Wprowadzenie do sieci neuronowych

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Zadanie klasyfikacji czy regresji polegają na dopasowaniu do otykietowanego zbioru danych X,y funkcji, dla której z dostatecznie dużą dokładnością zachodzi $f_{\theta}(x) \approx y$ dla losowych x,y z tego zbioru.

Żeby tego dokonać, uznajemy, że naszą funkcję $f_{ heta}$ daje się sparametryzować wagami heta.

Przykładowy schemat wygląda następująco:

- 0. Do problemu dobierz architekturę modelu, parametryzowaną wagami θ , funkcję błędu $\mathcal{L}(x,y,\theta)$, której niska oczekiwana wartość dla danych wag gwarantuje dobrą jakość modelu
- 1. Niech X to dane wejściowe, y to etykiety
- 2. Zainicjalizuj parametry modelu heta
- 3. Powtarzaj dopóki $\mathcal{L}(heta)$ nie będzie wystarczająco niska
 - \circ Minimalizuj $\mathcal{L}(heta)$ zmieniając wagi heta
 - zazwyczaj powyższa minimalizacja oparta jest na gradiencie
 - o Innymi słowy zazwyczaj $\theta = \theta \alpha * \nabla_{\theta} \mathcal{L}(\theta)$

Algorytm regresji liniowej zakłada:

$$f_{ heta}(x) = heta^T x \ \mathcal{L}(x,y, heta) = (f_{ heta}(x)-y)^2$$

Algorytm regresji logistcznej zakłada:

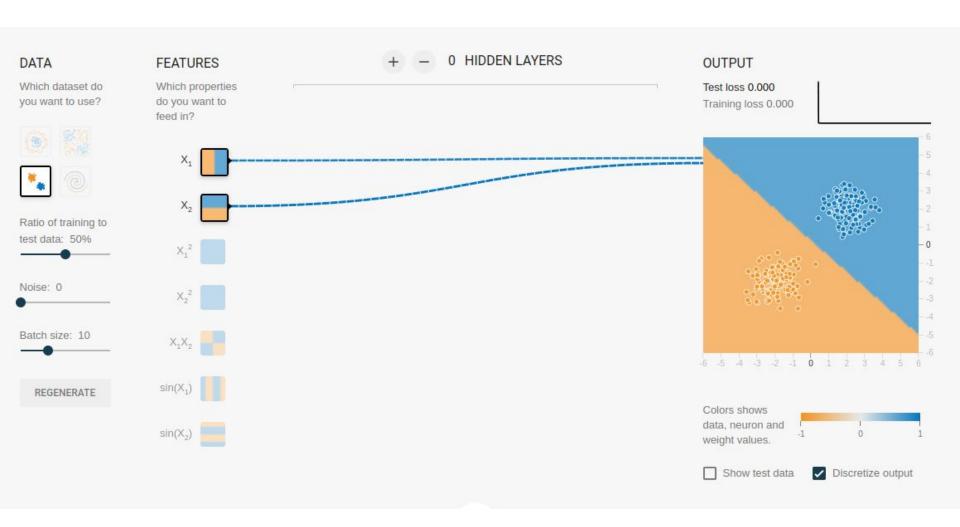
$$f_{ heta}(x) = rac{1}{1 + e^{- heta^T x}} \ \mathcal{L}(x,y, heta) = H(f_{ heta}(x),y)$$

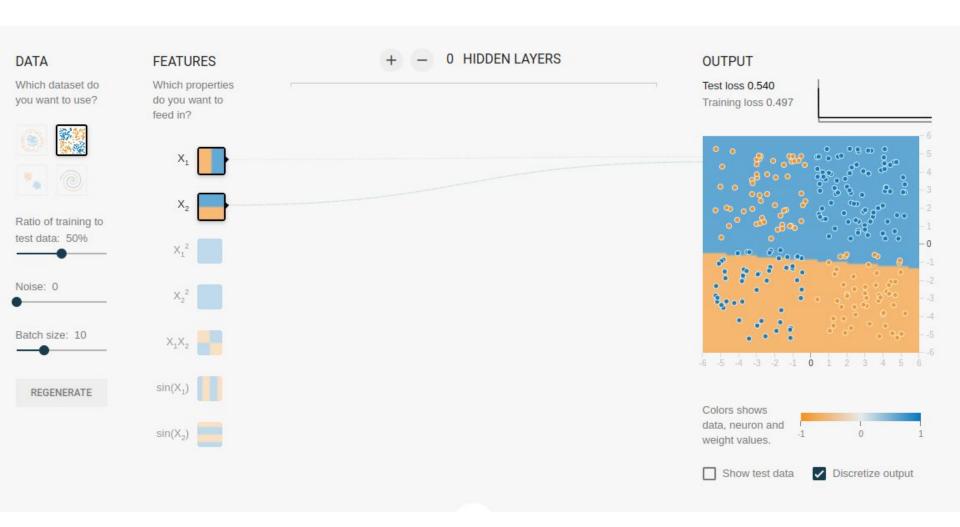
Algorytm regresji logistcznej z wieloma klasami (softmax regression/multinomal regression) zakłada:

