# Introduction to Computational Physics

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#### Course Information

- ► Every Thursday at 14.15, online only
- ► GitHub link: https://github.com/jakryd/0800-fizobl/
- ► Slack group: ncu-students/0800-fizobl-21
- Zoom meeting ID: 208 317 2371
- ► Exams take place in June 2021

### Outline

#### Part 1. Statistical Mechanics

- Probability
- ▶ Phase space
- ► Thermodynamic equilibrium
- Statistical ensembles

#### Part 2. Monte Carlo Methods

- Sampling probability distributions
- ► Importance sampling

#### Part 3. Molecular Dynamics

- Verlet integrator
- Force and energy

### Outline

#### Part 4. Enhanced Sampling

- ► Rare events
- ► Collective variables
- ► Free energy

#### Part 5. Machine Learning

- Connection between machine learning and statistical physics
- Unsupervised learning

#### Literature

- ► M. E. Tuckerman, *Statistical Mechanics: Theory and Simulation*, Oxford University Press (2016).
- ▶ D. Chandler, *Introduction to Modern Statistical Mechanics*, Oxford University Press (1987).

# Statistical Mechanics

- ► Probability is the language of statistical mechanics.
- ► Fundamental to the understanding of quantum mechanics.
- ► The large number of degrees of freedom of a macroscopic system make it necessary to use statistics.

#### Random Variable

A random variable  $\boldsymbol{X}$  is completely defined by the range of values it can take, and its probability distribution  $p_{\boldsymbol{X}}(x_1,\ldots,x_k)$ . The value  $p_{\boldsymbol{X}}$  is the probability that the random variable  $\boldsymbol{X}$  takes the value  $\mathbf{x}=(x_1,\ldots,x_k)$ .

- $ightharpoonup p_{oldsymbol{X}}(oldsymbol{x})$  is non-negative and satisfies the normalization condition:

$$\int d\mathbf{x} \ p_{\mathbf{X}}(\mathbf{x}) = 1. \tag{1}$$

lacktriangle The expectation value of f(X) (or average) is denoted by:

$$\mathbb{E}[f] = \int d\mathbf{x} \ p_{\mathbf{X}}(\mathbf{x}) f(\mathbf{x}). \tag{2}$$

<sup>&</sup>lt;sup>1</sup>From now on we write  $p(\mathbf{x})$  to denote  $p_{\mathbf{X}}(\mathbf{x})$ .

### Gaussian Random Variable $oldsymbol{X} \sim \mathcal{N}(oldsymbol{\mu}, oldsymbol{\Sigma})$

A continuous variable  $\pmb{X} \in \mathbb{R}^k$  has a Gaussian distribution of mean  $\pmb{\mu}$  and variance  $\pmb{\sigma}^2$  if its probability density is:

$$p(\mathbf{x}) = \frac{\exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^{\mathrm{T}}\boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right)}{\sqrt{(2\pi)^{k}\det(\boldsymbol{\Sigma})}}.$$
 (3)

We have  $\mathbb{E}[oldsymbol{X}] = oldsymbol{\mu}$  and  $\mathsf{Var}[oldsymbol{X}] = \Sigma.$ 

 $\blacktriangleright$  The entropy of a random variable  $\boldsymbol{X}$  with probability distribution  $p(\mathbf{x})$  is defined as:

$$H_{\mathbf{X}} \equiv -\int d\mathbf{x} \ p(\mathbf{x}) \log p(\mathbf{x}),$$
 (4)

where we define  $0 \log 0 = 0.2$ 

lacktriangle Entropy  $H_{oldsymbol{X}}$  is a measure of uncertainty of the random variable  $oldsymbol{X}$  .

<sup>&</sup>lt;sup>2</sup>Units for log<sub>2</sub>: bits and log<sub>e</sub>: nats

#### **Examples**

A fair coin has two values with equal probability. Its entropy is 1 bit.

Consider throwing M fair coins: the number of all possible outcomes is  $2^{\cal M}.$  The entropy equals M bits.

Bernoulli process. A Bernoulli random variable X can take two values 0, 1 with probabilities p(0)=q and p(1)=1-q. Its entropy is:

$$H_X = -q \log q - (1 - q) \log(1 - q). \tag{5}$$

The entropy vanishes for q=0 or q=1 because the outcome is certain.

