

Optimization problems

Unconstrained optimization:
- objective function f(x), smooth

- find w that minmzer f

- Flus stubal & local minima

-f(x) is convex if $\forall x, y \in \mathbb{R}^d$ a line segment (x, f(x) to (y, fly)) never goes below f(.)

- Continues coux for his one of:

- no minimum

- one unique global minimum (Strong convexity)

- connected set of local minima we equal f(.)

Som of fi, fi convex vi, Still convex

Algos for general snooth f:

- Gradient elecent

by blind (w) tearny rule)

by stochustic blind

by w) line search

- Newton's Method (requires thessian)

- Non linear Conjugate gradient

Algos for non-snooth &:
- gradient decent
- BRGS (Broyden-Flotchel-Goldferb-Shemo)

line search

-project clown to 1D and use that result to inform your step size.
Ly in 1D its easy to use secont method / Newton's method to chinest search

Constrained optimization

given f(x) and constraints g(x)=0Los use Lagrangian to make it unconstrained

min
$$C^T \times A \times \leq b$$

$$\times \mathbb{R}^d \mid A \in \mathbb{R}^{n \times d} \mid b \in \mathbb{R}^r \mid c \in \mathbb{R}^d$$

- optima lite or verticies (when some constraints hold up equality)

Hord-margin SVM: support vectors one active constraints

Algos:

- simplex: walk vertices to find optimum

- interior point methods

QPS

Algos:

-simplex (good in general)

- Sequential minimal optimization (SNO)

- coordinate descent