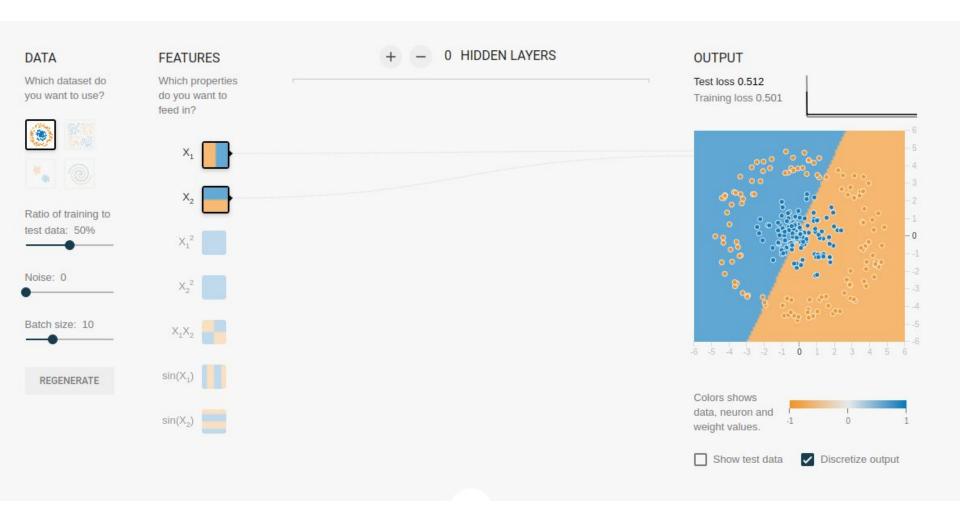
$$f_{\theta}(x) = softmax(\theta^T x)$$

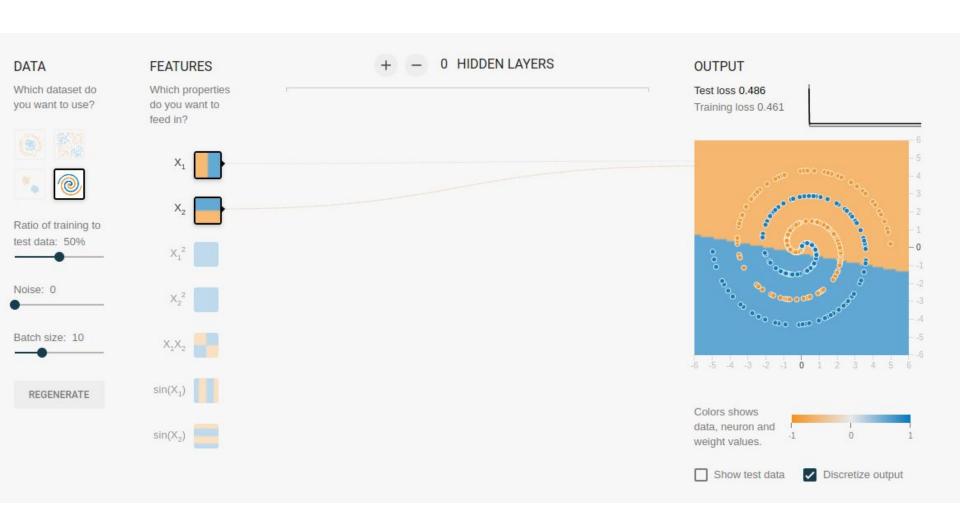
gdzie

$$egin{aligned} softmax(x_1,\dots,x_n) &= (rac{exp(x_i)}{exp(x_1)+\dots+exp(x_n)})_i \ \mathcal{L}(x,y, heta) &= H(f_{ heta}(x),y) \end{aligned}$$



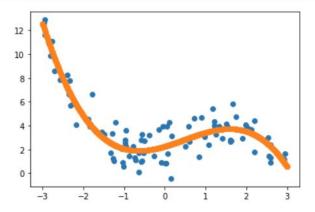






Przypomnienie – feature engineering

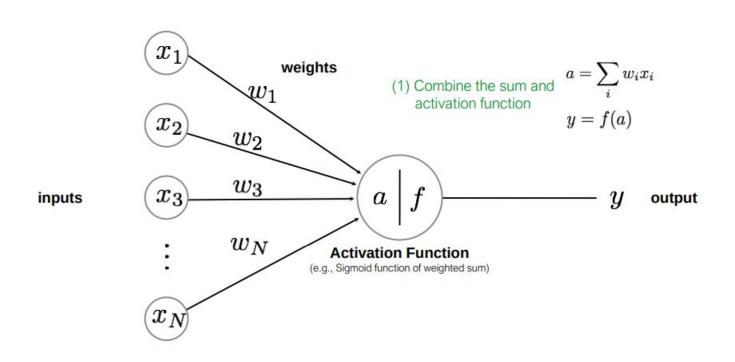
Zwizualizujmy dopasowanie naszego modelu:



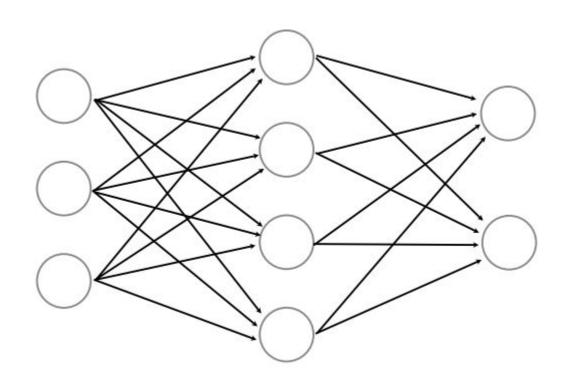
Jak rozwiązać te problemy?