The Kullback-Leibler (KL) divergence (or the relative entropy) measures a stiatistical distance between p(x) and q(x). It is defined as:

$$D_{\mathrm{KL}}(q||p) \equiv \int \mathrm{d}x \ q(x) \log \frac{q(x)}{p(x)}.$$
 (6)

- $ightharpoonup D_{\mathrm{KL}}(q\|p)$  is convex in q(x),
- $D_{\mathrm{KL}}(q||p) \ge 0,$
- ▶ and  $D_{\mathrm{KL}}(q\|p) = 0$  if q(x) = p(x).
- Not symmteric:  $D_{\mathrm{KL}}(q\|p) \neq D_{\mathrm{KL}}(p\|q)$ .

### Dirac $\delta$ function

- $lackbox{} \delta(x)=0 \text{ if } x 
  eq 0 \text{ and } \delta(x) 
  ightarrow \infty \text{ (undefined) if } x=0$
- $\blacktriangleright \int_{-\epsilon}^{\epsilon} \mathrm{d}x \; \delta(x) = 1 \text{ for all } \epsilon > 0$
- ► Gaussian model:

$$\delta_{\sigma}(x) = \lim_{\sigma \to 0} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{x^2}{2\sigma^2}} \tag{7}$$

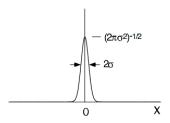


Figure 1: Gaussian model for the Dirac  $\delta$  function.

### Dirac $\delta$ function

lacktriangledown  $\delta$  function times any arbitrary function f(x) is:

$$\int_{\infty}^{\infty} dx \, \delta(x) f(x) = f(0). \tag{8}$$

lacktriangle Other models for  $\delta$  function include Fourier integral:

$$\delta_{\sigma}(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dk \, e^{ikx - |\sigma|x}, \tag{9}$$

and scaled sinc:

$$\delta_{\sigma}(x) = \frac{1}{\pi \sigma} \operatorname{sinc}(x/\sigma). \tag{10}$$

▶ Important for building histograms (notice the change of variables):

$$\int_{-\infty}^{\infty} \mathrm{d}x \ \delta(x-a)f(x) = f(a). \tag{11}$$

### **Definitions**

- ► *Microscopic variable*: A variable pertaining to the individual atoms and molecules making up the system.
- Macroscopic variable: A measurable quantity used to describe the state of the system. It depends collectively on the behavior of all the atoms and molecules. These arealso referred to as thermodynamic variables.
- ightharpoonup Extensive variables: The system under consideration is often defined as encompassing some specific N molecules. Then extensive variables are those whose magnitude is proportional to N.
- lacktriangleright Intensive variables: Those macroscopic variables whose magnitude is independent of N.

### **Scales**

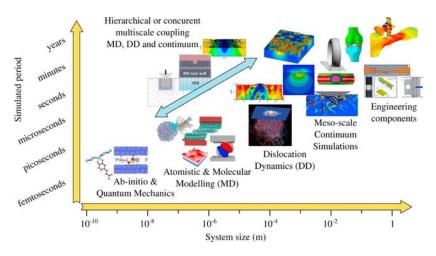


Figure 2: Spatial and temporal scales.

# Phase Space

- ightharpoonup Consider a system with N particles.
- lacktriangle Microscopic coordinates:  ${f r}\equiv (r_1,\ldots,r_{3N})$ .
- ightharpoonup Conjugate momenta:  $\mathbf{p} \equiv (p_1, \dots, p_{3N})$ .
- ► We introduce the notion of generalized coordinates by stacking coordinates and momenta:

$$\mathbf{x} \equiv (r_1, \dots, r_{3N}, p_1, \dots, p_{3N}).$$
 (12)

ightharpoonup x evolves in  $\Gamma$  which defines the 6N-dimensional phase space.

## Ensemble Average

- ► Ergodicity hypothesis the assumption that all states in an ensemble are reached by the time evolution of the corresponding system.
- lacktriangle We define the ensemble average of a quantity  $A({f x})$  as:

$$\langle A \rangle = \frac{\int d\mathbf{x} \ A(\mathbf{x})\rho(\mathbf{x})}{\int d\mathbf{x} \ \rho(\mathbf{x})},$$
 (13)

where  $\rho(\mathbf{x})$  is the phase space probability density.

