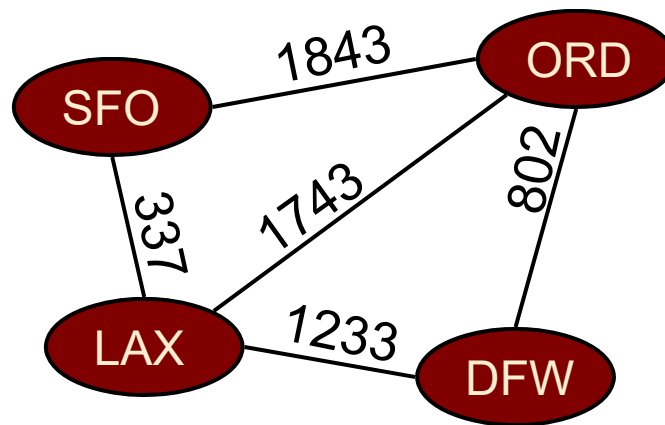
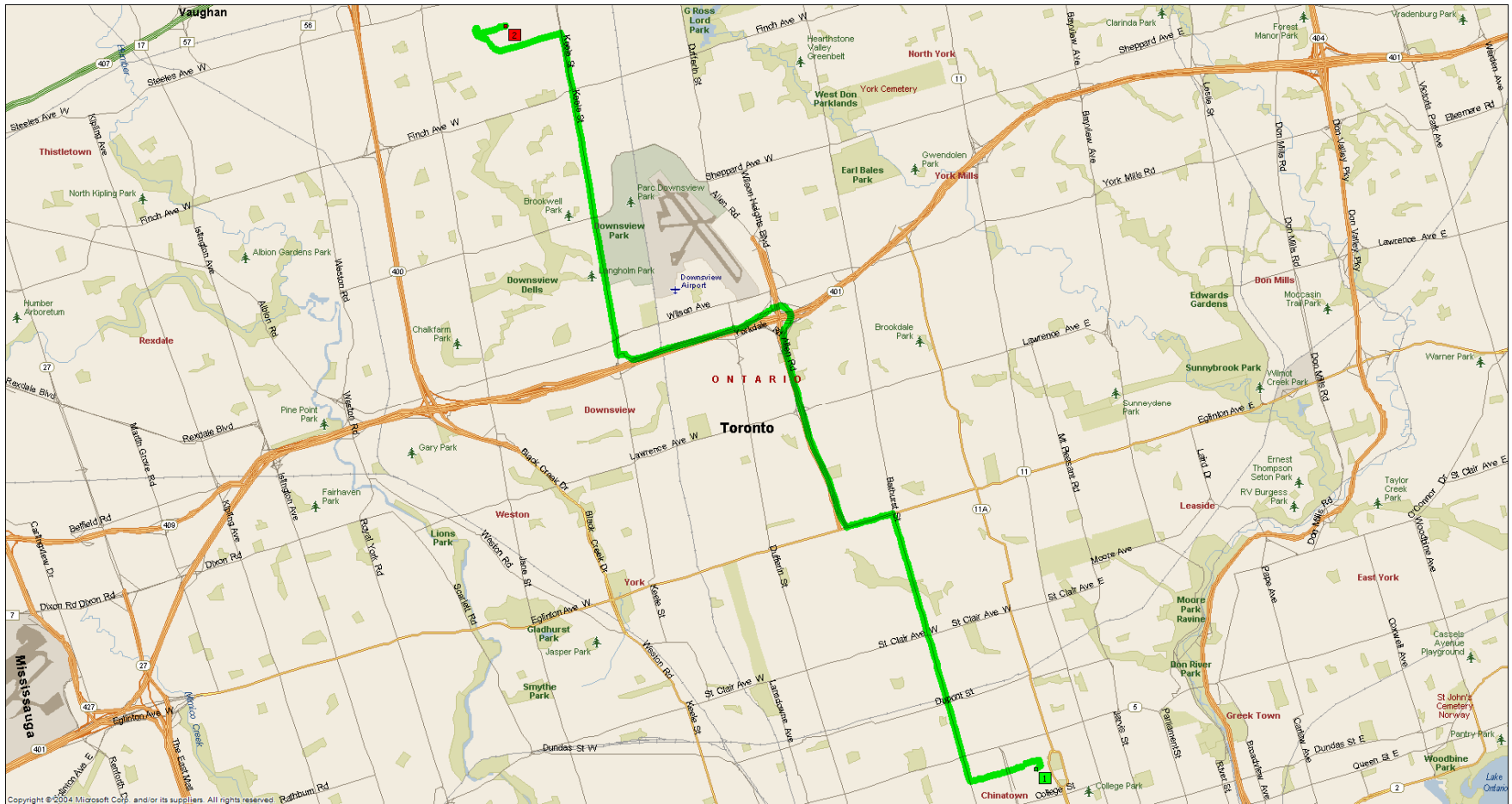


Graphs – Depth First Search



Graph Search Algorithms



Outline

- DFS Algorithm
- DFS Example
- DFS Applications

Outline

- **DFS Algorithm**
- DFS Example
- DFS Applications

Depth First Search (DFS)

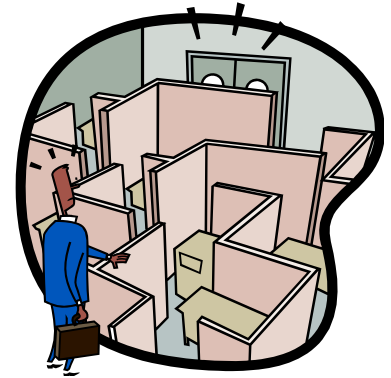
➤ Idea:

- ❑ Continue searching “deeper” into the graph, until we get stuck.
- ❑ If all the edges leaving v have been explored we “backtrack” to the vertex from which v was discovered.
- ❑ Analogous to Euler tour for trees

➤ Used to help solve many graph problems, including

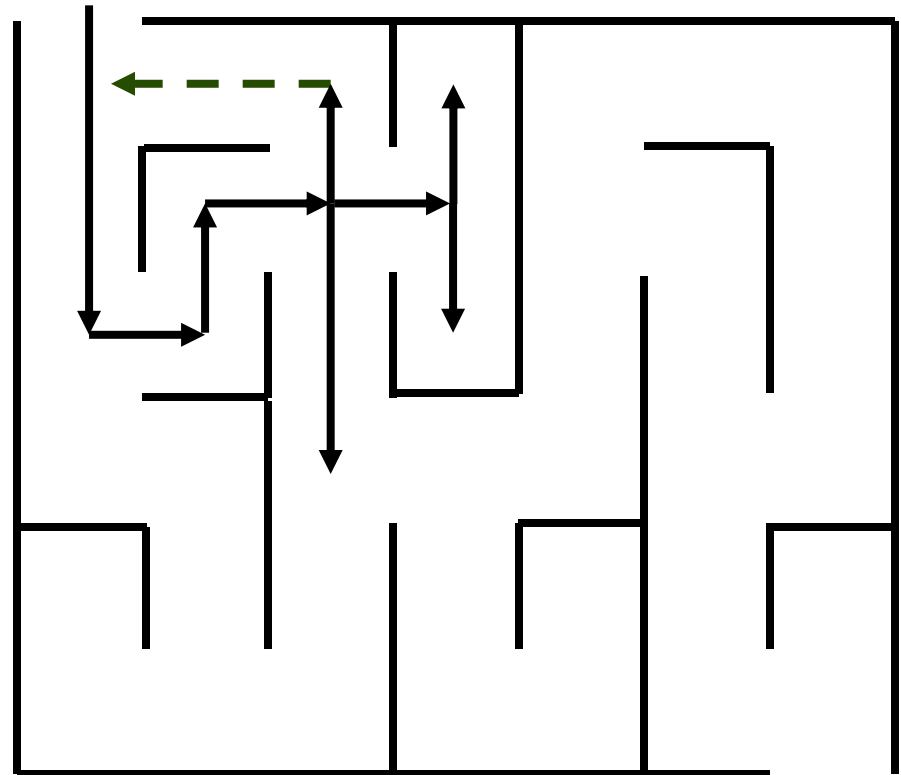
- ❑ Nodes that are reachable from a specific node v
- ❑ Detection of cycles
- ❑ Extraction of strongly connected components
- ❑ Topological sorts

Depth-First Search



➤ The DFS algorithm is similar to a classic strategy for exploring a maze

- ❑ We mark each intersection, corner and dead end (vertex) visited
- ❑ We mark each corridor (edge) traversed
- ❑ We keep track of the path back to the entrance (start vertex) by means of a rope (recursion stack)

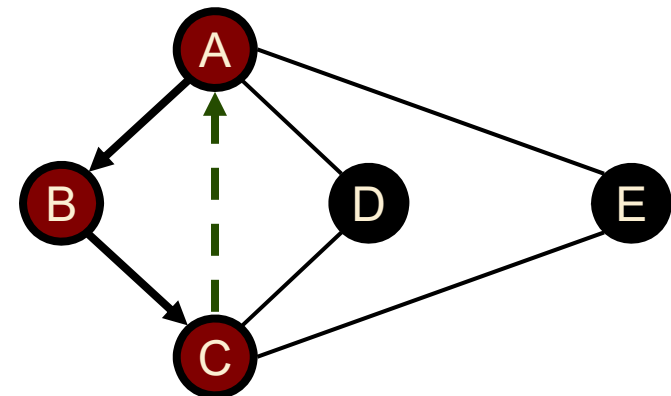
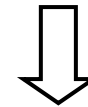
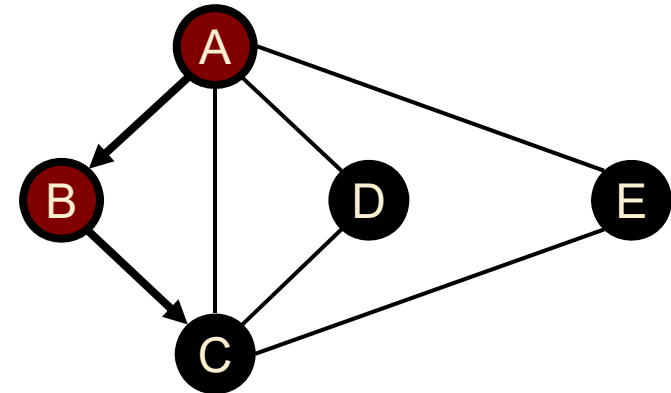
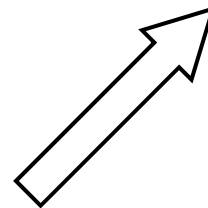
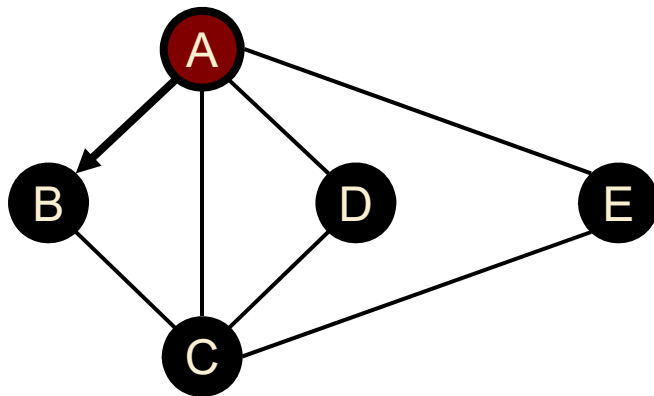
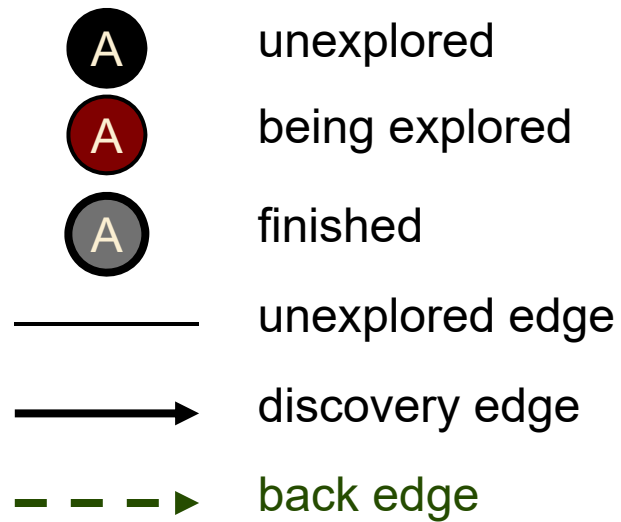


Depth-First Search

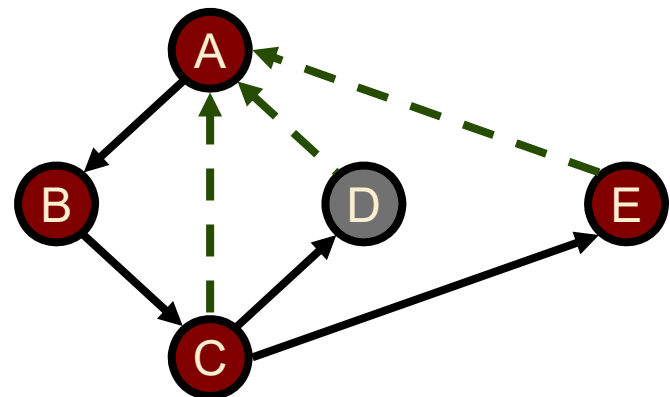
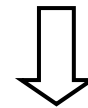
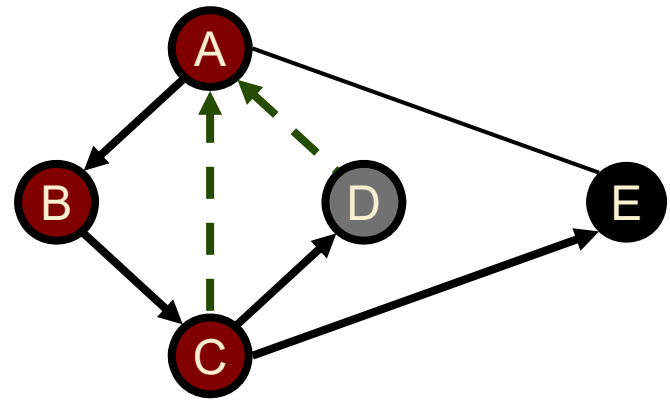
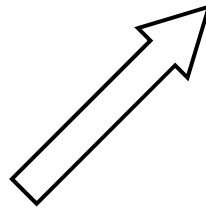
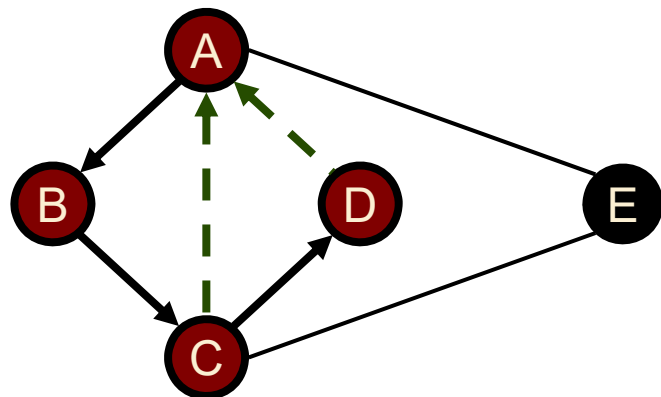
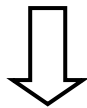
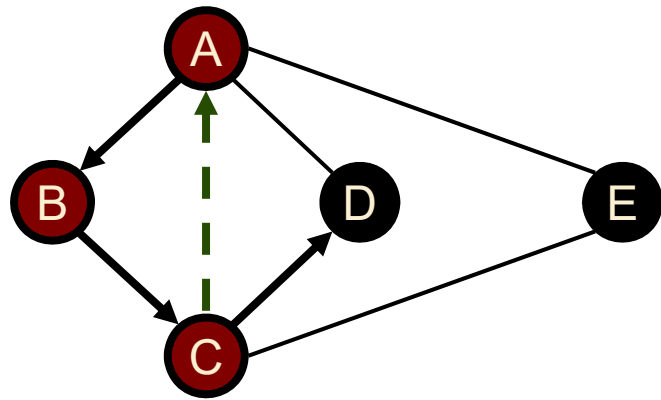
Input: Graph $G = (V, E)$ (directed or undirected)

- Explore *every* edge, starting from different vertices if necessary.
- As soon as vertex discovered, explore from it.
- Keep track of progress by colouring vertices:
 - ❑ Black: undiscovered vertices
 - ❑ Red: discovered, but not finished (still exploring from it)
 - ❑ Gray: finished (found everything reachable from it).

DFS Example on Undirected Graph



Example (cont.)



DFS Algorithm Pattern

DFS(G)

Precondition: G is a graph

Postcondition: all vertices in G have been visited

for each vertex $u \in V[G]$

$\text{color}[u] = \text{BLACK}$ //initialize vertex

for each vertex $u \in V[G]$

 if $\text{color}[u] = \text{BLACK}$ //as yet unexplored

 DFS-Visit(u)



DFS Algorithm Pattern



DFS-Visit (u)

Precondition: vertex u is undiscovered

Postcondition: all vertices reachable from u have been processed

$\text{colour}[u] \leftarrow \text{RED}$

for each $v \in \text{Adj}[u]$ //explore edge (u, v)

if $\text{color}[v] = \text{BLACK}$

DFS-Visit(v)

$\text{colour}[u] \leftarrow \text{GRAY}$



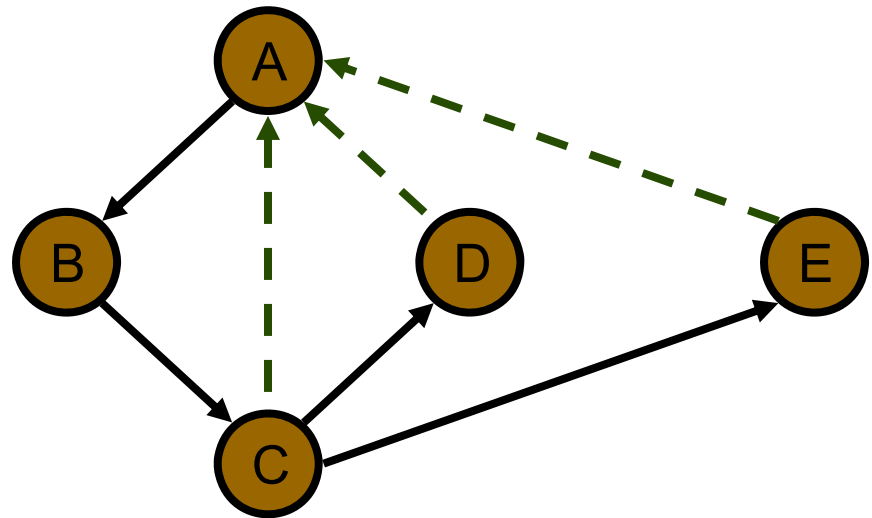
Properties of DFS

Property 1

DFS-Visit(u) visits all the vertices and edges in the connected component of u

Property 2

The discovery edges labeled by *DFS-Visit*(u) form a spanning tree of the connected component of u



DFS Algorithm Pattern

DFS(G)

Precondition: G is a graph

Postcondition: all vertices in G have been visited

for each vertex $u \in V[G]$

 color[u] = BLACK //initialize vertex

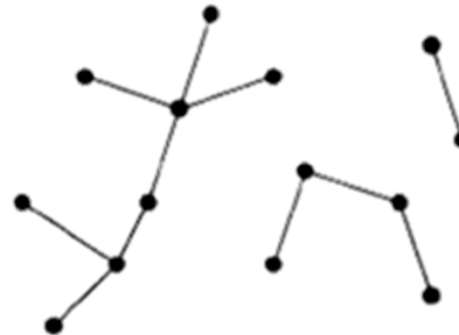
for each vertex $u \in V[G]$

 if color[u] = BLACK //as yet unexplored

 DFS-Visit(u)

total work

= $\theta(V)$



DFS Algorithm Pattern

DFS-Visit (u)

Precondition: vertex u is undiscovered

Postcondition: all vertices reachable from u have been processed

$\text{colour}[u] \leftarrow \text{RED}$

for each $v \in \text{Adj}[u]$ //explore edge (u,v)

if $\text{color}[v] = \text{BLACK}$

DFS-Visit(v)

$\text{colour}[u] \leftarrow \text{GRAY}$

$$\left. \begin{array}{l} \text{total work} \\ = \sum_{v \in V} |\text{Adj}[v]| = \theta(E) \end{array} \right\}$$



Thus running time = $\theta(V + E)$

(assuming adjacency list structure)

Variants of Depth-First Search

- In addition to, or instead of labeling vertices with colours, they can be labeled with **discovery** and **finishing** times.
- 'Time' is an integer that is incremented whenever a vertex changes state
 - ❑ from **unexplored** to **discovered**
 - ❑ from **discovered** to **finished**
- These **discovery** and **finishing** times can then be used to solve other graph problems (e.g., computing strongly-connected components)

Input: Graph $G = (V, E)$ (directed or undirected)

Output: 2 timestamps on each vertex:

$d[v]$ = discovery time.

$f[v]$ = finishing time.

$$1 \leq d[v] < f[v] \leq 2|V|$$

DFS Algorithm with Discovery and Finish Times

DFS(G)

Precondition: G is a graph

Postcondition: all vertices in G have been visited

for each vertex $u \in V[G]$

$\text{color}[u] = \text{BLACK}$ //initialize vertex

time $\leftarrow 0$

for each vertex $u \in V[G]$

 if $\text{color}[u] = \text{BLACK}$ //as yet unexplored

 DFS-Visit(u)



DFS Algorithm with Discovery and Finish Times

DFS-Visit (u)

Precondition: vertex u is undiscovered

Postcondition: all vertices reachable from u have been processed

$\text{colour}[u] \leftarrow \text{RED}$

$\text{time} \leftarrow \text{time} + 1$

$d[u] \leftarrow \text{time}$

for each $v \in \text{Adj}[u]$ //explore edge (u,v)

if $\text{color}[v] = \text{BLACK}$

 DFS-Visit(v)

$\text{colour}[u] \leftarrow \text{GRAY}$

$\text{time} \leftarrow \text{time} + 1$

$f[u] \leftarrow \text{time}$



Other Variants of Depth-First Search

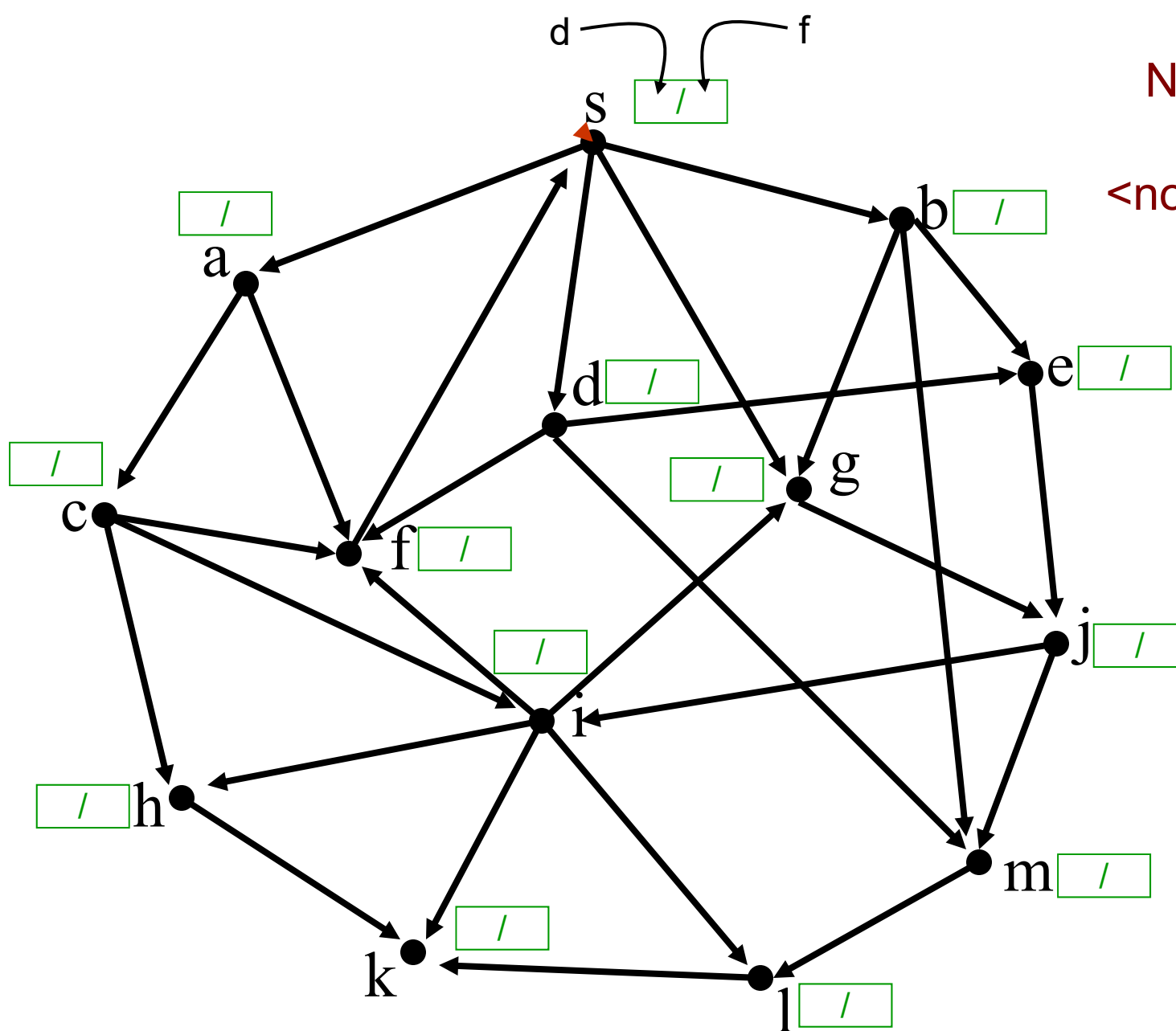
- The DFS Pattern can also be used to
 - ❑ Compute a forest of spanning trees (one for each call to DFS-visit) encoded in a predecessor list $\pi[u]$
 - ❑ Label edges in the graph according to their role in the search (see textbook)
 - ✧ **Tree edges**, traversed to an undiscovered vertex
 - ✧ **Forward edges**, traversed to a descendent vertex on the current spanning tree
 - ✧ **Back edges**, traversed to an ancestor vertex on the current spanning tree
 - ✧ **Cross edges**, traversed to a vertex that has already been discovered, but is not an ancestor or a descendent

Outline

- DFS Algorithm
- **DFS Example**
- DFS Applications

DFS

Note: Stack is Last-In First-Out (LIFO)

