main ex3

April 7, 2021

```
[1]: # python
     import numpy as np
     import matplotlib.pyplot as plt
     from typing import Any, List, Dict, Optional
     import time
     # pytorch:
     import torch as t
     import torchvision.transforms as ttf
     from torch.optim import Adam
     from torch.nn import (
         Sequential,
         Conv2d,
         BatchNorm2d,
         ReLU,
         MaxPool2d,
         Dropout,
         Flatten,
         Linear,
         Module,
         CrossEntropyLoss,
         Dropout2d
     )
     from torch.nn.functional import (
         nll_loss
     )
     # Custom lib:
     import jx_pytorch_lib as jp
     import jx_lib
```

0.1 E3 - Q1: NN on MNIST > 90%

- We use VGG-11 architecture from last assignment for the MNIST data, see layer details below:
- The Final Accuracy is 98.94% for training and 98.4% for testing dataset

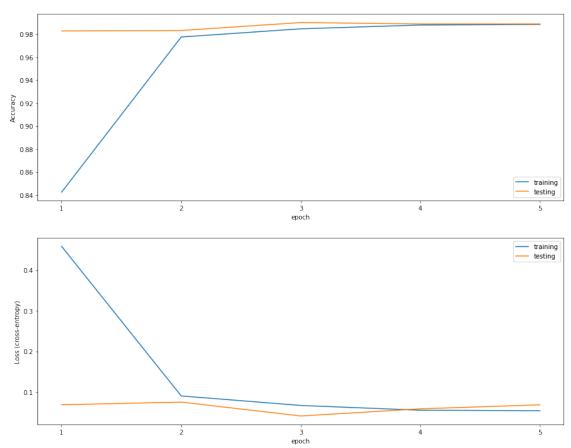
```
[2]: | # USER DEFINE: ---- #
    TOTA_NUM_EPOCHS = 5
    LEARNING_RATE
                   = 0.001
    BATCH_SIZE
                    = 100
    MAX SAMPLES
                   = None # Default: None => all data
    # const:
    OUT DIR E3
                   = "output/E3"
    IMG SIZE
                   = (32, 32)
    VERBOSE LEVEL = jp.VerboseLevel.HIGH
    DATA AUG
                   = None #["HFlip", "VFlip", "GAUSS-Op5-Op5"]
    # INIT: ----
    ### Directory generation ###
    jp.create_all_folders(DIR=OUT_DIR_E3)
    ### MODEL ###
    MODEL_DICT = {
        "VGG11":
            Sequential(
                ## CNN Feature Extraction
                Conv2d( 1, 64, 3, 1, 1), BatchNorm2d( 64), ReLU(), MaxPool2d(2,2),
                Conv2d(64, 128, 3, 1, 1), BatchNorm2d(128), ReLU(), MaxPool2d(2,2),
                Conv2d(128, 256, 3, 1, 1), BatchNorm2d(256), ReLU(),
                Conv2d(256, 256, 3, 1, 1), BatchNorm2d(256), ReLU(), MaxPool2d(2,2),
                Conv2d(256, 512, 3, 1, 1), BatchNorm2d(512), ReLU(),
                Conv2d(512, 512, 3, 1, 1), BatchNorm2d(512), ReLU(), MaxPool2d(2,2),
                Conv2d(512, 512, 3, 1, 1), BatchNorm2d(512), ReLU(),
                Conv2d(512, 512, 3, 1, 1), BatchNorm2d(512), ReLU(), MaxPool2d(2,2),
                # Classifier
                Flatten(1),
                Linear(512, 4096), ReLU(), Dropout(0.5),
                Linear(4096, 4096), ReLU(), Dropout(0.5),
                Linear(4096, 10),
            ),
        "VGG11-FGSM":
            Sequential(
                ## CNN Feature Extraction
                Conv2d( 1, 64, 3, 1, 1), BatchNorm2d(64), ReLU(), MaxPool2d(2,2),
                Conv2d(64, 128, 3, 1, 1), BatchNorm2d(128), ReLU(), MaxPool2d(2,2),
                Conv2d(128, 256, 3, 1, 1), BatchNorm2d(256), ReLU(),
                Conv2d(256, 256, 3, 1, 1), BatchNorm2d(256), ReLU(), MaxPool2d(2,2),
                Conv2d(256, 512, 3, 1, 1), BatchNorm2d(512), ReLU(),
                Conv2d(512, 512, 3, 1, 1), BatchNorm2d(512), ReLU(), MaxPool2d(2,2),
                Conv2d(512, 512, 3, 1, 1), BatchNorm2d(512), ReLU(),
                Conv2d(512, 512, 3, 1, 1), BatchNorm2d(512), ReLU(), MaxPool2d(2,2),
                # Classifier
                Flatten(1),
```

```
Linear(512, 4096), ReLU(), Dropout(0.5),
                 Linear(4096, 4096), ReLU(), Dropout(0.5),
                 Linear (4096,
                                10),
             ),
     }
[3]: # LOAD NET: ----
     # check device:
     # hardware-acceleration
     device = None
     if t.cuda.is_available():
         print("[ALERT] Attempt to use GPU => CUDA:0")
         device = t.device("cuda:0")
     else:
         print("[ALERT] GPU not found, use CPU!")
         device = t.device("cpu")
     MODEL DICT["VGG11"].to(device)
    [ALERT] Attempt to use GPU => CUDA:0
[3]: Sequential(
       (0): Conv2d(1, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
       (2): ReLU()
       (3): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil mode=False)
       (4): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (5): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
    track_running_stats=True)
       (6): ReLU()
       (7): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil mode=False)
       (8): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (9): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
    track_running_stats=True)
       (10): ReLU()
       (11): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (12): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
    track_running_stats=True)
       (13): ReLU()
       (14): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil_mode=False)
       (15): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (16): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
       (17): ReLU()
```

```
(19): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
    track_running_stats=True)
       (20): ReLU()
       (21): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
    ceil_mode=False)
      (22): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
      (23): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
    track running stats=True)
      (24): ReLU()
      (25): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
      (26): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
    track running stats=True)
      (27): ReLU()
      (28): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
    ceil_mode=False)
      (29): Flatten(start_dim=1, end_dim=-1)
       (30): Linear(in_features=512, out_features=4096, bias=True)
      (31): ReLU()
      (32): Dropout(p=0.5, inplace=False)
      (33): Linear(in_features=4096, out_features=4096, bias=True)
      (34): ReLU()
      (35): Dropout(p=0.5, inplace=False)
      (36): Linear(in features=4096, out features=10, bias=True)
    )
[4]: # LOAD DATASET: ---- #
     # Loading training dataset:
    train_dataset = jp.A4_EX1_CNN_HELPER.load_mnist_data(
        batch_size = BATCH_SIZE,
        resize
                    = IMG_SIZE, # NOTE: make sure you understand why
        n workers
        augmentation = DATA_AUG, # Options: ["HFlip", "VFlip", "GAUSS-0.01"],
        shuffle
                    = True,
                   = True,
        train_set
    test_dataset = jp.A4_EX1_CNN_HELPER.load_mnist_data(
        batch_size = BATCH_SIZE,
                     = IMG_SIZE, # NOTE: make sure you understand why
        resize
        n_workers
        augmentation = DATA AUG, # Options: ["HFlip", "VFlip", "GAUSS-0.01"],
        shuffle
                   = False,
        train set
                    = False,
    === Loading Data ...
    > Resized to (32, 32)
```

