

# MA-224 Review

Jacob Sigman

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# 1 Probability

## 1.1 Basic Concepts

**Statistics** The study of collected data.

**Data** Qualitative or quantitative information that you obtain through experiments.

**Experiment** An unbiased, random, planned activity. Outcomes are simple, events are more complex.

**Frequency** The number of times that something occurs. There are three ways to display frequency: A frequency table, a bar graph, and a relative frequency table.

**Probability** Experimental and theoretical are two types. Theoretical is if an experiment is done many times. It is equivalent to  $\frac{\# \text{ of times event occurs}}{\text{Total}}$ .

**Probability Mass Function** A way of defining the relative frequency with a function.

## 1.2 Properties of Probability

A **set** is a group or collection of well-defined objects. The set of all possible outcomes is called the **sample space** and is denoted by  $\Omega$  or  $S$ .

### Operations of Sets

**Union**  $A \cup B = \{x \mid x \in A \text{ \& } x \in B\}$

**Intersection**  $A \cap B = \{x \mid x \in A \text{ or } x \in B\}$

**Complement**  $\bar{A}$  or  $A^C = \{x \mid x \in A \text{ \& } x \notin A\}$

### Special Sets

**Universal Set** Set of all events, denoted by  $U$ .

**Empty Set** Nothing in this set, denoted by  $\emptyset$ .

**Singleton** A set with one element.

**Mutually Exclusive Sets**  $A \cap B = \emptyset$

**Exhaustive Sets** Mutually exclusive but the union covers  $U$ .

**Equally Likely Events** Events that have the same probability of happening.

## 1.3 Methods of Enumeration

### Multiplication Principle

If one experiment has  $n_1$  outcomes, and another experiment has  $n_2$  outcomes, the composite experiment will have  $n_1 n_2$  outcomes.

### Permutations

Now suppose that that  $n$  positions are to be filled with  $n$  objects. There are  $(n)(n-1) \dots (2)(1)$  or  $n!$  possible arrangements. Each of these arrangements is called a **permutation**. A permutation of  $n$  objects with  $r$  taken at a time is denoted as follows.

$${}_n P_r = \frac{n!}{(n-r)!}$$

## Combinations

The number of ways in which  $r$  objects can be selected without replacement from  $n$  objects is called a **combination**. A combination of  $n$  objects with  $r$  taken at a time is denoted as follows.

$$\binom{n}{r} = {}_nC_r = \frac{n!}{r!(n-r)!}$$

## 1.4 Conditional Probability

The **conditional probability** of an event, or the probability of  $A$  occurring given that  $B$  will occur is denoted as follows.

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

By rearranging the above equation, the probability of both  $A$  and  $B$  occurring can be denoted as follows.

$$P(A \cap B) = P(A|B) * P(B)$$

$$P(A \cap B) = P(B|A) * P(A)$$

## 1.5 Independent Events

If the occurrence of one event will not change the probability of the occurrence of another event, these events are **independent**. Properties of independent events are as follows.

$$P(B|A) = P(B) \quad P(A|B) = P(A)$$

$$P(A \cap B) = P(A) P(B) = P(B) P(A)$$

If an event does not satisfy these properties, the events are called **dependent**. Below are other sets that are independent if  $A$  and  $B$  are independent.

$$A \text{ and } B' \quad A' \text{ and } B \quad A' \text{ and } B'$$

## 1.6 Bayes's Theorem

The probability of an event  $A$  can be calculated as follows.

$$P(A) = \sum_{i=1}^m P(B_i \cap A) = \sum_{i=1}^m P(B_i) P(A|B_i)$$

To determine the probability of a specific outcome  $B_k$ , the equation for conditional probability can be used to obtain **Bayes's Theorem**, which is as follows.

$$P(B_k|A) = \frac{P(B_k)P(A|B_k)}{\sum_{i=1}^m P(B_i)P(A|B_i)} \quad \text{for } k = 1, 2, 3 \dots m$$

# 2 Discrete Distributions

## 2.1 Random Variables of the Discrete Type

Given a random experiment with outcome space  $S$ , a function  $X$  that assigns one real number to each element in  $S$  is called a **random variable**. If  $S$  contains a finite number of points, or the points of  $S$  can be put into a one-to-one correspondence with positive integers,  $X$  becomes a random variable of the **discrete type**. A probability mass function of a discrete random variable satisfies the following properties.

$$f(x) > 0 \quad \sum_{x \in S} f(x) = 1 \quad P(X \in A) = \sum_{x \in A} f(x)$$

There are two ways of representing a probability mass function. One way is with a **bar graph**, in which  $f(x)$  is represented with a vertical line segment. Another way of representing a probability mass function is with a **probability histogram**, where each probability is depicted by a rectangle with base length 1.