- Feature engineering (inżynieria cech)
- Silniejszy, nieliniowy model

Model Regresji Liniowej, ale inaczej

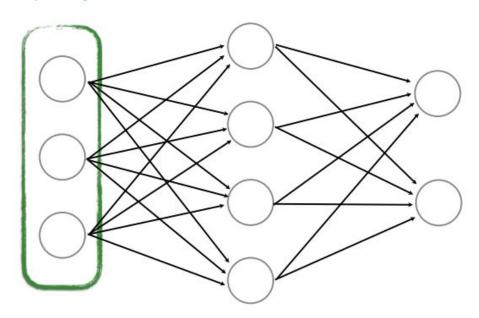


Dlaczego by nie dołożyć dodatkowych węzłów?

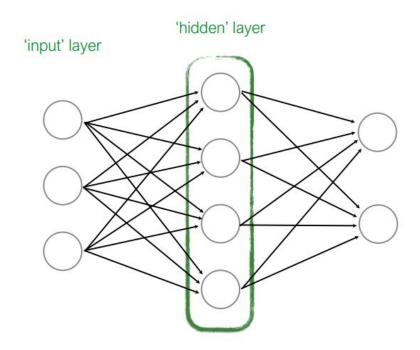


Nazewnictwo

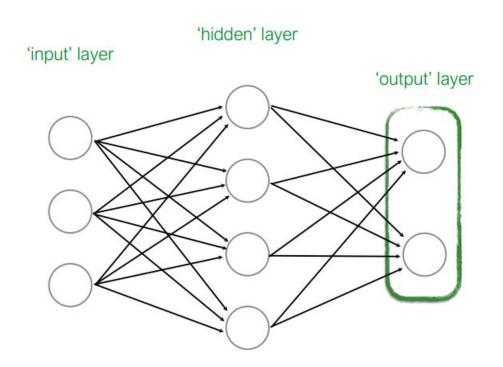
'input' layer



Nazewnictwo



Nazewnictwo



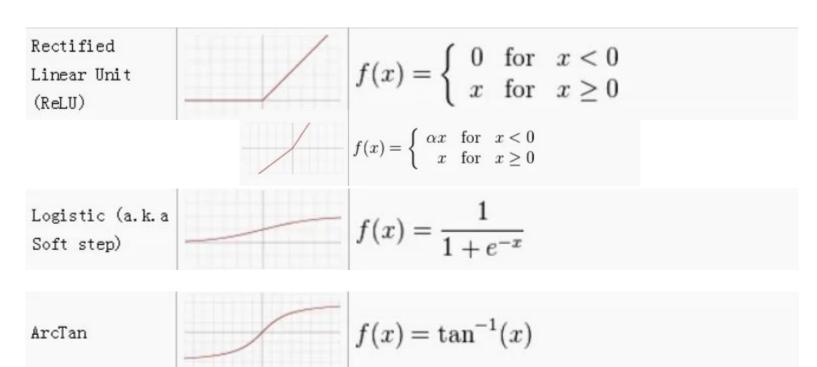
Problem? To nie jest silniejsza klasa modeli

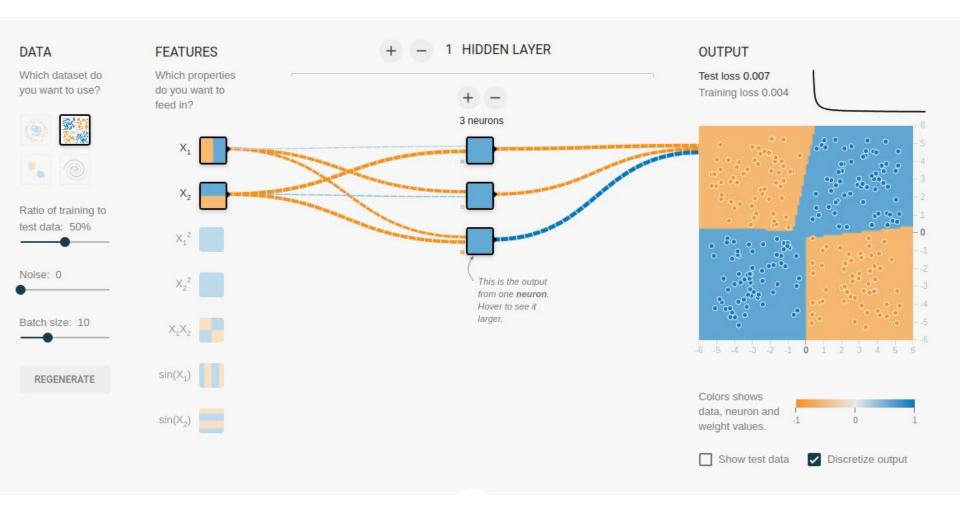
$$y=W_2W_1x=W^{\prime}x,\; ext{gdzie}\; W=W_2W_1$$

