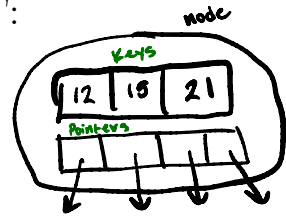


k -ary Search Trees

A k -ary search tree T is defined such that for each node x of T :

- x has at most k children (i.e., T is a k -ary tree)
- x stores an ordered list of pointers to its children and an ordered list of keys
- For every internal node: # of keys = # of children - 1
- x fulfills the **search tree property**:
keys in subtree rooted at i^{th} child $\leq i^{\text{th}}$ key $<$ keys in subtree rooted at $(i + 1)^{\text{th}}$ child



Example of a 4-ary search tree:

=> These notes are in
data structures journal

B-Trees

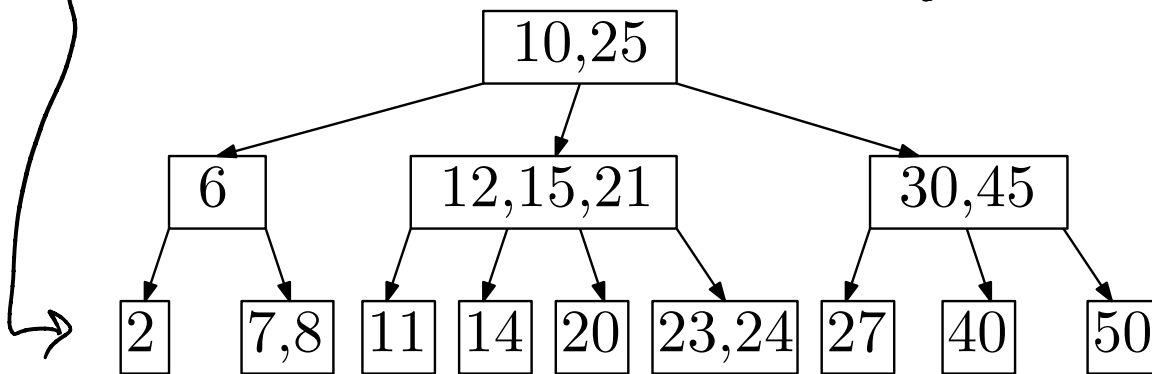
A B-tree T with minimum degree $k \geq 2$ is defined as follows:

- T is a $2k$ -ary search tree
- Every node, except the root, stores at least $k - 1$ keys
(Thus, every internal non-root node has at least k children)
- The root must store at least one key
- All leaves are on the same level of the tree

↳ Nodes shouldn't be empty


$$\left[\begin{array}{l} \text{min} \quad \text{except root} \quad \text{max} \\ k \leq \# \text{ children} \leq 2k \\ k-1 \leq \# \text{ keys} \leq 2k-1 \\ 1 \leq \# \text{ root keys} \leq 2k-1 \end{array} \right]$$

Example of a B-tree with $k = 2$:

