

## 1 Introduction

Denote by  $\text{PGr}(k, n; q)$  the Grassmannian of projective  $k$ -planes in  $\mathbb{P}_{\mathbb{F}_q}^n$  (that is,  $\text{PGr}(k, n; q) = \text{Gr}(k+1, n+1; q)$ , the Grassmannian of  $k+1$ -dimensional vector subspaces of  $\mathbb{F}_q^n$ ).

Then

$$\#\text{PGr}(k, n; q) = \binom{n+1}{k+1}_q := \frac{(1-q^{n+1}) \cdots (1-q^{(n+1)-(k+1)+1})}{(1-q^{k+1}) \cdots (1-q)}.$$

Let  $\mathcal{A} = \text{PGr}(k, n; q)$  and  $\mathcal{B} = \text{PGr}(h, n; q)$ , with  $k < h$ . We take  $R$  to be the incidence relation  $R = \{(\ell, m) \in \mathcal{A} \times \mathcal{B} : \ell \subseteq m\}$ . Since each  $k$ -subspace is contained in  $\binom{n-k}{h-k}_q$  subspaces of dimension  $h$  and each  $h$ -space contains  $\binom{h+1}{k+1}_q$  subspaces of dimension  $k$ , we obtain a

$$\left( \left[ \binom{n+1}{k+1}_q \right]_{\binom{n-k}{h-k}_q}, \left[ \binom{n+1}{h+1}_q \right]_{\binom{h+1}{k+1}_q} \right) \text{-configuration.}$$

This is a *projective geometry configuration* and will be denoted  $\text{PG}(n, k, h; q)$ . Note that this is a complete configuration of Grassmannians;  $\mathcal{A}$  is all of  $\text{PGr}(k, n; q)$  and  $\mathcal{B}$  is all of  $\text{PGr}(h, n; q)$ .

We will define a *projective design* as a  $\text{PG}(n, 0, h; q)$ .

In general, a **design** is a  $(v_k, b_r)$ -configuration where, for any distinct  $x, y \in \mathcal{A}$ ,

$$\#(R(x) \cap R(y)) = \lambda \neq 0 \text{ is constant.}$$

We will call  $\lambda$  the **type** of the design. A symmetric  $v_k$ -design of type  $\lambda$  has the additional property that, for any  $x, y \in \mathcal{B}$ ,

$$\#(R(x) \cap R(y)) = \lambda.$$

The type of  $\text{PG}(n, 0, h; q)$  is  $\binom{n-1}{h-1}_q$ .

## 2 Examples

A **linear**  $(v_k, b_r)$ -configuration over an infinite field  $K$  is a configuration in which the set  $\mathcal{A}$  (resp.  $\mathcal{B}$ ) is realized by a set of linear subspaces of dimension  $d_1$  (resp.  $d_2$ ) of the projective  $\mathbb{P}_K^n$ , and the relation  $R$  is an incidence relation  $x \in R(y)$  if  $x$  intersects  $y$  along a subspace of fixed dimension  $s$ . The data  $(\mathbb{P}_K^n, s; d_1, d_2)$  is the type of a linear realization.

For example, any finite linear configuration  $\text{PG}(n, k, h; q)$  is a linear configuration over  $\overline{\mathbb{F}}_q$  of  $(\mathbb{P}_{\overline{\mathbb{F}}_q}^n, k; k, h)$ .

One can perform the following operations upon a linear

## 2.1 Elliptic Embedding

**Proposition 1.** Let  $(E, x_0)$  be an elliptic curve with determined zero point  $x_0$ . Then for  $n \in \mathbb{Z}$ , the linear system  $|nx_0|$  induces an embedding  $\Phi_n : E \hookrightarrow \mathbb{P}^{n-1}$  in such a way that the image of every point in  $(E, x_0)[n]$  is hyperosculating on  $\Phi_n(E)$ .

First let us observe the proposition for the specific curve  $(E, x_0) = (V(x^3+y^3+z^3), (-1, 1, 0))$  for  $n = 3$ .

