Introduction to Boolean Satisfiability (SAT) Solving

Jakob Nordström

University of Copenhagen and Lund University

SAT + SMT Winter School Chennai, India December 15, 2022

This Is Me...

Jakob Nordström

Professor

University of Copenhagen and Lund University www.jakobnordstrom.se



And This Is What I Do for a Living

 $(x_{1,1} \lor x_{1,2} \lor x_{1,3} \lor x_{1,4} \lor x_{1,5} \lor x_{1,6} \lor x_{1,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,2} \lor x_{2,3} \lor x_{2,4} \lor x_{2,5} \lor x_{2,6} \lor x_{2,7}) \land (x_{2,1} \lor x_{2,5} \lor x_{2,6} \lor x_{2,6} \lor x_{2,6} \lor x_{2,6} \lor x_{2,6}) \land (x_{2,1} \lor x_{2,5} \lor x_{2,6} \lor x_{2,6}) \land (x_{2,1} \lor x_{2,6} \lor x_{2,6} \lor x_{2,6}) \land (x_{2,1} \lor x_{2,6} \lor x_{2,6} \lor x_{2,6}) \land (x_{2,1} \lor x_{2,6} \lor x_{2,6} \lor x_{2,6}) \lor (x_{2,1} \lor x_{2,6} \lor x_{2,6} \lor x_{2,6}) \lor (x_{2,1} \lor x_{2,6} \lor x_{2,6}) \lor (x_{2,1} \lor x_{2,6} \lor x_{2,6} \lor x_{2,6}) \lor (x_{2,1} \lor x_{2,6} \lor x_{2,6}) \lor (x_{2,1}$ $(x_{3,1} \lor x_{3,2} \lor x_{3,3} \lor x_{3,4} \lor x_{3,5} \lor x_{3,6} \lor x_{3,7}) \land (x_{4,1} \lor x_{4,2} \lor x_{4,3} \lor x_{4,4} \lor x_{4,5} \lor x_{4,6} \lor x_{4,7}) \land (x_{5,1} \lor x_{5,1} \lor$ $x_{5,2} \lor x_{5,3} \lor x_{5,4} \lor x_{5,5} \lor x_{5,6} \lor x_{5,7}) \land (x_{6,1} \lor x_{6,2} \lor x_{6,3} \lor x_{6,4} \lor x_{6,5} \lor x_{6,6} \lor x_{6,7}) \land (x_{7,1} \lor x_{7,2} \lor x_{7,4} \lor$ $x_{7,3} \vee x_{7,4} \vee x_{7,5} \vee x_{7,6} \vee x_{7,7}) \wedge (x_{8,1} \vee x_{8,2} \vee x_{8,3} \vee x_{8,4} \vee x_{8,5} \vee x_{8,6} \vee x_{8,7}) \wedge (\neg x_{1,1} \vee \neg x_{2,1}) \wedge (\neg x_{1,1} \vee \neg x_{2,1})$ $(\neg x_{1,1} \lor \neg x_{3,1}) \land (\neg x_{1,1} \lor \neg x_{4,1}) \land (\neg x_{1,1} \lor \neg x_{5,1}) \land (\neg x_{1,1} \lor \neg x_{6,1}) \land (\neg x_{1,1} \lor \neg x_{7,1}) \land (\neg x_{1,1} \lor \neg x$ $(\neg x_{1,1} \lor \neg x_{8,1}) \land (\neg x_{2,1} \lor \neg x_{3,1}) \land (\neg x_{2,1} \lor \neg x_{4,1}) \land (\neg x_{2,1} \lor \neg x_{5,1}) \land (\neg x_{2,1} \lor \neg x_{6,1}) \land (\neg x_{2,1} \lor \neg x$ $(\neg x_{2,1} \lor \neg x_{7,1}) \land (\neg x_{2,1} \lor \neg x_{8,1}) \land (\neg x_{3,1} \lor \neg x_{4,1}) \land (\neg x_{3,1} \lor \neg x_{5,1}) \land (\neg x_{3,1} \lor \neg x_{6,1}) \land (\neg x_{3,1} \lor \neg x_{6,1})$ $\neg x_{7,1}) \wedge (\neg x_{3,1} \vee \neg x_{8,1}) \wedge (\neg x_{4,1} \vee \neg x_{5,1}) \wedge (\neg x_{4,1} \vee \neg x_{6,1}) \wedge (\neg x_{4,1} \vee \neg x_{7,1}) \wedge (\neg x_{4,1} \vee \neg x_{8,1}) \wedge (\neg x_{4,1} \vee \neg x_{6,1}) \wedge (\neg$ $(\neg x_{5,1} \lor \neg x_{6,1}) \land (\neg x_{5,1} \lor \neg x_{7,1}) \land (\neg x_{5,1} \lor \neg x_{8,1}) \land (\neg x_{6,1} \lor \neg x_{7,1}) \land (\neg x_{6,1} \lor \neg x_{8,1}) \land (\neg x_{7,1} \lor \neg x_{7,1}) \land (\neg x_{7,1} \lor \neg x$ $\neg x_{8,1}) \land (\neg x_{1,2} \lor \neg x_{2,2}) \land (\neg x_{1,2} \lor \neg x_{3,2}) \land (\neg x_{1,2} \lor \neg x_{4,2}) \land (\neg x_{1,2} \lor \neg x_{5,2}) \land (\neg x_{1,2} \lor \neg x_{6,2}) \land (\neg$ $(\neg x_{1,2} \lor \neg x_{7,2}) \land (\neg x_{1,2} \lor \neg x_{8,2}) \land (\neg x_{2,2} \lor \neg x_{3,2}) \land (\neg x_{2,2} \lor \neg x_{4,2}) \land (\neg x_{2,2} \lor \neg x_{5,2}) \land (\neg x_{2,2} \lor \neg x$ $\neg x_{6,2}) \wedge (\neg x_{2,2} \vee \neg x_{7,2}) \wedge (\neg x_{2,2} \vee \neg x_{8,2}) \wedge (\neg x_{3,2} \vee \neg x_{4,2}) \wedge (\neg x_{3,2} \vee \neg x_{5,2}) \wedge (\neg x_{3,2} \vee \neg x_{6,2}) \wedge (\neg$ $(\neg x_{3,2} \lor \neg x_{7,2}) \land (\neg x_{3,2} \lor \neg x_{8,2}) \land (\neg x_{4,2} \lor \neg x_{5,2}) \land (\neg x_{4,2} \lor \neg x_{6,2}) \land (\neg x_{4,2} \lor \neg x_{7,2}) \land (\neg x_{4,2} \lor \neg x$ $\neg x_{8,2}) \wedge (\neg x_{5,2} \vee \neg x_{6,2}) \wedge (\neg x_{5,2} \vee \neg x_{7,2}) \wedge (\neg x_{5,2} \vee \neg x_{8,2}) \wedge (\neg x_{6,2} \vee \neg x_{7,2}) \wedge (\neg x_{6,2} \vee \neg x_{8,2}) \wedge (\neg x_{6,2} \vee \neg x_{7,2}) \wedge (\neg x_{6,2} \vee \neg x_{8,2}) \wedge (\neg x_{6,2} \vee \neg x_{7,2}) \wedge (\neg$ $(\neg x_{7,2} \lor \neg x_{8,2}) \land (\neg x_{1,3} \lor \neg x_{2,3}) \land (\neg x_{1,3} \lor \neg x_{3,3}) \land (\neg x_{1,3} \lor \neg x_{4,3}) \land (\neg x_{1,3} \lor \neg x_{5,3}) \land (\neg x_{1,3} \lor \neg x$ $\neg x_{6,3}) \wedge (\neg x_{1,3} \vee \neg x_{7,3}) \wedge (\neg x_{1,3} \vee \neg x_{8,3}) \wedge (\neg x_{2,3} \vee \neg x_{3,3}) \wedge (\neg x_{2,3} \vee \neg x_{4,3}) \wedge (\neg x_{2,3} \vee \neg x_{5,3})$

Colouring

Does the graph G = (V, E) have a colouring with k colours such that all neighbours have distinct colours?

Colouring

Does the graph G = (V, E) have a colouring with k colours such that all neighbours have distinct colours?



3-colouring?

Colouring

Does the graph G = (V, E) have a colouring with k colours such that all neighbours have distinct colours?



3-colouring? Yes

Colouring

Does the graph G = (V, E) have a colouring with k colours such that all neighbours have distinct colours?