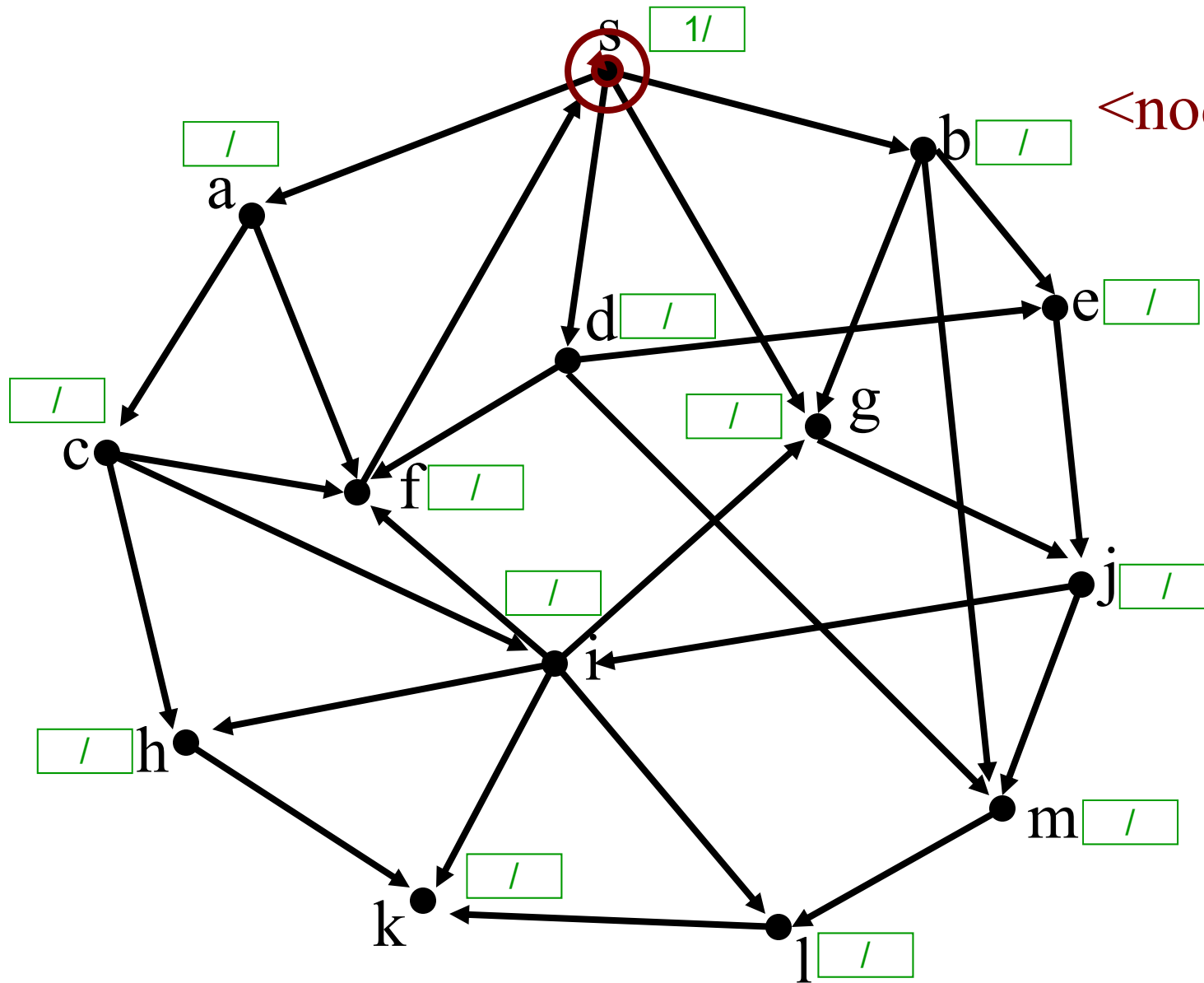


Found
Not Handled
Stack
<node,# edges>

DFS

Found
Not Handled
Stack

<node,# edges>

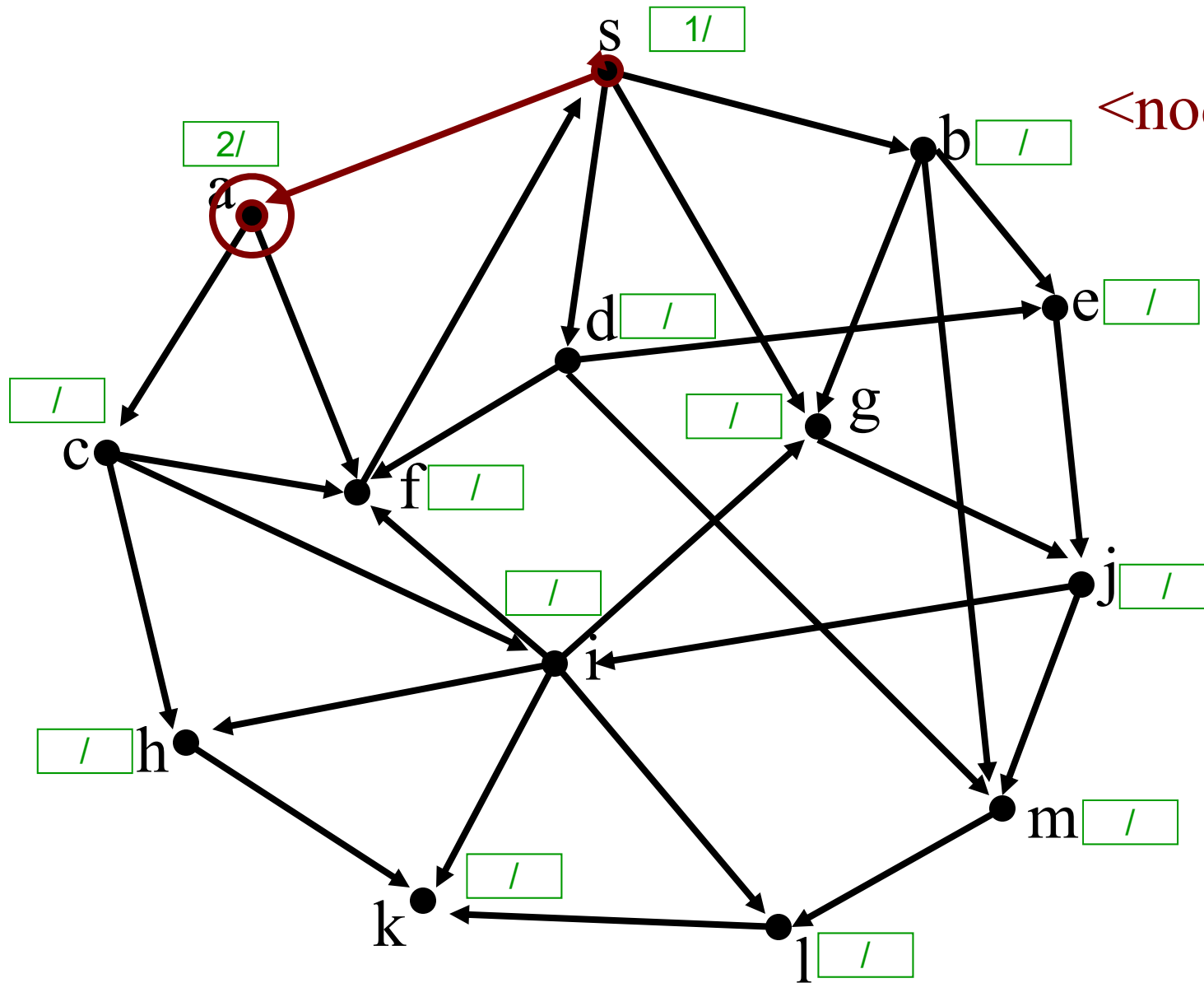


s,0

DFS

Found
Not Handled
Stack

<node,# edges>

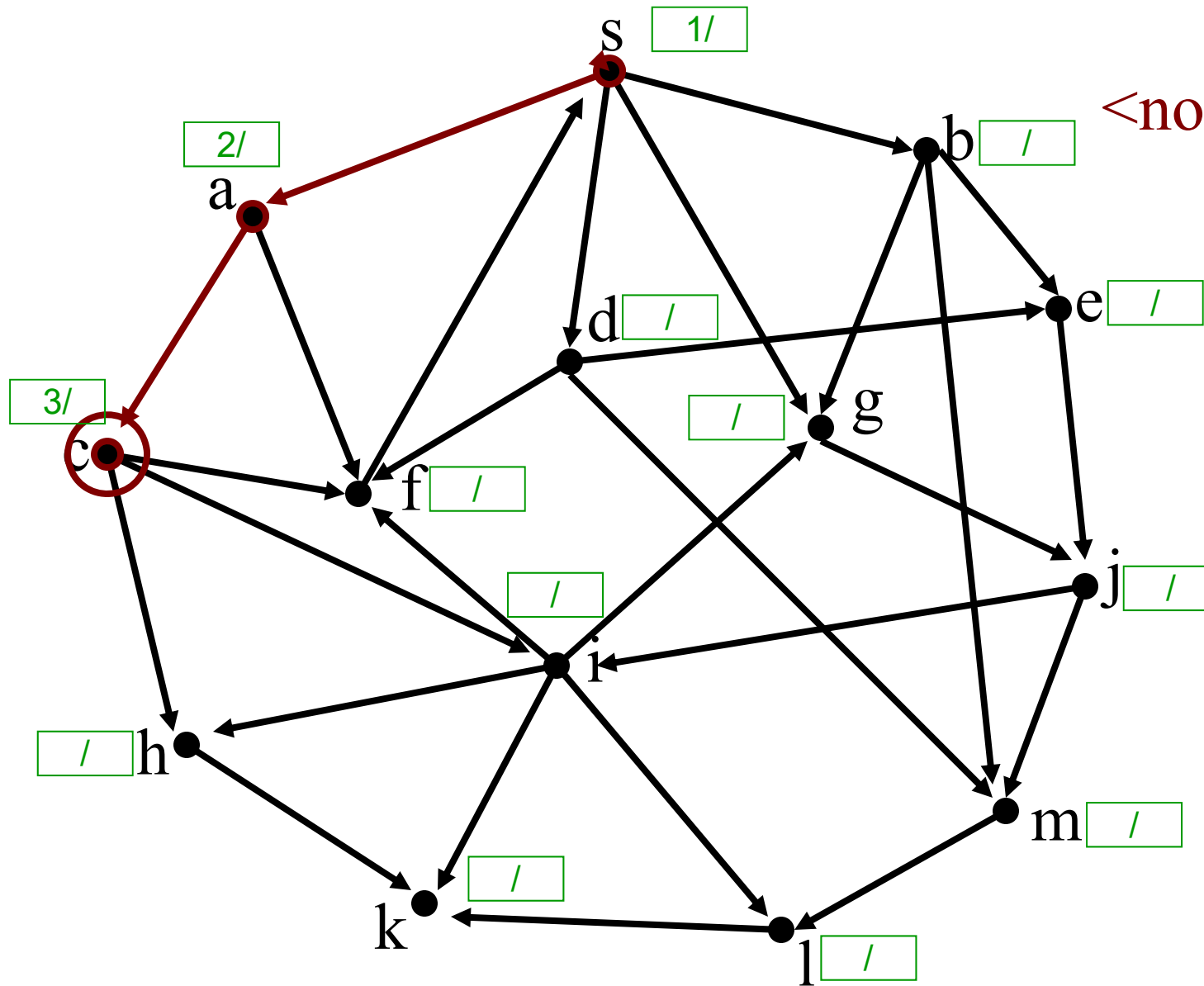


a,0
s,1

DFS

Found
Not Handled
Stack

<node,# edges>

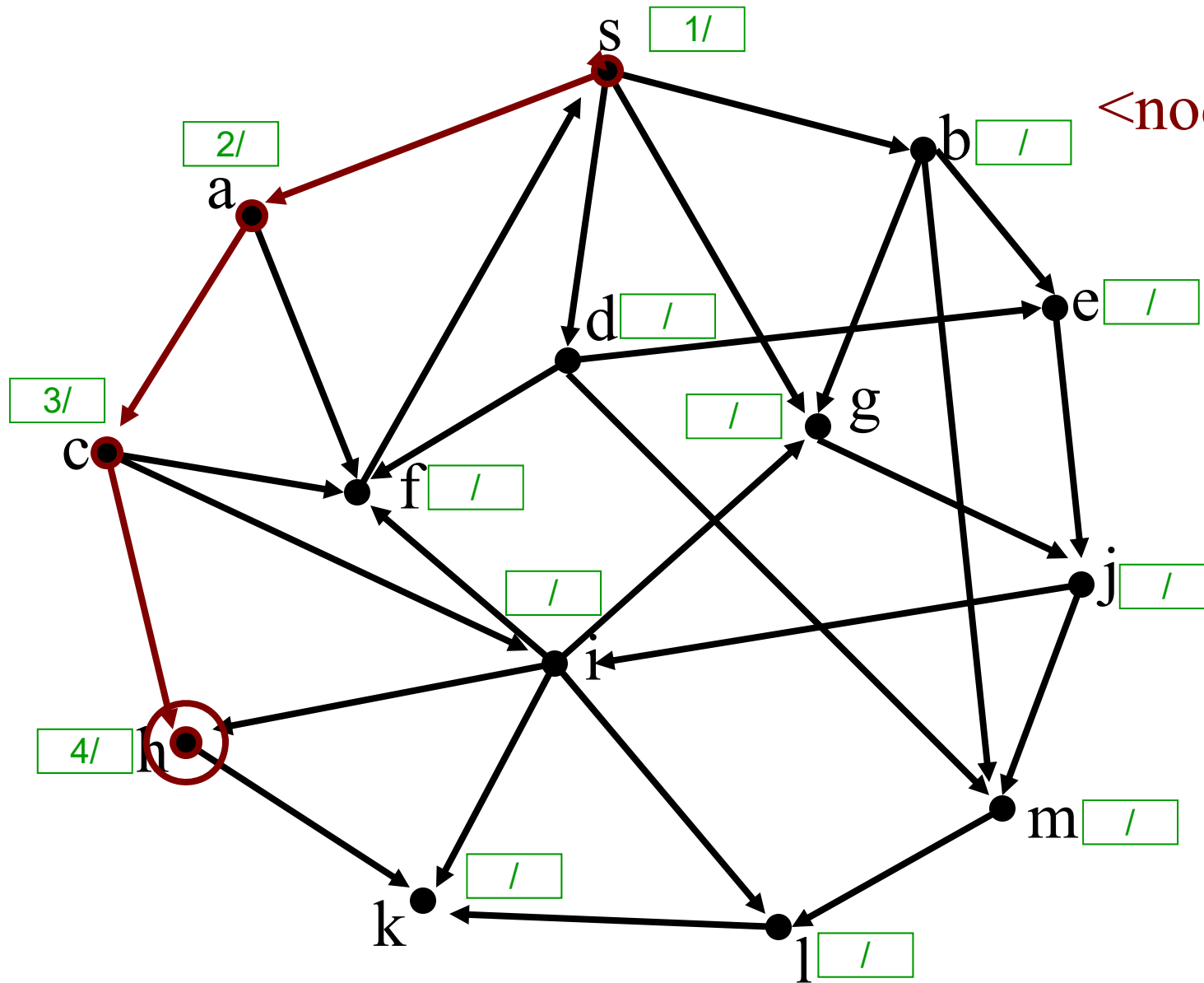


c,0
a,1
s,1

DFS

Found
Not Handled
Stack

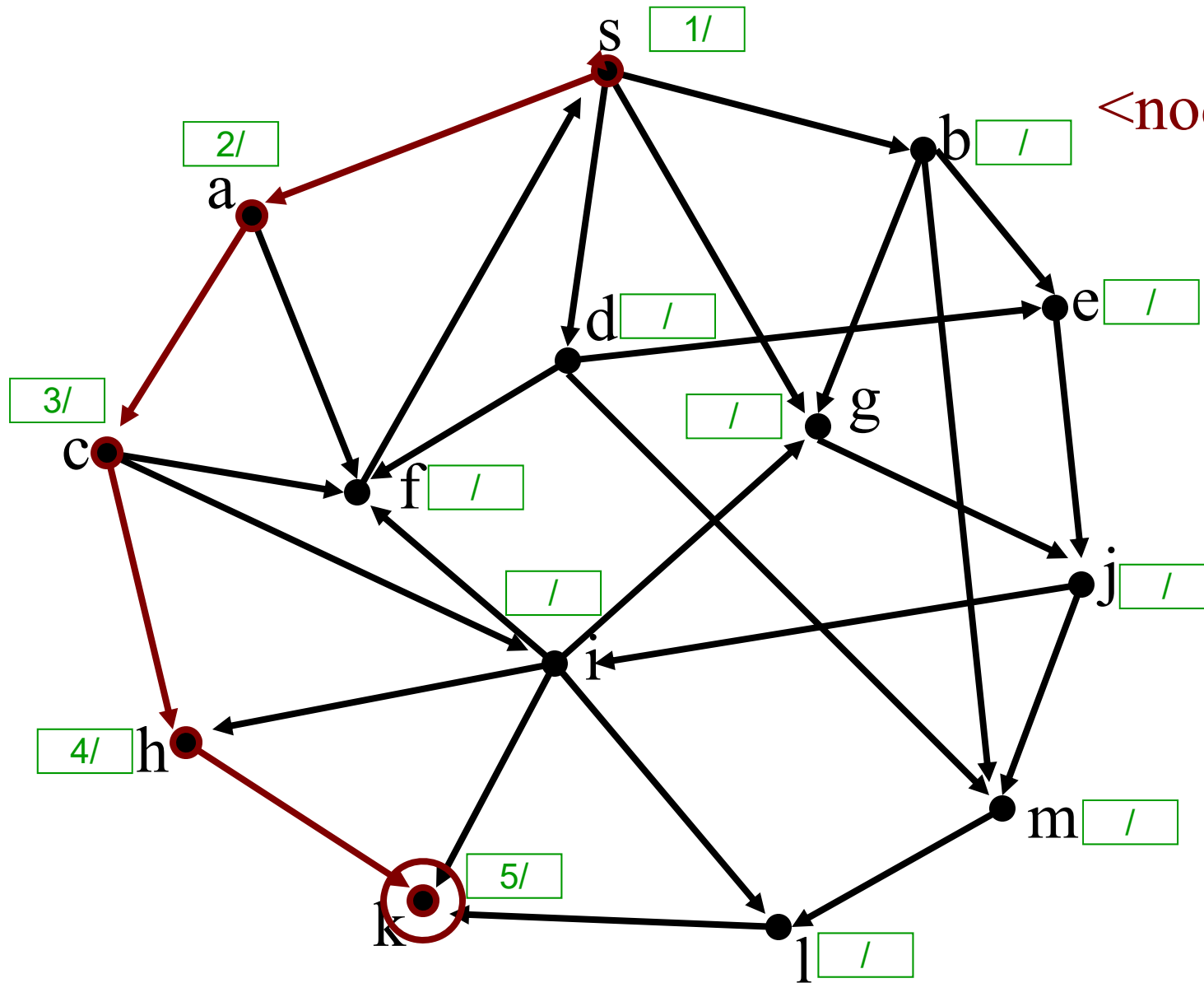
<node,# edges>



DFS

Found
Not Handled
Stack

<node,# edges>

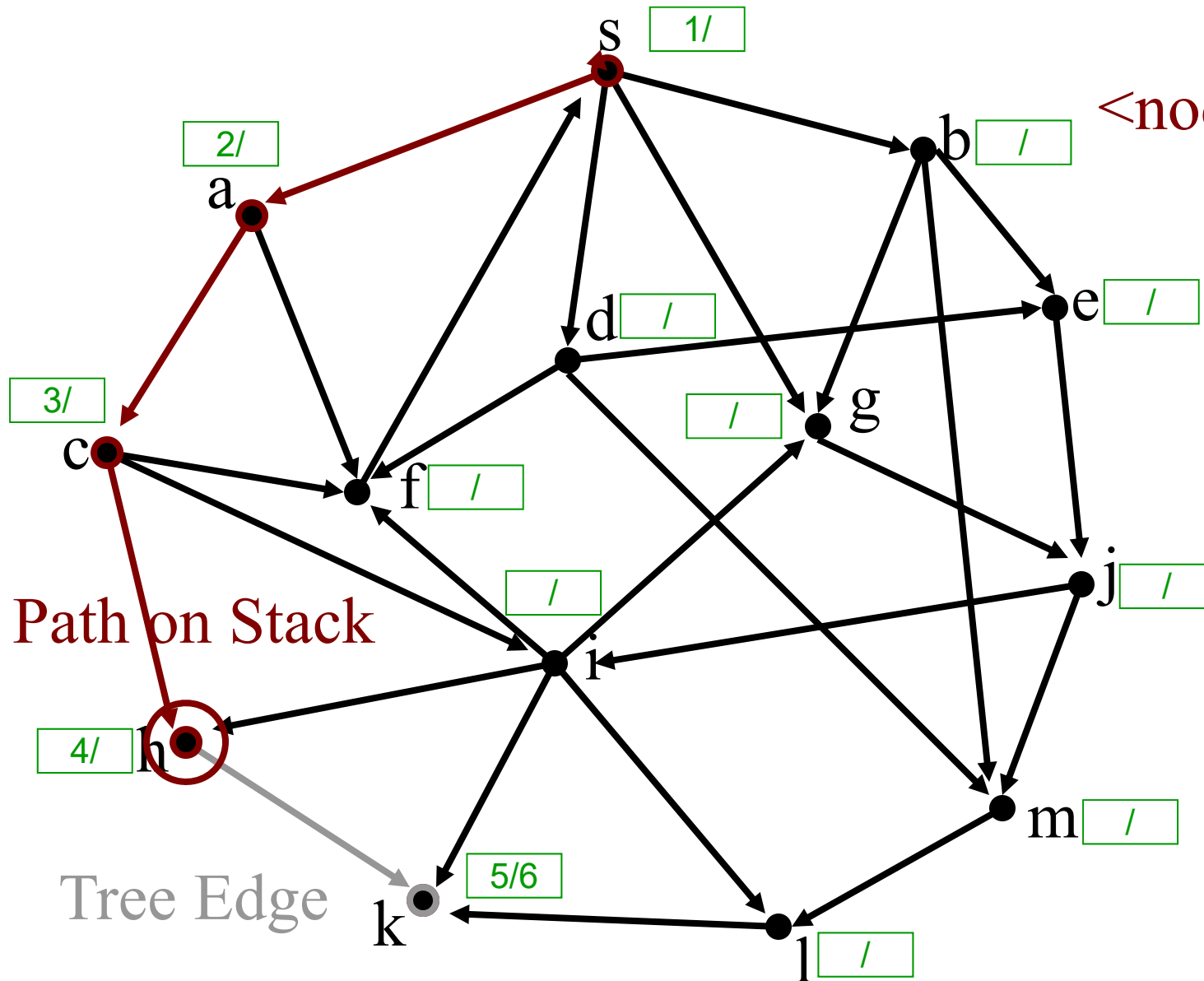


k,0
h,1
c,1
a,1
s,1

DFS

Found
Not Handled
Stack

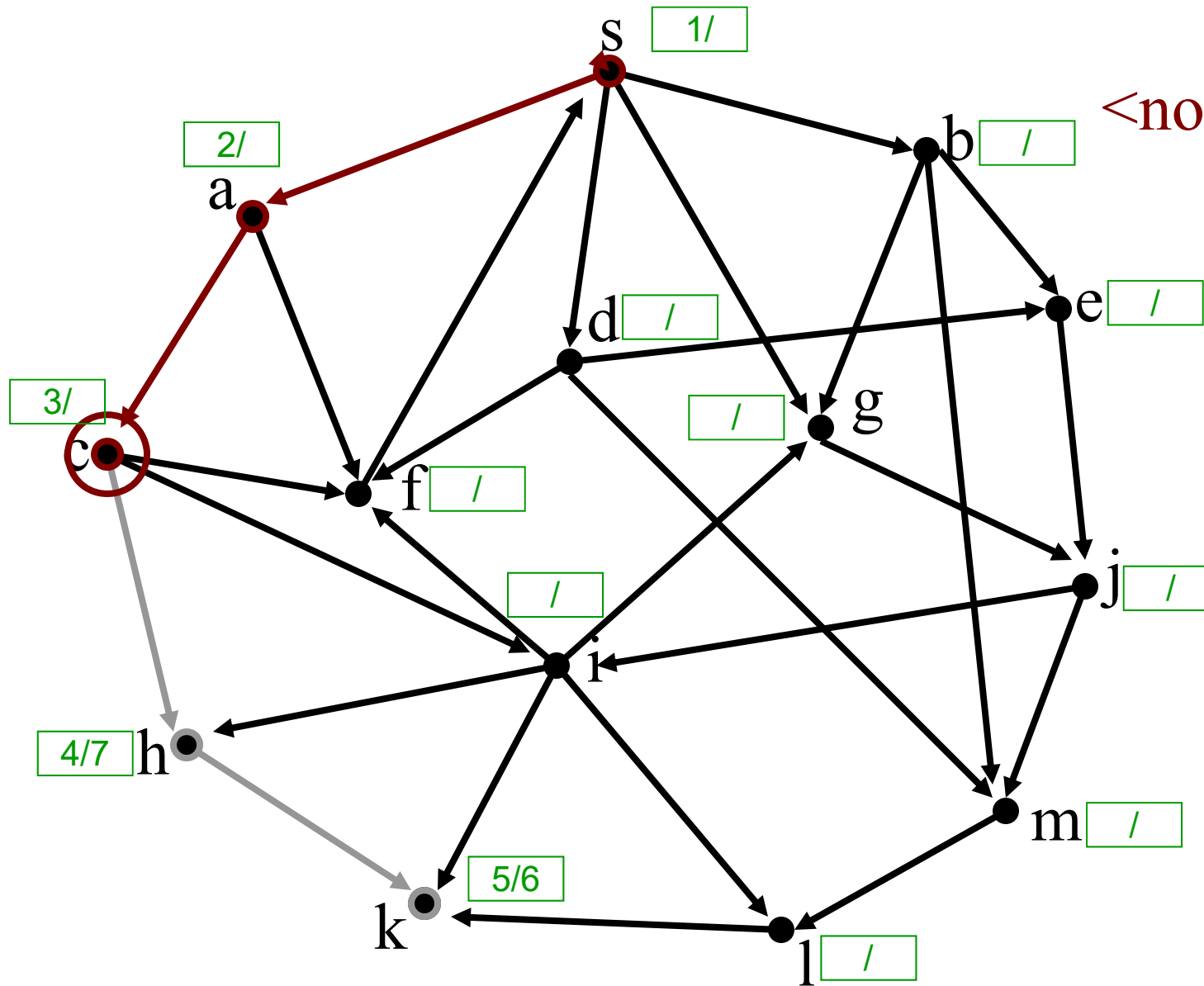
<node,# edges>



DFS

Found
Not Handled
Stack

<node,# edges>

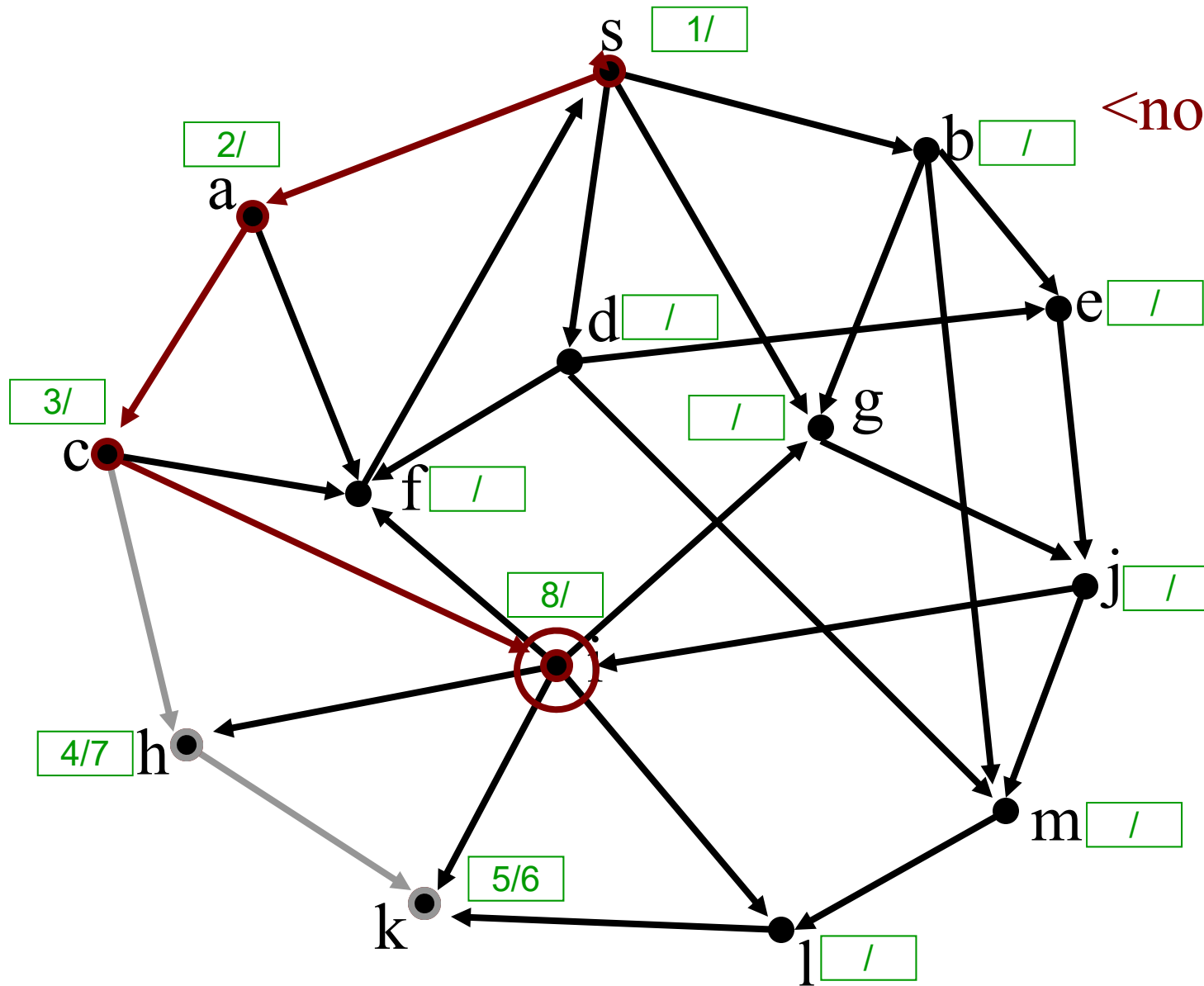


c,1
a,1
s,1

DFS

Found
Not Handled
Stack

<node,# edges>