Then  $\mathcal{L}(3x_0) = \langle 1, \tau_1/\tau_0, \tau_2/\tau_0 \rangle$ , where  $\tau_0 = x + y$  is the flex tangent line through  $x_0$ ,  $\tau_1 = x + z$  is the flex tangent line through  $(-1, 0, 1)$ , and  $\tau_2 = tx + z$  is the flex tangent line through  $(-1, 0, t)$ . So  $|3x_0|$  defines the embedding  $\Phi_3 : E \rightarrow \mathbb{P}^2$  given by

$$\Phi_3(x, y, z) = (1, (x+z)/(x+y), (tx+z)/(x+y)) = (x+y, x+z, tx+z).$$

This is just a linear change of coordinates in  $\text{PGL}(2)$ , so flex points must map to flex points, which are hyperosculating.

In particular,  $x_0$  maps to  $(0, 1, t)$ ; and  $x_0$  must be the only point of  $E$  that maps into the line  $w_0 = 0$  (using  $w_0, w_1, w_2$ -variables for the codomain  $\mathbb{P}^2$ ) because  $x_0$  is the only point of  $E$  on  $x + y = 0$ , so  $w_0 = 0$  is hyperosculating. By the same reasoning,  $w_1 = 0$  is the hyperosculating line of  $\Phi_3(-1, 0, 1)$ , and  $w_2 = 0$  is the hyperosculating line of  $\Phi_3(-1, 0, t)$ .

Now let us go up to the  $n = 4$  case. Let

$$\mathcal{L}(4x_0) = \langle 1, r_1/\tau_0, \tau_1/\tau_0, r_1^2/\tau_0^2 \rangle,$$

where  $r_1$  is the line connecting the flex point  $(-1, 0, 1)$  to  $x_0 = (-1, 1, 0)$ , so  $r_1 = x + y + z$ . Then  $|4x_0|$  defines an embedding  $\Phi_4 : E \rightarrow \mathbb{P}^3$  given by

$$\Phi_4(x, y, z) = ((x+y)^2, (x+y+z)(x+y), (x+y)(x+z), (x+y+z)^2).$$

We can see a Desmos graph of this embedding here.

Then note that  $x_0$  seems to map to  $(0, 0, 0, 0)$  under this map. In reality,  $x_0 \mapsto (0^6, 0 * 0^3, 0 * 0^3, 0^2)$ , so removing two orders of 0 gives us  $\Phi_4(x_0) = (0, 0, 0, 1)$ .

We can also see this by taking the limit

$$\lim_{\varepsilon \rightarrow 0} \Phi_4(-1, 1, \varepsilon) = \lim_{\varepsilon \rightarrow 0} (0, 0, 0, \varepsilon^2) = \lim_{\varepsilon \rightarrow 0} (0, 0, 0, 1) = (0, 0, 0, 1).$$

The hyperosculating plane to this point of  $\Phi_4(E)$  is  $w_0 = 0$ , since  $x_0$  is the only point of  $E$  on  $\tau_0^2 = 0$ .

Now let  $q$  be any 4-torsion point of  $(E, x_0)$ : that is,  $q \in (E, x_0)[4]$ . Then there is a rational function  $Q$  such that

$$\text{div}(Q) = 4q - 4x_0,$$

which means  $Q \in \mathcal{L}(4x_0)$ . Thus there are coefficients  $A, B, C, D \in K$  where

$$Q = A + B(r_1/\tau_0) + C(\tau_1/\tau_0) + D(r_1/\tau_0)^2,$$

or

$$Q\tau_0^2 = A\tau_0^2 + Br_1\tau_0 + C\tau_1\tau_0 + Dr_1^2.$$

Then  $Q\tau_0^2$  is a degree-2 function where

$$\text{div}(Q\tau_0) = 4q + 2x_0,$$

so  $\text{ord}_q(Q\tau_0) = 4$ . Thus the plane

$$V(Aw_0 + Bw_1 + Cw_2 + Dw_3) \subseteq \mathbb{P}_K^3$$

contains  $\Phi_4(q)$ , and meets  $\Phi_4(E)$  **only** at  $\Phi_4(E)$  (remember we had to account for two orders of 0's for  $x_0$ ).

