# MTRX2700 Major Project

## 11am - 2pm 4<sup>th</sup> May 2021 (MTRX Lab)

#### 1. Attendance:

- Matthew
- James
- Shigita

#### 2. Purpose:

- Read through assignment sheet.
- Create GitHub Repo.
- Decide on means of communication.
- Decide on assistive technology.
- Design how technology can be modularised.
- Allocate modules/tasks to each group member.
- Schedule next meeting.

#### 3. Previous actions:

None.

#### 4. Regular items:

- Team updates:
  - Matthew: began designing servo controller module.
  - James: began designing lidar measurement module.
  - Shigita: began designing matlab lidar data processing module.
- Encountered issues:
  - None.

- How are we going to design module so that they can interface with each other seamlessly and intuitively?
- Review lectures from weeks 6-8 to help with designing modular systems.
- Read up on PWM and lidar/servo datasheets.
- 6. Next Meeting: 11am 2pm 11<sup>th</sup> May (MTRX Lab).

# MTRX2700 Major Project

## 11am - 2pm 11<sup>th</sup> May 2021 (MTRX Lab)

#### 1. Attendance:

- Matthew
- James
- Shigita

#### 2. Purpose:

- Finalise servo controller code design.
- Test servo controller code worked on during the week.
- Oral progress report from each member.
- Schedule next meeting.

#### 3. Previous actions:

- Created repository.
- Created Facebook Messenger group chat for communication.
- Determined assistive technologies to use.
- Delegated modules for each member.

#### 4. Regular items:

#### • Team updates:

- Matthew: continued work on servo controller module.
- James: continued lidar measurement module.
- Shigita: continued matlab lidar data processing module.

### • Encountered issues:

- Issues in initialising PWM registers for servo controller.

- What type of functions are we going to need to control the lidar positioning?
- Review week 10 lecture to design test functions.
- How are we going to format lidar code for matlab processing module?
- 6. Next Meeting: 11am 2pm 18<sup>th</sup> May (MTRX Lab).

## MTRX2700 Major Project

# 11am - 2pm 25<sup>th</sup> May 2021 (MTRX Lab)

#### 1. Attendance:

- Matthew
- James
- Shigita

#### 2. Purpose:

- Test and finalise servo controller module.
- Make solid progress on lidar module.
- Test lidar/pwm code.
- Finish matlab module design.
- Oral progress report from each member.

#### 3. Previous actions:

- Finished servo controller module design.
- Tested servo controller and lidar code.

### 4. Regular items:

#### • Team updates:

- Matthew: putting final touches on servo code.
- James: made good progress on lidar module.
- Shigita: also made good progress on matlab module.

#### • Encountered issues:

- Issues with initialising and test pwm and lidar signals.
- Was unable to go through with scheduled meeting due to group member personal matters.

- How will we be implementing testing procedures into our code?
- How are we going to integrate individually-worked modules into one codewarrior project?
- Next Meeting: 12pm 4pm 30<sup>th</sup> May (online).

## MTRX2700 Major Project

### 12pm - 5pm 30th May 2021 (online)

#### 1. Attendance:

- Matthew
- James
- Shigita

#### 2. Purpose:

- Push complete servo controller module onto repository.
- Build functions for lidar code.
- Debug lidar code.
- Continue writing matlab code.
- Progress report over text.

#### 3. Previous actions:

- Test and finalise servo controller code.
- Tested lidar/pwm.
- Matlab module design complete.

### 4. Regular items:

### • Team updates:

- Matthew: pushed servo controller module onto repository.
- James: progressing through lidar code. Ensuring it all works correctly
- Shigita: continued work on matlab code.

#### • Encountered issues:

- Issues with overflow interrupt and capturing rising/falling edge using polling method.

- Preparing project documentation (minutes, README.md).
- Prepare presentation.
- How are we going to integrate individually-worked modules into one codewarrior project?
- **6. Next Meeting:** sporadic throughout day 31<sup>th</sup> May.

## MTRX2700 Major Project

## 12pm - 2pm 31<sup>th</sup> May 2021 (online)

#### 7. Attendance:

- Matthew
- James
- Shigita

### 8. Purpose:

- Finalise lidar code
- Finalise matlab code
- Push both modules onto repository
- write presentation
- · report on progress

### 9. Previous actions:

- Test and finalise servo controller code.
- Built functions for lidar code.
- Test/debug of lidar code.
- Pushed servo controller module onto repository.

### 10. Regular items:

#### • Team updates:

- Matthew: work on documentation.
- James: finalising lidar code and integrating modules.
- Shigita: finalising matlab code. Work on presentation.

#### • Encountered issues:

- Minor hiccups when integration code into one project.

- How are we going to demonstrate the technology within 10-minute presentation?
- Is code fully-functional, demonstrates proof-of-concept, etc.
- Check through code comments and documentation for errors (both logical and spelling).
- **12. Next Meeting:** 11am-2pm 1<sup>st</sup> June (MTRX2700 Lab demo/presentation).