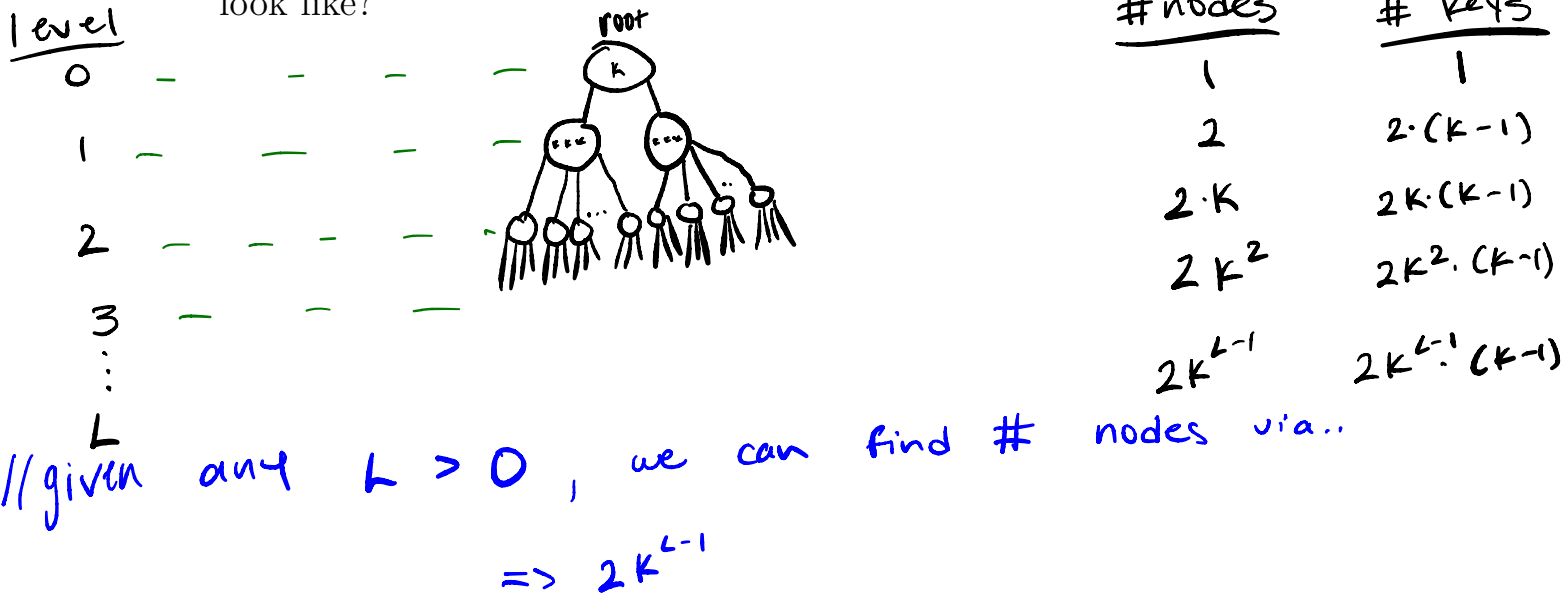


Theorem.

Given a B-tree with minimum degree $k \geq 2$ which stores n keys and has height h it is the case that $h \leq \log_k((n+1)/2)$.

Proof: *What is max height?* 

What does a B-tree with the minimum number of keys per level look like?




If the above tree had height h , how many keys would it contain? // using info above
keys in above tree: // change index

$$\Rightarrow 1 + \sum_{i=1}^h 2k^{i-1}(k-1) = 1 + \sum_{i=0}^{h-1} 2 \cdot k^i (k-1)$$

level 0 key

$$= 1 + 2(k-1) \sum_{i=0}^{h-1} k^i = \# \text{ of total nodes in above B-Tree}$$

Since we put our n keys in a B-tree of height h we know:

// lower bound  - geometric series

$$n \geq 1 + 2(k-1) \sum_{i=0}^{h-1} k^i = 1 + 2(k-1) \cdot \left(\frac{k^h - 1}{k - 1} \right)$$

$$= 1 + 2k^h - 2$$

$$= 2k^h - 1$$

$$\Rightarrow n \geq 2k^h - 1 \quad // \text{solve for } h$$

$$\Rightarrow \frac{n+1}{2} \geq k^h \quad // \log_k \text{ here}$$

$\hookrightarrow \log_k k^h = h$

$$\Rightarrow \log_k \left(\frac{n+1}{2} \right) \geq h \quad \text{therefore } h \in O(\log_k n)$$

Why Use B-Trees? *Make Tree nodes bigger*

Problem: Given a large amount of data that does not fit into main memory (i.e., in RAM), process it into a dictionary data structure.

- (Thus we have to store our data on disk which is very expensive to access)
- Need to minimize number of disk accesses
- With each disk read, read a whole block of data *ONLY some of data is useful*
- Construct a balanced search tree that uses one disk block per tree node *Tree node should fill entire disk block, then all is our data*
- Thus we want each node to contain more than one key (B-trees!)

Find the a key k in our B-tree using the following algorithm.