3-colouring? Yes, but no 2-colouring

CLIQUE

Is there a clique in the graph G=(V,E) with k vertices that are all pairwise connected by edges in E?

Intro to SAT Solving



3-clique?

CLIQUE

Is there a clique in the graph G=(V,E) with k vertices that are all pairwise connected by edges in E?



3-clique? Yes

CLIQUE

Is there a clique in the graph G=(V,E) with k vertices that are all pairwise connected by edges in E?



3-clique? Yes, but no 4-clique

CLIQUE

Is there a clique in the graph G=(V,E) with k vertices that are all pairwise connected by edges in E?

Colouring

Does the graph G = (V, E) have a colouring with k colours such that all neighbours have distinct colours?

CLIQUE

Is there a clique in the graph G=(V,E) with k vertices that are all pairwise connected by edges in E?

Sat

Given propositional logic formula, is there a satisfying assignment?

Colouring

Does the graph G=(V,E) have a colouring with k colours such that all neighbours have distinct colours?

CLIQUE

Is there a clique in the graph G=(V,E) with k vertices that are all pairwise connected by edges in E?

SAT

Given propositional logic formula, is there a satisfying assignment?

$$(x \lor z) \land (y \lor \neg z) \land (x \lor \neg y \lor u) \land (\neg y \lor \neg u)$$

$$\land (u \lor v) \land (\neg x \lor \neg v) \land (\neg u \lor w) \land (\neg x \lor \neg u \lor \neg w)$$

Colouring

Does the graph G = (V, E) have a colouring with k colours such that all neighbours have distinct colours?

CLIQUE

Is there a clique in the graph G=(V,E) with k vertices that are all pairwise connected by edges in E?

Sat

Given propositional logic formula, is there a satisfying assignment?

$$(x \lor z) \land (y \lor \neg z) \land (x \lor \neg y \lor u) \land (\neg y \lor \neg u)$$
$$\land (u \lor v) \land (\neg x \lor \neg v) \land (\neg u \lor w) \land (\neg x \lor \neg u \lor \neg w)$$

- Variables should be set to true or false
- Constraint $(x \lor \neg y \lor z)$: means x or z should be true or y false
- \(\) means all constraints should hold simultaneously
- Is there a truth value assignment satisfying all constraints?

Colouring

Does the graph G = (V, E) have a colouring with k colours such that all neighbours have distinct colours?

CLIQUE

Is there a clique in the graph G=(V,E) with k vertices that are all pairwise connected by edges in E?

SAT

Given propositional logic formula, is there a satisfying assignment?

COLOURING: frequency allocation for mobile base stations

CLIQUE: bioinformatics, computational chemistry

SAT: easily models these and many other problems

... with Huge Practical Implications

- Some more examples of problems that can be encoded as propositional logic formulas:
 - computer hardware verification
 - computer software testing
 - artificial intelligence
 - cryptography
 - bioinformatics
 - et cetera...
- Leads to humongous formulas (100,000s or even 1,000,000s of variables)
- Can we use computers to solve these problems efficiently?
- Question mentioned already in Gödel's famous letter in 1956 to von Neumann (the "father of computer science")
- Topic of intense research in computer science ever since 1960s

Dramatic progress last 20–25 years on so-called SAT solvers
 Today routinely used to solve large-scale real-world problems

- Dramatic progress last 20–25 years on so-called SAT solvers
 Today routinely used to solve large-scale real-world problems
- ullet But... There are also small formulas (just $\sim \! 100$ variables) that are completely beyond reach of even the very best SAT solvers

- Dramatic progress last 20–25 years on so-called SAT solvers
 Today routinely used to solve large-scale real-world problems
- But... There are also small formulas (just \sim 100 variables) that are completely beyond reach of even the very best SAT solvers
- Best known SAT solving algorithms based on Davis-Putnam-Logemann-Loveland or DPLL method from early 1960s (although with many clever optimizations)

- Dramatic progress last 20–25 years on so-called SAT solvers
 Today routinely used to solve large-scale real-world problems
- But... There are also small formulas (just \sim 100 variables) that are completely beyond reach of even the very best SAT solvers
- Best known SAT solving algorithms based on Davis-Putnam-Logemann-Loveland or DPLL method from early 1960s (although with many clever optimizations)
- Some natural questions:
 - How do these SAT solvers work?

- Dramatic progress last 20–25 years on so-called SAT solvers
 Today routinely used to solve large-scale real-world problems
- ullet But...There are also small formulas (just $\sim\!100$ variables) that are completely beyond reach of even the very best SAT solvers
- Best known SAT solving algorithms based on Davis-Putnam-Logemann-Loveland or DPLL method from early 1960s (although with many clever optimizations)
- Some natural questions:
 - How do these SAT solvers work?
 - How can they be so good in practice?

- Dramatic progress last 20–25 years on so-called SAT solvers
 Today routinely used to solve large-scale real-world problems
- ullet But...There are also small formulas (just $\sim\!100$ variables) that are completely beyond reach of even the very best SAT solvers
- Best known SAT solving algorithms based on Davis-Putnam-Logemann-Loveland or DPLL method from early 1960s (although with many clever optimizations)
- Some natural questions:
 - How do these SAT solvers work?
 - How can they be so good in practice?
 - When they fail to be efficient, can we understand why?

- Dramatic progress last 20–25 years on so-called SAT solvers
 Today routinely used to solve large-scale real-world problems
- But... There are also small formulas (just \sim 100 variables) that are completely beyond reach of even the very best SAT solvers
- Best known SAT solving algorithms based on Davis-Putnam-Logemann-Loveland or DPLL method from early 1960s (although with many clever optimizations)
- Some natural questions:
 - How do these SAT solvers work?
 - How can they be so good in practice?
 - When they fail to be efficient, can we understand why?
 - It's 2022 now can we go beyond techniques from 1960s?

What we will cover today:

• Define more precisely the computational problem

- Define more precisely the computational problem
- Give (simplified) description of how modern SAT solvers work

- Define more precisely the computational problem
- Give (simplified) description of how modern SAT solvers work
- Present tools to analyze SAT solver performance

- Define more precisely the computational problem
- Give (simplified) description of how modern SAT solvers work
- Present tools to analyze SAT solver performance
- Discuss possible ways to go beyond the current state of the art [in the pseudo-Boolean tutorial]

What we will cover today:

- Define more precisely the computational problem
- Give (simplified) description of how modern SAT solvers work
- Present tools to analyze SAT solver performance
- Discuss possible ways to go beyond the current state of the art [in the pseudo-Boolean tutorial]

... And in the process also touch on some of the research being done in the Mathematical Insights into Algorithms for Optimization (MIAO) group



Formal Description of SAT Problem

- Variable x: takes value 1 (true) or 0 (false)
- Literal ℓ : variable x or its negation \overline{x} (write \overline{x} instead of $\neg x$)
- Clause $C = \ell_1 \lor \cdots \lor \ell_k$: disjunction of literals (Consider as sets, so no repetitions and order irrelevant)
- Conjunctive normal form (CNF) formula $F = C_1 \wedge \cdots \wedge C_m$: conjunction of clauses

Formal Description of SAT Problem

- Variable x: takes value 1 (true) or 0 (false)
- Literal ℓ : variable x or its negation \overline{x} (write \overline{x} instead of $\neg x$)
- Clause $C = \ell_1 \lor \cdots \lor \ell_k$: disjunction of literals (Consider as sets, so no repetitions and order irrelevant)
- Conjunctive normal form (CNF) formula $F = C_1 \wedge \cdots \wedge C_m$: conjunction of clauses

The Satisfiability (or just Sat) Problem

Given a CNF formula F, is it satisfiable?

Formal Description of SAT Problem

- Variable x: takes value 1 (true) or 0 (false)
- Literal ℓ : variable x or its negation \overline{x} (write \overline{x} instead of $\neg x$)
- Clause $C = \ell_1 \vee \cdots \vee \ell_k$: disjunction of literals (Consider as sets, so no repetitions and order irrelevant)
- Conjunctive normal form (CNF) formula $F = C_1 \wedge \cdots \wedge C_m$: conjunction of clauses

The Satisfiability (or just Sat) Problem

Given a CNF formula F, is it satisfiable?

For instance, what about our example formula?

$$(x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y} \lor u) \land (\overline{y} \lor \overline{u})$$

$$\land (u \lor v) \land (\overline{x} \lor \overline{v}) \land (\overline{u} \lor w) \land (\overline{x} \lor \overline{u} \lor \overline{w})$$

How to Solve the SAT Problem?

