

# Theoretical Computer Science III Term 2 Summative

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## 1 Advanced Algorithms

### Question 1

Let us partition  $\mathcal{U}$  into the sets  $\mathcal{U}_i = \{x : x \in \mathcal{U} \wedge h(x) = i\}$ . It can be seen that the union of these subsets is the original set  $\mathcal{U}$ . Let us assume that all of the subsets have size less than  $m$ . This means that  $|\bigcup_{i=0}^{n-1} \mathcal{U}_i| = \sum_{i=0}^{n-1} |\mathcal{U}_i| < \sum_{i=0}^{n-1} m = nm = |\mathcal{U}|$ . Therefore,  $|\mathcal{U}| > |\bigcup_{i=0}^{n-1} \mathcal{U}_i| \Rightarrow |\bigcup_{i=0}^{n-1} \mathcal{U}_i| \neq \mathcal{U}$ , which is a contradiction to the initial statement. Let  $j$  be such that some subset  $|\mathcal{U}_j| \geq m$ . If we have equality then the proof is complete, otherwise if the subset is of size greater than  $m$ , then the subset can be partitioned into two parts, one of the requisite size  $m$ , and the remainder of the subset. This gives the subset of size  $m$ , as required.

If you have to hash  $v$  values, and  $k$  keys, and for the first value of  $m$  for which  $v \geq m \cdot k$ , then there is a subset of size  $m$  values which hash to the same key. As such in hashing with chaining, the worst case time complexity to find a value is  $\Omega(m)$ .

### Question 2

(a)

There are  $n = 1000$  different buckets that values could be hashed into. The probability that  $k$  values are hashed to different buckets is given by the following formula  $\frac{n!}{(n-k)! \cdot n^k} = \frac{k! \cdot \binom{n}{k}}{n^k}$ . As such the probability that two values hash to the same key, denoted  $S$ , is  $P(S) = 1 - \frac{k! \cdot \binom{n}{k}}{n^k}$ .  $k$  is equal to the number of insertions. Let  $k = 57$ ,  $P(S) = 1 - \frac{57! \cdot \binom{1000}{57}}{1000^{57}} = 0.8034....$  For  $k = 56$ ,  $P(S) = 0.7918....$  Therefore, the answer is  $k = 57$ .

(b)

We are given that in the first  $k - 1$  insertions there have been no collisions and that on the  $k$ -th insertion the probability of collision must be strictly less than 20%. The first fact means that  $k - 1$  buckets are used in the hash table  $\Rightarrow$  the probability of collision in the  $k$ -th insertion should be less than  $\frac{k-1}{1000}$ .

From the second fact provided, we know that  $\frac{k-1}{1000} < 0.2 \Rightarrow k - 1 < 200 \Rightarrow k < 201$ . As such, the value of  $k$  when the size of the hash table should be increased and thus the first

time that the collision probability is greater than or equal to 20%, meaning that the size of the hash table needs to be increased, is on the **200th insertion**.

### Question 3

We are aiming to prove that the expected running time of an entire sequence of  $m$  operations, on a hash table of size  $n$ , is upper bounded by  $m \cdot (1 + \frac{m}{2n})$ . Let us define  $L_i$  as the expected length of a chain in a bucket after  $i$  operations. The worst case number of collisions for the  $k$ -th operation, for element  $x$  is where  $x$  is at the end of the chain for bucket  $h(x)$ , irrespective of the type of operation. This means that,  $K_k = L_{k-1}$  because  $k$ -th operation does not change the expected bucket size for itself. We are told that  $H$  is a 2-universal set of hash functions, as such:

$$L_k \leq \sum_{i=1}^k \frac{1}{n} = \frac{k}{n}$$

Using the above facts we can prove the upper bound on the expected time for  $m$  operations:

$$\sum_{i=1}^m E_i = \sum_{i=1}^m 1 + K_i = m + \sum_{i=1}^m K_i = m + \sum_{i=1}^m L_{i-1} \leq m + \sum_{i=1}^m \frac{i-1}{n} = m + \frac{m(m-1)}{2n} = m \cdot (1 + \frac{m-1}{2n}) \leq m \cdot (1 + \frac{m}{2n})$$

## 2 Information Theory

### Question 4

The capacity of a channel is defined as follows:  $C = \max_{p(x)} I(X;Y)$ .  $I(X;Y) = H(Y) - H(Y|X)$ . This gives us  $I(X;Y) = H(Y)$  because of the fact that the channel is deterministic; if  $Y = f(X)$ , then  $H(Y|X) = 0$ .  $\therefore C = \max_{p(x)} H(Y) = \max_{p(x)} H(f(X))$ .  $p(x)$  is the probability distribution of, which maximises entropy when the distribution is uniform.  $\therefore C = \log|f(X)|$  when  $p(x)$  is a uniform distribution  $\square$ .

### Question 5

#### Property 2

**Line 1:** The sum of probabilities of all input sequences  $x^n \in \mathcal{X}^n$  is equal to 1.

**Line 2:** The typical set  $A_\epsilon^{(n)}$  is a subset of  $\mathcal{X}^n$  with particular properties. Therefore, it is obvious that the number of sequences in the typical set is not greater than the number of sequences in  $\mathcal{X}^n$ . Thus, the sum of the probabilities for this subset is  $\leq 1$ .