#### Hamiltonian

- ► The dynamics of the system under study is described by their Hamiltonian  $H(\mathbf{x}) = \sum_{i=1}^{N} \frac{\mathbf{p}_{i}^{2}}{2m_{i}} + U(\mathbf{r})$ .
- ► The equations of motion are:

$$\dot{p}_i = -\frac{\partial H}{\partial r_i}$$
 and  $\dot{r}_i = \frac{\partial H}{\partial p_i}$   $(i = 1, \dots, 3N)$ . (14)

► Can be rewritten as:

$$\dot{p}_i = -\frac{\partial U}{\partial r_i}$$
 and  $\dot{r}_i = \frac{p_i}{m_i}$ , (15)

where  $U(\mathbf{r})$  is the potential energy.

#### Liouville Theorem

 $\blacktriangleright$  Temporal evolution of a phase space element of volume V and boundary  $\partial V$  is given by:

$$\frac{\partial}{\partial t} \int_{V} dV \, \rho + \int_{\partial V} dB \, \rho \mathbf{v} = 0, \tag{16}$$

where  $\mathbf{V}$  is a generalized velocity vector.

▶ In Eq. 16,  $\rho$  satisfies the continuity equation:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0, \tag{17}$$

which simplifies to  $(\nabla \cdot \mathbf{v} = 0)$ :

$$\frac{\partial \rho}{\partial t} = \{H, \rho\} \tag{18}$$

#### Liouville Theorem

- ▶ The Liouville Theorem describes the time evolution of the phase space density  $\dot{\rho}=\{H,\rho\}.$
- ▶ Poisson bracket:  $\{u,v\} = \sum_i \left( \frac{\partial u}{\partial r_i} \frac{\partial v}{\partial p_i} \frac{\partial u}{\partial p_i} \frac{\partial v}{\partial r_i} \right)$ .

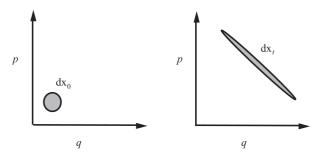


Figure 3: Illustration of phase space volume conservation prescribed by Liouville's theorem.

## Thermodynamic Equilibrium

- ▶ In general, if  $\rho(\mathbf{x},t)$  has an explicit time dependence, then so will an observable A.
- $\blacktriangleright$  However, a system in thermodynamic equilibrium do not change in time,  $\partial\rho/\partial t$  must be equal to 0.
- ► In such a case, no external forces act on the system.
- ► The Liouville equation reduces to:

$$\{\rho, H\} = 0. \tag{19}$$

### Thermodynamic Equilibrium

▶ The general solution to Eq. 19 is any function of H:

$$\rho(\mathbf{x}) \propto F[H(\mathbf{x})].$$
(20)

lacktriangle As ho needs to be properly normalized, we write the solutions as:

$$\rho(\mathbf{x}) = \frac{1}{Z} F[H(\mathbf{x})],\tag{21}$$

where  $Z = \int d\mathbf{x} \ F[H(\mathbf{x})]$  is referred to as the partition function.

- ► The partition function is a measure of the number of microscopic states in the phase space accessible within a given ensemble.
- ► Each ensemble has a particular partition function that depends on the macroscopic observables used to define the ensemble.

#### **Ensembles**

- $\blacktriangleright$  N the number of particles, V volume, P pressure, T temperature, E internal energy.
- ightharpoonup Microcanonical ensemble: constant NVE.
- ightharpoonup Canonical ensemble: constant NVT.
- ightharpoonup Canonical pressure ensemble: constant NPT.

### Microcanonical Ensemble

lacktriangleq NVE are fixed, so also the probability density is constant:

$$\rho(\mathbf{x}) = \frac{1}{Z}\delta[H(\mathbf{x}) - E],\tag{22}$$

where  $\delta[\cdot]$  is the Dirac delta function and the microcanonical partition function is given by:

$$Z = \int d\mathbf{x} \, \delta[H(\mathbf{x}) - E]. \tag{23}$$

 $lackbox{ }$  We can see that the function  $F[H(\mathbf{x})]$  from Eq. 20 is:

$$F[H(\mathbf{x})] \propto \delta[H(\mathbf{x}) - E].$$
 (24)

#### Microcanonical Ensemble

- ► State function is the entropy a quantity that can be related to the number of the microscopic states of the system.
- ► Control variables are:

$$\frac{1}{T} = \left(\frac{\partial S}{\partial E}\right)_{N,V}, \frac{P}{T} = \left(\frac{\partial S}{\partial V}\right)_{N,E}, \frac{\mu}{T} = -\left(\frac{\partial S}{\partial N}\right)_{V,E}.$$
 (25)

 $\blacktriangleright$  Let  $\Omega$  be the number of microscopic states; the relation of S to  $\Omega$  is:

$$S(N, V, E) = k_{\rm B} \log \Omega(N, V, E), \tag{26}$$

where  $k_{\rm B}$  is Boltzmann's constant:

$$k_{\rm B} = 1.3806505(24) \times 10^{-23} \,\mathrm{J/K}.$$
 (27)

ightharpoonup NVT are fixed.