Algorithm 1 node BTreeSearch(node x , int k)

```
1:  $i = 1$ ;  
2: while  $i \leq \#$  of keys in  $x$  and  $k > i^{\text{th}}$  key in  $x$  do Search all keys in node until data location found  
3:    $i = i + 1$ ;  
4: end while  
5: if  $i \leq \#$  of keys in  $x$  and  $k = i^{\text{th}}$  key in  $x$  then  
6:   return  $(x, i)$ ; → // data found return it  
7: end if  
8: if  $x$  is a leaf then  
9:   return NIL; → // data not found  
10: else  
11:    $b = \text{DISK-READ}(i^{\text{th}} \text{ child in } x)$ ;  
12:   return BTreeSearch( $b, k$ );  
13: end if
```

Runtime:

Worst case: $O(k \cdot \log k n)$ *from while loop* // data not found

B.S.T: $O(\log_2 n)$

of disk accesses:

expensive want to minimize

$O(\log_k n)$

B.S.T
 $O(\log_2 n)$

B-Tree insert

46:38

Make one pass down the tree:

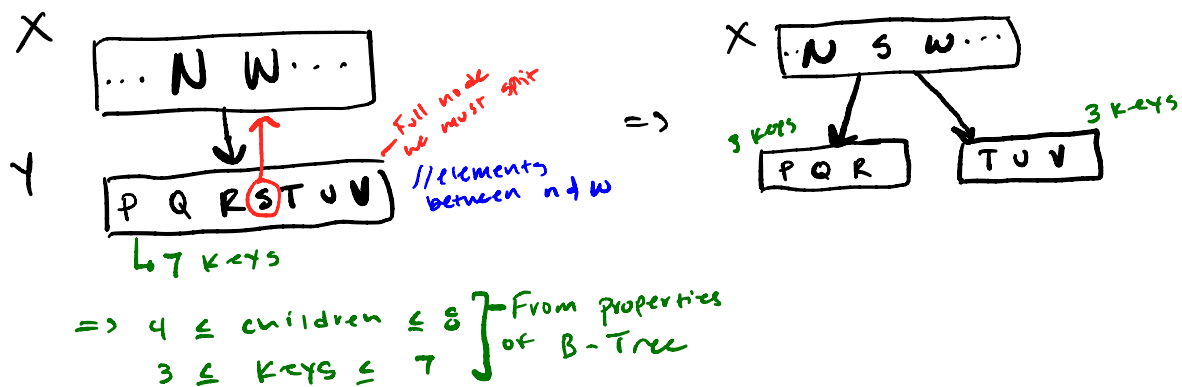
- The goal is to insert the new key into a leaf
- Search where key should be inserted
- Only descend into non-full nodes: // early split
 - If a node is full, split it. Then continue descending.
 - Splitting of the root node is the only way a B-tree grows in height.

↳ grows from root

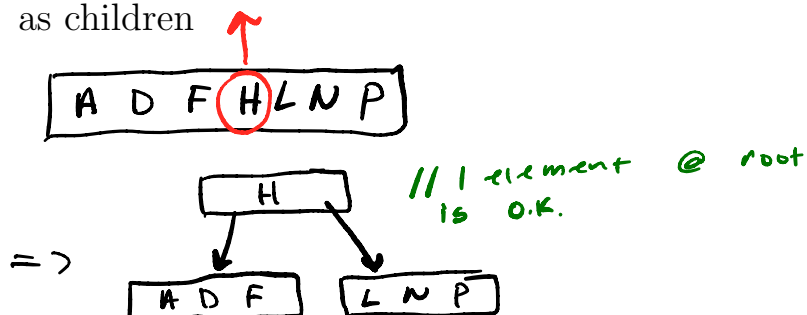


Overview of Insert Helper Functions

- BTreeSplitChild(x, i, y)
 - Split full node y into two nodes y and z of $k - 1$ keys
 - Median key of y is moved to x (which is the parent y)
 - It becomes the new i^{th} key in x



- BTreeSplitChild($s, 1, r$)
 - The full root node r is split in two
 - A new root node s is created
 - s contains the median key of r and has the two halves of r as children

