view_frames Result

Recorded at time: 1566914817.999

map

Broadcaster: /amcl
Average rate: 3.167 Hz
Most recent transform: 1566914806.557 (11.442 sec old)
Buffer length: 3.158 sec

odom

Broadcaster: /robot_driver
Average rate: 8.511 Hz
Most recent transform: 1566914817.956 (0.044 sec old)
Buffer length: 4.700 sec

base_link

Broadcaster: /base_link_to_laser4
Average rate: 10.181 Hz
Most recent transform: 1566914818.039 (-0.039 sec old)
Buffer length: 4.813 sec

base_scan