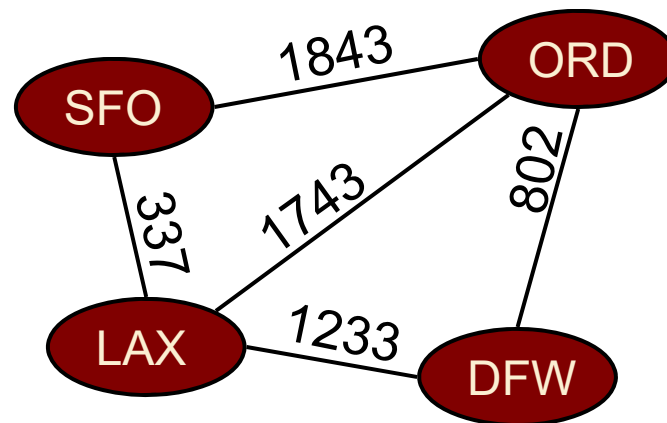
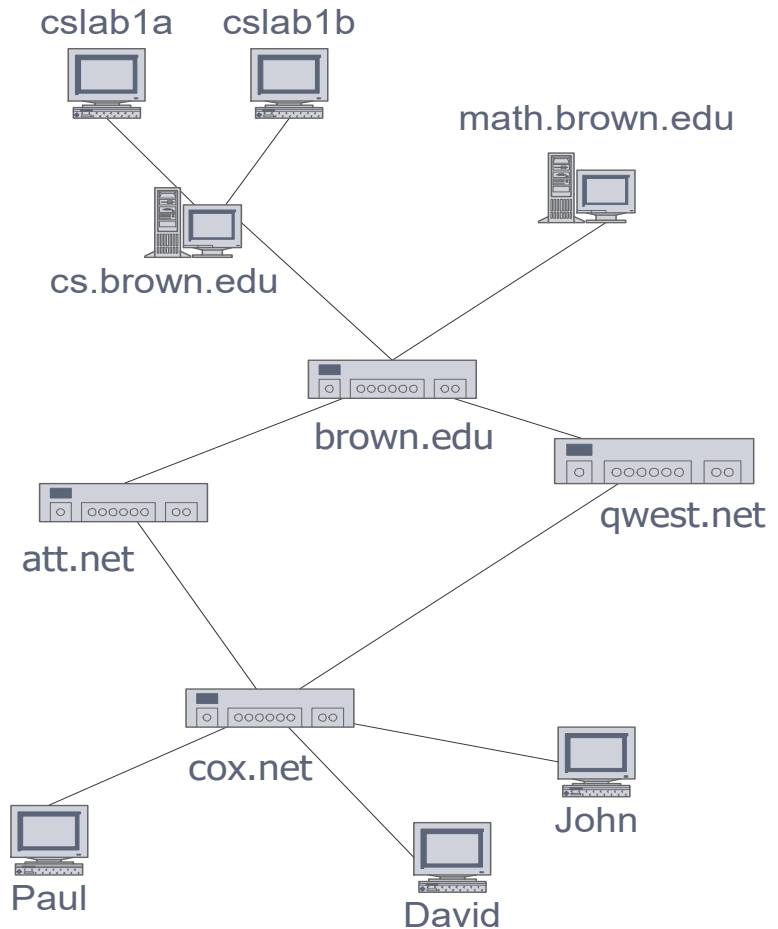


# Graphs – ADTs and Implementations



# Applications of Graphs

- Electronic circuits
  - ❑ Printed circuit board
  - ❑ Integrated circuit
- Transportation networks
  - ❑ Highway network
  - ❑ Flight network
- Computer networks
  - ❑ Local area network
  - ❑ Internet
  - ❑ Web
- Databases
  - ❑ Entity-relationship diagram



# Outline

- Definitions
- Graph ADT
- Implementations

# Outline

- **Definitions**
- Graph ADT
- Implementations

# Edge Types

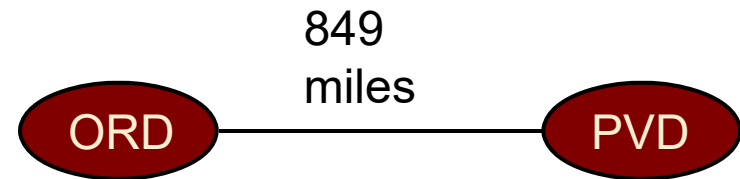
## ➤ Directed edge

- ❑ ordered pair of vertices  $(u,v)$
- ❑ first vertex  $u$  is the origin
- ❑ second vertex  $v$  is the destination
- ❑ e.g., a flight