(18): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))

```
=== Data Loaded [Testing] ===
    === Loading Data ...
    > Resized to (32, 32)
    === Data Loaded [Training] ===
[5]: # TRAIN: ----- -----
    # train & evaulate:
    report = jp.A4_EX1_CNN_HELPER.train_and_monitor(
        device
                     = device,
        train_dataset = train_dataset,
        test_dataset = test_dataset,
        loss_func
                  = CrossEntropyLoss(),
                     = MODEL_DICT["VGG11"],
        net
        optimizer
                    = Adam(MODEL_DICT["VGG11"].parameters(), lr=LEARNING_RATE),
        num_epochs = TOTA_NUM_EPOCHS,
        verbose_level = VERBOSE_LEVEL,
        max_data_samples = MAX_SAMPLES,
    > epoch 1/5:
      >> Learning (wip)
     >> Testing (wip)
        epoch 2 > Training: [LOSS: 0.4587 | ACC: 0.8426] | Testing: [LOSS: 0.0684 |
    ACC: 0.9827] Ellapsed: 22.73 s | rate:1.30241
    > epoch 2/5:
     >> Learning (wip)
     >> Testing (wip)
        epoch 3 > Training: [LOSS: 0.0902 | ACC: 0.9774] | Testing: [LOSS: 0.0750 |
    ACC: 0.9831] Ellapsed: 22.71 s | rate:1.32615
    > epoch 3/5:
     >> Learning (wip)
     >> Testing (wip)
        epoch 4 > Training: [LOSS: 0.0667 | ACC: 0.9846] | Testing: [LOSS: 0.0408 |
    ACC: 0.9900] Ellapsed: 22.73 s | rate:1.32067
    > epoch 4/5:
     >> Learning (wip)
     >> Testing (wip)
       epoch 5 > Training: [LOSS: 0.0549 | ACC: 0.9879] | Testing: [LOSS: 0.0585 |
    ACC: 0.9888] Ellapsed: 22.76 s | rate:1.32117
    > epoch 5/5:
     >> Learning (wip)
     >> Testing (wip)
        epoch 6 > Training: [LOSS: 0.0538 | ACC: 0.9884] | Testing: [LOSS: 0.0682 |
    ACC: 0.9888] Ellapsed: 22.77 s | rate:1.30130
[6]: # REPORT: ---- #
    AUG_STR = DATA_AUG if DATA_AUG else ""
```



```
[7]: # Loading training dataset:
    sample_x = None
    sample_y = None

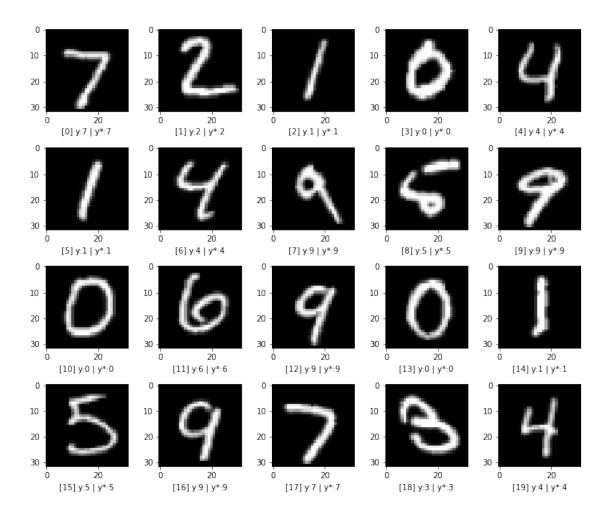
for X, y in test_dataset:
        sample_x = X
        sample_y = y
        break
```

```
# test
     sample_x_dev = sample_x.to(device)
     y_prediction_1 = MODEL_DICT["VGG11"](sample_x_dev).argmax(dim=1)
     # report:
     print("[{}]> \n> y:{} \n> y_pred:{}".format("test", sample_y.tolist(),_
      →y_prediction_1.tolist()))
    [test]>
    > y:[7, 2, 1, 0, 4, 1, 4, 9, 5, 9, 0, 6, 9, 0, 1, 5, 9, 7, 3, 4, 9, 6, 6, 5, 4,
    0, 7, 4, 0, 1, 3, 1, 3, 4, 7, 2, 7, 1, 2, 1, 1, 7, 4, 2, 3, 5, 1, 2, 4, 4, 6, 3,
    5, 5, 6, 0, 4, 1, 9, 5, 7, 8, 9, 3, 7, 4, 6, 4, 3, 0, 7, 0, 2, 9, 1, 7, 3, 2, 9,
    7, 7, 6, 2, 7, 8, 4, 7, 3, 6, 1, 3, 6, 9, 3, 1, 4, 1, 7, 6, 9]
    > y_pred: [7, 2, 1, 0, 4, 1, 4, 9, 5, 9, 0, 6, 9, 0, 1, 5, 9, 7, 3, 4, 9, 6, 6,
    5, 4, 0, 7, 4, 0, 1, 3, 1, 3, 4, 7, 2, 7, 1, 2, 1, 1, 7, 4, 2, 3, 5, 1, 2, 4, 4,
    6, 3, 5, 5, 6, 0, 4, 1, 9, 5, 7, 8, 9, 3, 7, 4, 6, 4, 3, 0, 7, 0, 2, 9, 1, 7, 3,
    2, 9, 7, 7, 6, 2, 7, 8, 4, 7, 3, 6, 1, 3, 6, 9, 3, 1, 8, 1, 7, 6, 9]
[8]: # Report samples
     imgs = {}
     for i in range(20):
         text = "[{}] y:{} | y*:{}".format(i, sample_y.tolist()[i], y_prediction_1.
     →tolist()[i])
         imgs[text] = sample_x[i][0]
     jx_lib.imgs_plot(dict_of_imgs=imgs, figsize=(10,10), OUT_DIR = OUT_DIR_E3, tag_
     ⇒= "Sample Images", cmap="gray")
    /home/jx/JXProject/Github/UW__4B_Individual_Works/CS 480/A5
```

