

LICS 2021 Lecture 11: Boolean Satisfiability (SAT) Solving

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January 6, 2022

Three Simple Problems. . .

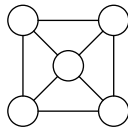
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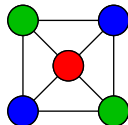


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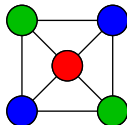


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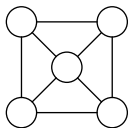
3-colouring? Yes, but no 2-colouring

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Is there a **clique** in graph $G = (V, E)$ with k vertices that are all pairwise connected?

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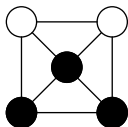


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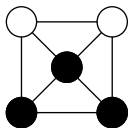


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- Variables should be set to **true** or **false**
- Constraint $(x \vee \neg y \vee z)$: means x or z should be true or y false
- \wedge means all constraints should hold simultaneously
- Is there a truth value assignment satisfying all constraints?

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COLOURING: frequency allocation for mobile base stations

CLIQUE: bioinformatics, computational chemistry

SAT: easily models these and many other problems

...with Huge Practical Implications

- Some more examples of problems that can be encoded as propositional logic formulas:
 - computer hardware verification
 - computer software testing
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 - cryptography
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 - et cetera...

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- Topic of intense research in computer science ever since 1960s

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 - It's 2022 now — can we go beyond techniques from 1960s?

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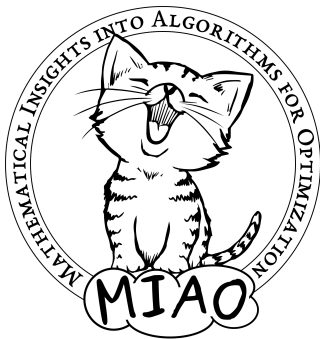
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... And in the process also touch on some of the research being done in the *Mathematical Insights into Algorithms for Optimization (MIAO)* group



Formal Description of SAT Problem

- **Variable** x : takes value 1 (**true**) or 0 (**false**)
- **Literal** ℓ : variable x or its negation \bar{x} (write \bar{x} instead of $\neg x$)
- **Clause** $C = \ell_1 \vee \dots \vee \ell_k$: disjunction of literals
(Consider as sets, so no repetitions and order irrelevant)
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For instance, what about our example formula?

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To understand how large this number is, consider that even if every atom in the known universe was a modern supercomputer that had been running at full speed ever since the beginning of time some 13.7 billion years ago, all of them together would only have covered a completely negligible fraction of these cases by now. So we really would not have time to wait for them to finish. . .

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- The family of problems for which solutions are easy to check have a name: **NP**

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- Widely believe to be impossible to solve efficiently on computer in the worst case, but we really don't know

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Ok, but suppose you're out there in reality and actually have to solve the problem — then what do you do?

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- Set $x = 0$, simplify F and **make recursive call**
- Set $x = 1$, simplify F and **make recursive call**
- If result in both cases **“unsatisfiable”**, then report **“unsatisfiable”** and return

A DPLL Toy Example

$$\begin{aligned} F = & (x \vee z) \wedge (y \vee \bar{z}) \wedge (x \vee \bar{y} \vee u) \wedge (\bar{y} \vee \bar{u}) \\ & \wedge (u \vee v) \wedge (\bar{x} \vee \bar{v}) \wedge (\bar{u} \vee w) \wedge (\bar{x} \vee \bar{u} \vee \bar{w}) \end{aligned}$$

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Pick variables in internal nodes; terminate in leaves when falsified clause found (i.e., when conflict reached)

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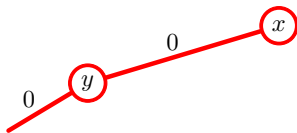
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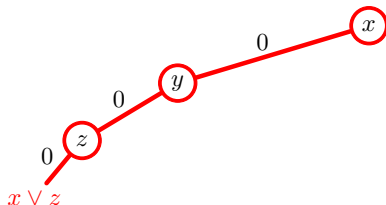
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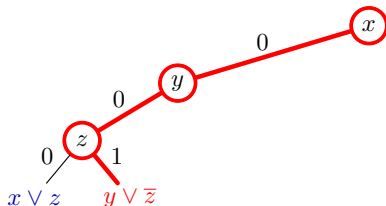
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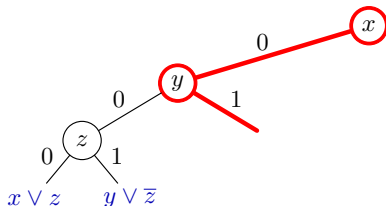
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- satisfied clauses
- falsified literals



A DPLL Toy Example

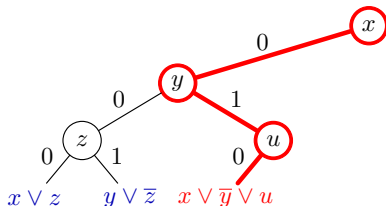
$$F = (z) \wedge (y \vee \bar{z}) \wedge (x \vee \bar{y} \vee u) \wedge (\bar{u}) \\ \wedge (v) \wedge (\bar{x} \vee \bar{v}) \wedge (\bar{u} \vee w) \wedge (\bar{x} \vee \bar{u} \vee \bar{w})$$

Visualize execution of DPLL algorithm as search tree

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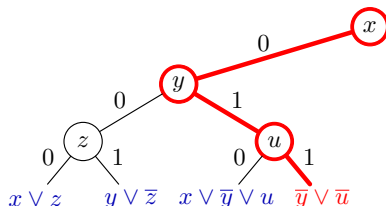
$$F = (z \wedge (y \vee \bar{z}) \wedge (u \wedge (\bar{y} \vee \bar{u}) \wedge (u \vee v) \wedge (\bar{x} \vee \bar{v}) \wedge (w) \wedge (\bar{x} \vee \bar{w}))$$

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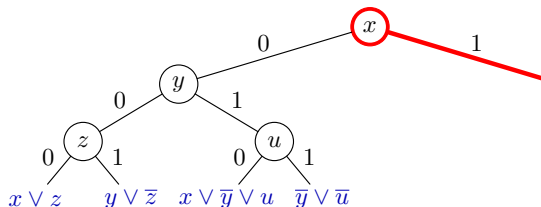
$$F = (x \vee z) \wedge (y \vee \bar{z}) \wedge (x \vee \bar{y} \vee u) \wedge (\bar{y} \vee \bar{u}) \\ \wedge (u \vee v) \wedge (\bar{v}) \wedge (\bar{u} \vee w) \wedge (\bar{u} \vee \bar{w})$$