## ➤ Undirected edge

- ❑ unordered pair of vertices  $(u,v)$
- ❑ e.g., a flight route



## ➤ Directed graph (Digraph)

- ❑ all the edges are directed
- ❑ e.g., route network

## ➤ Undirected graph

- ❑ all the edges are undirected
- ❑ e.g., flight network

# Vertices and Edges

➤ End vertices (or endpoints) of an edge

❑ U and V are the endpoints of a

➤ Edges incident on a vertex

❑ a, d, and b are incident on V

➤ Adjacent vertices

❑ U and V are adjacent

➤ Degree of a vertex

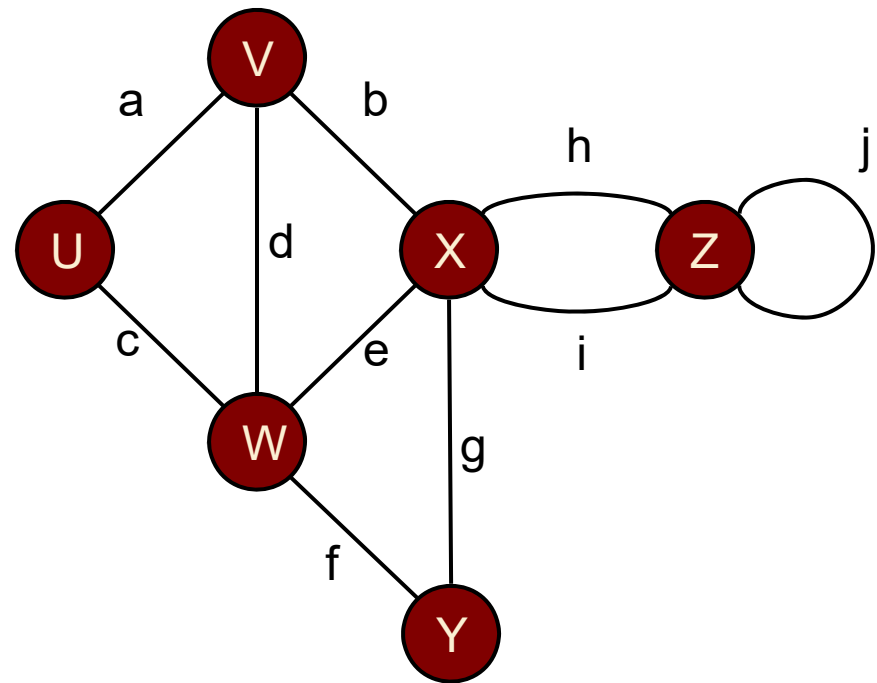
❑ X has degree 5

➤ Parallel edges

❑ h and i are parallel edges

➤ Self-loop

❑ j is a self-loop



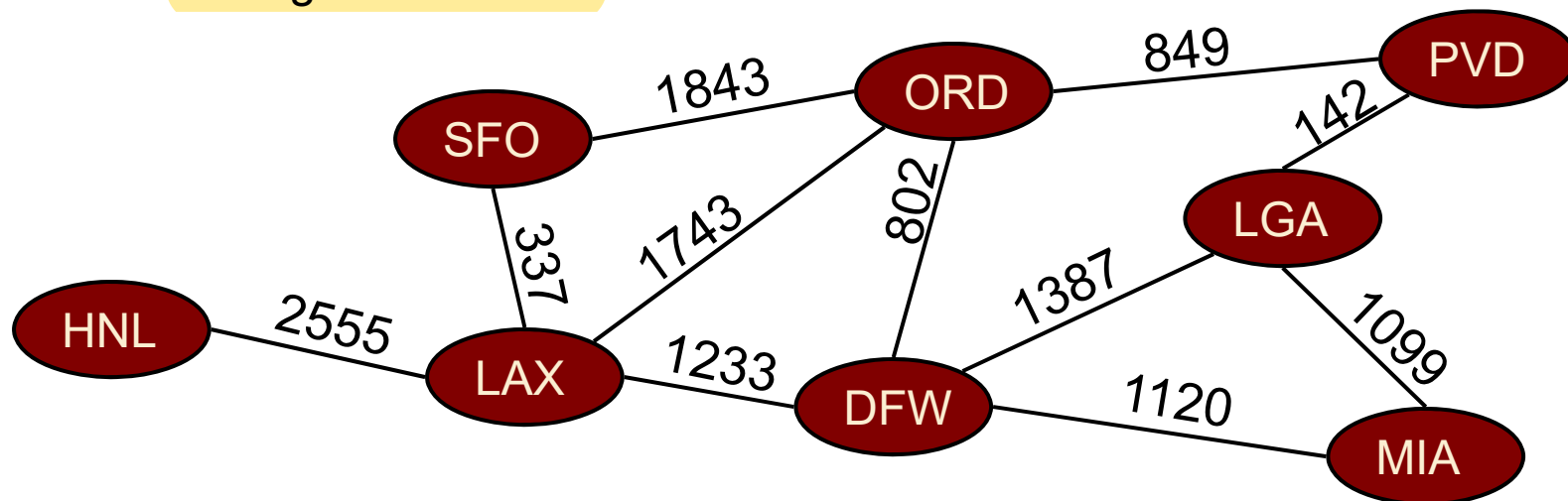
# Graphs

➤ A graph is a pair  $(V, E)$ , where

- ❑  $V$  is a set of nodes, called vertices
- ❑  $E$  is a collection of pairs of vertices, called edges
- ❑ Vertices and edges are positions and store elements