- Let computer check all possible assignments! Isn't this exactly the kind of monotone routine work at which computers excel?
- But how many cases to check?
- Suppose formula has n variables
- Each variable can be either true or false, so all in all get 2^n different cases
- If formula contains, say, one million variables, we get $2^{1,000,000}$ cases (a number with more than 300,000 digits)

How to Solve the SAT Problem?

- Let computer check all possible assignments! Isn't this exactly the kind of monotone routine work at which computers excel?
- But how many cases to check?
- Suppose formula has n variables
- Each variable can be either true or false, so all in all get 2^n different cases
- If formula contains, say, one million variables, we get $2^{1,000,000}$ cases (a number with more than 300,000 digits)

To understand how large this number is, consider that even if every atom in the known universe was a modern supercomputer that had been running at full speed ever since the beginning of time some 13.7 billion years ago, all of them together would only have covered a completely negligible fraction of these cases by now. So we really would not have time to wait for them to finish...

An Interesting Feature of the SAT Problem

- Deciding whether a satisfying assignment exists may take a long time
- But if you happen to know a satisfying assignment, easy to convince someone else that formula is satisfiable
- How? Just give assignment can be verified in linear time
- So Sat problem might seem hard to solve, but verifying a solution is easy (not all problems have this property — how do you verify a winning position in chess?)
- The family of problems for which solutions are easy to check have a name: NP

How to Solve the SAT Problem, Take 2

- SAT problem can be used to describe any problem in NP it is NP-complete [Coo71, Lev73]
- If you can solve SAT efficiently, then you can solve any problem in NP efficiently (this is why SAT is so useful)
- So how hard is it to solve SAT? (Ok, brute force didn't work, but it usually doesn't maybe can do something smarter?)

How to Solve the SAT Problem, Take 2

- SAT problem can be used to describe any problem in NP it is NP-complete [Coo71, Lev73]
- If you can solve SAT efficiently, then you can solve any problem in NP efficiently (this is why SAT is so useful)
- So how hard is it to solve SAT? (Ok, brute force didn't work, but it usually doesn't maybe can do something smarter?)
- We don't know
- This one of the million-dollar "Millennium Prize Problems" posed as the main challenges for mathematics in the new millennium
- Widely believe to be impossible to solve efficiently on computer in the worst case, but we really don't know

Ok, but suppose you're out there in reality and actually have to solve the problem — then what do you do?

Ok, but suppose you're out there in reality and actually have to solve the problem — then what do you do?

Chances are you'll use some variant of the DPLL method developed by Davis, Putnam, Logemann & Loveland [DP60, DLL62]

Ok, but suppose you're out there in reality and actually have to solve the problem — then what do you do?

Chances are you'll use some variant of the DPLL method developed by Davis, Putnam, Logemann & Loveland [DP60, DLL62]

Ok, but suppose you're out there in reality and actually have to solve the problem — then what do you do?

Chances are you'll use some variant of the DPLL method developed by Davis, Putnam, Logemann & Loveland [DP60, DLL62]

DPLL (somewhat simplified description)

 If F contains empty clause (without literals), report "unsatisfiable" and return — refer to as conflict

Ok, but suppose you're out there in reality and actually have to solve the problem — then what do you do?

Chances are you'll use some variant of the DPLL method developed by Davis, Putnam, Logemann & Loveland [DP60, DLL62]

- If F contains empty clause (without literals), report "unsatisfiable" and return — refer to as conflict
- ullet If F contains no clauses, report "satisfiable" and terminate

Ok, but suppose you're out there in reality and actually have to solve the problem — then what do you do?

Chances are you'll use some variant of the DPLL method developed by Davis, Putnam, Logemann & Loveland [DP60, DLL62]

- If F contains empty clause (without literals), report "unsatisfiable" and return — refer to as conflict
- ullet If F contains no clauses, report "satisfiable" and terminate
- ullet Otherwise pick some variable x in F

Ok, but suppose you're out there in reality and actually have to solve the problem — then what do you do?

Chances are you'll use some variant of the DPLL method developed by Davis, Putnam, Logemann & Loveland [DP60, DLL62]

- If F contains empty clause (without literals), report "unsatisfiable" and return — refer to as conflict
- ullet If F contains no clauses, report "satisfiable" and terminate
- ullet Otherwise pick some variable x in F
- Set x = 0, simplify F and make recursive call

Ok, but suppose you're out there in reality and actually have to solve the problem — then what do you do?

Chances are you'll use some variant of the DPLL method developed by Davis, Putnam, Logemann & Loveland [DP60, DLL62]

- If F contains empty clause (without literals), report "unsatisfiable" and return — refer to as conflict
- ullet If F contains no clauses, report "satisfiable" and terminate
- ullet Otherwise pick some variable x in F
- Set x = 0, simplify F and make recursive call
- Set x = 1, simplify F and make recursive call

Ok, but suppose you're out there in reality and actually have to solve the problem — then what do you do?

Chances are you'll use some variant of the DPLL method developed by Davis, Putnam, Logemann & Loveland [DP60, DLL62]

- If F contains empty clause (without literals), report "unsatisfiable" and return — refer to as conflict
- ullet If F contains no clauses, report "satisfiable" and terminate
- ullet Otherwise pick some variable x in F
- Set x = 0, simplify F and make recursive call
- Set x = 1, simplify F and make recursive call
- If result in both cases "unsatisfiable", then report "unsatisfiable" and return

$$F = (x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y} \lor u) \land (\overline{y} \lor \overline{u})$$
$$\land (u \lor v) \land (\overline{x} \lor \overline{v}) \land (\overline{u} \lor w) \land (\overline{x} \lor \overline{u} \lor \overline{w})$$

$$F = (x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y} \lor u) \land (\overline{y} \lor \overline{u})$$
$$\land (u \lor v) \land (\overline{x} \lor \overline{v}) \land (\overline{u} \lor w) \land (\overline{x} \lor \overline{u} \lor \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

$$F = (x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y} \lor u) \land (\overline{y} \lor \overline{u})$$
$$\land (u \lor v) \land (\overline{x} \lor \overline{v}) \land (\overline{u} \lor w) \land (\overline{x} \lor \overline{u} \lor \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

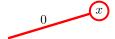


$$F = (z) \wedge (y \vee \overline{z}) \wedge (\overline{y} \vee u) \wedge (\overline{y} \vee \overline{u})$$
$$\wedge (u \vee v) \wedge (\overline{x} \vee \overline{v}) \wedge (\overline{u} \vee w) \wedge (\overline{x} \vee \overline{u} \vee \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

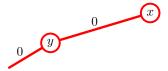


$$F = (z) \wedge (\overline{z}) \wedge (\overline{y} \vee u) \wedge (\overline{y} \vee \overline{u})$$
$$\wedge (u \vee v) \wedge (\overline{x} \vee \overline{v}) \wedge (\overline{u} \vee w) \wedge (\overline{x} \vee \overline{u} \vee \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

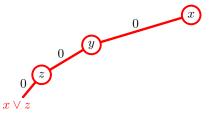


$$F = (x \lor z) \land (\overline{z}) \land (\overline{y} \lor u) \land (\overline{y} \lor \overline{u})$$
$$\land (u \lor v) \land (\overline{x} \lor \overline{v}) \land (\overline{u} \lor w) \land (\overline{x} \lor \overline{u} \lor \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

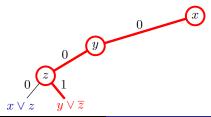


$$F = (z) \wedge (\underline{y} \vee \overline{z}) \wedge (\overline{y} \vee u) \wedge (\overline{y} \vee \overline{u})$$
$$\wedge (u \vee v) \wedge (\overline{x} \vee \overline{v}) \wedge (\overline{u} \vee w) \wedge (\overline{x} \vee \overline{u} \vee \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

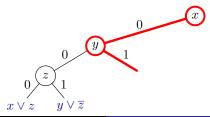


$$F = (z) \wedge (y \vee \overline{z}) \wedge (u) \wedge (\overline{u})$$
$$\wedge (u \vee v) \wedge (\overline{x} \vee \overline{v}) \wedge (\overline{u} \vee w) \wedge (\overline{x} \vee \overline{u} \vee \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