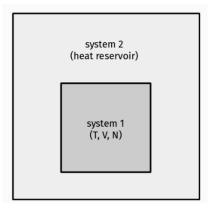


Figure 4: In a canonical ensemble setup, the system we study (system 1) is coupled to a heat reservoir (system 2) that guarantees a constant temperature.

Source: M. E. Tuckerman, Statistical Mechanics: Theory and Simulation, Oxford University Press (2016).

At a given temperature T, the probability for a system to be in a certain configuration  ${\bf x}$  with energy  $E({\bf x})$  is:

$$\rho(\mathbf{x}) = \frac{1}{Z} e^{-\beta E(\mathbf{x})},\tag{28}$$

where  $\beta=\frac{1}{k_{\rm B}T}$  is the <code>inverse temperature^3</code>, and the canonical partition function is:

$$Z = \int d\mathbf{x} \, e^{-\beta E(\mathbf{x})}.$$
 (29)

ightharpoonup The ensemble average of a quantity A is given by:

$$\langle A \rangle = \frac{1}{Z} \int d\mathbf{x} \ A(\mathbf{x}) e^{-\beta E(\mathbf{x})}.$$
 (30)

 $<sup>^{3}\</sup>beta \approx 0.4 \text{ kJ/mol at } 300 \text{ K}.$ 

► We can derive Eq. 28 by using the maximum entropy princliple. We know that:

$$\int d\mathbf{x} \, \rho(\mathbf{x}) E(\mathbf{x}) = E_0, \tag{31}$$

and that  $\rho$  must be normalized.

lacktriangle We introduce the augumented function J:

$$J \equiv -\int d\mathbf{x} \ \rho(\mathbf{x}) \log \rho(\mathbf{x}) \tag{32}$$

$$+ \lambda_1 \left( \int d\mathbf{x} \, \rho(\mathbf{x}) E(\mathbf{x}) - E_0 \right) \tag{33}$$

$$+\lambda_0 \left( \int d\mathbf{x} \, \rho(\mathbf{x}) - 1 \right),$$
 (34)

where  $\lambda_0$  and  $\lambda_1$  are the Lagrange multipliers.

 $\blacktriangleright$  Taking the functional derivative w.r.t. to  $\rho$  and setting it to zero, we have:

$$\frac{\delta J}{\delta \rho} = -\log \rho(\mathbf{x}) - 1 + \lambda_1 E + \lambda_0 = 0, \tag{35}$$

which implies that the maximum entropy distribution is:

$$\rho(\mathbf{x}) = Z^{-1} \lambda_1 e^{\lambda_1 E(\mathbf{x})},\tag{36}$$

where Z is the canonical partition function, and  $Z=\mathrm{e}^{1-\lambda_0}.$ 

► We get that the density must have a form:

$$\rho(\mathbf{x}) = \frac{1}{Z} e^{\lambda_1 E(\mathbf{x})} \tag{37}$$

and

$$Z = \int d\mathbf{x} \, e^{\lambda_1 E(\mathbf{x})}.$$
 (38)

The main steps of the Monte Carlo sampling are:

- ► Choose randomly a new configuration in phase space based on a Markov chain.
- Accept or reject the new configuration, depending on the strategy used.
- Compute the physical quantity and add it to the averaging procedure.
- ► Repeat the previous steps until convergence.

$$I = \int_0^1 \mathrm{d}x \int_0^{\sqrt{1-x^2}} \mathrm{d}y = \frac{\pi}{4}$$
 (39)

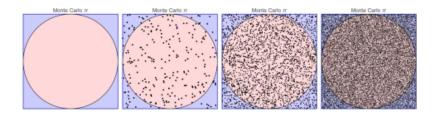


Figure 5: Example of a Monte Carlo method to compute  $\pi$ .