➤ Example:

- ❑ A vertex represents an airport and stores the three-letter airport code
- ❑ An edge represents a flight route between two airports and stores the mileage of the route



# Paths

## ➤ Path

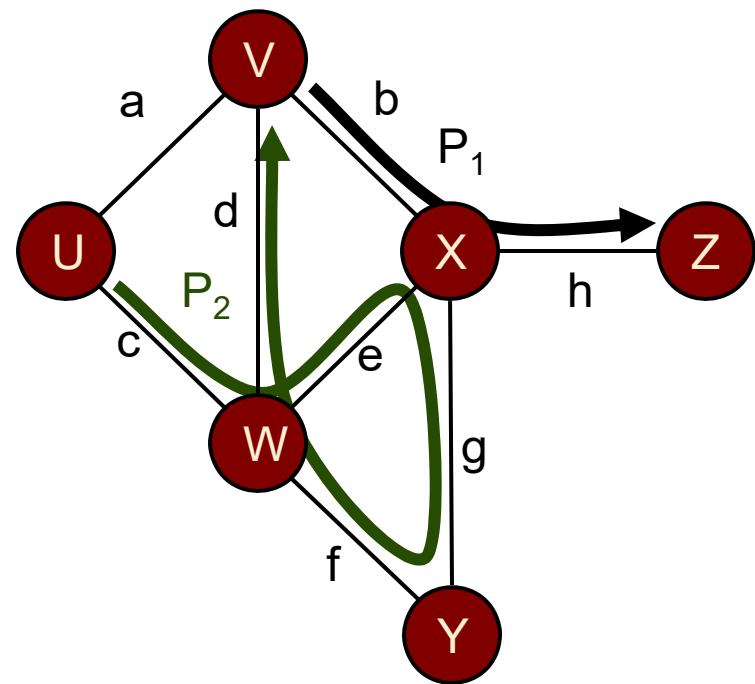
- sequence of alternating vertices and edges
- begins with a vertex
- ends with a vertex
- each edge is preceded and followed by its endpoints

## ➤ Simple path

- path such that all its vertices and edges are distinct

## ➤ Examples

- $P_1 = (V, b, X, h, Z)$  is a simple path
- $P_2 = (U, c, W, e, X, g, Y, f, W, d, V)$  is a path that is not simple





# Cycles

## ➤ Cycle

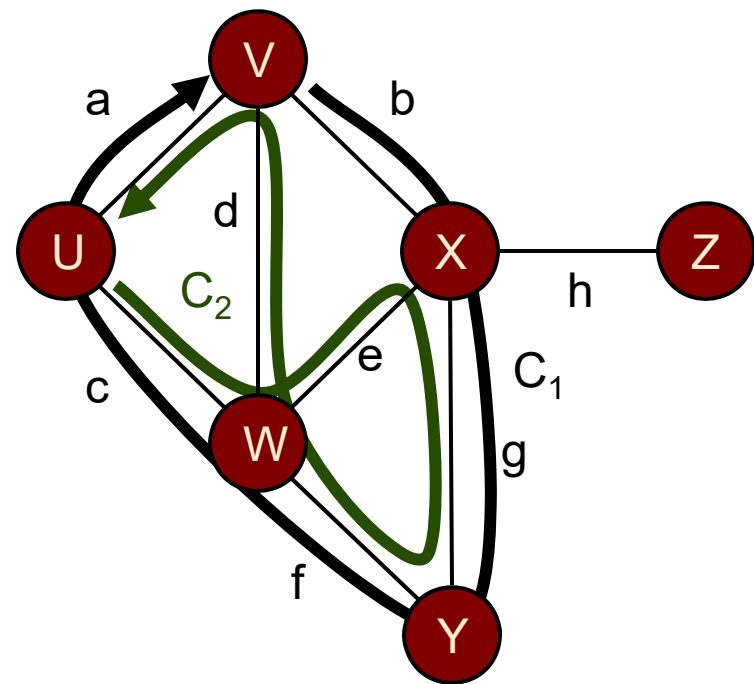
- ❑ circular sequence of alternating vertices and edges
- ❑ each edge is preceded and followed by its endpoints