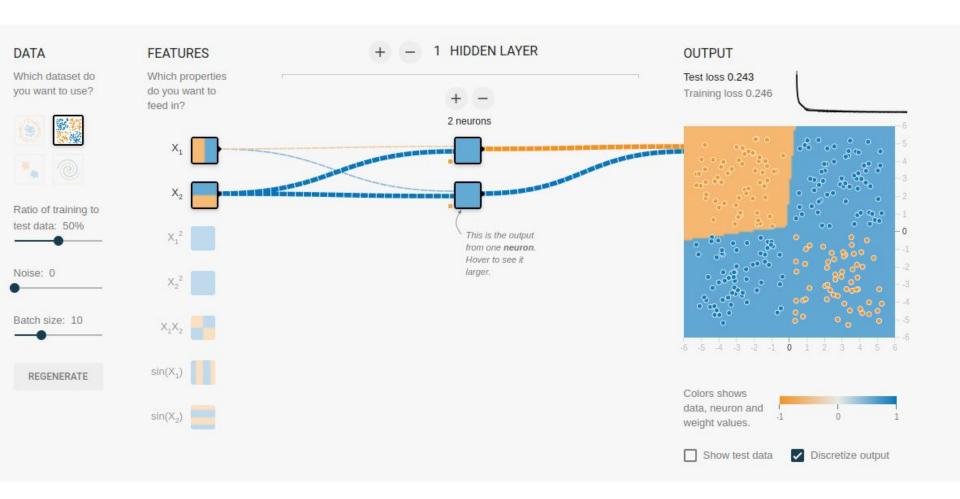
Złamanie liniowości

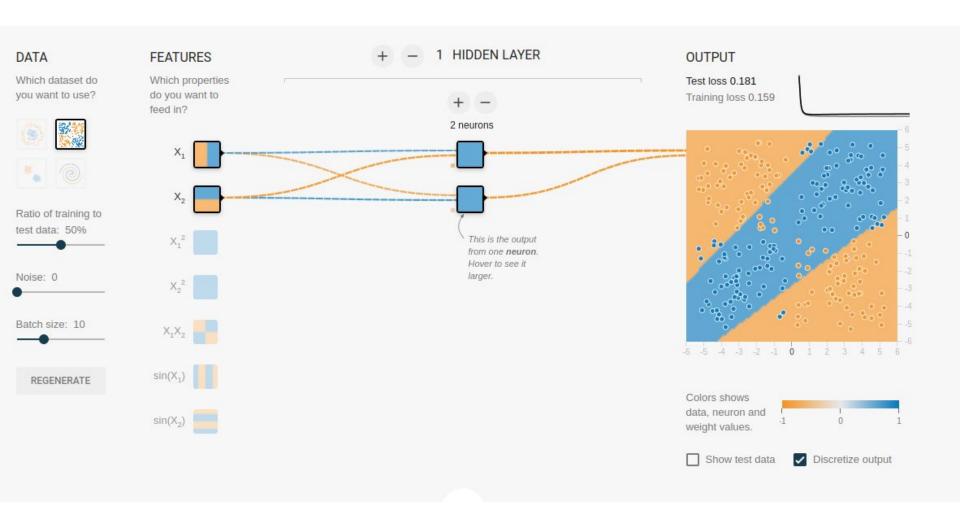
$$y = f(W_2 f(W_1 x))$$
, gdzie f nieliniowa