In general, if  $x_0$  is not flex, we can take  $\mathcal{L}(3x_0) = \langle 1, f_1/f_2, g_1/g_2 \rangle$  where  $\text{ord}_{x_0}(f_1/f_2) = -2$  and  $\text{ord}_{x_0}(g_1/g_2) = -3$ . Then whatever...

## 2.2 Modular Configurations

Let  $p > 2$  be prime, and consider the group  $G = (\mathbb{Z}/p\mathbb{Z})^2$ . We take  $\mathcal{A}$  to be the set of cosets for each subgroup of order  $p$  of  $G$ . We take  $\mathcal{B}$  to be  $G$  itself.

Note that  $\mathcal{A}$  is equivalent to lines through the affine space  $\mathbb{A}_{\mathbb{F}_p}^2$ : this is because each subgroup of order  $p$  is a line through the origin of  $\mathbb{A}_p^2$ , and then each coset shifts the line of the same slope.

Thus

$$\#\mathcal{A} = \frac{p^2(p^2 - 1)}{p(p - 1)} = p(p + 1).$$

Each line contains  $p$  points, and each line is on  $p + 1$  points, so we get a

$$(p(p + 1)_p, p_{p+1}^2)\text{-configuration.}$$

We can define an action of  $G$  on  $\mathbb{P}_K^{p-1}$  the following way (assuming  $K$  has  $p$  distinct  $p^{\text{th}}$  roots of unity). We can define

$$(1, 0) \cdot (x_0, \dots, x_{p-1}) = (x_{p-1}, x_0, \dots, x_{p-2}),$$

and

$$(0, 1) \cdot (x_0, \dots, x_{p-1}) = (x_0, \zeta x_1, \zeta^2 x_2, \dots, \zeta^{p-1} x_{p-1}).$$

Then  $G \hookrightarrow \text{PGL}(p, K)$  and one can check using spectral theory that there are  $p$  fixed hyperplanes for each vector of  $\{(1, 0)\} \cup \{(n, 1) : n \in \mathbb{Z}/p\mathbb{Z}\}$ , and thus for each subgroup of order  $p$  of  $G$ .

Specifically,  $(1, 0)$  fixes all hyperplanes of the form

$$\begin{aligned} x_0 + x_1 + x_2 + \cdots + x_{p-1} &= 0, \\ x_0 + \zeta x_1 + \zeta^2 x_2 + \cdots + \zeta^{p-1} x_{p-1} &= 0, \\ x_0 + \zeta^2 x_1 + \zeta^4 x_2 + \cdots + \zeta^{p-2} x_{p-1} &= 0, \\ &\vdots \\ x_0 + \zeta^{p-1} x_1 + \zeta^{p-2} x_2 + \cdots + \zeta x_{p-1} &= 0. \end{aligned}$$

The action of  $(0, 1)$  fixes hyperplanes of the form

$$x_i = 0, \text{ for } 0 \leq i \leq p - 1.$$

Note, that the fixed planes are each **set-wise** fixed, not **point-wise** fixed.