## ➤ Simple cycle

- ❑ cycle such that all its vertices and edges are distinct

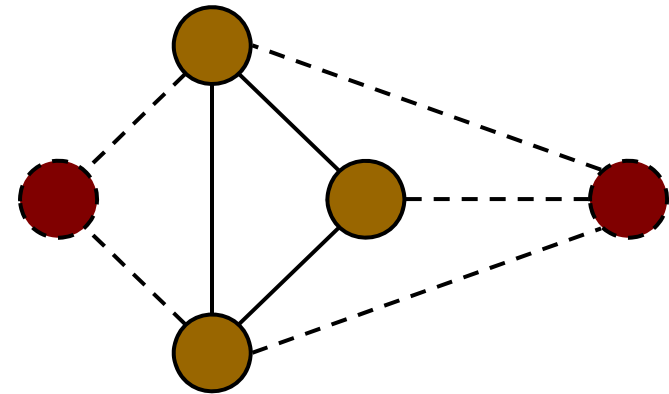
## ➤ Examples

- ❑  $C_1 = (V, b, X, g, Y, f, W, c, U, a, V)$  is a simple cycle
- ❑  $C_2 = (U, c, W, e, X, g, Y, f, W, d, V, a, U)$  is a cycle that is not simple

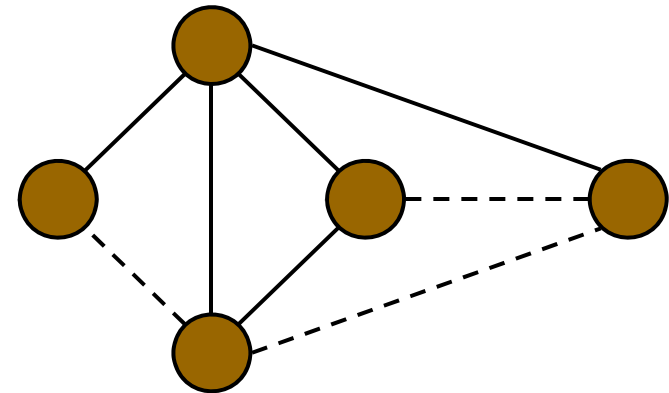


# Subgraphs

- A subgraph  $S$  of a graph  $G$  is a graph such that
  - ❑ The vertices of  $S$  are a subset of the vertices of  $G$
  - ❑ The edges of  $S$  are a subset of the edges of  $G$
- A spanning subgraph of  $G$  is a subgraph that contains all the vertices of  $G$



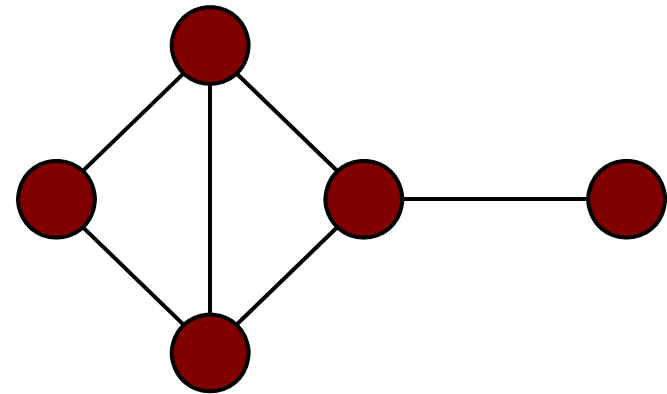
Subgraph



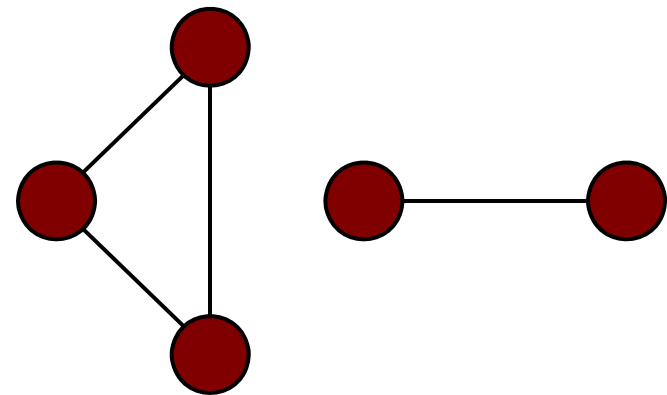
Spanning subgraph

# Connectivity

- A graph is connected if there is a path between every pair of vertices
- A connected component of a graph  $G$  is a maximal connected subgraph of  $G$