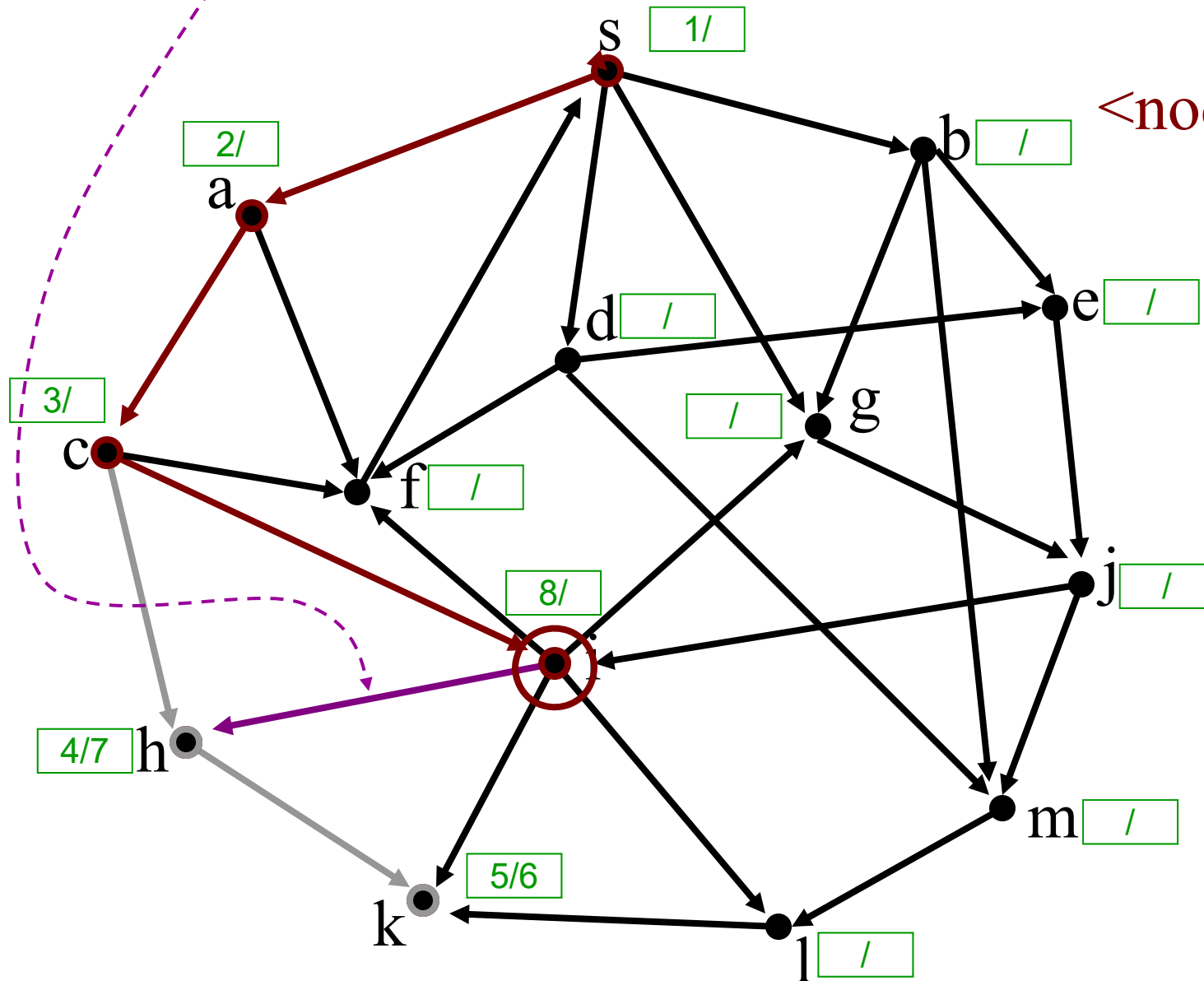


DFS

Found
Not Handled
Stack

<node,# edges>

Cross Edge to handled node: $d[h] < d[i]$

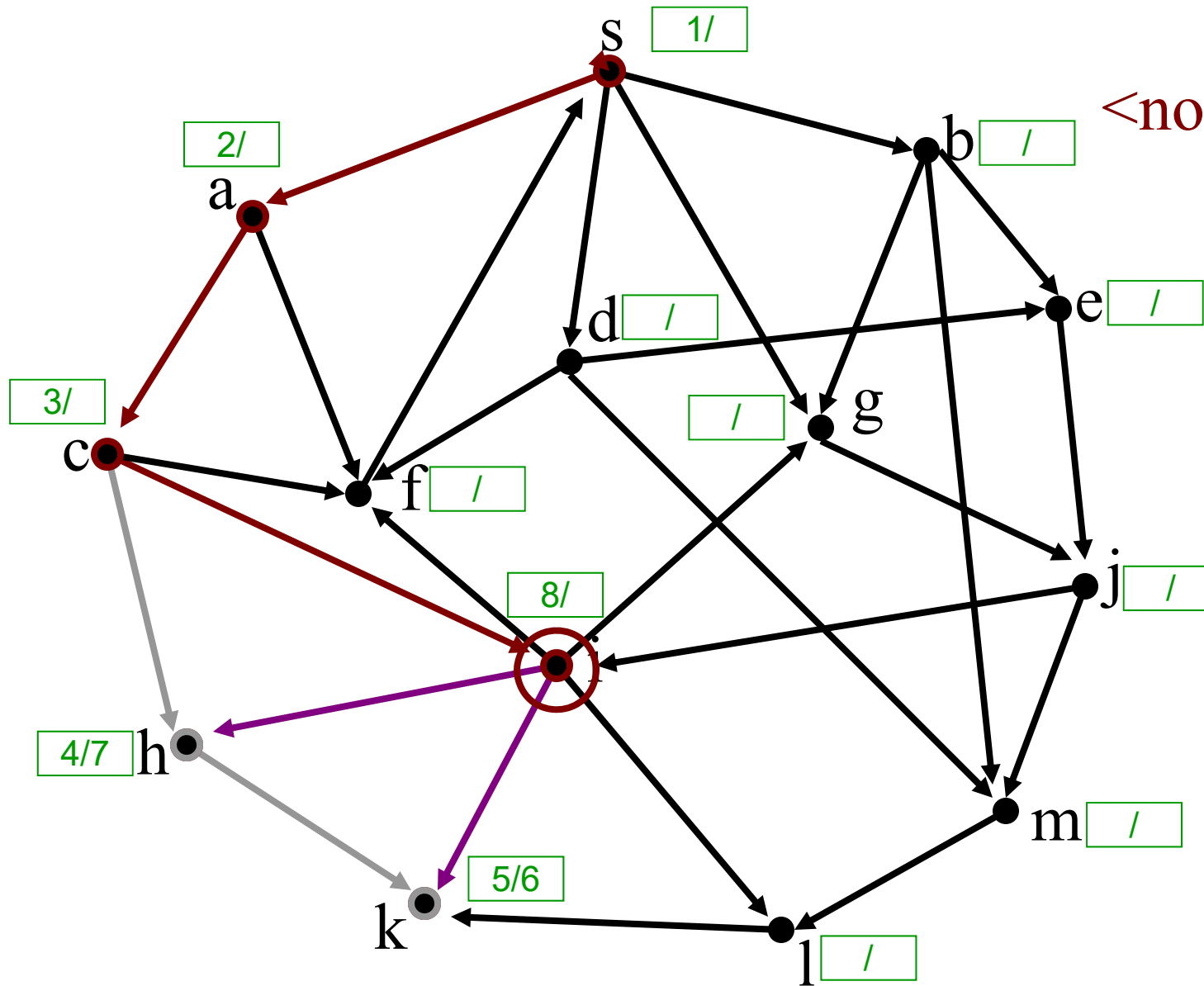


i,1
c,2
a,1
s,1

DFS

Found
Not Handled
Stack

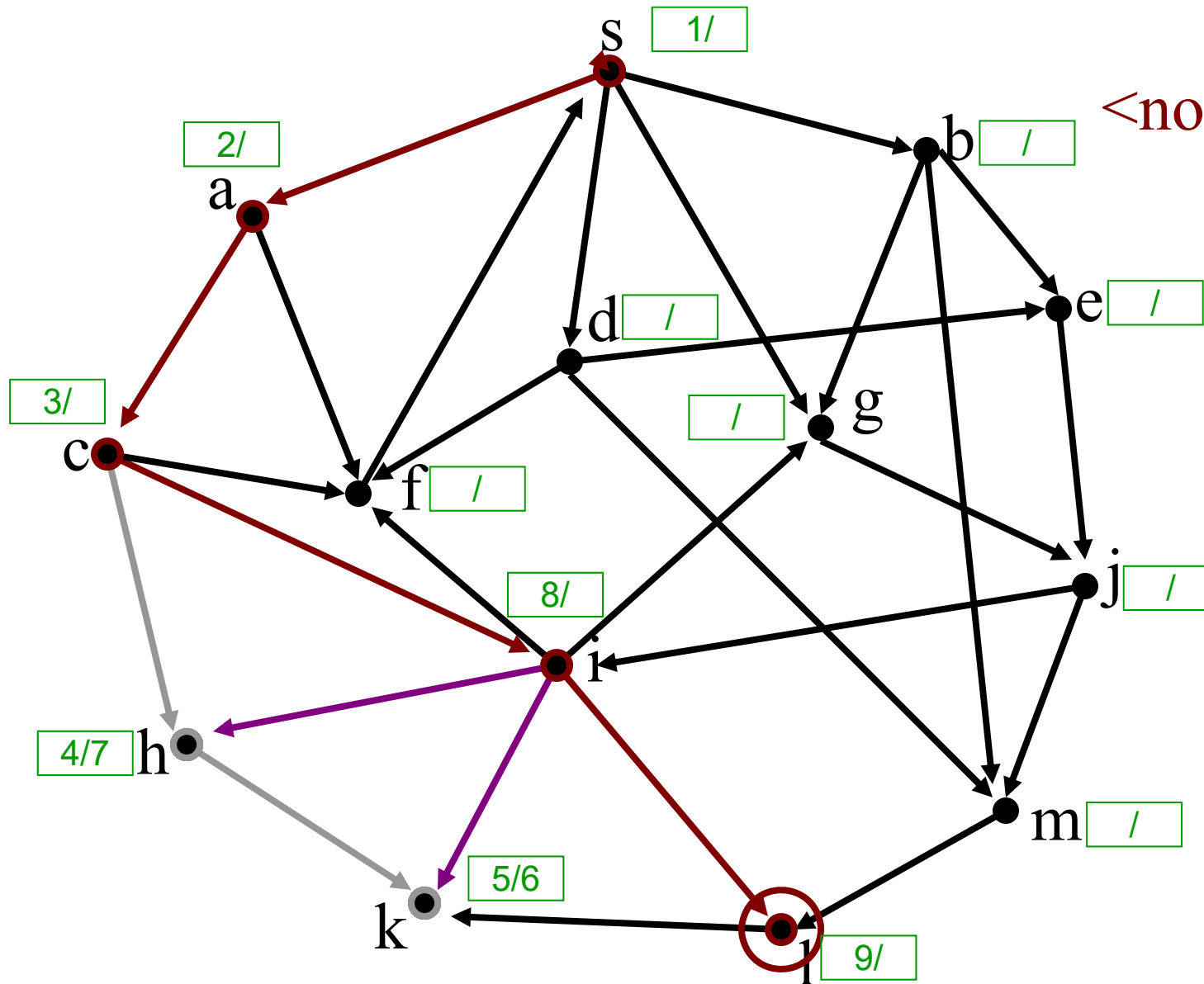
<node,# edges>



DFS

Found
Not Handled
Stack

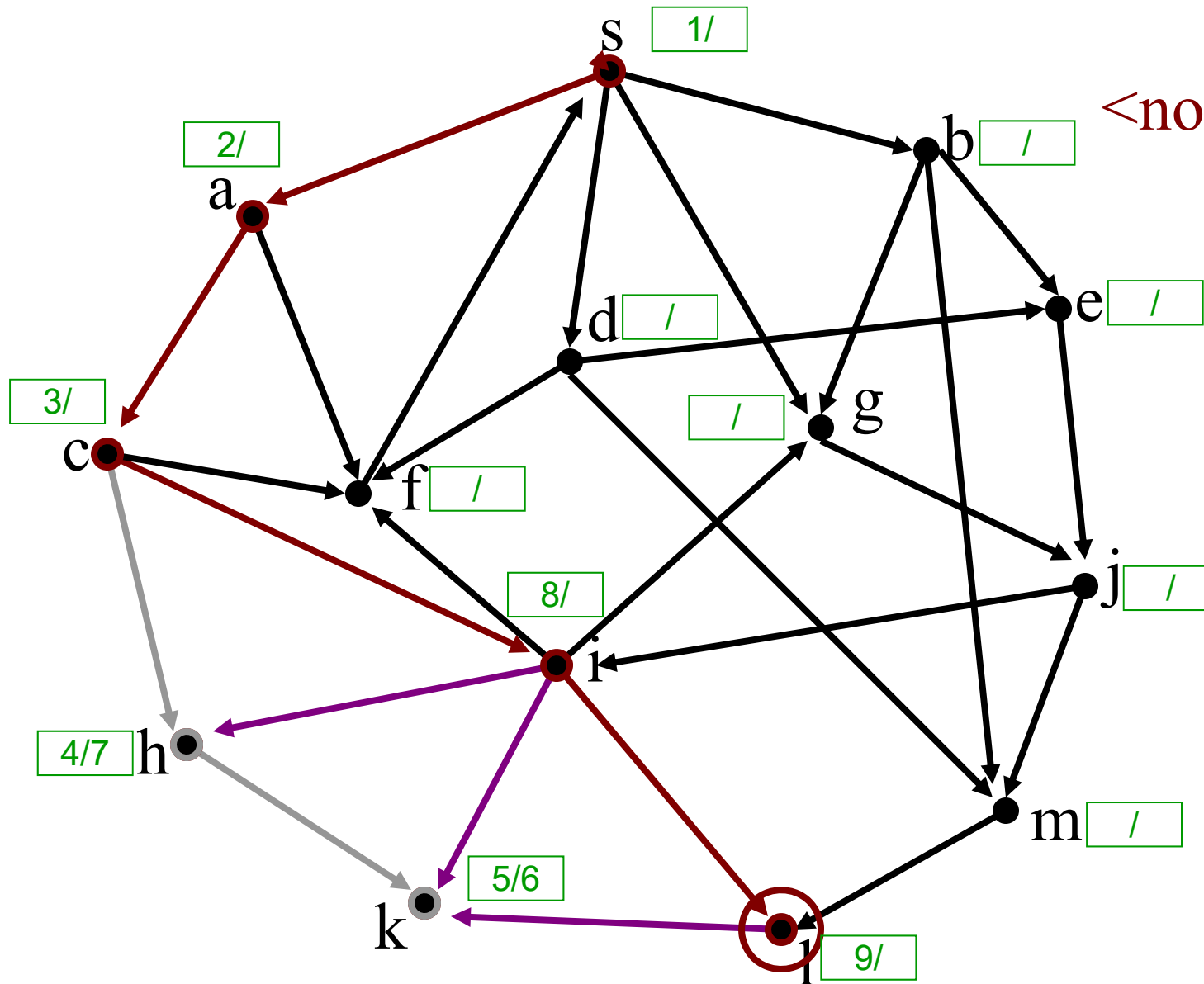
<node,# edges>



DFS

Found
Not Handled
Stack

<node,# edges>

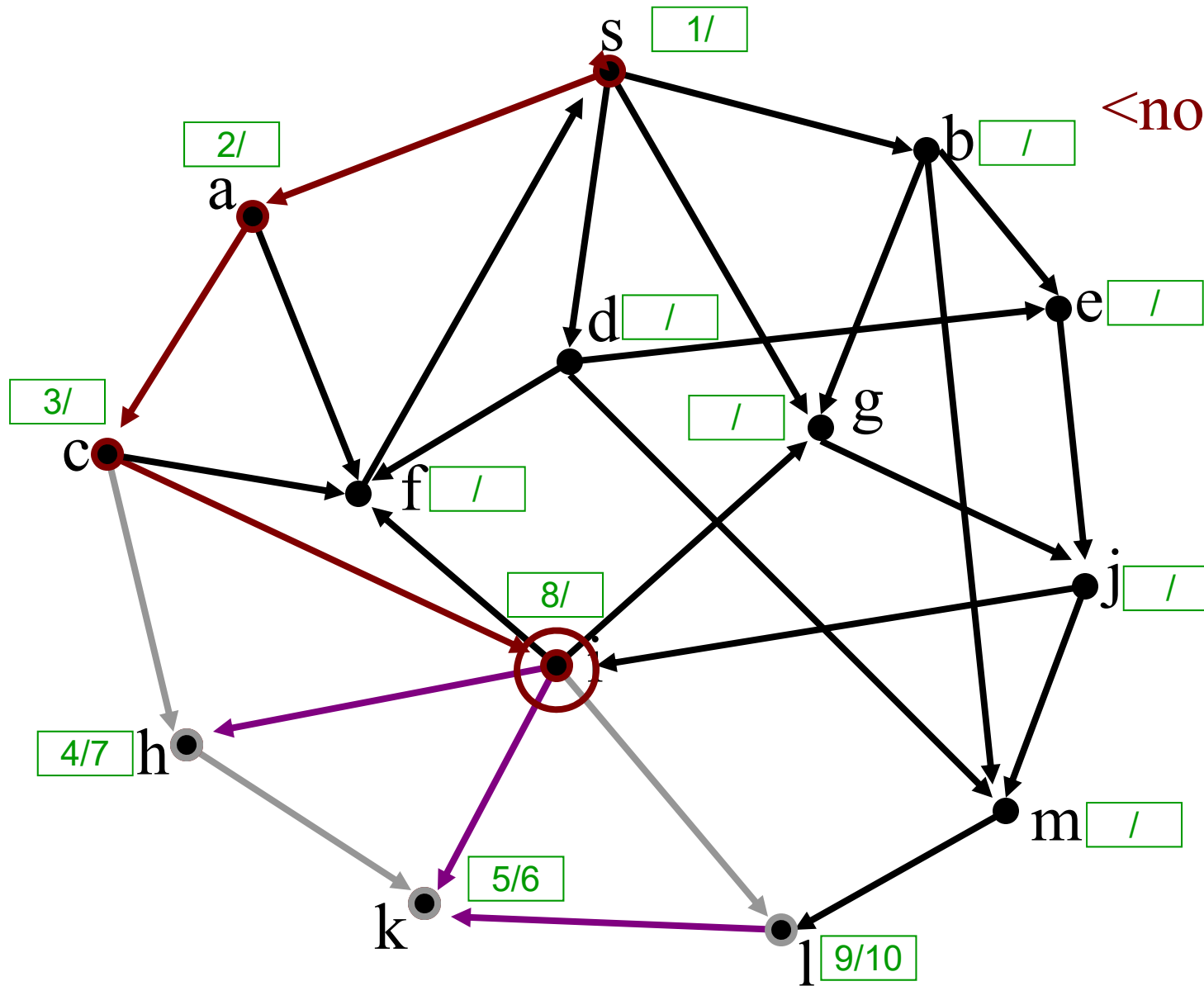


l,1
i,3
c,2
a,1
s,1

DFS

Found
Not Handled
Stack

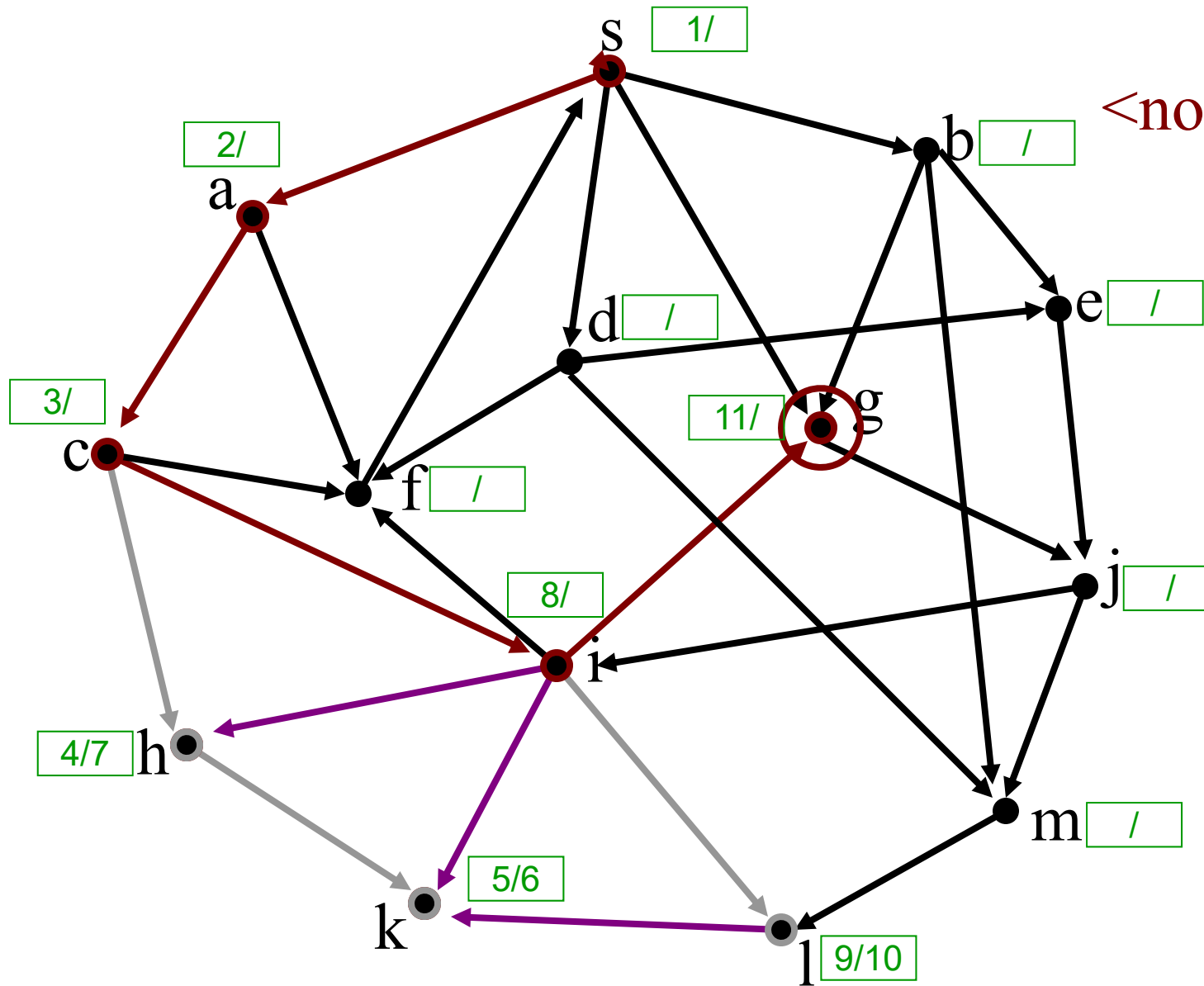
<node,# edges>



DFS

Found
Not Handled
Stack

<node,# edges>

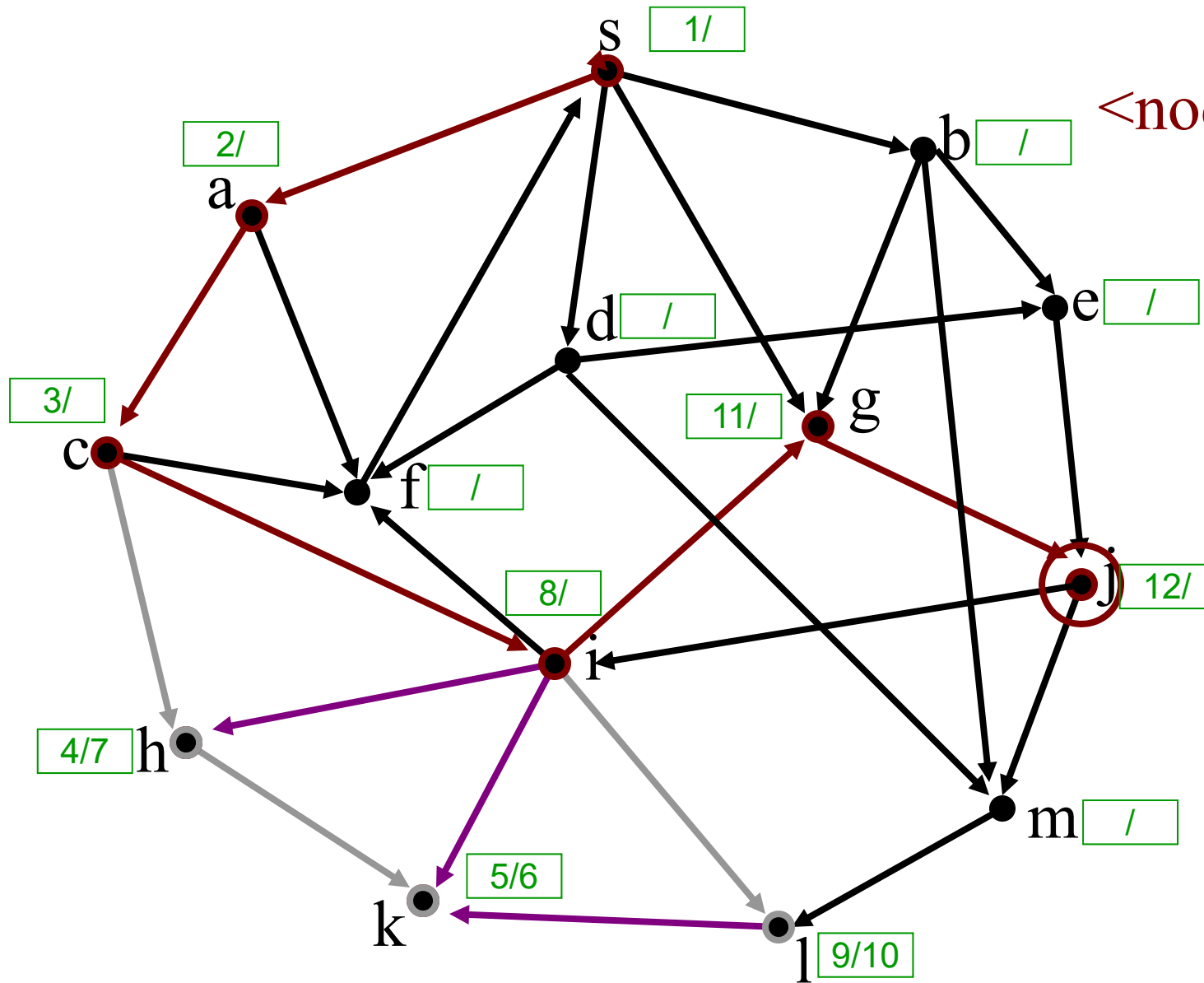


g,0
i,4
c,2
a,1
s,1

DFS

Found Not Handled Stack

<node,# edges>



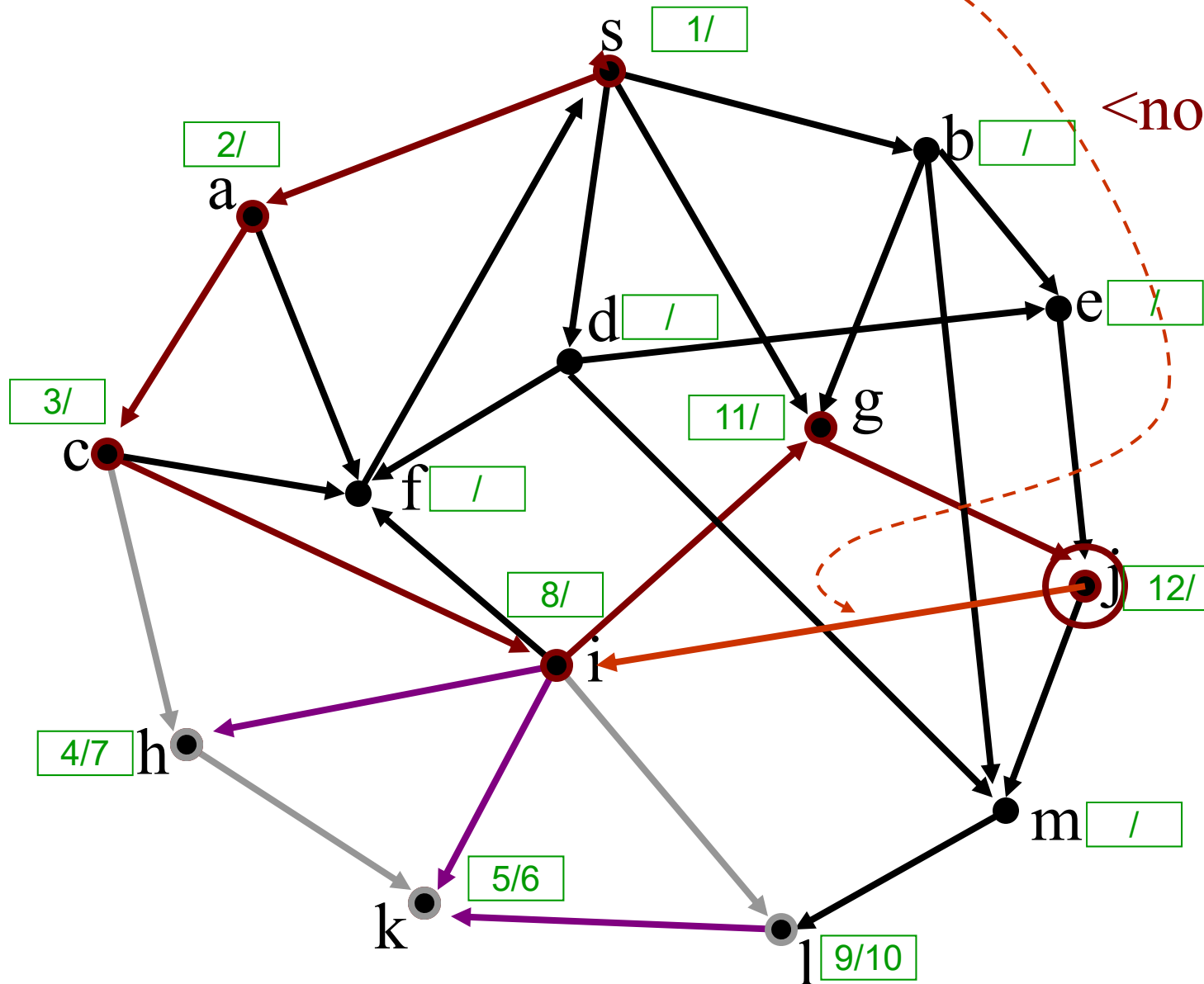
j,0
g,1
i,4
c,2
a,1
s,1

DFS

Back Edge to node on Stack:

Found
Not Handled
Stack

<node,# edges>

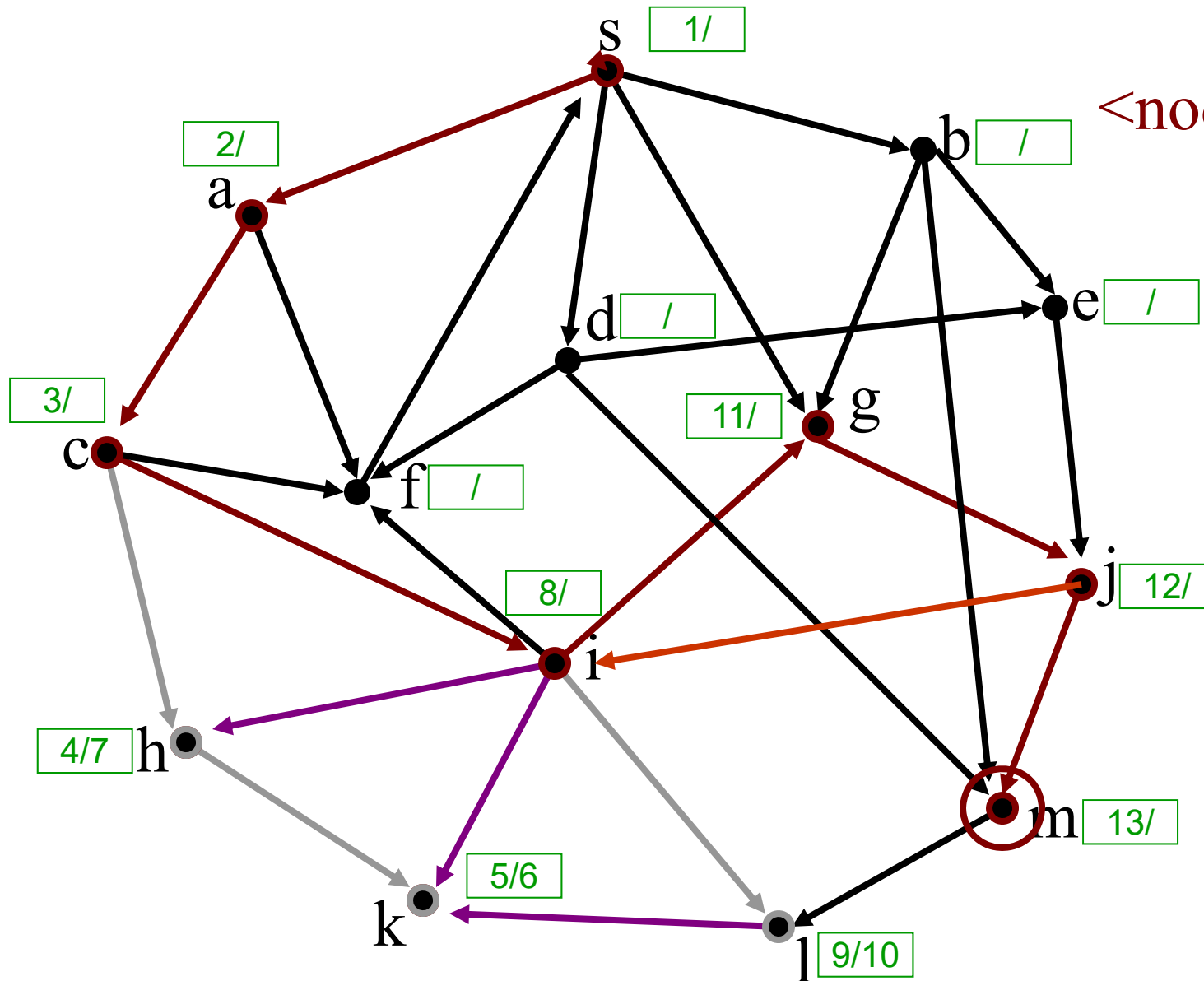


j,1
g,1
i,4
c,2
a,1
s,1

DFS

Found
Not Handled
Stack

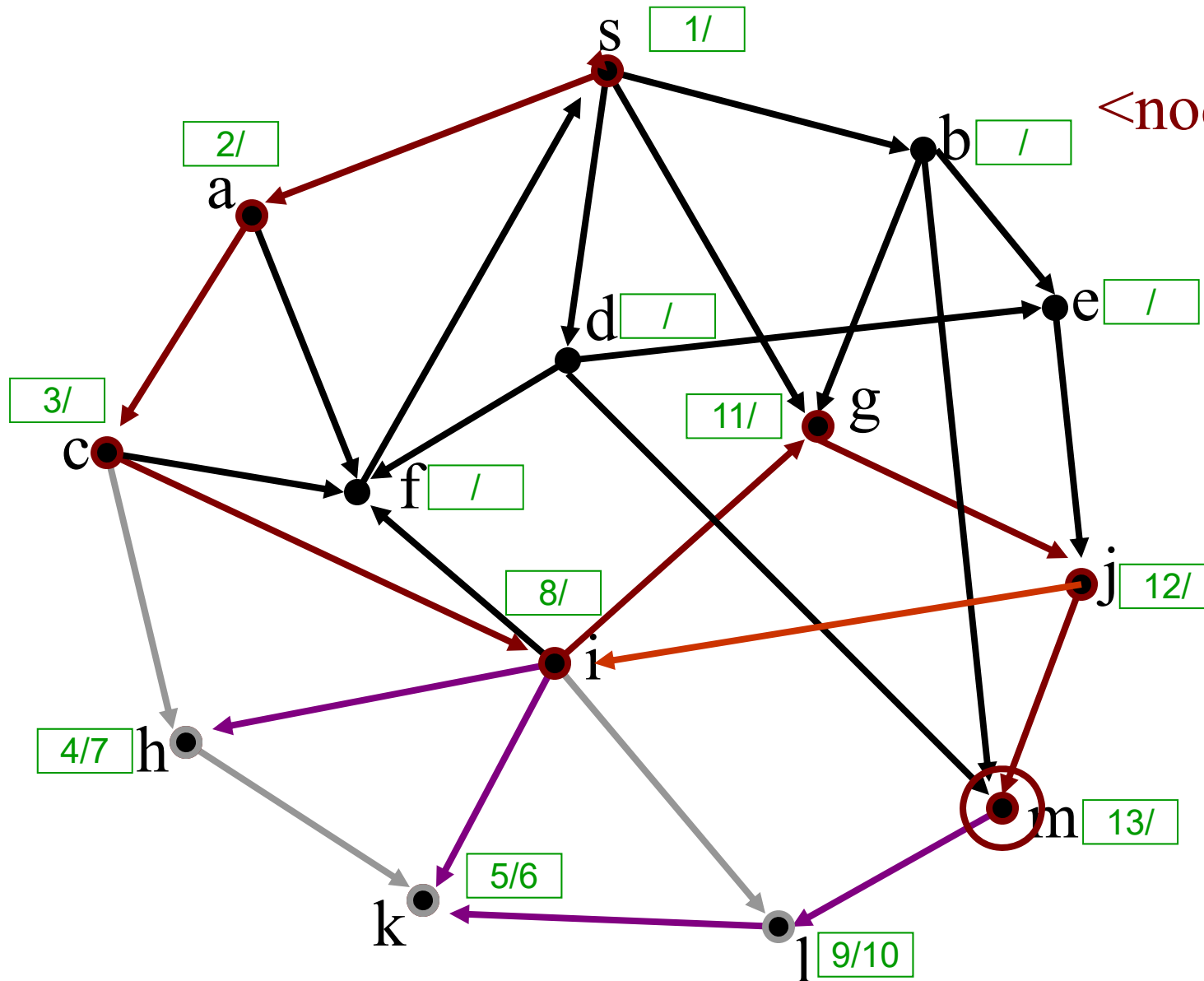
<node,# edges>



DFS

Found
Not Handled
Stack

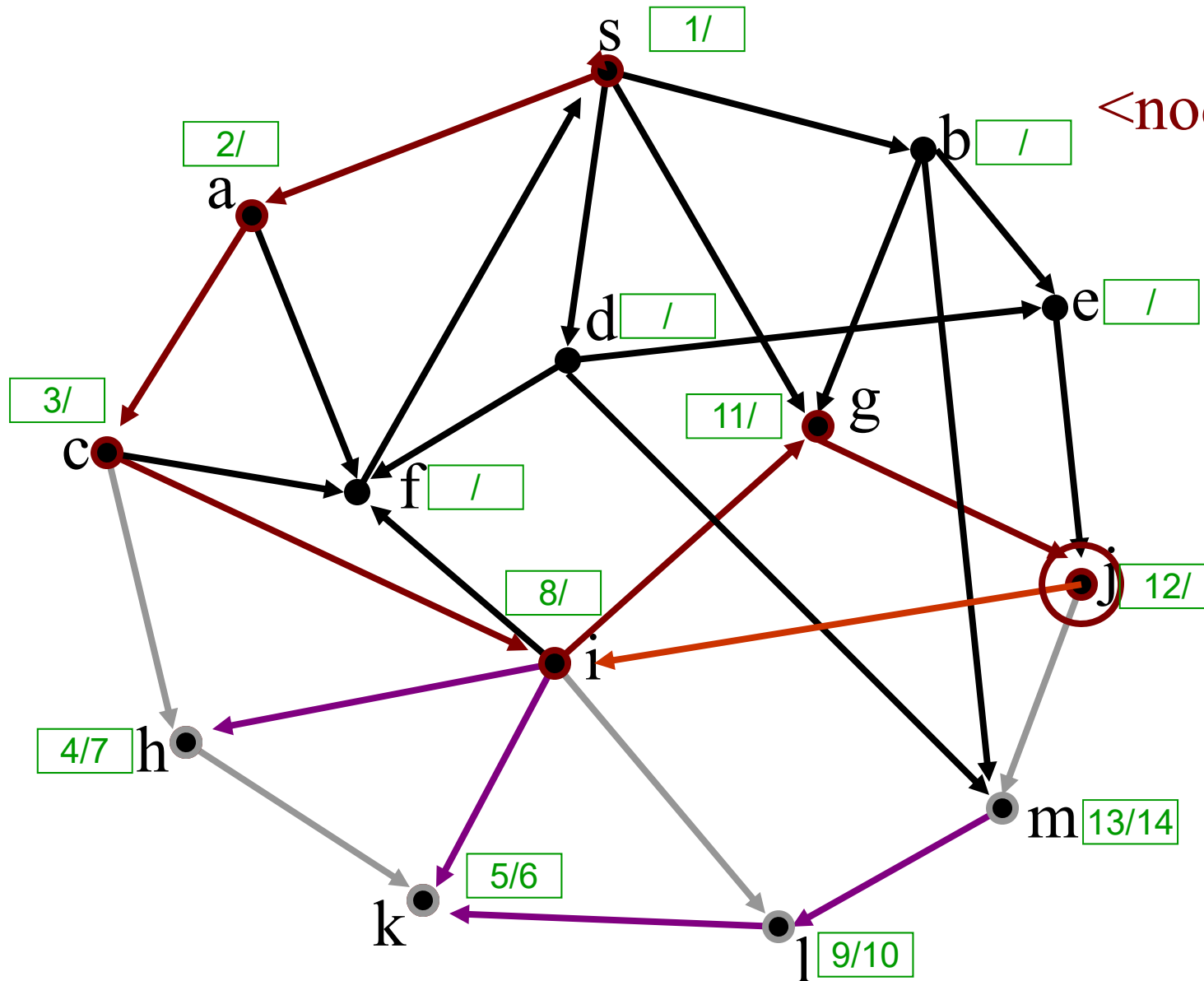
<node,# edges>



DFS

Found
Not Handled
Stack

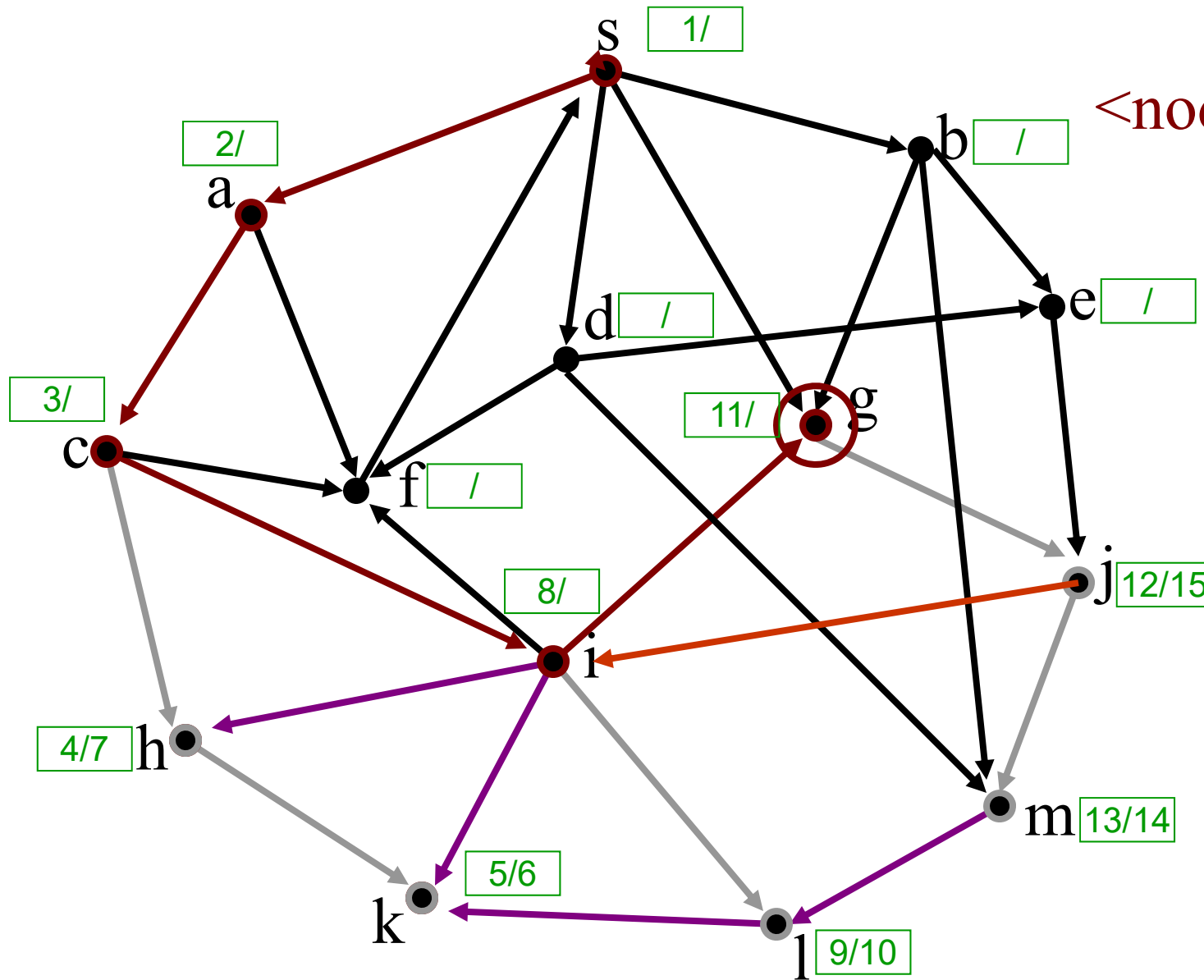
<node,# edges>



DFS

Found
Not Handled
Stack

<node,# edges>

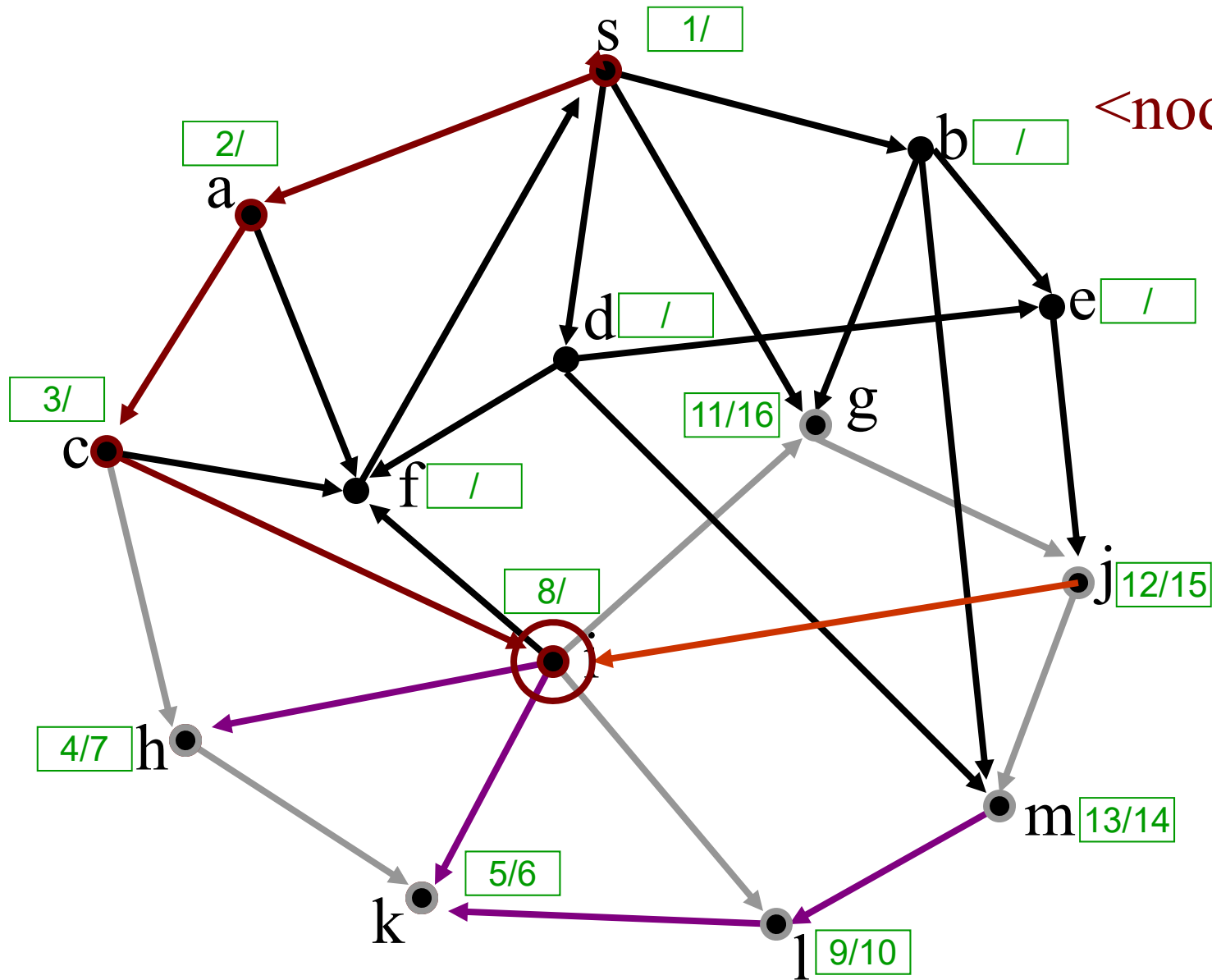


g,1
i,4
c,2
a,1
s,1

DFS

Found Not Handled Stack

<node,# edges>

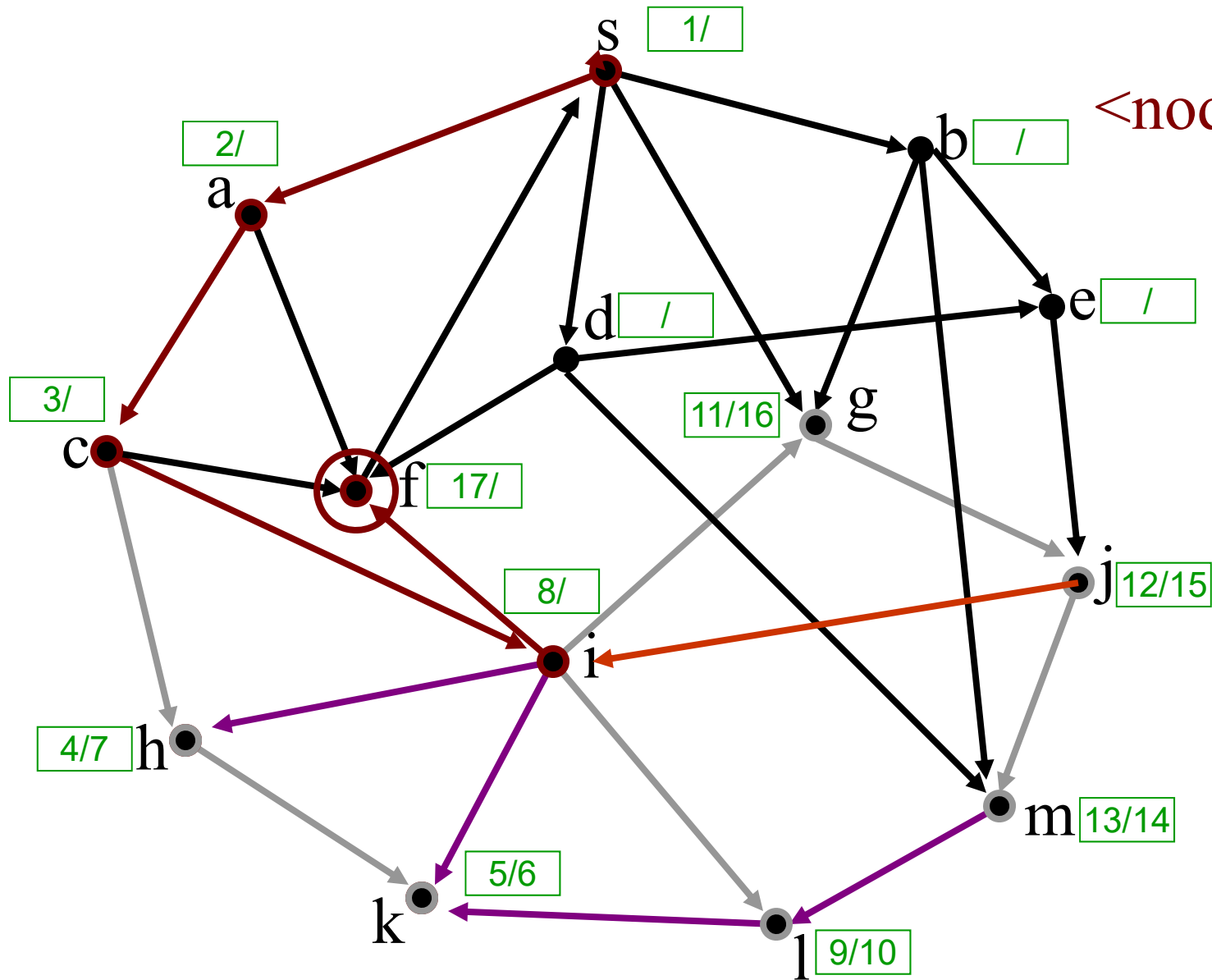


i,4
c,2
a,1
s,1

DFS

Found
Not Handled
Stack

<node,# edges>

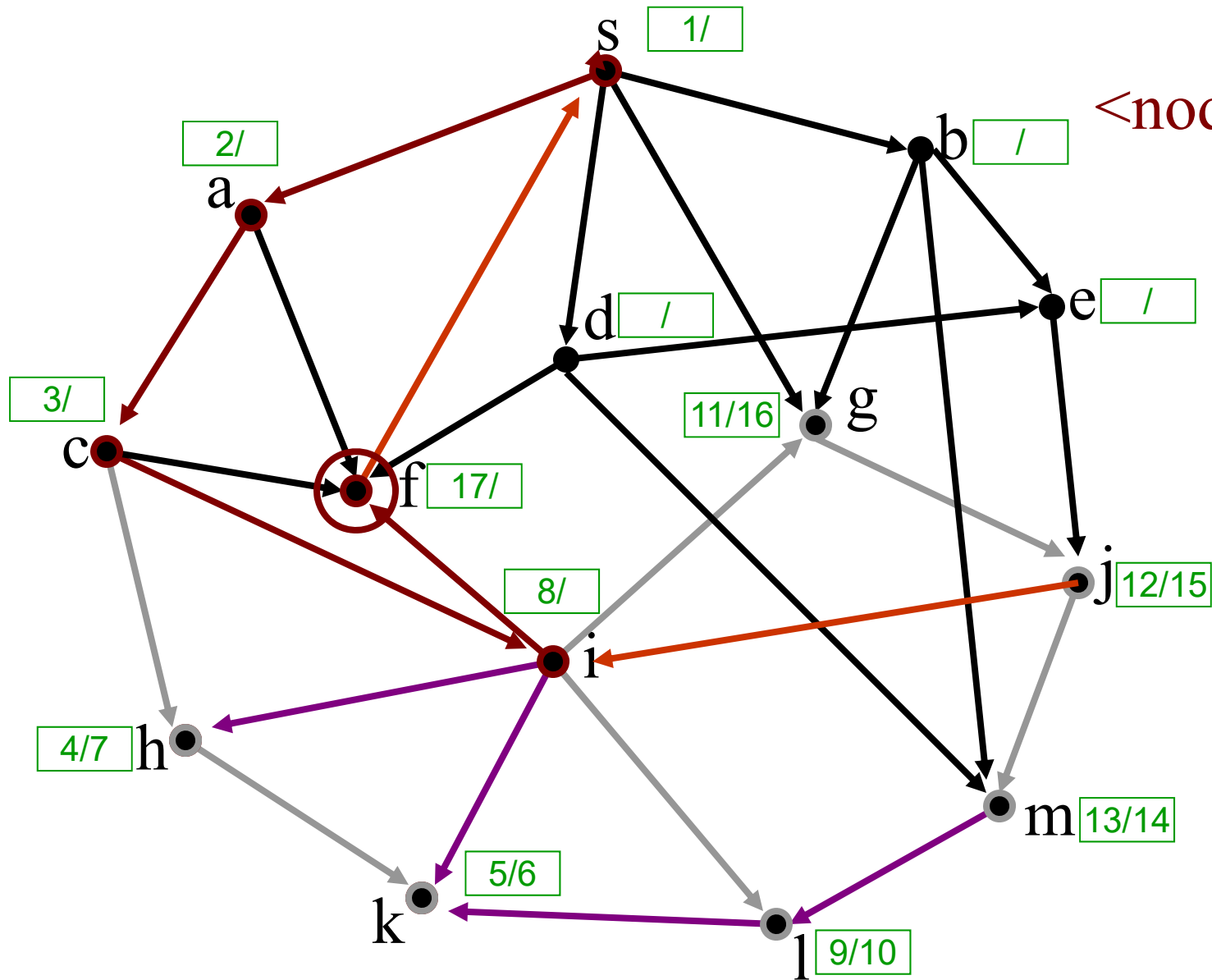


f,0
i,5
c,2
a,1
s,1

DFS

Found
Not Handled
Stack

<node,# edges>

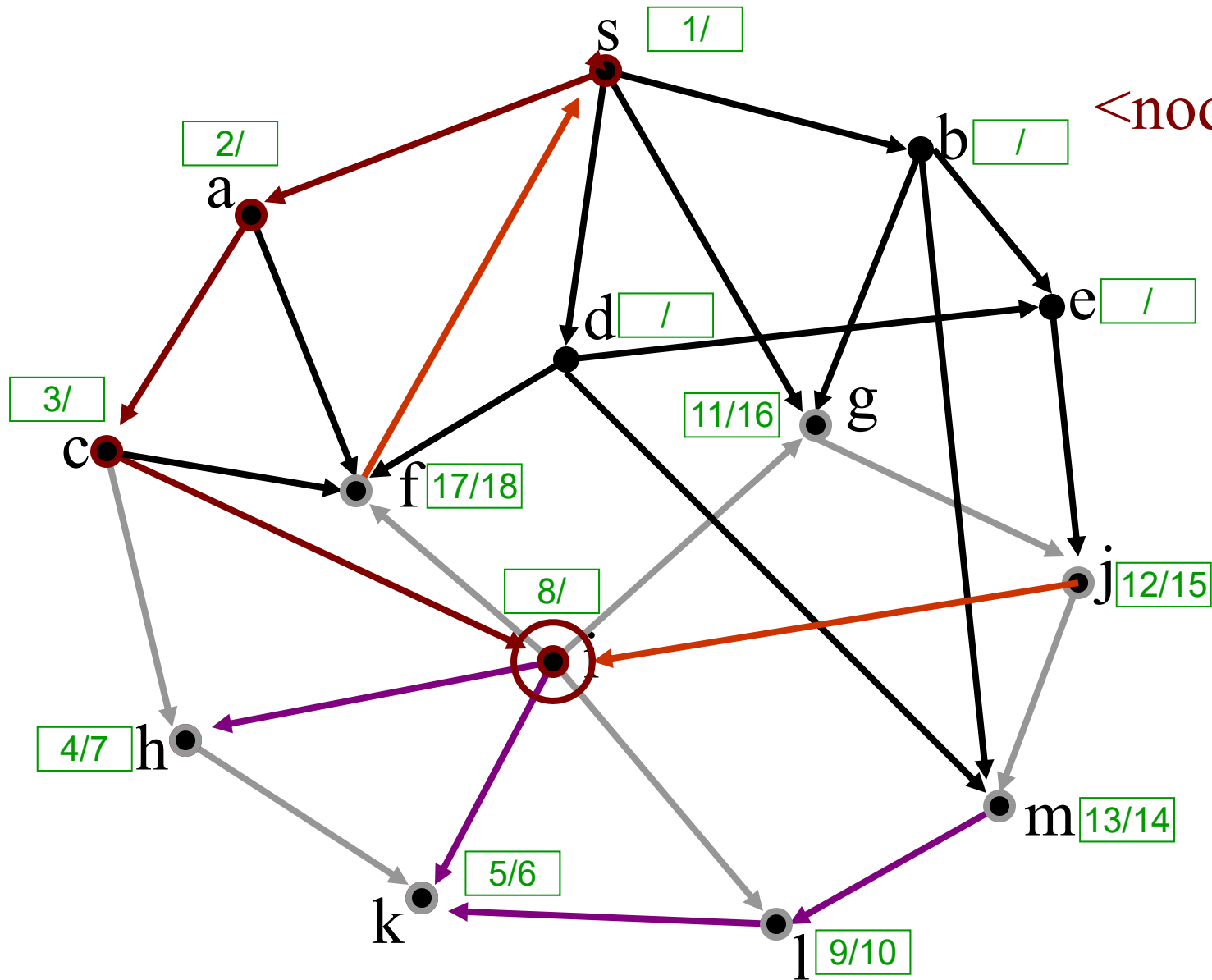


f,1
i,5
c,2
a,1
s,1

DFS

Found
Not Handled
Stack

<node,# edges>

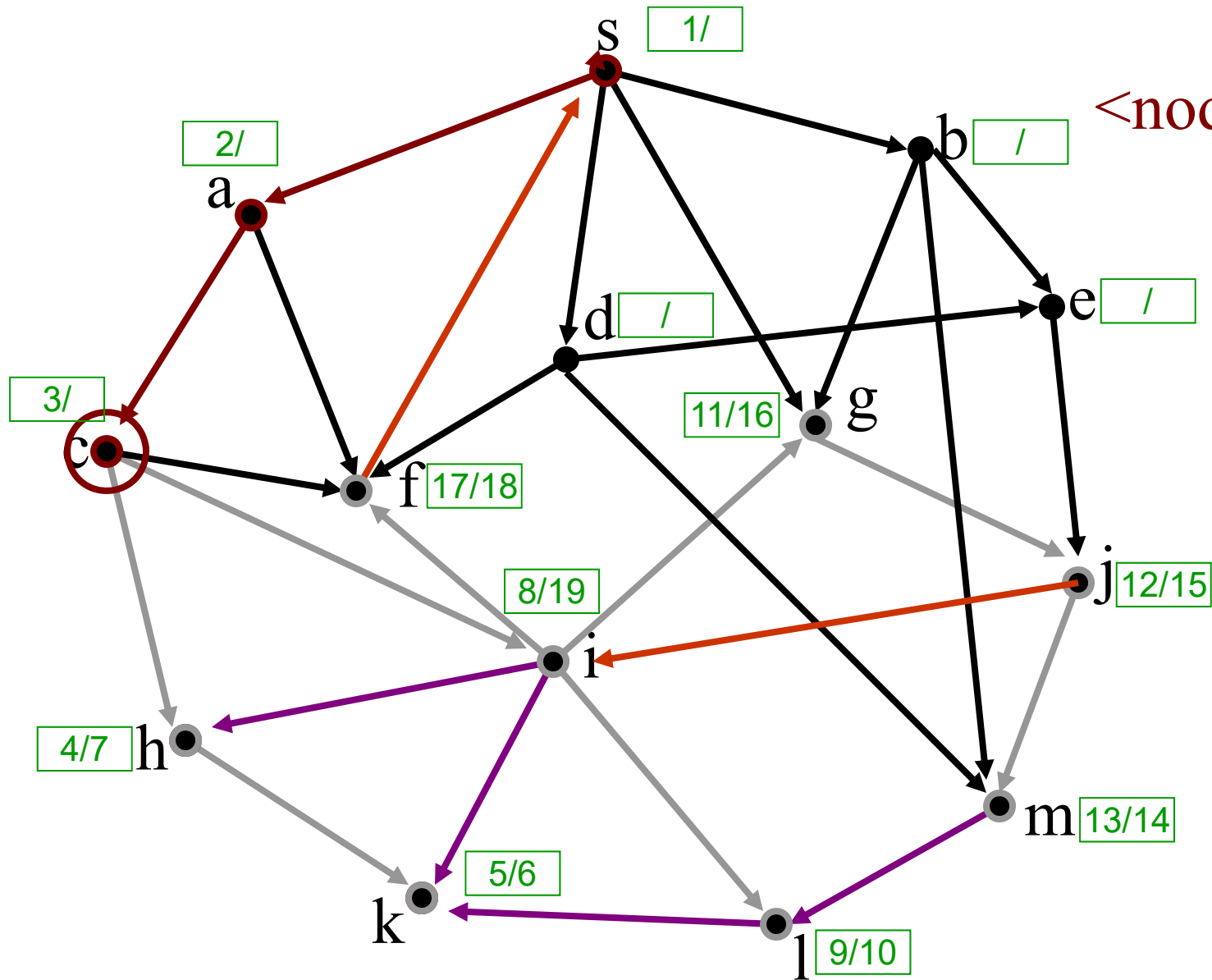


i,5
c,2
a,1
s,1

DFS

Found
Not Handled
Stack

<node,# edges>

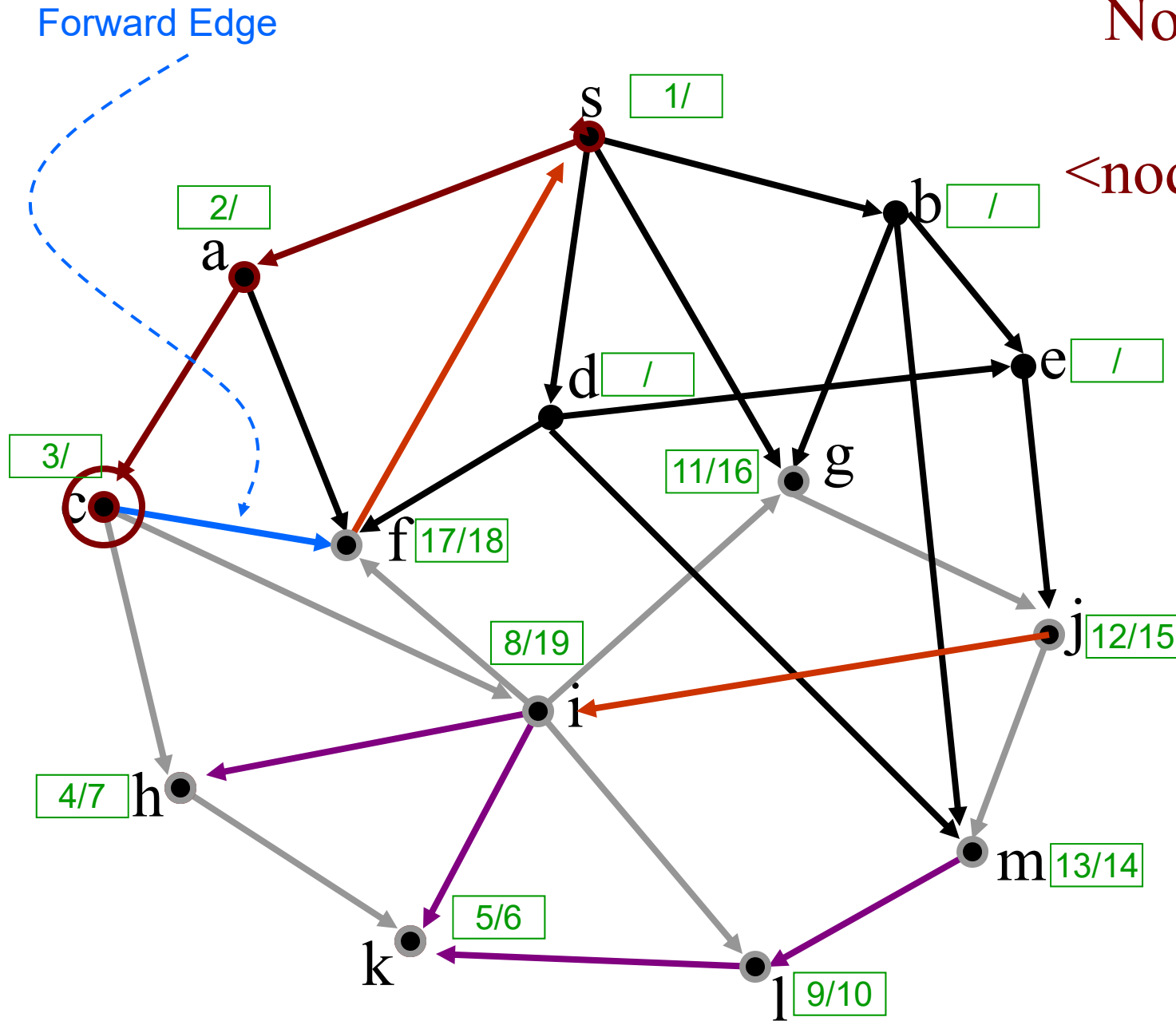


c,2
a,1
s,1

DFS

Found
Not Handled
Stack

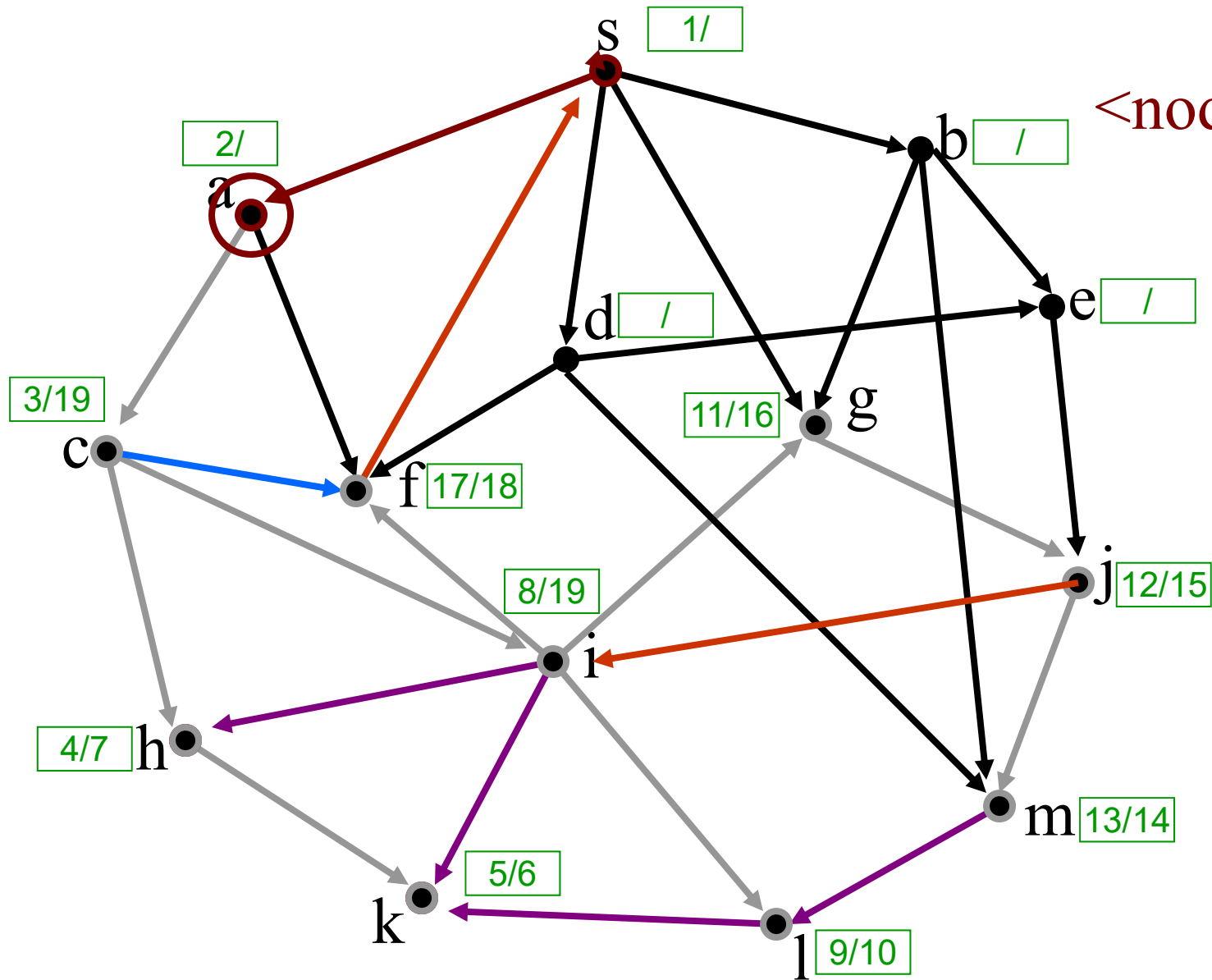
<node,# edges>



DFS

Found
Not Handled
Stack

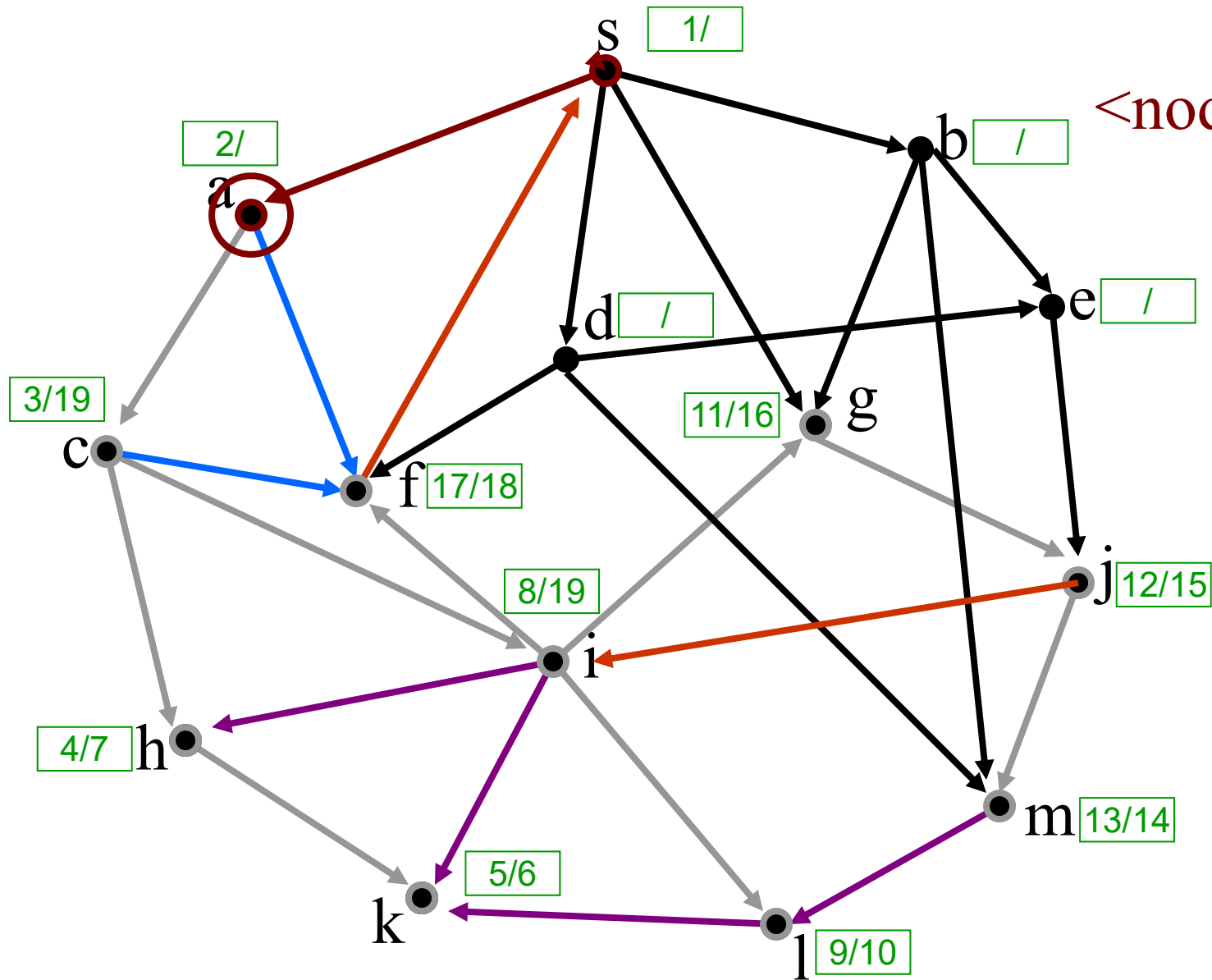
<node,# edges>



DFS

Found
Not Handled
Stack

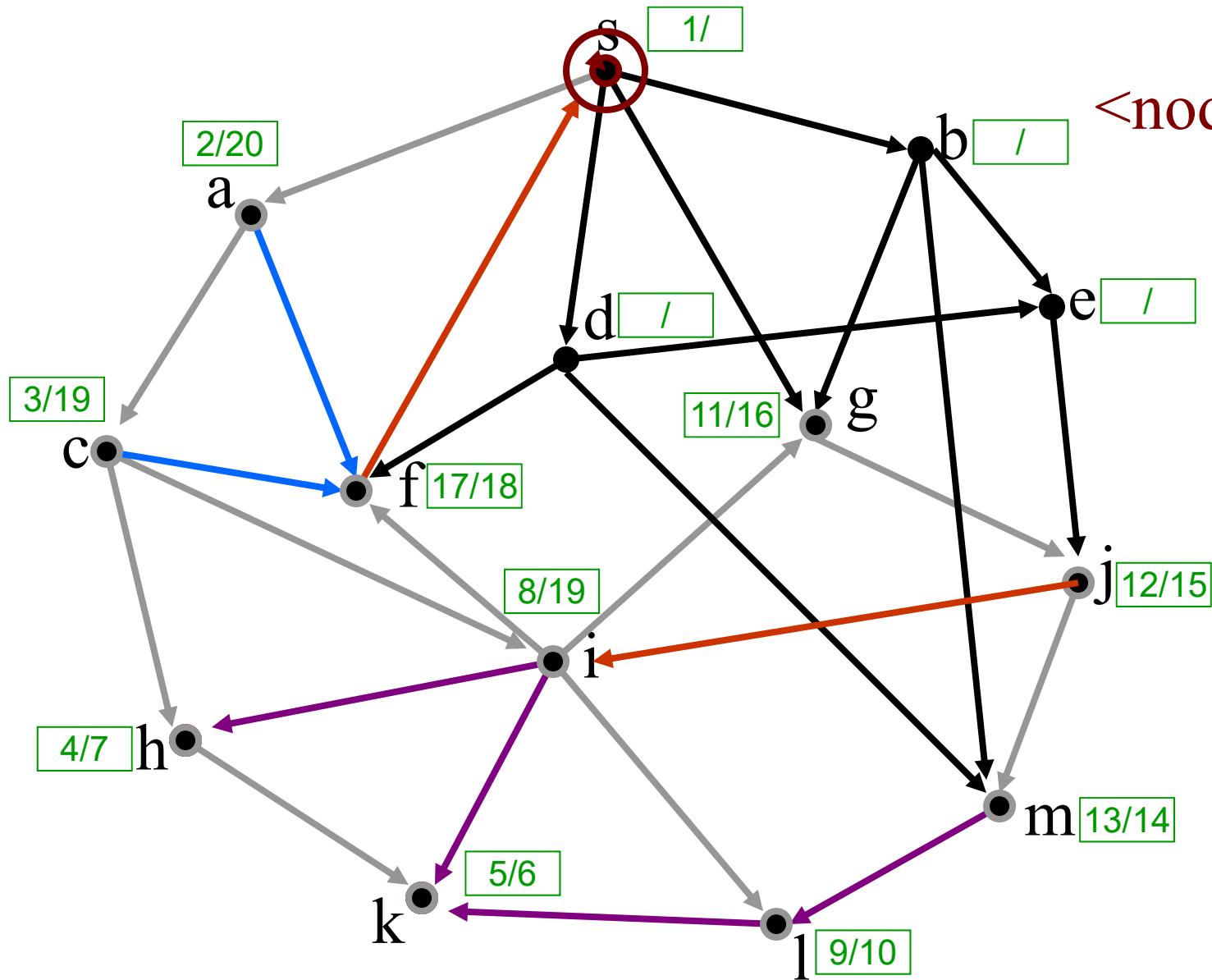
<node,# edges>



DFS

Found
Not Handled
Stack

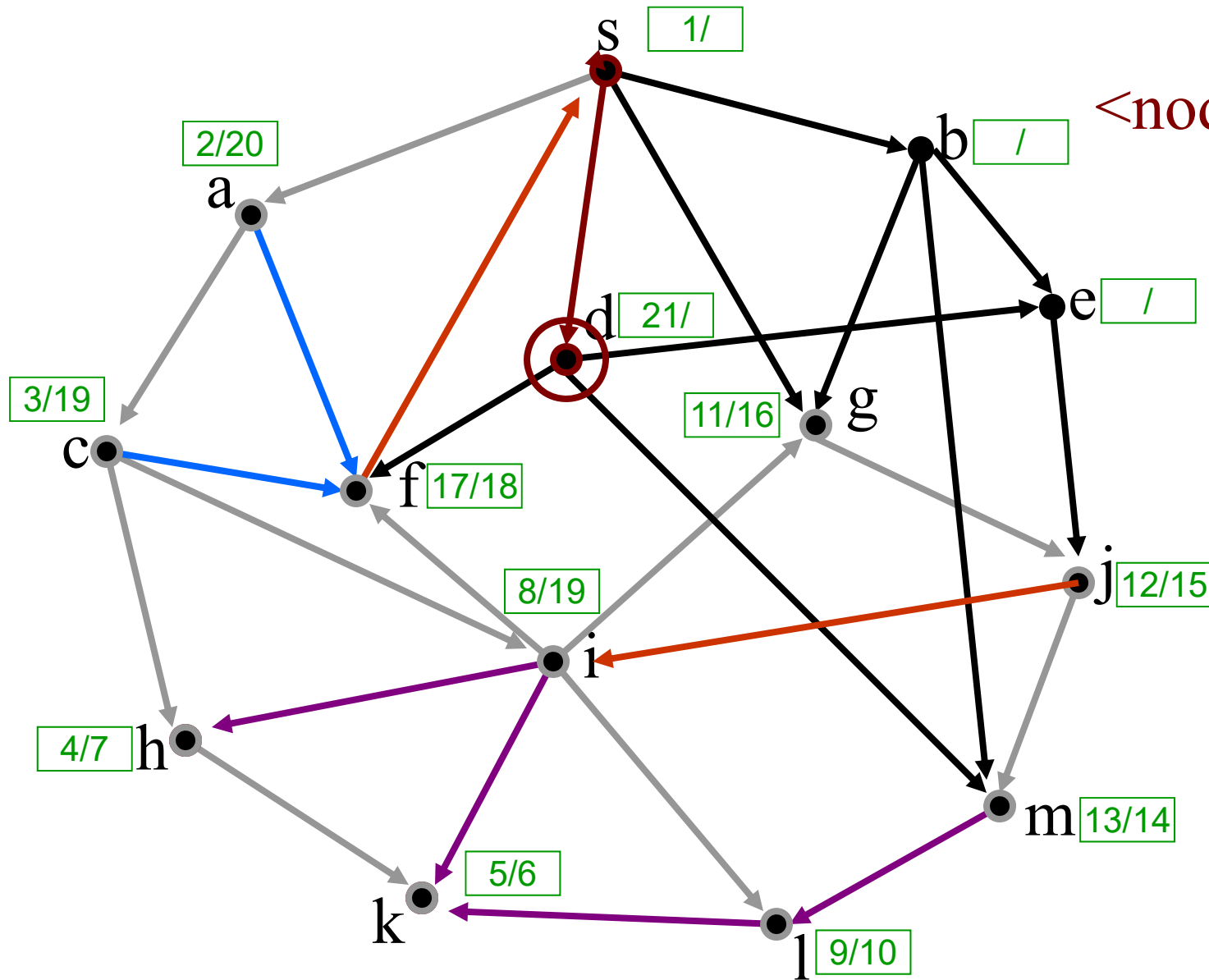
<node,# edges>



DFS

Found
Not Handled
Stack

<node,# edges>

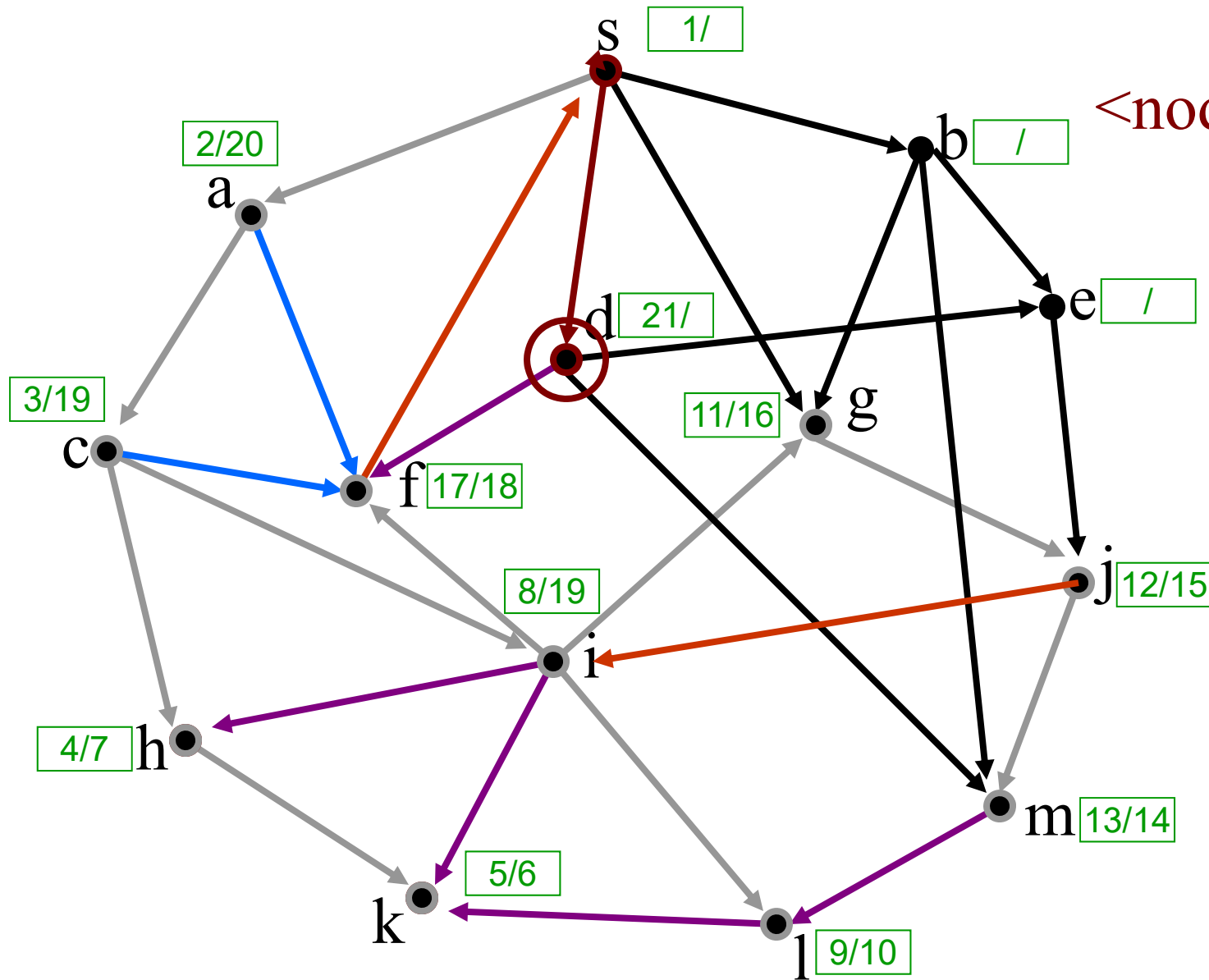


d,0
s,2

DFS

Found
Not Handled
Stack

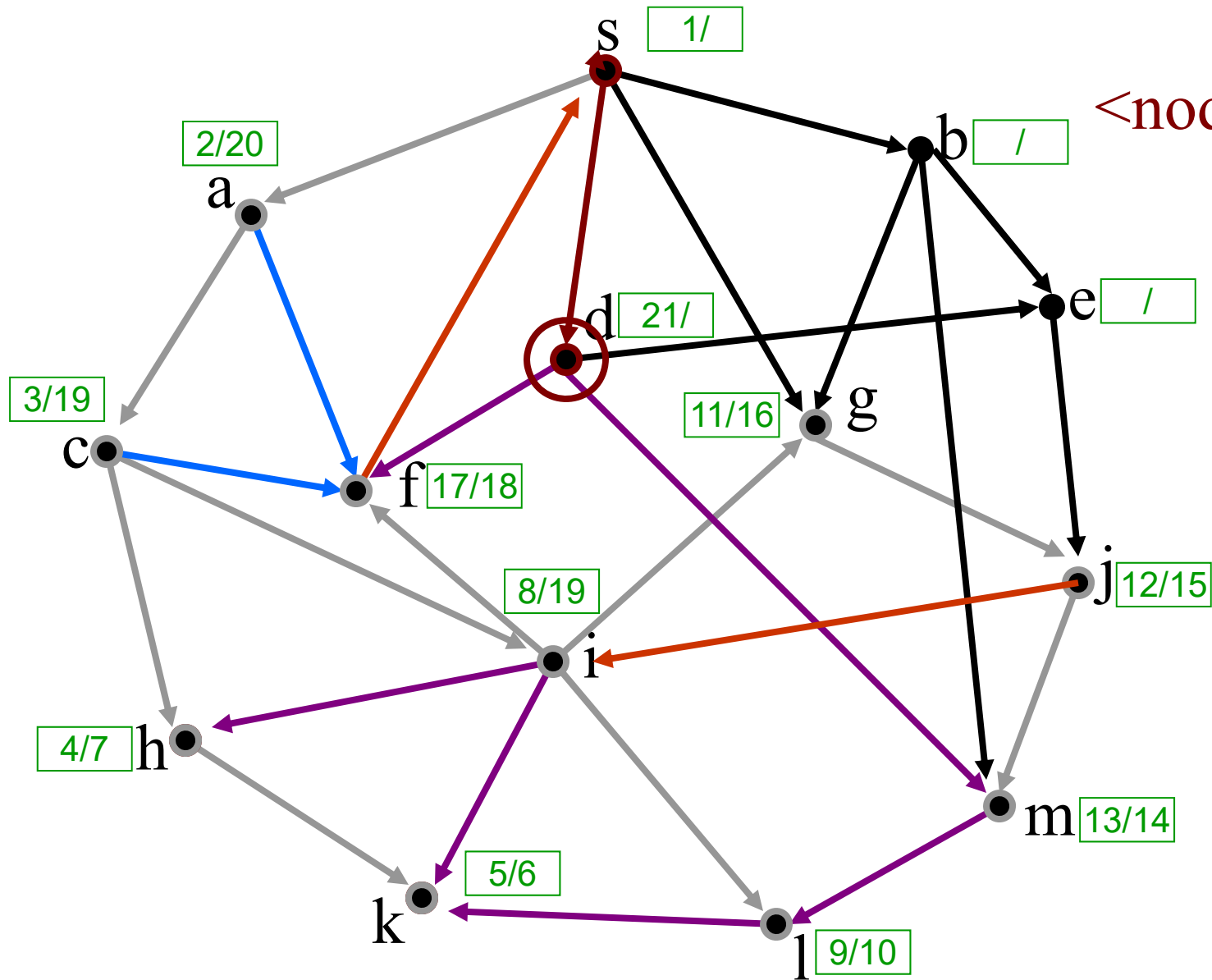
<node,# edges>



DFS

Found Not Handled Stack

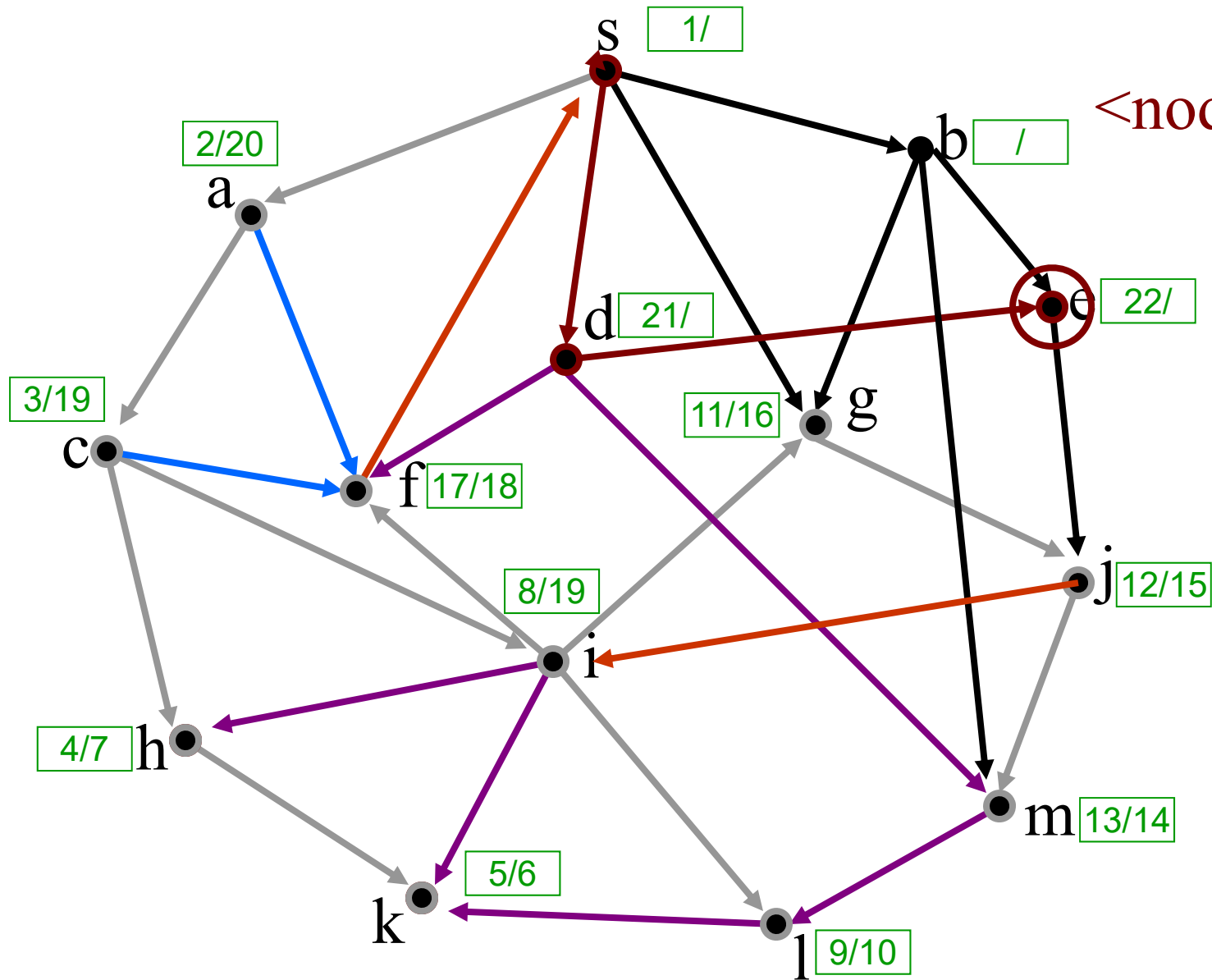
<node,# edges>


$$\begin{array}{c} \text{d}, 2 \\ \text{s}, 2 \end{array}$$

DFS

Found Not Handled Stack

<node,# edges>

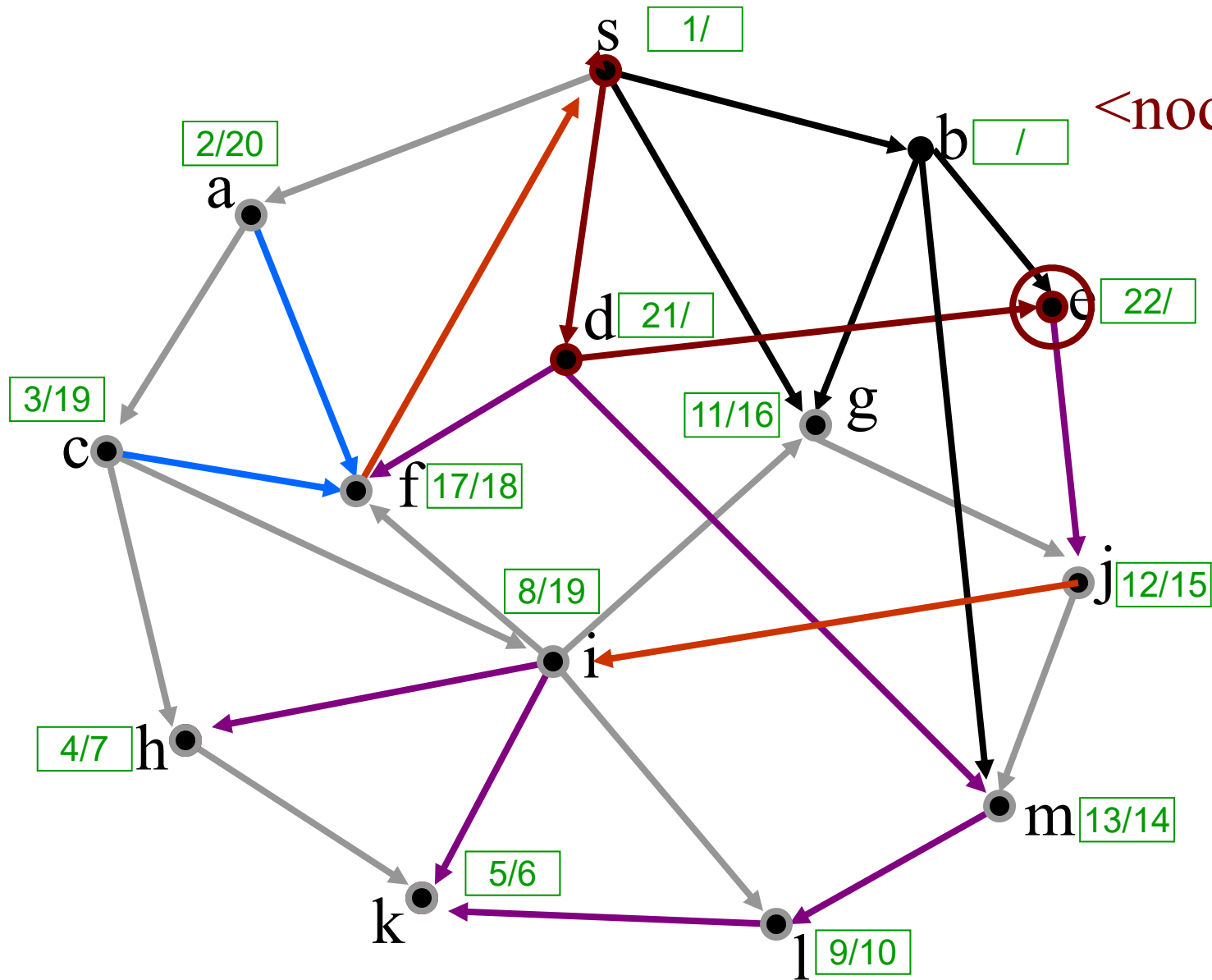


e,0
d,3
s,2

DFS

Found
Not Handled
Stack

<node,# edges>

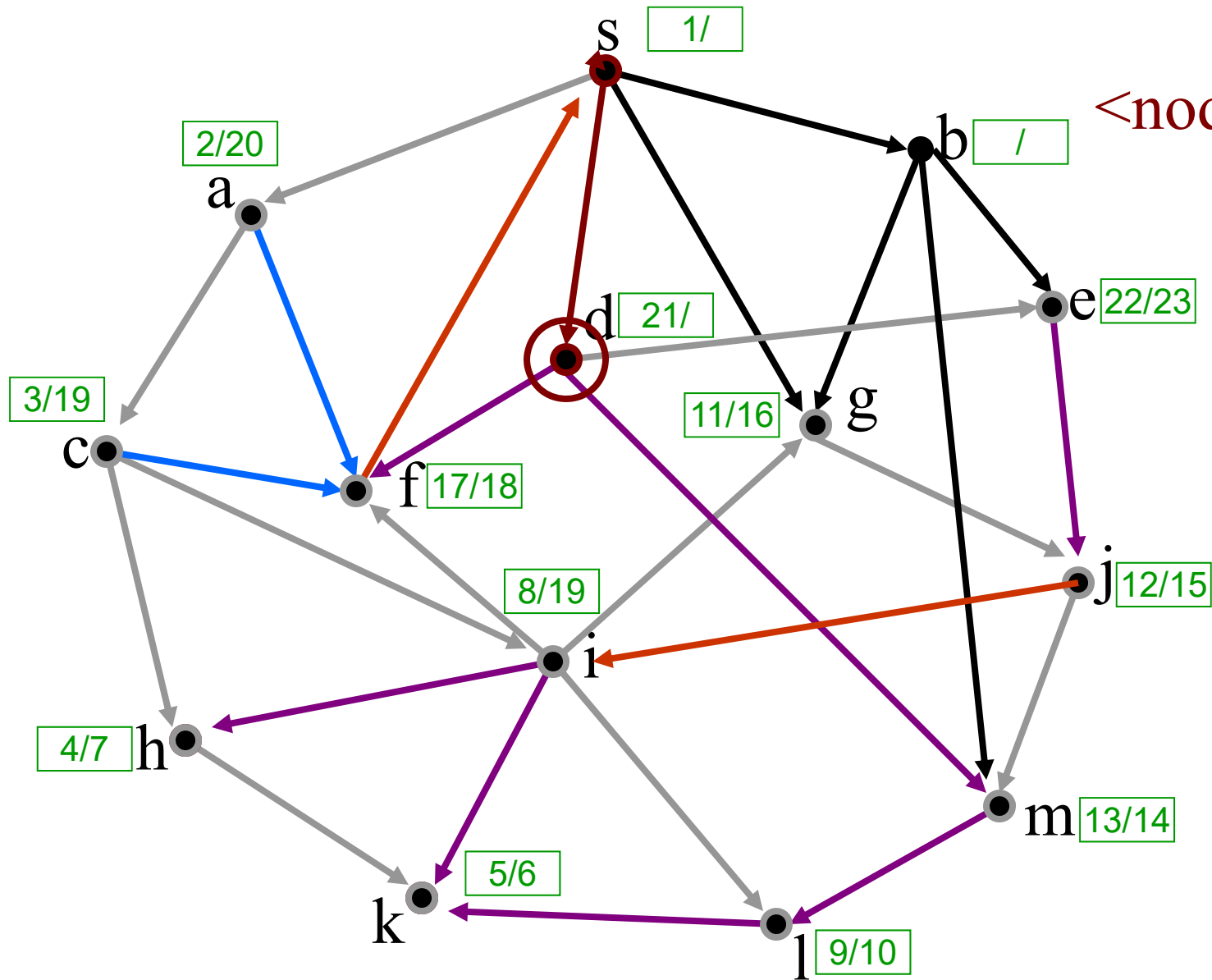


e,1
d,3
s,2

DFS

Found
Not Handled
Stack

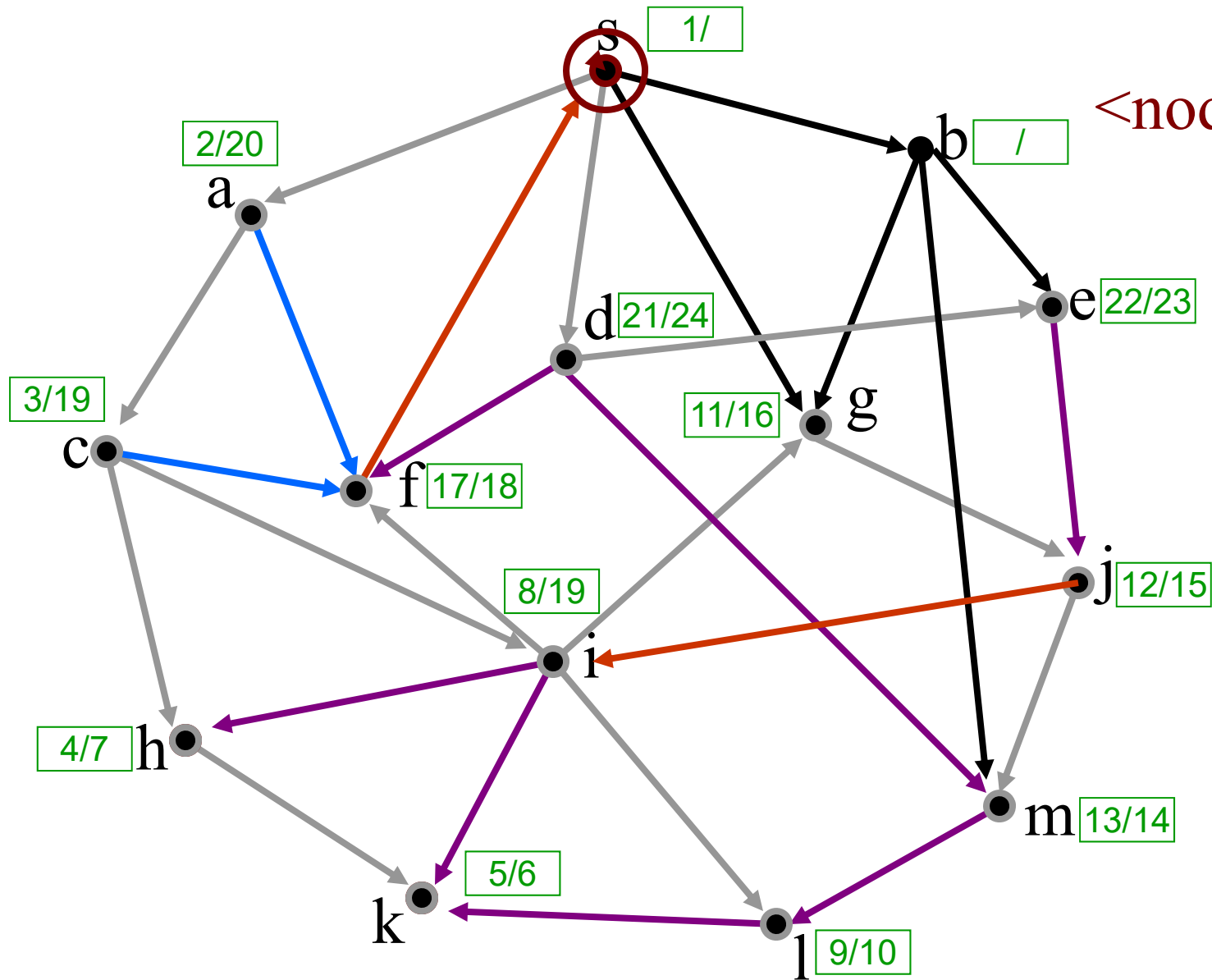
<node,# edges>



DFS

Found
Not Handled
Stack

<node,# edges>

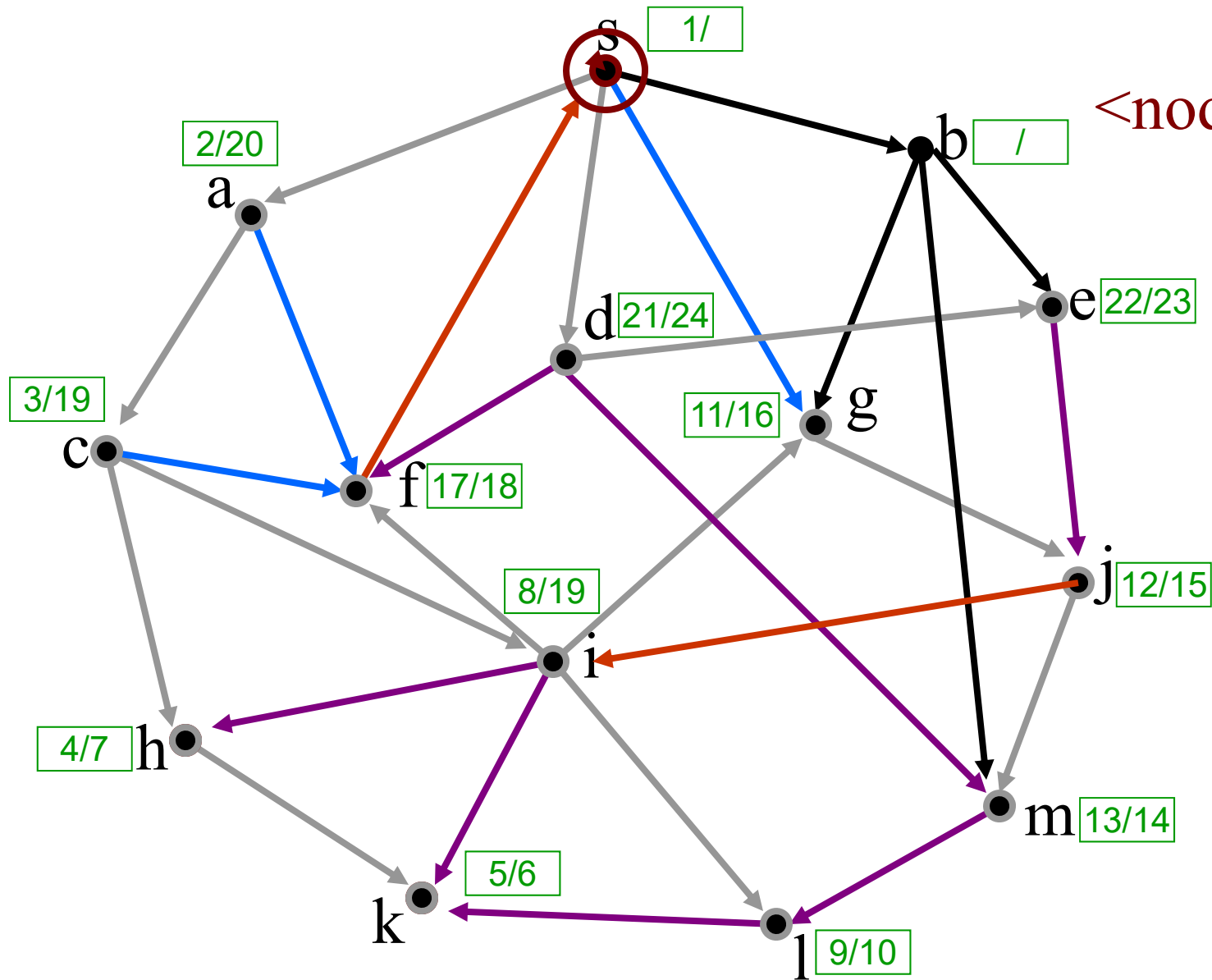


s,2

DFS

Found
Not Handled
Stack

<node,# edges>

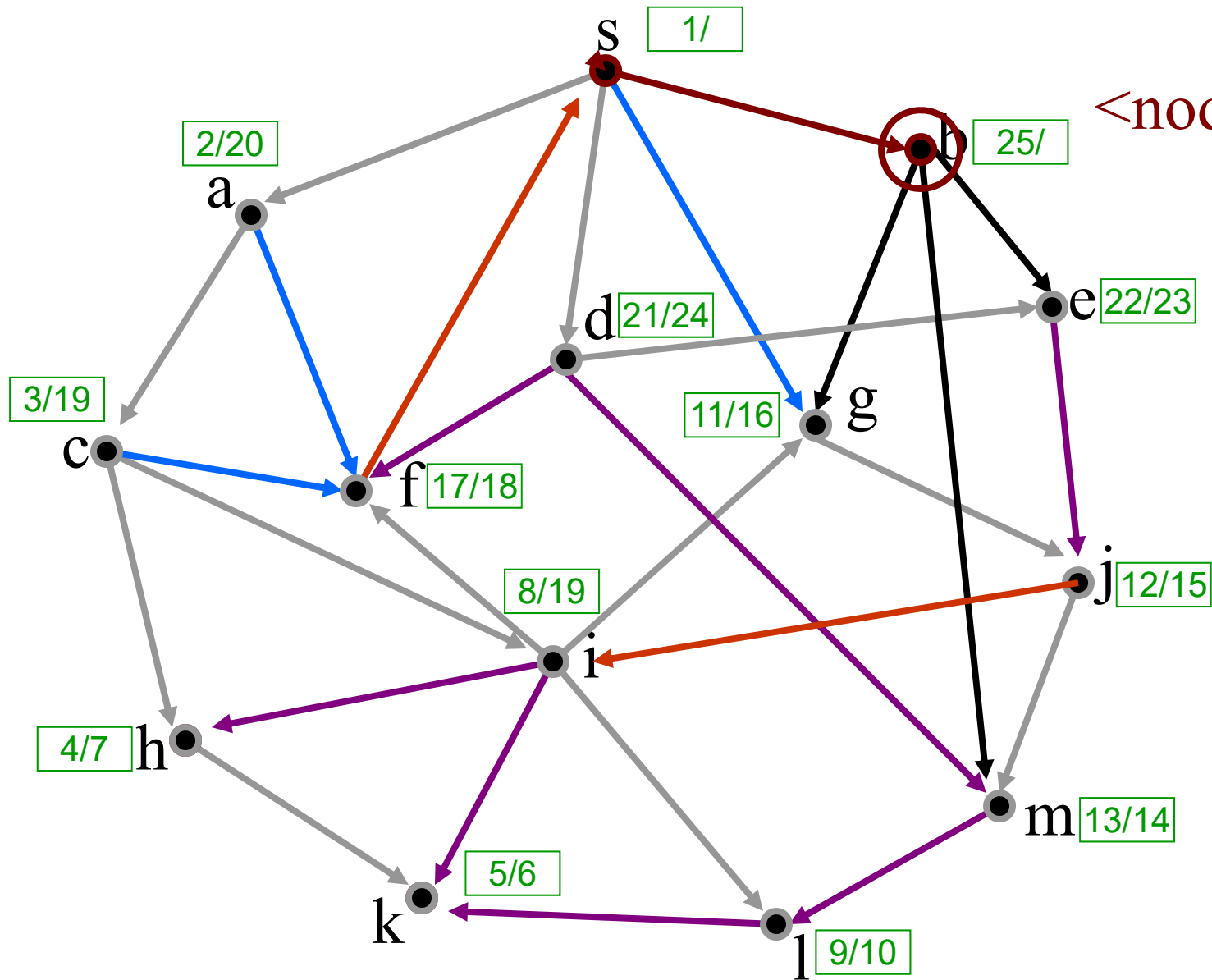


s,3

DFS