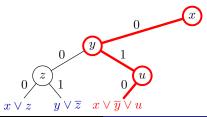


$$F = (z) \wedge (y \vee \overline{z}) \wedge (x \vee \overline{y} \vee u) \wedge (\overline{u})$$
$$\wedge (v) \wedge (\overline{x} \vee \overline{v}) \wedge (\overline{u} \vee w) \wedge (\overline{x} \vee \overline{u} \vee \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

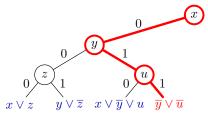


$$F = (z) \wedge (y \vee \overline{z}) \wedge (u) \wedge (\overline{y} \vee \overline{u})$$
$$\wedge (u \vee v) \wedge (\overline{x} \vee \overline{v}) \wedge (w) \wedge (\overline{x} \vee \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

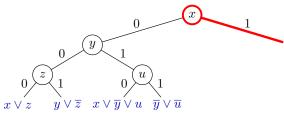


$$F = (x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y} \lor u) \land (\overline{y} \lor \overline{u})$$
$$\land (u \lor v) \land (\overline{v}) \land (\overline{u} \lor w) \land (\overline{u} \lor \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

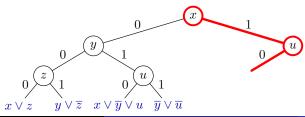


$$F = (x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y}) \land (\overline{y} \lor \overline{u})$$
$$\land (v) \land (\overline{v}) \land (\overline{u} \lor w) \land (\overline{u} \lor \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

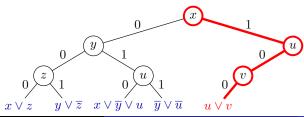


$$F = (x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y}) \land (\overline{y} \lor \overline{u})$$
$$\land (\underline{u} \lor \underline{v}) \land (\overline{v}) \land (\overline{u} \lor w) \land (\overline{u} \lor \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

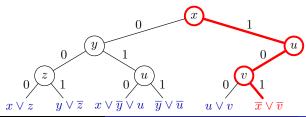


$$F = (x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y}) \land (\overline{y} \lor \overline{u})$$
$$\land (v) \land (\overline{x} \lor \overline{v}) \land (\overline{u} \lor w) \land (\overline{u} \lor \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

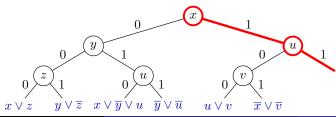


$$F = (x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y} \lor u) \land (\overline{y} \lor \overline{u})$$
$$\land (u \lor v) \land (\overline{v}) \land (w) \land (\overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

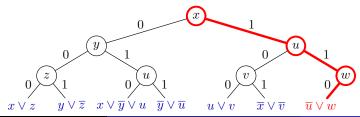


$$F = (x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y} \lor u) \land (\overline{y} \lor \overline{u})$$
$$\land (u \lor v) \land (\overline{v}) \land (\overline{u} \lor w) \land (\overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

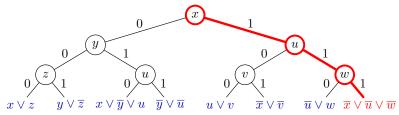


$$F = (x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y} \lor u) \land (\overline{y} \lor \overline{u})$$
$$\land (u \lor v) \land (\overline{v}) \land (w) \land (\overline{x} \lor \overline{u} \lor \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals

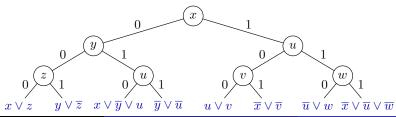


$$F = (x \lor z) \land (y \lor \overline{z}) \land (x \lor \overline{y} \lor u) \land (\overline{y} \lor \overline{u})$$
$$\land (u \lor v) \land (\overline{x} \lor \overline{v}) \land (\overline{u} \lor w) \land (\overline{x} \lor \overline{u} \lor \overline{w})$$

Visualize execution of DPLL algorithm as search tree

Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

- satisfied clauses
- falsified literals



State-of-the-art SAT solvers: Ingredients

Many more ingredients in modern conflict-driven clause learning (CDCL) SAT solvers (as pioneered in [MS99, MMZ⁺01]), e.g.:

- Branching or decision heuristic (choice of pivot variables crucial)
- When reaching leaf, compute explanation for conflict and add to formula as new clause (clause learning)
- Every once in a while, restart from beginning (but save computed info)

Let us discuss these ingredients

Variable Assignment Heuristics

Unit propagation

- Suppose current assignment ρ falsifies all literals in $C = \ell_1 \vee \ell_2 \vee \cdots \vee \ell_k$ except one (say ℓ_k) C is unit under ρ
- Then ℓ_k has to be true, so set it to true
- Known as unit progagation or Boolean constraint progagation
- Always propagate if possible in modern solvers aim for \approx 99% of assignments being unit propagations

Variable Assignment Heuristics

Unit propagation

- Suppose current assignment ρ falsifies all literals in $C = \ell_1 \vee \ell_2 \vee \cdots \vee \ell_k$ except one (say ℓ_k) C is unit under ρ
- Then ℓ_k has to be true, so set it to true
- Known as unit progagation or Boolean constraint progagation
- Always propagate if possible in modern solvers aim for \approx 99% of assignments being unit propagations

VSIDS (Variable state independent decaying sum)

- When backtracking, score +1 for variables "causing conflict"
- Also multiply all scores with factor $\kappa < 1$ exponential filter rewarding variables involved in recent conflicts
- When no propagations, decide on variable with highest score

 At conflict, want to add clause avoiding same part of search tree being explored again

- At conflict, want to add clause avoiding same part of search tree being explored again
- Suppose we can compute that decisions x=1, y=0, z=1 responsible for conflict

- At conflict, want to add clause avoiding same part of search tree being explored again
- Suppose we can compute that decisions $x=1,\ y=0,\ z=1$ responsible for conflict
- Then can add $\overline{x} \lor y \lor \overline{z}$ to avoid these decisions being made again decision learning scheme

- At conflict, want to add clause avoiding same part of search tree being explored again
- Suppose we can compute that decisions x=1, y=0, z=1 responsible for conflict
- Then can add $\overline{x} \lor y \lor \overline{z}$ to avoid these decisions being made again decision learning scheme
- In practice, more advanced learning schemes

- At conflict, want to add clause avoiding same part of search tree being explored again
- Suppose we can compute that decisions $x=1,\ y=0,\ z=1$ responsible for conflict
- Then can add $\overline{x} \lor y \lor \overline{z}$ to avoid these decisions being made again decision learning scheme
- In practice, more advanced learning schemes
- Derive new clause from clauses unit propagating on the way to conflict

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$

Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathrm{d}}{=} 0$$

Intro to SAT Solving

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$

$$p \stackrel{\mathsf{d}}{=} 0$$

Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathsf{d}}{=} 0$$

Two kinds of assignments — illustrate on example formula:

$$(\underline{p}\vee\overline{u})\wedge(q\vee r)\wedge(\overline{r}\vee w)\wedge(u\vee x\vee y)\wedge(x\vee\overline{y}\vee z)\wedge(\overline{x}\vee z)\wedge(\overline{y}\vee\overline{z})\wedge(\overline{x}\vee\overline{z})\wedge(\overline{p}\vee\overline{u})$$

$$p \stackrel{\mathsf{d}}{=} 0$$

Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathrm{d}}{=} 0$$

Unit propagation

Forced choice to avoid falsifying clause Given p=0, clause $p\vee \overline{u}$ forces u=0

Notation
$$u \stackrel{p \vee \overline{u}}{=} 0$$
 ($p \vee \overline{u}$ is reason clause)

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$

$$\begin{array}{c|c}
p \stackrel{\mathsf{d}}{=} 0 \\
 & \stackrel{p \vee \overline{u}}{=} 0
\end{array}$$

Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathsf{d}}{=} 0$$

Unit propagation

Forced choice to avoid falsifying clause Given p=0, clause $p\vee \overline{u}$ forces u=0

Notation
$$u \stackrel{p \vee \overline{u}}{=} 0$$
 ($p \vee \overline{u}$ is reason clause)

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$

$$\begin{array}{c}
p \stackrel{d}{=} 0 \\
u \stackrel{p \vee \overline{u}}{=} 0 \\
q \stackrel{d}{=} 0
\end{array}$$

Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathrm{d}}{=} 0$$

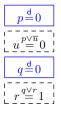
Unit propagation

Forced choice to avoid falsifying clause Given p=0, clause $p\vee \overline{u}$ forces u=0