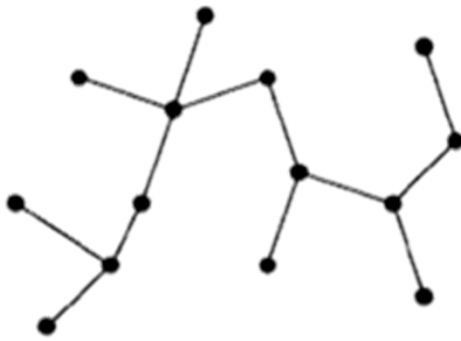


Connected graph



Non connected graph with two connected components

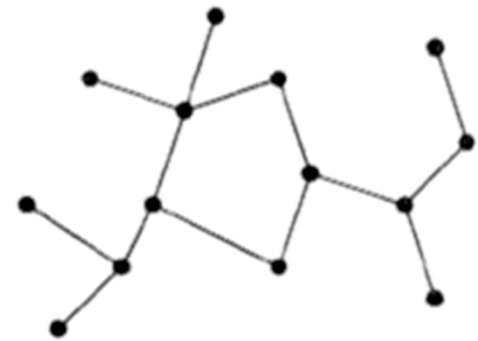
# Trees



Tree



Forest



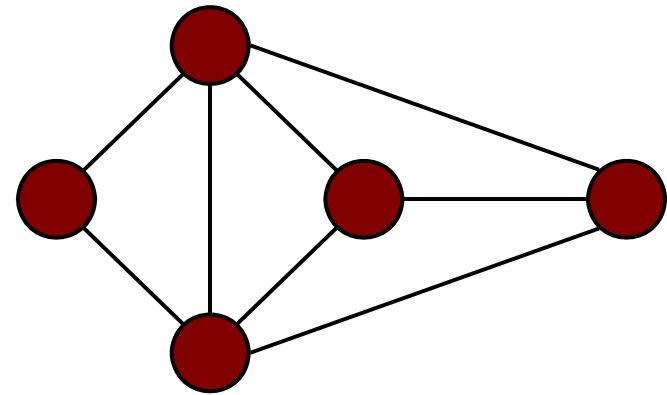
Graph with Cycle

A tree is a **connected**, **acyclic**, **undirected** graph.

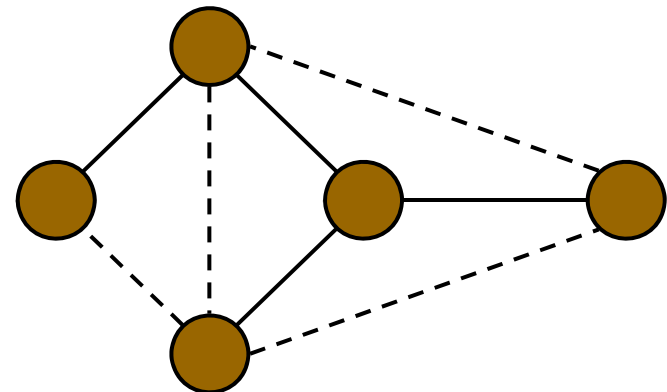
A forest is a **set** of trees (not necessarily connected)

# Spanning Trees

- A spanning tree of a connected graph is a spanning subgraph that is a tree
- A spanning tree is not unique unless the graph is a tree
- Spanning trees have applications to the design of communication networks
- A spanning forest of a graph is a spanning subgraph that is a forest



Graph

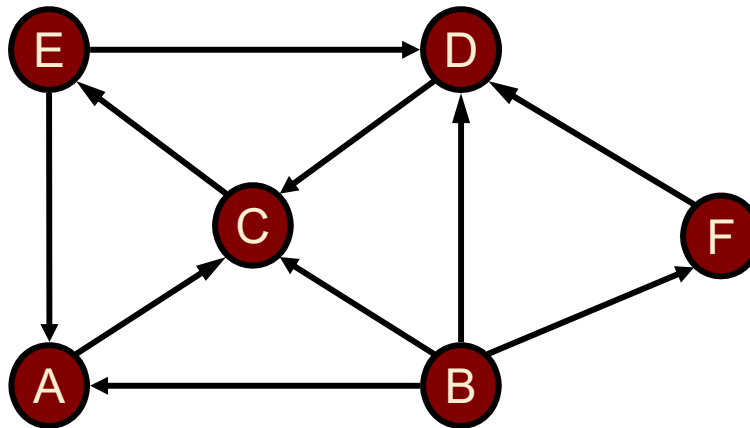


Spanning tree

# Reachability in Directed Graphs

➤ A node  $w$  is **reachable** from  $v$  if there is a directed path originating at  $v$  and terminating at  $w$ .

- ☐ E is reachable from B
- ☐ B is not reachable from E



# Properties

## Property 1

$$\sum_v \deg(v) = 2|E|$$

Proof: each edge is counted twice

## Notation

$|V|$  number of vertices

$|E|$  number of edges

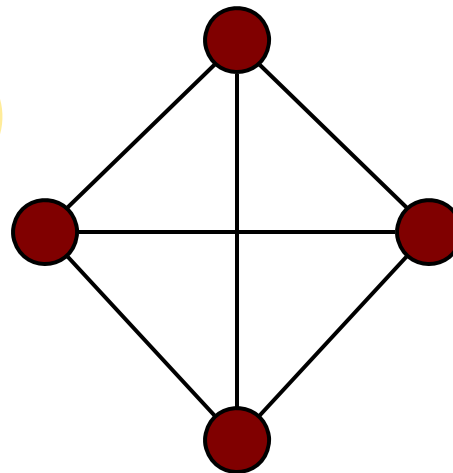
$\deg(v)$  degree of vertex  $v$

## Property 2

In an undirected graph with no self-loops and no multiple edges

$$|E| \leq |V|(|V| - 1)/2$$

Proof: each vertex has degree at most  $(|V| - 1)$



## Example

- $|V| = 4$
- $|E| = 6$
- $\deg(v) = 3$

Q: What is the bound for a digraph?