/home/jx/JXProject/Github/UW_4B_Individual_Works/CS 480/A5 Package/src_code/jx_lib.py:209: MatplotlibDeprecationWarning: Passing non-integers as three-element position specification is deprecated since 3.3 and will be removed two minor releases later.

ax = plt.subplot(sqr,sqr,i+1)

[8]:



0.2 E3 - Q2: FGSM

- See implementation of fgsm attack below:
- See resultant testing samples in the end.

0.2.1 Results:

 $[\mathrm{e}{=}0.10] > \mathrm{Original}$: [LOSS: -20.8493 | ACC: 0.9826] | FGSM-attack: [LOSS: -12.0806 | ACC: 0.6896] Ellapsed: 4.10 s

 $[\mathrm{e}{=}0.20] > \mathrm{Original}$: [LOSS: -20.8235 | ACC: 0.9824] | FGSM-attack: [LOSS: -8.8329 | ACC: 0.3972] Ellapsed: 4.08 s

 $[\mathrm{e}{=}0.50] > \mathrm{Original}$: [LOSS: -20.8055 | ACC: 0.9835] | FGSM-attack: [LOSS: -6.5080 | ACC: 0.2909] Ellapsed: 4.07 s

0.2.2 Comments

- As these adversarial images shown (in the end), as the epsilon increases, the image becomes much harder to recognize, and the overall accuracy drops dramatically.
- Invisible perturbation may completely changes the CNN VGG11 output as we may see at epsilon of 0.1, which drops to 69% from 98.3% prior the attack.
- CNNs' decision boundary is constructed based on sparsely populated training samples in a high-dimension. Hence, it could be quite sensitive to these adversarial attacks.

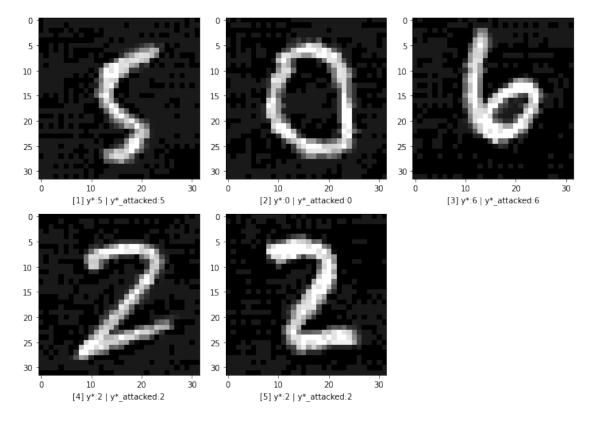
```
[9]: def gen_adversarial_image(
         image,
         epsilon,
         data_gradient
     ):
         sign_ = data_gradient.sign()
         preturbed_image = image + epsilon * sign_
         preturbed_image = t.clamp(preturbed_image, 0, 1) # clip [0,1]
         return preturbed_image
     def fgsm_attack(
         model,
         x_dev,
         y_dev,
         device,
         epsilon,
         loss_func
     ) -> Dict:
         status_dict = {}
         # grad
         x_dev.requires_grad = True
         # raw image feed:
         y_output = model(x_dev)
         y_pred_initial = y_output.argmax(dim=1)
         # compute loss:
         loss = loss_func(y_output, y_dev)
         # reset:
         model.zero_grad()
         # compute backward gradients:
         loss.backward()
         # collect grad from hardware:
         data_grad = x_dev.grad.data
```

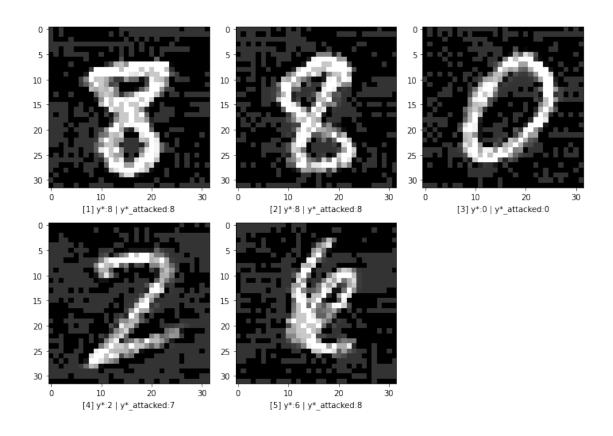
```
# generate adversarial image (with fqsm attack):
   x_dev_perturbed = gen_adversarial_image(
        image = x_dev,
        epsilon = epsilon,
       data_gradient = data_grad
   )
   # re-compute the fgsm attacked image:
   y_output_perturbed = model(x_dev_perturbed)
   y_pred_perturbed = y_output_perturbed.argmax(dim=1)
   loss_perturbed = loss_func(y_output_perturbed, y_dev)
   # log:
   status_dict["loss"] = loss
   status_dict["loss_perturbed"] = loss_perturbed
   status_dict["y_pred_initial"] = y_pred_initial
   status_dict["y_pred_perturbed"] = y_pred_perturbed
   return status_dict, x_dev_perturbed
def perform_fgsm_attack(
   model,
   device,
   test_dataset,
   epsilon,
   loss_func,
   n_samples
):
   print("=== Performing FGSM Attack: ")
   test_loss_sum, test_acc_sum, test_n, test_start = 0.0, 0.0, 0, time.time()
   test_loss_sum_perturbed, test_acc_sum_perturbed = 0.0, 0.0
   img_samples = {}
   batch count = 0
   for i, (X, y) in enumerate(test_dataset):
        print(" > [{}/{}]".format(i+1, len(test_dataset)), end="0027\r"0027)
        # device acc.
       x_dev, y_dev = X.to(device), y.to(device)
        # attack:
        status_dict, x_dev_perturbed = fgsm_attack(
            model = model,
            device = device,
```