Found Not Handled Stack

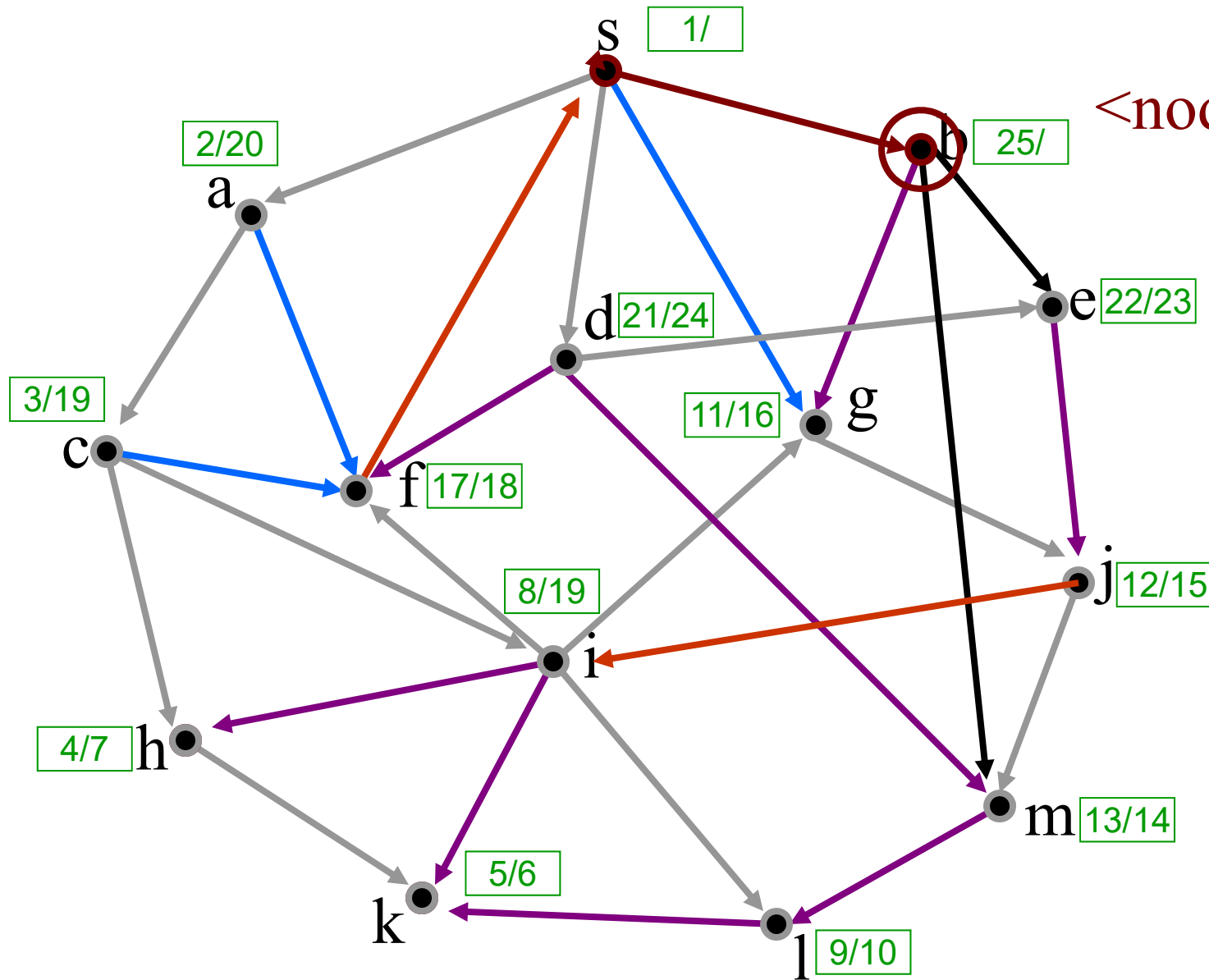
<node,# edges>


$$\begin{matrix} \mathbf{b},0 \\ \mathbf{s},4 \end{matrix}$$

DFS

Found
Not Handled
Stack

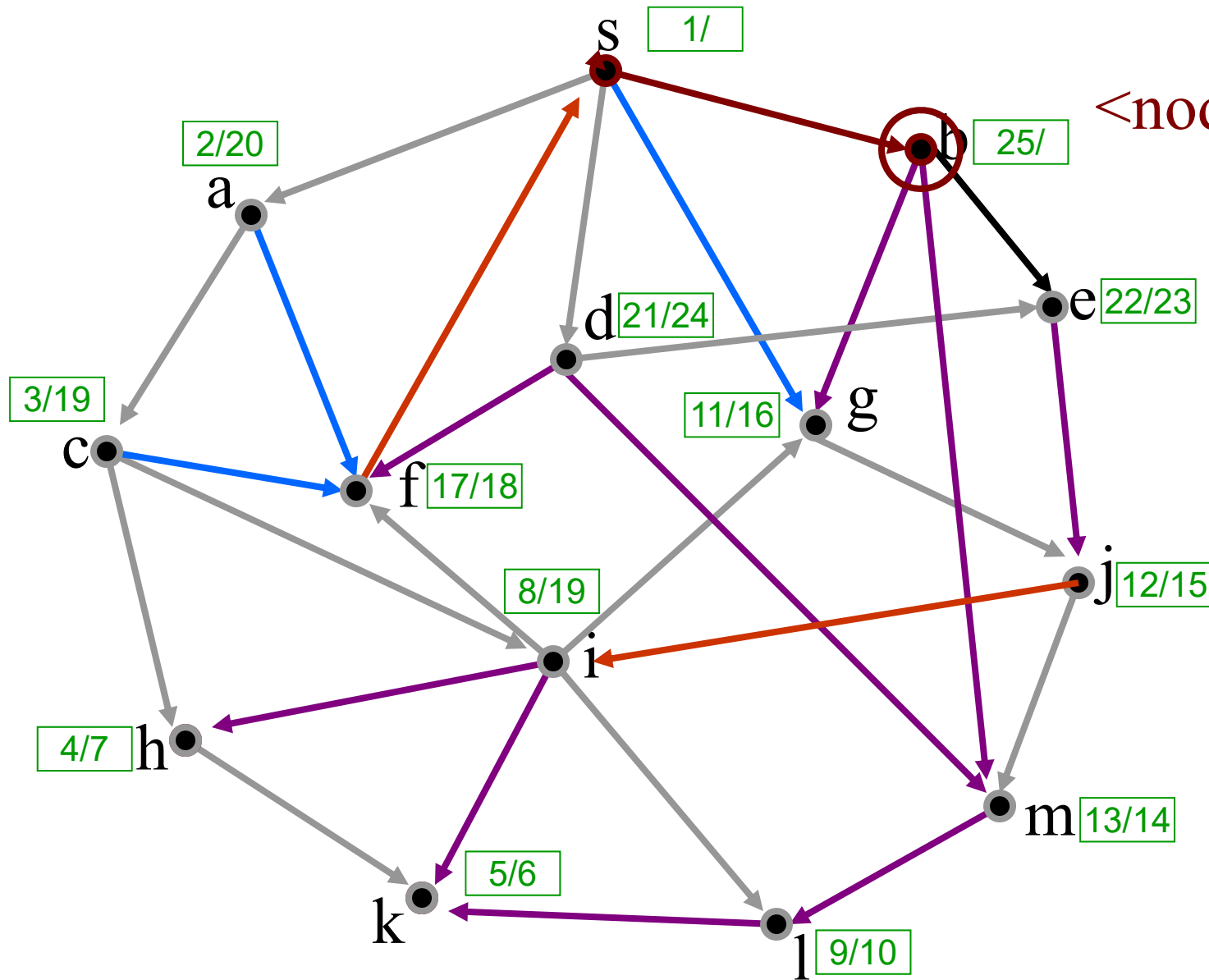
<node,# edges>



DFS

Found
Not Handled
Stack

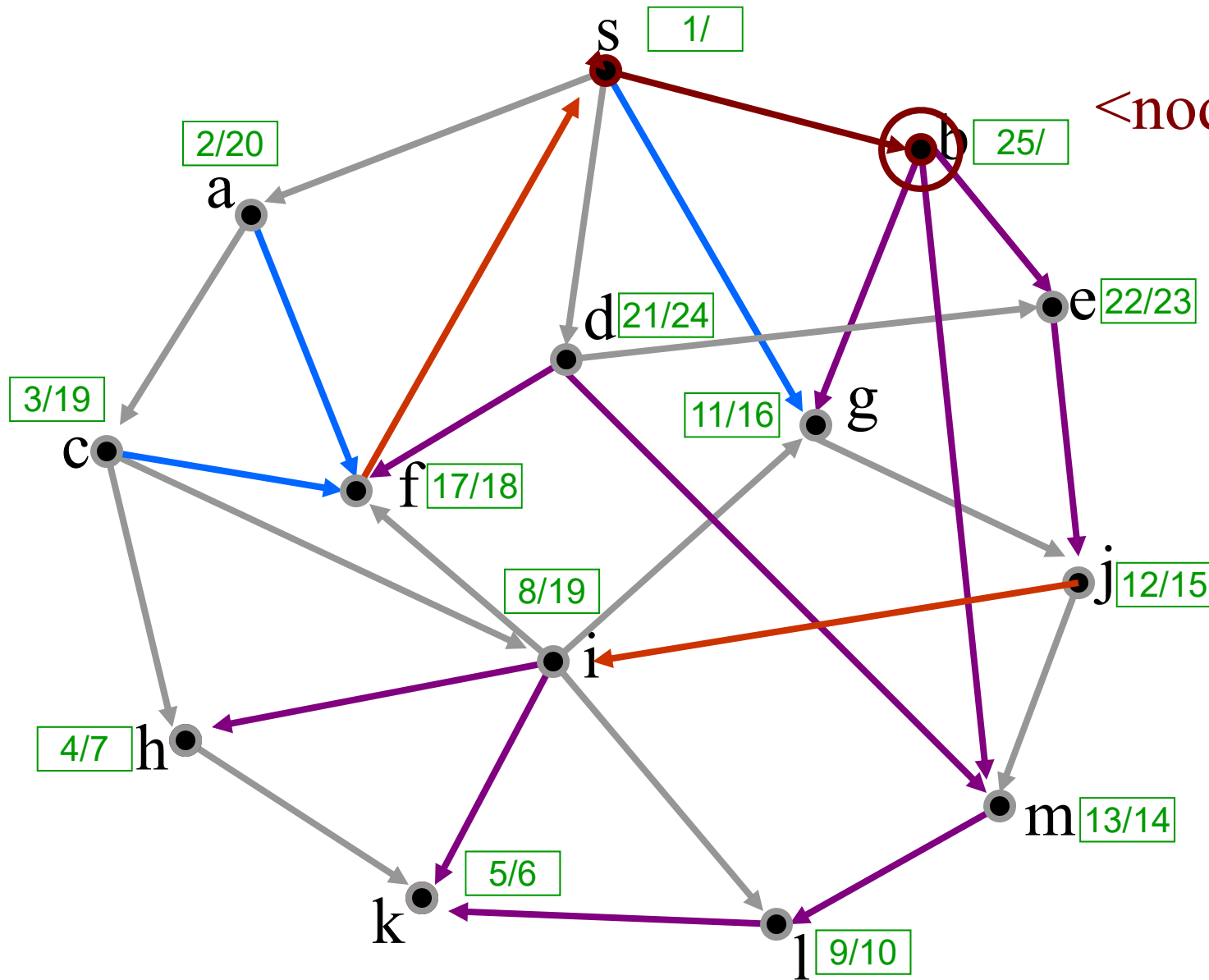
<node,# edges>



DFS

Found
Not Handled
Stack

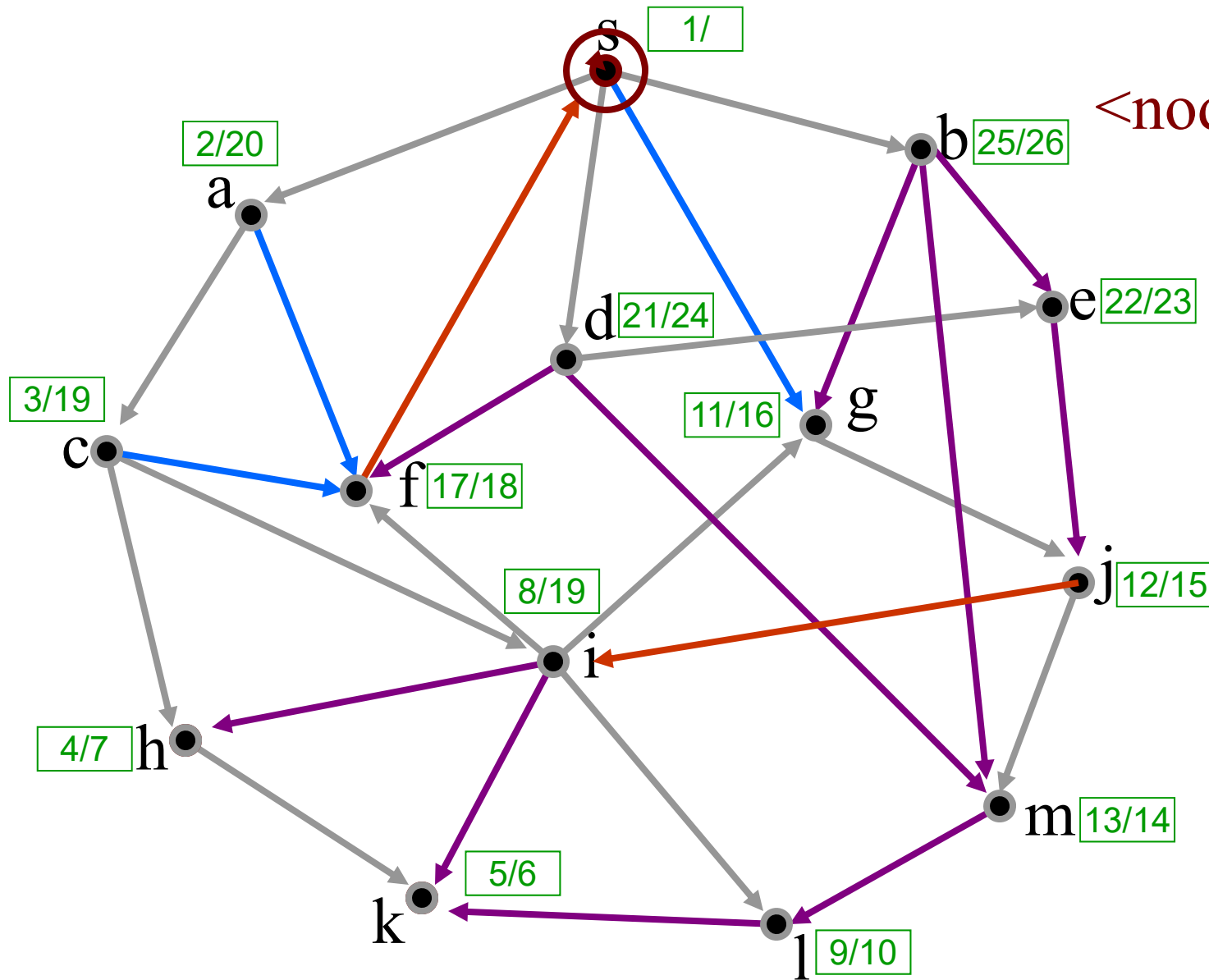
<node,# edges>



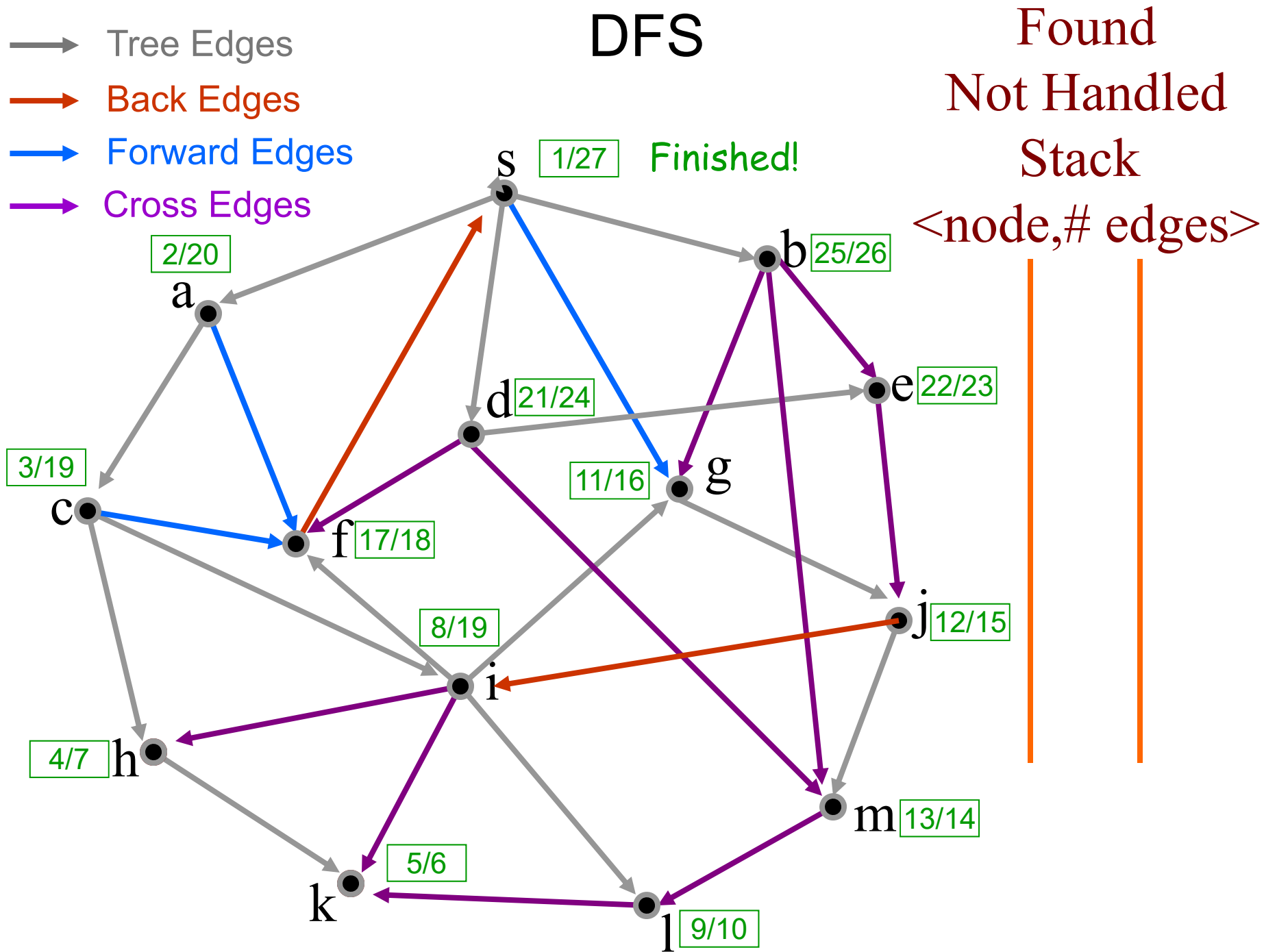
DFS

Found
Not Handled
Stack

<node,# edges>

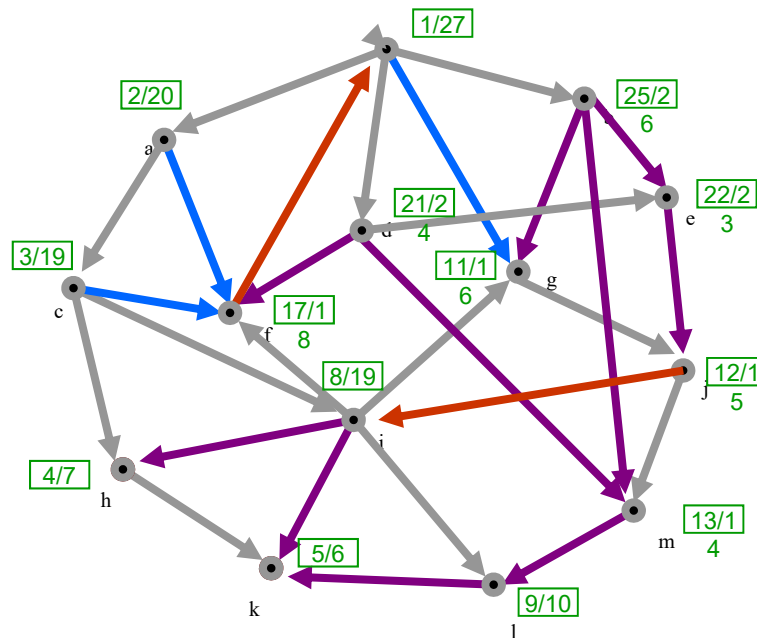


s,4



Classification of Edges in DFS

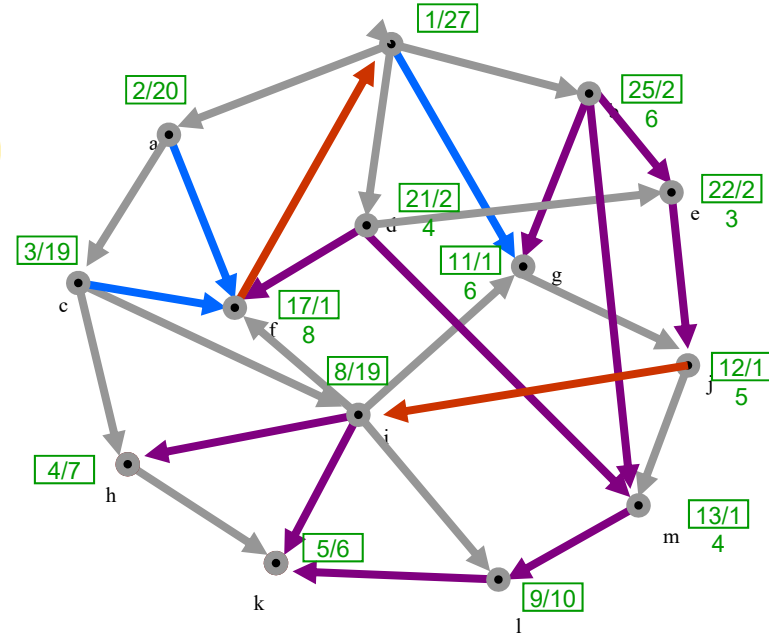
1. **Tree edges** are edges in the depth-first forest G_π . Edge (u, v) is a tree edge if v was first discovered by exploring edge (u, v) .
2. **Back edges** are those edges (u, v) connecting a vertex u to an ancestor v in a depth-first tree.
3. **Forward edges** are non-tree edges (u, v) connecting a vertex u to a descendant v in a depth-first tree.
4. **Cross edges** are all other edges. They can go between vertices in the same depth-first tree, as long as one vertex is not an ancestor of the other.



Classification of Edges in DFS

1. **Tree edges:** Edge (u, v) is a **tree edge** if v was **black** when (u, v) traversed.
2. **Back edges:** (u, v) is a **back edge** if v was **red** when (u, v) traversed.
3. **Forward edges:** (u, v) is a **forward edge** if v was **gray** when (u, v) traversed and $d[v] > d[u]$.
4. **Cross edges:** (u, v) is a **cross edge** if v was **gray** when (u, v) traversed and $d[v] < d[u]$.

Classifying edges can help to identify properties of the graph, e.g., a graph is acyclic iff DFS yields no **back edges**.

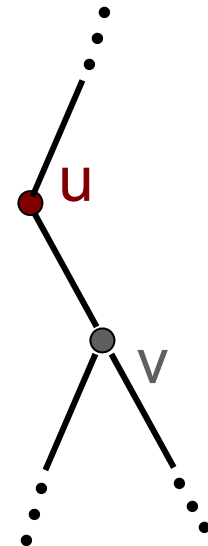


DFS on Undirected Graphs

- In a depth-first search of an *undirected* graph, every edge is either a **tree edge** or a **back edge**.
- **Why?**

DFS on Undirected Graphs

- Suppose that (u,v) is a **forward edge** or a **cross edge** in a DFS of an undirected graph.
- (u,v) is a **forward edge** or a **cross edge** when v is already **handled (grey)** when accessed from u .
- This means that all vertices reachable from v have been explored.
- Since we are currently handling u , u must be **red**.