A:  $|E| \leq |V|(|V| - 1)$

# Outline

- Definitions
- **Graph ADT**
- Implementations



# Main Methods of the (Undirected) Graph ADT

## ➤ Vertices and edges

- ❑ are positions
- ❑ store elements

## ➤ Accessor methods

- ❑ **endVertices**(e): an array of the two endvertices of e
- ❑ **opposite**(v, e): the vertex opposite to v on e
- ❑ **areAdjacent**(v, w): true iff v and w are adjacent
- ❑ **replace**(v, x): replace element at vertex v with x
- ❑ **replace**(e, x): replace element at edge e with x

## ➤ Update methods

- ❑ **insertVertex**(o): insert a vertex storing element o
- ❑ **insertEdge**(v, w, o): insert an edge (v,w) storing element o
- ❑ **removeVertex**(v): remove vertex v (and its incident edges)
- ❑ **removeEdge**(e): remove edge e

## ➤ Iterator methods

- ❑ **incidentEdges**(v): edges incident to v
- ❑ **vertices**(): all vertices in the graph
- ❑ **edges**(): all edges in the graph

# Directed Graph ADT

## ➤ Additional methods:

- ❑ `isDirected(e)`: return true if `e` is a directed edge
- ❑ `insertDirectedEdge(v, w, o)`: insert and return a new directed edge with origin `v` and destination `w`, storing element `o`

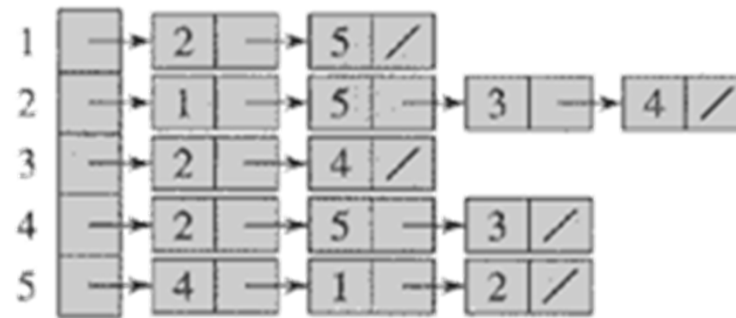
# Outline

- Definitions
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# Running Time of Graph Algorithms

- Running time often a function of both  $|V|$  and  $|E|$ .
- For convenience, we sometimes drop the  $|\dots|$  in asymptotic notation, e.g.  $O(V+E)$ .

# Implementing a Graph (Simplified)



	1	2	3	4	5
1	0	1	0	0	1
2	1	0	1	1	1
3	0	1	0	1	0
4	0	1	1	0	1
5	1	1	0	1	0

Adjacency List

Adjacency Matrix

Space complexity:

$$\theta(V + E)$$

$$\theta(V^2)$$

Time to find all neighbours of vertex  $u$ :

$$\theta(\text{degree}(u))$$

$$\theta(V)$$

Time to determine if  $(u, v) \in E$ :