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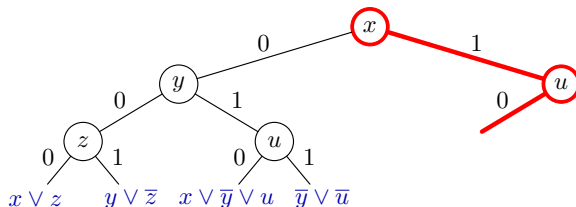
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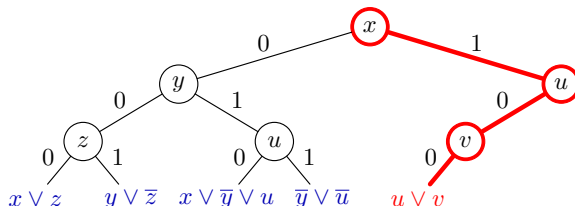
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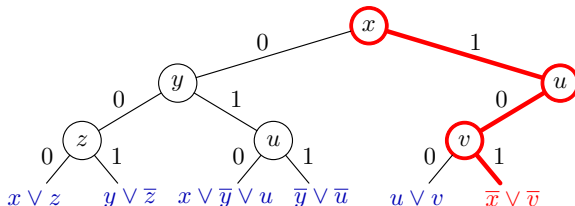
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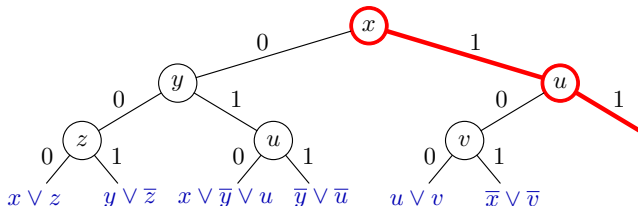
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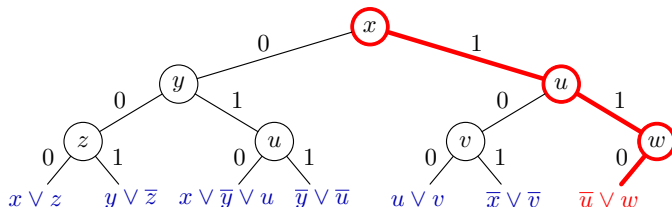
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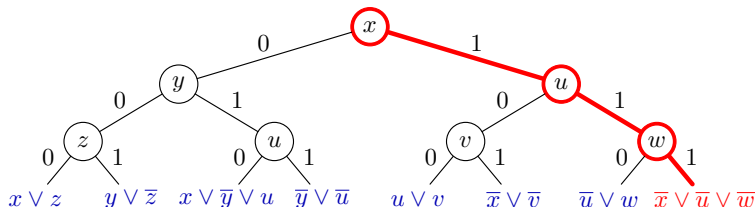
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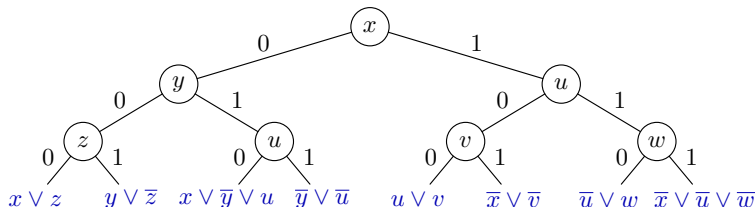
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State-of-the-art SAT solvers: Ingredients

Many more ingredients in modern **conflict-driven clause learning (CDCL)** SAT solvers (as pioneered in [MS99, MMZ⁺01]), e.g.:

- **Branching** or **decision heuristic** (choice of pivot variables crucial)
- When reaching leaf, **compute explanation for conflict** and **add to formula** as new clause (**clause learning**)
- Every once in a while, **restart** from beginning (but save computed info)

Let us discuss these ingredients

Variable Assignment Heuristics

Unit propagation

- Suppose current assignment ρ falsifies all literals in $C = \ell_1 \vee \ell_2 \vee \dots \vee \ell_k$ except one (say ℓ_k) — C is **unit under ρ**
- Then ℓ_k has to be true, so set it to true
- Known as **unit propagation** or **Boolean constraint propagation**
- Always propagate if possible — in modern solvers aim for 99% of assignments being unit propagations

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VSIDS (Variable state independent decaying sum)

- When backtracking, score $+1$ for variables “causing conflict”
- Also multiply all scores with factor $\kappa < 1$ — exponential filter rewarding variables involved in recent conflicts
- When no propagations, **decide** on variable with highest score

Clause Learning

- At conflict, want to add clause avoiding same part of search tree being explored again

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- In practice, more advanced learning schemes

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- In practice, more advanced learning schemes
- Derive new clause from clauses unit propagating on the way to conflict

Decisions, Unit Propagations, and Conflict

Two kinds of assignments — illustrate on example formula:

$$(p \vee \bar{u}) \wedge (q \vee r) \wedge (\bar{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \bar{y} \vee z) \wedge (\bar{x} \vee z) \wedge (\bar{y} \vee \bar{z}) \wedge (\bar{x} \vee \bar{z}) \wedge (\bar{p} \vee \bar{u})$$

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Free choice to assign value to variable

Notation $p \stackrel{d}{=} 0$

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Until satisfying assignment or **conflict**

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Decision

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$$z \stackrel{x \vee \bar{y} \vee z}{=} 1$$

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$$\perp$$

Decision

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$$p \stackrel{d}{=} 0$$

decision
level 1

Decision

Free choice to assign value to variable

$$u \stackrel{p \vee \bar{u}}{=} 0$$

Notation $p \stackrel{d}{=} 0$

$$q \stackrel{d}{=} 0$$

decision
level 2

Unit propagation

Forced choice to avoid falsifying clause

Given $p = 0$, clause $p \vee \bar{u}$ forces $u = 0$

$$r \stackrel{q \vee r}{=} 1$$

$$w \stackrel{\bar{r} \vee w}{=} 1$$

$$x \stackrel{d}{=} 0$$

Notation $u \stackrel{p \vee \bar{u}}{=} 0$ ($p \vee \bar{u}$ is **reason clause**)

$$y \stackrel{u \vee x \vee y}{=} 1$$

decision
level 3

Always propagate if possible, else decide

Add to assignment **trail**

Until satisfying assignment or **conflict**

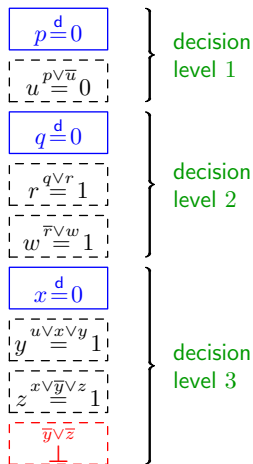
$$z \stackrel{x \vee \bar{y} \vee z}{=} 1$$

$$\bar{y} \vee \bar{z}$$

Conflict Analysis

Time to analyse this conflict and learn from it!