- Clearly v is reachable from u .
- Since the graph is undirected, u must also be reachable from v .
- Thus u must already have been handled: u must be **grey**.
- **Contradiction!**



Outline

- DFS Algorithm
- DFS Example
- **DFS Applications**

DFS Application 1: Path Finding

- The DFS pattern can be used to find a path between two given vertices u and z , if one exists
- We use a stack to keep track of the current path
- If the destination vertex z is encountered, we return the path as the contents of the stack

DFS-Path ($u, z, stack$)

Precondition: u and z are vertices in a graph, $stack$ contains current path

Postcondition: returns true if path from u to z exists, $stack$ contains path

colour[u] \leftarrow RED

push u onto $stack$

if $u = z$

 return TRUE

for each $v \in \text{Adj}[u]$ //explore edge (u, v)

 if color[v] = BLACK

 if DFS-Path($v, z, stack$)

 return TRUE

colour[u] \leftarrow GRAY

pop u from $stack$

return FALSE

DFS Application 2: Cycle Finding

- The DFS pattern can be used to determine whether a graph is acyclic.
- If a back edge is encountered, we return true.

DFS-Cycle (u)

Precondition: u is a vertex in a graph G

Postcondition: returns true if there is a cycle reachable from u .

$colour[u] \leftarrow RED$

for each $v \in Adj[u]$ //explore edge (u,v)

 if $color[v] = RED$ //back edge

 return true

 else if $color[v] = BLACK$

 if DFS-Cycle(v)

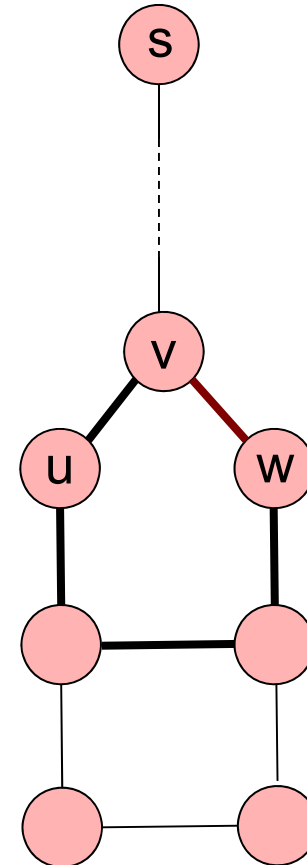
 return true

$colour[u] \leftarrow GRAY$

return false

Why must DFS on a graph with a cycle generate a back edge?

- Suppose that vertex s is in a connected component S that contains a cycle C .
- Since all vertices in S are reachable from s , they will all be visited by a DFS from s .
- Let v be the first vertex in C reached by a DFS from s .
- There are two vertices u and w adjacent to v on the cycle C .
- wlog, suppose u is explored first.
- Since w is reachable from u , w will eventually be discovered.
- When exploring w 's adjacency list, the back-edge (w, v) will be discovered.



DFS Application 3. Topological Sorting (e.g., putting tasks in linear order)

Note: The textbook also describes a breadth-first TopologicalSort algorithm (Section 13.4.3)

