Loop Invariants and Binary Search

Chapter 4.4, 5.1

Outline

- ➤ Iterative Algorithms, Assertions and Proofs of Correctness
- Binary Search: A Case Study

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- > Iterative Algorithms, Assertions and Proofs of Correctness
- Binary Search: A Case Study

Assertions

- An assertion is a statement about the state of the data at a specified point in your algorithm.
- ➤ An assertion is not a task for the algorithm to perform.
- ➤ You may think of it as a comment that is added for the benefit of the reader.

Loop Invariants

- ➤ Binary search can be implemented as an **iterative algorithm** (it could also be done recursively).
- Loop Invariant: An assertion about the current state useful for designing, analyzing and proving the correctness of iterative algorithms.

Other Examples of Assertions

- Preconditions: Any assumptions that must be true about the input instance.
- Postconditions: The statement of what must be true when the algorithm/program returns.
- Exit condition: The statement of what must be true to exit a loop.

Iterative Algorithms

Take one step at a time towards the final destination

loop (done)

take step

end loop

Establishing Loop Invariant

From the Pre-Conditions on the input instance we must establish the loop invariant.



Maintain Loop Invariant



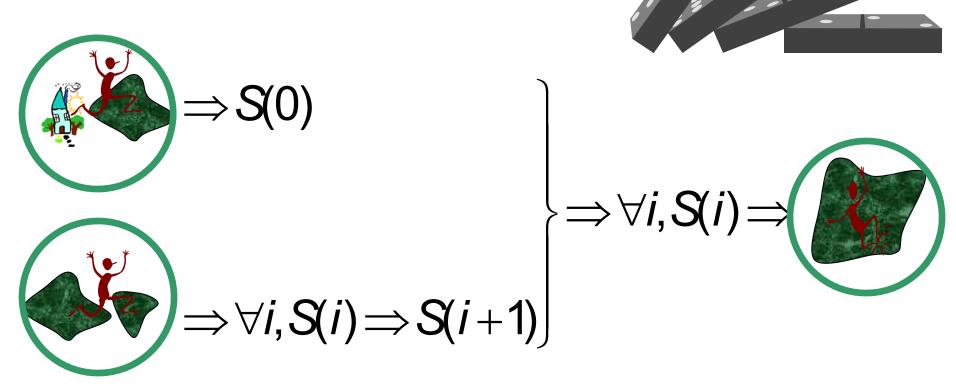
- ☐ We start in a safe location (pre-condition)
- ☐ If we are in a safe location, we always step to another safe location (loop invariant)
- Can we be assured that the computation will always be in a safe location?
- By what principle?





Maintain Loop Invariant

• By <u>Induction</u> the computation will always be in a safe location.

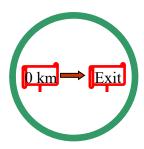


Ending The Algorithm

Define Exit Condition



Termination: With sufficient progress, the exit condition will be met.



- When we exit, we know
 - exit condition is true
 - ☐ loop invariant is true

from these we must establish the post conditions.



Definition of Correctness

<PreCond> & <code> -> <PostCond>

If the input meets the preconditions, then the output must meet the postconditions.

If the input does not meet the preconditions, then nothing is required.

Outline

- ➤ Iterative Algorithms, Assertions and Proofs of Correctness
- > Binary Search: A Case Study

Define Problem: Binary Search



- ☐ Key 25
- ☐ Sorted List



PostConditions

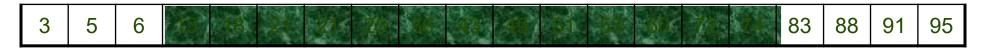
☐ Find key in list (if there).



Define Loop Invariant

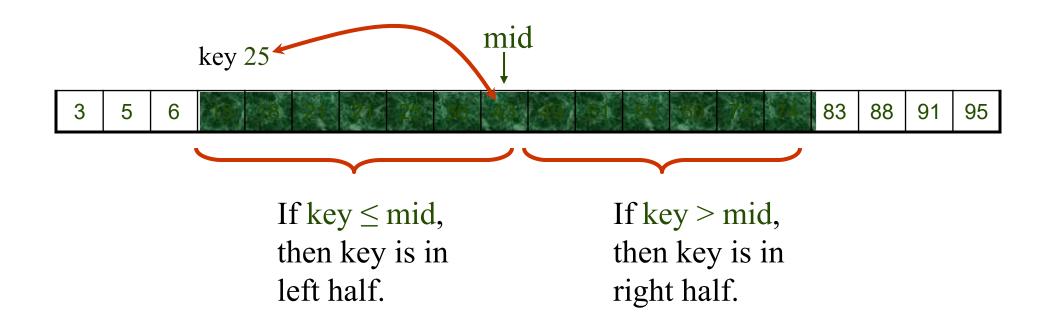
- Maintain a sublist.
- ➤ If the key is contained in the original list, then the key is contained in the sublist.