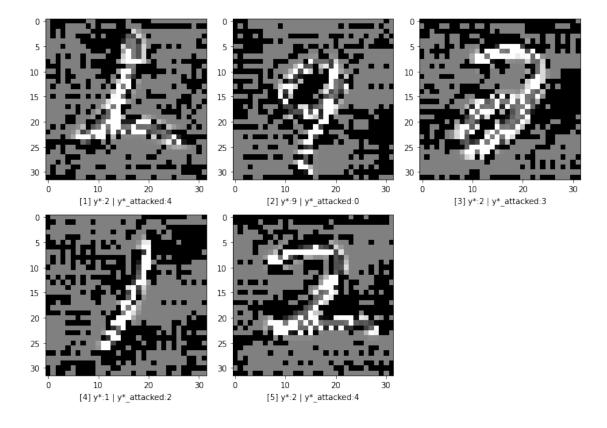
```
epsilon = epsilon,
           loss_func = loss_func,
           x_{dev} = x_{dev},
           y_dev = y_dev,
       )
       # Compute Accuracy
       test_loss_sum += status_dict["loss"].item()
       test_acc_sum += (status_dict["y_pred_initial"] == y_dev).sum().item()
       test_loss_sum_perturbed += status_dict["loss_perturbed"].item()
       test_acc_sum_perturbed += (status_dict["y_pred_perturbed"] == y_dev).
→sum().item()
       test_n += y.shape[0]
       batch_count += 1
       # Sample Images Randomly:
       if len(img samples) < n samples and np.random.rand() > 0.5:
           sample_index = np.random.choice(range(len(y_dev.tolist())))
           label = "[{}] y*:{} | y*_attacked:{}".format(
               (len(img_samples)+1),
               status_dict["y_pred_initial"].tolist()[sample_index],
               status_dict["y_pred_perturbed"].tolist()[sample_index]
           img_samples[label] = x_dev_perturbed[sample_index][0].squeeze().
→detach().cpu().numpy()
   test loss = test loss sum / batch count
   test_acc = test_acc_sum / test_n
   fgsm_test_loss = test_loss_sum_perturbed / batch_count
   fgsm_test_acc = test_acc_sum_perturbed / test_n
   test_ellapse = time.time() - test_start
   return test_loss, test_acc, fgsm_test_loss, fgsm_test_acc, test_n,_
→test_ellapse, img_samples
```

```
[10]: # Perform FGSM: --- ---- #
for epsilon in [0.1, 0.2, 0.5]:
    test_loss, test_acc, fgsm_test_loss, fgsm_test_acc, test_n, test_ellapse, ing_samples = perform_fgsm_attack(
        model = MODEL_DICT["VGG11"],
        device = device,
        test_dataset = test_dataset,
        epsilon = epsilon,
        # loss_func = CrossEntropyLoss(),
        loss_func = nll_loss, # Negative log likelihood loss
```

```
=== Performing FGSM Attack:
[e=0.10] > Original: [LOSS: -16.6127 | ACC: 0.9879] | FGSM-attack: [LOSS: -9.9447 | ACC: 0.8027] Ellapsed: 4.13 s
=== Performing FGSM Attack:
[e=0.20] > Original: [LOSS: -16.5788 | ACC: 0.9886] | FGSM-attack: [LOSS: -6.0281 | ACC: 0.4275] Ellapsed: 4.11 s
=== Performing FGSM Attack:
[e=0.50] > Original: [LOSS: -16.5478 | ACC: 0.9884] | FGSM-attack: [LOSS: -3.4546 | ACC: 0.2688] Ellapsed: 4.12 s
```







0.3 E3 - Q3: Adversarial Training

- See results below:
- See implementation below (modified version based on `jx_pytorch_lib'.