DAGs and Topological Ordering

- A directed acyclic graph (DAG) is a digraph that has no directed cycles
- A topological ordering of a digraph is a numbering

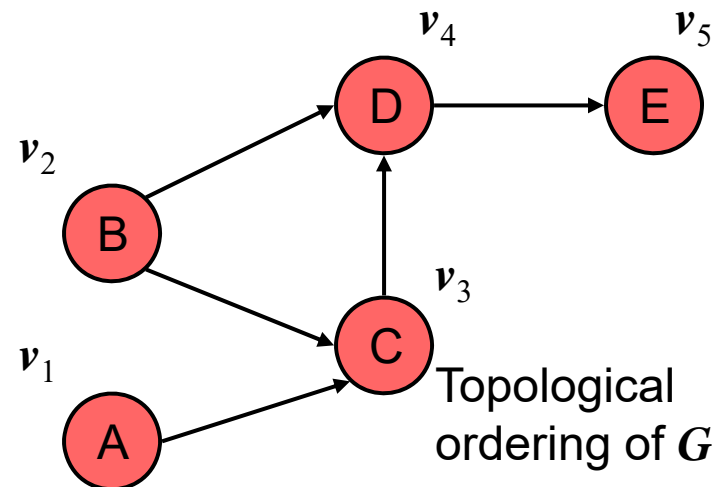
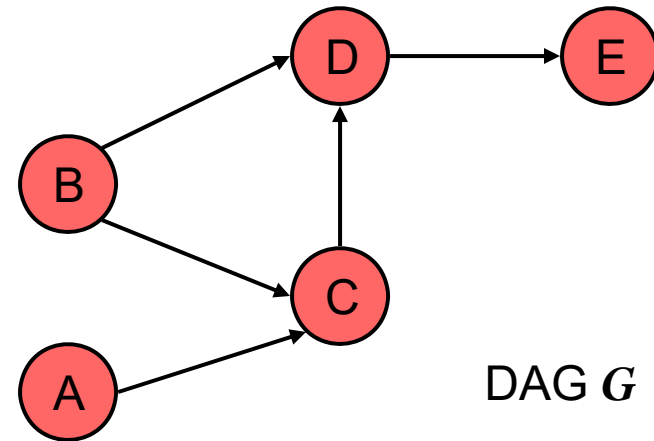
$$v_1, \dots, v_n$$

of the vertices such that for every edge (v_i, v_j) , we have $i < j$

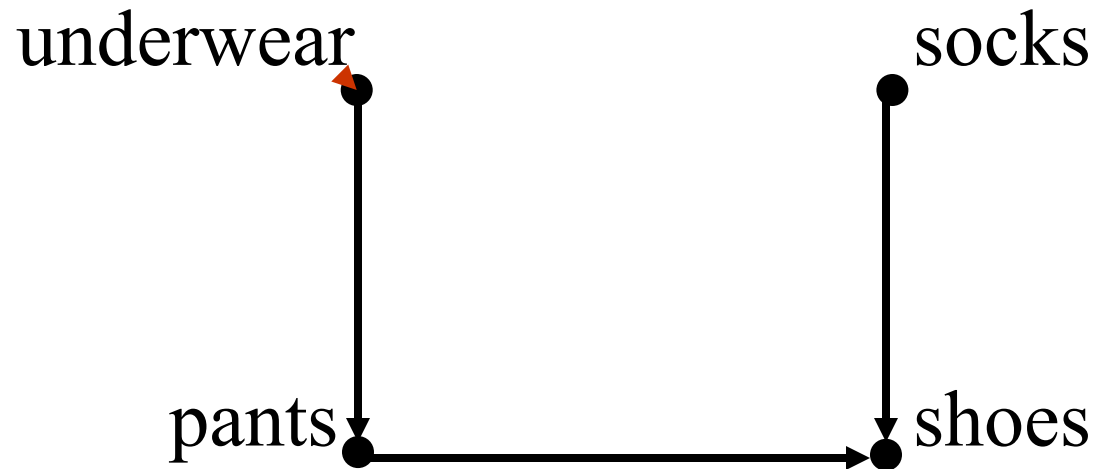
- Example: in a task scheduling digraph, a topological ordering is a task sequence that satisfies the precedence constraints

Theorem

A digraph admits a topological ordering if and only if it is a DAG



Topological (Linear) Order



underwear
pants
socks
shoes

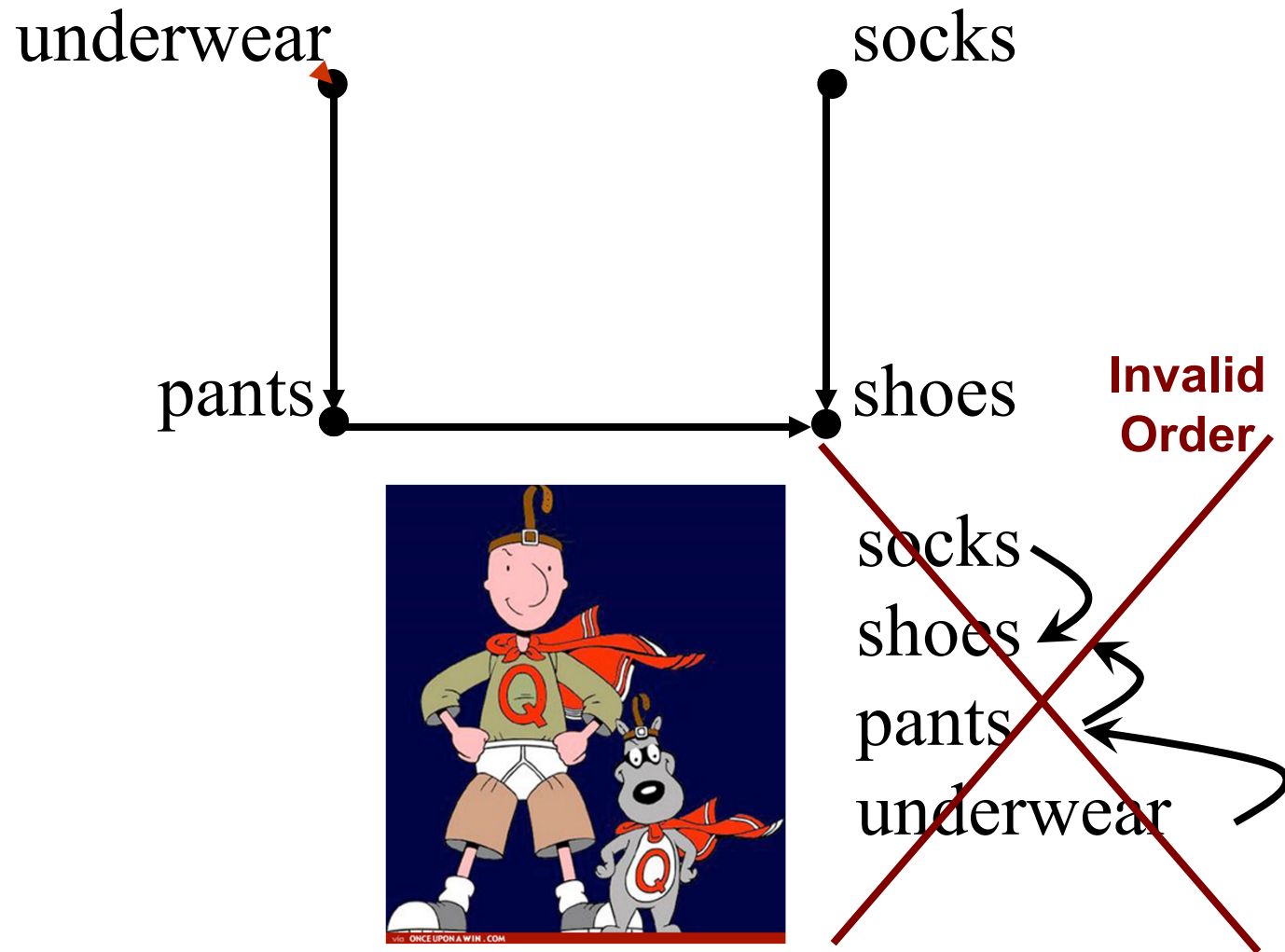
Two curved arrows on the right side of the list point from 'socks' to 'underwear' and from 'shoes' to 'pants', indicating a reverse topological sort.



socks
underwear
pants
shoes

Two curved arrows on the right side of the list point from 'socks' to 'underwear' and from 'shoes' to 'pants', indicating a reverse topological sort.

Topological (Linear) Order



Algorithm for Topological Sorting

- Note: This algorithm is different than the one in Goodrich-Tamassia

Method TopologicalSort(**G**)

H \leftarrow **G** // Temporary copy of **G**

n \leftarrow **G.numVertices()**

while **H** is not empty **do**

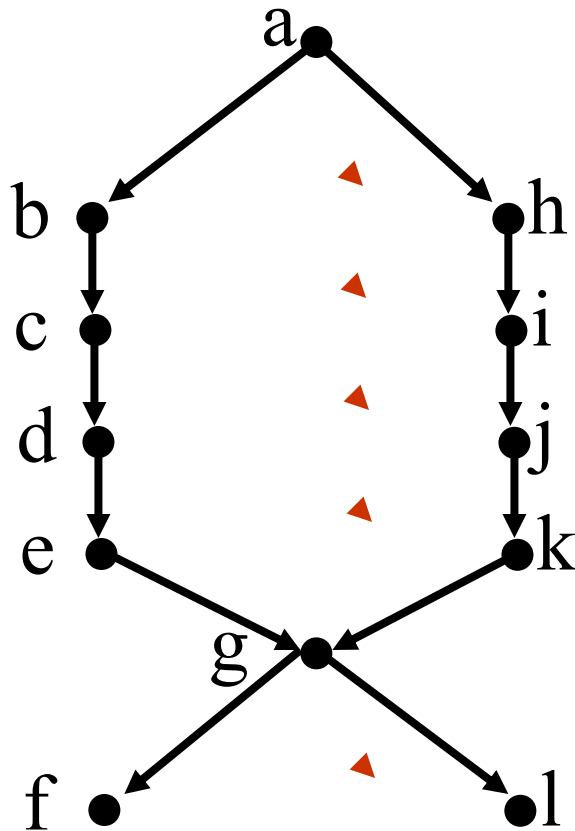
Let **v** be a vertex with no outgoing edges

Label **v** \leftarrow **n**

n \leftarrow **n** - 1

Remove **v** from **H** //as well as edges involving **v**

Linear Order



Pre-Condition:

A Directed Acyclic Graph
(DAG)

Post-Condition:

Find one valid linear order

Algorithm:

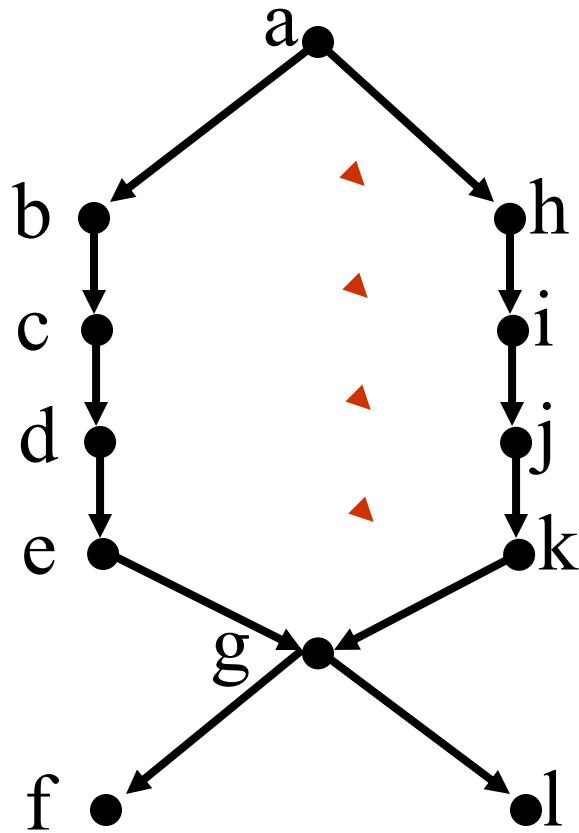
- Find a terminal node (sink).
 - Put it last in sequence.
 - Delete from graph & repeat
- } $O(|V|)$

Running time: $\sum_{i=1}^{|V|} i = O(|V|^2)$

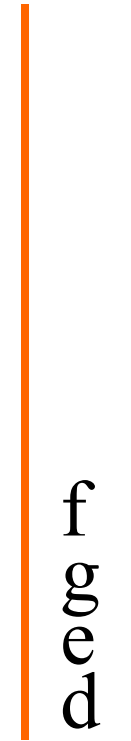
..... 1 Can we do better?

Linear Order

Alg: DFS



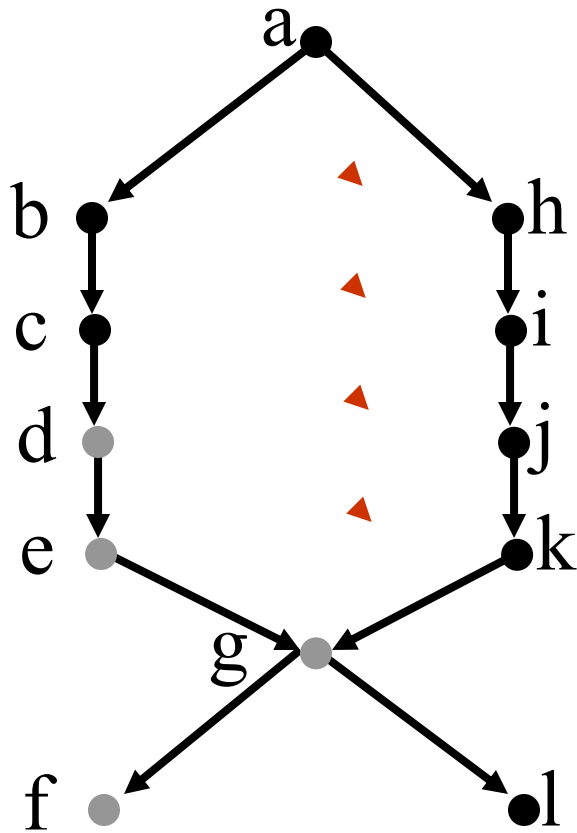
Found
Not Handled
Stack



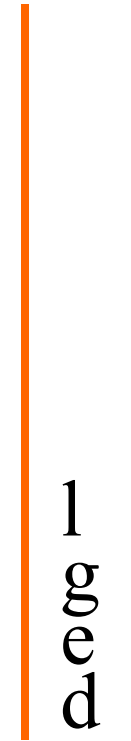
..... f

Linear Order

Alg: DFS



Found
Not Handled
Stack



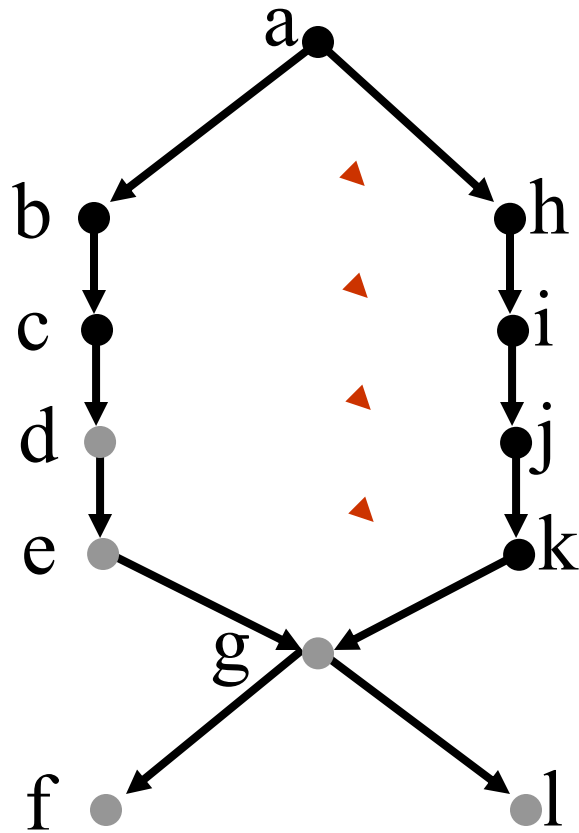
When node is popped off stack, insert at front of linearly-ordered “to do” list.