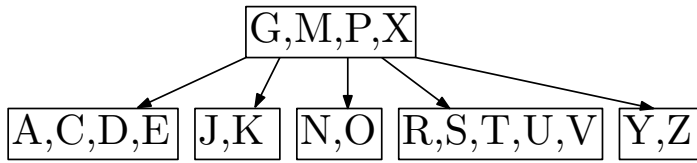


$$K = 3$$

$$2 \leq \text{keys} \leq 5$$

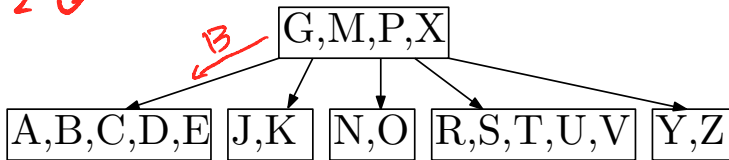
$$3 \leq \text{children} \leq 6$$

Example Insertions:



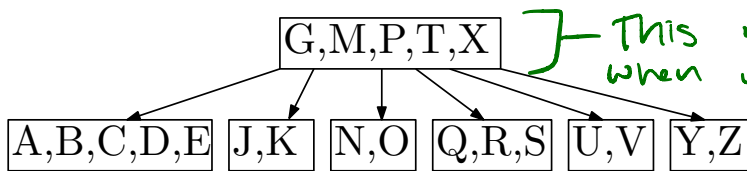
INSERT B (insert at leaf)

$B < G$



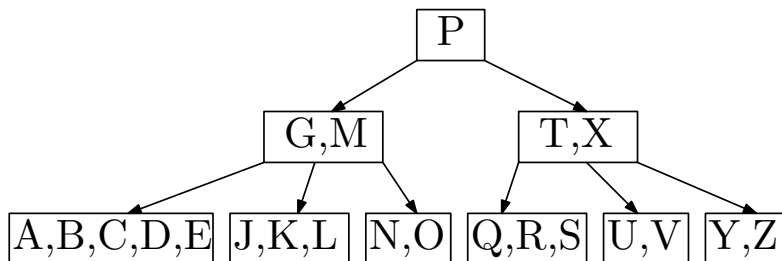
INSERT Q

// Q R S {T} U V

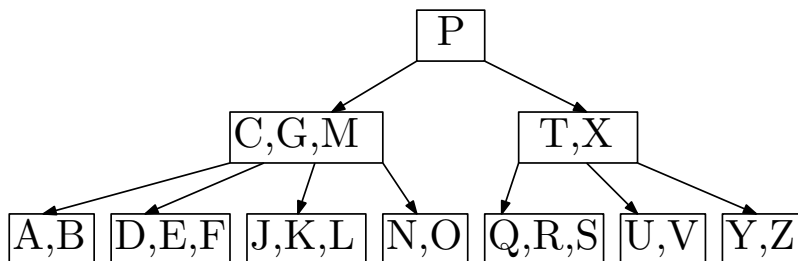


This node splits when we insert L because computer sees this node is full before inserting which leads to be split at root

INSERT L



INSERT F



Algorithm 2 void BTreeInsert(tree T , int key)

```
1:  $r = root[T]$ ;  
2: if # of keys in  $r = 2k - 1$  then //root  $r$  is full  
3:   //create and insert new root node  $s$   
4:    $s = AllocateNode()$ ;  
5:   //split  $r$  to be two children of new root create and insert new root  
   node  $s$   
6:   BTreeSplitChild( $s, 1, r$ );  
7:   BTreeInsertNonfull( $s, key$ );  
8: else  
9:   BTreeInsertNonfull( $r, key$ );  
10: end if
```

Algorithm 3 void BTreeInsertNonfull(node x , int key)

```
1: if  $x$  is a leaf then  
2:   insert  $key$  at correct (i.e., sorted) position in  $x$   
3:   DISK-WRITE( $x$ );  
4: else  
5:   find child  $c$  of  $x$  which by the search tree property should contain  
   should contain  $key$   
6:   DISK-READ( $c$ );  
7:   if  $c$  is full then //  $c$  contains  $2k - 1$   
8:     //Let the  $i^{th}$  key in  $x$  be the largest key smaller than the keys in  $c$   
9:     BTreeSplitChild( $s, i, r$ );  
10:     $c = \text{child of } x \text{ which should contain } key$   
11:  end if  
12:  BTreeInsertNonfull( $c, key$ );  
13: end if
```