0.3.1 Comments:

• As we may observed from the test data results, and sampled output, we can see there is a dramatic improvements by incorporating the FGSM attack on training dataset. Here, an epsillon of 0.2 is used, and the epsillon of 0.5 FGSM attacks now can reach 94% performance in comparison to 29% in Ex3.2.

```
verbose_level: jp.VerboseLevel = jp.VerboseLevel.LOW,
):
    # Training:
    if verbose_level >= jp.VerboseLevel.LOW:
        print(" >> Learning (wip)")
    train_loss_sum, train_acc_sum, train_n, train_start = 0.0, 0.0, 0, time.
→time()
    batch_count = 0
    for i, (X, y) in enumerate(train_dataset):
        if max_data_samples is not None:
            if i >= max_data_samples:
                break
            if verbose_level >= jp.VerboseLevel.HIGH:
                print(" >[{}/{}]".format(i, max_data_samples),_
 \rightarrowend="0027\r"0027)
        elif verbose_level >= jp.VerboseLevel.HIGH:
            print(" >[{}/{}]".format(i, len(train_dataset)), __
 \rightarrowend="0027\r"0027)
        # hardware-acceleration
        if device != None:
            X = X.to(device)
            y = y.to(device)
        # > FGSM attack on training data:
        status_dict, x_dev_perturbed = fgsm_attack(
            model = net.
            device = device,
            epsilon = epsilon,
            loss_func = loss_func,
            x_dev = X,
            y_{dev} = y,
        # Train with Perturbed Images:
        # Predict:
        y_prediction = net(x_dev_perturbed)
        # Calculate loss
        loss = loss_func(y_prediction, y)
        # Gradient descent > [ LEARNING ]
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()
        # Compute Accuracy
        train_loss_sum += loss.item()
        train_acc_sum += (y_prediction.argmax(dim=1) == y).sum().item()
        train_n += y.shape[0]
```

```
batch_count += 1
    train_loss = train_loss_sum / batch_count
    train_acc = train_acc_sum / train_n
    train_ellapse = time.time() - train_start
    return train_loss, train_acc, train_n, train_ellapse
def train_and_monitor_with_FGSM_attack(
    device,
    train_dataset,
    test_dataset,
    optimizer,
    loss_func,
    net,
    epsilon: float,
    num_epochs: int,
    # history_epoch_resolution: float = 1.0, TODO: mini-batches progress!!!
    max_data_samples: Optional[int] = None,
   verbose_level: jp.VerboseLevel = jp.VerboseLevel.LOW,
):
   report = jp.ProgressReport()
    # Cross entropy
    for epoch in range(num_epochs):
        if verbose_level >= jp.VerboseLevel.LOW:
            print("> epoch {}/{}:".format(epoch + 1, num_epochs))
        # Train:
        train_loss, train_acc, train_n, train_ellapse = train_with_fgsm_attack(
            device = device,
            train_dataset = train_dataset,
            net = net,
            optimizer = optimizer,
            loss_func = loss_func,
            max_data_samples = max_data_samples,
            verbose_level = verbose_level,
            epsilon = epsilon,
        )
        # Testing:
        test_loss, test_acc, test_n, test_ellapse = jp.A4_EX1_CNN_HELPER.test(
            device = device,
            test_dataset = test_dataset,
            net = net,
            loss_func = loss_func,
            max_data_samples = max_data_samples,
            verbose_level = verbose_level
```

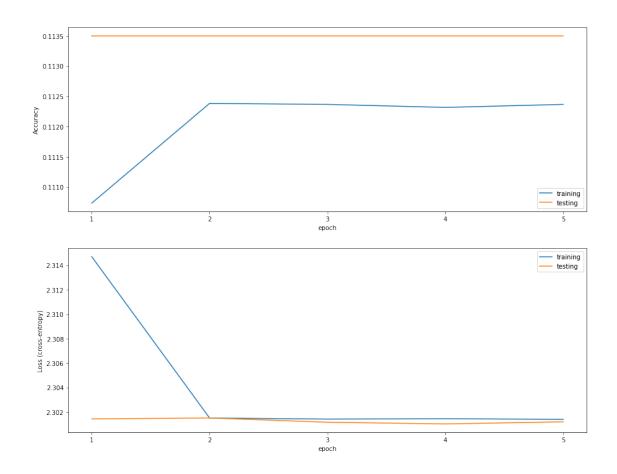
```
# Store
             report.append(
                  epoch
                              = epoch + 1,
                  train_loss = train_loss,
                  train_acc = train_acc,
                  train_time = train_ellapse,
                  test loss
                              = test loss,
                  test_acc
                              = test_acc,
                  test time
                                = test ellapse,
                  learning_rate = optimizer.param_groups[0]["lr"],
                  verbose
                              = (verbose_level >= jp.VerboseLevel.MEDIUM)
              )
          return report
[12]: # LOAD NET: ---- -
      # check device:
      # hardware-acceleration
      device = None
      if t.cuda.is_available():
          print("[ALERT] Attempt to use GPU => CUDA:0")
          device = t.device("cuda:0")
      else:
          print("[ALERT] GPU not found, use CPU!")
          device = t.device("cpu")
      MODEL_DICT["VGG11-FGSM"].to(device)
     [ALERT] Attempt to use GPU => CUDA:0
[12]: Sequential(
        (0): Conv2d(1, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
        (2): ReLU()
        (3): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
      ceil_mode=False)
        (4): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (5): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
        (6): ReLU()
        (7): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
      ceil_mode=False)
        (8): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (9): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
      track running stats=True)
        (10): ReLU()
```

```
track_running_stats=True)
        (13): ReLU()
        (14): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil_mode=False)
        (15): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (16): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track running stats=True)
        (17): ReLU()
        (18): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
        (19): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track running stats=True)
        (20): ReLU()
        (21): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil_mode=False)
        (22): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (23): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
        (24): ReLU()
        (25): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (26): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
        (27): ReLU()
        (28): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil mode=False)
        (29): Flatten(start_dim=1, end_dim=-1)
        (30): Linear(in features=512, out features=4096, bias=True)
        (31): ReLU()
        (32): Dropout(p=0.5, inplace=False)
        (33): Linear(in_features=4096, out_features=4096, bias=True)
        (34): ReLU()
        (35): Dropout(p=0.5, inplace=False)
       (36): Linear(in_features=4096, out_features=10, bias=True)
     )
[13]: | # TRAIN: ---- #
      # train & evaulate:
     report = train_and_monitor_with_FGSM_attack(
         device
                      = device,
         train_dataset = train_dataset,
         test_dataset = test_dataset,
                       = MODEL DICT["VGG11-FGSM"],
         net
                      = Adam(MODEL_DICT["VGG11-FGSM"].parameters(),_
         optimizer
      →lr=LEARNING_RATE),
         num epochs
                      = TOTA_NUM_EPOCHS,
         verbose_level = VERBOSE_LEVEL,
```

(11): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))