## 2.2 Mathematical Expectation

There are many important characteristics of a discrete distribution. One is the **mathematical expectation**. The mathematical expectation of a function of  $X$  is as follows.

$$E[X] = \sum_{x \in S} x f(x)$$

Below are some properties of the expected value of a function,  $E$ .

$$\begin{aligned} E(c) &= c & E[cX] &= cE[X] \\ E[c_1X + c_2X] &= c_1E[X] + c_2E[X] \end{aligned}$$

## 2.3 The Mean, Variance, and Standard Deviation

The **mean** of a random variable  $X$  is as follows.

$$\mu = \sum_{x \in S} x f(x) = E[X]$$

The **variance** of the random variable  $X$ , or of the distribution of  $X$  is as follows.

$$\sigma^2 = \sum_{x \in S} (x - \mu)^2 f(x) = E[(X - \mu)^2] = E[X^2] - \mu^2$$

The **standard deviation** is the square root of the variance.

$$\sigma = \sqrt{\sigma^2}$$

The  $r^{\text{th}}$  **moment** of the distribution about  $b$  is

$$E[(X - b)^r] = \sum_{x \in S} (x - b)^r f(x)$$

The  $r^{\text{th}}$  **factorial moment** is

$$E[(X)_r] = E[X(X - 1)(X - 2) \dots (X - r + 1)]$$

## 2.4 Bernoulli Trials and the Binomial Distribution

A **Bernoulli experiment** is a random experiment, the outcome of which can be classified as a success or a failure. A sequence of **Bernoulli trials** occurs when a Bernoulli experiment is performed several independent times so that the probability of success remains the same from trial to trial. Let the probability of success be  $p$  and the probability of failure be  $q = 1 - p$ .

If there are only outcomes of success and failure, we can say that  $X$  has a **Bernoulli distribution**. The expected value of  $X$  can be written as follows.

$$\mu = E[X] = \sum_{x=0}^1 xp^x(1-p)^{1-x} = p$$

The variance of  $X$  can be written as follows.

$$\sigma^2 = \sum_{x=0}^1 (x - p)^2 p^x (1 - p)^{1-x} = \sqrt{pq}$$

If the trials are independent, and the probabilities of success and failure on each trial are  $p$  and  $q$  respectively,  $X$  has a **binomial distribution**, and the probability mass function of  $X$  is as follows.

$$f(x) = \binom{n}{x} p^x (1-p)^{n-x}$$

## 2.5 The Moment-Generating Function

Let  $X$  be a discrete random variable with probability mass function  $f(x)$  and space  $S$ . If there is a positive number  $h$  such that  $-h \leq t \leq h$ , the **Moment-Generating function** can be defined as follows.

$$E[e^{tX}] = \sum_{x \in S} e^{tx} f(x)$$

The Moment-Generating function can be related to the mean and variance of a distribution.

$$\mu = M'(0) = E[X] \quad \sigma^2 = M''(0) - [M'(0)]^2 = E[X^2] - E[X]^2$$

A **negative binomial distribution** has a probability mass function defined as follows.

$$f(x) = \binom{x-1}{r-1} p^r q^{x-r}$$

If a negative binomial distribution has an  $r$  value of 1, the distribution is said to be a **geometric distribution** which has a probability mass function as follows.

$$f(x) = p(1-p)^{x-1}$$

## 2.6 The Poisson Distribution

Let the number of changes that occur over a continuous interval be counted. We can then define an **approximate Poisson process** with a parameter  $\lambda > 0$  if the following conditions are satisfied.

- The number of changes occurring on nonoverlapping intervals are independent.
- The probability of exactly one change occurring in a sufficiently short interval of length  $h$  is about  $\lambda h$ .
- The probability of two or more changes occurring in a sufficiently short interval is essentially zero.

We say that the random variable  $X$  has a **Poisson distribution** if its probability mass function is of the form

$$f(x) = \frac{\lambda^x e^{-\lambda}}{x!}$$

The mean ( $\mu$ ) and variance ( $\sigma^2$ ) of a Poisson distribution are both equal to  $\lambda$ .