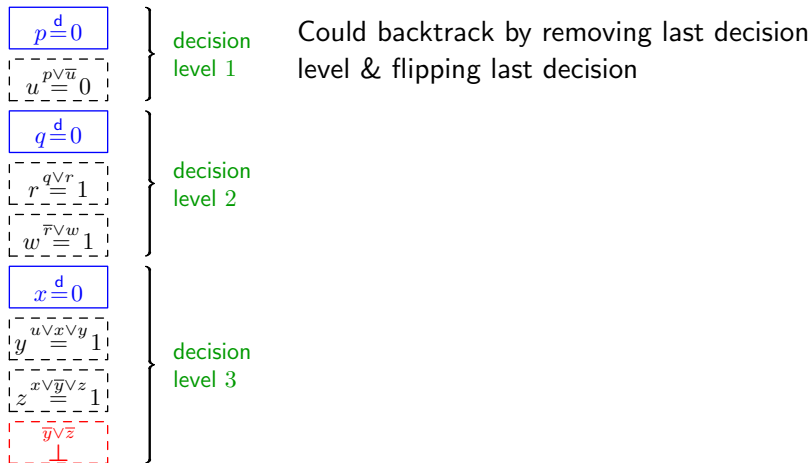
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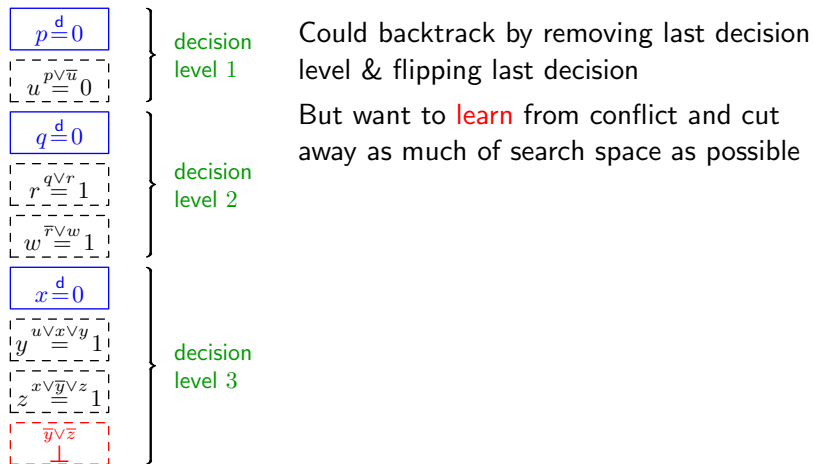
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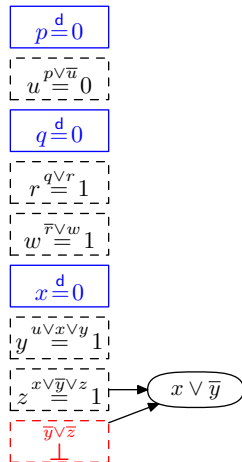
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Could backtrack by removing last decision level & flipping last decision

But want to **learn** from conflict and cut away as much of search space as possible

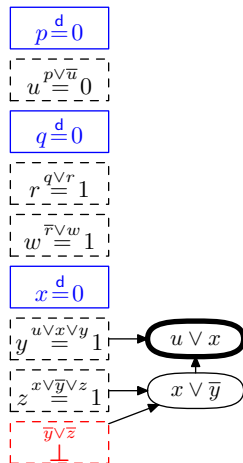
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- $x \vee \bar{y} \vee z$ wants $z = 1$
- $\bar{y} \vee \bar{z}$ wants $z = 0$
- **Resolve** clauses by merging them & removing z — must satisfy $x \vee \bar{y}$

Conflict Analysis

Time to analyse this conflict and learn from it!

$$(p \vee \bar{u}) \wedge (q \vee r) \wedge (\bar{r} \vee w) \wedge (u \vee x \vee y) \wedge (x \vee \bar{y} \vee z) \wedge (\bar{x} \vee z) \wedge (\bar{y} \vee \bar{z}) \wedge (\bar{x} \vee \bar{z}) \wedge (\bar{p} \vee \bar{u})$$



Could backtrack by removing last decision level & flipping last decision

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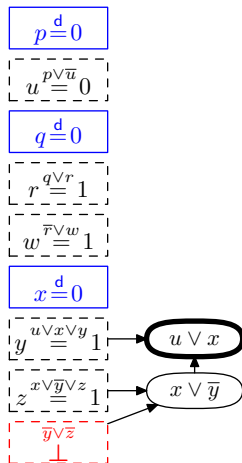
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Repeat until **UIP clause** with only 1 variable after last decision — **learn** and **backjump**

Complete Example of CDCL Execution

Backjump: undo max #decisions while learned clause propagates

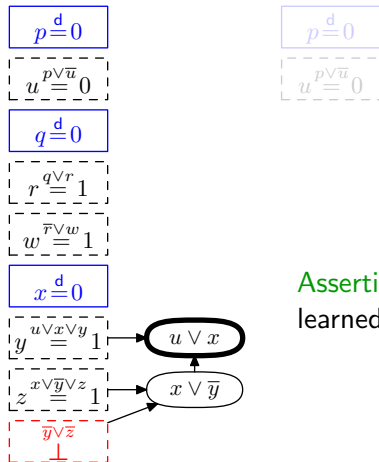
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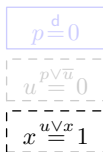
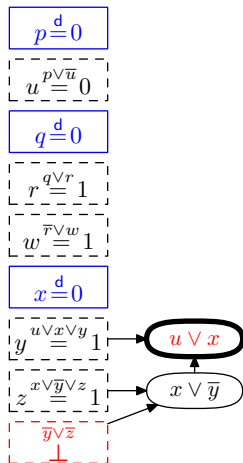


