Federated Learning

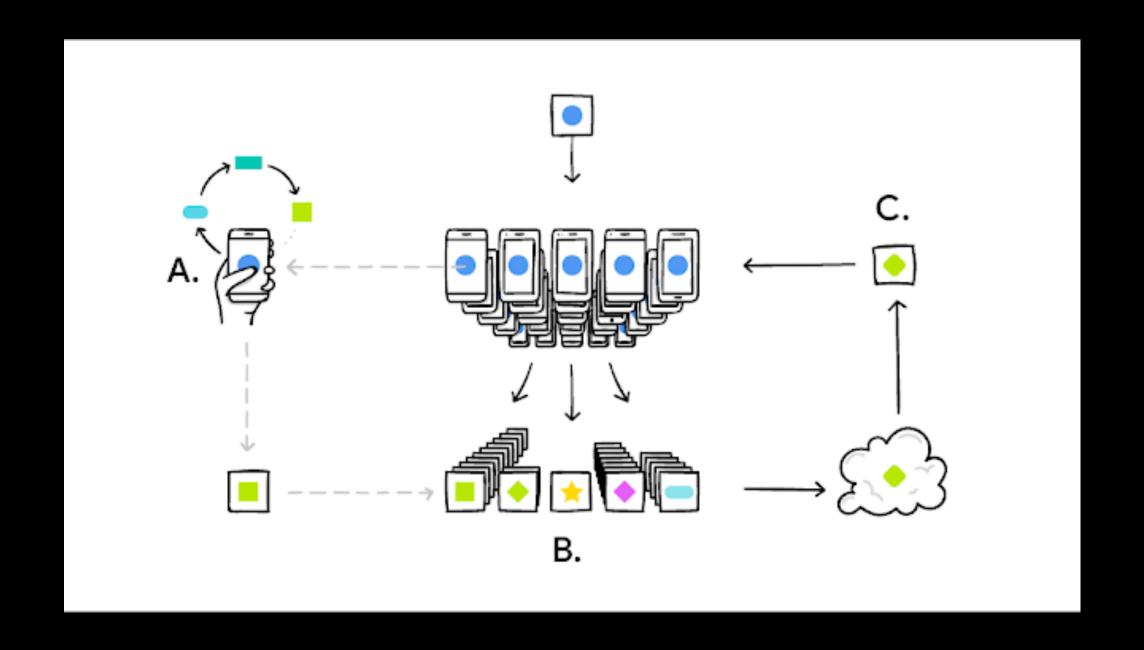
ECE 273 - Convex Optimization, Spring 2021

MotivationWhy Federated Learning?

- Privacy is an increasingly prominent concern in training machine learning models, and sometimes is legally required (HIPPA)
- Transmission of information over certain channels is expensive
- Utilize local computational resources

Federated Learning Overview

- Similar to a Distributed system, but more general
- Common assumptions in ML do not necessarily hold:
 - Data may not be IID
 - Compute nodes may be highly heterogeneous



https://ai.googleblog.com/2017/04/federated-learning-collaborative.html

Federated Learning An example: autocomplete

- Autocomplete on mobile phones
 - Text collected in private messages, internet browsing, etc.
 - Information collected across the US
- Clearly, the standard statistical and computational assumptions do not hold.
- Many more use cases exist, Ex. Medical data



Federated Learning The prototypical algorithm

- Dataset located on remote workers, not visible to master
- Worker weights can be used to tune less and more important workers
- The average of each worker's minibatch gradient is used for global update

Algorithm 1: Federated SGD Initialize weight: $w = w_0$; Worker weights: $p_1, ..., p_k$; Worker data: $\mathcal{D}_1, ..., \mathcal{D}_k$; Learning rate α ; while not converged do | Master broadcast w_t to all workers; foreach worker i = 1, ..., k do | $w_{t+1}^i := w_t - \alpha \nabla \mathcal{L}(w_t; \mathcal{D}_i)$; | Worker broadcast w_t^i master; end | Master calculate new weight $w_{k+1} := \sum_{i=1}^k p_i w_{t+1}^i$; end