Notation
$$u \stackrel{p \vee \overline{u}}{=} 0$$
 $(p \vee \overline{u} \text{ is reason clause})$

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (\overline{q} \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathrm{d}}{=} 0$$

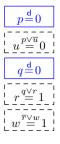
Unit propagation

Forced choice to avoid falsifying clause Given p=0, clause $p\vee \overline{u}$ forces u=0

Notation
$$u \stackrel{p \vee \overline{u}}{=} 0$$
 $(p \vee \overline{u} \text{ is reason clause})$

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathrm{d}}{=} 0$$

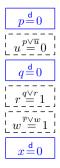
Unit propagation

Forced choice to avoid falsifying clause Given p=0, clause $p\vee \overline{u}$ forces u=0

Notation
$$u \stackrel{p \vee \overline{u}}{=} 0$$
 $(p \vee \overline{u} \text{ is reason clause})$

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathrm{d}}{=} 0$$

Unit propagation

Forced choice to avoid falsifying clause Given p=0, clause $p\vee \overline{u}$ forces u=0

Notation
$$u \stackrel{p \vee \overline{u}}{=} 0$$
 $(p \vee \overline{u} \text{ is reason clause})$

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge \underline{(u \vee x \vee y)} \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathrm{d}}{=} 0$$

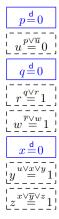
Unit propagation

Forced choice to avoid falsifying clause Given p=0, clause $p\vee\overline{u}$ forces u=0

Notation
$$u \stackrel{p \vee \overline{u}}{=} 0$$
 $(p \vee \overline{u} \text{ is reason clause})$

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge \underline{(x \vee \overline{y} \vee z)} \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathrm{d}}{=} 0$$

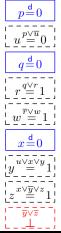
Unit propagation

Forced choice to avoid falsifying clause Given p=0, clause $p\vee \overline{u}$ forces u=0

Notation
$$u \stackrel{p \vee \overline{u}}{=} 0$$
 $(p \vee \overline{u} \text{ is reason clause})$

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathrm{d}}{=} 0$$

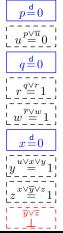
Unit propagation

Forced choice to avoid falsifying clause Given p=0, clause $p\vee\overline{u}$ forces u=0

Notation
$$u \stackrel{p \vee \overline{u}}{=} 0$$
 $(p \vee \overline{u} \text{ is reason clause})$

Two kinds of assignments — illustrate on example formula:

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



decision level 1

Decision

Free choice to assign value to variable

Notation
$$p \stackrel{\mathrm{d}}{=} 0$$

decision level 2

Unit propagation

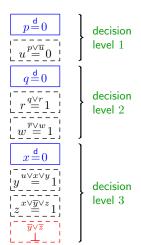
Forced choice to avoid falsifying clause Given p=0, clause $p\vee \overline{u}$ forces u=0

Notation
$$u \stackrel{p \vee \overline{u}}{=} 0$$
 $(p \vee \overline{u} \text{ is reason clause})$

decision level 3

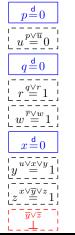
Time to analyse this conflict and learn from it!

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



Time to analyse this conflict and learn from it!

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



decision level 1

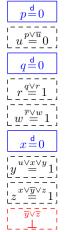
Could backtrack by removing last decision level & flipping last decision

decision level 2

decision level 3

Time to analyse this conflict and learn from it!

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



decision level 1

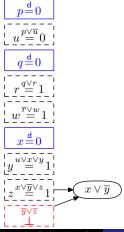
decision level 2

decision level 3 Could backtrack by removing last decision level & flipping last decision

But want to learn from conflict and cut away as much of search space as possible

Time to analyse this conflict and learn from it!

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



Could backtrack by removing last decision level & flipping last decision

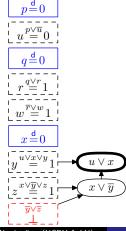
But want to learn from conflict and cut away as much of search space as possible

Case analysis over z for last two clauses:

- $x \vee \overline{y} \vee z$ wants z = 1
- $\overline{y} \vee \overline{z}$ wants z = 0
- Resolve clauses by merging them & removing z must satisfy $x \lor \overline{y}$

Time to analyse this conflict and learn from it!

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



Could backtrack by removing last decision level & flipping last decision

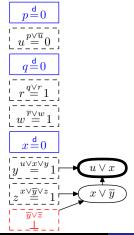
But want to learn from conflict and cut away as much of search space as possible

Case analysis over z for last two clauses:

- $x \vee \overline{y} \vee z$ wants z = 1
- $\overline{y} \vee \overline{z}$ wants z = 0
- Resolve clauses by merging them & removing z must satisfy $x \lor \overline{y}$

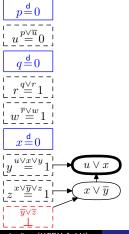
Repeat until UIP clause with only 1 variable after last decision — learn and backjump

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



Backjump: undo max #decisions while learned clause propagates

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$

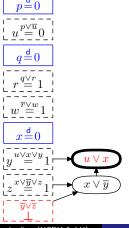


$$\begin{array}{c|c}
p \stackrel{\mathsf{d}}{=} 0 \\
 & u \stackrel{p \vee \overline{u}}{=} 0
\end{array}$$

Assertion level 1 (max for non-UIP literal in learned clause) — trim trail to that level

Backjump: undo max #decisions while learned clause propagates

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



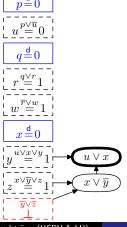


Assertion level 1 (max for non-UIP literal in learned clause) — trim trail to that level

Now UIP literal guaranteed to flip (assert) — but this is a propagation, not a decision

Backjump: undo max #decisions while learned clause propagates

$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



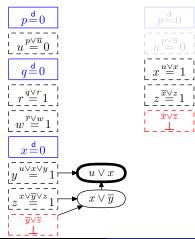


Assertion level 1 (max for non-UIP literal in learned clause) — trim trail to that level

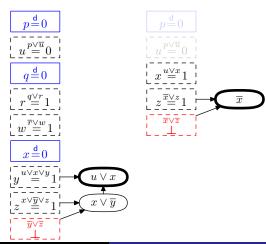
Now UIP literal guaranteed to flip (assert) — but this is a propagation, not a decision

Then continue as before...

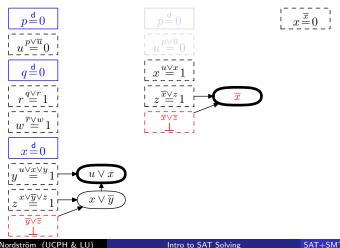
$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



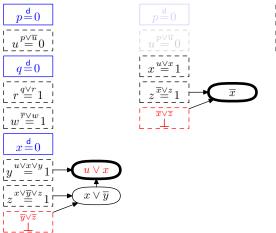
$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



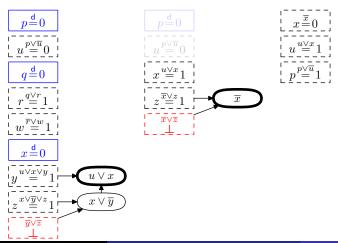
$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



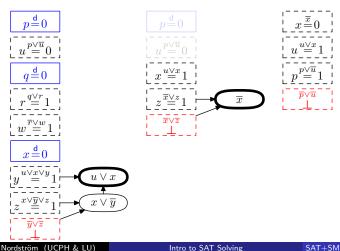
$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



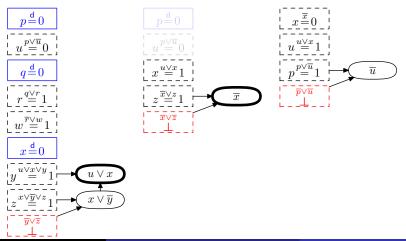
$$(\underline{p} \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



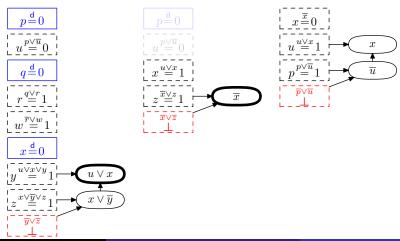
$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



