Iron Man’s First Experiment

Technical Specification

# Rover

### Ports

* Port B
  + RB4: Input, IR Receiver (Wireless Communication)
  + RB3: Output, CCP2 (Right Motor PWM)
* Port E – Output
  + RE0: Output , CCP3 (Left Motor PWM)

## Glove

### Ports

## Communication Protocol

Stop: 0

Forward: 1

Reverse: 2

Left: 3

Right 4:

Optional (figure out motions if have time): Loop (5), Figure 8 (6)