(12): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,

```
max_data_samples = MAX_SAMPLES,
         # Let"0027s use:
         loss_func = CrossEntropyLoss(),
         epsilon = 0.2,
     )
     > epoch 1/5:
       >> Learning (wip)
       >> Testing (wip)
         epoch 2 > Training: [LOSS: 2.3147 | ACC: 0.1107] | Testing: [LOSS: 2.3014 |
     ACC: 0.1135] Ellapsed: 46.41 s | rate:1.31416
     > epoch 2/5:
       >> Learning (wip)
       >> Testing (wip)
         epoch 3 > Training: [LOSS: 2.3015 | ACC: 0.1124] | Testing: [LOSS: 2.3015 |
     ACC: 0.1135] Ellapsed: 46.45 s | rate:1.32957
     > epoch 3/5:
       >> Learning (wip)
       >> Testing (wip)
         epoch 4 > Training: [LOSS: 2.3014 | ACC: 0.1124] | Testing: [LOSS: 2.3012 |
     ACC: 0.1135] Ellapsed: 46.46 s | rate:1.32234
     > epoch 4/5:
       >> Learning (wip)
       >> Testing (wip)
         epoch 5 > Training: [LOSS: 2.3014 | ACC: 0.1123] | Testing: [LOSS: 2.3010 |
     ACC: 0.1135] Ellapsed: 46.49 s | rate:1.32892
     > epoch 5/5:
       >> Learning (wip)
       >> Testing (wip)
         epoch 6 > Training: [LOSS: 2.3014 | ACC: 0.1124] | Testing: [LOSS: 2.3012 |
     ACC: 0.1135] Ellapsed: 46.51 s | rate:1.33543
[14]: # REPORT: ---- #
     AUG_STR = DATA_AUG if DATA_AUG else ""
      # output report:
     report.output_progress_plot(
                  = OUT_DIR_E3,
= "VGG11-FGSM_{}".format("_".join(AUG_STR)),
         OUT_DIR
         tag
         verbose_level = VERBOSE_LEVEL
     )
      # output model:
     t.save(MODEL_DICT["VGG11-FGSM"], "{}/last_fgsm_{{}}.pt".format(OUT_DIR_E3, "_".
      →join(AUG_STR)))
```



```
[15]: # Perform FGSM: --- -
      for epsilon in [0.1, 0.2, 0.5]:
          test_loss, test_acc, fgsm_test_loss, fgsm_test_acc, test_n, test_ellapse, u
      →img_samples = perform_fgsm_attack(
             model = MODEL_DICT["VGG11-FGSM"],
             device = device,
             test_dataset = test_dataset,
              epsilon = epsilon,
              # loss_func = CrossEntropyLoss(),
              loss_func = nll_loss, # Negative log likelihood loss
             n_{samples} = 5,
          )
          # report:
          print("0027[e={:.2f}] > Original: [LOSS: {:.4f} | ACC: {:.4f}] |
      →FGSM-attack: [LOSS: {:.4f} | ACC: {:.4f}] Ellapsed: {:.2f} s "0027.format(
              epsilon, test_loss, test_acc, fgsm_test_loss, fgsm_test_acc,_
       →test_ellapse
          ))
          jx_lib.imgs_plot(
```

```
dict_of_imgs=img_samples, figsize=(10,10), OUT_DIR = OUT_DIR_E3,
    tag = "Sample Images (VGG11-FGSM) [e={}]".format(epsilon), cmap="gray",
    show=True
)
```

=== Performing FGSM Attack:

[e=0.10] > Original: [LOSS: -0.0025 | ACC: 0.1135] | FGSM-attack: [LOSS: -0.0024

| ACC: 0.1135] Ellapsed: 4.13 s

=== Performing FGSM Attack:

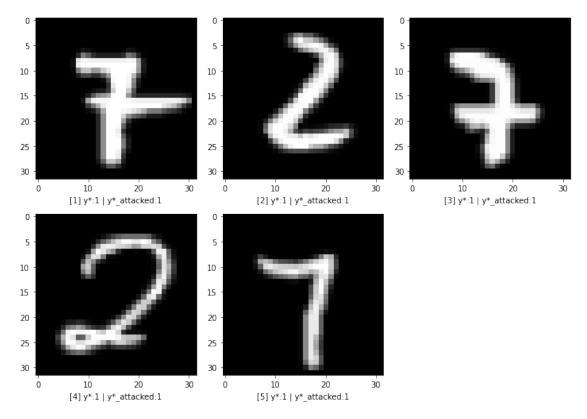
[e=0.20] > Original: [LOSS: -0.0025 | ACC: 0.1135] | FGSM-attack: [LOSS: -0.0025

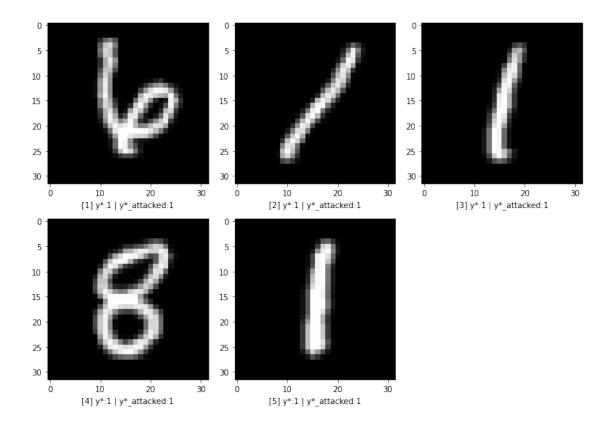
| ACC: 0.1135] Ellapsed: 4.13 s

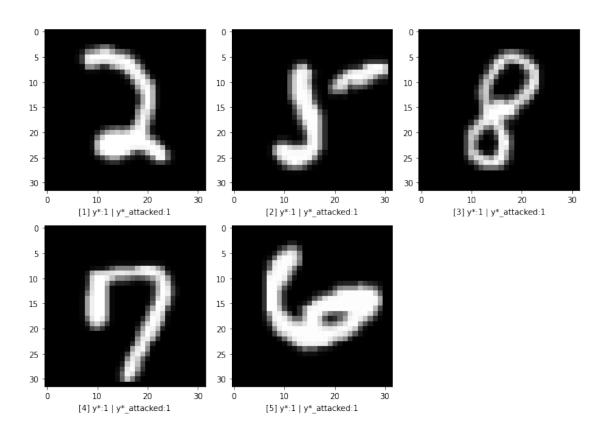
=== Performing FGSM Attack:

[e=0.50] > Original: [LOSS: -0.0024 | ACC: 0.1135] | FGSM-attack: [LOSS: -0.0025

| ACC: 0.1135] Ellapsed: 4.13 s







0.4 (Bonus: ~3pts) E3 - Q4: More Robust Model

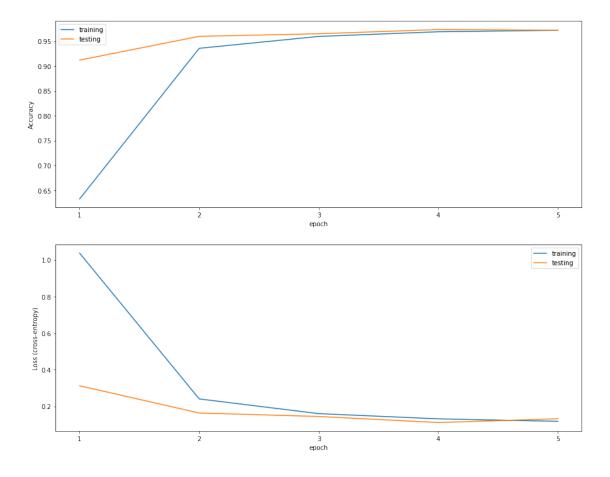
- CNNs' decision boundary is constructed based on sparsely populated training samples (Nguyen et al., 2014) in a high-dimension. Adversarial examples used in this experiment are populated around the decision boundary, therefore, they are often indistinguishable from natural images if one uses point-wise prediction.
- In the stochastic FF, uncertainty around the input pixel is propa- gated throughout every layer of CNNs and provides marginal information. Instead of point-wise prediction, integrating such information increases a chance to make correct prediction for adversar- ial examples. Adding stronger noise drags the adversarial examples farther apart from the correct decision region thereby lowering the accuracy.
- As a result, we may just simply dropout between each convolution layers, to introduce random noises to the system, hence correcting the decision by lowering the sensitivity.

```
[16]: MODEL_DICT["VGG11-ROBUST"] = Sequential(
                 ## CNN Feature Extraction
                 Conv2d( 1, 64, 3, 1, 1), BatchNorm2d( 64), ReLU(), MaxPool2d(2,2),
                 Dropout2d(p=0.5),
                 Conv2d(64, 128, 3, 1, 1), BatchNorm2d(128), ReLU(), MaxPool2d(2,2),
                 Dropout2d(p=0.5),
                 Conv2d(128, 256, 3, 1, 1), BatchNorm2d(256), ReLU(),
                 Dropout2d(p=0.5),
                 Conv2d(256, 256, 3, 1, 1), BatchNorm2d(256), ReLU(), MaxPool2d(2,2),
                 Dropout2d(p=0.5),
                 Conv2d(256, 512, 3, 1, 1), BatchNorm2d(512), ReLU(),
                 Dropout2d(p=0.5),
                 Conv2d(512, 512, 3, 1, 1), BatchNorm2d(512), ReLU(), MaxPool2d(2,2),
                 Dropout2d(p=0.5),
                 Conv2d(512, 512, 3, 1, 1), BatchNorm2d(512), ReLU(),
                 Dropout2d(p=0.5),
                 Conv2d(512, 512, 3, 1, 1), BatchNorm2d(512), ReLU(), MaxPool2d(2,2),
                 # Classifier
                 Flatten(1),
                 Linear(512, 4096), ReLU(), Dropout(0.5),
                 Linear(4096, 4096), ReLU(), Dropout(0.5),
                 Linear(4096, 10),
             )
      # LOAD NET: ---- ---- ----
      # check device:
      # hardware-acceleration
     device = None
     if t.cuda.is_available():
         print("[ALERT] Attempt to use GPU => CUDA:0")
         device = t.device("cuda:0")
```

```
else:
          print("[ALERT] GPU not found, use CPU!")
          device = t.device("cpu")
      MODEL_DICT["VGG11-ROBUST"].to(device)
     [ALERT] Attempt to use GPU => CUDA:0
[16]: Sequential(
        (0): Conv2d(1, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
        (2): ReLU()
        (3): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
      ceil mode=False)
        (4): Dropout2d(p=0.5, inplace=False)
        (5): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (6): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
        (7): ReLU()
        (8): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
      ceil mode=False)
        (9): Dropout2d(p=0.5, inplace=False)
        (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (11): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
      track running stats=True)
        (12): ReLU()
        (13): Dropout2d(p=0.5, inplace=False)
        (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (15): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
        (16): ReLU()
        (17): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
      ceil_mode=False)
        (18): Dropout2d(p=0.5, inplace=False)
        (19): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (20): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
        (21): ReLU()
        (22): Dropout2d(p=0.5, inplace=False)
        (23): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
        (24): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
      track running stats=True)
        (25): ReLU()
        (26): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
      ceil_mode=False)
        (27): Dropout2d(p=0.5, inplace=False)
        (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
```

```
(29): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
       (30): ReLU()
       (31): Dropout2d(p=0.5, inplace=False)
       (32): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (33): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
       (34): ReLU()
       (35): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1,
     ceil mode=False)
        (36): Flatten(start dim=1, end dim=-1)
       (37): Linear(in_features=512, out_features=4096, bias=True)
       (38): ReLU()
       (39): Dropout(p=0.5, inplace=False)
       (40): Linear(in_features=4096, out_features=4096, bias=True)
       (41): ReLU()
       (42): Dropout(p=0.5, inplace=False)
       (43): Linear(in_features=4096, out_features=10, bias=True)
     )
[17]: | # TRAIN: ---- ---- #
      # train & evaulate:
     report = jp.A4_EX1_CNN_HELPER.train_and_monitor(
         device
                  = device,
         train_dataset = train_dataset,
         test dataset = test dataset,
         loss_func = CrossEntropyLoss(),
                      = MODEL DICT["VGG11-ROBUST"],
         net
         optimizer = Adam(MODEL_DICT["VGG11-ROBUST"].parameters(),
      ⇒lr=LEARNING_RATE),
                    = TOTA_NUM_EPOCHS,
         num_epochs
         verbose_level = VERBOSE_LEVEL,
         max_data_samples = MAX_SAMPLES,
     )
     > epoch 1/5:
       >> Learning (wip)
       >> Testing (wip)
         epoch 2 > Training: [LOSS: 1.0377 | ACC: 0.6327] | Testing: [LOSS: 0.3128 |
     ACC: 0.9120] Ellapsed: 23.31 s | rate:1.35622
     > epoch 2/5:
       >> Learning (wip)
       >> Testing (wip)
         epoch 3 > Training: [LOSS: 0.2410 | ACC: 0.9357] | Testing: [LOSS: 0.1640 |
     ACC: 0.9598] Ellapsed: 23.31 s | rate:1.35821
     > epoch 3/5:
       >> Learning (wip)
```

```
>> Testing (wip)
        epoch 4 > Training: [LOSS: 0.1606 | ACC: 0.9597] | Testing: [LOSS: 0.1450 |
     ACC: 0.9650] Ellapsed: 23.33 s | rate:1.33857
     > epoch 4/5:
      >> Learning (wip)
      >> Testing (wip)
        epoch 5 > Training: [LOSS: 0.1321 | ACC: 0.9690] | Testing: [LOSS: 0.1120 |
     ACC: 0.9735] Ellapsed: 23.34 s | rate:1.35458
     > epoch 5/5:
      >> Learning (wip)
      >> Testing (wip)
        epoch 6 > Training: [LOSS: 0.1185 | ACC: 0.9720] | Testing: [LOSS: 0.1326 |
     ACC: 0.9722] Ellapsed: 23.34 s | rate:1.35658
[18]: # REPORT: ---- #
     AUG_STR = DATA_AUG if DATA_AUG else ""
     # output report:
     report.output_progress_plot(
         OUT_DIR = OUT_DIR_E3,
                      = "VGG11-ROBUST_{}".format("_".join(AUG_STR)),
         tag
         verbose_level = VERBOSE_LEVEL
     )
     # output model:
     t.save(MODEL_DICT["VGG11-ROBUST"], "{}/last_robust_{{}}.pt".format(OUT_DIR_E3,__
      →"_".join(AUG_STR)))
```