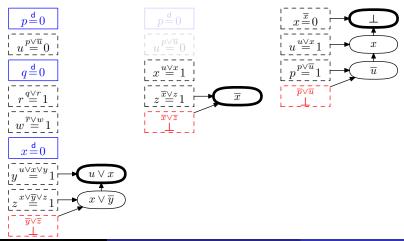
$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



$$(p \vee \overline{u}) \wedge (q \vee r) \wedge (\overline{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \overline{y} \vee z) \wedge (\overline{x} \vee z) \wedge (\overline{y} \vee \overline{z}) \wedge (\overline{x} \vee \overline{z}) \wedge (\overline{p} \vee \overline{u})$$



Clause Database Reduction

- In addition to learning clauses, also erase learned clauses that don't seem useful
- Modern solvers do this very aggressively
- Speeds up CDCL search (in particular, unit propagation, which dominates running time)
- ullet But erasing too aggressively can throw away clauses that would have made solver terminate faster [EGG $^+18$]
- So trade-off between search speed and search quality
- Except sometimes getting rid of clauses improves search quality too! [KN20]

Restarts

- Fairly frequently, start search all over (but keep learned clauses)
- Original intuition: stuck in bad part of search tree go somewhere else
- Not the reason this is done now
- Popular variables with high VSIDS scores get set again [MMZ+01]
- Are even set to same values (phase saving) [PD07]
- Current intution: improves the search by focusing on important variables
- Restart at fixed intervals or (better) make adaptive restarts depending on "quality" of learned clauses [AS09, AS12]

CDCL Main Loop Pseudocode

CDCL(F)

```
1 \mathcal{D} \leftarrow F; // initialize clause database to contain formula
 2 \rho \leftarrow \emptyset; // initialize assignment trail to empty
   forever do
         if \rho falsifies some clause C \in \mathcal{D} then
              A \leftarrow \mathsf{analyzeConflict}(\mathcal{D}, \rho, C);
              if A = \bot then output UNSATISFIABLE and exit;
              else
                    add A to \mathcal{D} and backjump by shrinking \rho;
         else if exists clause C \in \mathcal{D} unit propagating x to b \in \{0,1\} under \rho then
 9
              add propagated assignment x \stackrel{D}{=} b to \rho;
10
         else if time to restart then \rho \leftarrow \emptyset;
11
         else if time for clause database reduction then
12
              erase (roughly) half of learned clauses in \mathcal{D} \setminus F from \mathcal{D}
13
         else if all variables assigned then output SATISFIABLE and exit;
14
         else
15
              use decision scheme to choose assignment x \stackrel{d}{=} b to add to \rho;
16
```

CDCL Main Loop Pseudocode

CDCL(F)

```
1 \mathcal{D} \leftarrow F; // initialize clause database to contain formula
 2 
ho \leftarrow \emptyset ; // initialize assignment trail to empty
   forever do
         if \rho falsifies some clause C \in \mathcal{D} then
              A \leftarrow \mathsf{analyzeConflict}(\mathcal{D}, \rho, C);
              if A = \bot then output UNSATISFIABLE and exit;
              else
                   add A to \mathcal{D} and backjump by shrinking \rho;
         else if exists clause C \in \mathcal{D} unit propagating x to b \in \{0,1\} under \rho then
 9
              add propagated assignment x \stackrel{D}{=} b to \rho;
10
         else if time to restart then \rho \leftarrow \emptyset:
11
         else if time for clause database reduction then
12
13
         else if all variables assigned then output SATISFIABLE and exit;
14
         else
15
              use decision scheme to choose assignment x \stackrel{d}{=} b to add to \rho;
16
```

Conflict Analysis Pseudocode

```
analyzeConflict(\mathcal{D}, \rho, C_{\mathrm{confl}})

1 C_{\mathrm{learn}} \leftarrow C_{\mathrm{confl}};

2 while C_{\mathrm{learn}} not UIP clause and C_{\mathrm{learn}} \neq \bot do

3 | \ell \leftarrow literal assigned last on trail \rho;

4 if \ell propagated and \bar{\ell} occurs in C_{\mathrm{learn}} then

5 | C_{\mathrm{reason}} \leftarrow \mathrm{reason}(\ell, \rho, \mathcal{D});

6 | C_{\mathrm{learn}} \leftarrow \mathrm{resolve}(C_{\mathrm{learn}}, C_{\mathrm{reason}});

7 | \rho \leftarrow \rho \setminus \{\ell\};

8 return C_{\mathrm{learn}};
```

State-of-the-art SAT solvers: What About the Recipe?

List of ingredients again (not exhaustive):

- Variable decisions & propagations
- Clause learning
- Restarts
- Clause database reduction

State-of-the-art SAT solvers: What About the Recipe?

List of ingredients again (not exhaustive):

- Variable decisions & propagations
- Clause learning
- Restarts
- Clause database reduction

Some natural questions:

- How best to combine these ingredients into a recipe?
- When and why does this recipe work?

State-of-the-art SAT solvers: What About the Recipe?

List of ingredients again (not exhaustive):

- Variable decisions & propagations
- Clause learning
- Restarts
- Clause database reduction

Some natural questions:

- How best to combine these ingredients into a recipe?
- When and why does this recipe work?

Why SAT solvers actually work so well is a poorly understood question

Lots of research to comprehend this better (Among other places in the MIAO group)



SAT Solver Analysis and the Resolution Proof System

How to make rigorous analysis of SAT solver performance? Many intricate, hard-to-understand heuristics So focus instead on underlying method of reasoning

SAT Solver Analysis and the Resolution Proof System

How to make rigorous analysis of SAT solver performance? Many intricate, hard-to-understand heuristics So focus instead on underlying method of reasoning

Resolution proof system

- Start with clauses of CNF formula (axioms)
- Derive new clauses by resolution rule

$$\frac{C_1 \vee x \qquad C_2 \vee \overline{x}}{C_1 \vee C_2}$$

Resolution Proofs by Contradction

Resolution rule:

$$\frac{C_1 \vee x \qquad C_2 \vee \overline{x}}{C_1 \vee C_2}$$

Observation

If F is a satisfiable CNF formula and D is derived from clauses $D_1,D_2\in F$ by the resolution rule, then $F\wedge D$ is satisfiable.

Resolution Proofs by Contradction

Resolution rule:

$$\frac{C_1 \vee x \quad C_2 \vee \overline{x}}{C_1 \vee C_2}$$

Observation

If F is a satisfiable CNF formula and D is derived from clauses $D_1, D_2 \in F$ by the resolution rule, then $F \wedge D$ is satisfiable.

So can prove F unsatisfiable by deriving the unsatisfiable empty clause (denoted \perp) from F by resolution

Resolution Proofs by Contradction

Resolution rule:

$$\frac{C_1 \vee x \quad C_2 \vee \overline{x}}{C_1 \vee C_2}$$

Observation

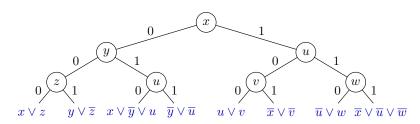
If F is a satisfiable CNF formula and D is derived from clauses $D_1, D_2 \in F$ by the resolution rule, then $F \wedge D$ is satisfiable.

So can prove F unsatisfiable by deriving the unsatisfiable empty clause (denoted \perp) from F by resolution

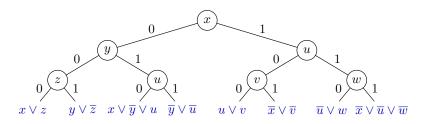
Such proof by contradiction also called resolution refutation

A DPLL execution is essentially a resolution proof

A DPLL execution is essentially a resolution proof Look at our example again

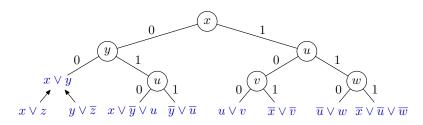


A DPLL execution is essentially a resolution proof Look at our example again



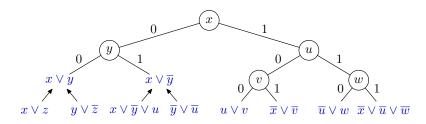
and apply resolution rule $\frac{C_1 \vee x - C_2 \vee \overline{x}}{C_1 \vee C_2}$ bottom-up

A DPLL execution is essentially a resolution proof Look at our example again



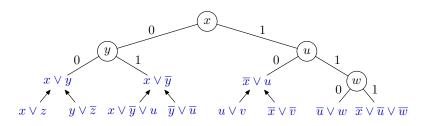
and apply resolution rule $\frac{C_1 \vee x - C_2 \vee \overline{x}}{C_1 \vee C_2}$ bottom-up