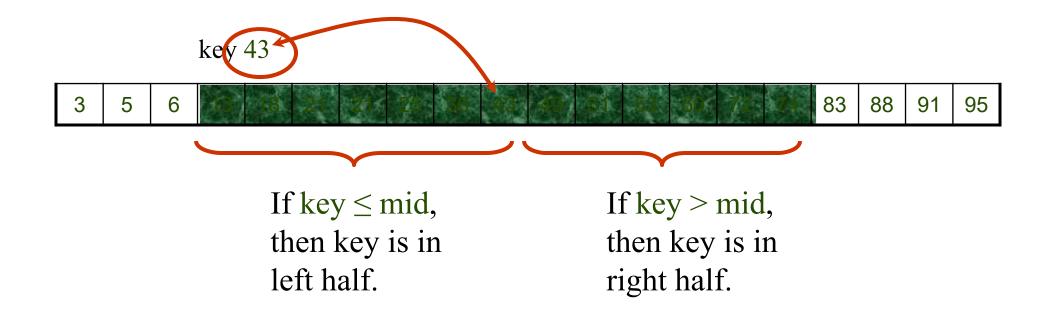
Define Step

- Cut sublist in half.
- Determine which half the key would be in.
- Keep that half.



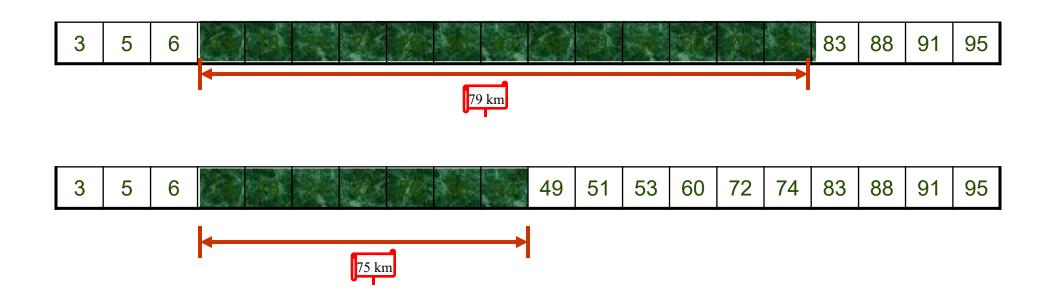
Define Step

- > It is faster not to check if the middle element is the key.
- Simply continue.



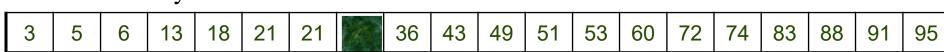
Make Progress

> The size of the list becomes smaller.



Exit Condition







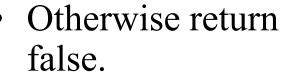
If the key is contained in the original list,

then the key is contained in the sublist.

Sublist contains one element.



 If element = key, return associated entry.

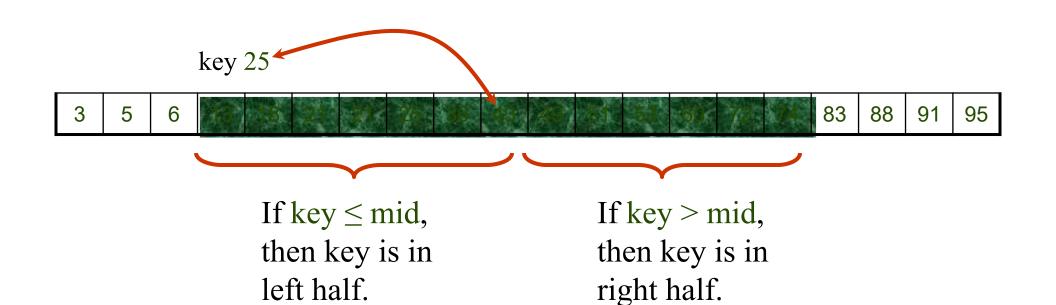


Running Time

The sublist is of size n, $\frac{n}{2}$, $\frac{n}{4}$, $\frac{n}{8}$,...,1

Each step O(1) time.