$$\theta(\text{degree}(u))$$

$$\theta(1)$$

# Representing Graphs (Details)

## ➤ Three basic methods

- ☐ Edge List

- ☐ Adjacency List

- ☐ Adjacency Matrix

# Edge List Structure

## ➤ Vertex object

- element
- reference to position in vertex sequence

## ➤ Edge object

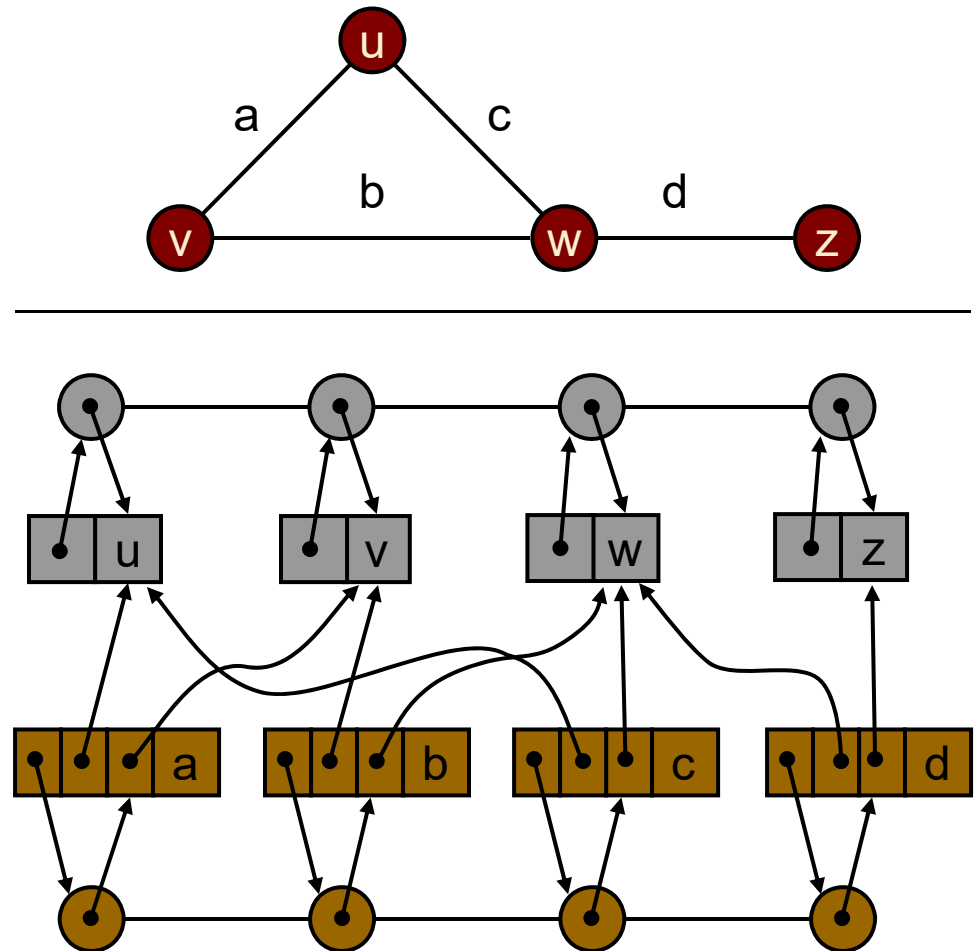
- element
- origin vertex object
- destination vertex object
- reference to position in edge sequence