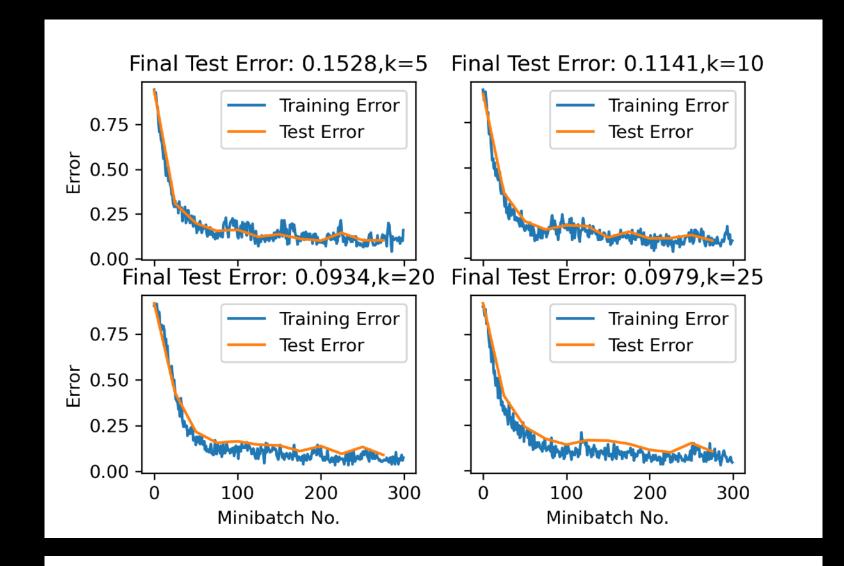
Problem Setup

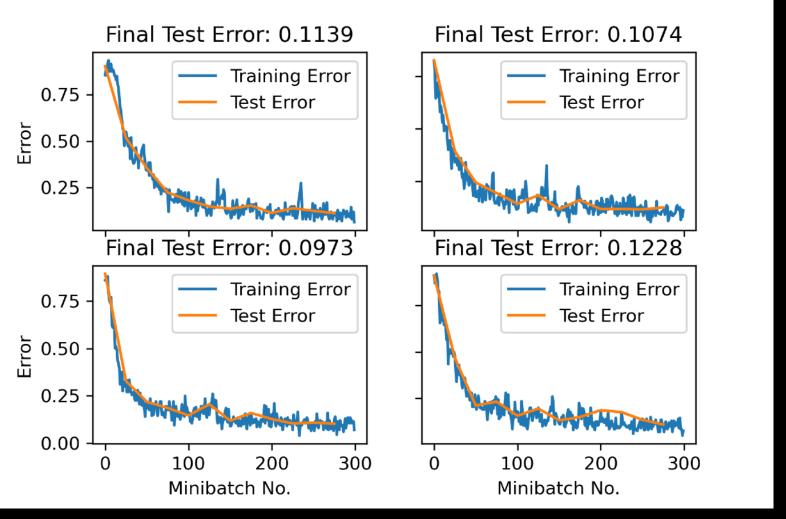
A simple problem

- Train a simple Convolutional Neural Network on the MNIST dataset
- The simple setup makes running multiple experiments much more feasible

Comparing Centralized to Federated SGD Federated at top, Centralized at bottom, k=Num Workers

- At first, they appear the same
 - However, once we realize the central node and worker nodes each have equal minibatch size, we realize this is not the case
- The Federated setup with k workers requires k times as much computation





Learning with malicious users Corrupt Data

- Let's imagine a scenario where some workers nodes send malicious or otherwise bad updates to the master
- Examples
 - Text completion (some users often use foul language)
 - Malicious intent

Learning with malicious users Corrupt Data

- Experimental setup:
 - Same learning problem as before (MNIST classification)
 - Now, some percentage of users say α send corrupted update
 - To mimic this, these users will train on datas with label 9-y, where y is the true label (an integer on [0,...,9]
 - To mitigate this, we will try to take taking the coordinate wise median, as well as the trimmed mean and see if performance improves.

Learning with malicious users Corrupt Data

- Sometimes the raw uncorrected model achieves the best error rate, though this is by an extremely thin margin when it does happen
- Overall the median is the best performer
- While the improvements are modest, using median is simple and sensible

Num Workers:	10	20	25
α			
.05	X	.1272	.1081
.1	.1327	.1467	.1212
.2	.1845	.1584	.1906

Table 1: Test Error results with malicious users, using the regular mean update rule

Num Workers:	10	20	25
α			
.05	X	.1447	.1486
.1	.0996	.1162	.1754
.2	.1563	.1609	.1353

Table 2: Test Error results with malicious users, using coordinate-wise trimmed mean, $\alpha = \beta$

Num Workers:	10	20	25
α			
.05	X	.0957	.1091
.1	.1215	.2027	.0998

Table 3: Test Error results with malicious users, using coordinate-wise median

Learning with malicious users Snooping

- Actual training data can be inferred from model parameter updates
- This can be achieved with knowledge only of the model state, and gradient update at a single step
- Only caveat is that batch size needs to be 1

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Input: F(\mathbf{x}; W): Differentiable machine learning model; W: parameter weights; \nabla W: gradients calculated by training data \mathbf{x}, \mathbf{y}

1: procedure \mathrm{DLG}(F, W, \nabla W)

2: \mathbf{x}'_1 \leftarrow \mathcal{N}(0,1), \mathbf{y}'_1 \leftarrow \mathcal{N}(0,1) \triangleright Initialize dummy inputs and labels.

3: \mathbf{for}\ i \leftarrow 1\ \text{to}\ n\ \mathbf{do}

4: \nabla W'_i \leftarrow \partial \ell(F(\mathbf{x}'_i, W_t), \mathbf{y}'_i)/\partial W_t \triangleright Compute dummy gradients.

5: \mathbb{D}_i \leftarrow ||\nabla W'_i - \nabla W||^2

6: \mathbf{x}'_{i+1} \leftarrow \mathbf{x}'_i - \eta \nabla_{\mathbf{x}'_i} \mathbb{D}_i, \mathbf{y}'_{i+1} \leftarrow \mathbf{y}'_i - \eta \nabla_{\mathbf{y}'_i} \mathbb{D}_i \triangleright Update data to match gradients.

7: end for

8: \mathbf{return}\ \mathbf{x}'_{n+1}, \mathbf{y}'_{n+1}

9: end procedure
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Algorithm 1 Deep Leakage from Gradients.

Learning with malicious users Snooping

- Able to reconstruct a training sample about 50% of the time
- It appears acquisition is more likely earlier on in the training process