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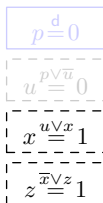
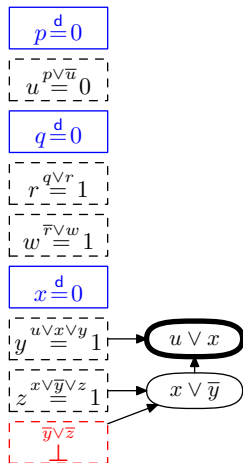


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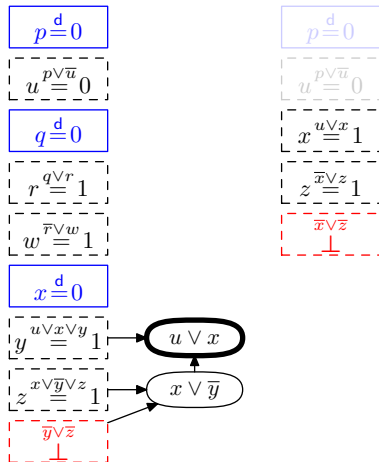
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Then continue as before. . .

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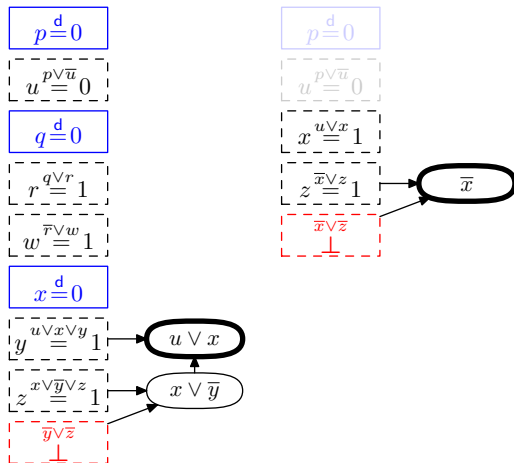
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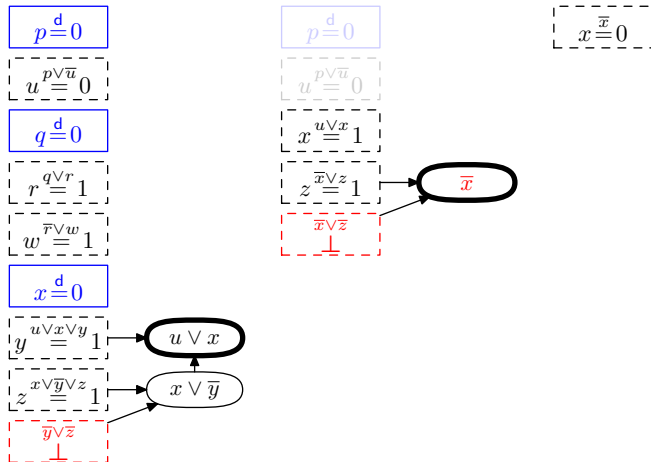
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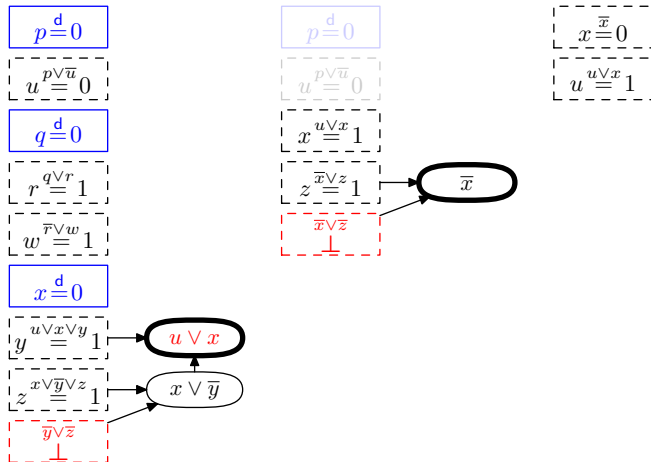
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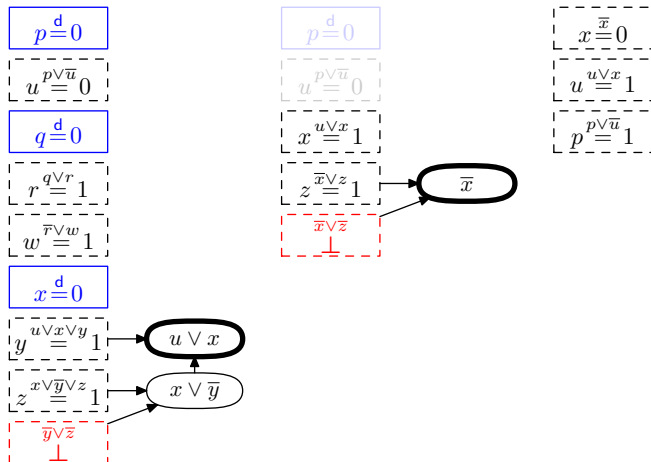
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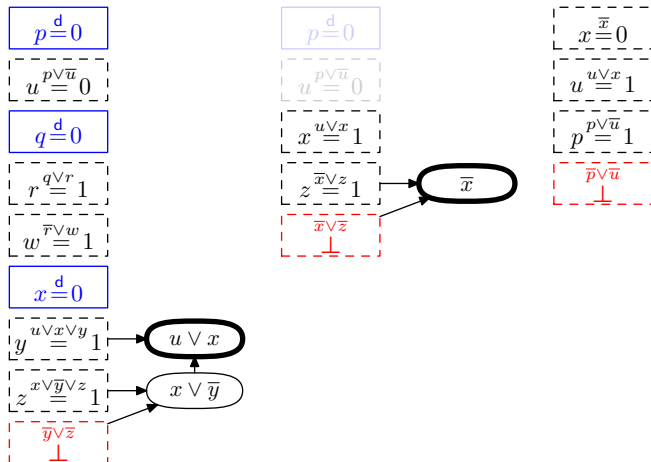
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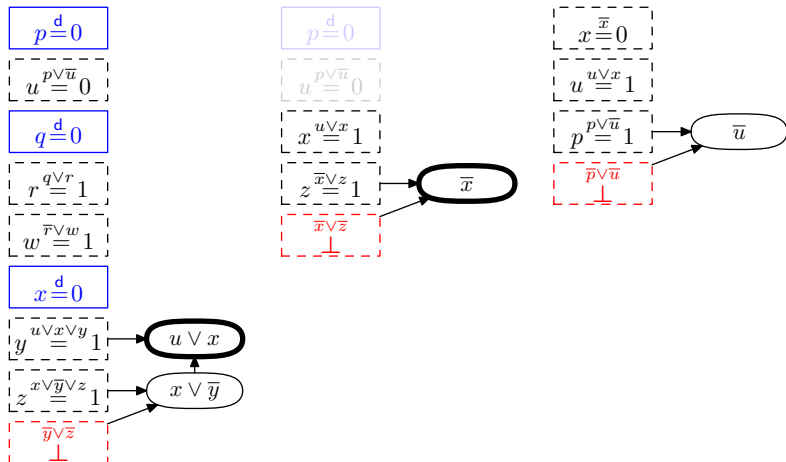
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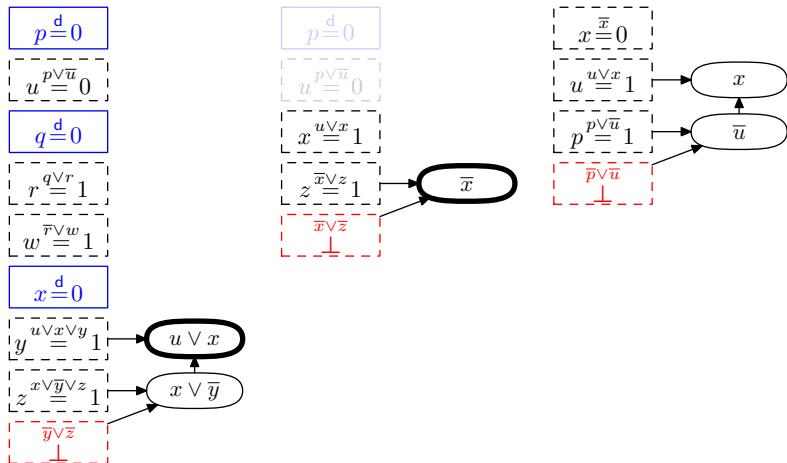
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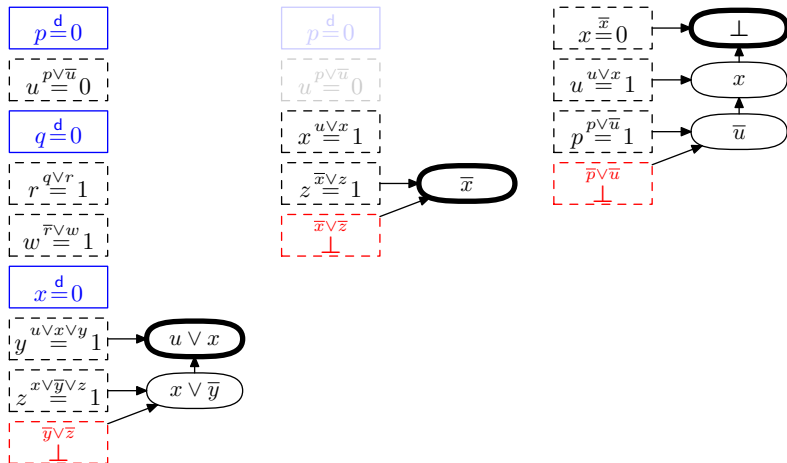
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Clause Database Reduction