A DPLL execution is essentially a resolution proof Look at our example again



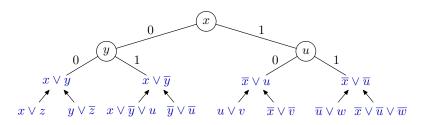
and apply resolution rule $\frac{C_1 \vee x \quad C_2 \vee \overline{x}}{C_1 \vee C_2}$ bottom-up

A DPLL execution is essentially a resolution proof Look at our example again



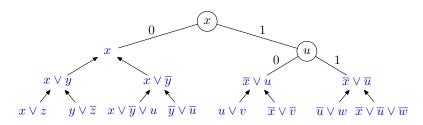
and apply resolution rule $\frac{C_1 \vee x - C_2 \vee \overline{x}}{C_1 \vee C_2}$ bottom-up

A DPLL execution is essentially a resolution proof Look at our example again



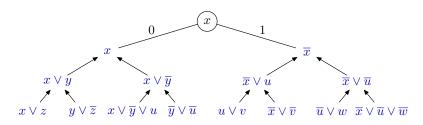
and apply resolution rule $\frac{C_1 \vee x \quad C_2 \vee \overline{x}}{C_1 \vee C_2}$ bottom-up

A DPLL execution is essentially a resolution proof Look at our example again



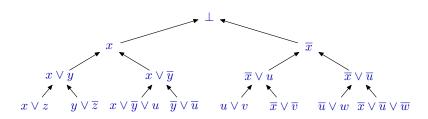
and apply resolution rule $\frac{C_1 \lor x \quad C_2 \lor \overline{x}}{C_1 \lor C_2}$ bottom-up

A DPLL execution is essentially a resolution proof Look at our example again



and apply resolution rule $\frac{C_1 \vee x \quad C_2 \vee \overline{x}}{C_1 \vee C_2}$ bottom-up

A DPLL execution is essentially a resolution proof Look at our example again



and apply resolution rule $\frac{C_1 \vee x \quad C_2 \vee \overline{x}}{C_1 \vee C_2}$ bottom-up

Intro to SAT Solving

• Can extract resolution proof from any DPLL execution

- Can extract resolution proof from any DPLL execution
- Requires an argument, of course, but not too hard to show

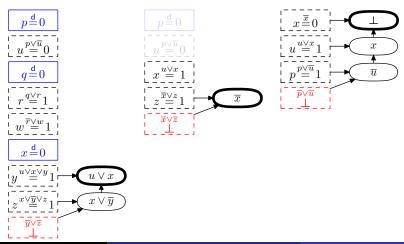
- Can extract resolution proof from any DPLL execution
- Requires an argument, of course, but not too hard to show
- Such proof is tree-like every derived clause used only once (to use a clause twice, we have to derive it twice from scratch)

- Can extract resolution proof from any DPLL execution
- Requires an argument, of course, but not too hard to show
- Such proof is tree-like every derived clause used only once (to use a clause twice, we have to derive it twice from scratch)
- Hence, lower bounds on tree-like proof size in resolution ⇒ lower bounds on DPLL running time

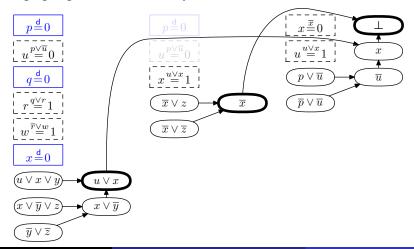
- Can extract resolution proof from any DPLL execution
- Requires an argument, of course, but not too hard to show
- Such proof is tree-like every derived clause used only once (to use a clause twice, we have to derive it twice from scratch)
- Hence, lower bounds on tree-like proof size in resolution ⇒ lower bounds on DPLL running time
- Conflict-driven clause learning adds "shortcut edges" in tree, but still yields resolution proof

Obtain resolution proof...

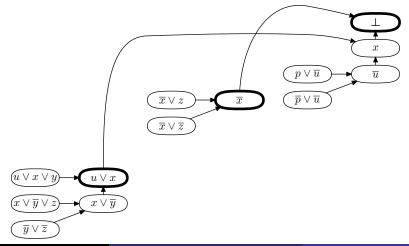
Obtain resolution proof from our example CDCL execution...



Obtain resolution proof from our example CDCL execution by stringing together conflict analyses:



Obtain resolution proof from our example CDCL execution by stringing together conflict analyses:



 Can extract general resolution proof (DAG-like, not tree-like) from CDCL execution

Intro to SAT Solving

- Can extract general resolution proof (DAG-like, not tree-like)
 from CDCL execution
- Again requires an argument, but you have seen enough in this lecture to be able to fill in the required details...

- Can extract general resolution proof (DAG-like, not tree-like)
 from CDCL execution
- Again requires an argument, but you have seen enough in this lecture to be able to fill in the required details...
- This holds even for CDCL solvers with sophisticated heuristics and optimizations that we have not discussed*

- Can extract general resolution proof (DAG-like, not tree-like)
 from CDCL execution
- Again requires an argument, but you have seen enough in this lecture to be able to fill in the required details...
- This holds even for CDCL solvers with sophisticated heuristics and optimizations that we have not discussed*
- Hence, lower bounds on resolution proof size ⇒ lower bounds on CDCL running time

- Can extract general resolution proof (DAG-like, not tree-like)
 from CDCL execution
- Again requires an argument, but you have seen enough in this lecture to be able to fill in the required details...
- This holds even for CDCL solvers with sophisticated heuristics and optimizations that we have not discussed*
- Hence, lower bounds on resolution proof size ⇒ lower bounds on CDCL running time
- Lower (and upper) bounds for different methods of reasoning about propositional logic formulas studied in proof complexity

- Can extract general resolution proof (DAG-like, not tree-like)
 from CDCL execution
- Again requires an argument, but you have seen enough in this lecture to be able to fill in the required details...
- This holds even for CDCL solvers with sophisticated heuristics and optimizations that we have not discussed*
- Hence, lower bounds on resolution proof size ⇒ lower bounds on CDCL running time
- Lower (and upper) bounds for different methods of reasoning about propositional logic formulas studied in proof complexity
- (*) Except for some preprocessing techniques, which is an important omission, but this gets complicated and we don't have time to go into details...

Current State of Affairs in SAT Solving

 State-of-the-art CDCL solvers often perform amazingly well ("SAT is easy in practice")

Intro to SAT Solving

Current State of Affairs in SAT Solving

- State-of-the-art CDCL solvers often perform amazingly well ("SAT is easy in practice")
- Very poor theoretical understanding:
 - Why do heuristics work?
 - Why are applied instances easy?

Current State of Affairs in SAT Solving

- State-of-the-art CDCL solvers often perform amazingly well ("SAT is easy in practice")
- Very poor theoretical understanding:
 - Why do heuristics work?
 - Why are applied instances easy?
- Paradox: resolution quite weak proof system; many strong proof complexity lower bounds for (seemingly) "obvious" formulas (e.g., [Hak85, Urq87, BW01])

Current State of Affairs in SAT Solving

- State-of-the-art CDCL solvers often perform amazingly well ("SAT is easy in practice")
- Very poor theoretical understanding:
 - Why do heuristics work?
 - Why are applied instances easy?
- Paradox: resolution quite weak proof system; many strong proof complexity lower bounds for (seemingly) "obvious" formulas (e.g., [Hak85, Urq87, BW01])
- See Chapter 7 on *Proof Complexity and SAT Solving* in the *Handbook of Satisfiability* for more details [BN21]

Theoretical Lower Bounds and Practical Reality

- If resolution so weak, how can CDCL SAT solvers be so good?
- One answer: "tricky" formulas don't show up too often in practice
- Another area of intense research: Try to describe what properties of "real-life" formulas make them easy or hard

Theoretical Lower Bounds and Practical Reality

- If resolution so weak, how can CDCL SAT solvers be so good?
- One answer: "tricky" formulas don't show up too often in practice
- Another area of intense research: Try to describe what properties of "real-life" formulas make them easy or hard
- But sometimes we would like to be able to solve also "tricky" formulas
- Can we go beyond resolution?

Theoretical Lower Bounds and Practical Reality

- If resolution so weak, how can CDCL SAT solvers be so good?
- One answer: "tricky" formulas don't show up too often in practice
- Another area of intense research: Try to describe what properties of "real-life" formulas make them easy or hard
- But sometimes we would like to be able to solve also "tricky" formulas
- Can we go beyond resolution?
- Explore stronger methods of reasoning!
- Algorithms based on such methods could potentially lead to exponential speed-ups [stay tuned for next lecture...]