Total = O(log n)



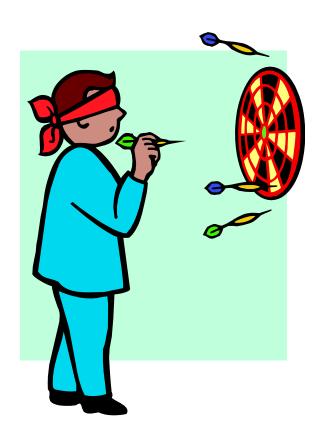
Running Time

- ➤ Binary search can interact poorly with the memory hierarchy (i.e. <u>caching</u>), because of its random-access nature.
- ➤ It is common to abandon binary searching for linear searching as soon as the size of the remaining span falls below a small value such as 8 or 16 or even more in recent computers.

```
BinarySearch(A[1..n], key)
condition>: A[1..n] is sorted in non-decreasing order
<postcondition>: If key is in A[1..n], algorithm returns its location
p = 1, q = n
while q > p
   < loop-invariant>: If key is in A[1..n], then key is in A[p..q]
   mid = \left| \frac{p+q}{2} \right|
   if key \leq A[mid]
       q = mid
   else
       p = mid + 1
   end
end
if key = A[p]
   return(p)
else
   return("Key not in list")
end
```

Simple, right?

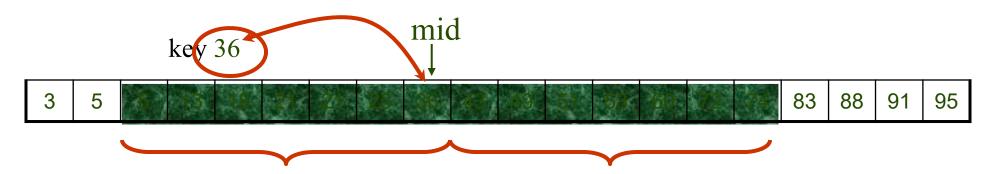
- ➤ Although the concept is simple, binary search is notoriously easy to get wrong.
- Why is this?



- The basic idea behind binary search is easy to grasp.
- ➤ It is then easy to write pseudocode that works for a 'typical' case.
- Unfortunately, it is equally easy to write pseudocode that fails on the boundary conditions.

```
\begin{array}{l} \text{if key } \leq A[\text{mid}\,] \\ q = \text{mid} \\ \text{else} \\ p = \text{mid} + 1 \\ \text{end} \end{array} \qquad \begin{array}{l} \text{if key } < A[\text{mid}\,] \\ q = \text{mid} \\ \text{else} \\ \text{or} \\ \text{end} \end{array}
```

What condition will break the loop invariant?



Code: $key \ge A[mid] \rightarrow select \ right \ half$ Bug!!

```
if key \leq A[mid]

q = mid

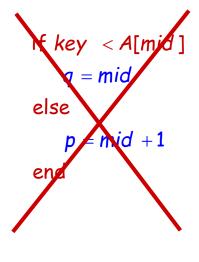
else

p = mid + 1

end
```

if key
$$A[mid]$$

$$q = mid - 1$$
else
$$p = mid$$
end

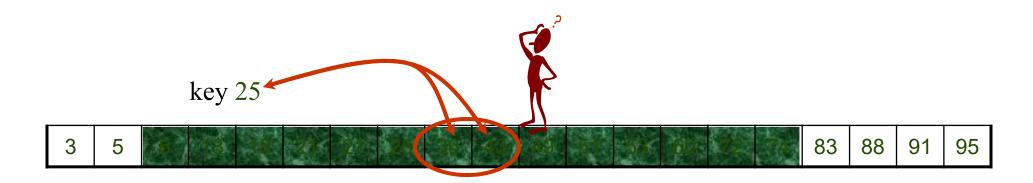


OK

OK

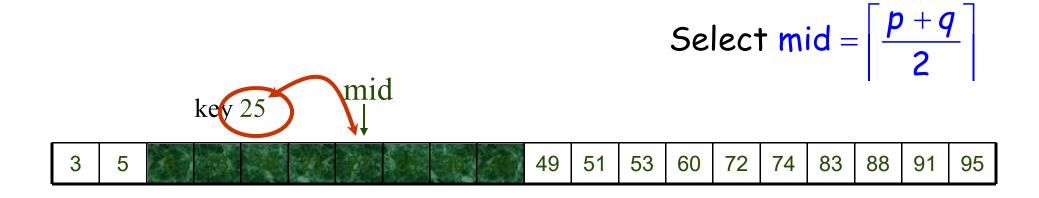
Not OK!!