► The integrals that must be evaluated in equilibrium statistical mechanics are generally of the form:

$$I = \int d\mathbf{x} \, \phi(\mathbf{x}) p(\mathbf{x}), \tag{40}$$

where  ${\bf x}$  is an n-dimensional vector,  $\phi({\bf x})$  is an arbitrary function, and  $p({\bf x})$  is a function satisfying the properties of a probability distribution:

$$p(\mathbf{x}) \ge 0$$
 and  $\int d\mathbf{x} \ p(\mathbf{x}) = 1.$  (41)

► Eq. 40 represents the ensemble average of a physical observable in equilibrium statistial mechanics.

- Let  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_M$  be a set of M n-dimensional vectors that are sampled from  $p(\mathbf{x})$ .
- lacktriangle The problem of sampling from  $p(\mathbf{x})$  is a nontrivial one.
- ► For now, let us assume that such an algorithm exists. Then, an estimator:

$$\hat{I}_M = \frac{1}{M} \sum_{i=1}^{M} \phi(\mathbf{x}_i) \tag{42}$$

is such that:

$$\lim_{M \to \infty} \hat{I}_M = I. \tag{43}$$

► Eq. 43 is guaranteed by the central limit theorem.<sup>4</sup>

<sup>&</sup>lt;sup>4</sup> For the derivation, see M. E. Tuckerman, *Statistical Mechanics: Theory and Simulation*, Oxford University Press (2016), p. 281.

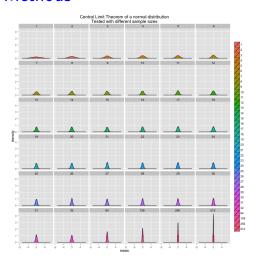


Figure 6: Central limit theorem for a normal distribution.

Source: https://www.reddit.com/r/math/comments/2wrduu/central\_limit\_theorem/.

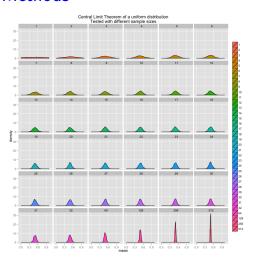


Figure 7: Central limit theorem for a uniform distribution.

Source: https://www.reddit.com/r/math/comments/2wrduu/central\_limit\_theorem/.

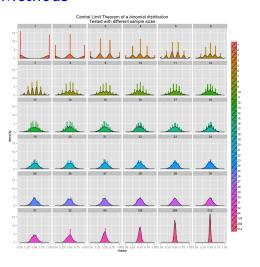


Figure 8: Central limit theorem for a binomial distribution.

Source: https://www.reddit.com/r/math/comments/2wrduu/central\_limit\_theorem/.

#### **Central Limit Theorem**

If  $\mathbf{x}_1, \mathbf{x}_2, \ldots, \mathbf{x}_n$  are n random variables drawn from a population with overall mean  $\mu$  and finite variance  $\sigma^2$ , and if  $\bar{\mathbf{x}}_n$  is the sample mean, the limiting form of the distribution,  $\lim_{n \to \infty} \sqrt{n} \left( \frac{\bar{\mathbf{x}}_n - \mu}{\sigma} \right)$ , is the standard normal distribution.

Example of sampling a simple distribution given by:

$$p(x) = ce^{-cx}, (44)$$

on the interval  $x \in [0, \infty)$ .

▶ To sample from p(x), we need P(X) such that:

$$P(X) = \int_0^X dx \ ce^{-cx} = 1 - e^{-cX}, \tag{45}$$

and equate Eq. 45 to a random number  $\xi \in [0,1]$ , then we can solve for X, which gives:

$$X = -\frac{1}{c}\log(1-\xi).$$
 (46)

► In general, we do not have such simple distribution to sample from in statistical mechanics.

▶ However, instead of sampling  $p(\mathbf{x})$  to estimate  $\int d\mathbf{x} \ \phi(\mathbf{x}) p(\mathbf{x})$ , we could sample from a different distribution  $b(\mathbf{x})$  by rewriting the integral as:

$$I = \int d\mathbf{x} \left[ \frac{\phi(\mathbf{x})p(\mathbf{x})}{b(\mathbf{x})} \right] b(\mathbf{x}).$$
(47)

 $lackbox{ We set } \psi(\mathbf{x}) = \phi(\mathbf{x}) p(\mathbf{x}) / b(\mathbf{x})$  which gives us:

$$I = \int d\mathbf{x} \ \psi(\mathbf{x}) b(\mathbf{x}) \tag{48}$$

$$\approx \frac{1}{M} \sum_{i=1}^{M} \psi(\mathbf{x}_i), \tag{49}$$

where the vectors  $\mathbf{x}_i$  are sampled from  $b(\mathbf{x})$ .