## ➤ Vertex sequence

- sequence of vertex objects

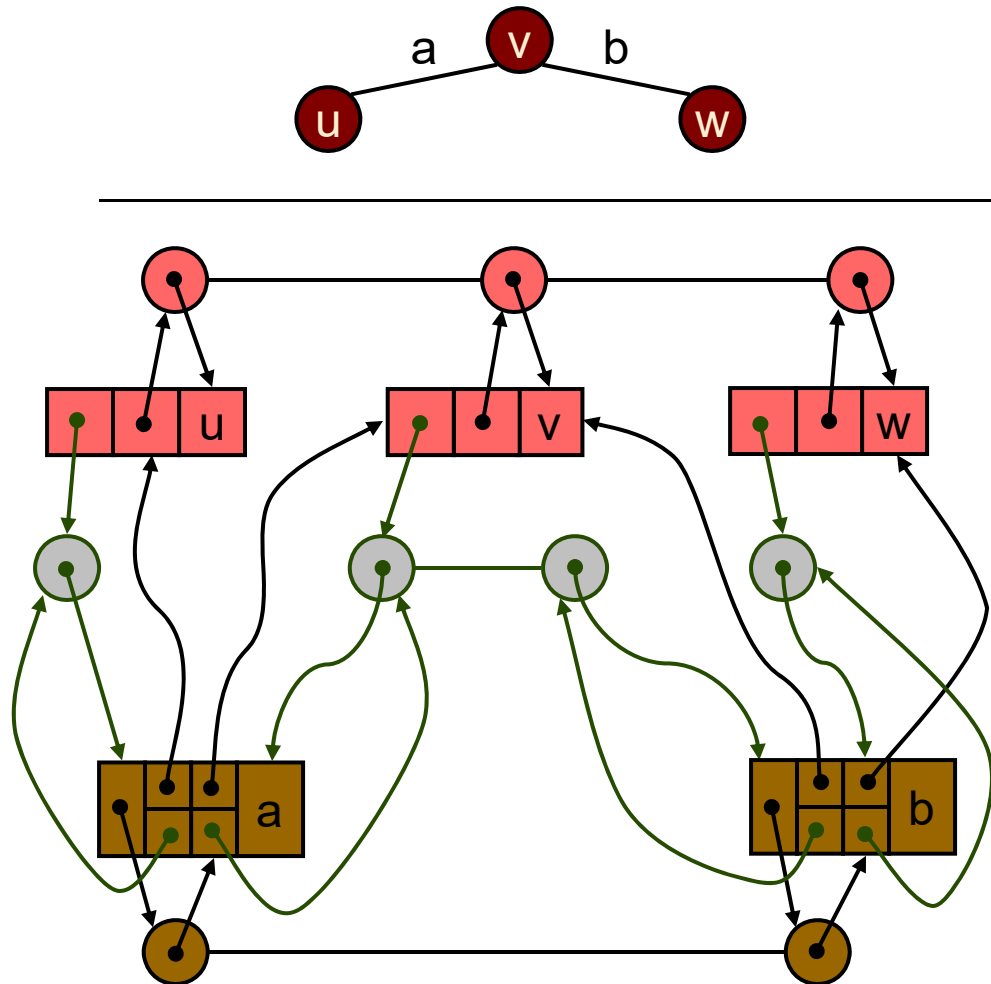
## ➤ Edge sequence

- sequence of edge objects



# Adjacency List Structure

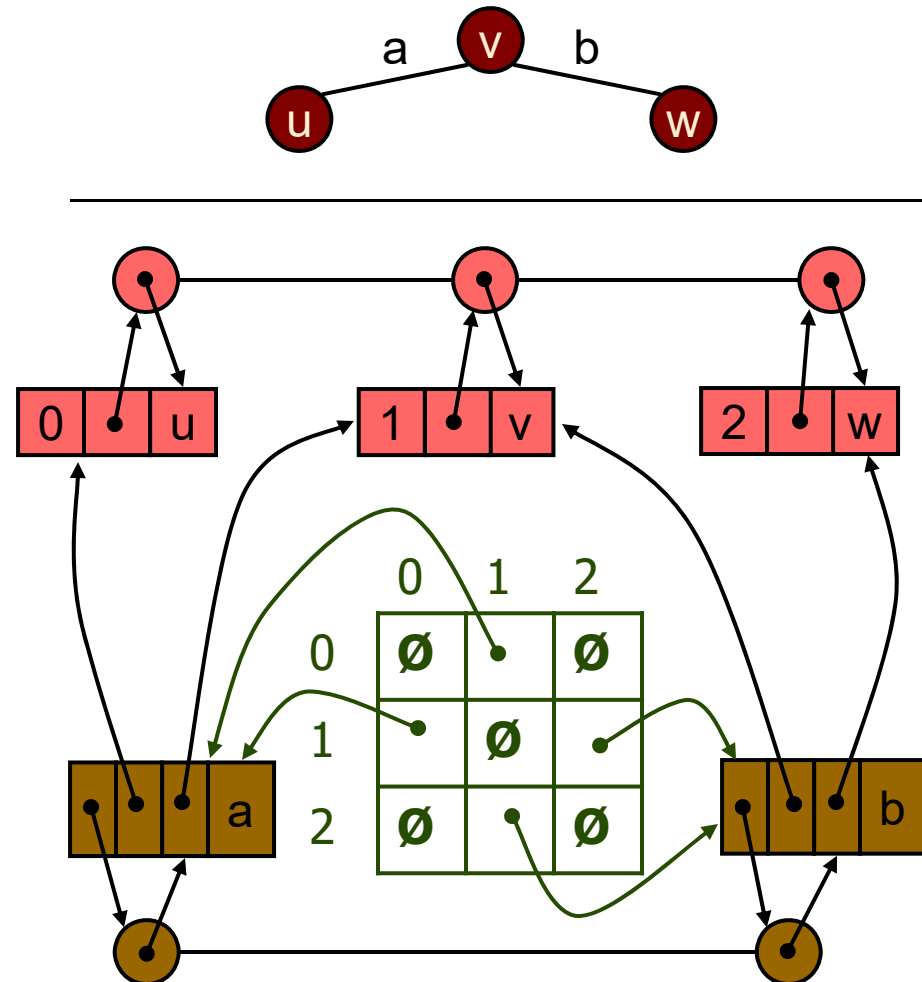
- Edge list structure
- Incidence sequence for each vertex
  - sequence of references to edge objects of incident edges
- Augmented edge objects
  - references to associated positions in incidence sequences of end vertices





# Adjacency Matrix Structure

- Edge list structure
- Augmented vertex objects
  - ❑ Integer key (index) associated with vertex
- 2D-array adjacency array
  - ❑ Reference to edge object for adjacent vertices
  - ❑ Null for non-adjacent vertices



# Asymptotic Performance

(assuming collections  $V$  and  $E$  represented as doubly-linked lists)

<ul style="list-style-type: none"> <li>◆ <math> V </math> vertices, <math> E </math> edges</li> <li>◆ no parallel edges</li> <li>◆ no self-loops</li> <li>◆ Bounds are "big-Oh"</li> </ul>	Edge List	Adjacency List	Adjacency Matrix
Space	$ V + E $	$ V + E $	$ V ^2$
incidentEdges( $v$ )	$ E $	deg( $v$ )	$ V $
areAdjacent ( $v, w$ )	$ E $	min(deg( $v$ ), deg( $w$ ))	1
insertVertex( $o$ )	1	1	$ V ^2$
insertEdge( $v, w, o$ )	1	1	1
removeVertex( $v$ )	$ E $	deg( $v$ )	$ V ^2$
removeEdge( $e$ )	1	1	1

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