MA-224 Review

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1 Probability

1.1 Basic Concepts

Statistics The study of collected data.

Data Qualitative or quantitative information that you obtain through experiments.

Experiment An unbiased, random, planned activity. Outcomes are simple, events are more complex.

Frequency The number of times that something occurs. There are three ways to display frequency: A frequency table, a bar graph, and a relative frequency table.

Probability Experimental and theoretical are two types. Theoretical is if an experiment is done many times. It is equivalent to $\frac{\# \text{ of times event occurs}}{\text{Total}}$.

Probability Mass Function A way of defining the relative frequency with a function.

1.2 Properties of Probability

A set is a group or collection of well-defined objects. The set of all possible outcomes is called the sample space and is denoted by Ω or S.

Operations of Sets

Union $A \cup B = \{x \mid x \in A \& x \in B\}$

Intersection $A \cap B = \{x \mid x \in A \text{ or } x \in B\}$

Complement \bar{A} or $A^C = \{x \mid x \in A \& x \not\in A\}$

Special Sets

Universal Set Set of all events, denoted by U.

Empty Set Nothing in this set, denoted by \emptyset .

Singleton A set with one element.

Mutually Exclusive Sets $A \cap B = \emptyset$

Exhaustive Sets Mutually exclusive but the union covers U.

Equally Likely Events Events that have the same probability of happening.

1.3 Methods of Enumeration

Multiplication Principle

If one experiment has n_1 outcomes, and another experiment has n_2 outcomes, the composite experiment will have n_1n_2 outcomes.

Permutations

Now suppose that that n positions are to be filled with n objects. There are $(n)(n-1)\dots(2)(1)$ or n! possible arrangements. Each of these arrangements is called a **permutation**. A permutation of n objects with r taken at a time is denoted as follows.

$$_{n}P_{r} = \frac{n!}{(n-r)!}$$

Combinations

The number of ways in which r objects can be selected without replacement from n objects is called a **combination**. A combination of n objects with r taken at a time is denoted as follows.

$$\binom{n}{r} =_{n} C_{r} = \frac{n!}{r! (n-r)!}$$

1.4 Conditional Probability

The **conditional probability** of an event, or the probability of A occurring given that B will occur is denoted as follows.

 $P(A \mid B) = \frac{P(A \cap B)}{P(B)}$

By rearranging the above equation, the probability of both A and B occurring can be denoted as follows.

$$P(A \cap B) = P(A \mid B) * P(B)$$

$$P(A \cap B) = P(B \mid A) * P(A)$$

1.5 Independent Events

If the occurrence of one event will not change the probability of the occurrence of another event, these events are **independent**. Properties of independent events are as follows.

$$P(B \mid A) = P(B) \qquad P(A \mid B) = P(A)$$

$$P(A \cap B) = P(A) P(B) = P(B) P(A)$$

If an event does not satisfy these properties, the events are called **dependent**. Below are other sets that are independent if A and B are independent.

$$A$$
 and B' A' and B A' and B'

1.6 Bayes's Theorem

The probability of an event A can be calculated as follows.

$$P(A) = \sum_{i=1}^{m} P(B_i \cap A) = \sum_{i=1}^{m} P(B_i) P(A \mid B_i)$$

To determine the probability of a specific outcome B_k , the equation for conditional probability can be used to obtain **Bayes's Theorem**, which is as follows.

$$P(B_k | A) = \frac{P(B_k)P(A | B_k)}{\sum_{i=1}^{m} P(B_i) P(A | B_i)}$$
 for $k = 1, 2, 3 ... m$

2 Discrete Distributions

2.1 Random Variables of the Discrete Type

Given a random experiment with outcome space S, a function X that assigns one real number to each element int S is called a **random variable**. If S contains a finite number of points, or the points of S can be put into a one-to-one correspondence with positive integers, X becomes a random variable of the **discrete type**. A probability mass function of a discrete random variable satisfies the following properties.

$$f(x) > 0$$
 $\sum_{x \in S} f(x) = 1$ $P(X \in A) = \sum_{x \in A} f(x)$

There are two ways of representing a probability mass function. One way is with a **bar graph**, in which f(x) is represented with a vertical line segment. Another way of representing a probability mass function is with a **probability histogram**, where each probability is depicted by a rectangle with base length 1.

