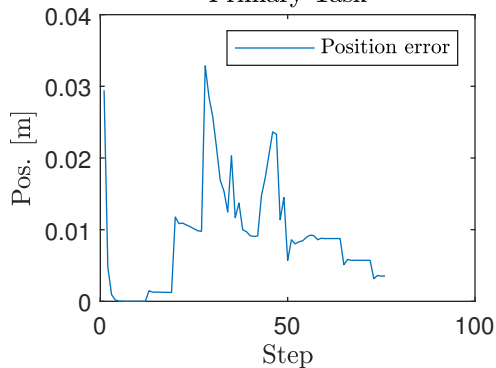
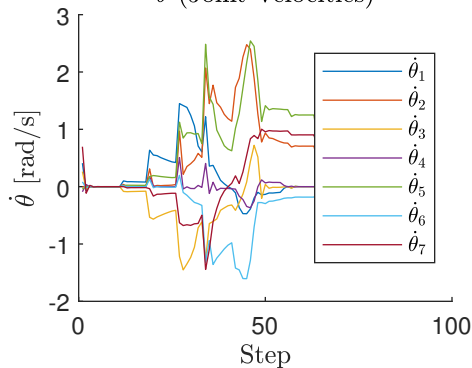
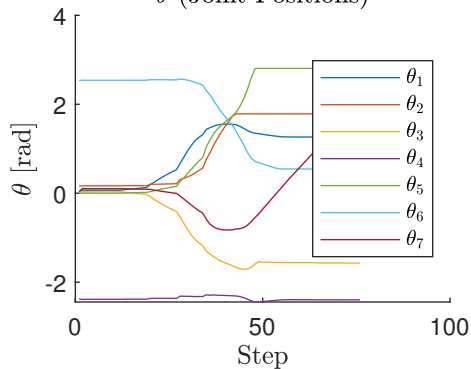


Primary Task

 $\dot{\theta}$ (Joint Velocities) θ (Joint Positions) $\|v_{rep}\|$ Repulsive Velocities