► This trick is the basis of *importance sampling*.

- lackbox Using  $b(\mathbf{x})$  as an importance function may lead to easier sampling.
- ▶ But how do we select  $b(\mathbf{x})$ ?
- ls there an optimal choice of  $b(\mathbf{x})$ ? The best one leads to the smallest possible variance:

$$Var[b(\mathbf{x})] = \int d\mathbf{x} \ \psi^2(\mathbf{x})b(\mathbf{x}) - \left(\int d\mathbf{x} \ \psi(\mathbf{x})b(\mathbf{x})\right)^2 \quad (50)$$

that gives us:

$$\int d\mathbf{x} \, \frac{\phi^2(\mathbf{x})p^2(\mathbf{x})}{b^2(\mathbf{x})} b(\mathbf{x}) - \left(\int d\mathbf{x} \, \phi(\mathbf{x})p(\mathbf{x})\right)^2 \tag{51}$$

lacktriangle Minimize Var w.r.t.  $b(\mathbf{x})$  subject to the constraint  $\int \mathrm{d}\mathbf{x} \ b(\mathbf{x}) = 1$ 

From Eq. 51, we have:

$$F[b(\mathbf{x})] = Var[b(\mathbf{x})] - \lambda \int d\mathbf{x} \ b(\mathbf{x}), \tag{52}$$

where  $\lambda$  is a Lagrange multiplier.

lacktriangle Computing the functional derivative  $\delta F/\delta b({f x})$ , we obtain:

$$\frac{\phi^2(\mathbf{x})p^2(\mathbf{x})}{b^2(\mathbf{x})} + \lambda = 0 \tag{53}$$

or

$$b(\mathbf{x}) = \frac{1}{\sqrt{-\lambda}} \phi(\mathbf{x}) p(\mathbf{x}). \tag{54}$$

Normalizing  $b(\mathbf{x})$ , we have:

$$\int d\mathbf{x} \ b(\mathbf{x}) = \frac{1}{\sqrt{-\lambda}} \int d\mathbf{x} \ \phi(\mathbf{x}) p(\mathbf{x}) = 1.$$
 (55)

ightharpoonup Thus, the optimal choice for  $b(\mathbf{x})$  is:

$$b(\mathbf{x}) = \frac{\phi(\mathbf{x})p(\mathbf{x})}{I}.$$
 (56)

ightharpoonup But if we knew the integral value I, we would not need to perform the calculation...

# $M(RT)^2$

#### Markov Chain

If the vectors  $\mathbf{X}_1, \dots, \mathbf{X}_M$  are generated sequentially, and  $\mathbf{X}_{i+1}$  is generated only based on the knowledge of  $\mathbf{X}_i$ . the sequence is called a Makov chain.

#### Markov state diagram of a child behaviour

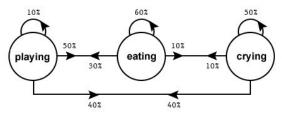


Figure 9: Example of a simple Markov chain.

# $M(RT)^2$

- For physical systems, a Markov chain must satisfy the condition of detailed balance, which ensures that the Markov process is microscopically reversible.
- ightharpoonup M(RT)<sup>2</sup> is a rejection method.
- ► With the acceptance probability given by:

$$A(\mathbf{x}_i|\mathbf{x}_j) = \min\left[1, f(\mathbf{x}_i)/f(\mathbf{x}_j)\right],\tag{57}$$

where  $f(\mathbf{x})$  is the probability of the system being at  $\mathbf{x}$ .

► Sampling in the canonical ensemble:<sup>5</sup>

$$A(\mathbf{r}_i|\mathbf{r}_j) = \min\left[1, e^{-\beta\left[U(\mathbf{r}_i) - U(\mathbf{r}_j)\right]}\right],\tag{58}$$

as 
$$f(\mathbf{r}) \propto \mathrm{e}^{-\beta U(\mathbf{r})}$$
.

<sup>&</sup>lt;sup>5</sup>Reminder: r are microscopic coordinates.