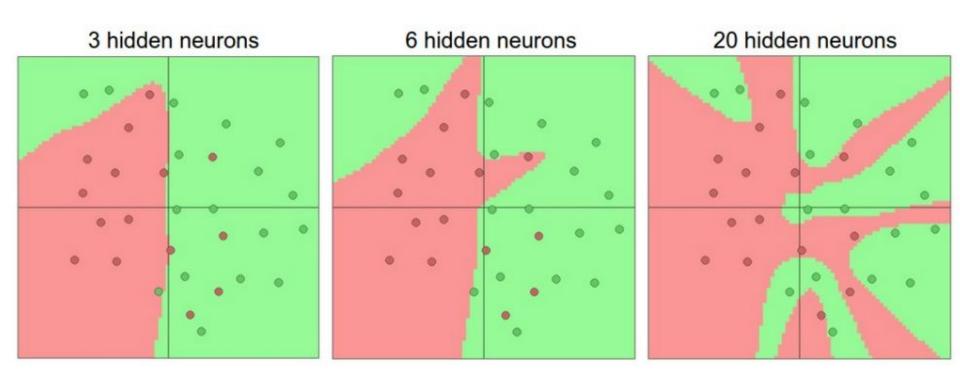
Sprawdzone wybory funkcji aktywacji f



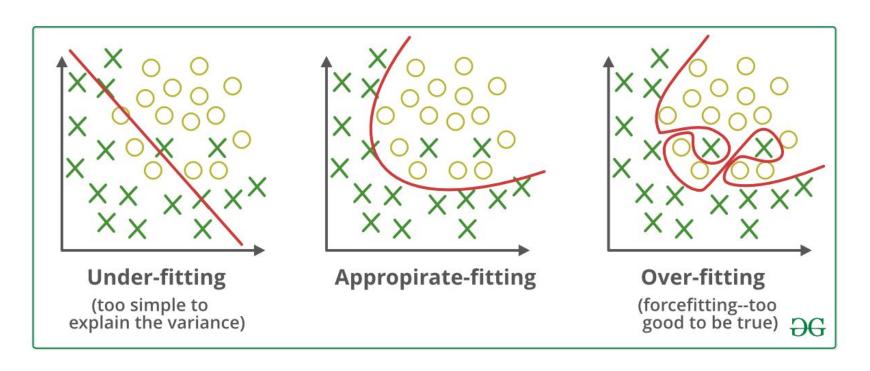


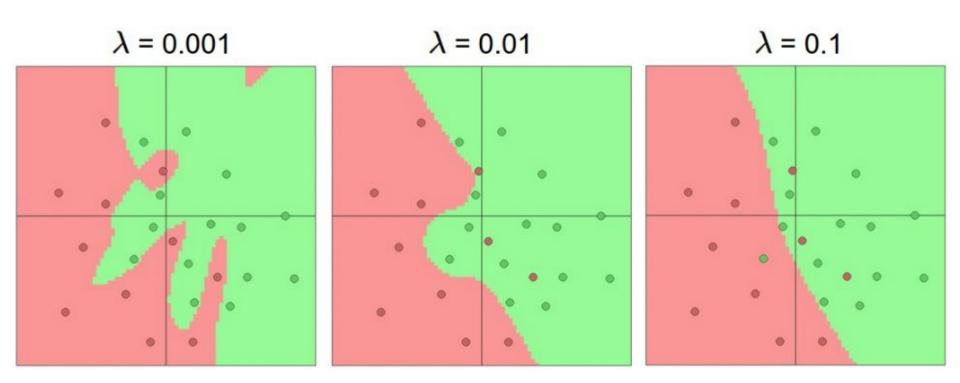


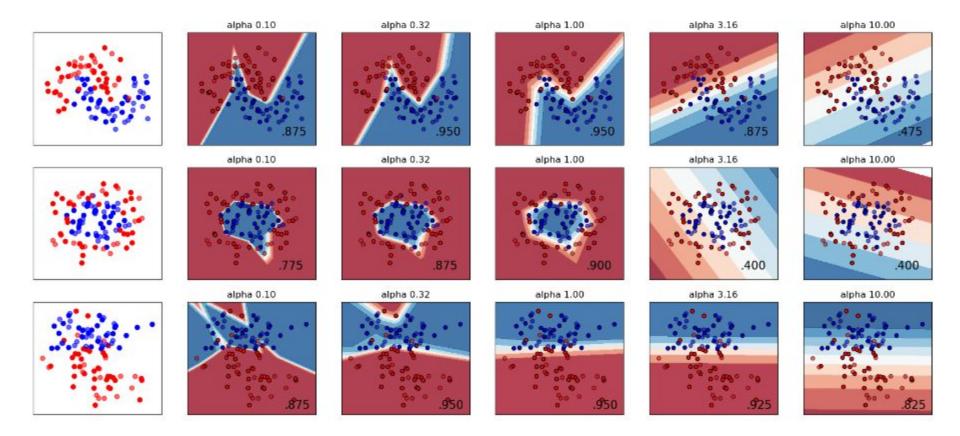




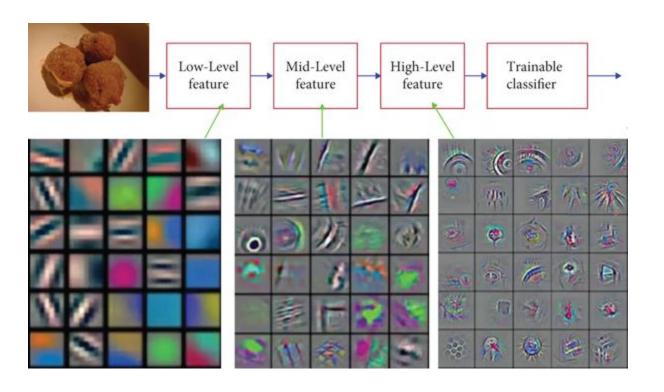
Przypomnienie – problem przeuczenia (overfitting)