**Line 3:** One of the properties of typical set is that  $H(X) - \epsilon \leq -\frac{1}{n} \log p(x^n) \leq H(X) + \epsilon$ . Will focus on the RHS of this inequality;  $-\frac{1}{n} \log p(x^n) \leq H(X) + \epsilon$ . Rearranging this we get  $p(x^n) \geq 2^{-n(H(X)+\epsilon)}$ .  $\therefore$  we get the inequality shown.

**Line 4:** The value  $2^{-n(H(X)+\epsilon)}$  is constant so we can pull it out of the sum  $\sum_{x^n \in A_\epsilon^{(n)}} 2^{-n(H(X)+\epsilon)} = 2^{-n(H(X)+\epsilon)} \sum_{x^n \in A_\epsilon^{(n)}} 1 = 2^{-n(H(X)+\epsilon)} |A_\epsilon^{(n)}|$ . To complete the proof simply multiply both sides of the inequality by  $2^{n(H(X)+\epsilon)}$ . This leaves  $|A_\epsilon^{(n)}| \leq 2^{n(H(X)+\epsilon)}$ , as required.

### Property 3

**Line 1:** The first line makes use of Property 1 of the AEP theorem for typical sequences. It states that, for  $n$  large enough, the probability of typical set is nearly 1. Should be noted that  $Pr\{A_\epsilon^{(n)}\} = \sum_{x^n \in A_\epsilon^{(n)}} p(x^n)$ .

**Line 2:** One of the properties of typical set is that  $H(X) - \epsilon \leq -\frac{1}{n} \log p(x^n) \leq H(X) + \epsilon$ . Will now focus on the LHS of this inequality;  $-\frac{1}{n} \log p(x^n) \geq H(X) - \epsilon$ . Rearranging this we get  $p(x^n) \leq 2^{-n(H(X)-\epsilon)}$ .  $\therefore$  we get the inequality shown.

**Line 3:** The value  $2^{-n(H(X)-\epsilon)}$  is constant so we can pull it out of the sum  $\sum_{x^n \in A_\epsilon^{(n)}} 2^{-n(H(X)-\epsilon)} = 2^{-n(H(X)-\epsilon)} \sum_{x^n \in A_\epsilon^{(n)}} 1 = 2^{-n(H(X)-\epsilon)} |A_\epsilon^{(n)}|$ . To complete the proof simply multiply both sides of the inequality by  $2^{n(H(X)-\epsilon)}$ . This leaves  $|A_\epsilon^{(n)}| \geq (1 - \epsilon)2^{n(H(X)+\epsilon)}$ , as required.

### Question 6

(a)

Let  $Z = S \cap T, S = Z \cup S', T = Z \cup T'$ . Given the definitions,  $S', T'$ , and  $Z$  are disjoint.

$$\begin{aligned} H(X_{S \cup T}) + H(X_{S \cap T}) &= H(X_Z, X_{S'}, X_{T'}) + H(X_Z) \\ &= 2H(X_Z) + H(X_{S'}, X_{T'} | X_Z) \\ &= 2H(X_Z) + H(X_{S'} | X_Z) + H(X_{T'} | X_Z) - I(X_{S'}, X_{T'} | X_Z) \\ &\leq H(X_Z) + H(X_{S'} | X_Z) + H(X_Z) + H(X_{T'} | X_Z) \\ &= H(X_Z, X_{S'}) + H(X_Z, X_{T'}) \\ &= H(X_S) + H(X_T) \quad \square \end{aligned}$$

(b)

$$\begin{aligned}
\sum_{i=1}^m H(X_{[m]/\{i\}}) &= H(X_2, \dots, X_m) + H(X_1, X_3, \dots, X_m) + \dots + H(X_1, \dots, X_{m-1}) \\
&= \sum_{i=1}^m H(X_i | X_{i-1}, \dots, X_2) - H(X_1) + \sum_{i=1}^m H(X_i | X_{i-1}, \dots, X_3, X_1) \\
&\quad - H(X_2 | X_1) + \dots + \sum_{i=1}^m H(X_i | X_{i-1}, \dots, X_1) - H(X_m | X_{m-1}, \dots, X_1)
\end{aligned}$$

**Conditioning reduces entropy** which means that adding the respective missing discrete random variable to RHS of each conditional entropy reduces the overall entropy.

$$\begin{aligned}
\therefore \sum_{i=1}^m H(X_{[m]/\{i\}}) &\geq m \sum_{i=1}^m H(X_i | X_{i-1}, \dots, X_1) - H(X_1) - H(X_2 | X_1) - \dots - H(X_m | X_{m-1}, \dots, X_1) \\
&= m \sum_{i=1}^m H(X_i | X_{i-1}, \dots, X_1) - \sum_{i=1}^m H(X_i | X_{i-1}, \dots, X_1) \\
&= (m-1) \sum_{i=1}^m H(X_i | X_{i-1}, \dots, X_1) \\
&= (m-1) H(X_1, \dots, X_m) = (m-1) H(X_{[m]}).
\end{aligned}$$

Thus,  $\sum_{i=1}^m H(X_{[m]/\{i\}}) \leq (m-1) H(X_{[m]}) \square$ .