# Computer Algebra Lecture 7

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11 September 2018

## Diagrammatic illustration

Figure: Diagrammatic illustration of Many Small Prime gcd Algorithm

$$egin{align*} \mathbf{Z}[x] & ----- & \mathbf{Z}[x] & & & & & \\ k imes \mathrm{reduce} \downarrow & & & \uparrow \& \mathrm{check} \\ & \mathbf{Z}_{p_1}[x] & \xrightarrow{\mathrm{gcd}} & \mathbf{Z}_{p_1}[x] \\ & \vdots & \vdots & \vdots \\ & \mathbf{Z}_{p_k}[x] & \xrightarrow{\mathrm{gcd}} & \mathbf{Z}_{p_k}[x] \end{array} \right\} \overset{\mathrm{C.R.T.}}{\longrightarrow} & \mathbf{Z}'_{p_1 \cdots p_k}[x]$$

 $\mathbf{Z}'_{p_1\cdots p_k}[\mathbf{x}]$  indicates that some of the  $p_i$  may have been rejected by the compatibility checks, so the product is over a subset of  $p_1\cdots p_k$ .

## More generally

gcd could be almost any algorithm that works over the integers. But we always have these questions.

- Are there "good" reductions from R?
- ② How can we tell if  $R_i$  is good?
- 4 How many reductions should we take?
- 4 How do we combine?
- 6 How do we check the result?

## For this gcd the answers are

- Are there "good" reductions from R?
- A All except (a) those that divide both leading coefficients; (b) those that divide a certain resultant
- 2 How can we tell if  $R_i$  is good?
- A Type (a) immediately, Type (b) we can't but given two different answers we know which is wrong
- How many reductions should we take?
- A The answer is given by the Landau–Mignotte Bounds, but these are often too pessimistic.
- 4 How do we combine?
- A Chinese Remainder Theorem
- 6 How do we check the result?
- A Lemma implies that, if G divides both, it is the g.c.d.

## Another Application: linear equations over Q

One problem is that, even if we have linear equations over **Z**, unless the determinant is 1, the answers will be over **Q** rather than **Z**. When we were looking for a g.c.d. with coefficients c: |c| < M, we needed  $\prod p_i < 2M$ . What happens over **Q**?

## Farey Reconstruction

```
procedure FAREY(y, N \in \mathbb{N})
    Output n, d \in \mathbf{Z} such that |n|, |d| < \sqrt{N/2} and n/d \equiv y
(mod N), or failed if none such exist.
    i := 1; a_0 := N; a_1 := v; a := 1; d := 1; b := c := 0
                 \triangleright Loop invariant: a_i = ay + bN; a_{i-1} = cy + dN;
    while a_i > \sqrt{N/2} do
        a_{i+1} = \text{rem}(a_{i-1}, a_i):
        q_i:=the corresponding quotient:
                                                    \triangleright a_{i+1} = a_{i-1} - q_i a_i
        e := c - q_i a; e' := d - q_i b;
                                                        \triangleright a_{i+1} = ef + e'g
        i := i + 1:
        (c,d) = (a,b);
        (a, b) = (e, e')
    end while
    if |a| < \sqrt{N/2} and gcd(a, N) = 1 then return (a_i, a)
    else return failed
    end if
end procedure
```

### Comments

This is essentially the Euclidean algorithm on y, N; tracking the dependencies.

Correctness of this algorithm, i.e. the fact that the first  $a_i < \sqrt{N/2}$  corresponds to the solution if it exists, is proved in [WGD82], using [HW79, Theorem 184].

The condition gcd(a, N) = 1 was stressed by [CE95], without which we may return meaningless results, such as (-2, 2), when trying to reconstruct 5 (mod 12).

It is possible (not well written up!) to handle the case of reconstructing  $\frac{c}{d}$  where |c| < C, |d| < D (i.e. different bounds), as long as N > 2CD.

## How big is the determinant |M| of an $n \times n$ matrix M?

#### Notation

If  $\mathbf{v}$  is a vector, then  $||\mathbf{v}||_2$  (sometimes also written |v|) denotes the Euclidean norm of  $\mathbf{v}$ ,  $\sqrt{\sum |v_i^2|}$ .

#### **Proposition**

If M is an  $n \times n$  matrix with entries  $\leq B$ ,  $|M| \leq n!B^n$ .

This is true because the determinant is the sum of n! summands, each the product of n elements, therefore bounded by  $B^n$ . This bound is frequently used, but we can do better.