- In addition to learning clauses, also **erase learned clauses that don't seem useful**
- Modern solvers do this **very aggressively**
- Speeds up CDCL search (in particular, unit propagation, which dominates running time)
- But erasing too aggressively can throw away clauses that would have made solver terminate faster [EGG⁺18]
- So **trade-off** between **search speed** and **search quality**
- Except sometimes getting rid of clauses improves search quality too! [KN20]

Restarts

- Fairly frequently, **start search all over** (but keep learned clauses)
- Original intuition: stuck in bad part of search tree — go somewhere else
- Not the reason this is done now
- Popular variables with high VSIDS scores get set again [MMZ⁺01]
- Are even set to same values (**phase saving**) [PD07]
- Current intuition: improves the search by focusing on important variables
- Restart at fixed intervals or (better) make **adaptive restarts** depending on “quality” of learned clauses [AS09, AS12]

CDCL Main Loop Pseudocode

Algorithm 1: CDCL(F)

```

1  $\mathcal{D} \leftarrow F$  ; // initialize clause database to contain formula
2  $\rho \leftarrow \emptyset$  ; // initialize assignment trail to empty
3 forever do
4   if  $\rho$  falsifies some clause  $C \in \mathcal{D}$  then
5      $A \leftarrow \text{ConflictAnalysis}(\mathcal{D}, \rho, C)$  ;
6     if  $A = \perp$  then output UNSATISFIABLE and exit;
7     else
8        $\perp$  add  $A$  to  $\mathcal{D}$  and backjump by shrinking  $\rho$  ;
9   else if exists clause  $C \in \mathcal{D}$  unit propagating  $x$  to  $b \in \{0, 1\}$  under  $\rho$  then
10    add propagated assignment  $x \stackrel{D}{=} b$  to  $\rho$  ;
11   else if time to restart then  $\rho \leftarrow \emptyset$  ;
12   else if time for clause database reduction then
13    erase (roughly) half of learned clauses in  $\mathcal{D} \setminus F$  from  $\mathcal{D}$ 
14   else if all variables assigned then output SATISFIABLE and exit;
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Conflict Analysis Pseudocode

Algorithm 2: ConflictAnalysis($\mathcal{D}, \rho, C_{\text{confl}}$)