#### Replica Exchange Monte Carlo

- ► Barrier crossing are frequently rarely encountered during a simulation.
- For a barrier height of 15 kJ/mol at 300 K, the Boltzmann factor is approximately  $3\times 10^{-3}$ ; for 30 kJ/mol is  $6\times 10^{-6}$ .

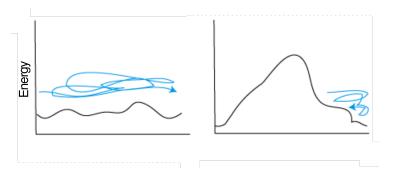


Figure 10: Barrier crossing showing a trajectory in the case of a low and a high energy barrier, respectively.

# Parallel Tempering<sup>6</sup>

- ► Temperature is used as the control variable, and different temperatures are assigned to the *replicas*.
- In the parallel tempering scheme, a set of temperatures  $T_1, \ldots, T_M$  such that:

$$T_1 < T_2 < \dots < T_M \tag{59}$$

are assigned to the M replicas, where  $T_1$  is the temperature T of the canonical distribution.

- ► The high-temperature replicas easily cross potential energy barriers.
- ► We attempt exchanges between the neighboring replicas.

<sup>&</sup>lt;sup>6</sup>Marinari and Parisi. Simulated tempering: A new Monte Carlo scheme Europhys. Lett. 19 (1992)

# Parallel Tempering

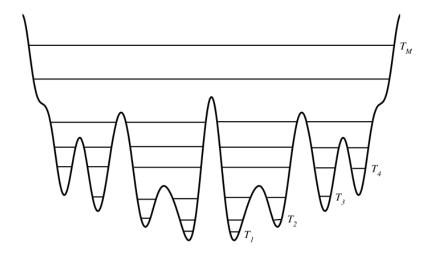


Figure 11: Schematic of the parallel-tempering replica exchange Monte Carlo.<sup>7</sup>

<sup>&</sup>lt;sup>7</sup>Source: M. E. Tuckerman, *Statistical Mechanics: Theory and Simulation*, Oxford University Press (2016)

# Parallel Tempering

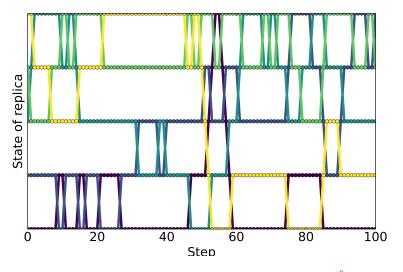


Figure 12: An example of a parallel tempering trajectory.<sup>8</sup>

 $<sup>^8</sup> Source: \ https://coulomb.umontpellier.fr/perso/daniele.coslovich/pt/$ 

### Paralell Tempering

- ▶ Let  $\mathbf{r}^{(1)}, \dots, \mathbf{r}^{(M)}$  be the complete configurations of the M replicas, i.e.,  $\mathbf{r}^{(K)} \equiv (\mathbf{r}_1^{(K)}, \dots, \mathbf{r}_N^{(K)})$ .
- ▶ The replicas are independent, so the total probability distribution  $F(\mathbf{r}^{(1)},\dots,\mathbf{r}^{(M)})$  is:

$$F(\mathbf{r}^{(1)},\dots,\mathbf{r}^{(M)}) = \prod_{K=1}^{M} f_K\left(\mathbf{r}^{(K)}\right),\tag{60}$$

where:

$$f_K\left(\mathbf{r}^{(K)}\right) = \frac{1}{Z}e^{-\beta_K U\left(\mathbf{r}^{(K)}\right)},$$
 (61)

in which  $\beta_K = (k_{\rm B}T_K)^{-1}$ .

#### Parallel Tempering

lacktriangle Periodically, a neighboring pair of replicas K and K+1 is selected, and an attempted switch is made with probability:

$$A_s = A\left[ (\mathbf{r}^{(K+1)}, \mathbf{r}^{(K)}) | (\mathbf{r}^{(K)}, \mathbf{r}^{(K+1)}) \right]$$
 (62)

$$= \min \left[ 1, \frac{f_K(\mathbf{r}^{(K+1)})}{f_K(\mathbf{r}^{(K)})} \cdot \frac{f_{K+1}(\mathbf{r}^{(K)})}{f_{K+1}(\mathbf{r}^{(K+1)})} \right]$$
(63)

$$= \min\left[1, e^{-\Delta_{K,K+1}}\right],\tag{64}$$

where:

$$\Delta_{K,K+1} = (\beta_K - \beta_{K+1}) \left[ U(\mathbf{r}^{(K)}) - U(\mathbf{r}^{(K+1)}) \right]$$
 (65)