$$\operatorname{mid} = \left\lfloor \frac{p+q}{2} \right\rfloor \qquad \text{or} \qquad \operatorname{mid} = \left\lceil \frac{p+q}{2} \right\rceil$$

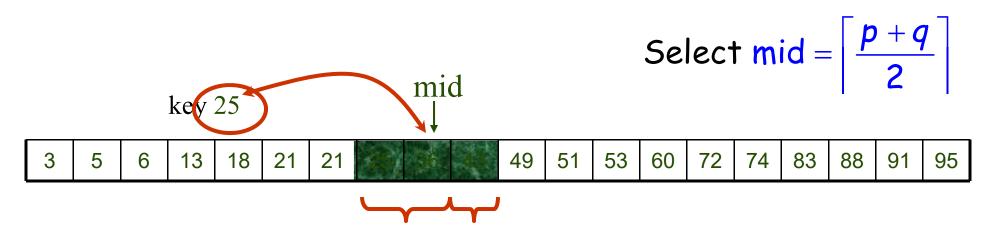


Shouldn't matter, right?

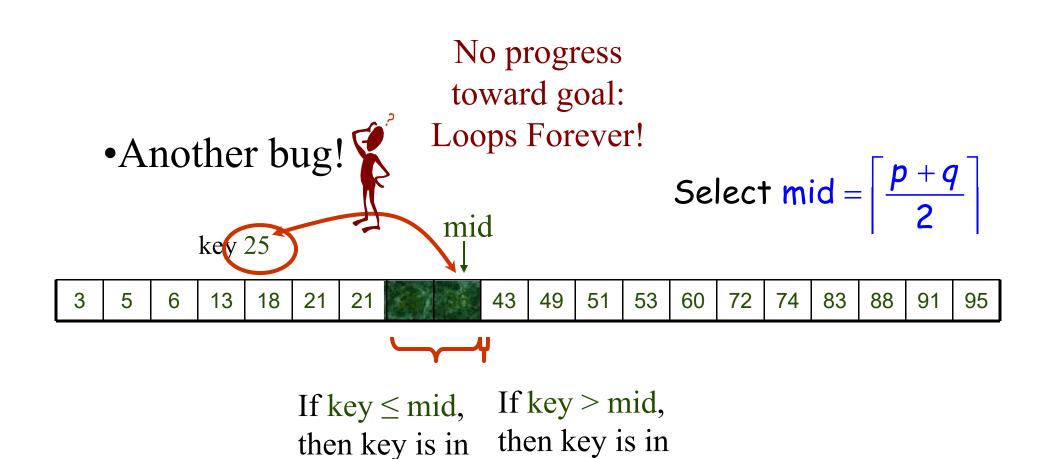
Select mid =
$$\left\lceil \frac{p+q}{2} \right\rceil$$



If key \leq mid, then key is in left half. If key > mid, then key is in right half.



If key \leq mid, If key > mid, then key is in left half. If key > mid, then key is in right half.



right half.

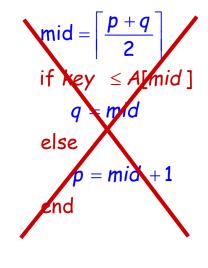
left half.

$$mid = \left\lfloor \frac{p+q}{2} \right\rfloor$$
if $key \leq A[mid]$

$$q = mid$$
else
$$p = mid + 1$$
end

$$mid = \left\lceil \frac{p+q}{2} \right\rceil$$
if $key < A[mid]$

$$q = mid -1$$
else
$$p = mid$$
end



OK

OK

Not OK!!

Getting it Right

- How many possible algorithms?
- How many correct algorithms?
- Probability of guessing correctly?