Finally,

$$\begin{aligned} (1, n) \cdot (x_0, \dots, x_{p-1}) &= (1, 0) \cdot (x_0, \zeta^n x_1, \zeta^{2n} x_2, \dots, \zeta^{(p-1)n} x_{p-1}) \\ &= (\zeta^{(p-1)n} x_{p-1}, x_0, \zeta^n x_1, \dots, \zeta^{(p-2)n} x_{p-2}). \end{aligned}$$

Note: this is equivalent to

$$\begin{aligned} (0, n) \cdot (x_{p-1}, x_0, \dots, x_{p-2}) &= (x_{p-1}, \zeta^n x_0, \zeta^{2n} x_1, \dots, \zeta^{(p-1)n} x_{p-2}) \\ &= \zeta^{(p-1)n} * (x_{p-1}, \zeta^n x_0, \zeta^{2n} x_1, \dots, \zeta^{(p-1)n} x_{p-2}) = (\zeta^{(p-1)n} x_{p-1}, x_0, \zeta^n x_1, \dots, \zeta^{(p-2)n} x_{p-2}), \end{aligned}$$

using scalar invariance of projective points, verifying the group action is truly well-defined under composition.

This action has fixed planes

$$\begin{aligned} \zeta^n x_0 + x_1 + x_2 + \cdots + x_{p-2} + x_{p-1} &= 0, \\ x_0 + \zeta^n x_1 + x_2 + \cdots + x_{p-2} + x_{p-1} &= 0, \\ &\vdots \\ x_0 + x_1 + x_2 + \cdots + x_{p-2} + \zeta^n x_{p-1} &= 0. \end{aligned}$$

Thus there is a correspondence between each point of  $\mathbb{P}_{\mathbb{F}_p}^1$  and a set of  $p$  invariant planes of  $\mathbb{P}_K^{p-1}$ . Thus we can take  $\mathcal{A}$  to be the total set of  $p(p+1)$  invariant planes.

Now consider the transformation

$$\iota : \mathbb{P}^{p-1} \rightarrow \mathbb{P}^{p-1}$$

where  $\iota = (1) \oplus J_{p-1}$ , where  $J_{p-1}$  is the  $(p-1) \times (p-1)$  exchange matrix. Viewing  $\iota$  as a  $p \times p$  matrix, we can see that

$$\mathcal{E}_1(\iota) = \langle e_0, e_i + e_{p-i+1} : 1 \leq i \leq (p-1)/2 \rangle,$$

(assuming  $p$  is an odd prime) and

$$\mathcal{E}_{-1}(\iota) = \langle e_i - e_{p-i+1} : 1 \leq i \leq (p-1)/2 \rangle,$$

so as vector spaces,  $\dim \mathcal{E}_1 = (p+1)/2$  and  $\dim \mathcal{E}_{-1} = (p-1)/2$ . After projectivizing, this gives us  $F^+$ , a  $(p-1)/2$ -dimensional hyperplane, and  $F^-$ , a  $(p-3)/2$ -dimensional hyperplane.

The transforms of  $F^-$  under the group  $G$  defines a set  $\mathcal{B}$  of  $p^2$  hyperplanes of dimension  $(p-3)/2$ . Each of the hyperplanes of  $\mathcal{B}$  is in  $p+1$  of the hyperplanes of  $\mathcal{A}$ , and each hyperplane in  $\mathcal{A}$  contains exactly  $p$  of the hyperplanes of  $\mathcal{B}$ . This gives us a geometric realization of a  $(p(p+1)_p, p_{p+1}^2)$ -configuration.

## 2.3 Return to the Elliptic Embedding

Recall the linear system  $|px_0|$  defines an embedding of the elliptic curve into  $\mathbb{P}^{p-1}$ . Then  $x_0$  is in the hyperplane  $F^-$ , so the image of each  $G$ -translate of  $x_0$  is mapped to  $F^-$ . Each hyperosculating point belongs to a unique hyperplane  $g(F^-)$ . A hyperplane from  $\mathcal{A}$  cuts out  $E$  in  $p$  hyperosculating points. When  $p = 3$ , we get the **Hesse configuration** (or Wendepunkts-configuration).