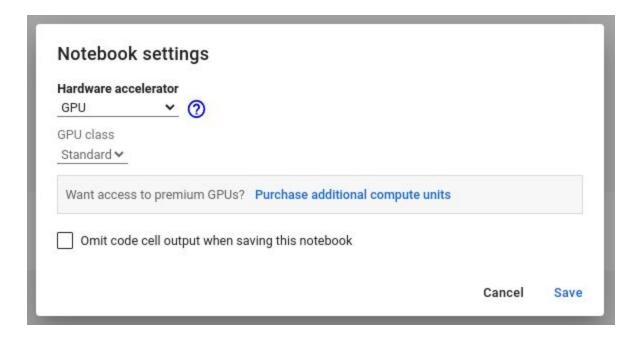


Hierarchiczność/kompozycyjność reprezentacji



- Przykłady na slajdach zostały stworzone z użyciem <u>https://playground.tensorflow.org/</u>
- Proszę poeksperymentować ze:
 - Zbiorami danych
 - Architekturą sieci neuronowej
 - Współczynnikiem uczenia (learning rate)
 - Funkcją aktywacji

- Będziemy rozwiązywać zadanie klasyfikacji z użyciem sieci neuronowych
- Będziemy pracować na zbiorze danych CIFAR10
- Porównamy jakość modelu sieci neuronowej z modelem liniowym



```
Invidia-smi
Thu Apr 13 07:00:44 2023
 NVIDIA-SMI 525.85.12 Driver Version: 525.85.12 CUDA Version: 12.0
 GPU Name Persistence-M| Bus-Id Disp.A | Volatile Uncorr. ECC
 Fan Temp Perf Pwr:Usage/Cap| Memory-Usage | GPU-Util Compute M.
                                                           MTG M.
   0 Tesla T4 Off | 00000000:00:04.0 Off |
 N/A 71C P8 11W / 70W |
                                0MiB / 15360MiB | 0% Default
                                                             N/A
 Processes:
      GI CI PID Type Process name
                                                   GPU Memory
       ID
                                                       Usage
  No running processes found
```

Krok 1: Import podstawowy bibliotek

```
[2] import torch
import torch.nn as nn
import torch.optim as optim
import torchvision
import torchvision.transforms as transforms
```

Krok 2: Wczytanie zbioru danych CIFAR10

```
# Define the transforms to be applied to the CIFAR-10 dataset transform = transforms.Compose(
    [transforms.ToTensor(),
        transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])
```

```
# Load the CIFAR-10 training and test datasets
trainset = torchvision.datasets.CIFAR10(
    root='./data',
    train=True,
    download=True,
    transform=transform
)
```

```
trainloader = torch.utils.data.DataLoader(
    trainset,
    batch_size=4,
    shuffle=True,
    num_workers=2
)
```

```
testset = torchvision.datasets.CIFAR10(
    root='./data',
    train=False,
    download=True,
    transform=transform
testloader = torch.utils.data.DataLoader(
    testset.
    batch_size=4,
    shuffle=False,
    num workers=2
Downloading <a href="https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz">https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz</a> to ./data/cifar-10-python.tar.gz
             170498071/170498071 [00:03<00:00, 43232169.68it/s]
```

Downloading https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz to ./data/cifar-10-python.tar.gz to ./data/cifar-10-python.tar.gz to ./data

Extracting ./data/cifar-10-python.tar.gz to ./data

Files already downloaded and verified

Krok 3: Wizualizacja zbioru danych CIFAR10

```
import matplotlib.pyplot as plt
   import numpy as np
   # Define the classes for the CIFAR-10 dataset
   classes = ('plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
   # Get some random training images
   dataiter = iter(trainloader)
   images, labels = dataiter.__next__()
   # Show the images
   fig, axes = plt.subplots(1, len(images), figsize=(10,2))
   for i, image in enumerate(images):
       # Unnormalize the image
       image = image / 2 + 0.5
       np_image = image.numpy()
       # Transpose the channels to display the image
       transposed = np.transpose(np_image, (1, 2, 0))
       # Show the image
       axes[i].imshow(transposed)
       axes[i].set_title(classes[labels[i]])
   # Display the images
   plt.show()
C>
```



Krok 4. Definicja modelu sieci neuronowej oraz modelu liniowego

```
class MLP(nn.Module):
    def __init__(self):
        super(MLP, self).__init__()
        self.fc1 = nn.Linear(32*32*3, 512)
        self.fc2 = nn.Linear(512, 256)
        self.fc3 = nn.Linear(256, 10)
    def forward(self, x):
         TODO: your code goes here.
         Hints:
            * flatten the image before passing it through layers
            * use self.fc1, self.fc2, self.fc3
            * apply nonlinearity nn.functional.relu after every layer
       return x
```

```
class LinearModel(nn.Module):
    def __init__(self):
        super(LinearModel, self).__init__()
        self.linear = nn.Linear[32*32*3, 10]]

def forward(self, x):
        """
        TODO: your code goes here.
        Hints:
            * flatten the image before passing it through layers
            * use self.linear
            """
        return x
```

Krok 5. Implementacja pętli uczącej

```
def train(net, criterion, optimizer, trainloader, device):
    running loss = 0.0
    for i, data in enumerate(trainloader, 0):
        inputs, labels = data
          TODO: move the inputs and labels to device
        optimizer.zero grad()
        0.00
          TODO:
            1. pass the inputs through the model to obtain the outputs
            2. calculate the criterion loss, based on the outputs and labels
            3. calculate the gradients using loss object
            4. perform the optimization step using optimizer
        0.00
        running_loss += loss.item()
    return running_loss / len(trainloader)
```