```

1  $C_{\text{learn}} \leftarrow C_{\text{confl}}$  ;
2 while  $C_{\text{learn}}$  not UIP clause and  $C_{\text{learn}} \neq \perp$  do
3    $\ell \leftarrow$  literal assigned last on trail  $\rho$ ;
4   if  $\ell$  propagated and  $\bar{\ell}$  occurs in  $C_{\text{learn}}$  then
5      $C_{\text{reason}} \leftarrow \text{reason}(\ell, \rho, \mathcal{D})$ ;
6      $C_{\text{learn}} \leftarrow \text{resolve}(C_{\text{learn}}, C_{\text{reason}})$ ;
7    $\rho \leftarrow \rho \setminus \{\ell\}$ ;
8 return  $C_{\text{learn}}$ ;

```

State-of-the-art SAT solvers: What About the Recipe?

List of ingredients again (not exhaustive):

- Variable decisions & propagations
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- Restarts
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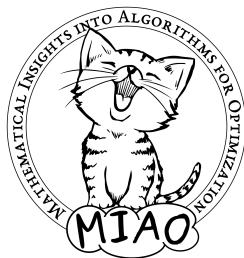
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Why SAT solvers actually work so well
is a poorly understood question

Lots of research to comprehend this better
(Among other places in the MIAO group)



SAT Solver Analysis and the Resolution Proof System

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Many intricate, hard-to-understand heuristics

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Resolution proof system

- Start with clauses of CNF formula (**axioms**)
- Derive new clauses by **resolution rule**

$$\frac{C_1 \vee x \quad C_2 \vee \bar{x}}{C_1 \vee C_2}$$

Resolution Proofs by Contradiction

Resolution rule:

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If F is a satisfiable CNF formula and D is derived from clauses $D_1, D_2 \in F$ by the resolution rule, then $F \wedge D$ is satisfiable.

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Such proof by contradiction also called **resolution refutation**

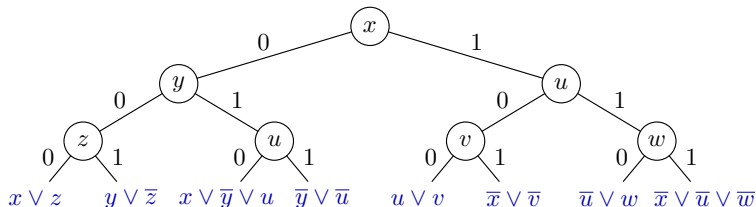
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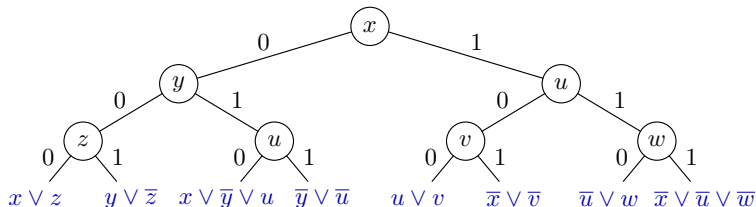
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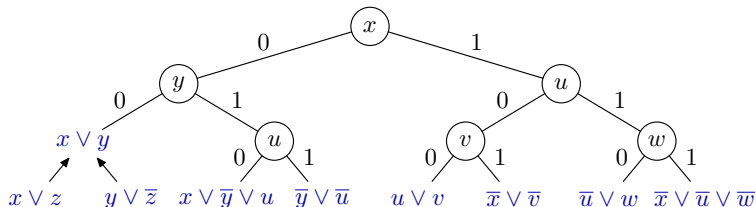


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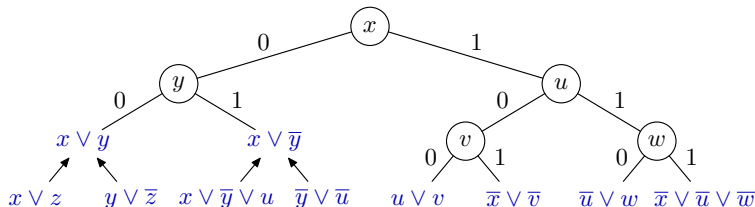


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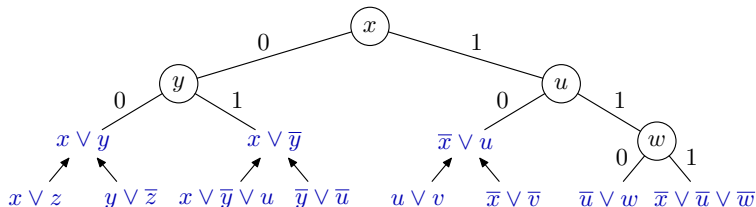


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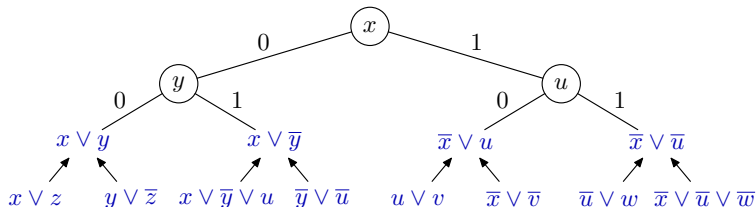


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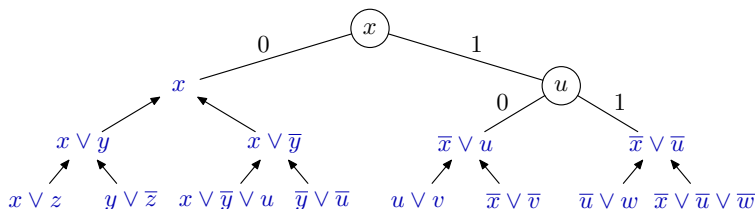


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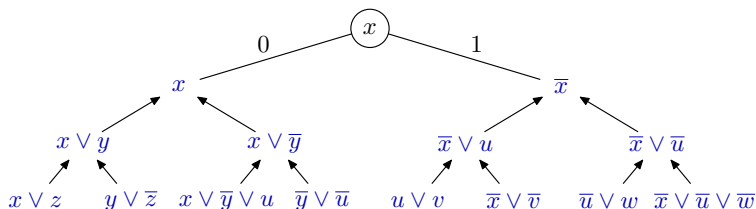


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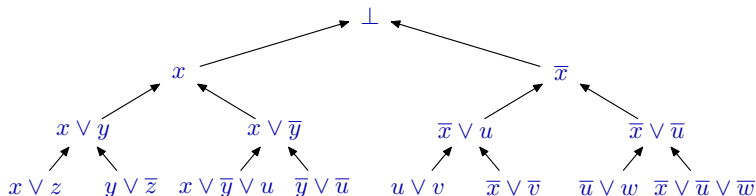


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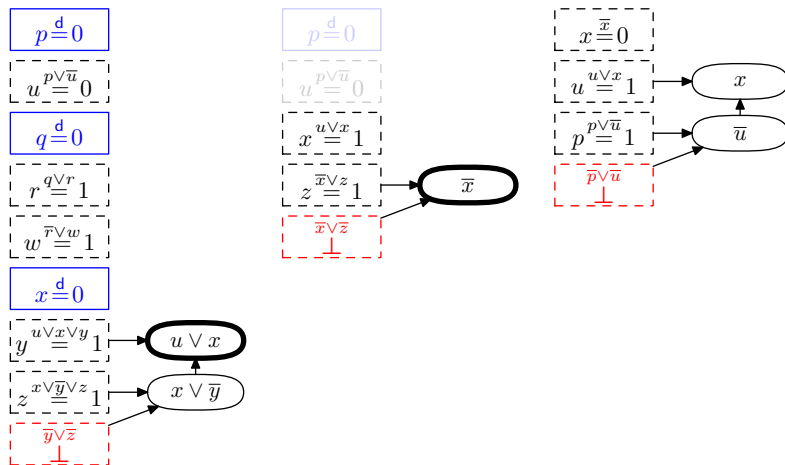
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- Conflict-driven clause learning adds “shortcut edges” in tree, but still yields resolution proof

CDCL and Resolution Proofs

Obtain resolution proof. . .

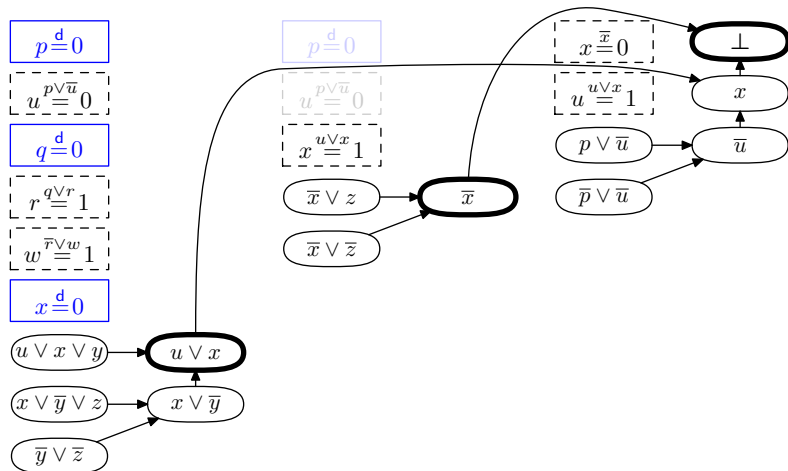
CDCL and Resolution Proofs

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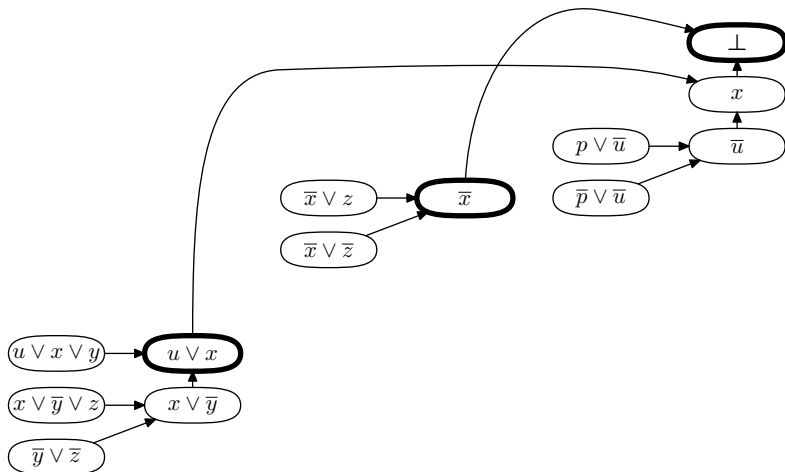
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Obtain resolution proof from our example CDCL execution by stringing together conflict analyses:



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- Hence, **lower bounds on resolution proof size** \Rightarrow lower bounds on **CDCL running time**
- Lower (and upper) bounds for different methods of reasoning about propositional logic formulas studied in **proof complexity**

CDCL Running Time and General Resolution Proof Size

- Can extract general resolution proof (DAG-like, not tree-like) from CDCL execution
- Again requires an argument, but you have seen enough in this lecture to be able to fill in the required details. . .
