03814
                                             3.538
                                                       6.528
                                                                  11.47
                                                                            4001
                                                                                      6000
 lambda_nonbike[7] 7.776 2.268
                                  0.06609
                                             4.298
                                                       7.449
                                                                  13.22
                                                                            4001
                                                                                      6000
 lambda_nonbike[8] 7.241 2.082
                                   0.04642
                                             3.834
                                                       6.98
                                                                  12.08
                                                                            4001
                                                                                      6000
                                  0.004732
                                            0.0451
                                                       0.1557
                                                                 0.3952
                                                                            4001
                                                                                      6000
 mu_bike
             0.173
                        0.09305
                                                                  15.07
                                                                                      6000
 mu_nonbike 2.256
                        3.544
                                  0.2961
                                             0.1075
                                                       0.7772
                                                                            4001
 r_bike
              3.675
                        1.871
                                  0.09523
                                             1.133
                                                       3.326
                                                                 8.246
                                                                            4001
                                                                                      6000
                        22.25
                                   1.854
                                             0.8555
                                                       4.963
                                                                 91.68
                                                                            4001
                                                                                      6000
              14.4
 r_nonbike
                      TITIO_HOHDING Ugarrima(0.01, 0.01)
```

```
(d).
   model
   {
   for( i in 1 : k bike ) {
```

```
y_bike[i] ~ dpois(lambda_bike[i])
lambda_bike[i] ~ dgamma(r_bike, mu_bike)
}
for( i in 1 : k_nonbike ) {
  y_nonbike[i] ~ dpois(lambda_nonbike[i])
lambda_nonbike[i] ~ dgamma(r_nonbike, mu_nonbike)
}
  r_bike ~ dgamma(0.01, 0.01)
  mu_bike ~ dgamma(0.01, 0.01)
  r_nonbike ~ dgamma(0.01, 0.01)
  mu_nonbike ~ dgamma(0.01, 0.01)

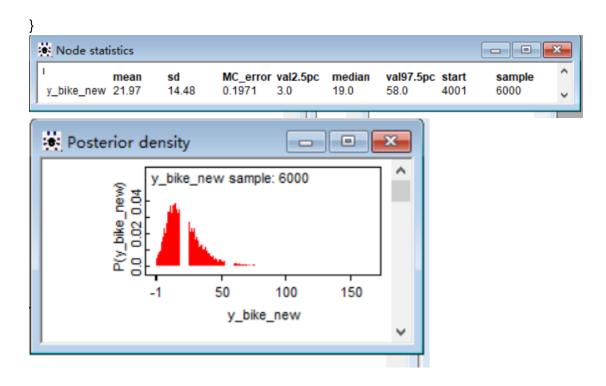
mean_bike<-r_bike/mu_bike
  mean_nonbike<-r_nonbike/mu_nonbike
bike_gt_nonbike <- step(mean_bike-mean_nonbike)
}
```



```
(e).
model
{
for( i in 1 : k_bike ) {
y_bike[i] ~ dpois(lambda_bike[i])
lambda bike[i] ~ dgamma(r bike, mu bike)
}
for( i in 1 : k_nonbike ) {
y_nonbike[i] ~ dpois(lambda_nonbike[i])
lambda_nonbike[i] ~ dgamma(r_nonbike, mu_nonbike)
r_bike ~ dgamma(0.01, 0.01)
mu_bike ~ dgamma(0.01, 0.01)
r_nonbike ~ dgamma(0.01, 0.01)
mu_nonbike ~ dgamma(0.01, 0.01)
mean_bike<-r_bike/mu_bike
mean nonbike<-r nonbike/mu nonbike
```

# bike\_gt\_nonbike <- step(mean\_bike-mean\_nonbike)</pre>

```
lambda_bike_new~dgamma(r_bike,mu_bike)
y_bike_new~dpois(lambda_bike_new)
```



#### 4.

```
Example R code:
####define the target density###
f<-function(x){
  out < (1/3) * dnorm(x, mean = -5) + (1/3) * dnorm(x) + (1/3) * dnorm(x, mean = 5)
  return(out)
}
####importance sampling###
set.seed(100)
## sampling from candidate density
n < -200
x < -rnorm(n, 0, sqrt(20))
####calculate the weights###
w < -f(x)/dnorm(x, sd = sqrt(20))
round(weighted.mean(x, w),2)
round(weighted.mean(x^2, w) - weighted.mean(x,w)^2,2)
####rejection sampling###
rej_algorithm <- function(xxx) {</pre>
  accept <- 0
  while(accept == 0) {
    M < -3
```

```
theta <- rnorm(n=1, sd = 5)
  U <- runif(n=1,min = 0, max = 1)
  accept <- 1*(U < f(theta) / (M * dnorm(theta, sd = 5)))
}
return(theta)
}
set.seed(100)
rej_samples <- sapply(1:200, rej_algorithm)
round(mean(rej_samples),2)
round(var(rej_samples),2)</pre>
```