Linear Order:

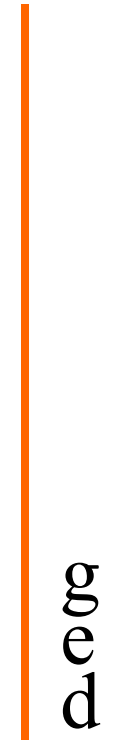
..... f

Linear Order

Alg: DFS



Found
Not Handled
Stack

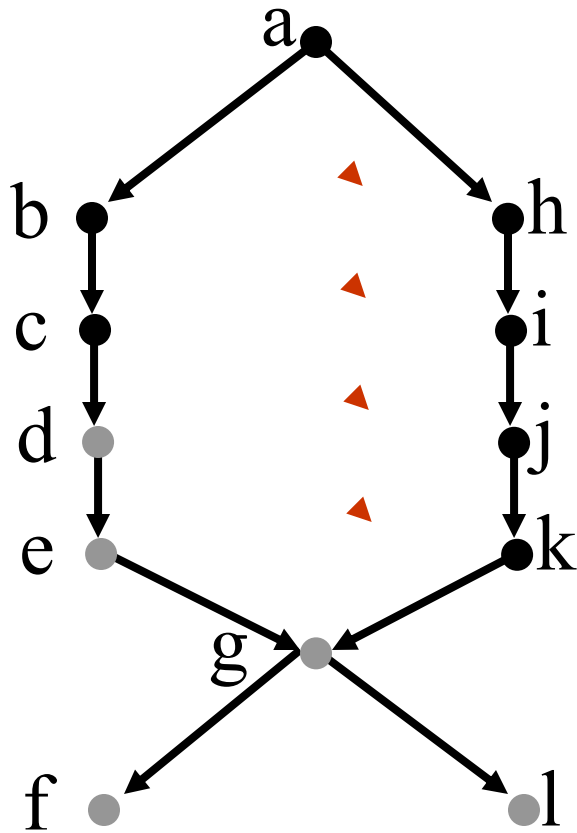


Linear Order:

l,f

Linear Order

Alg: DFS



Found
Not Handled
Stack

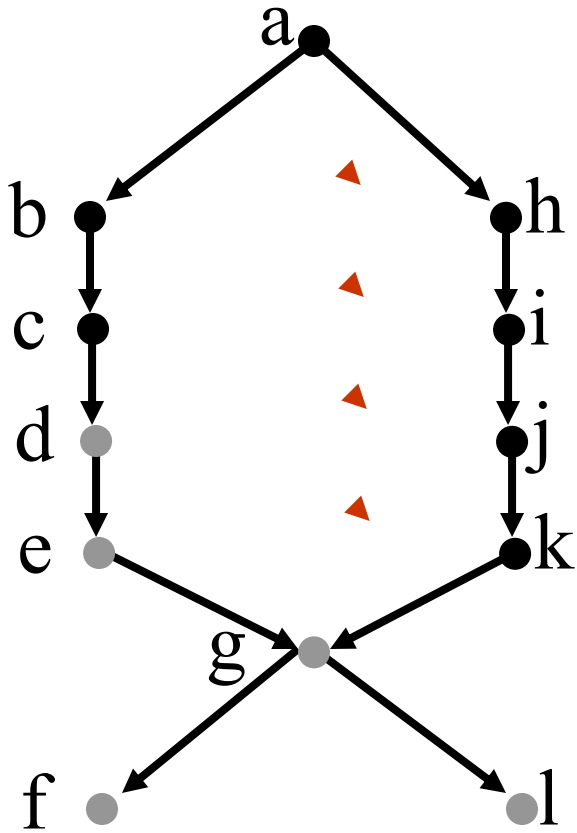


Linear Order:

g,l,f

Linear Order

Alg: DFS



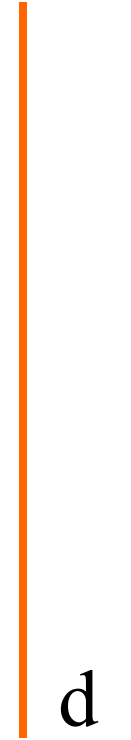
Linear Order:

e,g,l,f

Found

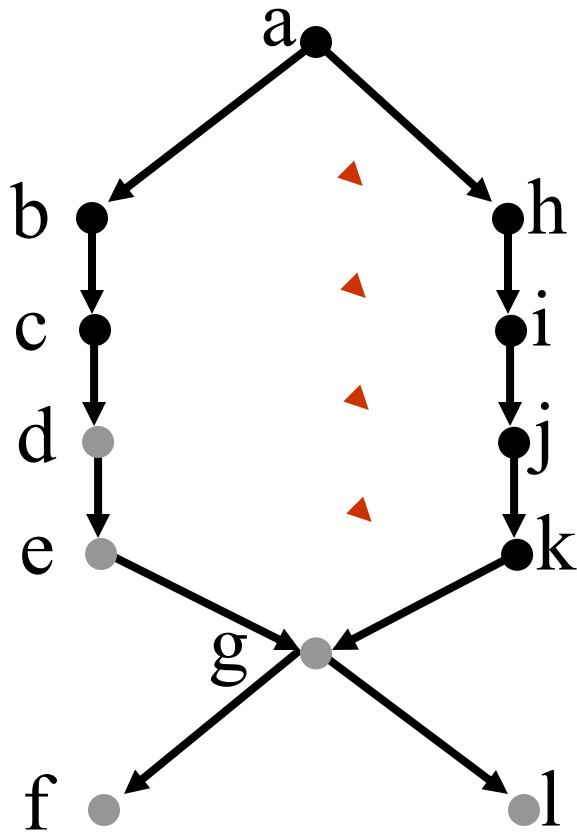
Not Handled

Stack

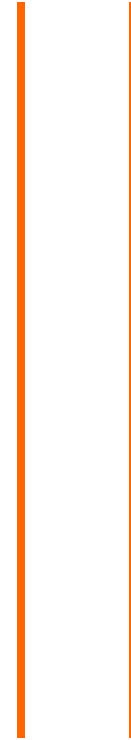


Linear Order

Alg: DFS



Found
Not Handled
Stack

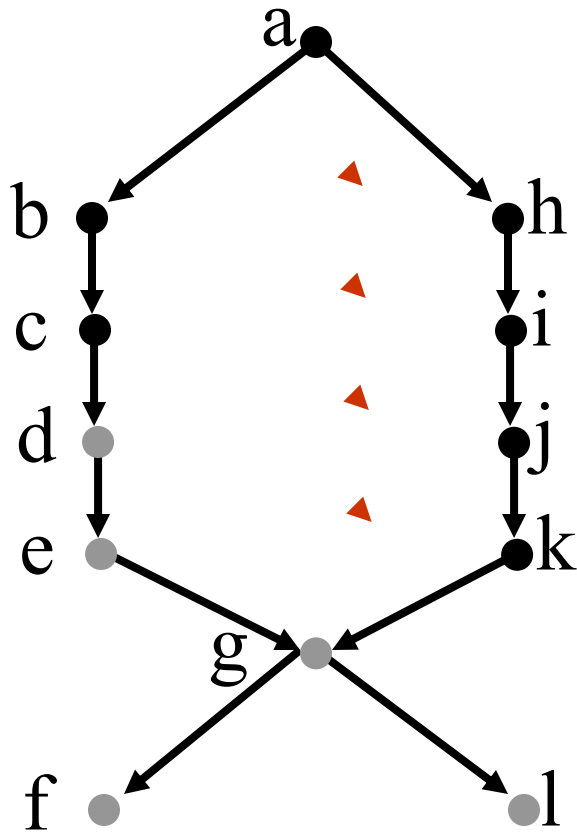


Linear Order:

d,e,g,l,f

Linear Order

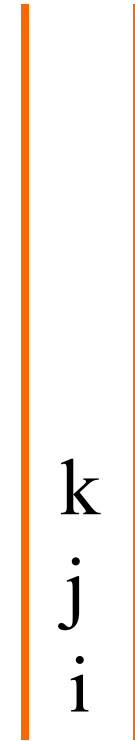
Alg: DFS



Linear Order:

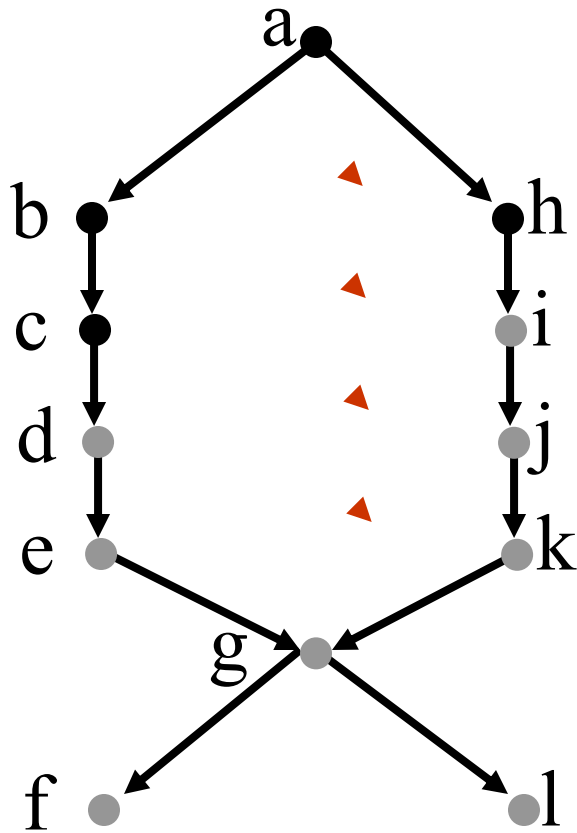
d,e,g,l,f

Found
Not Handled
Stack



Linear Order

Alg: DFS



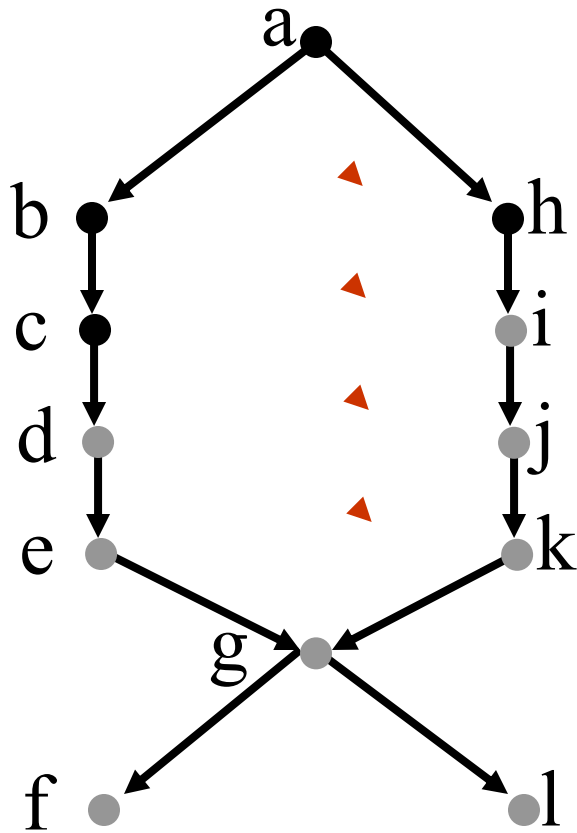
Linear Order: k,d,e,g,l,f

Found
Not Handled
Stack



Linear Order

Alg: DFS



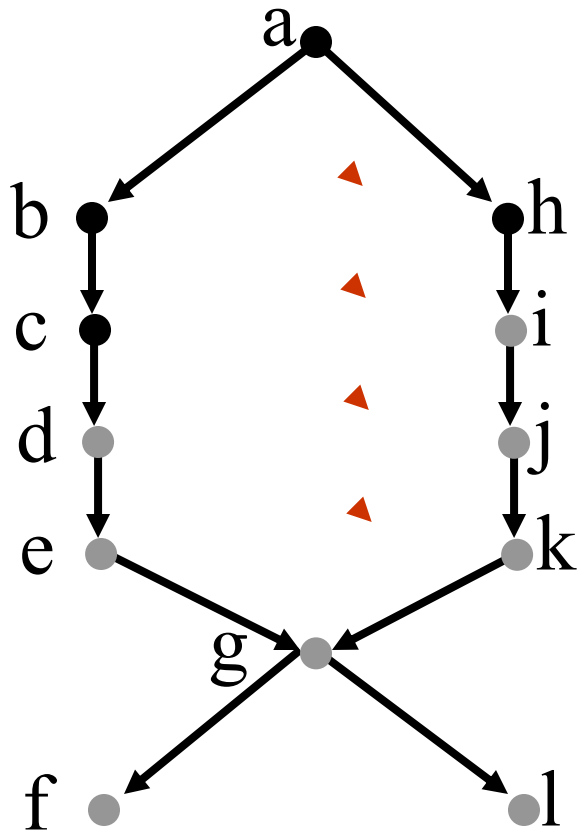
Found
Not Handled
Stack



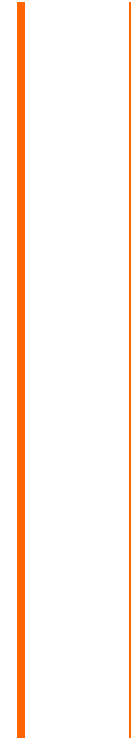
Linear Order: j,k,d,e,g,l,f

Linear Order

Alg: DFS



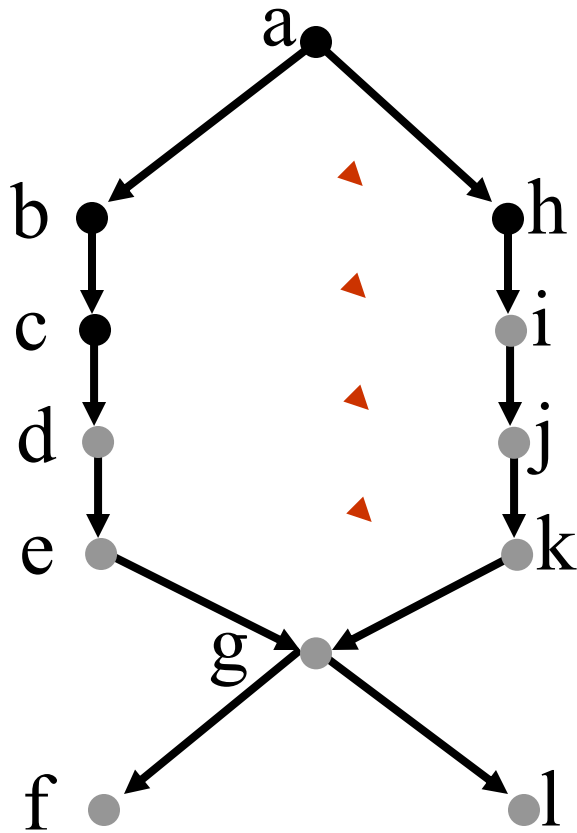
Found
Not Handled
Stack



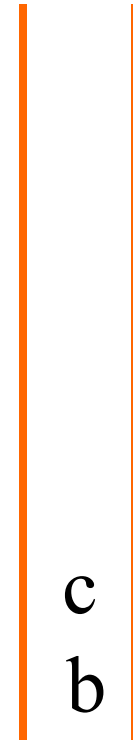
Linear Order: i,j,k,d,e,g,l,f

Linear Order

Alg: DFS



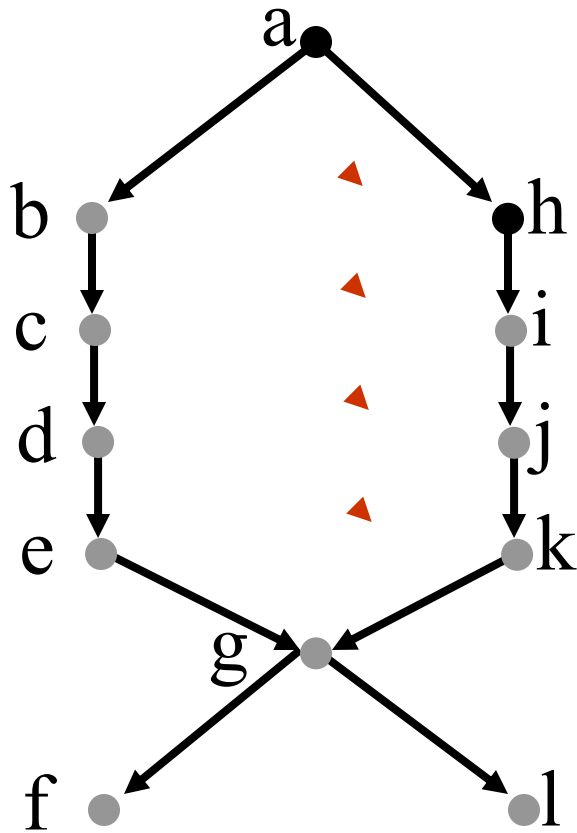
Found
Not Handled
Stack



Linear Order: i,j,k,d,e,g,l,f

Linear Order

Alg: DFS

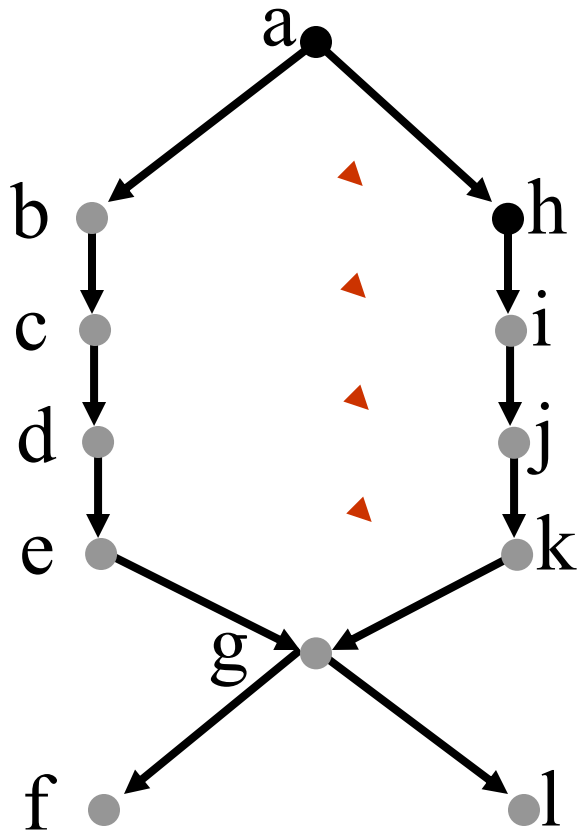


Found
Not Handled
Stack

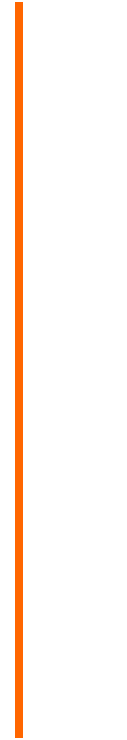
Linear Order: c,i,j,k,d,e,g,l,f

Linear Order

Alg: DFS



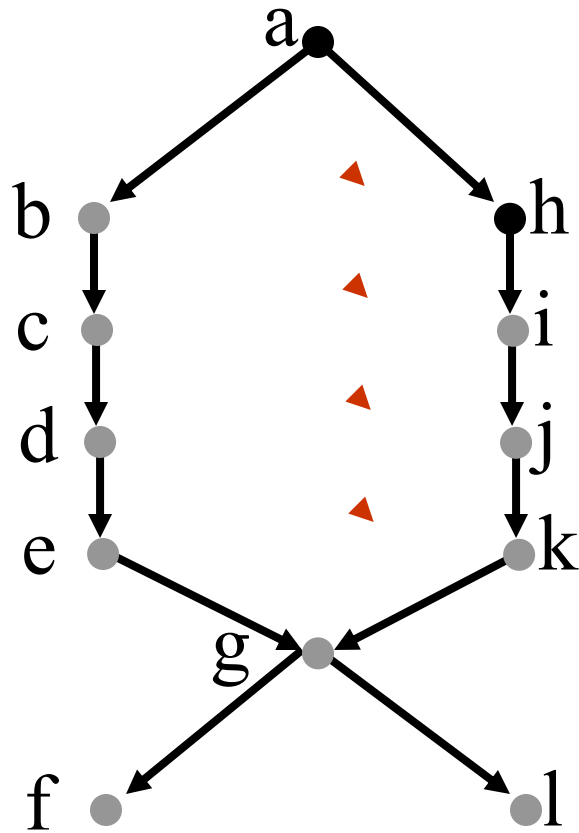
Found
Not Handled
Stack



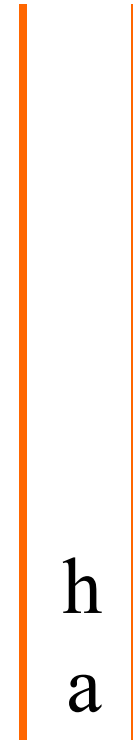
Linear Order: b,c,i,j,k,d,e,g,l,f

Linear Order

Alg: DFS



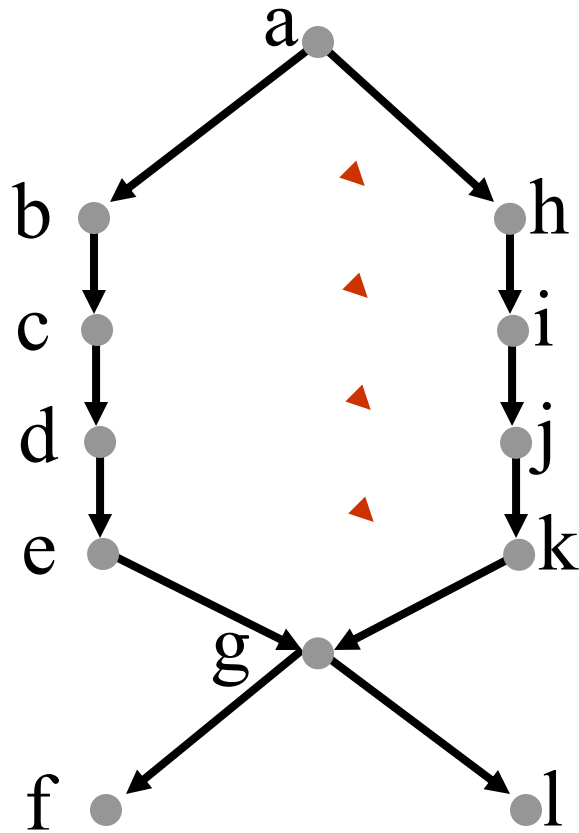
Found
Not Handled
Stack



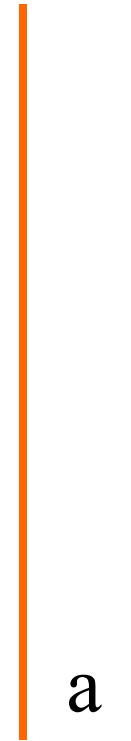
Linear Order: b,c,i,j,k,d,e,g,l,f

Linear Order

Alg: DFS

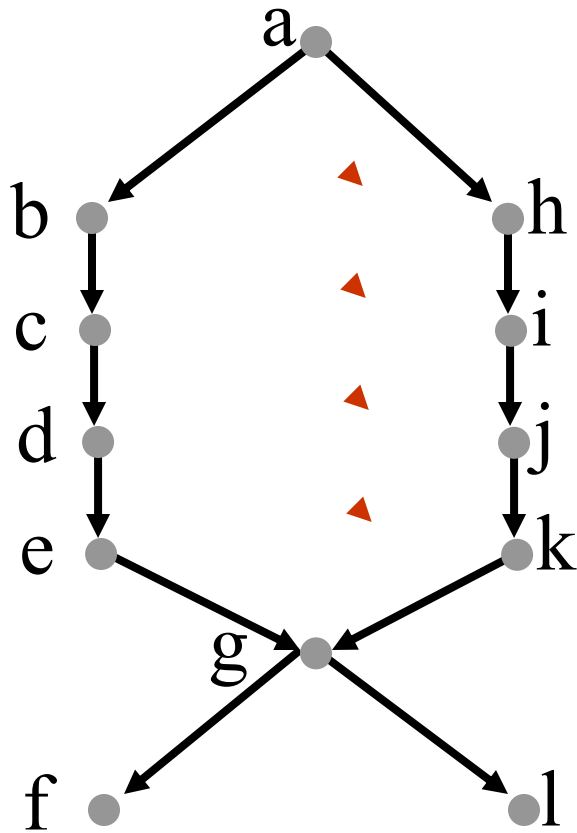


Found
Not Handled
Stack



Linear Order: h,b,c,i,j,k,d,e,g,l,f

Linear Order
Alg: DFS



Found
Not Handled
Stack



Linear Order: a,h,b,c,i,j,k,d,e,g,l,f Done!

DFS Algorithm for Topological Sort

➤ Makes sense. But how do we prove that it works?

Linear Order

Proof: Consider each edge

- Case 1: u goes on stack first before v .
 - Because of edge,
 - v goes on before u comes off
 - v comes off before u comes off
 - v goes after u in order. ☺

Found
Not Handled
Stack



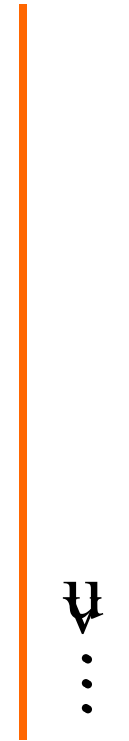
$u \dots v \dots$

Linear Order

Proof: Consider each edge

- Case 1: u goes on stack first before v.
- Case 2: v goes on stack first before u.
v comes off before u goes on.
- v goes after u in order. ☺

Found
Not Handled
Stack



u...v...

Linear Order

Proof: Consider each edge

- Case 1: u goes on stack first before v.
- Case 2: v goes on stack first before u.
v comes off before u goes on.
- Case 3: v goes on stack first before u.
u goes on before v comes off.
- Panic: u goes after v in order. ☹
- Cycle means linear order
is impossible ☺

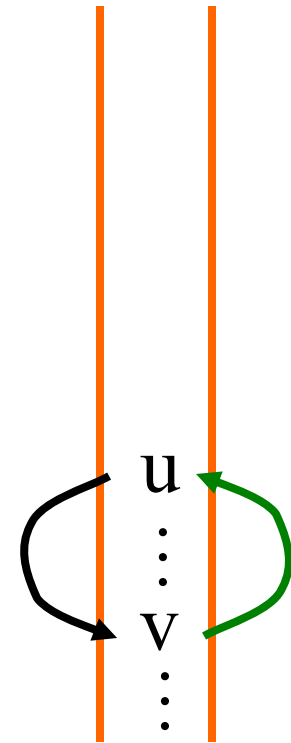


The nodes in the stack form a path starting at s.

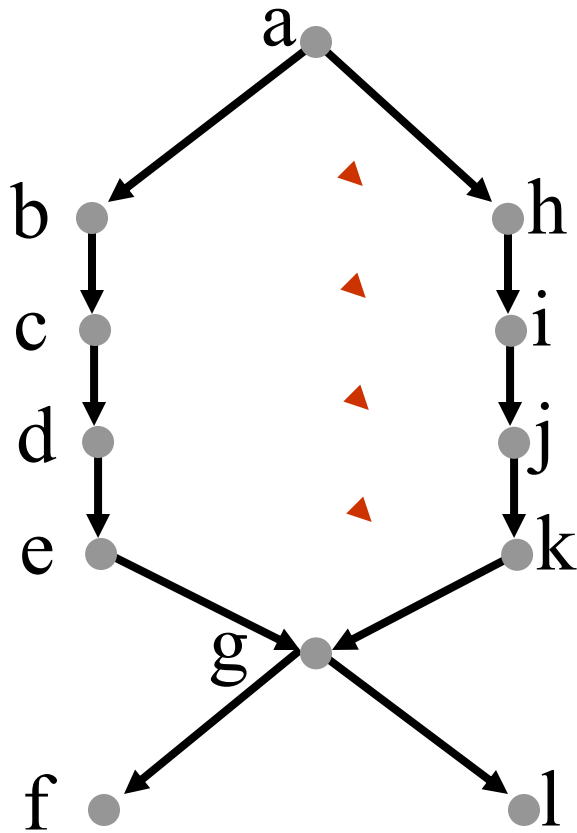
u ● → ● v

v...u...

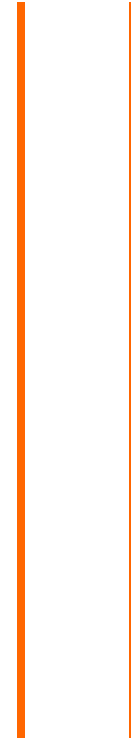
Found
Not Handled
Stack



Linear Order
Alg: DFS



Found
Not Handled
Stack



Analysis: $\Theta(V+E)$

Linear Order: a,h,b,c,i,j,k,d,e,g,l,f Done!

DFS Application 3. Topological Sort

Topological-Sort(G)

Precondition: G is a graph

Postcondition: all vertices in G have been pushed onto stack in reverse linear order

for each vertex $u \in V[G]$

color[u] = BLACK //initialize vertex

for each vertex $u \in V[G]$

if color[u] = BLACK //as yet unexplored

Topological-Sort-Visit(u)



DFS Application 3. Topological Sort

Topological-Sort-Visit (u)

Precondition: vertex u is undiscovered

Postcondition: u and all vertices reachable from u
have been pushed onto stack in reverse linear order

$\text{colour}[u] \leftarrow \text{RED}$

for each $v \in \text{Adj}[u]$ //explore edge (u, v)

if $\text{color}[v] = \text{BLACK}$

Topological-Sort-Visit(v)

push u onto stack

$\text{colour}[u] \leftarrow \text{GRAY}$

Outline

- DFS Algorithm
- DFS Example
- DFS Applications