- This holds even for CDCL solvers with sophisticated heuristics and optimizations that we have not discussed*
- Hence, **lower bounds on resolution proof size** \Rightarrow lower bounds on **CDCL running time**
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(*) Except for some **preprocessing techniques**, which is an important omission, but this gets complicated and we don't have time to go into details. . .

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 - Why are applied instances easy?
- Paradox: resolution quite weak proof system; many strong proof complexity lower bounds for (seemingly) “obvious” formulas

Examples of Hard Formulas For Resolution (1/3)

Pigeonhole principle (PHP) formulas [Hak85]

“ $n + 1$ pigeons don't fit into n holes”

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$$p_{i,1} \vee p_{i,2} \vee \cdots \vee p_{i,n}$$

every pigeon i gets a hole

$$\bar{p}_{i,j} \vee \bar{p}_{i',j}$$

no hole j gets two pigeons $i \neq i'$

Can also add “functionality” and “onto” axioms

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Even onto functional PHP hard — **“resolution cannot count”**

Resolution proof requires $\exp(\Omega(n)) = \exp(\Omega(\sqrt[3]{N}))$ clauses
 (measured in terms of formula size N)

Examples of Hard Formulas For Resolution (2/3)

Tseitin formulas [Urq87]

“Sum of degrees of vertices in graph is even”

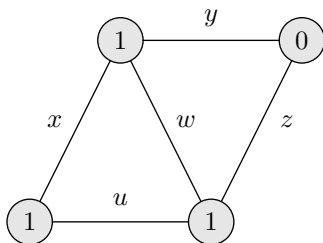
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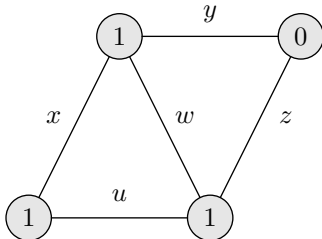
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$$\begin{array}{ll}
 (u \vee x) & \wedge (y \vee \bar{z}) \\
 \wedge (\bar{u} \vee \bar{x}) & \wedge (\bar{y} \vee z) \\
 \wedge (w \vee x \vee y) & \wedge (u \vee w \vee z) \\
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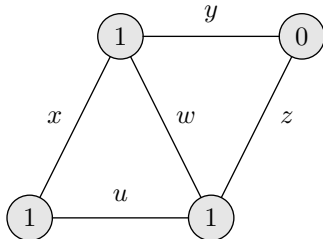
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 \end{aligned}$$

Requires **proof size** $\exp(\Omega(N))$ on well-connected so-called **expander graphs** — **“resolution cannot count mod 2”**

Examples of Hard Formulas for Resolution (3/3)

Random k -CNF formulas [CS88]

Δn randomly sampled k -clauses over n variables

($\Delta \gtrsim 4.5$ sufficient to get unsatisfiable 3-CNF almost surely)

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And more...

- COLOURING [BCMM05]
- CLIQUE and VERTEXCOVER [BIS07]
- Zero-one designs [Spe10, VS10, MN14]
- Et cetera... (See, e.g., [BN21] for overview)

Theoretical Lower Bounds and Practical Reality

- If resolution so weak, how can CDCL SAT solvers be so good?
- One answer: this kind of “tricky” formulas don’t show up too often in practice
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- Can we go beyond resolution?
- Explore **stronger methods of reasoning!**
- Algorithms based on such methods could potentially lead to **exponential speed-ups**

Cutting Planes Proof System

Introduced in [CCT87] to model integer linear programming algorithm in [Gom63, Chv73]

Clauses translated to **linear inequalities** over the reals with **integer coefficients**

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Derivation rules

<p>Variable axioms $\frac{}{0 \leq x \leq 1}$</p>	<p>Multiplication $\frac{\sum a_i x_i \geq A}{\sum c a_i x_i \geq cA}$</p>
<p>Addition $\frac{\sum a_i x_i \geq A \quad \sum b_i x_i \geq B}{\sum (a_i + b_i) x_i \geq A + B}$</p>	<p>Division $\frac{\sum c a_i x_i \geq A}{\sum a_i x_i \geq \lceil A/c \rceil}$</p>

Cutting Planes Refutation of CNF Formula

- Translate CNF formula to set of 0-1 linear inequalities
- Apply derivation rules
- Derive $0 \geq 1 \Leftrightarrow$ formula unsatisfiable
- Also makes sense for more general 0-1 linear inequalities (not just translations of CNF formulas)