2.2 Mathematical Expectation

There are many important characteristics of a discrete distribution. One is the **mathematical expectation**. The mathematical expectation of a function of X is as follows.

$$E[X] = \sum_{x \in S} x f(x)$$

Below are some properties of the expected value of a function, E.

$$E(c) = c$$
 $E[cX] = cE[X]$

$$E[c_1X + c_2X] = c_1E[X] + c_2E[X]$$

2.3 The Mean, Variance, and Standard Deviation

The **mean** of a random variable X is as follows.

$$\mu = \sum_{x \in S} x f(x) = E[X]$$

The **variance** of the random variable X, or of the distribution of X is as follows.

$$\sigma^2 = \sum_{x \in S} (x - \mu)^2 f(x) = E([(X - \mu)]^2 = E[X^2] - \mu^2$$

The standard deviation is the square root of the variance.

$$\sigma = \sqrt{\sigma^2}$$

The r^{th} moment of the distribution about b is

$$E[(X - b)^r] = \sum_{x \in S} (x - b)^r f(x)$$

The r^{th} factorial moment is

$$E[(X)_r] = E[X(X-1)(X-2)...(X-r+1)]$$

2.4 Bernoulli Trials and the Binomial Distribution

A **Bernoulli experiment** is a random experiment, the outcome of which can be classified as a success or a failure. A sequence of **Bernoulli trials** occurs when a Bernoulli experiment is performed several independent times so that the probability of success reminds the same from trial to trial. Let the probability of success be p and the probability of failure be q = 1 - p.

If there are only outcomes of success and failure, we can say that X has a **Bernoulli distribution**. The expected value of X can be written as follows.

$$\mu = E[X] = \sum_{x=0}^{1} xp^{x} (1-p)^{1-x} = p$$

The variance of X can be written as follows.

$$\sigma^2 = \sum_{x=0}^{1} (x-p)^2 p^x (1-p)^{1-x} = \sqrt{pq}$$

If the trials are independent, and the probabilities of success and failure on each trial are p and q respectively, X has a **binomial distribution**, and the probability mass function of X is as follows.

$$f(x) = \binom{n}{x} p^x (1-p)^{n-x}$$

2.5 The Moment-Generating Function

Let X be a discrete random variable with probability mass function f(x) and space S. If there is a positive number h such that $-h \le t \le h$, the **Moment-Generating function** can be defined as follows.

$$E[e^{tX}] = \sum_{x \in S} e^{tx} f(x)$$

The Moment-Generating function can be related to the mean and variance of a distribution.

$$\mu = M'(0) = E[X]$$
 $\sigma^2 = M''(0) - [M'(0)]^2 = E[X^2] - E[X]^2$

A negative binomial distribution has a probability mass function defined as follows.

$$f(x) = \begin{pmatrix} x-1 \\ r-1 \end{pmatrix} \, p^r \, q^{x-r}$$

If a negative binomial distribution has an r value of 1, the distribution is said to be a **geometric distribution** which has a probability mass function as follows.

$$f(x) = p(1-p)^{x-1}$$

2.6 The Poisson Distribution

Let the number of changes that occur over a continuous interval be counted. We can then define an **approximate Poisson process** with a parameter $\lambda > 0$ if the following conditions are satisfied.

- The number of changes occurring on nonoverlapping intervals are independent.
- The probability of exactly one change occurring in a sufficiently short interval of length h is about λh .
- The probability of two or more changes occurring in a sufficiently short interval is essentially zero.

We say that the random variable X has a **Poisson distribution** if its probability mass function is of the form

$$f(x) = \frac{\lambda^x e^{-\lambda}}{r!}$$

The mean (μ) and variance (σ^2) of a Poisson distribution are both equal to λ .

3 Continuous Distributions

3.1 Continuous-Type Data

Many experiments do not have integers as outcomes. If the measurements could come from an interval of possible outcomes, this data would be of the **continuous type**. For this type of data, group the data into classes and construct a histogram from these classes.

- 3.2 Exploratory Data Analysis
- 3.3 Random Variables of the Continuous Type
- 3.4 The Uniform and Exponential Distributions
- 3.5 The Gamma and Chi-Squared Distributions
- 3.6 The Normal Distribution