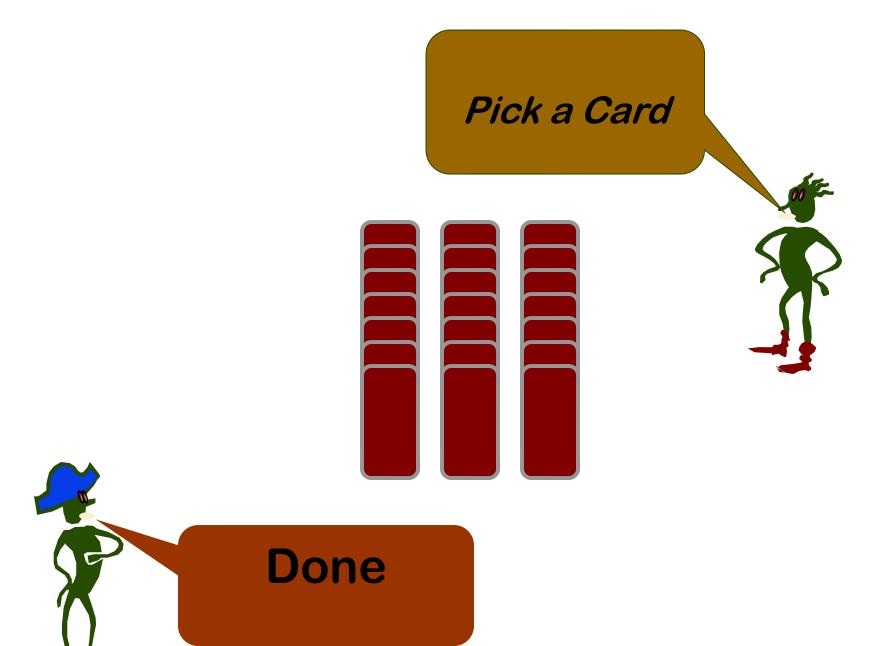
```
mid = \left| \frac{p+q}{2} \right| \qquad or mid = \left\lceil \frac{p+q}{2} \right\rceil ?
if key \leq A[mid] \leftarrow \text{ or if key } \langle A[mid] ?
     q = mid
 else
     p = mid + 1 or
                                    q = mid - 1
 end
                                     else
                                          p = mid
                                     end
```

Alternative Algorithm: Less Efficient but More Clear

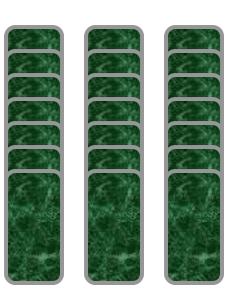
```
BinarySearch(A[1..n], key)
condition>: A[1..n] is sorted in non-decreasing order
<postcondition>: If key is in A[1..n], algorithm returns its location
p = 1, q = n
while q \ge p
   < loop-invariant>: If key is in A[1..n], then key is in A[p..q]
   mid = \frac{p+q}{2}
   if key < A[mid]
       q = mid - 1
   else if key > A[mid]
       p = mid + 1
   else
                                    Still \Theta(\log n), but with slightly larger constant.
       return(mid)
   end
end
return("Key not in list")
```

Card Trick



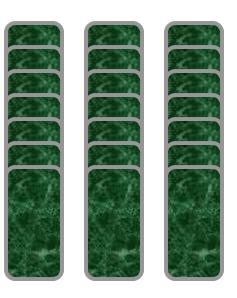


Thanks to J. Edmonds for this example.

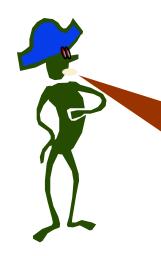




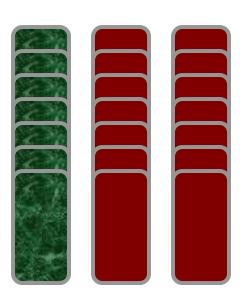
Which column?





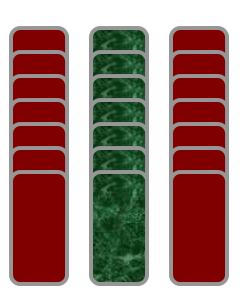


left



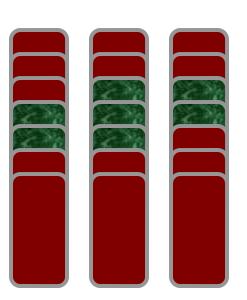


Selected column is placed in the middle



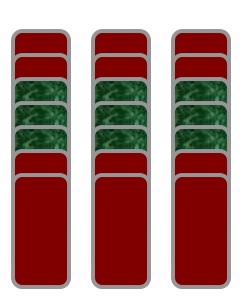


I will rearrange the cards



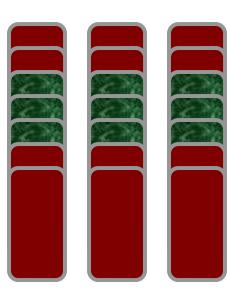


Relax Loop Invariant:
I will remember the same about each column.