Krok 6. Wyuczenie modeli

```
# Define the device to be used
device = torch.device("cuda:0" if torch.cuda.is_available() else "cpu")

# Define the MLP model and optimizer
mlp_net = MLP().to(device)
mlp_criterion = nn.CrossEntropyLoss()
mlp_optimizer = optim.SGD(mlp_net.parameters(), lr=0.001, momentum=0.9)
"""

TODO:
    experiment with the learning rate
"""
```

```
# Define the linear model and optimizer
linear_net = LinearModel().to(device)
linear_criterion = nn.CrossEntropyLoss()
linear_optimizer = optim.SGD(linear_net.parameters(), lr=0.001, momentum=0.9)
"""
TODO:
    experiment with the learning rate
"""
```

```
# Define the number of epochs
epochs = 10
  TODO:
    experiment with length of the training, does adding more epochs helps?
# Train the MLP model
for epoch in range(epochs):
    train mlp loss = train(mlp net, mlp criterion, mlp optimizer, trainloader, device)
    print('Epoch %d MLP loss: %.3f' % (epoch + 1, train mlp loss))
# Train the linear model
for epoch in range(epochs):
    train linear loss = train(linear net, linear criterion, linear optimizer, trainloader, device)
    print('Epoch %d Linear loss: %.3f' % (epoch + 1, train linear loss))
```

```
Epoch 1 MLP loss: 1.649
Epoch 2 MLP loss: 1.419
Epoch 3 MLP loss: 1.304
Epoch 4 MLP loss: 1.215
Epoch 5 MLP loss: 1.136
Epoch 6 MLP loss: 1.066
Epoch 7 MLP loss: 0.993
Epoch 8 MLP loss: 0.930
Epoch 9 MLP loss: 0.870
Epoch 10 MLP loss: 0.810
Epoch 1 Linear loss: 2.153
Epoch 2 Linear loss: 2.106
Epoch 3 Linear loss: 2.080
Epoch 4 Linear loss: 2.067
Epoch 5 Linear loss: 2.057
Epoch 6 Linear loss: 2.057
Epoch 7 Linear loss: 2.046
Epoch 8 Linear loss: 2.046
Epoch 9 Linear loss: 2.039
Epoch 10 Linear loss: 2.030
```

Krok 7. Ewaluacja modeli na zbiorze testowym

```
# Evaluate the models on the test set
   mlp_correct = 0
   linear correct = 0
   total = 0
   with torch.no_grad():
        for data in testloader:
            images, labels = data
            images, labels = images.to(device), labels.to(device)
            mlp_outputs = mlp_net(images)
            _, mlp_predicted = torch.max(mlp_outputs.data, 1)
            linear_outputs = linear_net(images)
            _, linear_predicted = torch.max(linear_outputs.data, 1)
            total += labels.size(0)
            mlp_correct += (mlp_predicted == labels).sum().item()
            linear_correct += (linear_predicted == labels).sum().item()
   mlp_accuracy = """ TODO: your code goes here """
   linear_accuracy = """ TODO: your code goes here """
    print('MLP Accuracy on the test images: %d %%' % mlp_accuracy)
    print('Linear Accuracy on the test images: %d %%' % linear accuracy)
MLP Accuracy on the test images: 53 %
   Linear Accuracy on the test images: 33 %
```

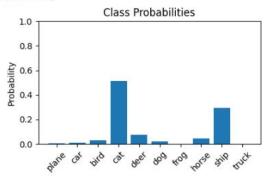
Krok 8. Wizualizacja predykcji obu modeli

```
# Get a batch of test images
testloader = torch.utils.data.DataLoader(
   testset,
    batch size=32,
    shuffle=False,
    num_workers=2
dataiter = iter(testloader)
images, labels = dataiter.__next__()
# Move the images to the device
images = images.to(device)
# Get the MLP predictions and output probabilities
mlp outputs = mlp net(images)
mlp predicted = torch.max(mlp outputs, 1)[1]
mlp_probs = torch.nn.functional.softmax(mlp_outputs, dim=1)
# Get the linear predictions and output probabilities
linear outputs = linear net(images.view(images.size(0), -1))
linear_predicted = torch.max(linear_outputs, 1)[1]
linear_probs = torch.nn.functional.softmax(linear_outputs, dim=1)
```

```
# Define the labels for the classes
classes = ('plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
# Define a function to show an image along with its predicted class and probabilities
def imshow probs(img, title, probs):
    img = img / 2 + 0.5 # unnormalize the image
    npimg = img.numpy()
   fig, (ax1, ax2) = plt.subplots(ncols=2, figsize=(8,3))
    ax1.imshow(np.transpose(npimg, (1, 2, 0)))
    ax1.set_title(title)
   ax1.axis('off')
    ax2.bar(classes, probs)
    ax2.set xticklabels(classes, rotation=45)
    ax2.set vlim([0, 1])
    ax2.set vlabel('Probability')
    ax2.set_title('Class Probabilities')
    fig.tight_layout()
# Show the images with their predicted classes and probabilities for the MLP model
for i in range(10):
    print("MLP:")
    mlp probs i = mlp probs[i].cpu().detach().numpy()
    imshow_probs(images[i].cpu(), classes[mlp_predicted[i]], mlp_probs_i)
    plt.show()
    print("Linear:")
    linear_probs_i = linear_probs[i].cpu().detach().numpy()
    imshow probs(images[i].cpu(), classes[linear predicted[i]], linear probs i)
    plt.show()
```