So... Is There a Smarter Way Than Brute-Force?

In theory, probably no...

- COLOURING, CLIQUE, SAT, and 1000s other problems are "all the same" — efficient algorithm for one can solve all (the problems are all NP-complete)
- Widely believed impossible to construct algorithms that are always (a) efficient and (b) correct (even in worst case)
- Settling this question is one of Millennium Prize Problems: Are there efficient algorithms for NP-complete problems?

So... Is There a Smarter Way Than Brute-Force?

In theory, probably no...

- COLOURING, CLIQUE, SAT, and 1000s other problems are "all the same" — efficient algorithm for one can solve all (the problems are all NP-complete)
- Widely believed impossible to construct algorithms that are always (a) efficient and (b) correct (even in worst case)
- Settling this question is one of Millennium Prize Problems: Are there efficient algorithms for NP-complete problems?

In practice, definitely yes!

- Real-world problems are usually not "worst-case" but highly structured
- Fairly simple (but clever) methods work amazingly well amazingly often (though we don't really understand why)

So... Is There a Smarter Way Than Brute-Force?

In theory, probably no...

- COLOURING, CLIQUE, SAT, and 1000s other problems are "all the same" — efficient algorithm for one can solve all (the problems are all NP-complete)
- Widely believed impossible to construct algorithms that are always (a) efficient and (b) correct (even in worst case)
- Settling this question is one of Millennium Prize Problems: Are there efficient algorithms for NP-complete problems?

In practice, definitely yes!

- Real-world problems are usually not "worst-case" but highly structured
- Fairly simple (but clever) methods work amazingly well amazingly often (though we don't really understand why)

Stark disconnect between theory and practice. . .

Research Goals in the MIAO Group (1/2)

Strengthen the mathematical analysis of algorithmic methods

- Study methods of reasoning powerful enough to capture state-of-the-art algorithms used in practice
- Prove theorems about their power and limitations
- E.g., resolution proof system captures CDCL reasoning

Research Goals in the MIAO Group (1/2)

Strengthen the mathematical analysis of algorithmic methods

- Study methods of reasoning powerful enough to capture state-of-the-art algorithms used in practice
- Prove theorems about their power and limitations
- E.g., resolution proof system captures CDCL reasoning

Construct stronger algorithms for combinatorial problems

- ullet Use insights into stronger mathematical methods of reasoning to build algorithms for SAT and other combinatorial problems
- Aiming for exponential speed-ups over state of the art
- E.g., use cutting planes to build pseudo-Boolean solvers

Research Goals in the MIAO Group (2/2)

Improve understanding of efficient computation in practice

- Use computational complexity theory to study "real-world" (not worst-case) problems
- Combine theoretical study and empirical experiments
- E.g., take "crafted formulas" with provable theoretical properties and investigate correlation with practical solver performance

Research Goals in the MIAO Group (2/2)

Improve understanding of efficient computation in practice

- Use computational complexity theory to study "real-world" (not worst-case) problems
- Combine theoretical study and empirical experiments
- E.g., take "crafted formulas" with provable theoretical properties and investigate correlation with practical solver performance

Certify correctness for modern combinatorial solvers

- In many combinatorial optimization paradigms, state-of-the-art solvers are known to be buggy
- Develop methods to make solvers output not just answer but machine-verifiable proof of correctness of this answer

Some References for Further Reading

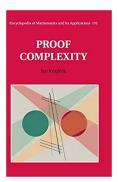
Handbook of Satisfiability

(Especially chapter 7 ©)



[BHvMW21]

Proof Complexity by Jan Krajíček



[Kra19]

And survey papers, slides, and videos at www.jakobnordstrom.se

Take-Home Message

- Modern SAT solvers, although based on old and simple DPLL method, can be enormously efficient in practice
- SAT solving more of an art form than a science theoretical understanding lagging far behind
- Can use proof complexity to analyze potential and limitations of SAT solvers
- And to get inspirations for algorithms based on stronger methods of reasoning
- Lots of challenging work for PhD students and postdocs (we're hiring!)

Take-Home Message

- Modern SAT solvers, although based on old and simple DPLL method, can be enormously efficient in practice
- SAT solving more of an art form than a science theoretical understanding lagging far behind
- Can use proof complexity to analyze potential and limitations of SAT solvers
- And to get inspirations for algorithms based on stronger methods of reasoning
- Lots of challenging work for PhD students and postdocs (we're hiring!)

Thanks for listening!

References I

- [AS09] Gilles Audemard and Laurent Simon. Predicting learnt clauses quality in modern SAT solvers. In *Proceedings of the 21st International Joint Conference on Artificial Intelligence (IJCAI '09)*, pages 399–404, July 2009.
- [AS12] Gilles Audemard and Laurent Simon. Refining restarts strategies for SAT and UNSAT. In Proceedings of the 18th International Conference on Principles and Practice of Constraint Programming (CP '12), volume 7514 of Lecture Notes in Computer Science, pages 118–126. Springer, October 2012.
- [BHvMW21] Armin Biere, Marijn J. H. Heule, Hans van Maaren, and Toby Walsh, editors. Handbook of Satisfiability, volume 336 of Frontiers in Artificial Intelligence and Applications. IOS Press, 2nd edition, February 2021.
- [BN21] Samuel R. Buss and Jakob Nordström. Proof complexity and SAT solving. In Biere et al. [BHvMW21], chapter 7, pages 233–350.
- [BW01] Eli Ben-Sasson and Avi Wigderson. Short proofs are narrow—resolution made simple. *Journal of the ACM*, 48(2):149–169, March 2001. Preliminary version in *STOC '99*.

References II

[Coo71]	Stephen A. Cook. The complexity of theorem-proving procedures. In
	Proceedings of the 3rd Annual ACM Symposium on Theory of Computing
	(STOC '71), pages 151–158, May 1971.

- [DLL62] Martin Davis, George Logemann, and Donald Loveland. A machine program for theorem proving. Communications of the ACM, 5(7):394–397, July 1962.
- [DP60] Martin Davis and Hilary Putnam. A computing procedure for quantification theory. Journal of the ACM, 7(3):201–215, 1960.
- [EGG⁺18] Jan Elffers, Jesús Giráldez-Cru, Stephan Gocht, Jakob Nordström, and Laurent Simon. Seeking practical CDCL insights from theoretical SAT benchmarks. In Proceedings of the 27th International Joint Conference on Artificial Intelligence (IJCAI '18), pages 1300–1308, July 2018.
- [Hak85] Armin Haken. The intractability of resolution. *Theoretical Computer Science*, 39(2-3):297–308, August 1985.

References III

- [KN20] Janne I. Kokkala and Jakob Nordström. Using resolution proofs to analyse CDCL solvers. In Proceedings of the 26th International Conference on Principles and Practice of Constraint Programming (CP '20), volume 12333 of Lecture Notes in Computer Science, pages 427–444. Springer, September 2020.
- [Kra19] Jan Krajíček. Proof Complexity, volume 170 of Encyclopedia of Mathematics and Its Applications. Cambridge University Press, March 2019.
- [Lev73] Leonid A. Levin. Universal sequential search problems. Problemy peredachi informatsii, 9(3):115–116, 1973. In Russian. Available at http://mi.mathnet.ru/ppi914.
- [MMZ+01] Matthew W. Moskewicz, Conor F. Madigan, Ying Zhao, Lintao Zhang, and Sharad Malik. Chaff: Engineering an efficient SAT solver. In *Proceedings of the 38th Design Automation Conference (DAC '01)*, pages 530–535, June 2001.
- [MS99] João P. Marques-Silva and Karem A. Sakallah. GRASP: A search algorithm for propositional satisfiability. *IEEE Transactions on Computers*, 48(5):506–521, May 1999. Preliminary version in *ICCAD '96*.

References IV

[PD07] Knot Pipatsrisawat and Adnan Darwiche. A lightweight component caching scheme for satisfiability solvers. In Proceedings of the 10th International Conference on Theory and Applications of Satisfiability Testing (SAT '07), volume 4501 of Lecture Notes in Computer Science, pages 294–299. Springer, May 2007.

[Urq87] Alasdair Urquhart. Hard examples for resolution. *Journal of the ACM*, 34(1):209–219, January 1987.