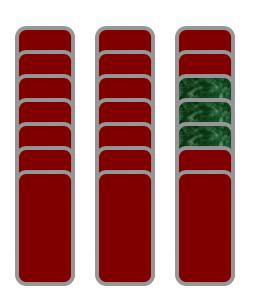






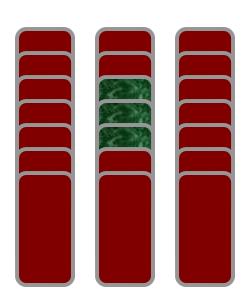


right



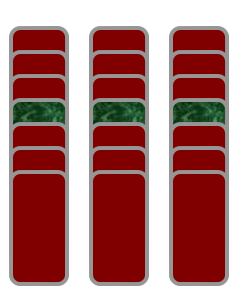


Selected column is placed in the middle



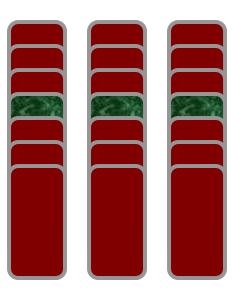


I will rearrange the cards





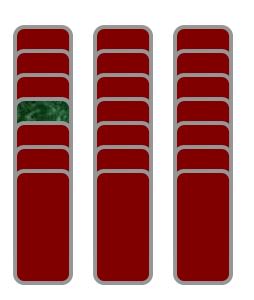






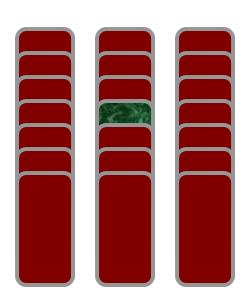


left

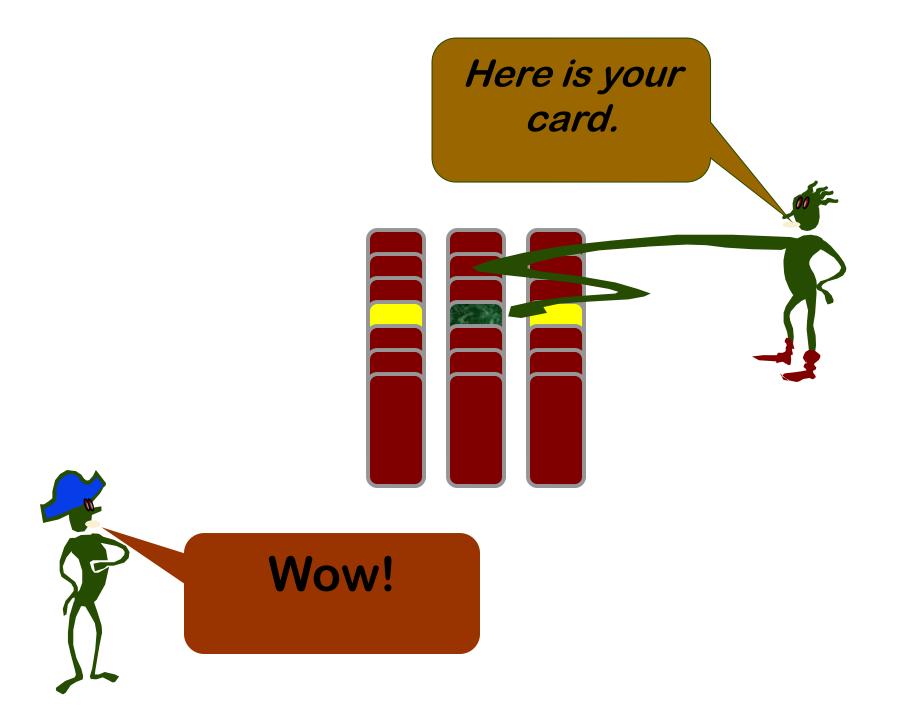




Selected column is placed in the middle







Ternary Search

Loop Invariant: selected card in central subset of cards

```
Size of subset = \lceil n/3^{i-1} \rceil
where n = \text{total number of cards}
i = \text{iteration index}
```

How many iterations are required to guarantee success?

Learning Outcomes

From this lecture, you should be able to:
☐ Use the loop invariant method to think about iterative algorithms.
☐ Prove that the loop invariant is established.
☐ Prove that the loop invariant is maintained in the 'typical' case.
Prove that the loop invariant is maintained at all boundary conditions.
☐ Prove that progress is made in the 'typical' case
Prove that progress is guaranteed even near termination, so that the exit condition is always reached.
Prove that the loop invariant, when combined with the exit condition, produces the post-condition.
☐ Trade off efficiency for clear, correct code.