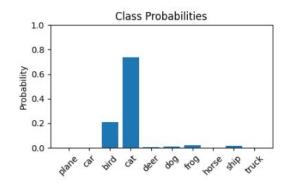
MLP:
<ipython-input-11-f1c0206d2b07>:37: UserWarning: FixedFormatter should only be used together with FixedLocator
ax2.set_xticklabels(classes, rotation=45)





Linear:



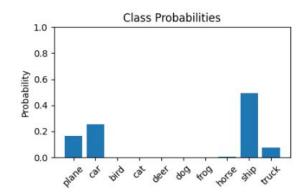


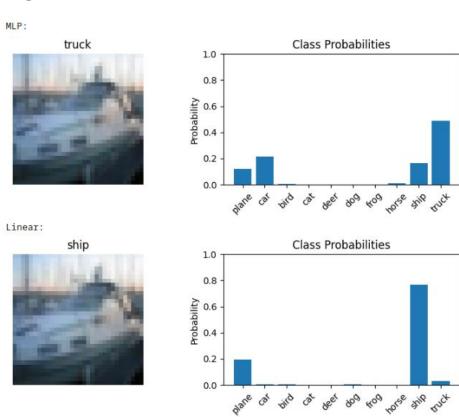
MLP:



Linear:

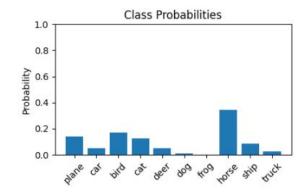
ship





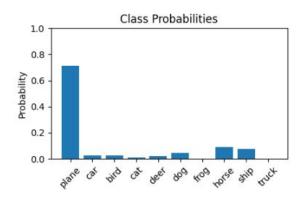
MLP:





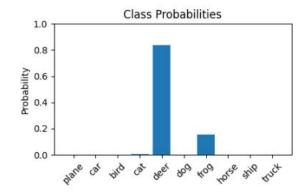
Linear:





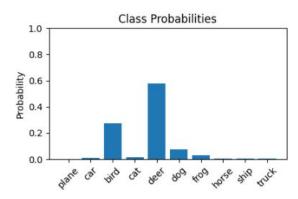


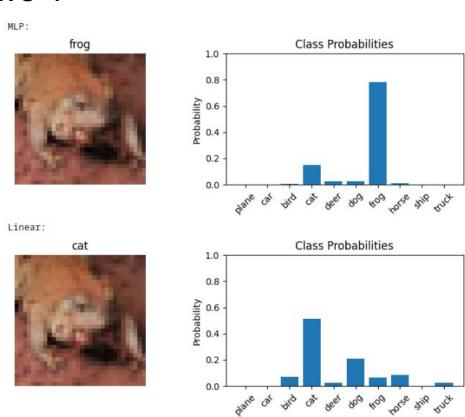


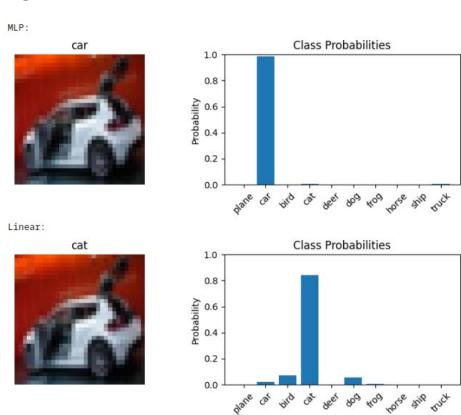


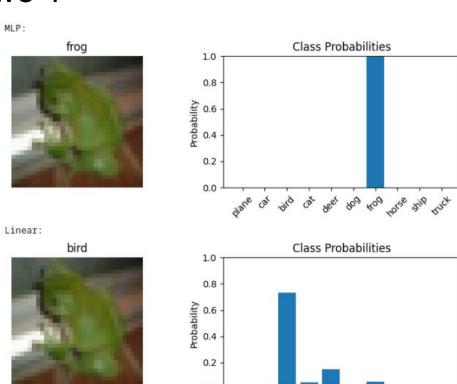
Linear:



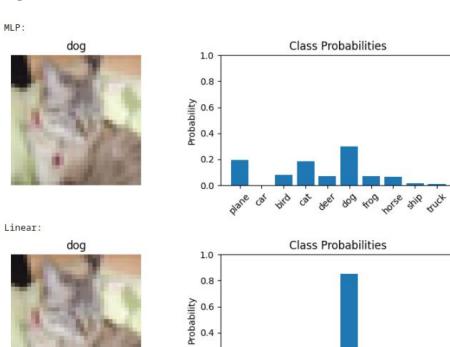








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