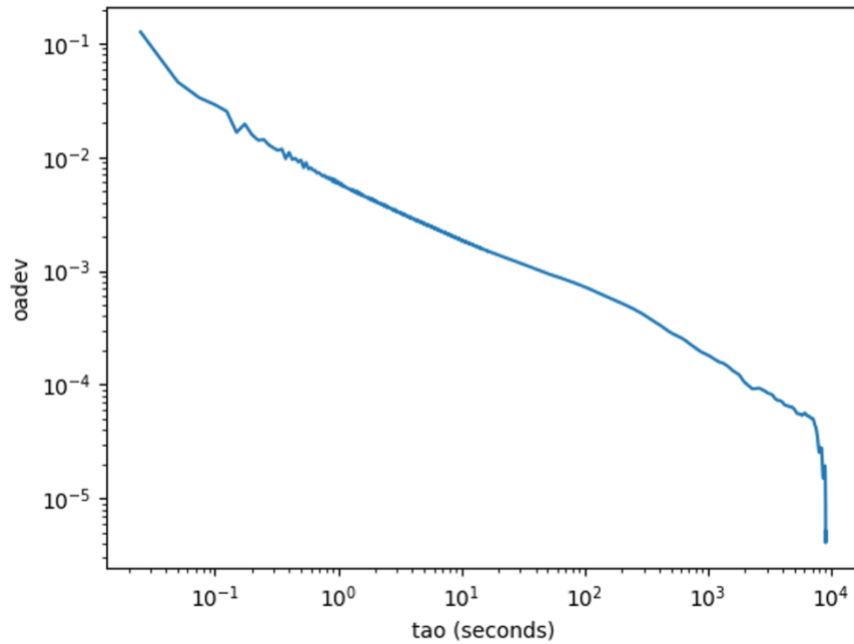
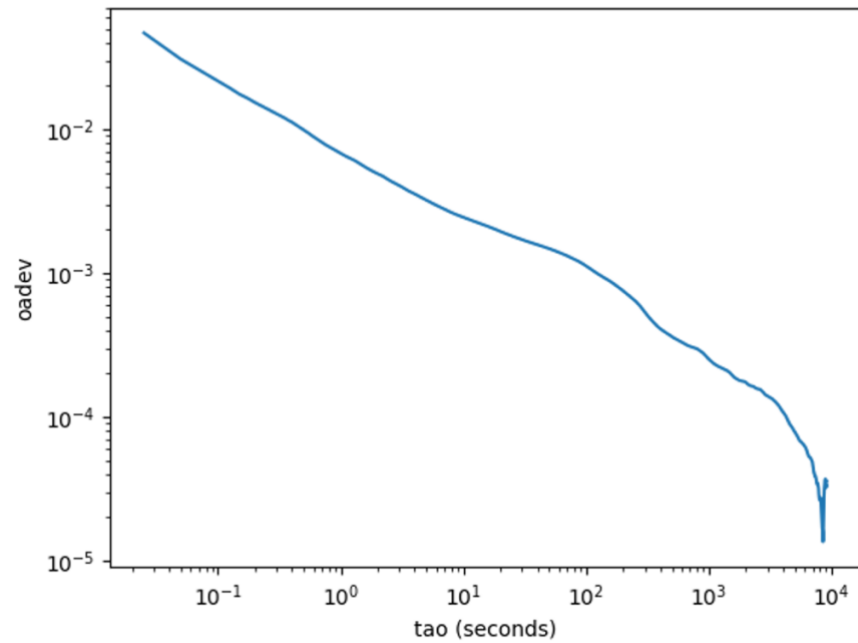


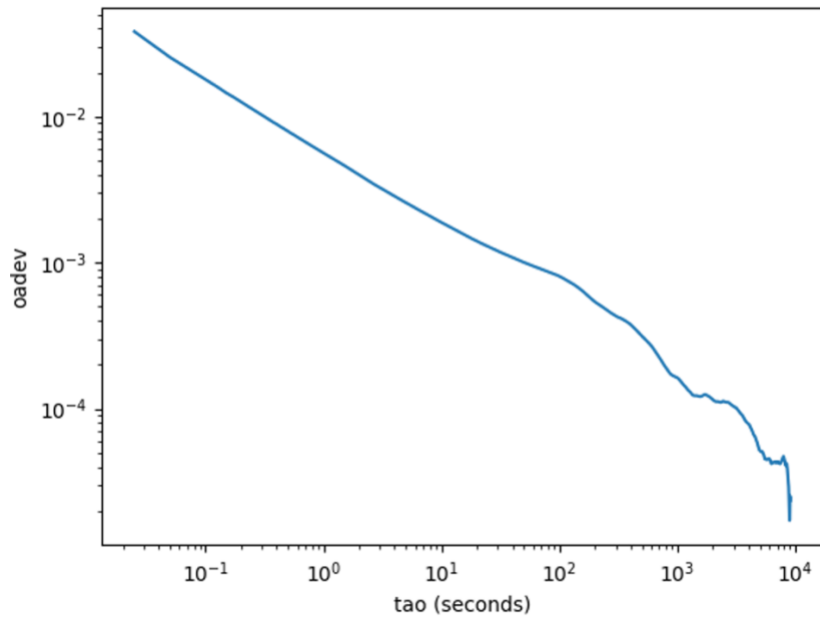
Gyro in x direction
Allan Deviation



Gyro in y direction
Allan Deviation



Gyro in z direction
Allan Deviation



```
B, the bias instability of gyro_x is:4.0782527480521955e-06
B, the bias instability of gyro_y is:1.3541079847219341e-05
B, the bias instability of gyro_z is:1.7170881804556535e-05
N, the angle random walk value of gyro_x is:-0.12069800554364701
N, the angle random walk value of gyro_y is:-0.03994756408233623
N, the angle random walk value of gyro_z is:-0.03251782417233452
K, the rate random walk value of gyro_x is:6754573.430798074
K, the rate random walk value of gyro_y is:159354152.65831387
K, the rate random walk value of gyro_z is:165247410.07082018
```