Cutting Planes vs. Resolution

- Cutting planes can simulate resolution reasoning efficiently and is sometimes exponentially stronger (e.g., for PHP, just count to see $\#pigeons > \#holes$)

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- And **0-1 linear inequalities much more concise** than CNF

Compare

$$x_1 + x_2 + x_3 + x_4 + x_5 + x_6 \geq 3$$

and

$$\begin{aligned} & (x_1 \vee x_2 \vee x_3 \vee x_4) \wedge (x_1 \vee x_2 \vee x_3 \vee x_5) \wedge (x_1 \vee x_2 \vee x_3 \vee x_6) \\ & \wedge (x_1 \vee x_2 \vee x_4 \vee x_5) \wedge (x_1 \vee x_2 \vee x_4 \vee x_6) \wedge (x_1 \vee x_2 \vee x_5 \vee x_6) \\ & \wedge (x_1 \vee x_3 \vee x_4 \vee x_5) \wedge (x_1 \vee x_3 \vee x_4 \vee x_6) \wedge (x_1 \vee x_3 \vee x_5 \vee x_6) \\ & \wedge (x_1 \vee x_4 \vee x_5 \vee x_6) \wedge (x_2 \vee x_3 \vee x_4 \vee x_5) \wedge (x_2 \vee x_3 \vee x_4 \vee x_6) \\ & \wedge (x_2 \vee x_3 \vee x_5 \vee x_6) \wedge (x_2 \vee x_4 \vee x_5 \vee x_6) \wedge (x_3 \vee x_4 \vee x_5 \vee x_6) \end{aligned}$$

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- Construct **more efficient SAT solvers** using **cutting planes**?

SAT Solvers Based on Cutting Planes?

So-called **pseudo-Boolean solvers** using (subset of) cutting planes reasoning developed in, e.g., [CK05, LP10, EN18]

Counter-intuitively, **hard to make competitive with CDCL**

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Is it truly harder to build good pseudo-Boolean solvers?

Or has just so much more work has been put into CDCL solvers?

So... Is There a Smarter Way Than Brute-Force?

In theory, probably no...

- COLOURING, CLIQUE, SAT, and 1000s other problems are “all the same” — efficient algorithm for one can solve all (the problems are all **NP-complete**)
- Widely believed impossible to construct algorithms that are always (a) efficient and (b) correct (even in **worst case**)
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Stark disconnect between theory and practice...

Research Goals in the MIAO Group (1/2)

Strengthen the mathematical analysis of algorithmic methods

- Study methods of reasoning powerful enough to capture state-of-the-art algorithms used in practice
- Prove theorems about their power and limitations
- E.g., resolution proof system captures CDCL reasoning

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Construct stronger algorithms for combinatorial problems

- Use insights into stronger mathematical methods of reasoning to build algorithms for SAT and other combinatorial problems
- Aiming for exponential speed-ups over state of the art
- E.g., use cutting planes to build pseudo-Boolean solvers

Research Goals in the MIAO Group (2/2)

Improve understanding of efficient computation in practice

- Use computational complexity theory to study “real-world” (not worst-case) problems
- Combine theoretical study and empirical experiments
- E.g., take “crafted formulas” with provable theoretical properties and investigate correlation with practical solver performance

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Certify correctness for modern combinatorial solvers

- In many combinatorial optimization paradigms, state-of-the-art solvers are known to be buggy
- Develop methods to make solvers output not just answer but machine-verifiable proof of correctness of this answer

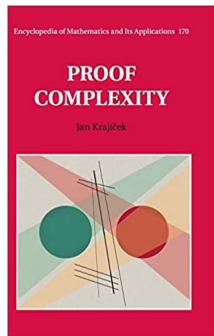
Some References for Further Reading

Handbook of Satisfiability (Especially chapter 7 ☺)



[BHvMW21]

Proof Complexity by Jan Krajíček



[Kra19]

And survey papers, slides, and videos at www.jakobnordstrom.se

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Thanks for listening! See you again Tuesday Jan 18!

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