## 2.4 Ceva Configuration

Let  $n \in \mathbb{N}$  and  $\mu_n$  be the group of  $n^{\text{th}}$  roots of unity of a field  $K$  of prime characteristic. Then we may define the  $n^3$  points in  $\mathbb{P}_K^2$  as follows:

$$P_{0,\zeta} = (0, 1, \zeta), P_{1,\zeta} = (\zeta, 0, 1), P_{2,\zeta} = (1, \zeta, 0),$$

where  $\zeta \in \mu_n$ . Let

$$\begin{aligned} \mathbf{L}_{0,\zeta} &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & \zeta \end{pmatrix}, \\ \mathbf{L}_{1,\zeta} &= \begin{pmatrix} 0 & 1 & 0 \\ \zeta & 0 & 1 \end{pmatrix}, \\ \mathbf{L}_{2,\zeta} &= \begin{pmatrix} 0 & 0 & 1 \\ 1 & \zeta & 0 \end{pmatrix}. \end{aligned}$$

Then the lines  $L_{0,\alpha}, L_{1,\beta}, L_{2,\gamma}$  meet at one point  $p_{\alpha,\beta,\gamma}$  if and only if  $\alpha\beta\gamma = -1$ . Thus we obtain  $n^2$  points which together with the  $3n$  lines  $L_{i,\zeta}$  form an  $(n_3^2, 3n_n)$ -configuration. This is called the **Ceva configuration** and will be denoted  $\text{Ceva}(n)$ .

Observation: I think the nine points in each fundamental plane of the Penrose configuration form a  $(9_3, 9_3)$  Ceva configuration.

For  $n \neq 3$ , the symmetry group of  $\text{Ceva}(n)$  is  $\mu_n^2 \rtimes S_3$ ; it is generated by permutations of  $\mathbb{P}^2$ -coordinates and homotheties  $(x_0, x_1, x_2) \mapsto (\alpha x_0, \beta x_1, \gamma x_2)$ .

When  $n = 3$ , the symmetry group is larger; for example, over  $\mathbb{P}^2(\mathbb{F}_4)$ , when we get an additional symmetry realized by the Frobenius automorphism, and a duality automorphism, so we get the Hesse group of order 216.

Blowing up the set of points  $p_{\alpha,\beta,\gamma}$ , we get a rational surface  $V$  together with a morphism  $\pi : V \rightarrow \mathbb{P}^1$  whose general fibre is a nonsingular curve of genus  $g = (n-1)(n-2)/2$ . There are 3 singular fibres; each is the union of  $n$  smooth rational curves with self-intersection  $1-n$  intersecting at one point. The morphism admits  $n^2$  disjoint sections; each is a smooth rational curve with self-intersection  $-1$ . The Ceva configuration is realized by the set of sections and the set of irreducible components of singular fibres. If  $n \neq 3$ , the symmetry group of the configuration is realized by an automorphism group of the surface. There is a realization of  $\text{Ceva}(3)$  which realizes a subgroup of index 2 of  $\text{Sym}(\text{Ceva}(3))$ .

## 2.5 The Hesse-Salmon Configuration

The Hesse-Salmon Configuration is the general projection of the Reye  $(12_4, 16_3)$ -configuration into the plane: we get 12 points on a cubic curve  $E$  that are formed by taking a line  $L$  through  $E$  meeting at  $L \cdot E = A + B + C$ , and taking  $E[2] = \langle \gamma_1, \gamma_2 \rangle$  and forming  $\{A, B, C\} + E[2]$ .

## 2.6 Double-six

This is a  $(6_5)$ -configuration realized by a double-six of lines on a nonsingular cubic surface. The full symmetry group is the double extension of  $S_6$ . It is generated by permutation of lines in one family and a switch. In the full group of symmetries of 27 lines on a cubic surface this is the subgroup of  $W(E_6)$  of index 36 which fixes a subset  $\{\alpha, -\alpha\}$ , where  $\alpha$  is a positive root. (So  $\#W(E_6) = 51840$ . Wow!) One can realize the full symmetry group over a field of characteristic 2 by considering the Fermat cubic surface  $x^3 + y^3 + z^3 + w^3 = 0$ . Its automorphism group is isomorphic to the Weyl group  $W(E_6)$ .