#### Proposition

[Hadamard bound  $H_r$ ] If M is an  $n \times n$  matrix whose rows are the vectors  $\mathbf{v}_i$ , then  $|M| \leq H_r = \prod ||\mathbf{v}_i||_2$ , which in turn is  $\leq n^{n/2}B^n$ .

Much better if some rows are much larger than others.

## There's also a column variant

#### Proposition

[Hadamard bound  $H_r$ ] If M is an  $n \times n$  matrix whose columns are the vectors  $\mathbf{v}_i$ , then  $|M| \leq H_r = \prod ||\mathbf{v}_i||_2$ , which in turn is  $< n^{n/2}B^n$ .

Much better if some columns are much larger than others.

## Application to Linear Equations

Suppose we have  $M.\mathbf{x} = \mathbf{a}$  (and assume  $|M| \neq 0$ ). Then  $x_i = \frac{D_i}{D}$  where D = |M| and  $D_i$  is the determinant of the matrix replacing the *i*-th column of M by  $\mathbf{a}$ .

Hence we can choose lots of small primes and solve the linear equations (discarding those where the determinant is zero).

Choose a bound (probably using column version if a is bigger than M), and reconstruct.

## Hence the questions

- 4 Are there "good" reductions from R?
- A Yes, all primes with  $|M| \neq 0 \pmod{p}$
- ② How can we tell if  $R_i$  is good?
- A  $|M| \neq 0 \pmod{p}$ , i.e. fairly upfront. Certainly before we reconstruct.
- 4 How many reductions should we take?
- A given by the bounds
- 4 How do we combine?
- A Farey reconstruction after C.R.T.
- 6 How do we check the result?
- A We don't need to: all primes are good (as long as  $|M| \neq 0$  (mod p))

## Are the bounds too great?

They certainly can be.

But [AM01] shows that, for random  $n \times n$  matrices,  $-\log_e(|M|/H) \approx \frac{n}{2}$ , so the number of "wasted bits"  $\approx \frac{3n}{4}$  on average.

What about early termination?

- Note that it's early termination by constancy of  $\frac{p}{q}$  that matters: the integer will change!
- If we are reconstructing the whole of  $\mathbf{x}$ , then we can check the result. But this is a much bigger win when we are only reconstructing a few  $x_i$ , and then we have no check.

## Diagrammatic illustration (2)

f is some finite algorithm of +, -, \*, / (and therefore tests for division by zero), producing a single result

Figure: Diagrammatic illustration of Many Small Prime f Algorithm

 $\mathbf{Z}'_{p_1\cdots p_k}[x]$  indicates that some of the  $p_i$  may have been rejected by the compatibility checks, so the product is over a subset of  $p_1\cdots p_k$ .

## Hence the questions

- 4 Are there "good" reductions from R?
- A Yes. On a given input, f tests a finite set  $z_1, \ldots, z_N$  for being zero. Therefore, any prime not dividing  $\prod z_i$  is good.
- N.B. Some primes dividing a  $z_i$  might still be good.
  - ② How can we tell if  $R_i$  is good?
    - A Good question.
  - 4 How many reductions should we take?
  - A Good question.
  - 4 How do we combine?
  - A C.R.T., possibly with Farey reconstruction.
  - How do we check the result?
  - A Good question.

## Some primes dividing a $z_i$ might still be good

Consider our g.c.d. example

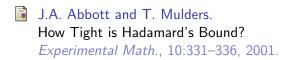
**Z** 
$$\pmod{5}$$
  
 $x^8 + x^6 - 3x^4 - 3x^3 + 8x^2 + 2x - 5$   $x^8 + x^6 + 2x^4 + 2x^3 + 3x^2 + 2x$   
 $3x^6 + 5x^4 - 4x^2 - 9x + 21$   $3x^6 + x^2 + x + 1$   
 $-15x^4 + 3x^2 - 9$   
 $15795x^2 + 30375x - 59535$   $4x^2 + 3$   
 $1254542875143750x$   $x$   
 $-1654608338437500$   $x$   
 $12593338[...]7500$   $x$ 

The mod 5 calculation takes a different route but ends up with the "right" answer: constant.

# So what about Gröbner bases [Arn03, IPS11]

- Are there "good" reductions from R?
- A Yes, by the "finite tests" rule
- ② How can we tell if  $R_i$  is good?
- A Good question. We can look at  $\{lm(g_i)\}$  for compatibility. But we don't have an equivalent of "larger degree is bad" rule from g.c.d.
- Mow many reductions should we take?
- A No useful bounds. Just wait for the answer (over **Q**) to stabilise.
- How do we combine?
- A C.R.T. with Farey reconstruction to get a monic Gröbner base over **Q**.
- 6 How do we check the result?
- A Good question.

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