0.4.1 Comments:

• Recall the original VGG11 after the attack:

 $[\mathrm{e}{=}0.10] > \mathrm{Original}$: [LOSS: -20.8493 | ACC: 0.9826] | FGSM-attack: [LOSS: -12.0806 | ACC: 0.6896] Ellapsed: 4.10 s

 $[\mathrm{e}{=}0.20] > \mathrm{Original}$: [LOSS: -20.8235 | ACC: 0.9824] | FGSM-attack: [LOSS: -8.8329 | ACC: 0.3972] Ellapsed: 4.08 s

 $[\mathrm{e}{=}0.50] > \mathrm{Original}$: [LOSS: -20.8055 | ACC: 0.9835] | FGSM-attack: [LOSS: -6.5080 | ACC: 0.2909] Ellapsed: 4.07 s

• Now, lets attack the robust model trained with the same attack:

 $[\mathrm{e}{=}0.10] > \mathrm{Original}$: [LOSS: -12.2066 | ACC: 0.9787] | FGSM-attack: [LOSS: -9.2008 | ACC: 0.8717] Ellapsed: 4.23 s

 $[\mathrm{e}{=}0.20] > \mathrm{Original}$: [LOSS: -12.1912 | ACC: 0.9786] | FGSM-attack: [LOSS: -6.2752 | ACC: 0.6440] Ellapsed: 4.20 s

 $[\mathrm{e}{=}0.50] > \mathrm{Original}$: [LOSS: -12.1313 | ACC: 0.9787] | FGSM-attack: [LOSS: -1.4502 | ACC: 0.2111] Ellapsed: 4.20 s

• As, we may see, there is a significant improvements in terms of FGSM attack, although the model is trained with original dataset as VGG11.

```
[19]: # Perform FGSM: --- #
     for epsilon in [0.1, 0.2, 0.5]:
         test_loss, test_acc, fgsm_test_loss, fgsm_test_acc, test_n, test_ellapse,_
      →img_samples = perform_fgsm_attack(
            model = MODEL_DICT["VGG11-ROBUST"],
            device = device,
            test_dataset = test_dataset,
             epsilon = epsilon,
             # loss_func = CrossEntropyLoss(),
            loss_func = nll_loss, # Negative log likelihood loss
            n_{samples} = 5,
         )
         # report:
         print("0027[e={:.2f}] > Original: [LOSS: {:.4f} | ACC: {:.4f}] |
      \rightarrow FGSM-attack: [LOSS: {:.4f} | ACC: {:.4f}] Ellapsed: {:.2f} s "0027.format(
             epsilon, test_loss, test_acc, fgsm_test_loss, fgsm_test_acc,_
      →test_ellapse
         ))
         jx_lib.imgs_plot(
             dict_of_imgs=img_samples, figsize=(10,10), OUT_DIR = OUT_DIR_E3,
             tag = "Sample Images (VGG11-ROBUST) [e={}]".format(epsilon),
      )
```

```
=== Performing FGSM Attack:
[e=0.10] > Original: [LOSS: -11.4605 | ACC: 0.9735] | FGSM-attack: [LOSS: -8.9375 | ACC: 0.8651] Ellapsed: 4.24 s
=== Performing FGSM Attack:
[e=0.20] > Original: [LOSS: -11.5644 | ACC: 0.9734] | FGSM-attack: [LOSS: -6.2442 | ACC: 0.6536] Ellapsed: 4.22 s
=== Performing FGSM Attack:
[e=0.50] > Original: [LOSS: -11.4851 | ACC: 0.9742] | FGSM-attack: [LOSS: -2.0096 | ACC: 0.2610] Ellapsed: 4.23 s
```