# 3 Continuous Distributions

## 3.1 Continuous-Type Data

Many experiments do not have integers as outcomes. If the measurements could come from an interval of possible outcomes, this data would be of the **continuous type**. For this type of data, group the data into classes and construct a histogram from these classes. The interval with the largest class height is called the **modal class** and the respective class mark is called the **mode**. There's more here but it wasn't really covered that much in class.

### 3.2 Exploratory Data Analysis

This really wasn't covered much either, but some notable things are the idea of **percentiles**. The 50th percentile of a distribution is known as the **median**, the 25th percentile of a distribution is known as the **first quartile**, and the 75th percentile of a distribution is known as the **third quartile**. The distance between the first and third quartile is called the **interquartile range (IQR)**. You can make something called a **box plot** summarizing the minimum, first quartile, median, third quartile, and maximum. This is called a **five-number summary**.

### 3.3 Random Variables of the Continuous Type

The relative frequency histogram  $h(x)$  associated with  $n$  observations of a random variable of the continuous type is a nonnegative function defined so that the total area between its graph and the x-axis equals 1. The probability over an interval given as  $P(a < X < b)$  is given as

$$\int_a^b f(x) dx$$

This means that the probability is the area bounded by the graph of  $f(x)$ , the x-axis, and the lines  $x = a$  and  $x = b$ . The **probability density function** of a random variable  $X$  of the **continuous type** with space  $S$  that is an interval or a union of intervals, is an integrable function of  $f(x)$  satisfying the following conditions.

- $f(x) > 0 \quad x \in S$
- $\int_S f(x) dx = 1$
- $P(a < X < b) = \int_a^b f(x) dx$

The **cumulative distribution function** of a random variable  $X$  of continuous type is as follows.

$$F(x) = P(X \leq x) = \int_{-\infty}^x f(t) dt \quad -\infty < x < \infty$$

The mean, variance, and the moment-generating function of a continuous variable with a probability density function  $f(x)$ .

$$\begin{aligned}\mu &= E[X] = \int_{-\infty}^{\infty} x f(x) dx \\ \sigma^2 &= E[(X - \mu)^2] = \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx \\ M(t) &= \int_{-\infty}^{\infty} e^{tx} f(x) dx\end{aligned}$$

### 3.4 The Uniform and Exponential Distributions

The random variable  $X$  has a **uniform distribution** if its probability density function is equal to a constant on its support. If the support is on the interval  $[a, b]$ , then

$$f(x) = \frac{1}{b-a} \quad a \leq x \leq b$$

The mean, variance and moment-generating function of  $X$  are as follows.

$$\mu = \frac{a+b}{2} \quad \sigma^2 = \frac{(b-a)^2}{12} \quad M(t) = \begin{cases} \frac{e^{tb} - e^{ta}}{t(b-a)} & t \neq 0 \\ 1 & t = 0 \end{cases}$$

Sometimes in the Poisson process, we let  $\lambda = \frac{1}{\theta}$  and we say that random variable  $X$  has an **exponential distribution** if its probability density function is defined by

$$f(x) = \frac{1}{\theta} e^{-\frac{x}{\theta}}$$

The moment-generating function, mean, and variance of  $X$  are as follows.

$$M(t) = \int_0^{\infty} e^{tx} \left( \frac{1}{\theta} \right) e^{-\frac{x}{\theta}} dx$$

$$\mu = M'(0) = \theta \quad \sigma^2 = M''(0) - [M'(0)]^2 = \theta^2$$

### 3.5 The Gamma and Chi-Squared Distributions

Chi-Squared distributions were not covered in class, so I'm only doing gamma. The **gamma function** is defined by

$$\Gamma(t) = \int_0^{\infty} y^{t-1} e^{-y} dy$$

The random variable  $X$  has a **gamma distribution** if its probability density function is defined by

$$f(x) = \frac{1}{\Gamma(\alpha)\theta^\alpha} x^{\alpha-1} e^{-\frac{x}{\theta}}$$

The moment-generating function, mean, and variance are

$$M(t) = \frac{1}{(1 - \theta t)^\alpha} \quad \mu = \alpha\theta \quad \sigma^2 = \alpha\theta^2 = \frac{1}{1 - \theta t}$$

### 3.6 The Normal Distribution

The random variable  $X$  has a **normal distribution** if its probability density function is

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp \left[ -\frac{(x - \mu)^2}{2\sigma^2} \right]$$

The moment-generating function, mean, and variance are as follows.

$$M(t) = \exp \left[ \mu t + \frac{\sigma^2 t^2}{2} \right]$$

$$\mu = E[X] = \mu$$

$$\sigma^2 = M''(0) - [M'(0)]^2 = \sigma^2$$