### Wang-Landau Sampling

▶ Recall that the canonical partition function Z(N,V,T) can be expressed in terms of the microcanonical partition function  $\Omega(N,V,E)$ :

$$Z(N, V, T) = \frac{1}{E_0} \int_0^\infty dE \, e^{-\beta E} \Omega(N, V, E), \qquad (66)$$

where  $E_0$  is an arbitrary reference energy.

lacktriangle Setting  $E_0=1$  and dropping fixed V and N, we have:

$$Z(\beta) = \int_0^\infty dE \, e^{-\beta E} \Omega(E). \tag{67}$$

► Eq. 67 suggests a procedure to compute the canonical partition function, and thus, all thermodynamic quantities.

### Wang-Landau Sampling

#### Wang-Landau Algorithm<sup>9</sup>

- 1. Set  $\Omega(E)$  for all values of E.
- 2. Attempt a trial move from E to  $E^\prime$  with the acceptance probability given by:

$$A(E'|E) = \min\left[1, \frac{\Omega(E)}{\Omega(E')}\right]. \tag{68}$$

- 3. Modify the bin such that  $\Omega(E) \to \Omega(E)f$ , where f > 1.
- 4. Accumulate the histogram of energy,  $h(E) \rightarrow h(E) + 1$ .
- 5. If h(E) is flat enought, then  $f \to \sqrt{f}$ .
- 6. If not converged, move to 2; else return  $\Omega(E)$ .

<sup>&</sup>lt;sup>9</sup>Numerical implementations require that  $\Omega(E)$  be discretized into a number of energy bins.

# Wang-Landau Sampling

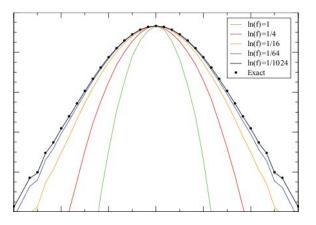


Figure 13: Convergence of the Wang-Landau algorithm. 10

<sup>&</sup>lt;sup>10</sup> Source: Brown, Odbadrakh, Nicholson, and Eisenbach, Convergence for the Wang-Landau density of states, Phys. Rev. E 84, 065702(R) (2011)

# Molecular Dynamics

#### Molecular Dynamics

There are three main ingredients in molecular dynamics (MD):

- ► The algorithm to integrate the equations of motion,
- ► The model describing the interparticle interactions,
- ► The calculation of forces and energies from the model.

#### Verlet Algorithm

► The simplest approach to obtain a numerical integration scheme is to use a Taylor series:

$$\mathbf{r}_{i}(t + \Delta t) \approx \mathbf{r}_{i}(t) + \Delta t \mathbf{v}_{i}(t) + \frac{\Delta t^{2}}{2m_{i}} \mathbf{F}_{i}(t),$$
 (69)

and

$$\mathbf{r}_i(t - \Delta t) \approx \mathbf{r}_i(t) - \Delta t \mathbf{v}_i(t) + \frac{\Delta t^2}{2m_i} \mathbf{F}_i(t).$$
 (70)

► Adding Eq. 69 to Eq. 70, we get a velocity-independent Verlet algorithm:

$$\mathbf{r}_{i}(t+\Delta t) = 2\mathbf{r}_{i}(t) - \mathbf{r}_{i}(t-\Delta t) + \frac{\Delta t^{2}}{m_{i}}\mathbf{F}_{i}(t). \tag{71}$$

#### Velocity Verlet Algorithm

► Consider a shift in time in comparision to Eq. 69:

$$\mathbf{r}_i(t) \approx \mathbf{r}_i(t+\Delta t) - \Delta t \mathbf{v}_i(t+\Delta t) + \frac{\Delta t^2}{2m_i} \mathbf{F}_i(t+\Delta t), \ \ (72)$$

which after some rearrangements takes the following form:

$$\mathbf{v}_{i}(t+\Delta t) = \mathbf{v}_{i}(t) + \frac{\Delta t}{2m_{i}} \left[ \mathbf{F}_{i}(t) + \mathbf{F}_{i}(t+\Delta t) \right]. \tag{73}$$

This scheme allows to use both evolution of the positions and velocities.